

Towards a better understanding of early stopping for boosting algorithms

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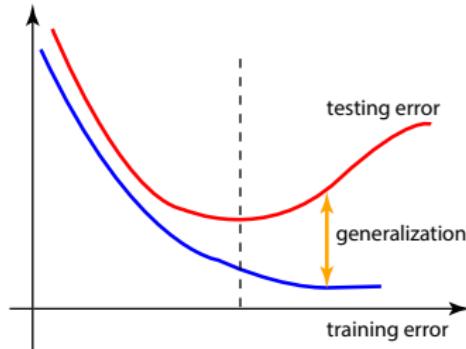
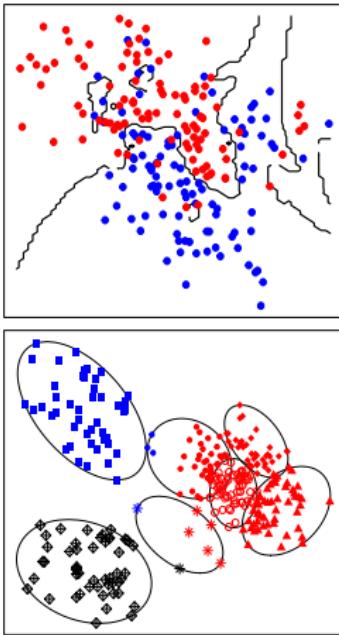
Fan Yang
ETH Zürich



Martin Wainwright
UC Berkeley

Overfitting and Generalization

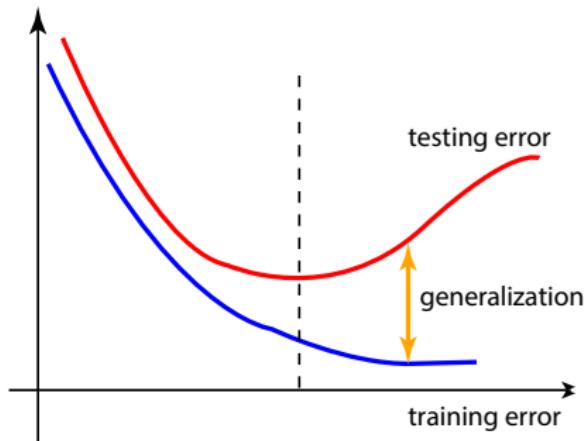
Textbook examples



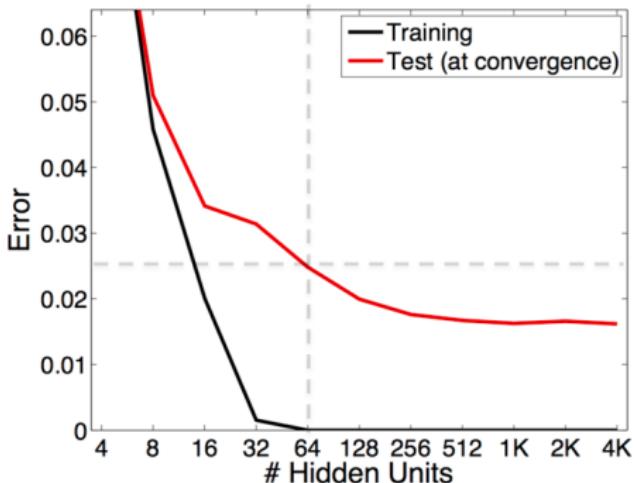
From "*The elements of statistical learning*" by Hastie, Tibshirani, Friedman

Lessons we learned...

- ▶ simpler models generalize better
- ▶ regularization is needed



Recent observed phenomenon



3-layer neural nets on MNIST (similar results on CIFAR)

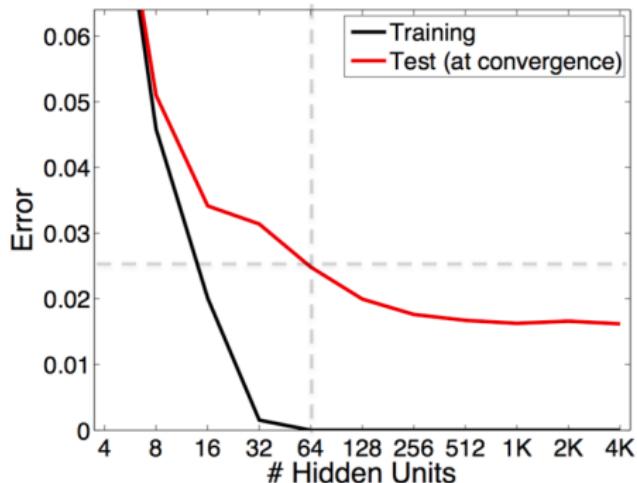
Neyshabur, Tomioka, Srebro ICLR'15

Our reactions to technologies:

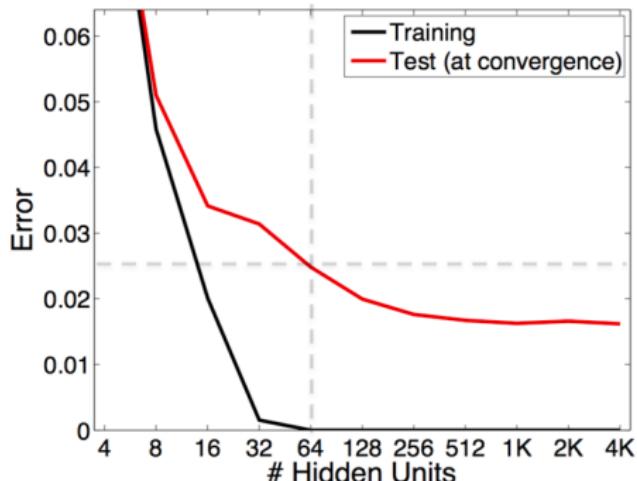
1. Anything that's in the world when you're born is *normal and ordinary* and is just a natural part of the way the world works.
2. Anything that's invented between when you're 15 and 35 is *new and exciting and revolutionary* and you can probably get a career in it.
3. Anything invented after you're 35 is *against the natural order of things*.

—*Douglas Adams, British author*

Recent observed phenomenon(continued)

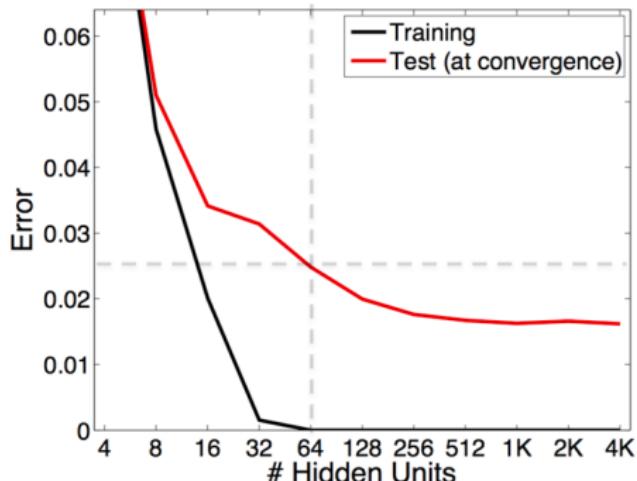


Recent observed phenomenon(continued)



- ▶ What is the right complexity measure?

Recent observed phenomenon(continued)



- ▶ What is the right complexity measure?
- ▶ What is this "error" here?

Does neural networks overfit the data?

UNDERSTANDING DEEP LEARNING REQUIRES RE-THINKING GENERALIZATION

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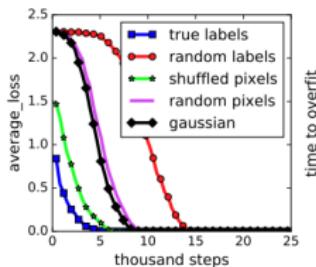
Samy Bengio
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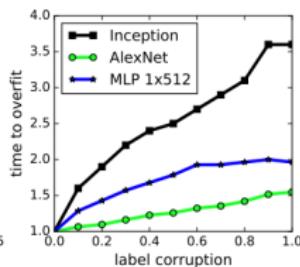
Benjamin Recht†
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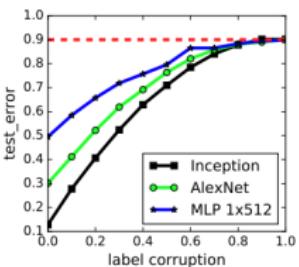
- ▶ Can fit any training data, given enough time and large enough network



(a) learning curves



(b) convergence slowdown



(c) generalization error growth

Zhang et al. '17

We need some form of regularization!

Empirical risk minimization

- ▶ Collect data $D_n = \{x_i, y_i\}_1^n \sim \mathbb{P}$

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- ▶ Squared loss $\mathcal{L}_n(f) = \frac{1}{2} \sum_{i=1}^n (y_i - f(x_i))^2$

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- ▶ Function class with norm $\|f\|_2^2 = \int f^2(x) dx$

From penalized to algorithmic regularization

Empirical loss function	Function class \mathcal{F}
$\mathcal{L}_n : \mathcal{F} \rightarrow \mathbb{R}$	Norm $\ \cdot\ _{\mathcal{F}}$

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Penalized regularization

Risk minimization with constraints

$$\hat{f} := \arg \min_{\|f\|_{\mathcal{F}} \leq R} \mathcal{L}_n(f; X_1^n, Y_1^n)$$

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Regularization by “**stopping early**”

early stopped estimator depends on complexity of \mathcal{F} , f^* , step sizes and algorithm nature

Boosting via functional gradient descent

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Given step size $\alpha^t > 0$,

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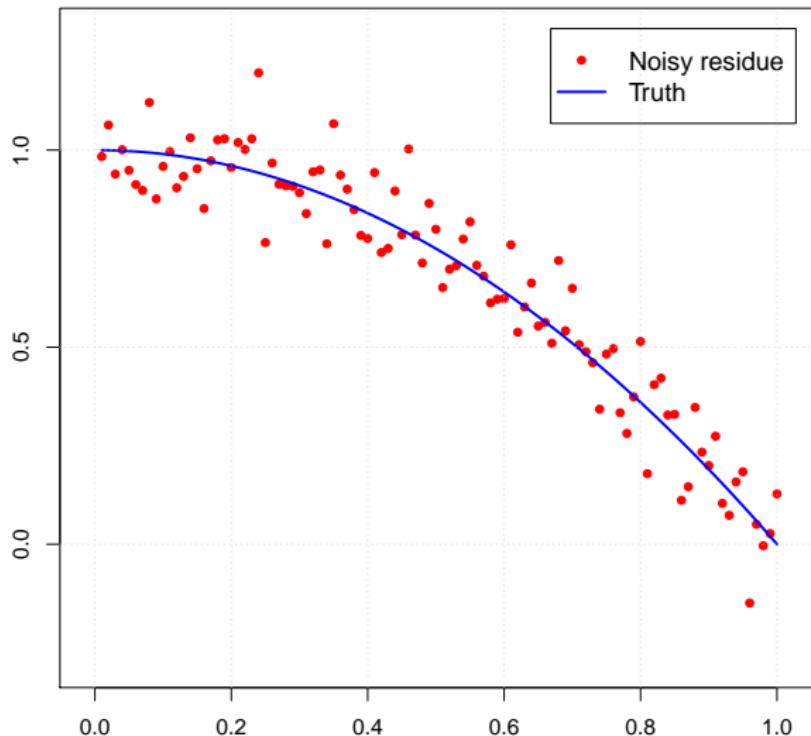
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- ▶ ℓ_2 -boosting: least-squares loss $\frac{1}{2}(y - f(x))^2$
- ▶ LogitBoost: logistic regression loss $\ln(1 + e^{-yf(x)})$
- ▶ AdaBoost: exponential loss $\exp(-yf(x))$

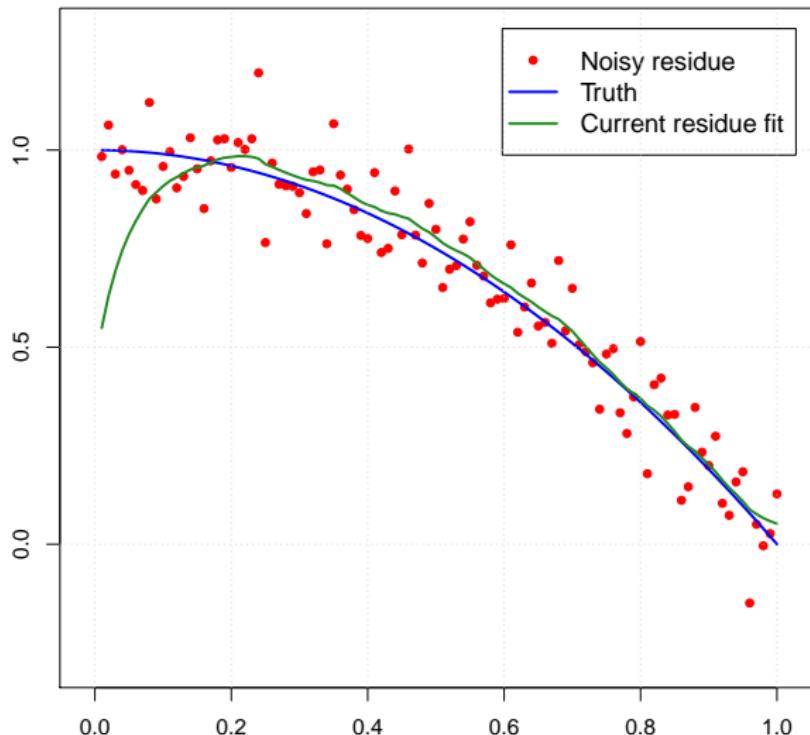
Boosting with a Laplacian kernel

Residues: kernel boosting at round 1



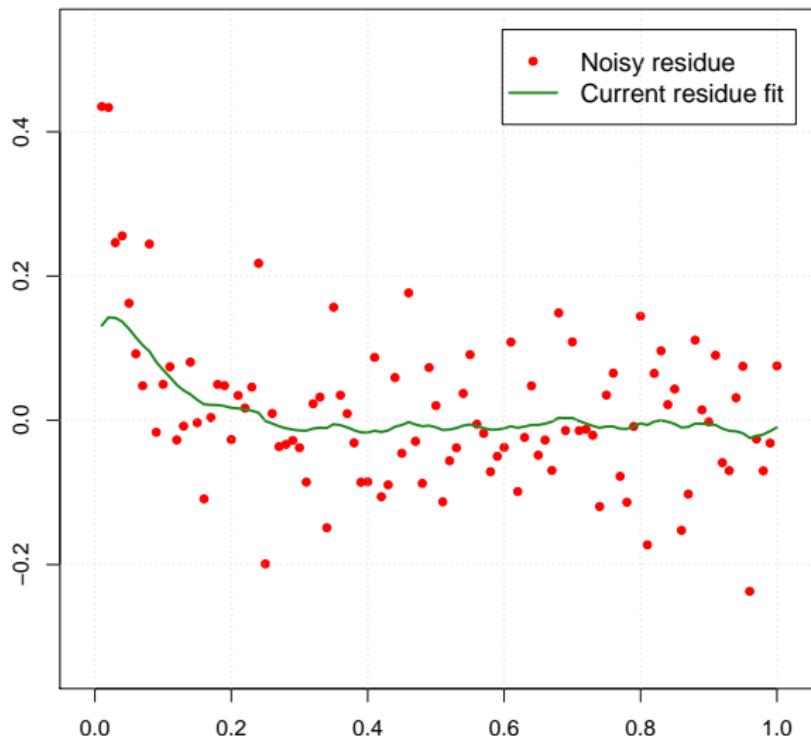
Boosting with a Laplacian kernel

Fit at round 1 of boosting



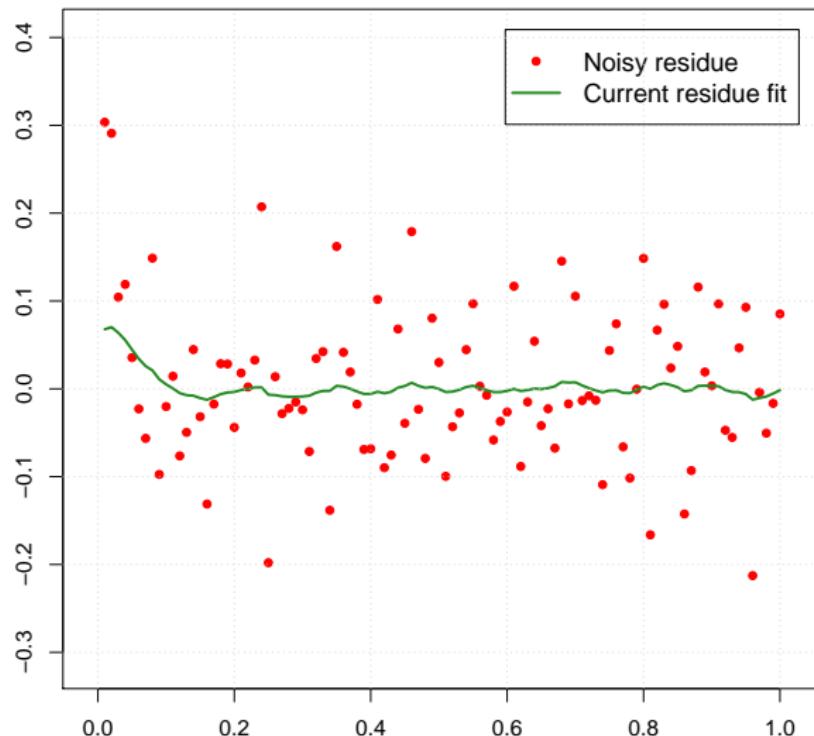
Boosting with a Laplacian kernel

Residues: kernel boosting at round 2



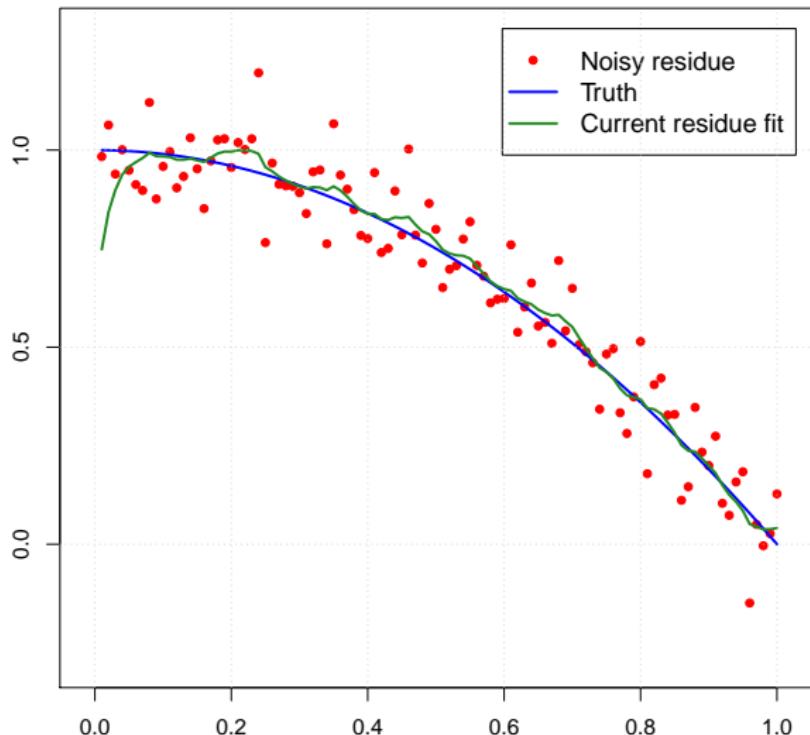
Boosting with a Laplacian kernel

Residues: kernel boosting at round 3



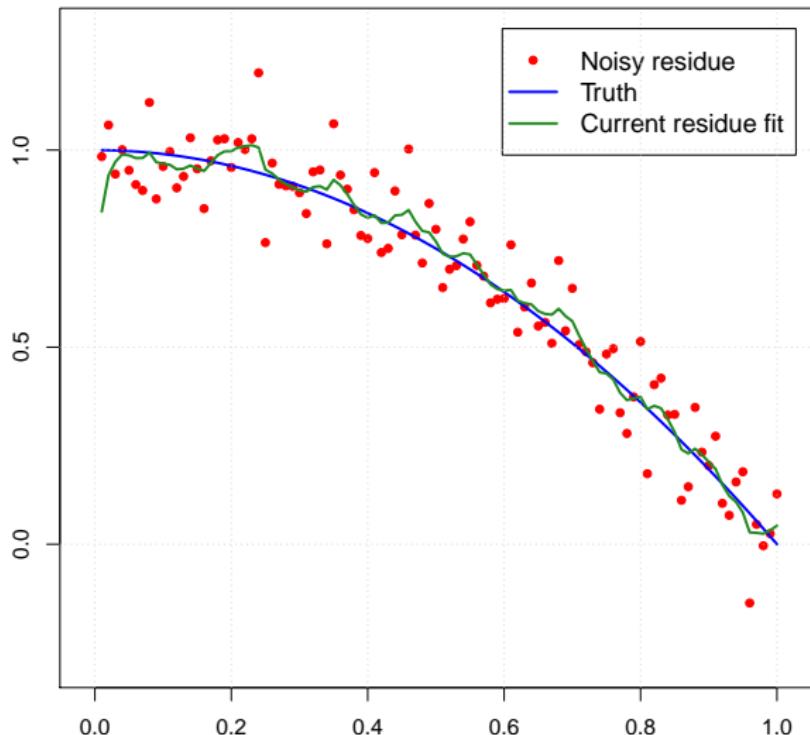
Boosting with a Laplacian kernel

Fit at round 3 of boosting



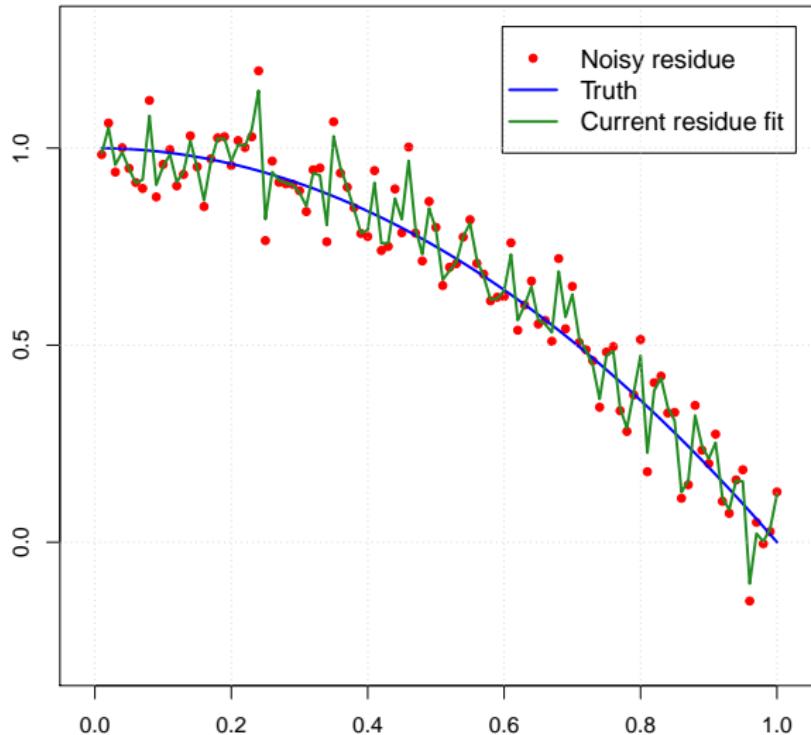
Boosting with a Laplacian kernel

Fit at round 6 of boosting



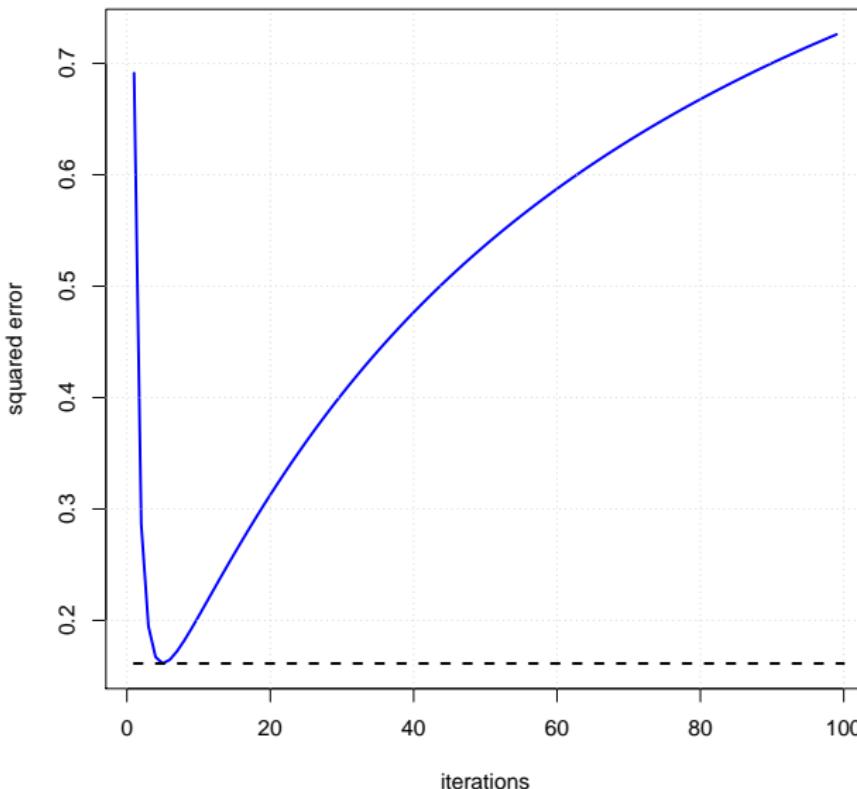
Boosting with a Laplacian kernel

Fit at round 100 of boosting



Mean-squared error $\|f^t - f^*\|_2^2$ versus iteration

MSE vs iteration

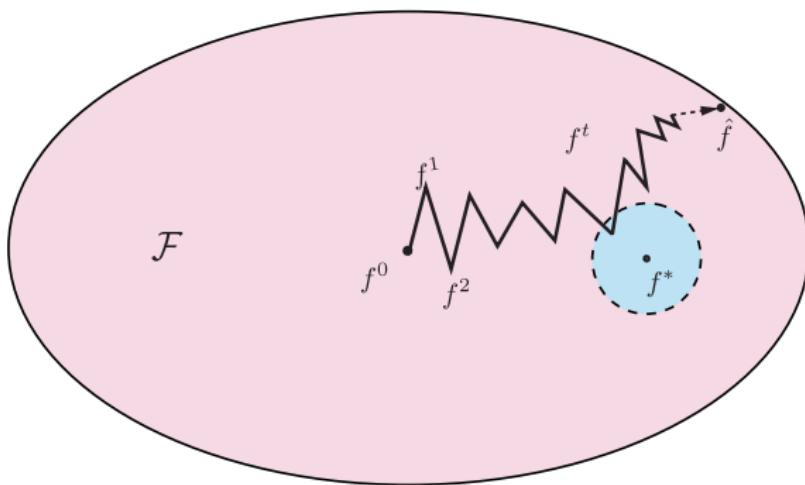


Early stopping for boosting

- ▶ Boosting algorithm:

$$f^{t+1} = f^t - \alpha^t \Pi_{\mathcal{F}}(\nabla \mathcal{L}_n(f^t))$$

Generate a sequence: $f^1, f^2, \dots, f^T, \dots, f^\infty$.



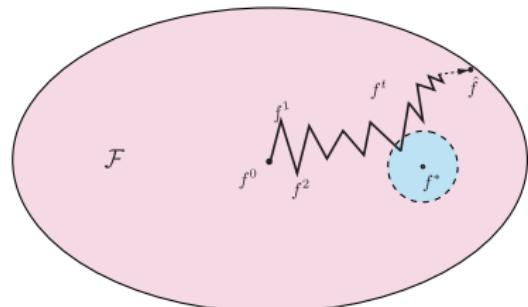
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What we would like:

Data-dependent stopping time T such that

$\mathcal{L}_n(f^T) \approx \mathcal{L}_n(f^*)$ where f^* is the population minimizer

$\|f^T - f^*\|_2 \rightarrow 0$ at the minimax-optimal rate as $n \rightarrow \infty$

Related results

- ▶ Consistency result of boosting algorithms
[Zhang'04, Zhang and Yu'05, Bartlett and Traskin'06, Bickel et al.'06]

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- ▶ Consistency result of boosting algorithms
[Zhang'04, Zhang and Yu'05, Bartlett and Traskin'06, Bickel et al.'06]
- ▶ Optimal rate
 - ▶ Bühlmann and Yu'03 proves optimality for early stopping of **ℓ_2 -boosting** for spline classes
 - ▶ Raskutti et al.'13 considers **ℓ_2 -boosting** for kernel classes and establishes connection to the localized Rademacher complexity

Main results

Theorem (W*, Yang* & Wainwright '17)

For any kernel class \mathcal{F} , any regular loss function and constant step size α , and any iterate $t = 1, 2, \dots, \lfloor \frac{1}{\delta_n^2} \rfloor$,

$$\underbrace{\mathcal{L}(\bar{f}^t) - \mathcal{L}(f^*)}_{\text{Excess loss}} \lesssim \underbrace{\frac{1}{\alpha t}}_{\text{Opt error}} + \underbrace{\delta_n^2}_{\text{Stat error}},$$

with high probability over the randomized realization.

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Statistical error is determined by **fixed point equation**:

$$\frac{1}{\sqrt{n}} \sqrt{\sum_{i=1}^n \min \left\{ 1, \frac{\mu_i}{\delta^2} \right\}} = \frac{\delta}{\sigma},$$

where μ_i are the eigenvalues of the kernel operator, and σ is the noise level.

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Function space \mathcal{F} :

- ▶ Reproducing kernel Hilbert space (RKHS) Wahba'90, Gu' 02, Berlinet and Thomas-Agnan'04
- ▶ Examples: splines functions, polynomials, Lipschitz functions, Sobolev functions...

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Loss functions:

- ▶ Regression (e.g. least squares)
- ▶ Classification (e.g. Logistic, Adaboost)

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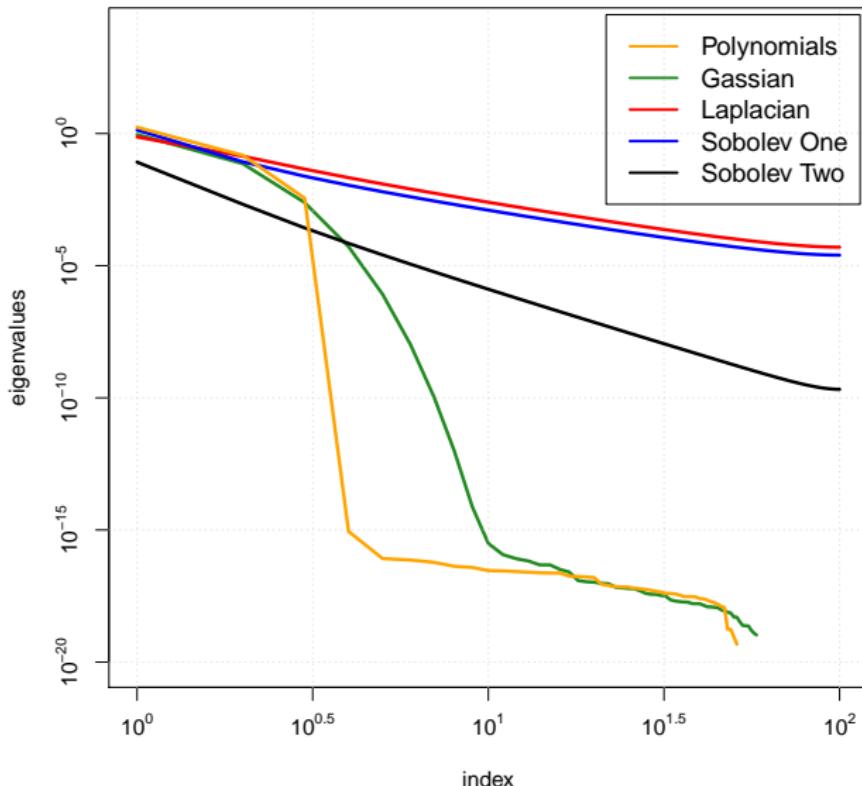
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Decay of kernel eigenvalues



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- ▶ Examples:

function class \mathcal{F}	δ_n^2
Polynomial with degree D	$\frac{D}{n}$
Gaussian kernel space	$\sqrt{\log n}$
Lipchitz functions	$n^{-2/3}$
β -smooth kernel space, d-dim	$n^{-\frac{2\beta}{2\beta+d}}$

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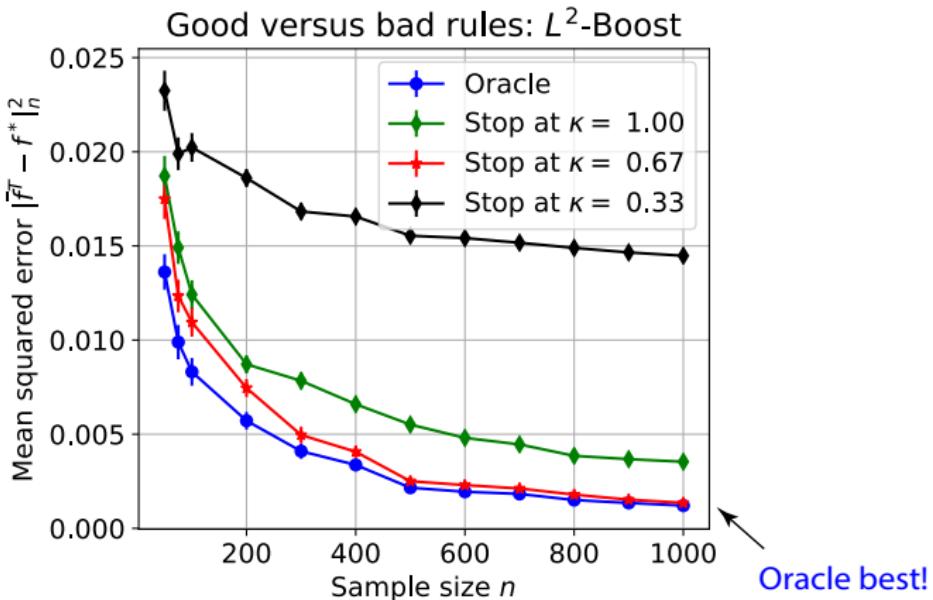
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Numerical results: Logit-Boost

- ▶ Setting: $\mathbb{P}(y_i = 1) = \frac{\exp(2f^*(x_i))}{1+\exp(2f^*(x_i))}$ where $f^*(x) = |x - \frac{1}{2}| - \frac{1}{4}$
- ▶ Stop after $\propto n^\kappa$ steps

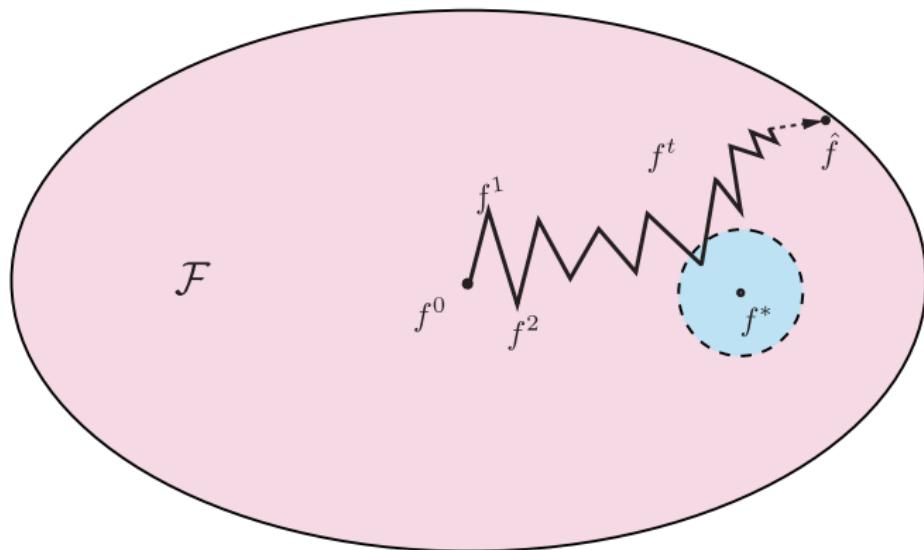
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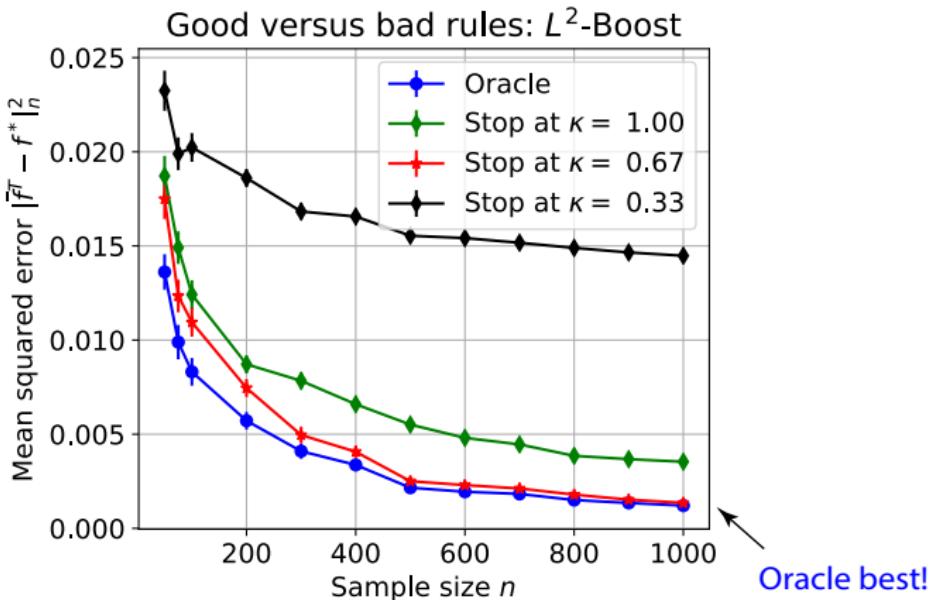
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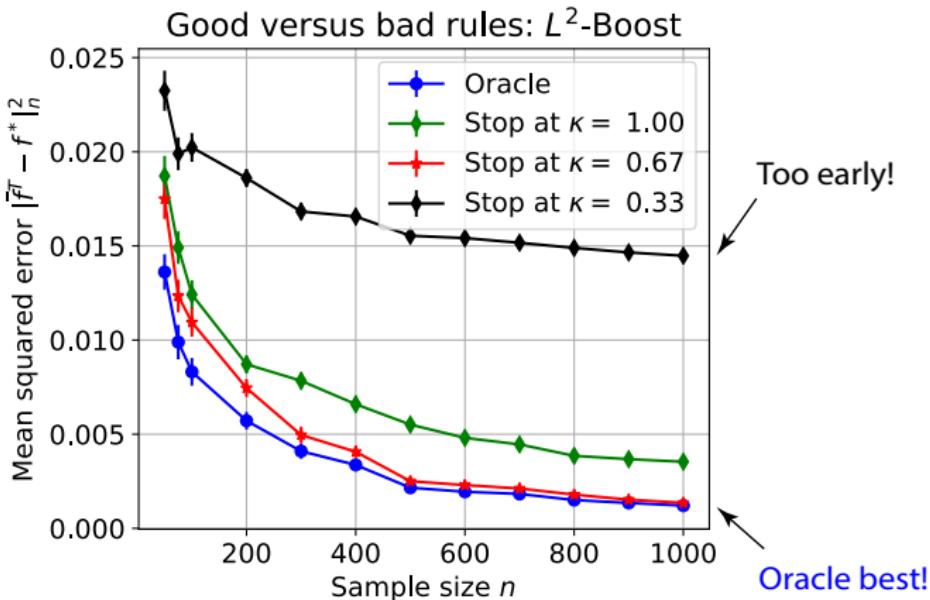
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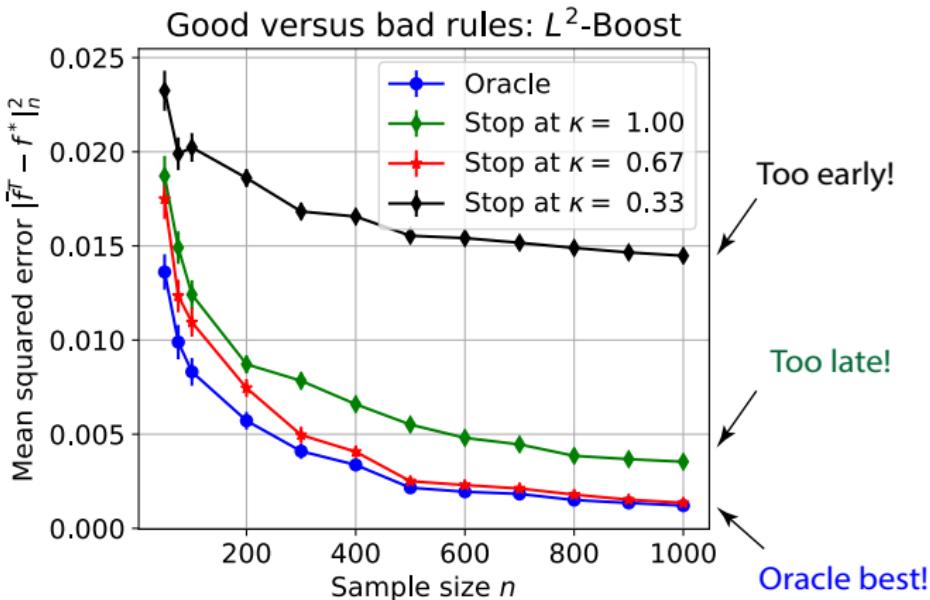
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- ▶ Setting: $\mathbb{P}(y_i = 1) = \frac{\exp(2f^*(x_i))}{1+\exp(2f^*(x_i))}$ where $f^*(x) = |x - \frac{1}{2}| - \frac{1}{4}$
- ▶ Stop after $\propto n^\kappa$ steps



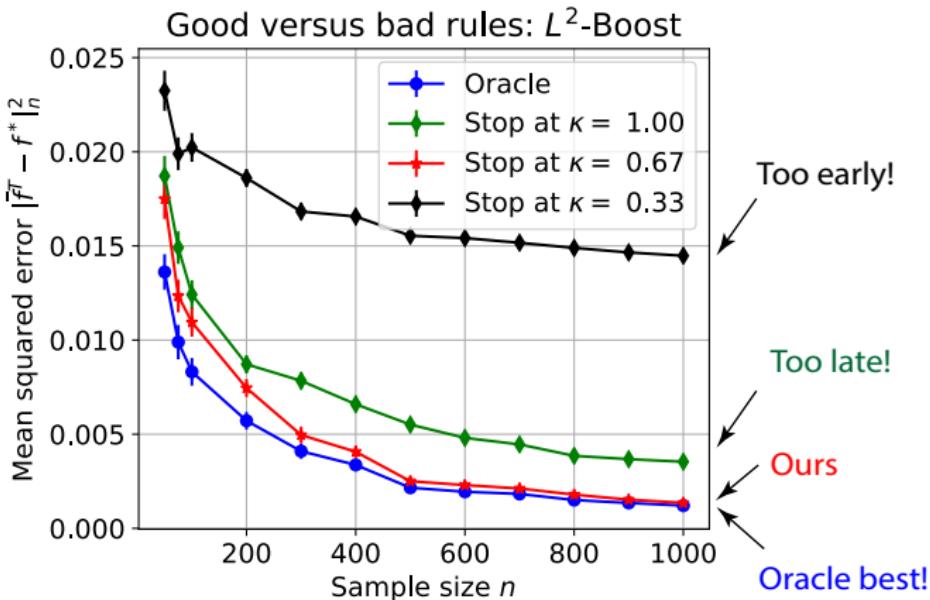
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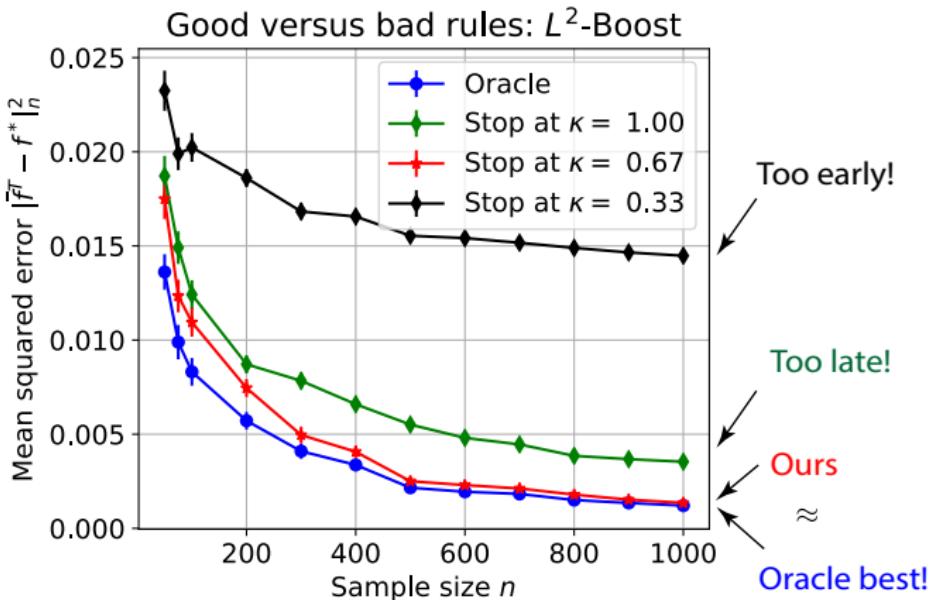
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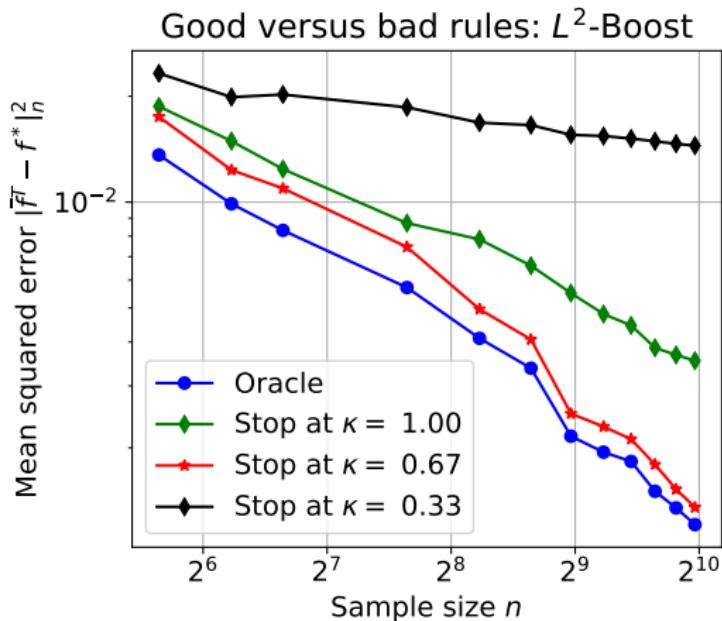
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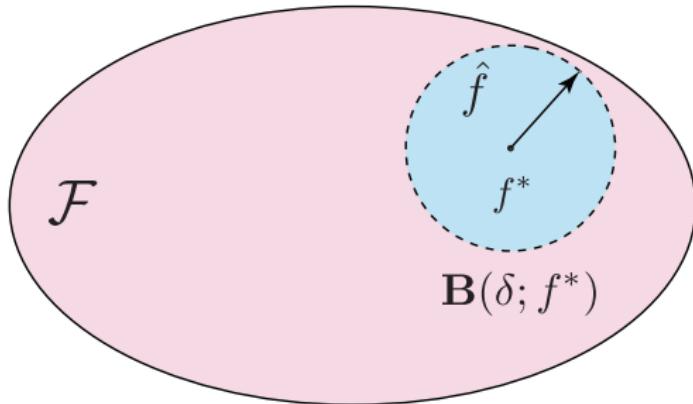


Numerical results: L^2 -Boost (logscale)

- ▶ Setting: $y_i = f^*(x_i) + w_i$ where $f^*(x) = |x - \frac{1}{2}| - \frac{1}{4}$
- ▶ Stop after $\propto n^\kappa$ steps



Tools for sharp analysis



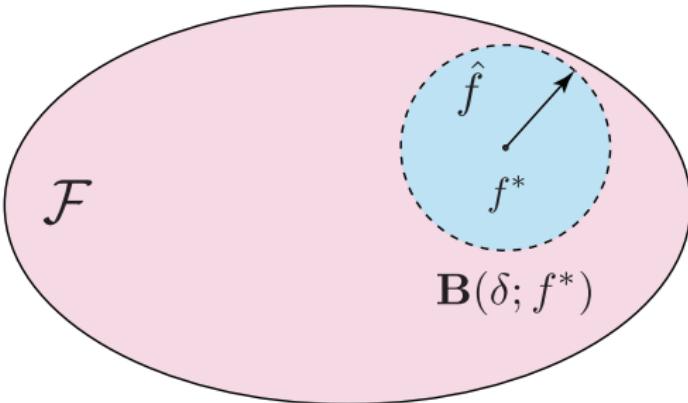
Gaussian complexity

How much you can align with i.i.d. noise sequence $\{w_i\}_1^n \sim N(0, 1)$?

$$\mathcal{G}_n(\cdot, \mathcal{F}) = \mathbb{E}_w \sup_{f \in \mathcal{F}} \left| \frac{1}{n} \sum_{i=1}^n w_i (f(x_i) - f^*(x_i)) \right|$$

(e.g., van de Geer'00, Bartlett et al.'05, Koltchinski '06)

Tools for sharp analysis



Localized Gaussian complexity

How much you can align with i.i.d. noise sequence $\{w_i\}_1^n \sim N(0, 1)$?

$$\mathcal{G}_n(\boxed{\delta}, \mathcal{F}) = \mathbb{E}_w \sup_{f \in \mathcal{F}} \left| \frac{1}{n} \sum_{i=1}^n w_i (f(x_i) - f^*(x_i)) \right|$$
$$\boxed{\|f - f^*\| \leq \delta}$$

(e.g., van de Geer'00, Bartlett et al.'05, Koltchinski '06)

Main results

Theorem (W*, Yang* & Wainwright '17)

For any kernel class \mathcal{F} , any regular loss function, constant step size α , and stopping criteria $T = \lfloor \frac{1}{\delta_n^2} \rfloor$, the excess loss

$$\mathcal{L}(\bar{f}^t) - \mathcal{L}(f^*) \lesssim \delta_n^2.$$

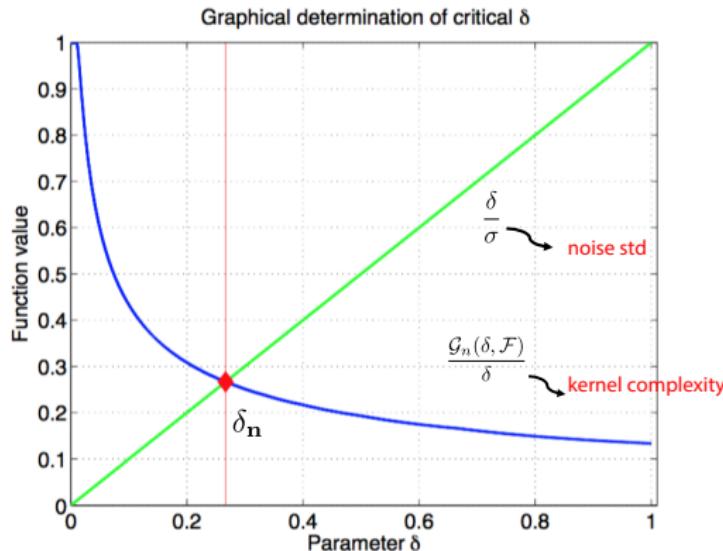
Statistical error is determined by **fixed point equation**:

$$\frac{1}{\sqrt{n}} \sqrt{\sum_{i=1}^n \min \left\{ 1, \frac{\mu_i}{\delta^2} \right\}} = \frac{\delta}{\sigma},$$

where μ_i are the eigenvalues of the kernel operator, and σ is the noise level.

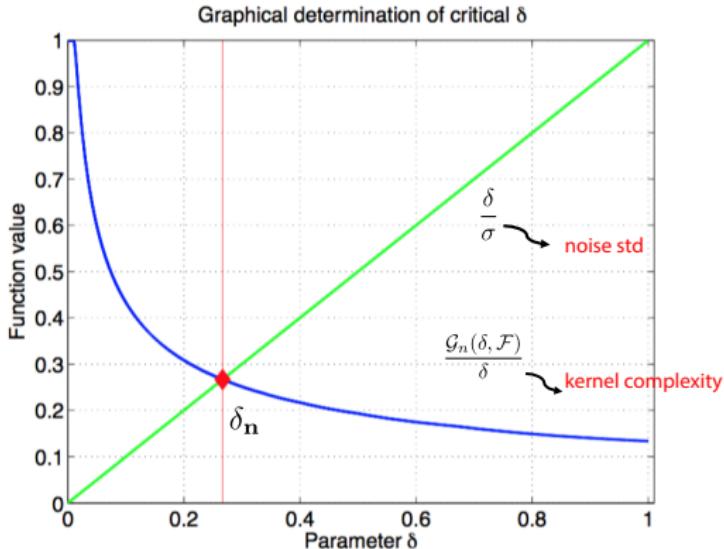
Fixed point equation

- ▶ Stopping rule T depends on critical radius δ_n



$$\frac{g_n(\delta, \mathcal{F})}{\delta} = \frac{\delta}{\sigma}$$

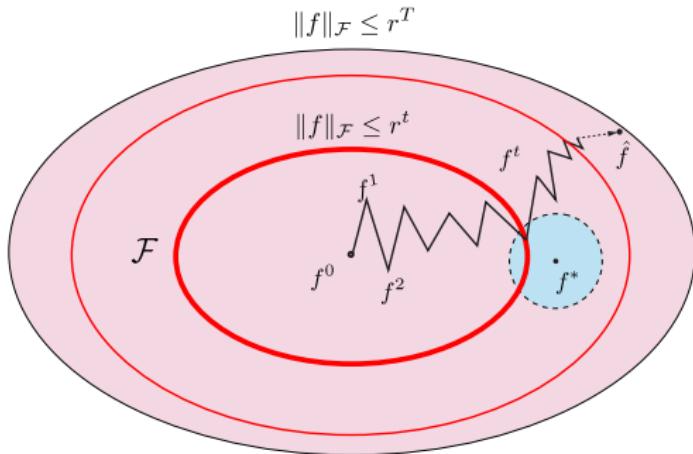
Fixed point equation



$$\frac{g_n(\delta, \mathcal{F})}{\delta} = \frac{\delta}{\sigma}$$

- ▶ penalized estimator \equiv early-stopped estimator

Geometric intuition in boosting analysis



- ▶ Boosted sequence $\{f^t\}_{t=1}^\infty$ takes a particular path
- ▶ Effective function classes \mathcal{F}^t explored at iteration t increases

Minimax optimality

Our early stopped estimator:

$$\mathcal{L}(\bar{f}^t) - \mathcal{L}(f^*) \lesssim \delta_n^2$$

Theorem (W*, Yang* & Wainwright '17)

Given any kernel class \mathcal{F} , and i.i.d. samples $\{y_i\}_{i=1}^n$ from a class of generalized linear model with some function f^* then

$$\inf_{\hat{f}} \sup_{\|f^*\|_{\mathcal{H}} \leq 1} \mathbb{E} \|\hat{f} - f^*\|_n^2 \gtrsim \delta_n^2.$$

(Yang et al.'17)

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Running time v.s. kernel complexity

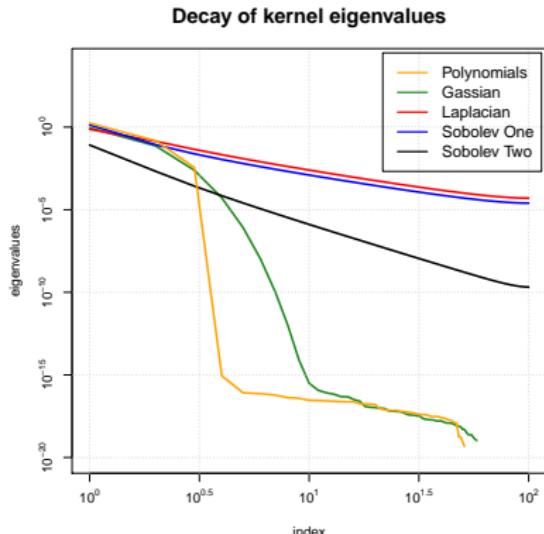
Table 1: Epochs to overfit (Laplacian)

Label	MNIST	SVHN	TIMIT
Original	4	8	3
Random	7	21	4

Table 2: Epochs to overfit (Gaussian)

Label	MNIST	SVHN	TIMIT
Original	20	46	7
Random	873	1066	22

Belkin et al.'18



Running time v.s. kernel complexity

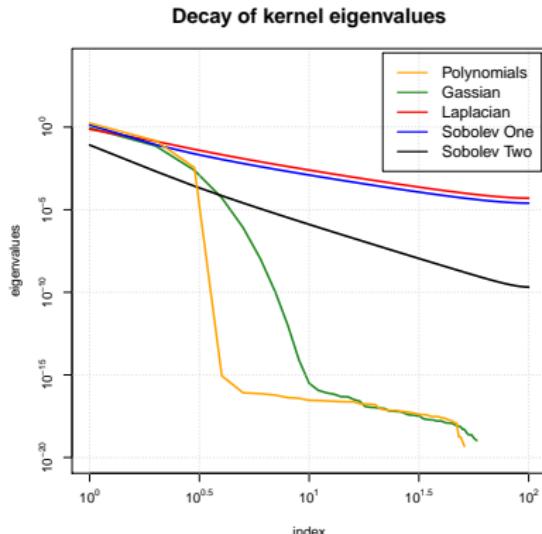
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Belkin et al.'18



Theoretically predicted running times to statistical precision:

Kernel	Laplacian	Gaussian
Time	$(\frac{n}{\sigma^2})^{2/3}$	$\frac{n}{\sigma^2}$

From kernels to neural networks

To Understand Deep Learning We Need to Understand Kernel Learning

Mikhail Belkin, Siyuan Ma, Soumik Mandal

Department of Computer Science and Engineering
Ohio State University

Kernel Methods for Deep Learning

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Neural Tangent Kernel: Convergence and Generalization in Neural Networks

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Conclusion

- ▶ An **effective** way of early-stopping for boosting algorithms

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- ▶ An **effective** way of early-stopping for boosting algorithms
- ▶ **Connection** between regularization through **penalization** and regularization through **early-stopping** over RKHS

Open questions

- ▶ Generalization ✓
 - ▶ $\bar{f}^t \rightarrow f^t$
 - ▶ kernel class → broader function classes

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 - ▶ $\bar{f}^t \rightarrow f^t$
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 - ▶ kernel class → broader function classes
- ▶ Boosting trees
- ▶ Non-convex loss functions

References

- ▶ Y. Wei, F. Yang, and M. J. Wainwright. (2017) Early stopping for kernel boosting algorithms: A general analysis with localized complexities. *NIPS'17* and arXiv (<https://arxiv.org/abs/1707.01543>)

Thanks! Questions?

Supplementary: RKHS

- ▶ Symmetric **kernel function** $\mathbb{K} : \mathcal{X} \times \mathcal{X} \rightarrow \mathbb{R}$
- ▶ RKHS is the closure of $f(\cdot) = \sum_{j \geq 1} \alpha_j \mathbb{K}(\cdot, x_j)$
- ▶ Reproducing relation

$$\langle f, \mathbb{K}(\cdot, x) \rangle_{\mathcal{F}} = f(x) \quad \text{for all } f \in \mathcal{F}$$

- ▶ Inner product

$$\langle f_1, f_2 \rangle_{\mathcal{F}} = \sum_{i=1}^{\ell_1} \sum_{j=1}^{\ell_2} \alpha_i \beta_j \mathbb{K}(x_i, x_j)$$

for $f_1(\cdot) = \sum_{i=1}^{\ell_1} \alpha_i \mathbb{K}(\cdot, x_i)$ and $f_2(\cdot) = \sum_{j=1}^{\ell_2} \beta_j \mathbb{K}(\cdot, x_j)$

back

Supplementary: Proof idea

Key lemma 1

For any stepsize and any iteration t we have

$$\frac{m}{2} \|\Delta^{t+1}\|_n^2 \leq \frac{1}{2\alpha} \left\{ \|\Delta^t\|_{\mathcal{F}}^2 - \|\Delta^{t+1}\|_{\mathcal{F}}^2 \right\} + \langle \nabla \mathcal{L}(\theta^* + \Delta^t) - \nabla \mathcal{L}_n(\theta^* + \Delta^t), \Delta^{t+1} \rangle.$$

Key lemma 2

With high probability, we have

$$\begin{aligned} & \langle \nabla \mathcal{L}(\theta^* + \tilde{\Delta}) - \nabla \mathcal{L}_n(\theta^* + \tilde{\Delta}), \Delta \rangle \\ & \leq 2\delta_n \|\Delta\|_n + 2\delta_n^2 \|\Delta\|_{\mathcal{F}} + \frac{m}{c} \|\Delta\|_n^2 \end{aligned}$$