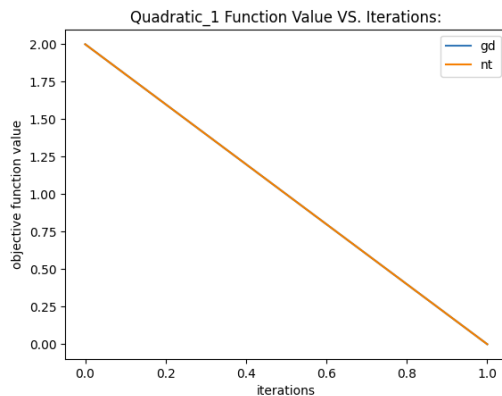


HW 1 Unconstrained minimization Programing Report –

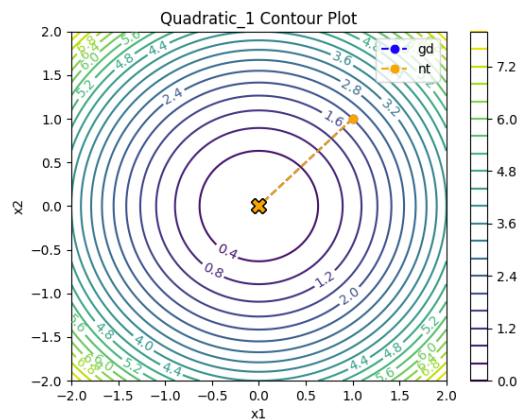
Yuval Barkan

Quadratic 1:

- **Function value vs. iteration plot:**



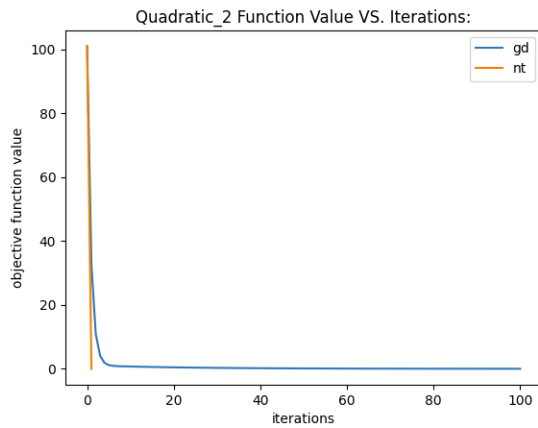
- **Contours with iteration paths:**



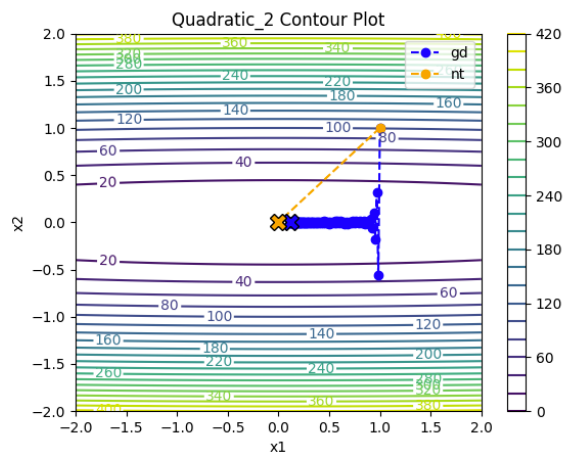
- **GD final iteration report:**
- $i=1, x=[0.0], f(x_1)=0.0, \text{Success: True}$
- **NT final iteration report:**
- $i=1, x=[0.0], f(x_1)=0.0 \text{ Success: True}$

Quadratic 2:

- **Function value vs. iteration plot:**



- **Contours with iteration paths:**



- **GD final iteration report:**

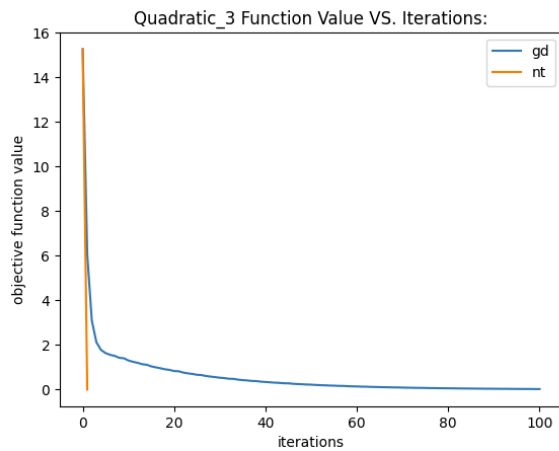
- $i=100$, $x=[0.11271997 \ 0.0008856]$, $f(x_{100})=0.012784220095399295$, Success: False

- **NT final iteration report:**

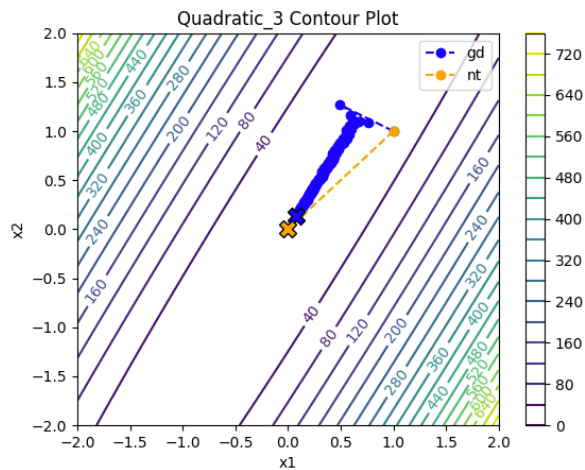
$i=1$, $x=[0. \ 0.]$, $f(x_1)=0.0$ Success: True

Quadratic 3:

- **Function value vs. iteration plot:**



- **Contours with iteration paths:**



- **GD final iteration report:**

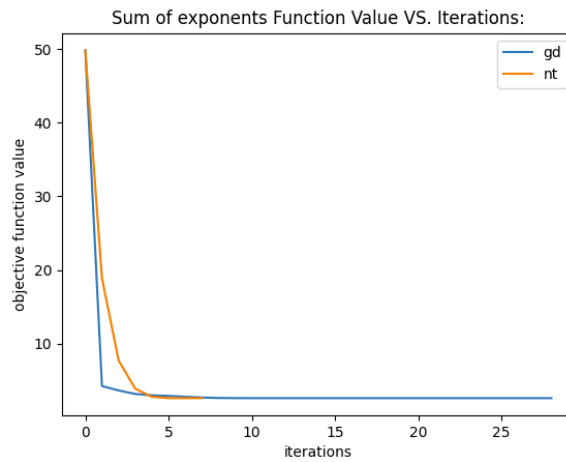
$i=100$, $x=[0.07682763 \ 0.13062022]$, $f(x_{100})=0.02311258419270041$, Success: False

- **NT final iteration report:**

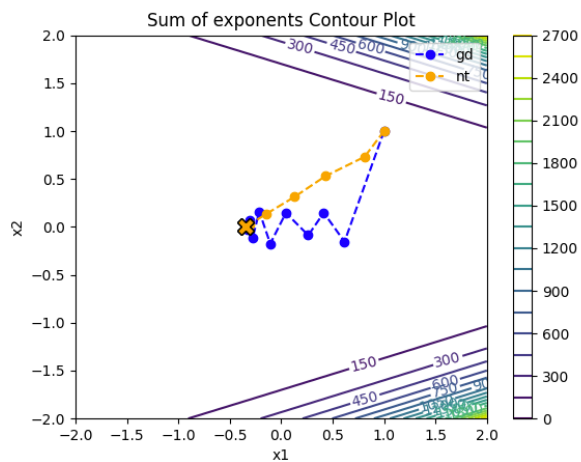
$i=1$, $x=[0. \ 0.]$, $f(x_1)=0.0$, Success: True

Sum of exponents:

- **Function value vs. iteration plot:**



- **Contours with iteration paths:**



- **GD final iteration report:**

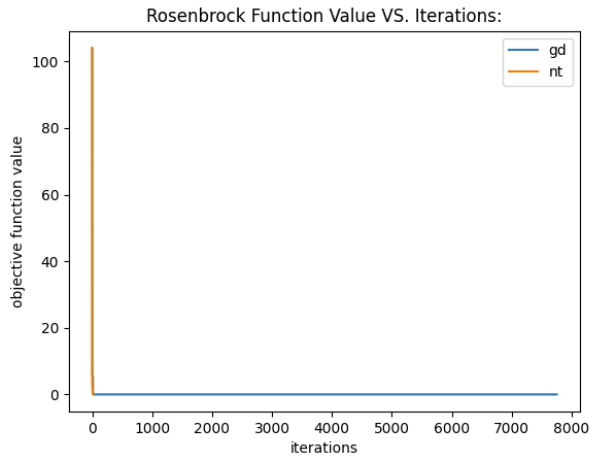
i=28, $x = [-3.46571635e-01 \ 5.19800828e-07]$, $f(x_{28}) = 2.5592666966646647$, Success: True

- **NT final iteration report:**

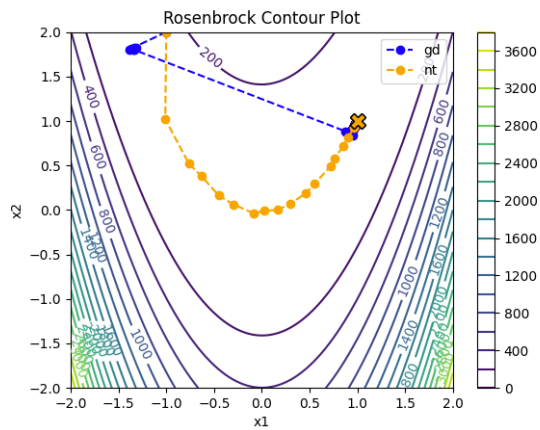
i=7, $x = [-3.46570386e-01 \ 2.12417725e-06]$, $f(x_7) = 2.559266696697338$, Success: True

Rosenbrock:

- **Function value vs. iteration plot:**



- **Contours with iteration paths:**



- **GD final iteration report:**

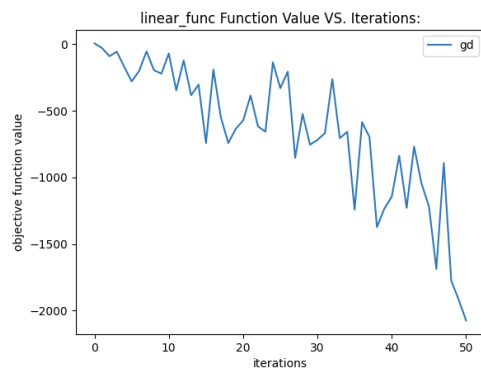
$i=7750$, $x=[0.99989387 \ 0.99978754]$, $f(x_{7750})=1.1267921607675336e-08$, Success: True

- **NT final iteration report:**

$i=19$, $x=[0.9999622 \ 0.99992331]$, $f(x_{19})=1.5495537433920102e-09$, Success: True

Linear function:

- **Function value vs. iteration plot:**



- **GD final iteration report:**

i=50, x=[-155.11059761 -143.08764839], f(x50)=-2075.364772796631, Success: True