Homograohy is defined by:

We learned in class that to solve an homography we need at least 4 pairs of matching points between two images (that are either only rotated or the in which the subject is planar) in order to get the homography. In addition, no linear dependent rows can be present in the constructed matrix.

For each pair of points we get two linear equations:

Where:

is a col vector representing the point in the src image ; () is the coords of the matching point in the dst image and are the rows of the homography matrix .

Similarly, we can write it in a different way:

Then:

Put in matrix, we get the following eq:

As stated above, each matching pair will add two additional rows to the final matrix A.

To get the conversion matrix from the equation system, we first need to calculate

Then we need to find the eigen vector that corresponds to the smallest eigen value, this can be done using SVD. The eigen vector that we got will be reordered to get the final homography matrix.