



Feedforward:

$$z_1 = X \cdot w_1 + \vec{b}_1$$

$$A_1 = g_1(z_1) \quad ; \text{ where } g_1 = \text{activation function}$$

$$z_2 = A_1 \cdot w_2 + \vec{b}_2$$

$$A_2 = g_2(z_2) \quad ; \text{ where } g_2 = \text{activation function}$$

$$z_3 = A_2 \cdot w_3 + \vec{b}_3$$

$$A_3 = g_3(z_3) = \hat{y} \quad ; \text{ where } g_3 = \text{activation function}$$

$g_1, g_2 \rightarrow \text{ReLU activation}$

$g_3 \rightarrow \text{Sigmoid activation}$

Loss: Cross-entropy,
$$\mathcal{L} = -\frac{1}{m} \sum_{i=0}^m (y^{(i)} \log(\hat{y}^{(i)}) + (1 - y^{(i)}) \log(1 - \hat{y}^{(i)}))$$

$$\frac{\partial \mathcal{L}}{\partial \hat{y}} = -\frac{y}{\hat{y}} + \frac{1-y}{1-\hat{y}}$$

Activation functions:

$$\text{ReLU}(x) = \begin{cases} x & \text{if } x > 0 \\ 0 & \text{otherwise} \end{cases}$$

$$\frac{d}{dx} \text{ReLU}(x) = \begin{cases} 1 & \text{if } x > 0 \\ 0 & \text{otherwise} \end{cases}$$

$$\sigma(x) = \frac{1}{1+e^{-x}}$$

$$\begin{aligned} \frac{d}{dx} \sigma(x) &= \frac{d}{dx} \left(\frac{1}{1+e^{-x}} \right) = -(1+e^{-x})^{-2} \cdot (-e^{-x}) \\ &= \frac{e^{-x}}{(1+e^{-x})^2} \\ &= \frac{1}{1+e^{-x}} \cdot \frac{e^{-x}}{1+e^{-x}} \\ &= \frac{1}{(1+e^{-x})} \cdot \frac{(1+e^{-x})-1}{(1+e^{-x})} \\ &= \frac{1}{1+e^{-x}} \cdot \left(1 - \frac{1}{1+e^{-x}} \right) \\ &= \sigma(x) \cdot (1 - \sigma(x)) \end{aligned}$$

Backpropagation:

$$\begin{aligned} \frac{\partial L}{\partial z_3} &= \frac{\partial L}{\partial \hat{y}} \cdot \frac{\partial \hat{y}}{\partial z_3} = \frac{\partial L}{\partial \hat{y}} \cdot \frac{\partial \sigma(z_3)}{\partial z_3} \\ &= \left(\frac{-y}{\hat{y}} + \frac{1-y}{1-\hat{y}} \right) \cdot (\hat{y}(1-\hat{y})) \\ &= \frac{-y(1-\hat{y}) + (1-y)\hat{y}}{\hat{y}(1-\hat{y})} \cdot \hat{y}(1-\hat{y}) \\ &= \hat{y} + y \cdot y + \hat{y} - y \cdot \hat{y} \\ &= \hat{y} - y \end{aligned}$$

$$\frac{\partial L}{\partial w_3} = \frac{\partial L}{\partial z_3} \cdot \frac{\partial z_3}{\partial w_3} = \frac{\partial L}{\partial z_3} \cdot \frac{\partial (A_3 \cdot w_3 + b_3)}{\partial w_3}$$

$$\therefore \frac{\partial L}{\partial w_3} = \hat{y} - y \cdot A_3$$

$$\frac{\partial L}{\partial b_3} = \frac{\partial L}{\partial z_3} \cdot \frac{\partial z_3}{\partial b_3} = \hat{y} - y \quad ; \quad \frac{\partial z_3}{\partial b_3} = 1$$

$$\begin{aligned} \frac{\partial L}{\partial z_3} &= \frac{\partial L}{\partial A_2} \cdot \frac{\partial A_2}{\partial z_2} = \frac{\partial L}{\partial z_3} \cdot \frac{\partial z_3}{\partial A_2} \cdot \frac{\partial A_2}{\partial z_2} \\ &= \hat{y} - y \cdot w_3 \cdot g'_1(z_2) \end{aligned}$$

$$\frac{\partial L}{\partial w_2} = \frac{\partial L}{\partial z_2} \cdot \frac{\partial z_2}{\partial w_2} = \frac{\partial L}{\partial z_2} \cdot A_1$$

$$\frac{\partial L}{\partial b_2} = \frac{\partial L}{\partial z_2} \cdot \frac{\partial z_2}{\partial b_2} = \frac{\partial L}{\partial z_2} \cdot 1$$

$$\begin{aligned} \frac{\partial L}{\partial z_1} &= \frac{\partial L}{\partial A_1} \cdot \frac{\partial A_1}{\partial z_1} = \frac{\partial L}{\partial z_2} \cdot \frac{\partial z_2}{\partial A_1} \cdot \frac{\partial A_1}{\partial z_1} \\ &= \frac{\partial L}{\partial z_2} \cdot w_2 \cdot g'_1(z_1) \end{aligned}$$

$$\frac{\partial L}{\partial w_1} = \frac{\partial L}{\partial z_1} \cdot \frac{\partial z_1}{\partial w_1} = \frac{\partial L}{\partial z_1} \cdot x$$

$$\frac{\partial L}{\partial b_1} = \frac{\partial L}{\partial z_1} \cdot \frac{\partial z_1}{\partial b_1} = \frac{\partial L}{\partial z_1} \cdot 1$$

Update parameters: $\theta := \theta - \alpha \frac{\partial L}{\partial \theta}$; where α = learning rate

$$w_3 = w_3 - \alpha \frac{\partial L}{\partial w_3}$$

$$w_2 = w_2 - \alpha \frac{\partial L}{\partial w_2}$$

$$w_1 = w_1 - \alpha \frac{\partial L}{\partial w_1}$$

$$b_3 = b_3 - \alpha \frac{\partial L}{\partial b_3}$$

$$b_2 = b_2 - \alpha \frac{\partial L}{\partial b_2}$$

$$b_1 = b_1 - \alpha \frac{\partial L}{\partial b_1}$$