exercise1 (Score: 16.0 / 20.0)

1. Task (Score: 4.0 / 4.0)
2. Test cell (Score: 2.0 / 2.0)
3. Test cell (Score: 4.0 / 4.0)
4. Test cell (Score: 2.0 / 2.0)
5. Task (Score: 2.0 / 4.0)
6. Task (Score: 2.0 / 4.0)
7. Comment

Lab 4

1. 提交作業之前，建議可以先點選上方工具列的**Kernel**，再選擇**Restart & Run All**，檢查一下是否程式跑起來都沒有問題，最後記得儲存。
2. 請先填上下方的姓名(name)及學號(stduent_id)再開始作答，例如：

```
name = "我的名字"
student_id= "B06201000"
```

3. 演算法的實作可以參考lab-4 (https://yuanyuyuan.github.io/itcm/lab-4.html), 有任何問題歡迎找助教詢問。
4. **Deadline: 11/20(Wed.)**

In [1]:

```
name = "黃宇文"
student_id = "B06201029"
```

Exercise 1. Finite Difference

Part 0.

Import necessary libraries. Note that diags library from scipy is used to construct the differentiation matrix below.

In [2]:

```
import numpy as np
import matplotlib.pyplot as plt
from scipy.sparse import diags
```

Part 1.

Given a function $u(x)$ which we want to find its derivative with numerical methods.

Consider a uniform grid partitioning x into $\{x_1, x_2, \ldots, x_n\}$ with grid size $\Delta x = x_{j+1} - x_j, j \in \{1, 2, \ldots, n\}$, and a set of corresponding data values $U = \{U_1, U_2, \ldots, U_n\}$, where

$$U_{j+k} = u(x_j + k\Delta x) = u(x_{j+k}), j \in \{1, 2, \ldots, n\}.$$

We want to use one-sided finite-difference formula

$$\alpha_1 U_j + \alpha_2 U_{j+1} + \alpha_3 U_{j+2}$$

to approximate the derivative of u at all the points $x_j, j \in \{1, 2, \ldots, n\}$, that is

$$u^{'}(x_j) \approx W_j \triangleq \alpha_1 U_j + \alpha_2 U_{j+1} + \alpha_3 U_{j+2}.$$

(Top)

Part 1.1

Find the coefficients α_j for $j = 1, 2, 3$ which make the stencil above accurate for as high degree polynomials as possible.

Write down your derivation in detail with Markdown/LaTeX.

$$\alpha_1 u(x_j) + \alpha_2 u(x_j + 1) + \alpha_3 u(x_j + 2) = u^{'}(x_j)$$

By Taylor series expansion,\

$$\alpha_1 u(x_j) + \alpha_2 \left(u(x_j) + u^{'}(x_j) + \frac{u^{''}(x_j)}{2} + \ldots \right) + \alpha_3 \left(u(x_j) + u^{'}(x_j)(2) + \frac{u^{''}(x_j)}{2}(2)^2 + \ldots \right) = u^{'}(x_j)$$

$$(\alpha_1 + \alpha_2 + \alpha_3)u(x_j) + (\alpha_2 + 2\alpha_3)u^{'}(x_j) + \left(\frac{1}{2}\alpha_2 + 2\alpha_3\right)u^{''}(x_j) + \ldots = u^{'}(x_j)$$

We get\

$$\begin{aligned} \alpha_1 + \alpha_2 + \alpha_3 &= 0 \\ \alpha_2 + 2\alpha_3 &= 1 \\ \frac{1}{2}\alpha_2 + 2\alpha_3 &= 0 \end{aligned}$$

\

$$\therefore\ \alpha_1 = -\frac{3}{2},\ \alpha_2 = 2,\ \alpha_3 = -\frac{1}{2} u^{'}(x_j) = -\frac{3}{2}U_j + 2U_{j+1} - \frac{1}{2}U_{j+2}$$

Part 1.2

Fill in the tuple variable `alpha` of lenght 3 with your answer above. (Suppose $\Delta x = 1$)

In [3]:

(Top)

```
# Hint: alpha = [value of alpha_1, value of alpha_2, value of alpha_3]
# ===== 請實做程式 =====
alpha = [-3/2, 2, -1/2]
# ====================
```

In [4]:

cell-e7c9469885bebc80 (Top)

```
print('My alpha =', alpha)
### BEGIN HIDDEN TESTS
assert alpha == [-1.5, 2, -0.5] or alpha == (-1.5, 2, -0.5)
### END HIDDEN TESTS
```

```
My alpha = [-1.5, 2, -0.5]
```

Part 2.

Suppose we use the finite-difference formula above to approximate and assume the problem is periodic, i.e. take $U_0 = U_n$, $U_1 = U_{n+1}$, and so on.

Find the differentiation matrix D so that the numerical differentiation problem can be represented as a matrix-vector multiplication $W \triangleq DU$, where $D \in \mathbb{R}^{n \times n}$, $U \in \mathbb{R}^n$, and $W \in \mathbb{R}^n$.

Part 2.1

Complete the following function to construct the desired differentiation matrix under the **periodic boundary condition** with given number of partition n, coefficients of 3-point finite-difference formula α, and mesh size Δx.

In [5]:

(Top)

```python
def construct_differentiation_matrix(n, alpha, delta_x):
    ''' Construct
    Parameters
    ----------
    n : int
        number of partition
    alpha : tuple of length 3
       alpha = (α1, α2, α3)
    delta_x : float
        mesh size

    Returns
    -------
    D : scipy.sparse.diags
    '''
    # ===== 請實做程式 =====
    diagonals = [
        alpha[0] * np.ones(n),
        alpha[1] * np.ones(n-1),
        alpha[2] * np.ones(n-2),
        alpha[2] * np.ones(2),
        alpha[1] * np.ones(1)
    ]

    A = diags(diagonals, offsets=[0, 1, 2, -n+2, -n+1])

    D = A

    D/=delta_x
    # ====================
    return D
```

Part 2.2

Print and check your implementation.

In [6]:

cell-2ca00ba5ff115302 (Top)

```python
print("For n = 8 and mesh size 1, D in dense form is")
sparse_D = construct_differentiation_matrix(8, alpha, 1)
dense_D = sparse_D.toarray()
print(dense_D)
### BEGIN HIDDEN TESTS
answer = np.array([
    [-1.5,  2.,  -0.5,  0.,   0.,   0.,   0.,   0. ],
    [ 0.,  -1.5,  2.,  -0.5,  0.,   0.,   0.,   0. ],
    [ 0.,   0.,  -1.5,  2.,  -0.5,  0.,   0.,   0. ],
    [ 0.,   0.,   0.,  -1.5,  2.,  -0.5,  0.,   0. ],
    [ 0.,   0.,   0.,   0.,  -1.5,  2.,  -0.5,  0. ],
    [ 0.,   0.,   0.,   0.,   0.,  -1.5,  2.,  -0.5],
    [-0.5,  0.,   0.,   0.,   0.,   0.,  -1.5,  2. ],
    [ 2.,  -0.5,  0.,   0.,   0.,   0.,   0.,  -1.5]
])
assert np.linalg.norm(dense_D - answer) < 1e-7
### END HIDDEN TESTS
```

```
For n = 8 and mesh size 1, D in dense form is
[[-1.5  2.  -0.5  0.   0.   0.   0.   0. ]
 [ 0.  -1.5  2.  -0.5  0.   0.   0.   0. ]
 [ 0.   0.  -1.5  2.  -0.5  0.   0.   0. ]
 [ 0.   0.   0.  -1.5  2.  -0.5  0.   0. ]
 [ 0.   0.   0.   0.  -1.5  2.  -0.5  0. ]
 [ 0.   0.   0.   0.   0.  -1.5  2.  -0.5]
 [-0.5  0.   0.   0.   0.   0.  -1.5  2. ]
 [ 2.  -0.5  0.   0.   0.   0.   0.  -1.5]]
```

Part 3.

Take $u(x) = e^{\sin x}$ on the domain $[-\pi, \pi]$. Find the finite difference approximation W for $\{u'(x_j)\}_{j=1}^{n}$ for various values of $n = 2^k$, $k = 3, 4, \ldots, 10$, and analyze the errors.

Part 3.1

Define the functinos u and $u'(x)$.

In [7]:

(Top)

```
def u(x):
    # ===== 請實做程式 =====
    return np.exp(np.sin(x))
    # ====================

def d_u(x):
    # ===== 請實做程式 =====
    return np.cos(x)*np.exp(np.sin(x))
    # ====================
```

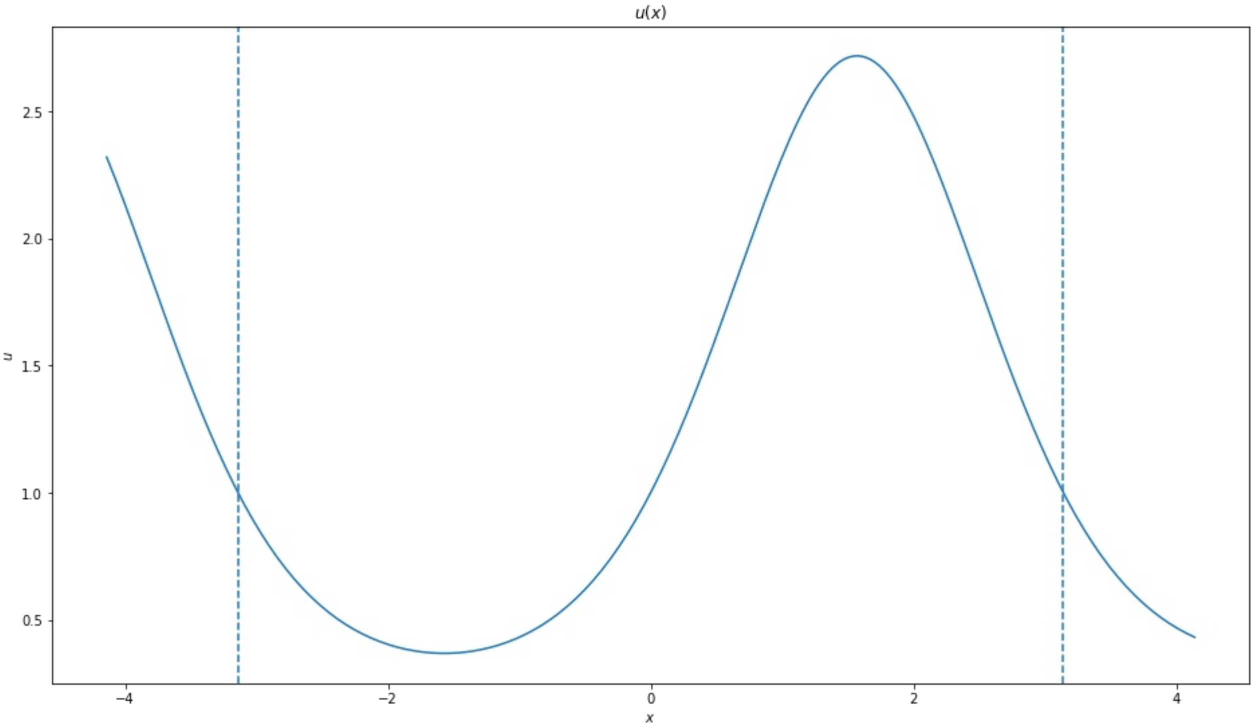
Plot and check the functions

In [8]:

(Top)

cell-f97d6fb0842a6055

```
x_range = np.linspace(-np.pi-1, np.pi+1, 2**8)
plt.figure(figsize=(16, 9))
plt.plot(x_range, u(x_range))
plt.axvline(x=np.pi, linestyle='--')
plt.axvline(x=-np.pi, linestyle='--')
plt.ylabel(r'$u$')
plt.xlabel(r'$x$')
plt.title(r'$u(x)$')
plt.show()
### BEGIN HIDDEN TESTS
assert u(1) == np.exp(np.sin(1))
assert u(3.14) == np.exp(np.sin(3.14))
assert d_u(1) == np.cos(1) * np.exp(np.sin(1))
assert d_u(0) == np.cos(0) * np.exp(np.sin(0))
### END HIDDEN TESTS
```



(Top)

Part 3.2

Plot the u' and W together for each point $x_j, j \in \{1, 2, \dots, n\}$ with $n = 2^k, k \in \{3, 4, \dots, 10\}$. Note that there're total 8 figures to be plotted. And you need to compute the error, display them in the plots, and store them into the list variable `error_list` for further analysis below.

In [9]:

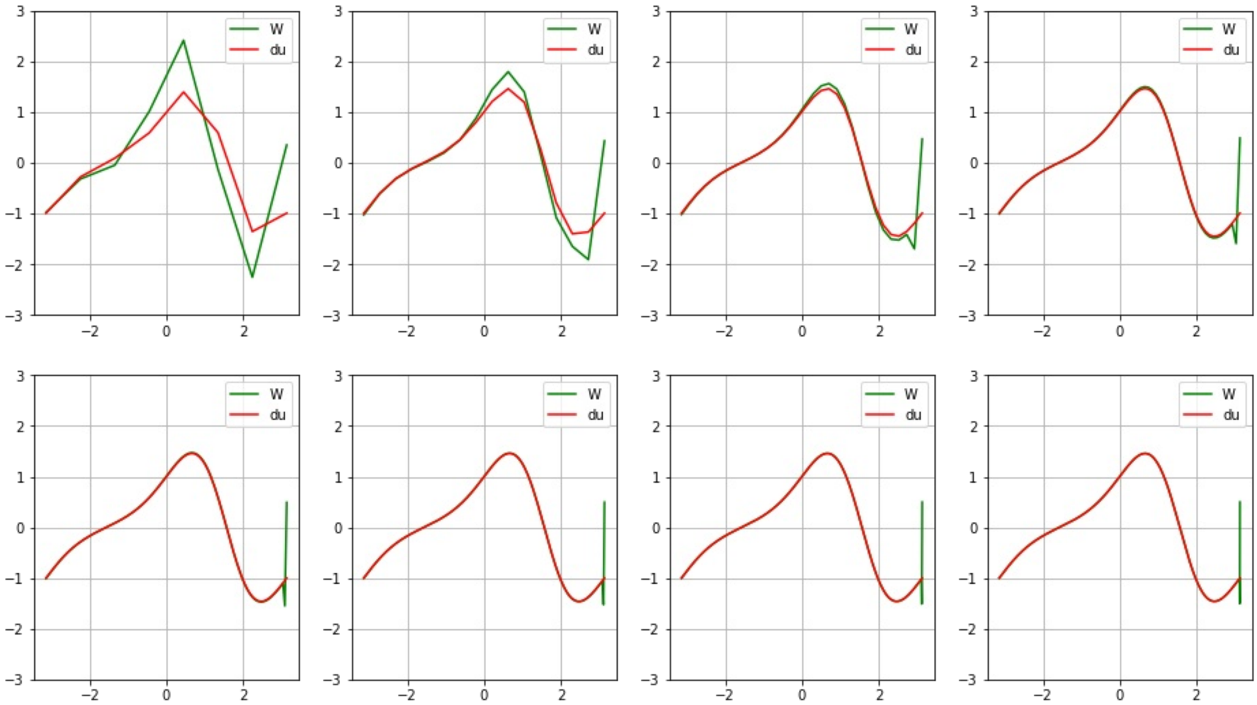
(Top)

```
error_list = []
fig, axes = plt.subplots(2, 4, figsize=(16,9))
for idx, ax in enumerate(axes.flatten()):
    '''Hints:
    For each case in this for loop, you may follow the steps below
        1. Use idx to set k and n.
        2. Prepare n partition points of the domain.
        3. Construct D.
        4. Find u', U, and W.
        5. Compute the error between u' and W.
        6. Append the error into error_list.
        7. Use ax to plot u', W with proper labels, title
        8. Enable legend to show the labels of curves.
        9. To make the plots more readable, set a consistent range of y-axis e.g. ax.set_ylim([-3, 3])
    '''
    # ===== 請實做程式 =====
    k = idx + 3
    n = 2**k

    x_range = np.linspace(-np.pi, np.pi, n)
    D = construct_differentiation_matrix(n,alpha,(2*np.pi)/n)
    du = d_u(x_range)
    U = u(x_range)
    W = D*U
    error_list.append(abs(du-W))

    ax.plot(x_range, W, color='g', label="W")
    ax.plot(x_range, du, color='r', label="du")
    ax.set_title('')
    ax.grid(True)
    ax.legend()
    ax.set_ylim([-3,3])


    # ====================
```



Plot the `error_list` with respect to $k = 3, 4, \ldots, 10$ in log scale to show the error behavior.

In [10]:

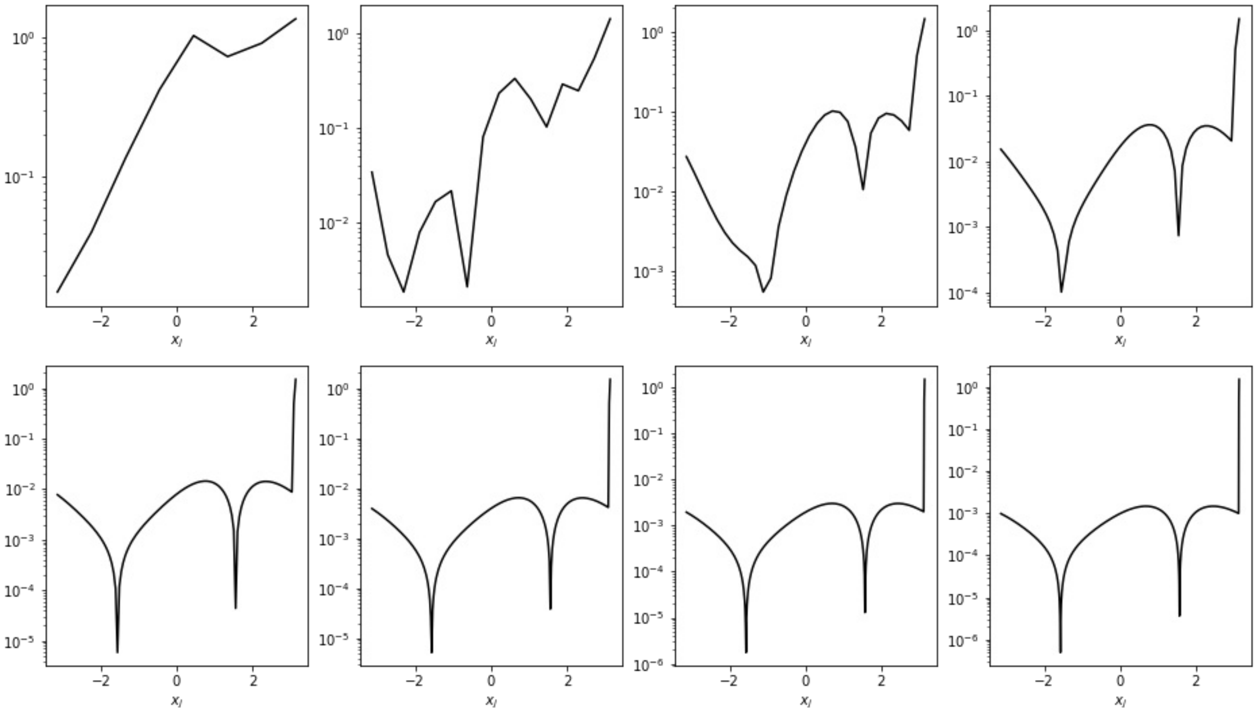
(Top)

```
# ===== 請實做程式 =====
error_list = []

fig, axes = plt.subplots(2, 4, figsize=(16,9))
for idx, ax in enumerate(axes.flatten()):
    k = idx + 3
    n = 2 ** k

    x_range = np.linspace(-np.pi, np.pi, n)
    D = construct_differentiation_matrix(n,alpha,(2*np.pi)/n)
    du = d_u(x_range)
    U = u(x_range)
    W = D*U
    error_list.append(abs(du-W))

    ax.plot(x_range, error_list[idx], color='black')
    ax.set_yscale('log')
    ax.set_xlabel('$x_j$')
# ====================
```



(Top)

Part 3.3

From the figure above, what rates of convergence do you observe as $\Delta x \to 0$?

Comments:
It finally converges...

At first, the error increases linearly.\ As the points increase, $\Delta x \to 0$, the error first decreases, then increases, and decreases again, eventually increases. It does not converge.

In [ ]: