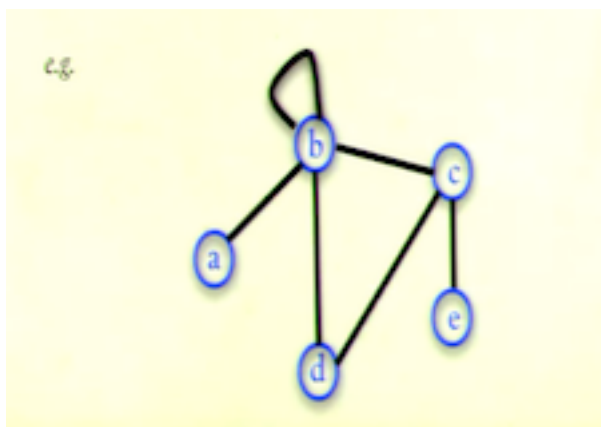


# Lecture 7: Graph Theory Review

## 1 Undirected Graphs

- An undirected graph  $G = (V, E)$  consists of :
  - A set  $V$  of **vertices** (or **nodes**).
  - A set  $E$  of **edges** (or **links**) denoting unordered vertex pairs.

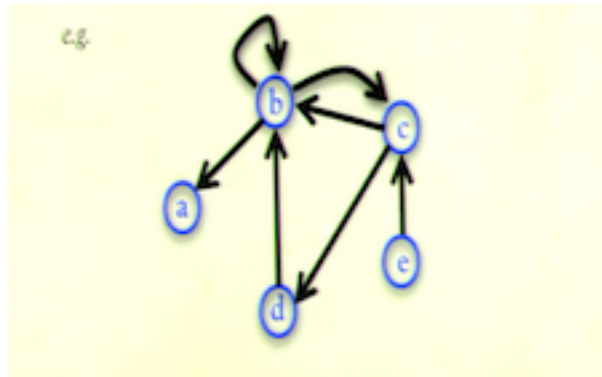


- We set  $n = |V|$  to be the cardinality of the vertex set.
- We set  $m = |E|$  to be the cardinality of the edge set.

## 2 Undirected Graphs

- A directed graph  $G = (V, E)$  consists of :
  - A set  $V$  of **vertices**.

- A set  $A$  of **arcs** (directed edges) denoting *ordered* vertex pairs.

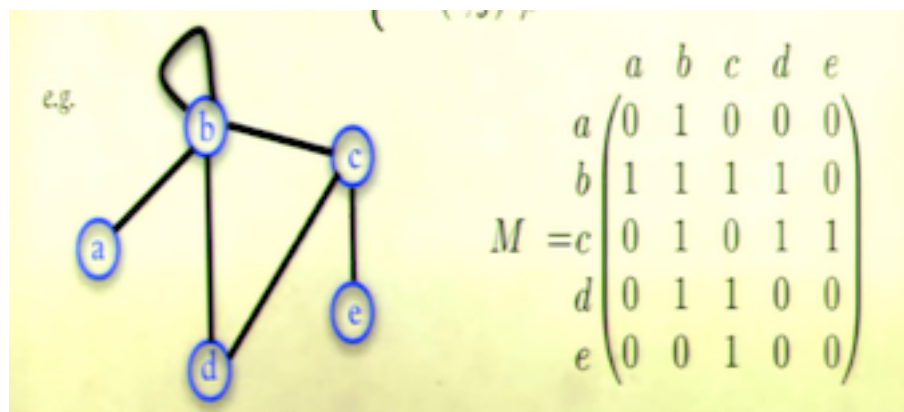


- We set  $n = |V|$  to be the cardinality of the vertex set.
- We set  $m = |A|$  to be the cardinality of the arc set.

### 3 Adjacency Matrix (Undirected Graphs)

- For an undirected graph, an **adjacency matrix**  $M$  has the properties that:
  - There is a **row** for each vertex.
  - There is a **column** for each vertex.
  - The  $ij$ -th **entry** of the matrix is defined by:

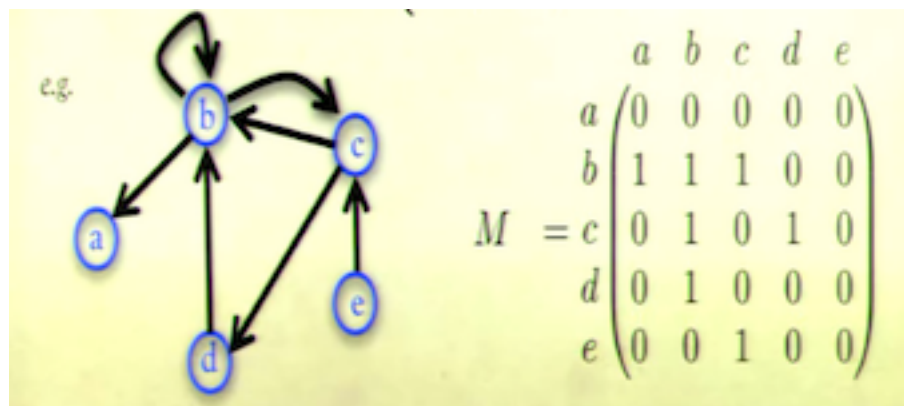
$$M_{ij} = \begin{cases} 1, & (i, j) \in E. \\ 0, & (i, j) \notin E. \end{cases}$$



## 4 Adjacency Matrix (Directed Graphs)

- For a directed graph, an **adjacency matrix**  $M$  has the properties that:
  - There is a **row** for each vertex.
  - There is a **column** for each vertex.
  - The  $ij$ -th **entry** of the matrix is defined by:

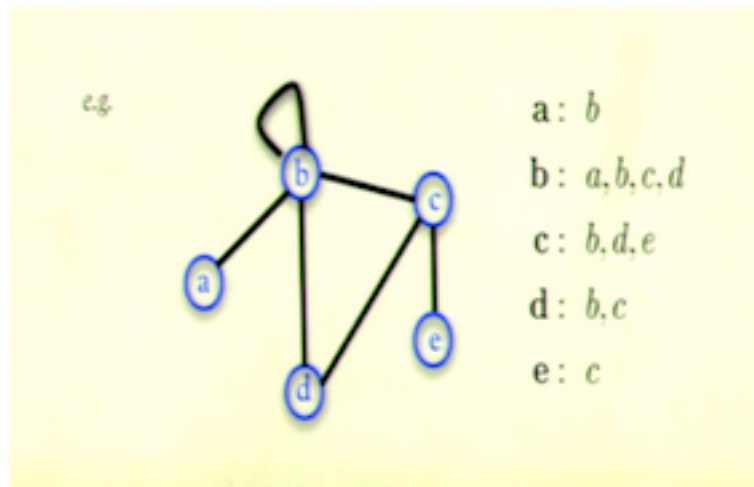
$$M_{ij} = \begin{cases} 1, & (i, j) \in A. \\ 0, & (i, j) \notin A. \end{cases}$$



Note: No longer symmetric as undirected graphs!

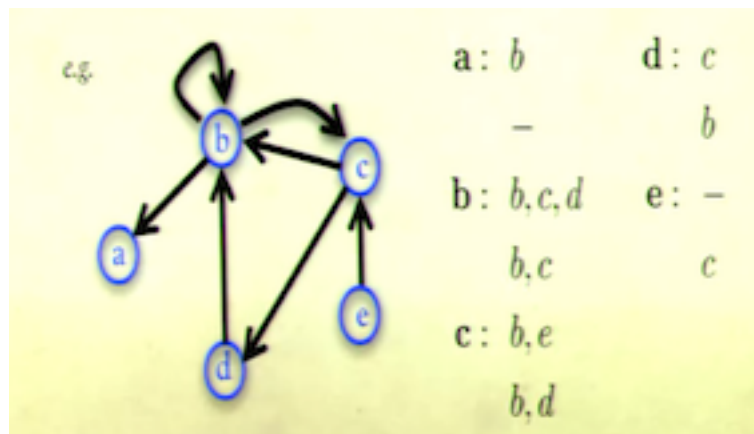
## 5 Adjacency Lists (Undirected Graphs)

- An undirected graph can also be stored using **adjacency lists**.
  - For each vertex  $i$ , we store a list of the **neighbours** of  $i$ .  
Neighbours: the set of vertices that  $i$  shares an edge with.
  - Equivalently, we store a list of the edges *incident* to each vertex.



## 6 Adjacency Lists (Directed Graphs)

- A directed graph can also be stored using **adjacency lists**.
    - For each vertex  $i$ , we store a list of the **in-neighbours** of  $i$ .
    - For each vertex  $i$ , we store a list of the **out-neighbours** of  $i$ .
- In-neighbours: the set of vertices with arcs that point to  $i$ .  
 Out-neighbours: the set of vertices that  $i$  has arcs pointing to



## 7 Adjacency Lists versus Adjacency Matrices

- The main difference is in the amount of **storage** required
  - An *adjacency* matrix requires storing  $\Theta(n^2)$  numbers.
  - An *adjacency* list requires storing  $\Theta(m)$  numbers.
    - Each arc will appear twice in a list.
- In any graph  $m = O(n^2)$  and often  $m \ll n^2$ 
  - In **sparse graphs** it is much more preferable to use adjacency lists.

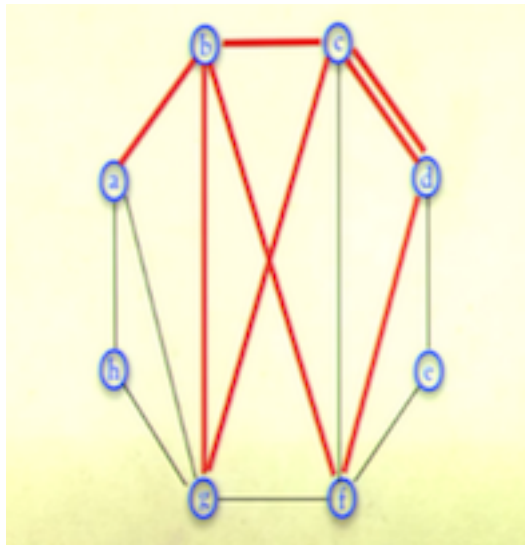
## 8 Graph Application

- The number of practical applications for is very large.
- Obviously there are useful in modelling networks.
  - Transportation Networks: e.g. Roads.
  - Social Networks: e.g. Facebook Graph.
  - Information Networks: e.g. the World Wide Web.
  - Financial Networks: e.g. Monetary Flows.
- But, their flexibility allows them to model a plethora of diverse applications:
  - Hierarchy: data structures, linguistics.
  - Similarity: data clustering, biology.
  - Conflict: wavelength allocation, scheduling.
  - Priority: industrial planning, operations research.
  - Structure: chemistry, physics.
  - Time Relations: evolution, migration patterns.

## 9 Graph Structure

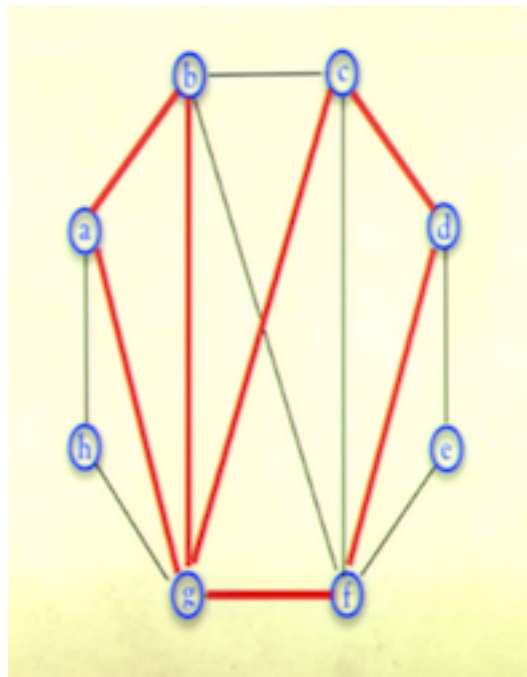
- Walks

- A **walk** is list of vertices  $\{v_0, v_1, \dots, v_l\}$  such that  $(v_i, v_{i+1}) \in E$  for all  $0 \leq i < l$ .

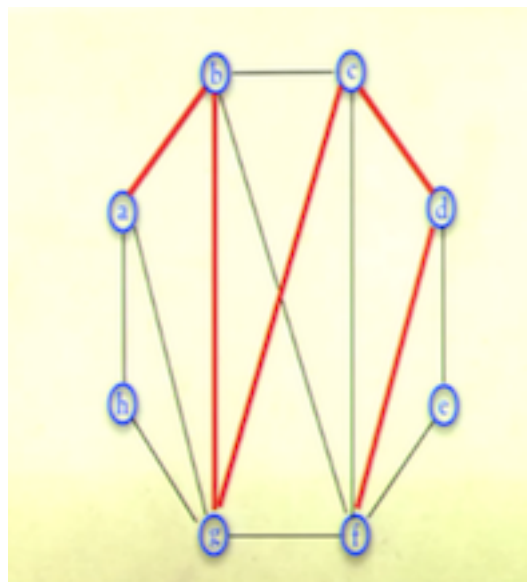


- Circuits

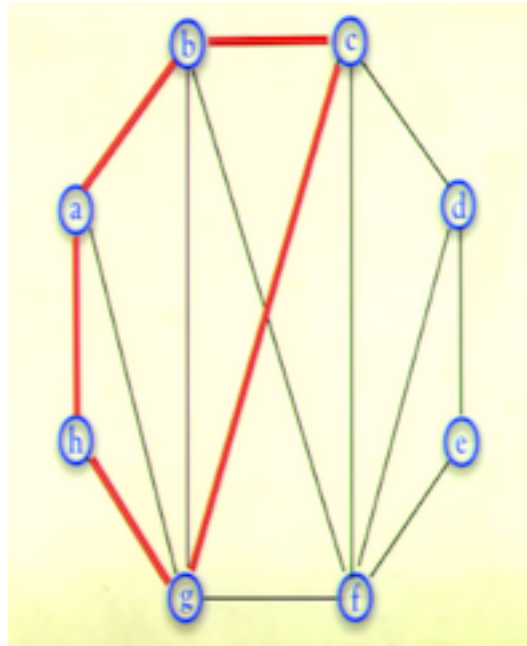
- A **circuit** is a walk  $\{v_0, v_1, \dots, v_l\}$  where  $v_0 = v_l$ .
- A circuit is a **closed** walk.
- We are not allowed to use same edge/arc more than once.
- An **Eulerian Circuit** is a circuit that uses every edge exactly once.



- Paths
  - A **path** is a walk where every vertex is distinct.
  - Revisit is not allowed.



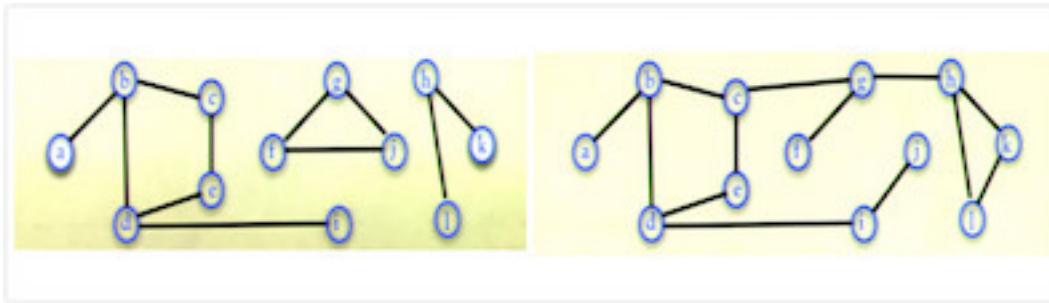
- Cycles
  - A **cycle** is a walk  $\{v_0, v_1, \dots, v_l\}$  where every vertex is distinct except for the end-vertices  $v_0 = v_l$ .
  - A cycle is a **closed** path.
  - An **Hamiltonian Cycle** is a cycle that uses every vertex exactly once.



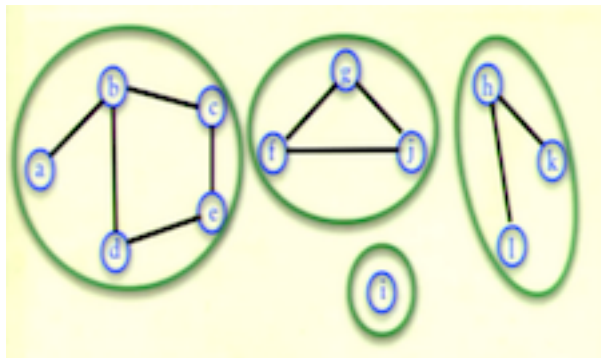
## 10 Connected Graphs

- A graph is **connected** if for every pair of vertices  $u, v \in V$ , it is possible to walk from u to v.
- A graph is **disconnected** if there exists a pair of vertices  $u, v \in V$ , for which there is no possible walk from u to v.



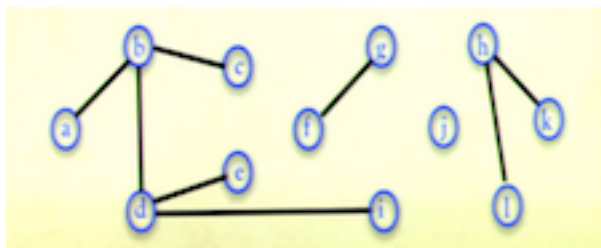


- Graph Components
  - A connected subgraphs are called the **components** of the graph.
  - Thus a connected graph has exactly one component.



## 11 Trees

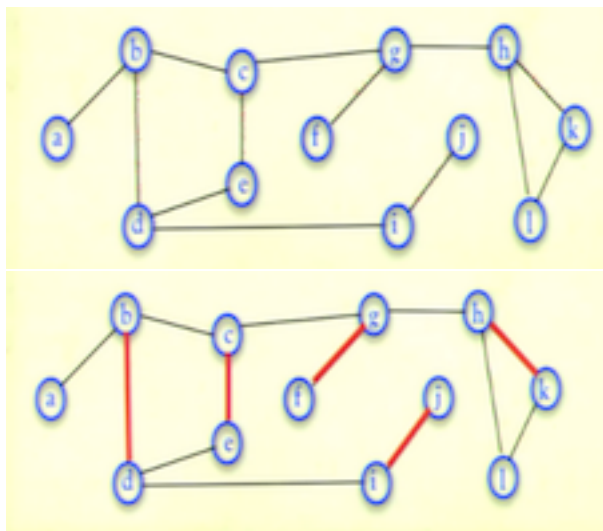
- A **tree** is a connected component with no cycles.
- A **forest** is a graph whose components are all trees.
- A tree is **spanning** if it contains every vertex in the graph.





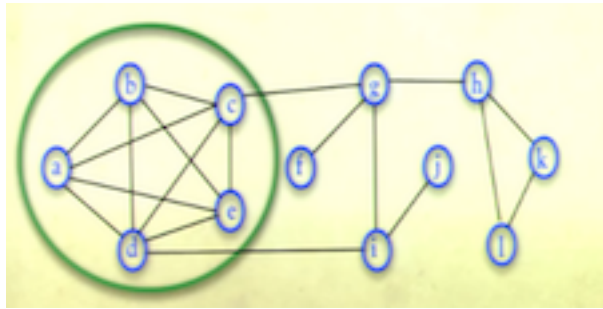
## 12 Matchings

- A **matching** is a set of vertex-disjoint edges.
- Hence, each vertex is incident to at most one edge in the matching.
- A matching is **perfect** if every vertex is incident to an edge in the matching.



## 13 Cliques

- A **clique** is a set of pairwise adjacent vertices.



## 14 Independent Sets

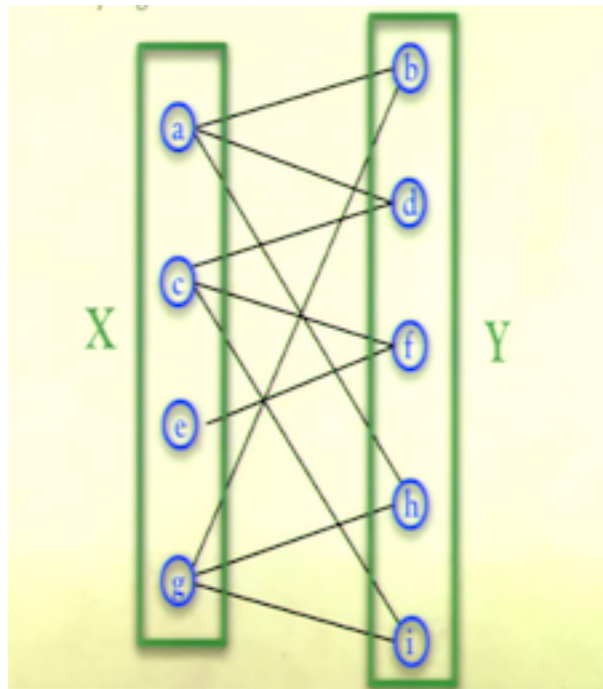
- An **independent set** (**stable set**) is a set of pairwise non-adjacent vertices.
- If you find a stable set, then there is no conflict. (Assume the graph representing conflicts.)



(c, f, j, l)

## 15 Bipartite Graphs

- In a **bipartite graph** the vertex set can be partitioned as  $V = X \cup Y$  such that every edge has one end-vertex in  $X$  and one end-vertex in  $Y$ .



Note that X and Y are both independent sets.

## 16 Some Theorems on Undirected Graphs

- The Handshaking Lemma
  - Let  $\tau(v) = \{u : (u, v) \in E\}$  be the set of neighbours of  $v$ .
  - The degree,  $\deg(v)$ , of a vertex  $v$  is the cardinality of  $\tau(v)$ .

**The Handshaking Lemma.** In an undirected graph, there are an even number of vertices with odd degree.

**Proof.**

- We have:

$$2 \cdot |E| = \sum_{v \in V} \deg(v)$$

(Double count the number of pairs  $(v, e)$  where  $e$  is an edge incident to  $v$ .)

$$= \sum_{v \in O} \deg(v) + \sum_{v \in E} \deg(v)$$

( $O$  is the set of vertices with odd degree, and  $\varepsilon$  is the set of vertices with even degree.)

$$\Rightarrow \sum_{v \in O} \deg(v) = 2 \cdot |E| - \sum_{v \in \varepsilon} \deg(v)$$

Even = Even - Even

## 17 Euler's Theorem

- The first result in Graph Theory is the following.

**Theorem.** An undirected graph contains an Euler Circuit if and only if every vertex has an even degree.

**Proof.** Exercise! (Use induction.)

## 18 A Theorem on Trees

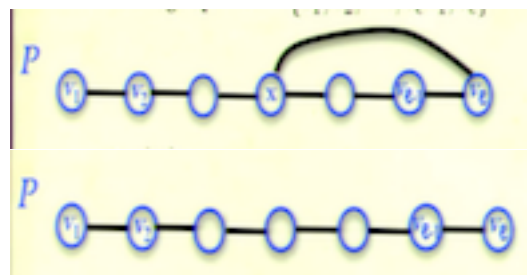
- Leaves

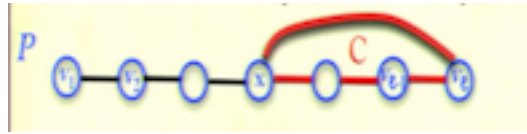
- A vertex with degree one in a tree is called a **leaf**.

**Lemma.** A tree  $T$  with  $n \geq 2$  vertices has at least one leaf vertex.

**Proof.**

- A tree is connected  $\Rightarrow$  There are no vertices with degree 0 as  $n \geq 2$ .
- For a contradiction, assume every vertex has degree at least 2.
- Take the **longest path**  $P = \{v_1, v_2, \dots, v_{l-1}, v_l\}$  in  $T$ .
- But  $\deg(v_k) \geq 2$  so  $v_l$  has a neighbour  $x \neq v_{l-1}$
- We must have  $x = v_j$  for some  $1 \leq j \leq l-2$  otherwise  $\{v_1, v_2, \dots, v_l, x\}$  is a longer path than  $P$ .
- But then  $C = \{x = v_j, v_{j+1}, \dots, v_l, x\}$  is a cycle, contradiction.





- The Number of Edges in a Tree

**Theorem.** A tree with  $n$  vertices has  $n-1$  edges.

**Proof.**

- Let's prove this by induction.

Base Case:

- A tree on **one** vertex has **zero** edges.

Induction Hypothesis:

- Assume that any tree on  $n-1$  vertices has  $n-2$  edges.

Induction Step:

- Take a tree  $T$  with  $n \geq 2$  vertices.
- By the previous lemma, this tree contains a **leaf** vertex  $v$ .  
 $\Rightarrow T \setminus \{v\}$  is a tree on  $n-1$  vertices.  
 $\Rightarrow$  By the induction hypothesis,  $T \setminus \{v\}$  is a tree on  $n-2$  vertices.  
 $\Rightarrow T$  is a tree with  $n-1$  edges.

## 19 Hall's Theorem

- How do we know if a bipartite graph  $G = (X \cup Y, E)$  contains a **perfect matching**?
- This is actually easy to test using Hall's Condition.

Hall's Condition:  $\forall B \subseteq X, |\tau(B)| \geq |B|$

**Hall's Theorem.** A bipartite graph, with  $|X| = |Y|$ , contains a perfect matching if and only if Hall's condition is satisfied.

**Proof.**

$(\Rightarrow)$

- If there is a set  $B \subseteq X$  with  $|\tau(B)| < |B|$  then the graph **cannot** have a perfect matching.

( $\Leftarrow$ )

- Suppose Hall's Condition is satisfied:  $\forall B \subseteq X, |\tau(B)| \geq |B|$
- Take a **maximum cardinality** matching  $M$  in the graph.
- If  $M$  is perfect we are done.
- So we may assume  $M$  is not perfect and there is an **unmatched** vertex  $b_0$  in  $X$ .
- As Hall's condition holds we have:  $|\tau(\{b_0\})| \geq |\{b_0\}| = 1$
- So  $b_0$  has at least one neighbour  $s_0$
- Let  $s_0$  be matched to  $b_1$  in  $M$
- As Hall's condition holds we have:  $|\tau(\{b_0, b_1\})| \geq |\{b_0, b_1\}| = 2$
- So either  $b_0$  or  $b_1$  has a neighbour  $s_1 \neq s_0$