

10:20

# Feature Overview

Create New Drawing

Import and Shared

10:20

Pixel 6 API 33 - Extended Controls

- Location
- Displays
- Cellular
- Battery
- Camera
- Phone
- Directional pad
- Microphone
- Fingerprint
- Virtual sensors**
- Bug report
- Record and Playback
- Settings
- Help

Device Pose Additional sensors



☒ Rotate ☐ Move

Z-Rot -180 180 1.3

X-Rot -180 180 6.8

Y-Rot -180 180 -4.9

Rot

Sen

Ac

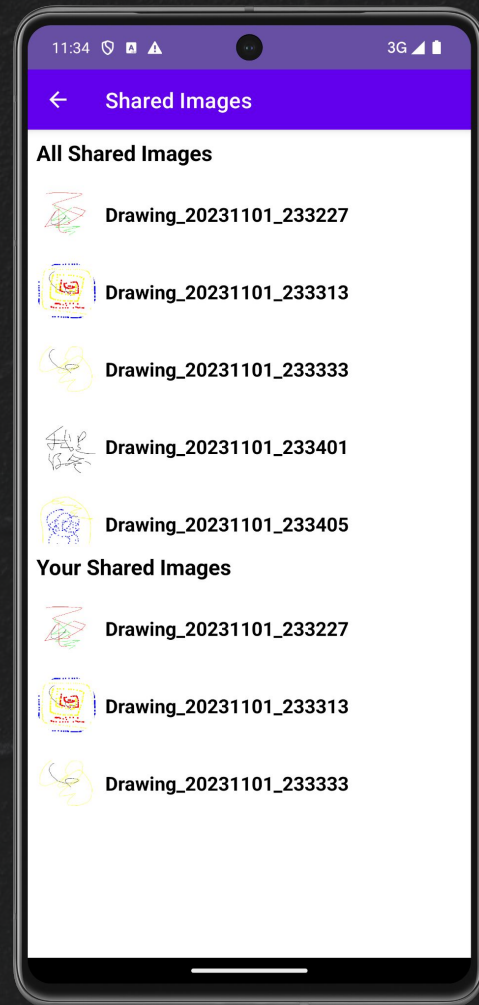
Gy

Mi

# Scaffold

```
Yutian_Qin +1 *
@SuppressLint("UnusedMaterialScaffoldPaddingParameter")
@Composable
fun DrawingLists(
    navController: NavController,
    drawingViewModel: DrawingViewModel,
    drawingRepository: DrawingRepository
) {
    val allUsersImages by drawingViewModel.allUsersImages.collectAsState()
    val thisUsersImages by drawingViewModel.thisUsersImages.collectAsState()
    val baseUrl = "http://10.0.2.2:8080/drawings/"
    val scope = rememberCoroutineScope()

    Scaffold(
        topBar = {
            TopAppBar(
                title = { Text(text = "Shared Images") },
                navigationIcon = {
                    IconButton(onClick = {
                        // Navigate back to the startFragment
                        navController.popBackStack()
                    }) {
                        Icon(Icons.Default.ArrowBack, contentDescription = null)
                    }
                }
            )
        }
    ) {
        it.PaddingValues
    }
}
```



# Gyro

- Senor based drawing using gyro sensor
- Main aspects of feature:
  - Button to start/stop feature
  - SensorEventListener
  - Handling the gyro data

Start Gyro Draw

Share

Pick Color

Brush/Size

Save

```
private fun startGyroSensor(sensorManager: SensorManager, gyroscope: Sensor, customView: CustomView) {  
    val gyroFlow: Flow<FloatArray> = getGyroData(gyroscope, sensorManager)  
  
    gyroFlowJob?.cancel()  
    gyroFlowJob = viewLifecycleOwner.lifecycleScope.launch { this: CoroutineScope  
        gyroFlow.collect { gyroReading ->  
            customView.handleGyroInput(gyroReading[0], gyroReading[1])  
        }  
    }  
}  
  
fun stopGyroSensor() {  
    if (gyroSensorListener != null) {  
        sensorManager.unregisterListener(gyroSensorListener)  
    }  
}
```



# Gyro

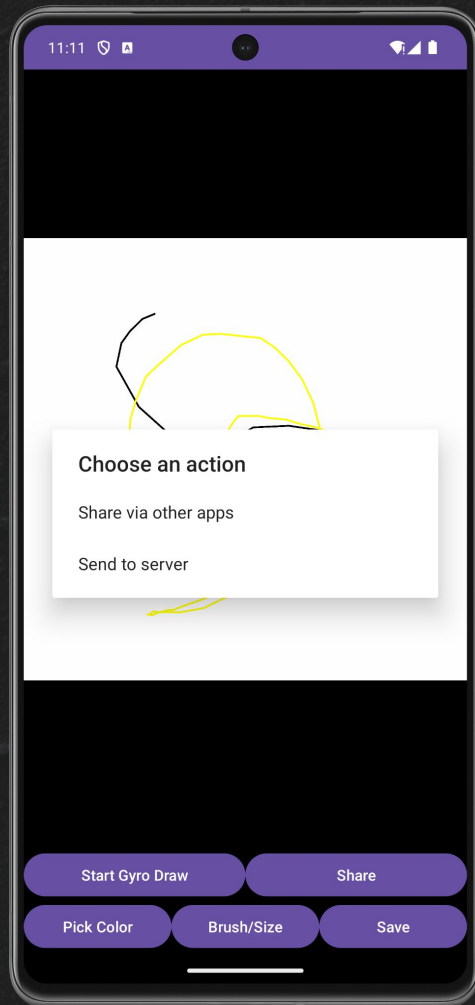
- Handling the data:
  - Keep track of the last path position
  - Grab only the x and y data
  - Clamp the data so path stays in bounds
  - Draw path to the new position
  - Can adjust sensitivity, higher the sensitivity the longer created paths

```
fun handleGyroInput(x: Float, y: Float) {  
    if (isGyroDrawing) {  
        lastGyroPosition?.let { lastPos ->  
            // Calculate the new position based on gyroscope input  
            val newX = lastPos.x + x * sensitivity  
            val newY = lastPos.y + y * sensitivity  
            // Clamp the values to make sure they're within the canvas bounds  
            val clampedX = newX.coerceIn(0f, width.toFloat())  
            val clampedY = newY.coerceIn(0f, height.toFloat())
```

# AlertDialog

Yutian\_Qin +1

```
private fun onClickShare(anchorView: View) {  
    val customView = view?.findViewById<CustomView>(R.id.custom_view)  
    val bitmap = customView?.getDrawingBitmap()  
  
    bitmap?.let { it: Bitmap  
        val choices = arrayOf("Share via other apps", "Send to server")  
        AlertDialog.Builder(requireContext()) AlertDialog.Builder  
            .setTitle("Choose an action") AlertDialog.Builder!  
            .setItems(choices) { _, which ->  
                when (which) {  
                    0 -> shareImageAndText(it) // Share via other apps  
                    1 -> sendImageToServer(it) // Send to server  
                }  
            }.show() ^let  
    }  
}
```





# UI

Changes made to the UI as the client added more requirements.

