

# Lecture 8: Graph Algorithms: Breadth First Search

## 1 Graph Exploration

- Given a graph and two specified vertices  $r$  and  $v$ , a fundamental question is:
  - Does the graph contain a path from  $r$  to  $v$ ?
- In fact, given a root vertex  $r$ , we will be able to answer this question simultaneously for all non-root vertices.
- That is, we can efficiently determine which vertices are reachable by **path traversal** starting at the root vertex.

## 2 Search Applications

- Graph Search has a **vast** number of applications.
- These can be simple applications:
  - How do we explore a maze?
  - How do I travel from Montreal to Toronto?
- Or, they can be much more substantive.
  - What is the best way to search the web?
  - How, and how far, will a disease spread through the population?

### 3 The Generic Search Algorithm

- The Generic Search Algorithm:

The Search Algorithm

Put  $r$  into a bag

**While** the bag is non-empty

    Remove  $v$  from the bag

    If  $v$  is unmarked

        Mark  $v$

        For each  $\text{arc}(v, w)$

            Put  $w$  into the bag

- Formal pseudocode:

Search( $r$ )

Set  $B = \{r\}$

While  $B \neq \emptyset$

    Let  $v \in B$

    Set  $B \leftarrow B \setminus \{v\}$

    If  $v$  is unmarked

        Mark  $v$

        For each  $\text{arc}(v, w)$

            Set  $B \leftarrow B \cup \{w\}$

- We can view a vertex as having been discovered when it is **marked**.
- We will see that if the graph is connected then every vertex is discovered.
- But first observe that there are one **strange** thing about this algorithm.
  - We add a vertex to the bag when it is the end-point of an examined edge.  
→ Multiple copies of a vertex may be in the bag!
- Surprisingly this will not affect the performance of the algorithm.
  - Indeed, this will actually be useful to us if we modify the algorithm to account for this by "bagging" edges instead of vertices.

## 4 The Revised Generic Search Algorithm

- Updated algorithm:

The Search Algorithm

Put  $(*, r)$  into a bag

**While** the bag is non-empty

    Remove  $(u, v)$  from the bag

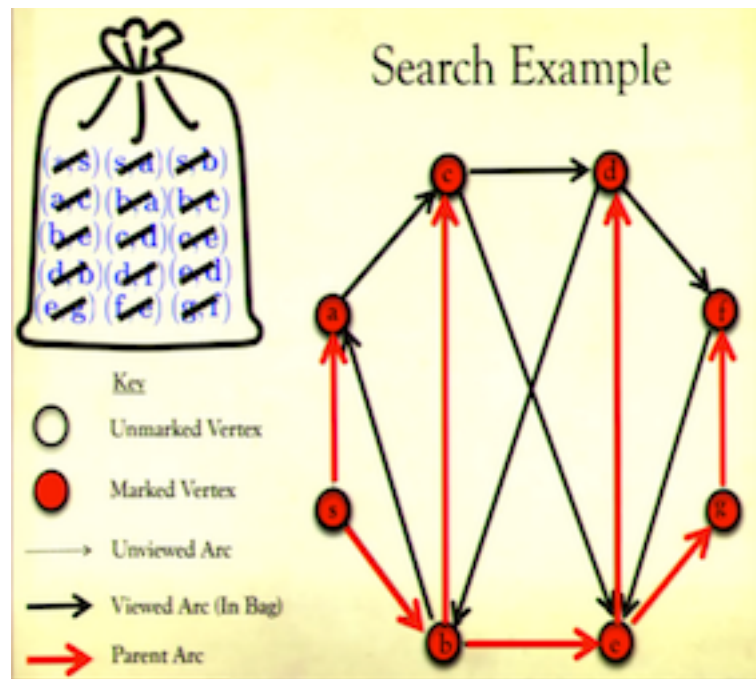
    If  $v$  is unmarked

        Mark  $v$

        Set  $p(v) \leftarrow u$  (*Keep track of the predecessor*)

        For each arc  $(v, w)$

            Put  $w$  into the bag



- Running Time:
  - We search each arc out of  $v$  only once, when  $v$  is first marked.
  - The arc is then added to the bag once and later removed from the bag once.
  - Runtime =  $O(m)$

- Linear time algorithm.
- Validity

**Theorem.** Let  $G$  be a connected, undirected graph. Then the search algorithm finds every vertex in  $G$ .

**Proof.**

- We must show that each vertex  $v$  is **marked** by the search algorithm.
- We prove this by induction on the smallest number  $k$  of edges in a path from the vertex to the root.

Base Case:  $k = 0$

- Then  $v$  is the root vertex  $r$ .
- But  $r$  is the first vertex marked in the algorithm, so the base case holds.

Induction Hypothesis:

- Assume any vertex  $v$  that has a path of  $(k - 1)$  (or fewer) edges to the root  $r$  is marked.

Induction Step:

- Assume there is a path  $P$  with  $k$  edges from  $v_k$  to  $r$ . Specifically let

$$P = \{v = v_k, v_{k-1}, \dots, v_1, v_0 = r\}$$

- Thus there is a path  $Q$  with  $(k - 1)$  edges from  $u = v_{k-1}$  to  $r$ . That is.

$$Q = \{u = v_{k-1}, \dots, v_1, v_0 = r\}$$

- So, by the induction hypothesis, the vertex  $u$  is marked.
- After we mark  $u$ , we place the edges incident to it in the bag,
  - The edge  $(u, v)$  is added to the bag.
- Thus, when  $(u, v)$  is removed from the bag we will mark  $v$ . (If it is not already marked.)
- Validity in Directed Graphs
  - For directed graphs, a similar argument proves that each vertex that has a directed path to it from the root  $r$  is **marked**.

## 5 Search Tree

- Observe that each non-root vertex has exactly one predecessor.

**Theorem.** Let  $G$  be a connected, undirected graph. Then the predecessor edges form a tree rooted at  $r$ .

**Proof.**

- By induction on the number of  $k$  of marked vertices.

Base Case:  $k = 1$

- Then  $v$  is the first vertex marked.  
→ So the base case holds.

Induction Hypothesis:

- Assume the predecessor edges for the first  $(k - 1)$  marked vertices form a tree rooted at  $r$ .

Induction Step:

- Let  $v$  be the  $k$ th vertex to be marked.
- Assume  $v$  was marked when we removed the edge  $(u, v)$ .  
→  $u = p(v)$
- But  $(u, v)$  was added to the bag when we marked vertex  $u$ .  
→ Vertex  $u$  is in the set  $S$  of the first  $(k - 1)$  vertices to be marked.
- By the induction hypothesis, the predecessor edges for  $S$  form a tree  $T$  rooted at  $r$ .
- $T \cup (p(v), v)$  is a tree rooted at  $r$  on the first  $k$  marked vertices.

## 6 Implementational Aspects

- There is some flexibility in how to implement the search algorithm?
  - If the bag contains many arcs, which one should we remove?
- In fact, what in computer science is a "bag"?
- The "bag" is just short-hand for a data structure.

- Moreover, the choice of data structure used has important consequences.
- Three choices of data structure for the bag give fundamental algorithms:
  - Queue: Breadth First Search
  - Stack: Depth First Search
  - Priority Queue: Minimum Spanning Tree Algorithm

## 7 Breadth First Search

- Using a **Queue** (FIFO) data structure produces:  
Breadth First Search Algorithm

Add  $(*, r)$  to a Queue

**While** the Queue is non-empty

Remove the first arc  $(u, v)$  from the Queue

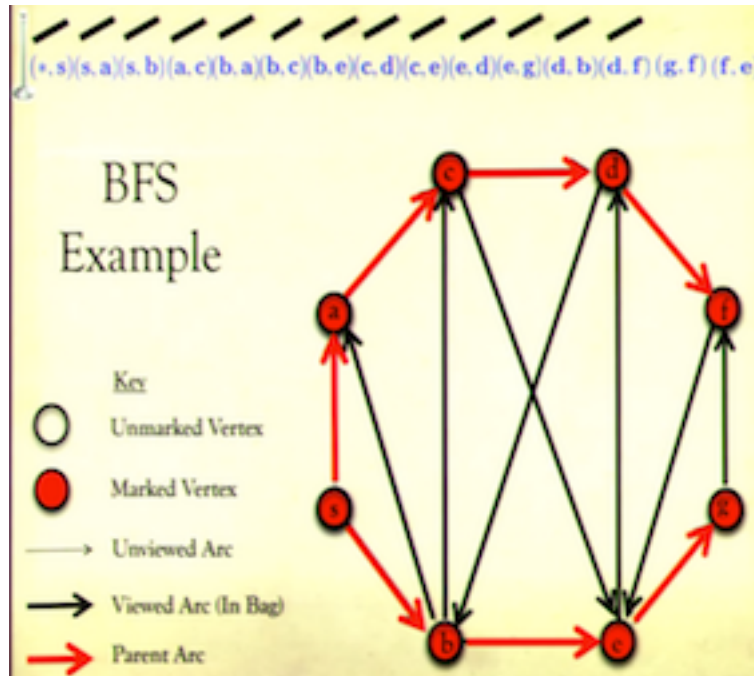
If  $v$  is unmarked

Mark  $v$

Set  $p(v) \leftarrow u$

For each arc  $(v, w)$

Add  $(v, w)$  into the back of the Queue

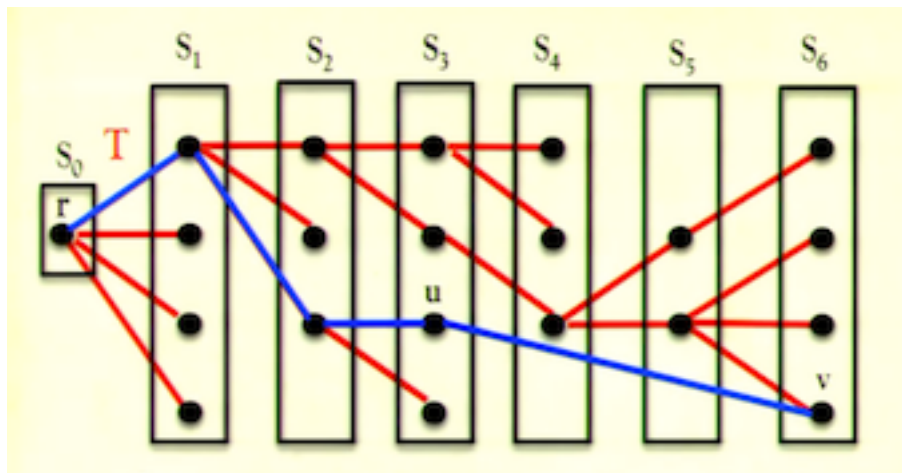


## 8 Breadth First Search Trees

- Because BFS uses a queue it is easy to verify that:
  - The edges are added to the queue in order of their distance from  $r$ /
  - The vertices are marked in order of their distance from  $r$ .
- Specifically:
 

**Theorem.** For any vertex  $v$ , the path from  $v$  to  $r$  given by the search tree  $T$  of predecessor edges is a shortest path.

Exercise: Verify this formally.
- Structure:
  - Let  $S_l$  be the set or "layer" of vertices at distance  $l$  from  $r$  in  $T$ .
  - Then a vertex  $v \in S_l$  is also at distance  $l$  from  $r$  in the whole graph  $G$ .
    - Thus implies for every non-tree edge  $(u, v)$ ,  $u$  and  $v$  are either in the same layer or in adjacent layers.
    - If not, we can find a shorter path to the root from  $u$  or  $v$ .



## 9 BFS and Bipartite Graphs

- Recall in a **bipartite graph** the vertex set can be partitioned as  $V = X \cup Y$  such that every edge has one end-vertex in  $X$  and one end-vertex in  $Y$ .

**Theorem.** A graph  $G$  is bipartite if and only if it contains no odd length cycles.

**Proof.**

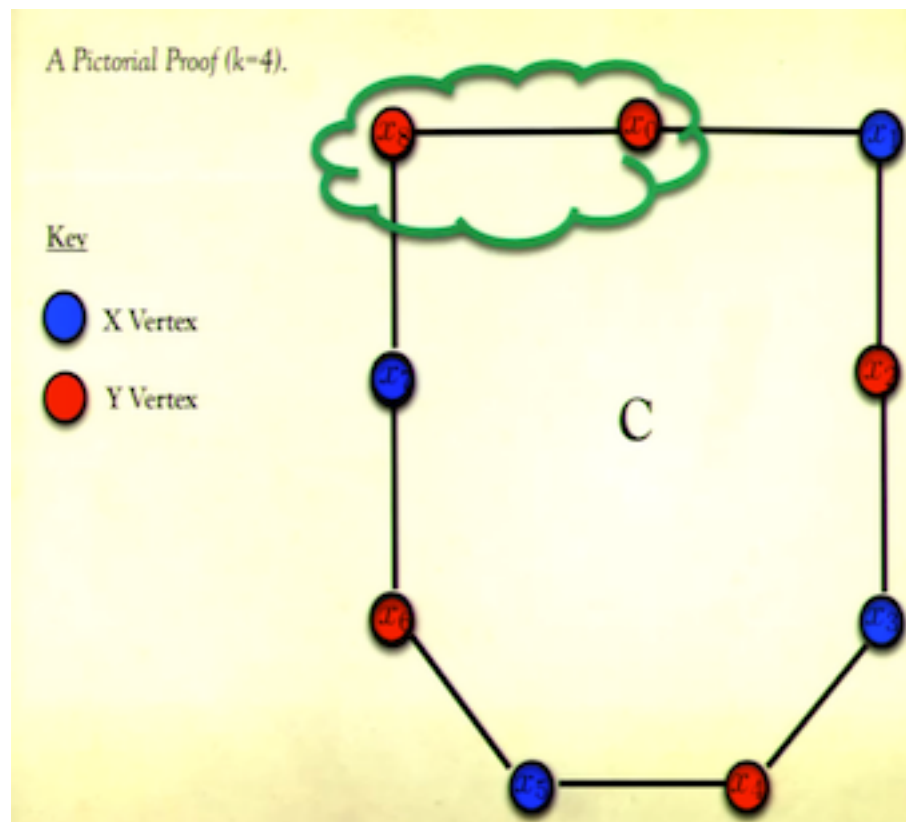
( $\Rightarrow$ )

- Assume  $G$  contains as a subgraph an odd length cycle  $C$ .
- let  $C = \{v_0, v_1, v_2, \dots, v_{2k}\}$
- Wlog we may assume vertex  $v_0 \in Y$ . Therefore:

$$v_0 \in Y \Rightarrow v_1 \in Y \Rightarrow \dots \Rightarrow v_{2k} \in Y$$

- But  $(v_0, v_{2k}) \in E$ . Thus

$$v_0 \in Y \Rightarrow v_{2k} \in Y$$





( $\Leftarrow$ )

- Assume  $G$  contains no odd length cycles.
- Select an arbitrary root vertex  $r$  and run the BFS algorithm.
- Recall that for every non-tree edge  $(u, v)$ ,  $u$  and  $v$  are either in the same layer or in adjacent layers.
- Now set:

$$X = \bigcup_{l \text{ odd}} S_l \quad Y = \bigcup_{l \text{ even}} S_l$$

- Suppose, for every non-tree edge  $(u, v)$ , that  $u$  and  $v$  are in adjacent layers.
- Now, for every tree edge  $(u, v)$  we also have  $u$  and  $v$  in adjacent layers.
- So assume, there is non-tree edge  $(u, v)$  with  $u$  and  $v$  in the same layer.
- Let  $z$  be the closest common ancestor of  $u$  and  $v$  in the search tree  $T$ .
- Let  $P$  be the path in  $T$  from  $u$  to  $z$ ; let  $Q$  be the path in  $T$  from  $v$  to  $z$ .
- Since  $u$  and  $v$  in the same layer we have:  $|P| = |Q|$
- But then the cycle  $C = P \cup Q \cup (u, v)$  has an odd number of edges as:

