

Probability

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1 Probability Spaces

1.1 Classical Probability Spaces

Textbook probability theory [1, 2, 3] is defined using the notions of a *sample space* Ω , a space of *events* \mathcal{F} , and a *probability measure* μ . In this paper, we will only consider *finite* sample spaces: we therefore define a sample space Ω as an arbitrary non-empty finite set and the space of events \mathcal{F} as, 2^Ω , the powerset of Ω . A *probability measure* is a function $\mu : \mathcal{F} \rightarrow [0, 1]$ such that:

- $\mu(\Omega) = 1$, and
- for a collection of pairwise disjoint events E_i , we have $\mu(\bigcup E_i) = \sum \mu(E_i)$.

Example 1 (Two coin experiment). Consider an experiment that tosses two coins. We have four possible outcomes that constitute the sample space $\Omega = \{HH, HT, TH, TT\}$. The event that the first coin is “heads” is $\{HH, HT\}$; the event that the two coins land on opposite sides is $\{HT, TH\}$; the event that at least one coin is tails is $\{HT, TH, TT\}$. Depending on the assumptions regarding the coins, we can define several probability measures. Here is a possible one:

$\mu(\emptyset)$	$= 0$	$\mu(\{HT, TH\})$	$= 2/3$
$\mu(\{HH\})$	$= 1/3$	$\mu(\{HT, TT\})$	$= 0$
$\mu(\{HT\})$	$= 0$	$\mu(\{TH, TT\})$	$= 2/3$
$\mu(\{TH\})$	$= 2/3$	$\mu(\{HH, HT, TH\})$	$= 1$
$\mu(\{TT\})$	$= 0$	$\mu(\{HH, HT, TT\})$	$= 1/3$
$\mu(\{HH, HT\})$	$= 1/3$	$\mu(\{HH, TH, TT\})$	$= 1$
$\mu(\{HH, TH\})$	$= 1$	$\mu(\{HT, TH, TT\})$	$= 2/3$
$\mu(\{HH, TT\})$	$= 1/3$	$\mu(\{HH, HT, TH, TT\})$	$= 1$

1.2 Quantum Probability Spaces

A classical model decides the occurrence or non-occurrence of all events simultaneously which is inconsistent with quantum mechanics. Indeed, in the quantum world, there are (non-commuting) events which cannot happen simultaneously. To accommodate this situation, we completely abandon the sample space Ω and define and reason directly about events. Thus a quantum probability space will consist of just two components: a set of events \mathcal{A} and a probability measure $\phi : \mathcal{A} \rightarrow [0, 1]$. These components are defined as follows.

We first assume an ambient Hilbert space \mathcal{H} and define the set of events \mathcal{A} as *projections* on \mathcal{H} . Similarly to the classical case, a probability measure is a function $\phi : \mathcal{A} \rightarrow [0, 1]$ satisfying:

- $\phi(\mathbb{1}) = 1$, and
- for all $A \in \mathcal{A}$, we have $\phi(A^*A) \geq 0$.

As an example, let P_1, P_2, \dots, P_k be mutually orthogonal projections on \mathcal{H} with sum $\mathbb{1}$ and define the event space \mathcal{A} to be the linear span of these operators:

$$\mathcal{A} = \left\{ \sum_{j=1}^k \lambda_j P_j \mid \lambda_1, \dots, \lambda_k \in \mathbb{C} \right\}.$$

Each state $|\psi\rangle$ of the Hilbert space induces a probability measure $\phi_\psi : \mathcal{A} \rightarrow [0, 1]$ defined as follows:

$$\phi_\psi(A) = \langle \psi | A \psi \rangle$$

Concrete example: consider the two qubit Hilbert space with computational bases $|0\rangle$ and $|1\rangle$ and consider the following families of projections:

- Family I: $|0\rangle\langle 0|, |1\rangle\langle 1|$
- Family II: $|+\rangle\langle +|, |-\rangle\langle -|$

and consider the two states ...

1.3 Plan

Several assumptions are woven in the definition of a quantum probability space:

- the Hilbert space \mathcal{H} ;
- the real interval $[0, 1]$;
- the fact that each state induces a probability measure, i.e., the Born rule;
- the fact that every probability measure is induced by a state, i.e., Gleason's theorem

In the remainder of the paper, we examine each of these assumptions and consider variations motivated by computation in a world with limited resources. In particular, we will consider a variant of the Hilbert space over finite fields; we will consider set-valued probability measures; we will consider ways other than the Born rule in which a state can induce a probability measure, and we will consider probability measures that may come from information beyond the quantum states.

References

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- [2] R.L. Graham, D.E. Knuth, and O. Patashnik. *Concrete Mathematics: A Foundation for Computer Science*. A foundation for computer science. Addison-Wesley, 1994.
- [3] V.K. Rohatgi and A.K.M.E. Saleh. *An Introduction to Probability and Statistics*. Wiley Series in Probability and Statistics. Wiley, 2011.