

## 8.6

By definition of PSPACE-hardness for a language  $L$ .

For all  $A \in \text{PSPACE}$ ,  $A \leq_P L$ .

$\text{SAT} \in \text{NP}$ ,  $\text{SAT} \in \text{PSPACE}$ , since  $\text{NP} \subseteq \text{PSPACE}$ .

So,  $\text{SAT} \leq_P L$ .

Since SAT is NP-complete.  $\Rightarrow$  It's NP-hard.

Thus,  $\text{SAT} \leq_P L$ .  $L$  is NP-hard by transitivity of  $\leq_P$ .

Thus, We can get that any PSPACE-hard language is also NP-hard.

## 8.8

Let DFA  $M_1$  with  $a$  states, DFA  $M_2$  with  $b$  state.

Assume  $M_1, M_2$  differ on some input iff they differ on some input of length at most  $ab$ .

Let  $w$  be a string of minimal length on which they differ.  $|w| > ab$ .

Only  $ab$  have possible combinations of  $w$ .

So, By pigeonhole, there must be  $j > i$  for which both  $M_1$  and  $M_2$  are at the same states after  $i$  or  $j$  symbol of  $w$ .

Delete  $i+1$  through  $j$  of  $w$ .

Therefore, we can get a shorter string which takes  $M_1$  and  $M_2$  to same states  $w$ .

So, this shorter string on which they differ. This is contradiction.

Assume  $M_1, M_2$  differ on some input iff they differ on some input of length at most  $2^{a+b}$ .

Set a straightforward nondeterministic algorithm to decide if two DFAs differ as follow:

1. Check if the input does encode  $M_1$  and  $M_2$ . If not, reject. Otherwise, let  $a = |M_1|$ ,  $b = |M_2|$ .
2. Store list of  $S \subseteq Q_{M_1}$  as  $Q(a)$  space, list of  $T \subseteq Q_{M_2}$  as  $Q(b)$  space, string length  $L$  as  $Atb$  space.
3. Initialize  $S$  to be  $\epsilon$ -closure of the initial state of  $M_1$ .
4. Initialize  $T$  to be  $\epsilon$ -closure of the initial state of  $M_2$ .
5. Set  $L = 0$ . For  $L = 0$  to  $2^{a+b}$ .

I. If  $M_1$  include a final state, but  $M_2$  do not. or vice versa. Accept.

II. Nondeterministically choose a symbol  $\sigma \in \Sigma$ .

III. Update  $S$  to be the union  $U_{s \in S} \delta m_1(s, \sigma)$ .

IV Update  $T$  to be the union  $U_{t \in T} \delta m_2(t, \sigma)$ .

So, this is accepted iff there is a string of length at most  $2^{a+b}$  on which  $M_1, M_2$  differs.

Complement of  $EQ_{REG}$  lies in  $NPSPACE = PSPACE$ .

But  $PSPACE$  is closed under complement.

We can switch the accept and reject states to get a decider for the complement.

So,  $EQ_{REG} \in PSPACE$ .

## 8.10

Set a algorithm decides whether player "X" has a winning strategy in instances of go-moku.

We can show that this algorithm runs in polynomial space.

Assume position  $p$  indicates which player is the next to move.

$M = \text{"on input } \langle P \rangle$ , where  $P$  is a position in generalized go-moku:

1. If "X" is next to move, it can win in this turn, then accept.

2. If "O" is next to move, it can win in this turn, then reject.

3. If "X" is next to move, it cannot win in this turn, then for each free grid position  $p$ , recursively call  $M$  on  $\langle P' \rangle$  where  $P'$  is updated  $P$  with "X"'s marker on position  $p$ , and "O" is the next to move. If one or more of these accepts, accept. If none of these calls, reject.

4. If "O" is next to move, it cannot win in this turn, then for each free grid position  $p$ , recursively call  $M$  on  $\langle P' \rangle$  where  $P'$  is updated  $P$  with "O"'s marker on position  $p$ , and "X" is the next to move. If all of those calls accepts, accept. If one or more of these calls reject, reject.

The only space required by the algorithm is for storing the recursion stack.

Each level adds a single position.

So, the stack uses at most  $O(n)$  space, at most  $n^2$  levels.

So, the algorithm runs in  $O(n^3)$ .

Thus, we get a polynomial space complexity.

$\Rightarrow GS \Rightarrow PSPACE$ .

### 8.11

Given if every NP-hard language is PSPACE-hard, then SAT is PSPACE-hard.

Consequently every PSPACE language is polynomial-time reducible to SAT.

Since,  $SAT \in NP$

Then,  $PSPACE \subseteq NP$

So,  $PSPACE = NP$ .

Thus, We proved if every NP-hard language is also PSPACE-hard, then  $PSPACE = NP$ .

### 8.16

(a) Set an algorithm as follow:

"On input  $\phi$ ."

1. Let each formula  $\psi$  is shorter than  $\phi$ .

2. Variables of  $\phi$  of each assignment.

i. If  $\psi$  and  $\phi$  differs on assignment, then continue go to next  $\psi$ .

ii. Else, continue go to next assignment.

iii. If  $\psi$  and  $\phi$  are equivalent, reject.

3. If there is no shorter equivalent formula, accept.

In this algorithm, the space can store one formula and one assignment

The total space usage is linear.

So, linear is in the size of  $\phi$  in this algorithm.

Thus,  $MIN-FORMULA \in PSPACE$ .

(b) Given. If  $\phi \notin MIN-FORMULA$ , then  $\phi$  has a smaller equivalent formula.

⇒ If  $\phi \in MIN-FORMULA$ , then some smaller formula  $\psi$  is equivalent to  $\phi$ .

Since, we can not check it within polynomial time.

So,  $\psi$  can not be an NP.

Check if two formula are equivalent that requires exponential time.

8.25

Let  $G$  is a bipartite graph.

Assume  $G$  contain a cycle that has odd of nodes  $\{n_1, n_2, n_3 \dots n_k, n_{k+1}\}$ .

By definition of bipartite graph,  $G$  is a bipartite, If  $n_1$  is in set  $A$ ,  $n_2$  in set  $B$ , then  $n_3$  must in  $A$  etc.

All nodes with odd subscript must in  $A$ . all the nodes with even subscript must in  $B$ .

So,  $n_1$  and  $n_{k+1}$  are both in  $A$ .

That's contradiction, because they are connect.

Thus,  $G$  does not contain a cycle with odd of nodes.

Then, we assume a graph does not contain any odd cycles.

Take a node, then label it  $A$ . Label all of its neighbors  $B$ . Label all of their unlabeled neighbors  $A$ , etc until nodes are labeled.

Assume this construction caused two adjacent nodes  $P, Q$  that have the same label.

⇒ In even of steps,  $P$  and  $Q$  were reached

⇒ Exclude start node, from start node to  $P$  or  $Q$ , the traverse of total number of nodes is even.

So, if we include start node, the total number of nodes is odd.

That's contradiction, because a graph does not contain any odd cycles.

Thus, the graph is bipartite.

After, we will show that  $BIPARTITE \in NL$ .

As we know  $NL = coNL$ .

$\overline{BIPARTITE} = \{G \mid G \text{ is a graph contain an odd cycle}\}$ .

Let  $M$  be the NTM that decides  $\langle G \rangle \mid G \in \overline{BIPARTITE}$  in logarithmic space.

$M$  is constructed as follows:

$M =$  "on input  $\langle G \rangle$ :

1. Set a counter.
2. Nondeterministically select a start node and successor
3. while counter less or equal than the number of nodes.
4. If counter is odd and successor = start, then accept.
5. Otherwise, successor := Nondeterministically select a successor.

6. If counter is bigger than the number of node, then reject.

So,  $BIPARTITE \in NL$ .

Thus,  $BIPARTITE \in NL$ .

## 8.27

PROVE  $STRONALY-CONNECTED \in NL$ . We need to construct a NTM  $N_1$  that decides  $STRONALY-CONNECTED$  is logarithmic space.

The construction of  $N_1$  as follow:

$N_1 =$  "On input  $\langle G \rangle$ :

1. Select two nodes  $x$  and  $y$  non-deterministically.

2. Run  $PATH(x, y)$ .

3. If it reject, then accept.

4. Otherwise, reject.

$x, y$  only takes  $\log$  space,  $PATH$  uses only  $\log$  space.

So,  $STRONALY-CONNECTED \in NL$

since,  $NL = coNL$ .

Thus,  $STRONALY-CONNECTED \in NL$

After, we will show that every language in  $L$  is  $\log$  space reducible to  $STRONALY-CONNECTED$ .

Build a NTM  $N_2$  to do this procedure as follow:

$N_2 =$  "On input  $\langle G, s, t \rangle$   $G$  is graph,  $s, t$  are vertices in  $G$ .

1. Copy all of  $G$  onto the output tape.

2. For each node  $i$  in  $G$ .

3. Set a counter for  $i$ .

4. Output on edge from  $i$  to  $s$

5. Output on edge from  $t$  to  $i$ .

For this algorithm, we only need  $\log$  space to store counter for  $i$ .

So, we proved  $STRONALY-CONNECTED \in NL$  and every language in  $L$  is  $\log$  space reducible to  $STRONALY-CONNECTED$ . Thus,  $STRONALY-CONNECTED$  is in  $NL$ -complete.

## 8.29

First, we show that  $\text{ANFA} \in \text{NL}$ .

Let  $N$  be an NFA and let  $w$  be some valid input word.

Assume that  $N$  does not contain  $\epsilon$  transitions without loss of generality.

Simulate  $N$  on input  $w$ .

1. One indicating the current position in  $w$ .

2. One pointing to the current state of  $N$ .

Each transition of  $N$  have more than one possibility.

When we run the end of the  $w$  the machine accepts iff the current state of  $N$  is final.

Then we show that ANFA is NL-hard.

Set a logspace reduction from reachability in directed graphs as follow:

1. Let  $G$  be a directed graph.

2. Let  $s, t$  be vertices in  $G$ .

3. Let  $N_G$  be NFA.

I. If  $u \rightarrow v \in G$ ,  $u \rightarrow v \in N_G$

II. The only initial state of  $N_G$  is  $s$ , the only final state of  $N_G$  is  $t$ .

3.  $G$  has a path from  $s$  to  $t$  iff  $N_G$  accepts empty.

4.  $N_G$  can be built in logarithmic space.

So, ANFA is NL-complete.