

Lecture 15: Analog to Digital Converters (ADCs) and Digital to Analog Converters (DACs)

18-100: Introduction to ECE

SPRING 2025



Agenda

- Analog and Digital Worlds – The Problem with Pizza
- Analog to Digital Converters (ADCs)
- Digital to Analog Converters (DACs)

Digital Inputs and Outputs

- Digital inputs and outputs (I/O) represent YES/NO or TRUE/FALSE information
- Examples:
 - The light is on.
 - A button is pushed.
 - Turn on a bell.
 - Turn off a light emitting diode.

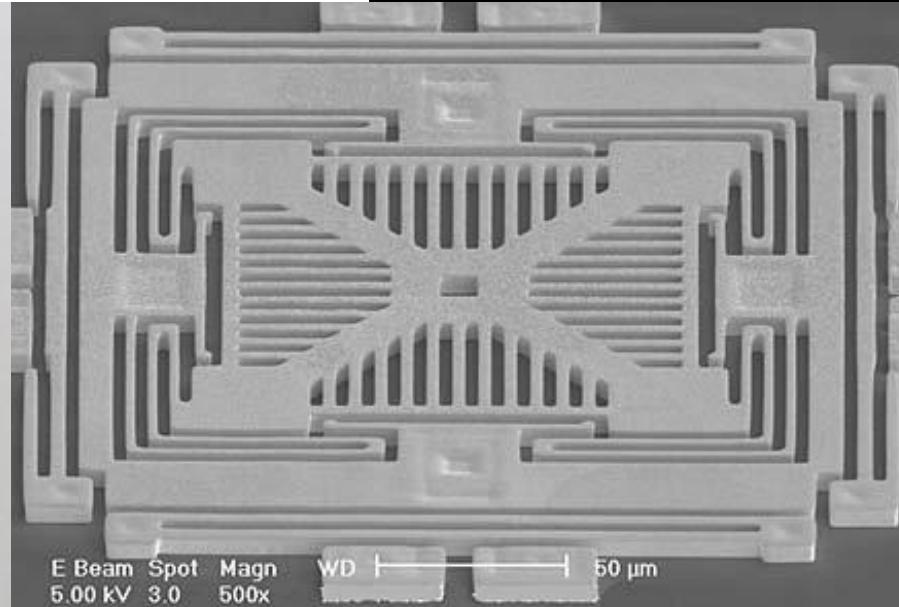
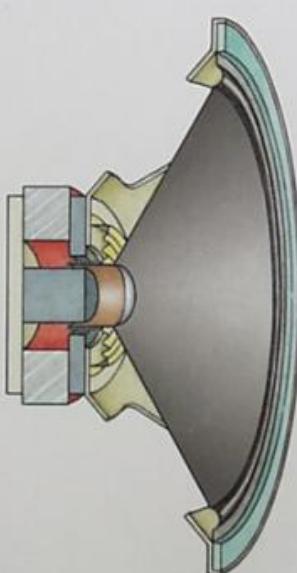
We Live in an Analog World

■ Everything in the physical world is an analog signal: Sound, light, temperature, pressure....

■ Need to convert “real world” information into electrical signals

■ Transducers: converts one type of energy to another

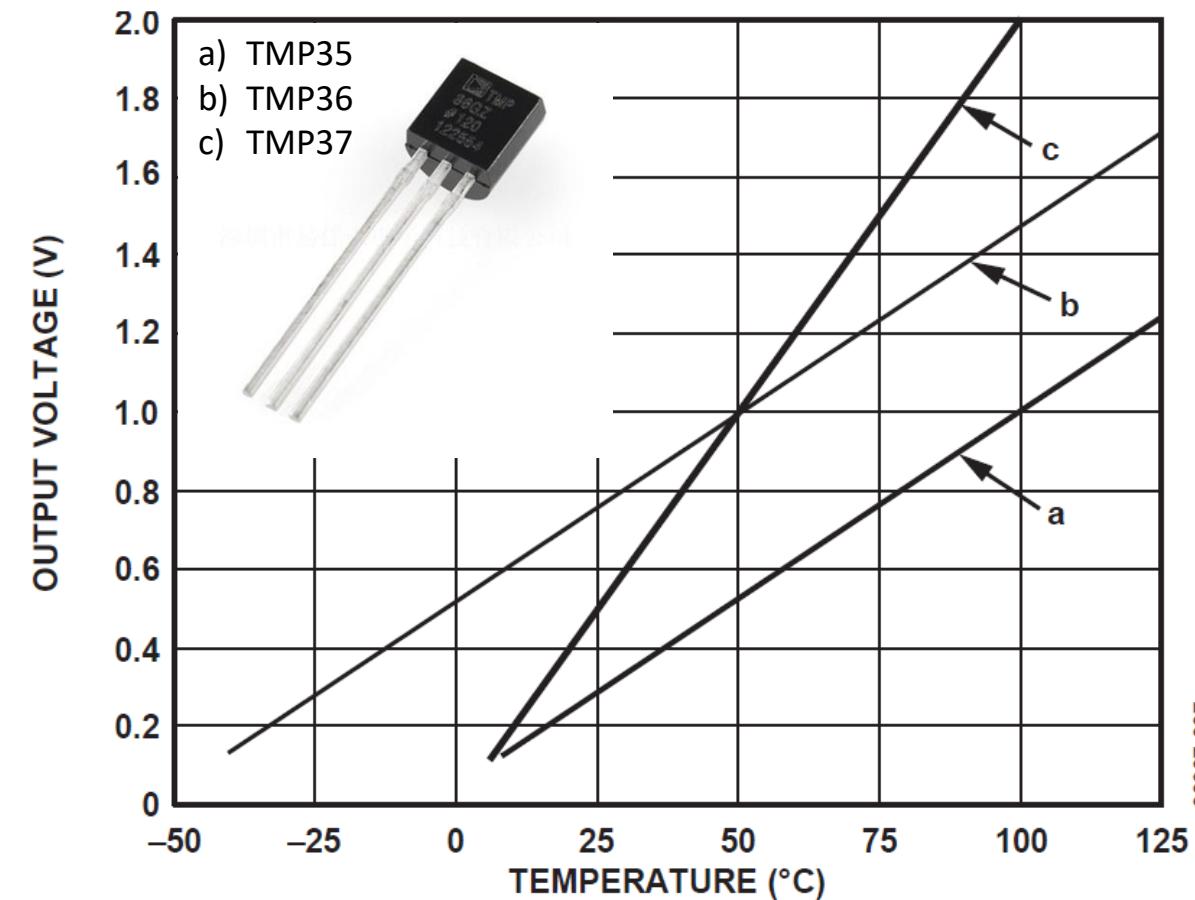
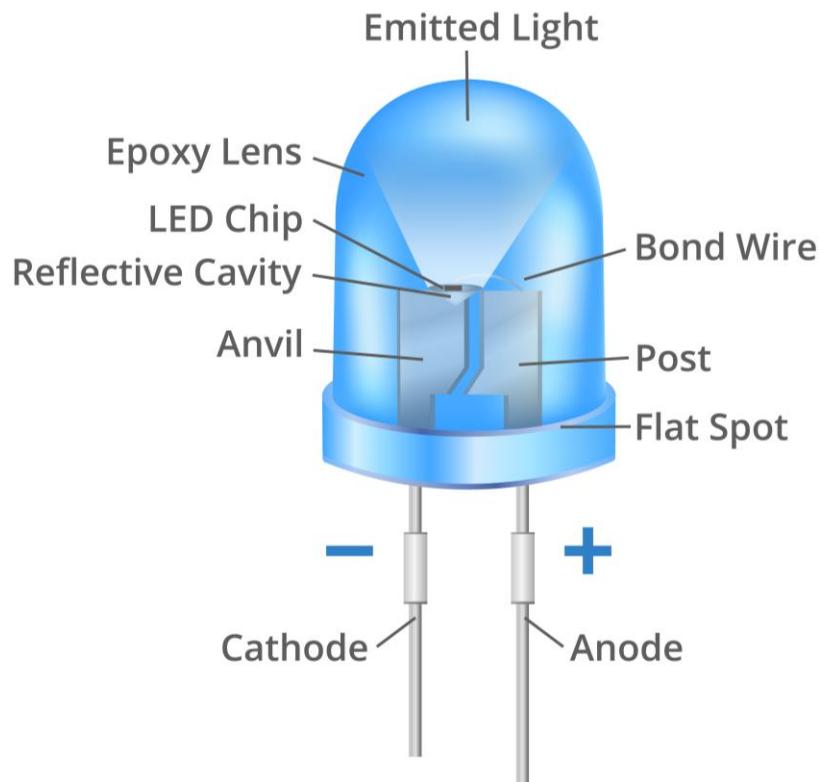
- Microphone
- Speaker
- Thermocouple
- Accelerometer
- Photoresistor
- LEDs
- Motors....



Transducers Convert One Form of Energy into Another

- Sensors convert real-world phenomena into electrical signals (like a temperature sensor)
- Actuators convert electrical signals into real-world phenomena (like an LED)

Light Emitting Diode

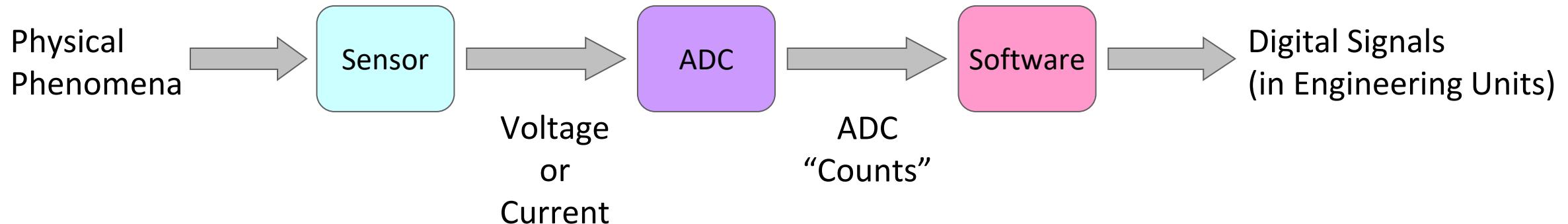


Going from an Analog Real-World Information to Digital Signals

■ What we want:

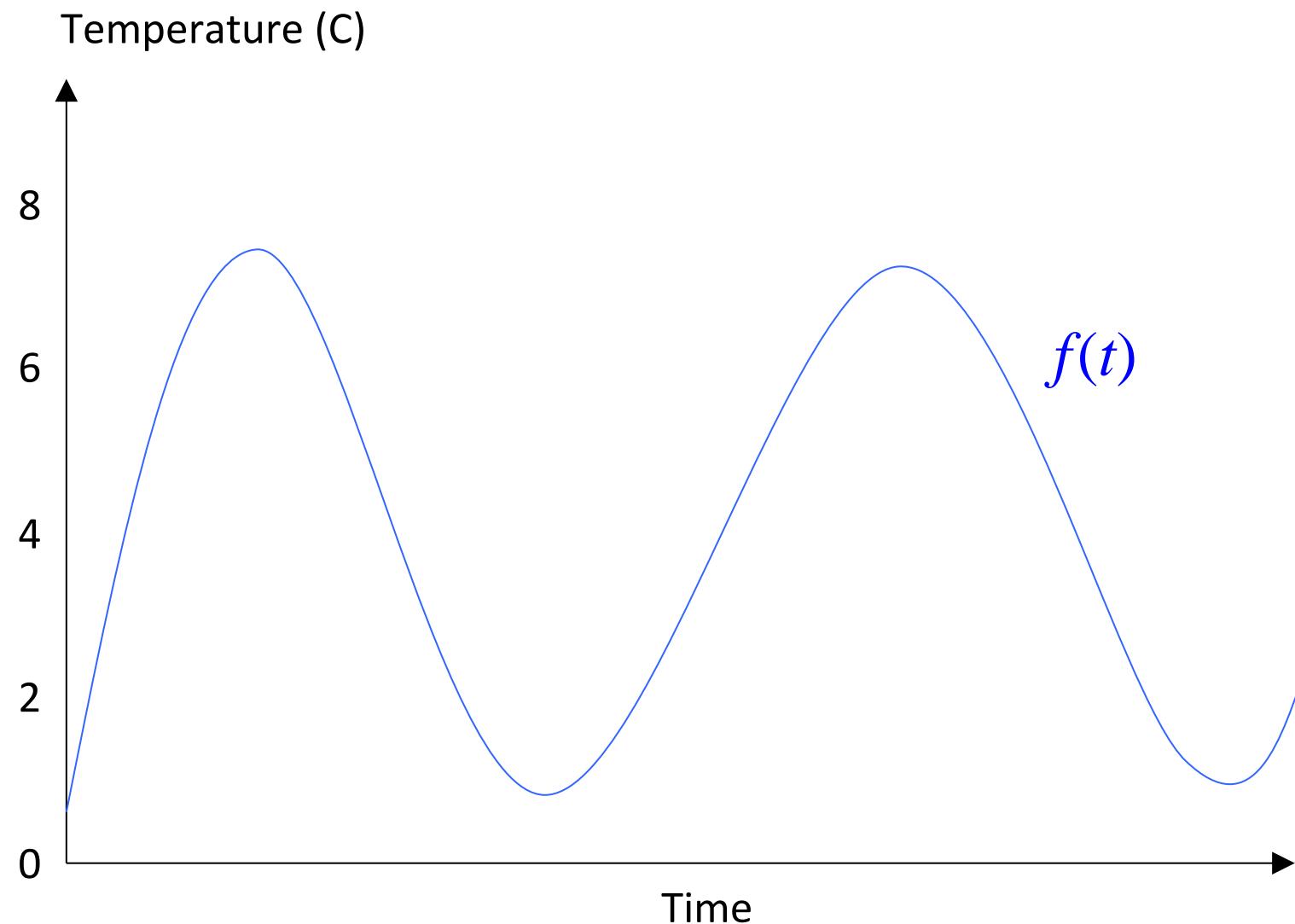


■ How we have to get there:



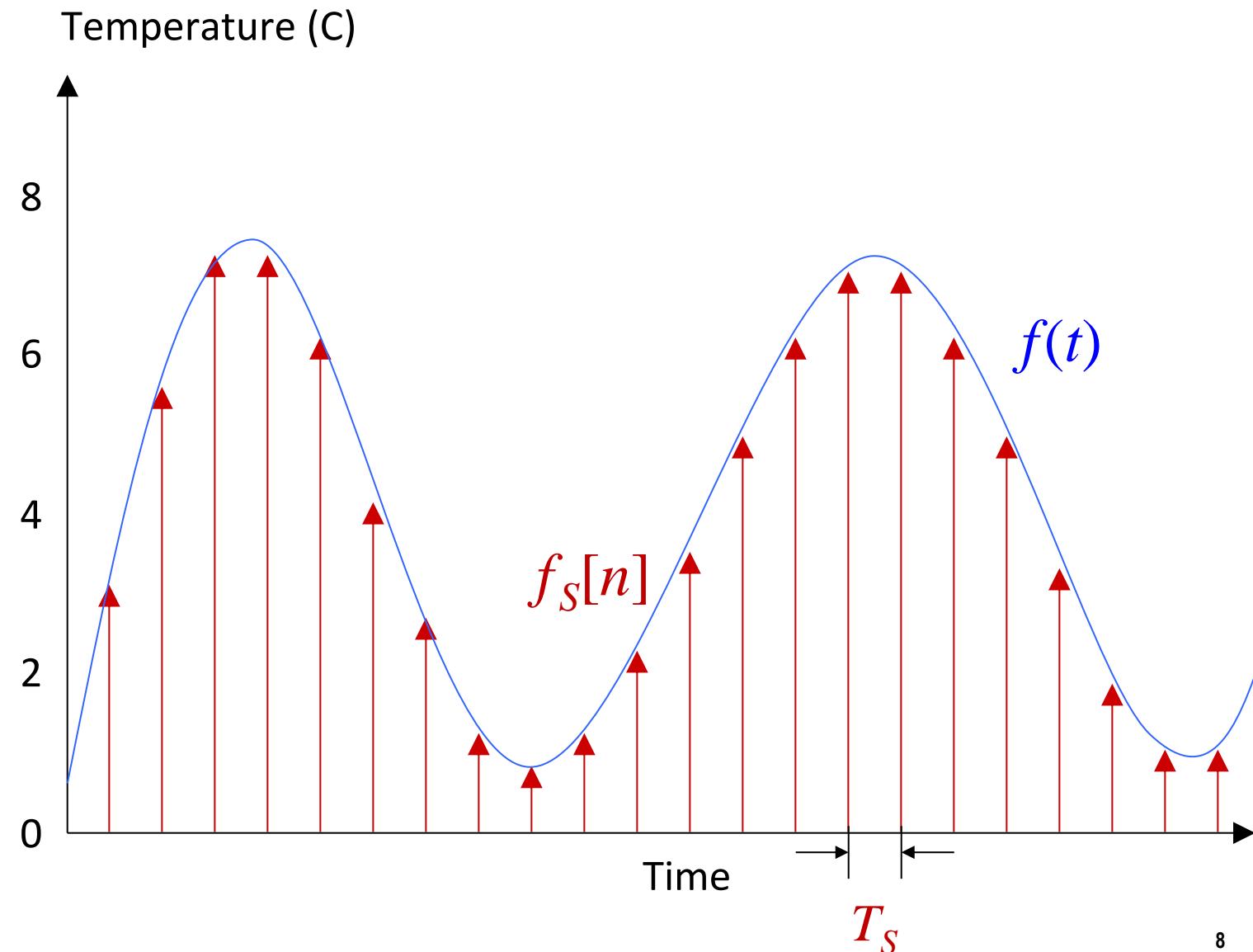
Most Real-World Phenomena: Analog **AND** Continuous-Time

- x-axis is often time
- y-axis is often amplitude
- Both are often analog and continuous signals



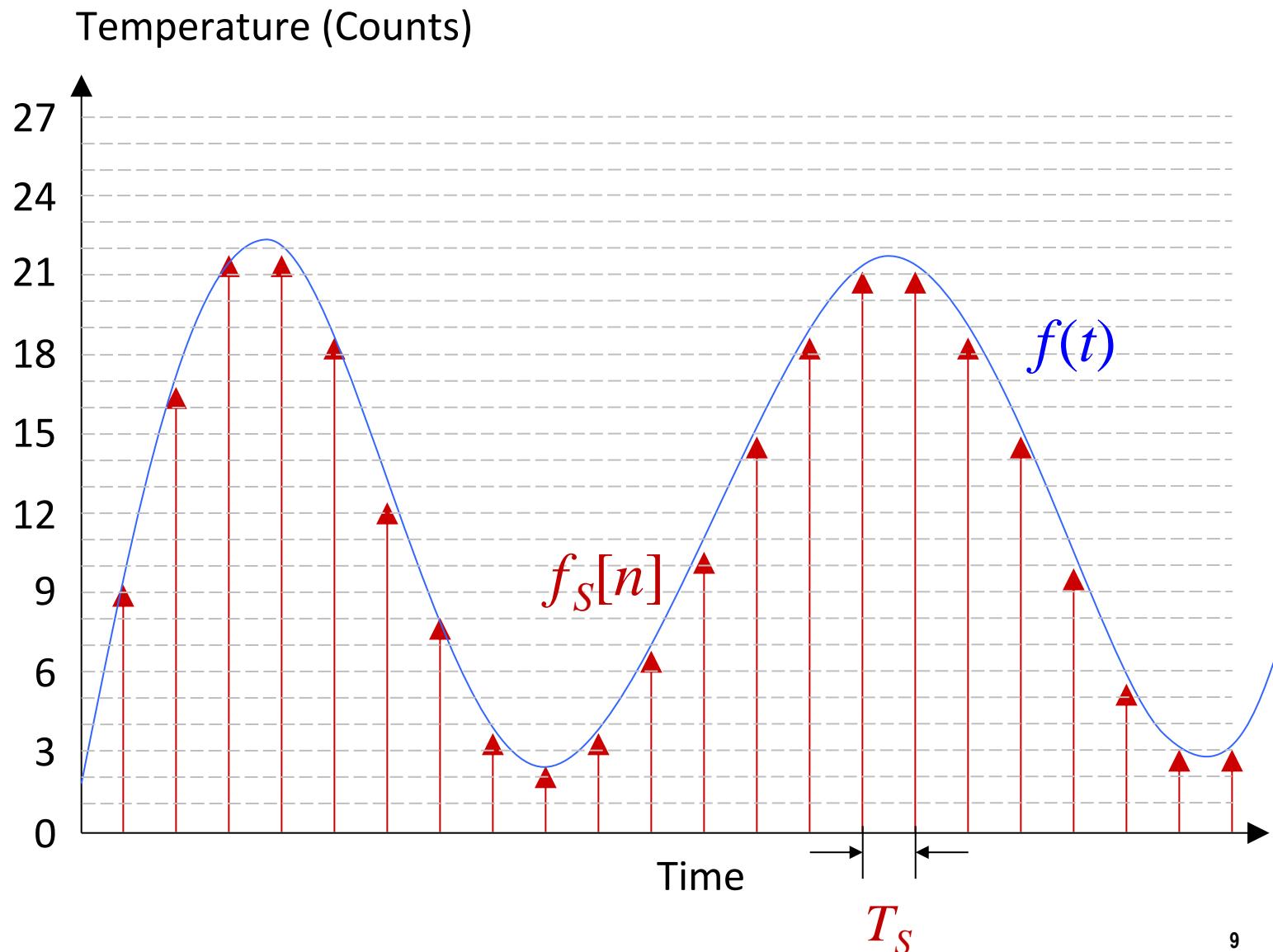
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- x-axis is often time
- y-axis is often amplitude
- Both are often analog and continuous signals
- Sample every T_S seconds to create a discrete-time signal



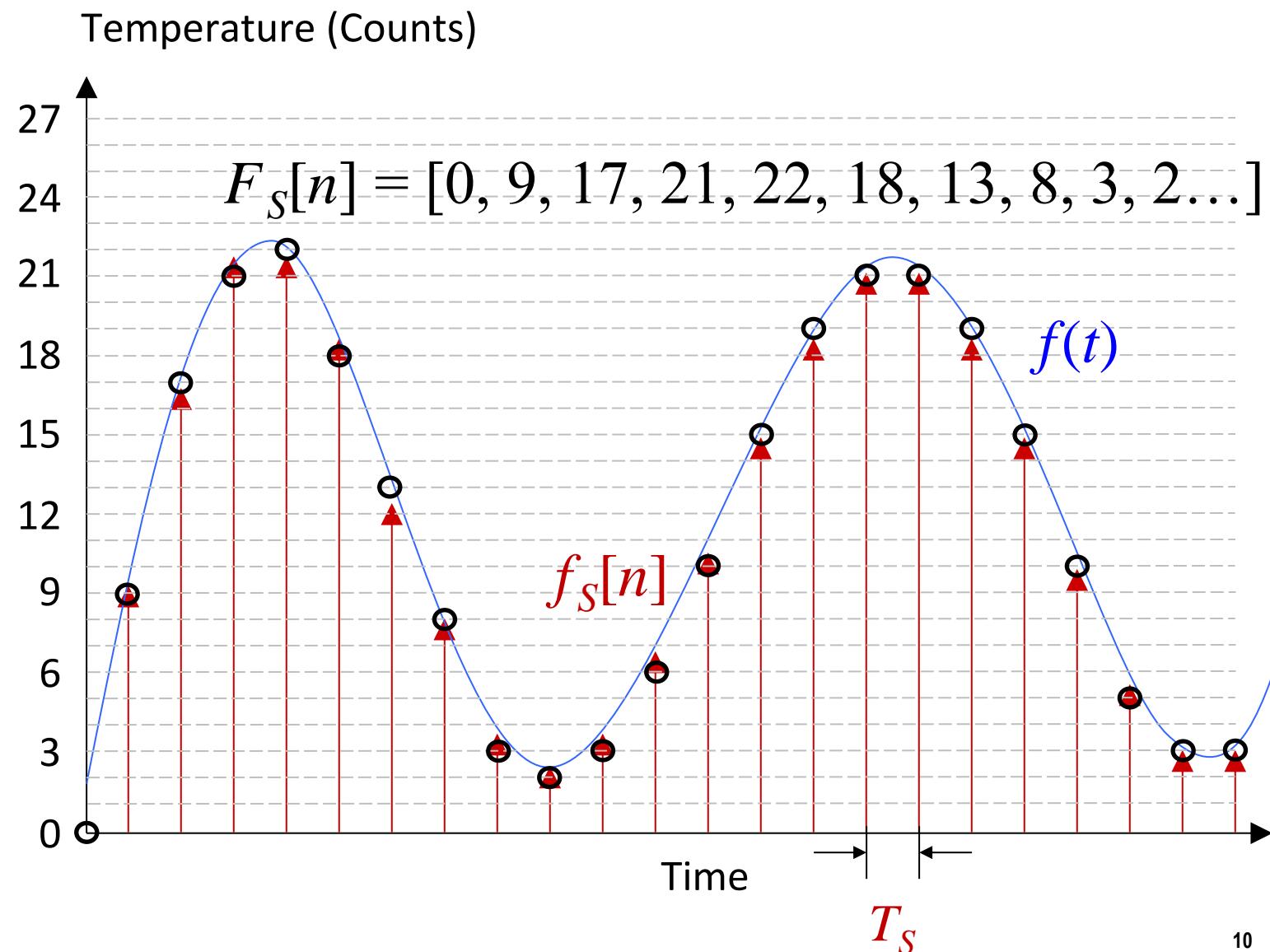
Most Real-World Phenomena: Analog **AND** Continuous-Time

- x-axis is often time
- y-axis is often amplitude
- Both are often analog and continuous signals
- Sample every T_S seconds to create a discrete-time signal
- Sample amplitude with a finite step-size to create a digital, discrete-value signal



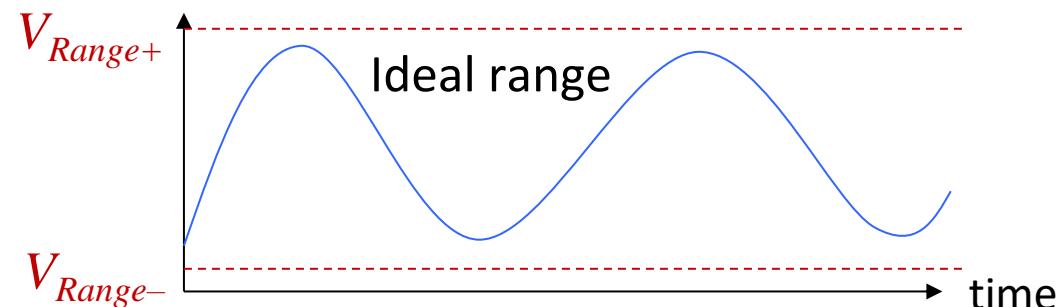
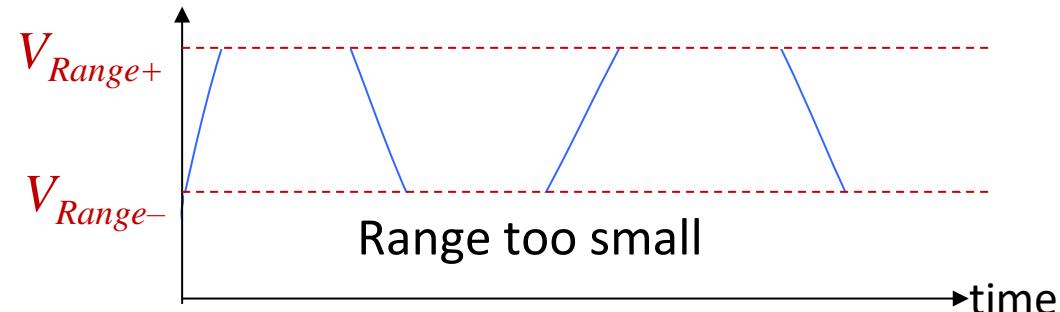
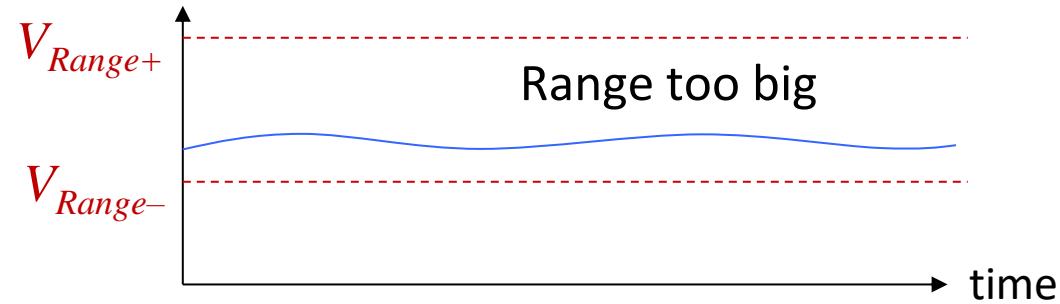
Most Real-World Phenomena: Analog **AND** Continuous-Time

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- Sample every T_S seconds to create a discrete-time signal
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Choosing the Right Sensor Range

- The sensor's (or sensor's circuit) has a specified output voltage range
- The ADC has a specified voltage range for its input V_{Range-} (or V_{r-}) to V_{Range+} (or V_{r+})
 - V_{Range-} is usually 0V, but some ADCs allow this to be changed to other values
 - V_{range+} is usually V_{DD} (like 3.3V), but some ADCs allow this to be changed to other values
- Usually want a little margin



Signal Conditioning with Operational Amplifiers (Op Amps)

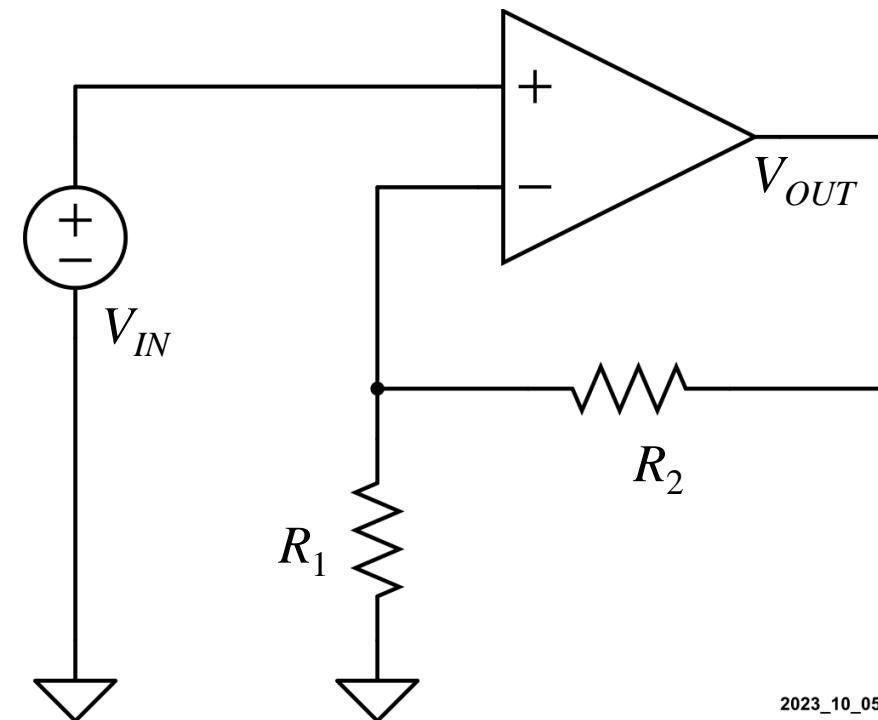
■ Usually, op amps are modeled as ideal devices with negative feedback:

- The non-inverting (V_+) and inverting (V_-) inputs will be the same voltage
- The current flowing into the V_+ and V_- inputs is 0A
- The output voltage will adjust to make the above two rules true

$$\frac{V_{OUT}}{V_{IN}} = 1 + \frac{R_2}{R_1}$$

■ Non-inverting amplifiers can make smaller voltages larger

■ Other configurations have different transfer functions



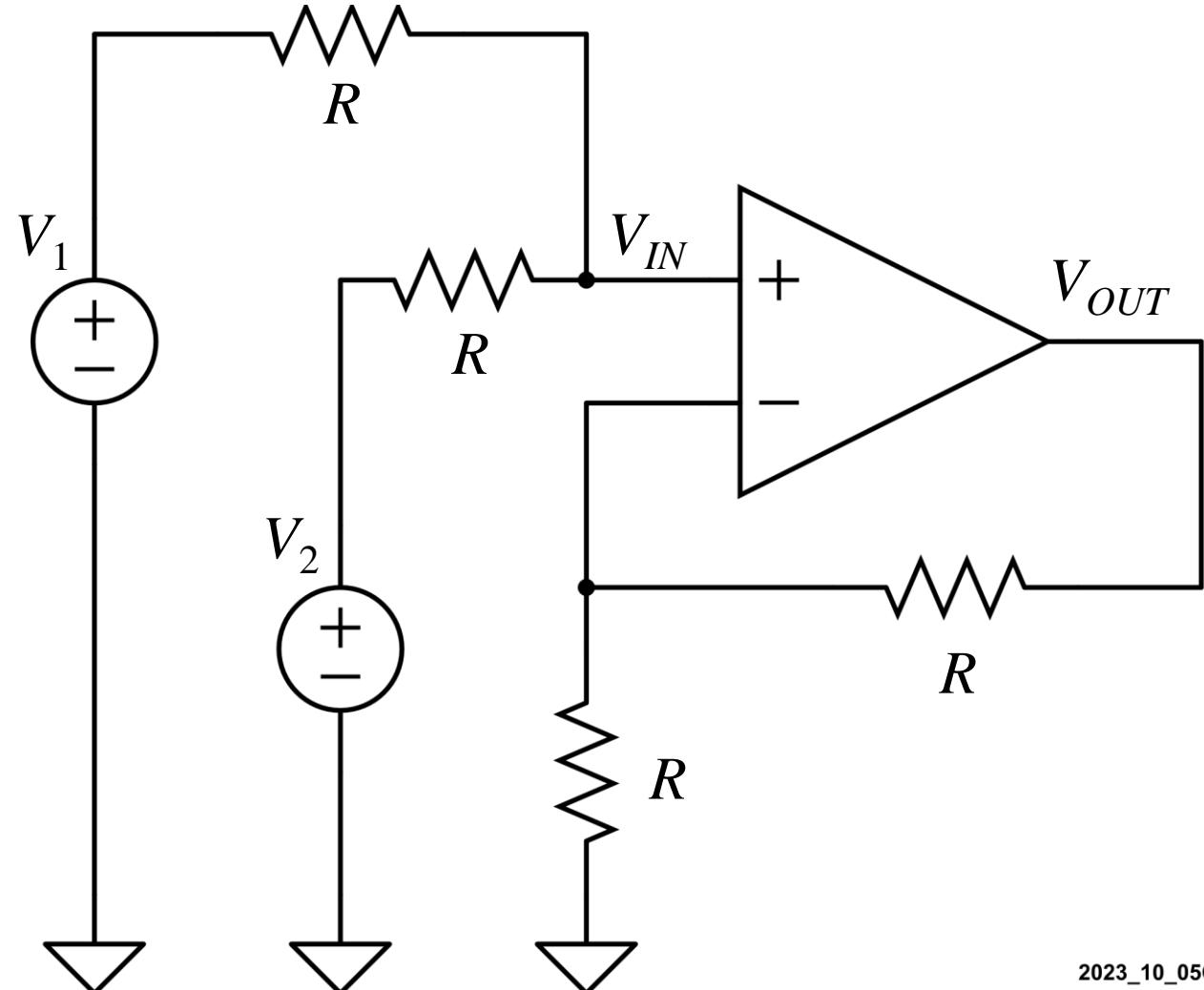
Add a DC Offset to Small Voltages with a Summing Amplifier Op Amp Circuit

- Add two (or more) voltages

$$V_{IN} = \frac{V_1 + V_2}{2}$$

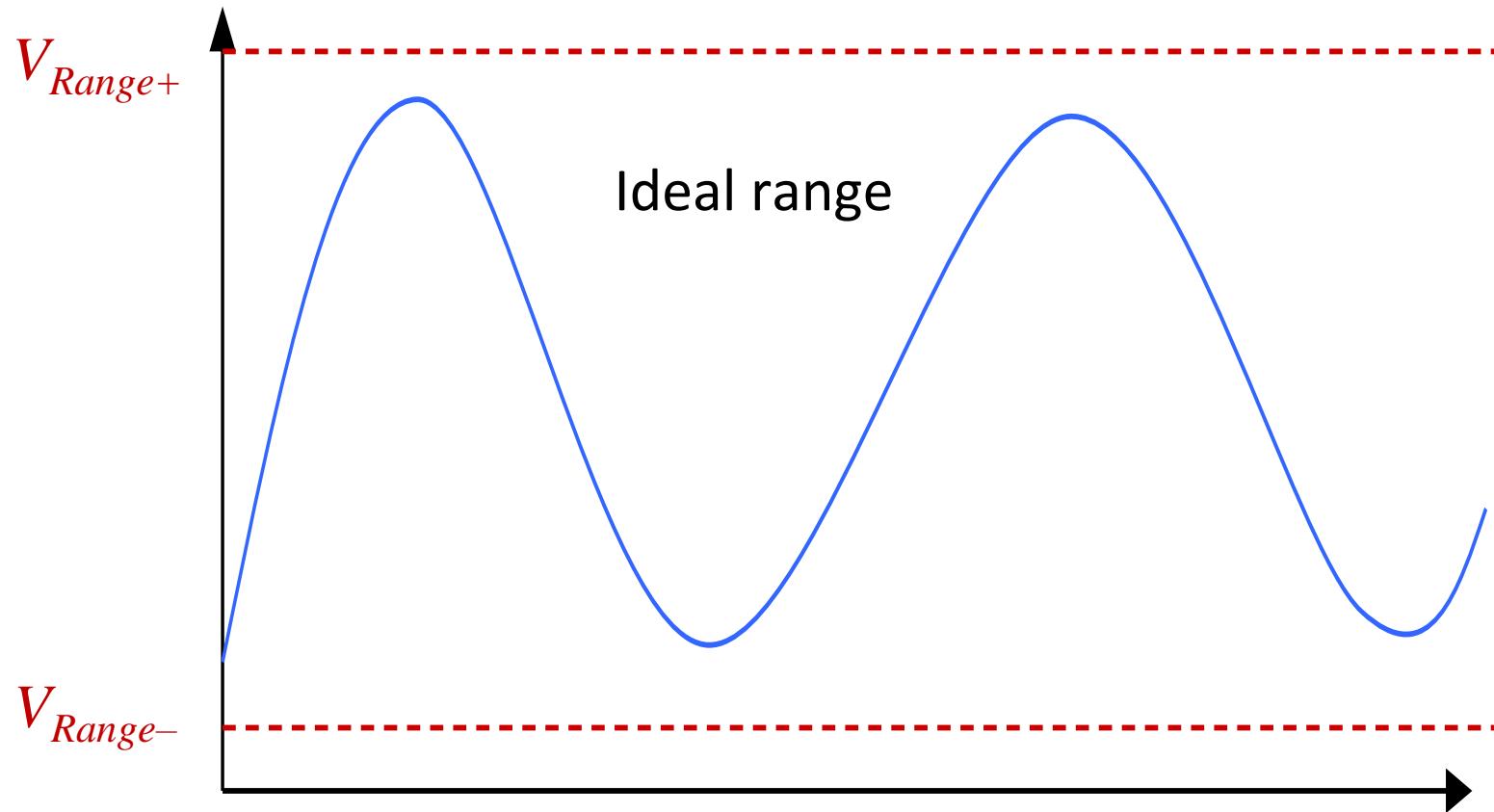
$$V_{OUT} = V_{IN} \left(1 + \frac{R}{R} \right) = 2V_{IN}$$

$$V_{OUT} = 2 \left(\frac{V_1 + V_2}{2} \right) = V_1 + V_2$$



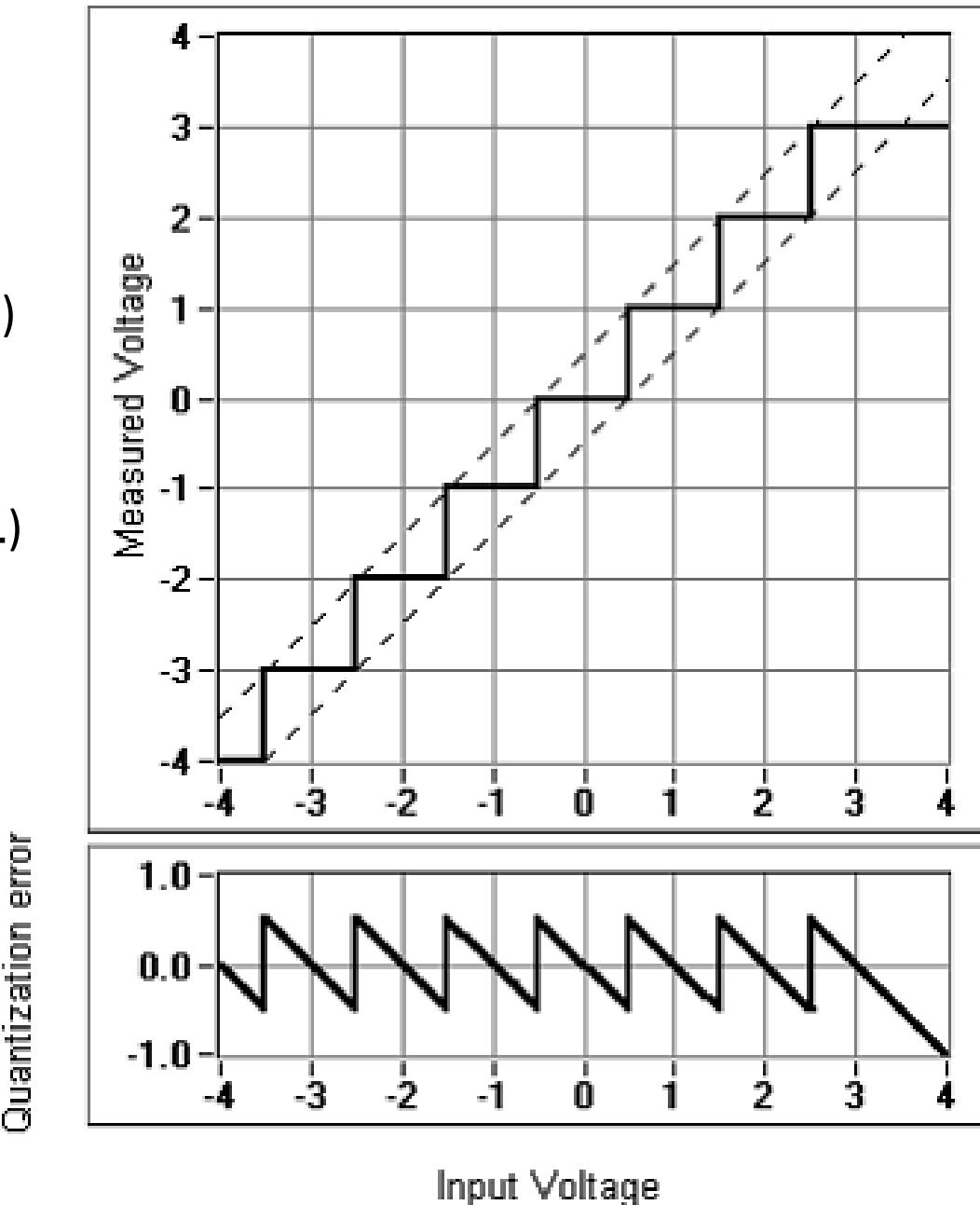
Condition the Sensor Output Voltage by Setting the ADC Range and DC Offset (with a Summing Amplifier)

- Adjust the ADC's range
- Maximize the signal's maximum and minimum values inside the ADC range
- Might require you to try a few different options to optimize



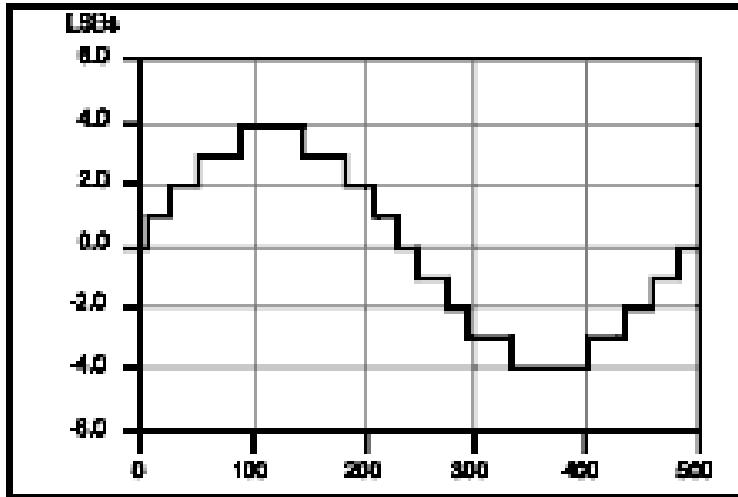
Amplitude Sampling Granularity

- Resolution: the range of analog values represented by a discrete digital value (infinite voltages \rightarrow finite binary values)
- Consider a 12-bit ADC
 - $2^{12} = 4096$ values (**000000000000** through **111111111111**)
 - Each binary value (step) represents $(V_{r+} - V_{r-}) / 4096$
 - For example, $(3.3V - 0V) / 4096$ steps = $806\mu V$ / step
- Larger range $(V_{r+} - V_{r-}) \rightarrow$ less information
- Larger range $(V_{r+} - V_{r-}) \rightarrow$ more quantization error
- More bits \rightarrow more information

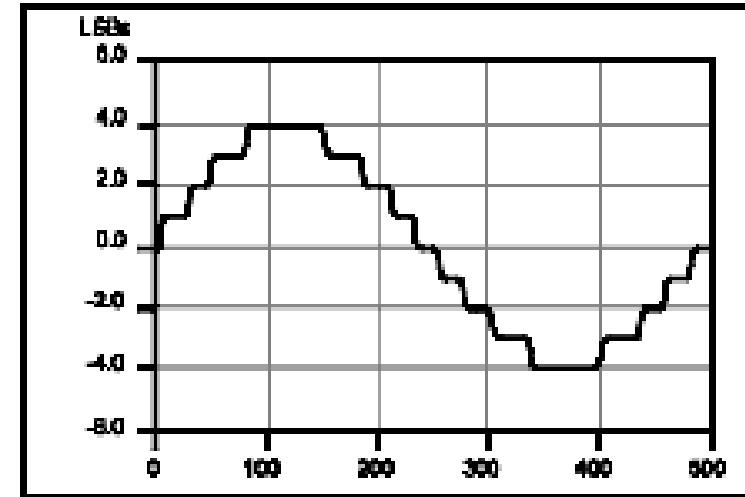


Reduce Quantization Errors with Dithering

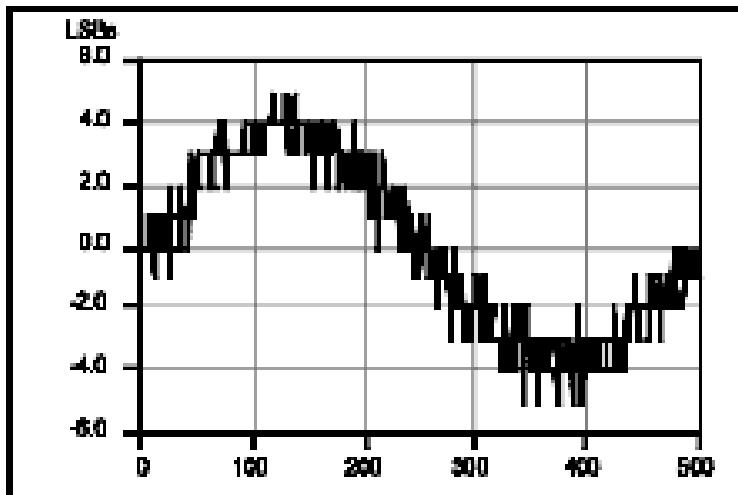
- Quantization errors can result in large-scale patterns that don't accurately describe the analog signal
- Oversample and dither (introduce white noise to randomize the quantization error)
- Many general-purpose microcontroller boards have white noise generation capability for this very reason



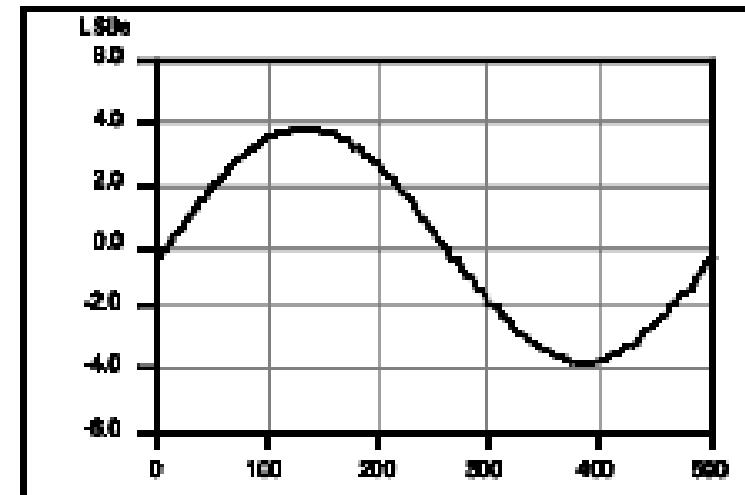
a. Dither disabled; no averaging



b. Dither disabled; average of 50 acquisitions



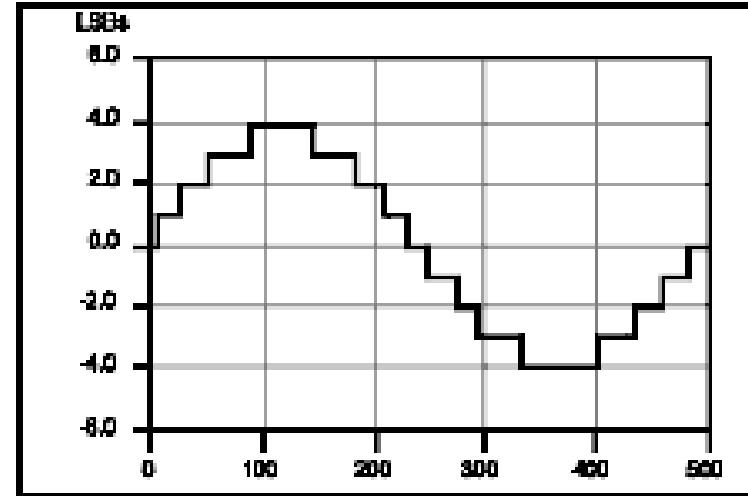
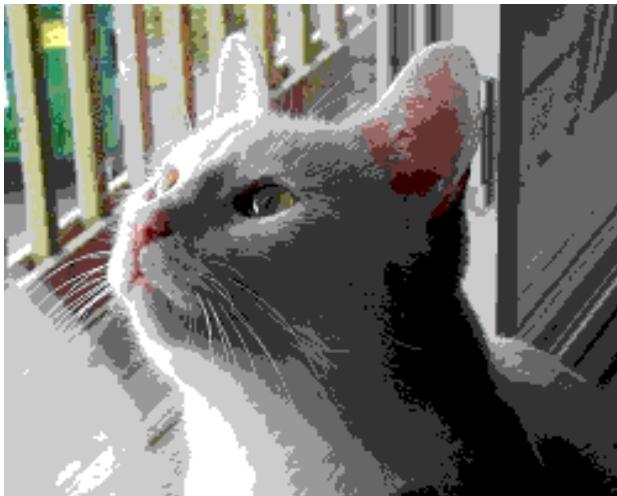
c. Dither enabled; no averaging



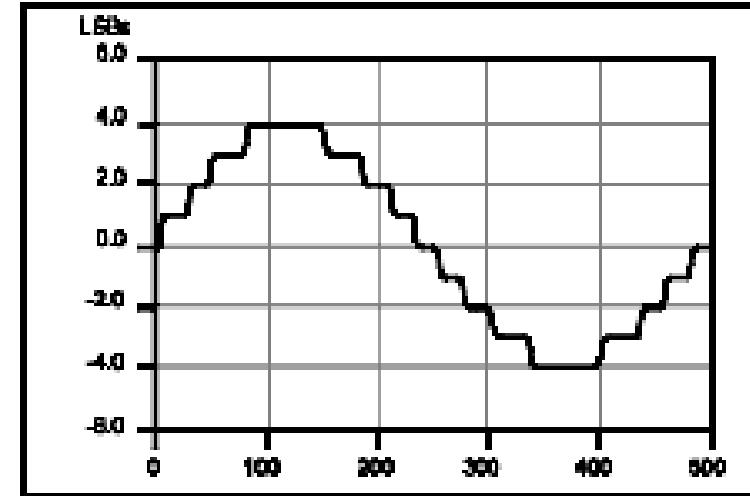
d. Dither enabled; average of 50 acquisitions

Reduce Quantization Errors with Dithering

Dithering
disabled

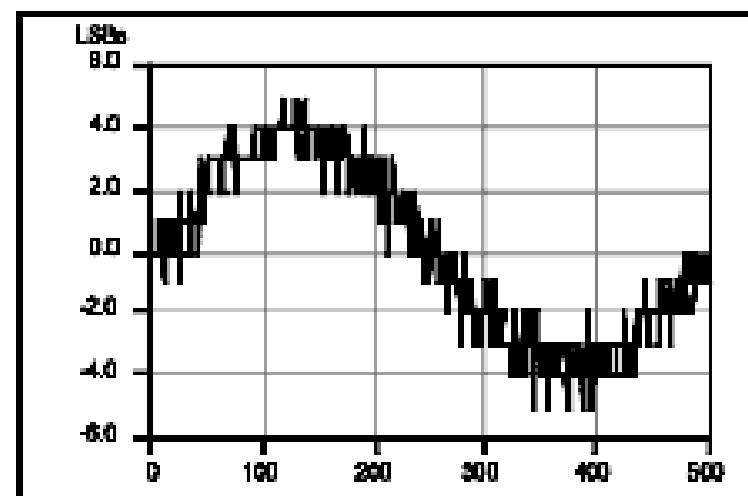


a. Dither disabled; no averaging

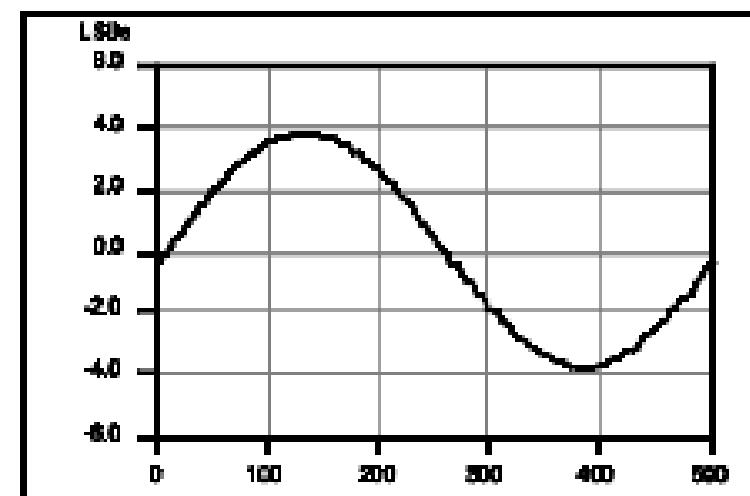


b. Dither disabled; average of 50 acquisitions

Dithering
enabled



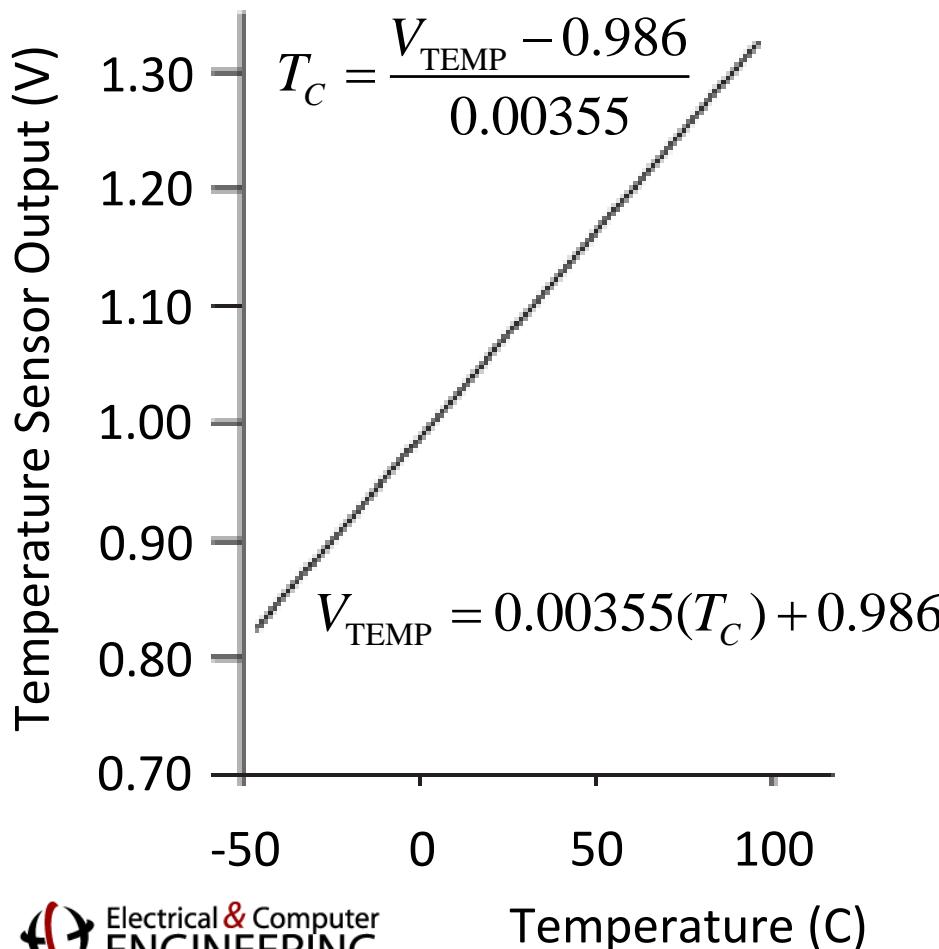
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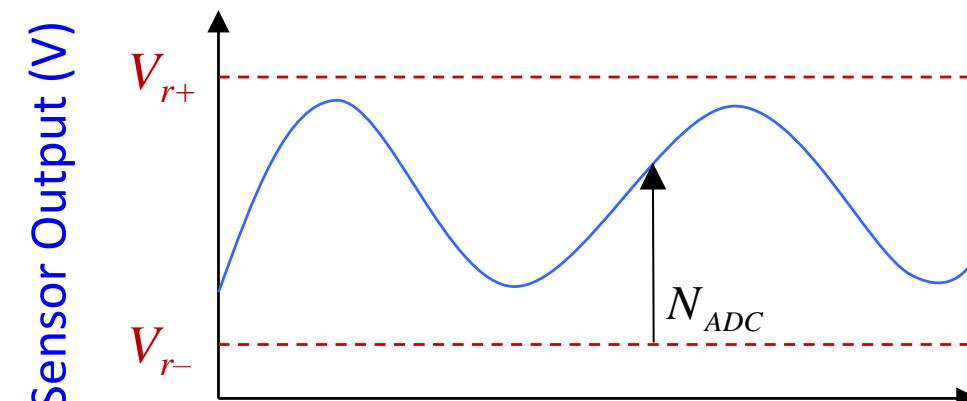
d. Dither enabled; average of 50 acquisitions

Converting Between Temperature, Voltage, ADC Counts, and Engineering Units

■ Converting temperature to voltage



■ Converting voltage to ADC counts or steps (N_{ADC})



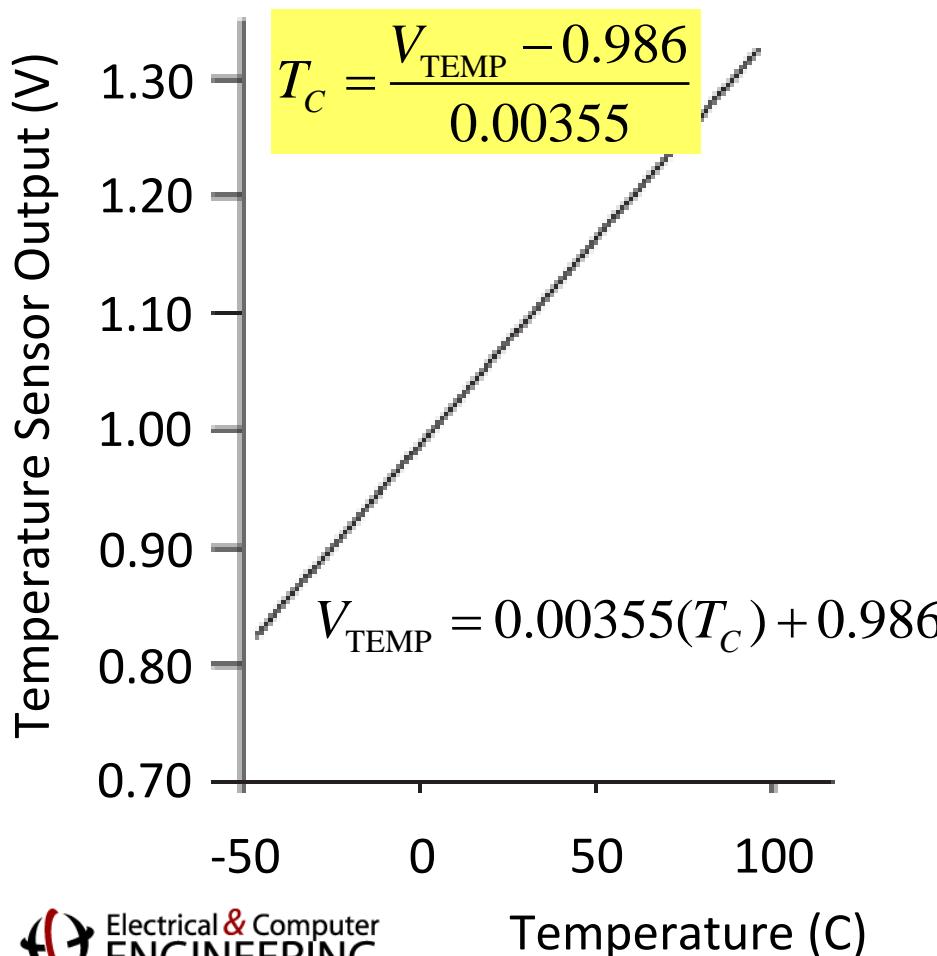
$$N_{ADC} = (2^n - 1) \left(\frac{V_{IN} - V_{r-}}{V_{r+} - V_{r-}} \right) = (2^{12} - 1) \left(\frac{V_{IN} - V_{r-}}{V_{r+} - V_{r-}} \right) = 4095 \left(\frac{V_{IN} - V_{r-}}{V_{r+} - V_{r-}} \right)$$

■ Converting ADC counts to engineering units

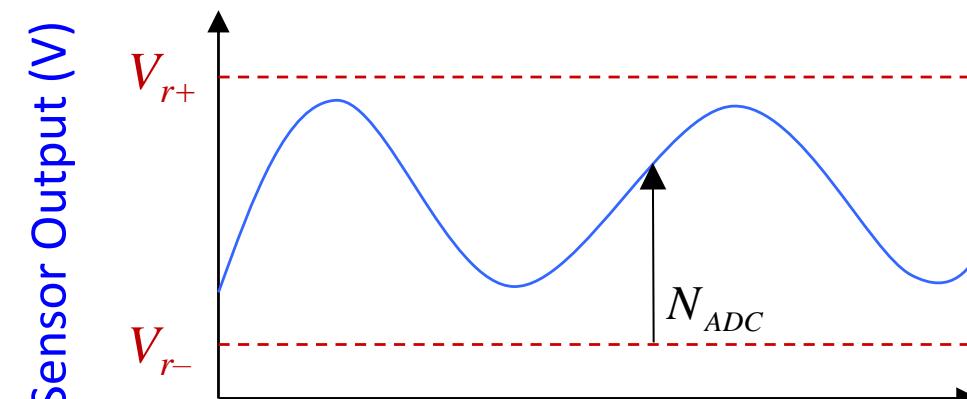
- Convert V_{TEMP} (between 0 and 4095) back into temperature (-40C and +100C)

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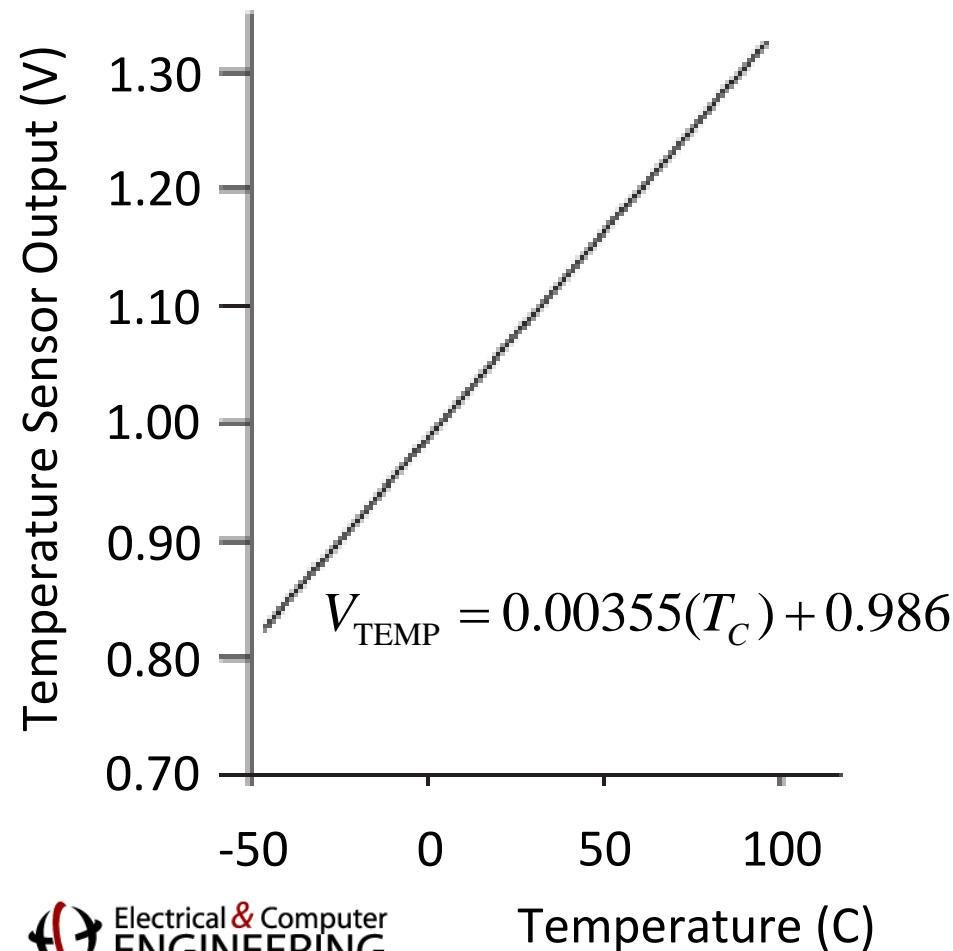


■ Converting ADC counts to engineering units

- Convert N_{ADC} (between 0 and 4095) back into temperature (-40C and +100C)

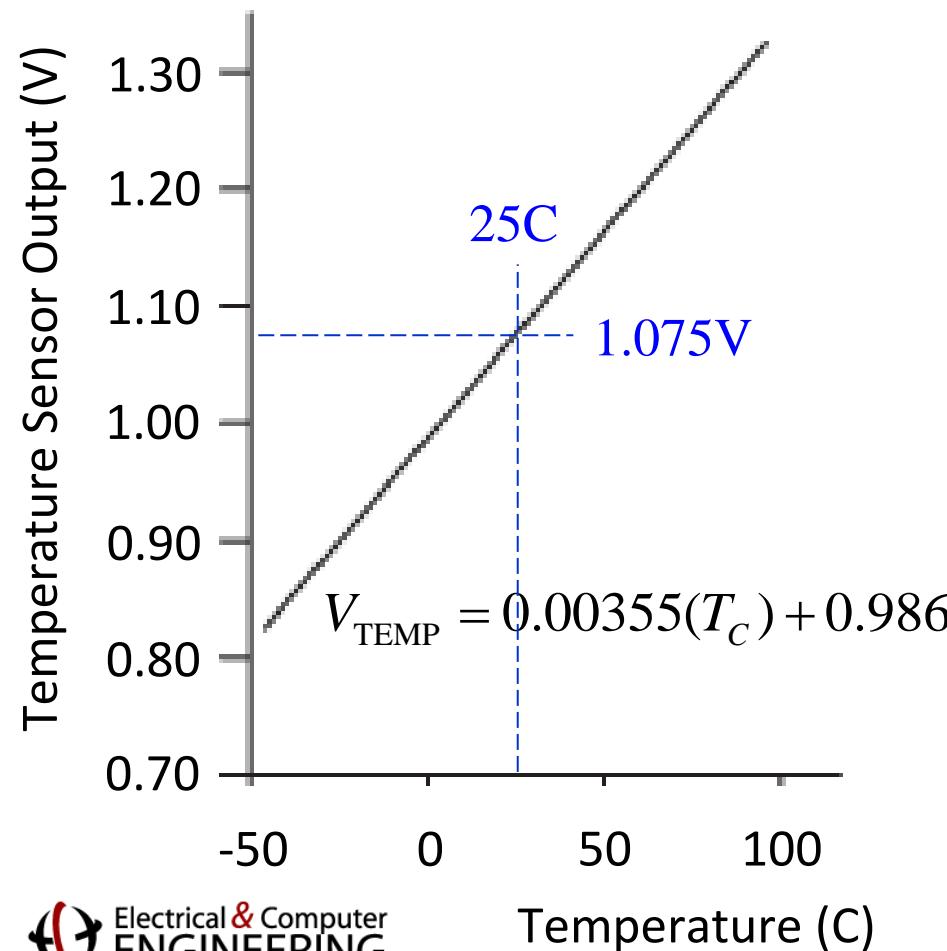
Example: Converting ADC Counts into Engineering Units

- Sensor: $0.8V < V_{OUT} < 1.35V$
- Choose $V_{r+} = 1.500V$ and $V_{r-} = 0.000V$



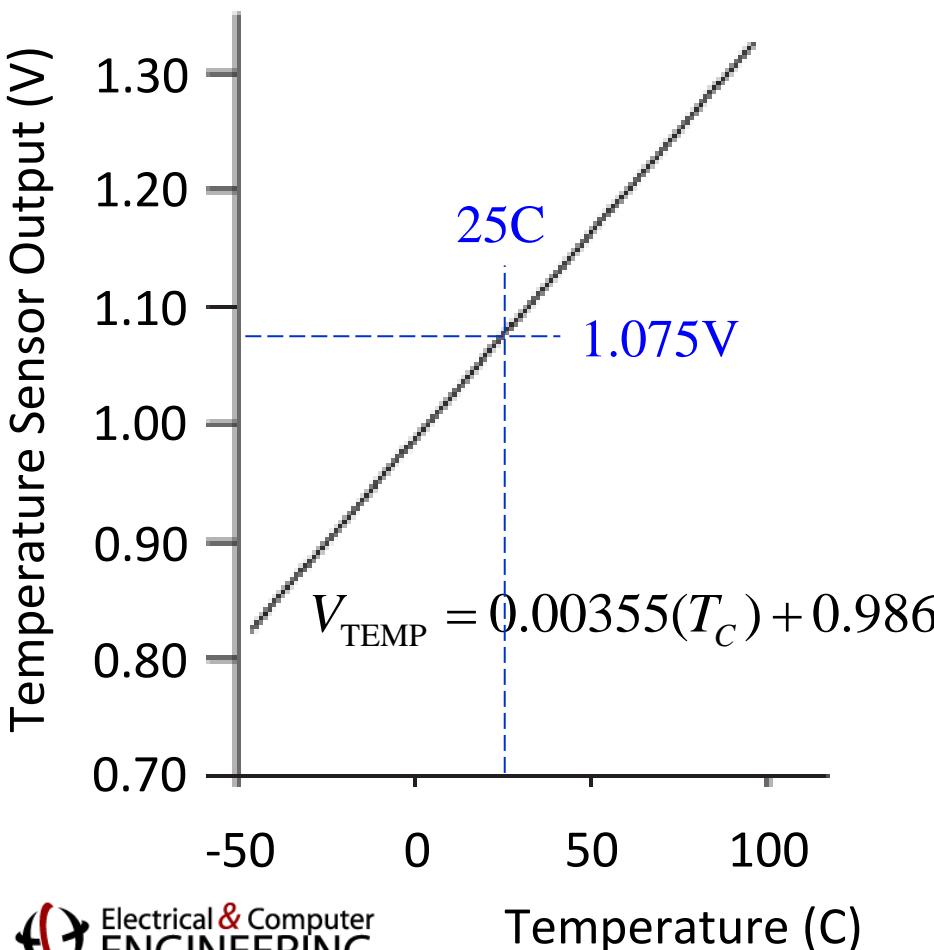
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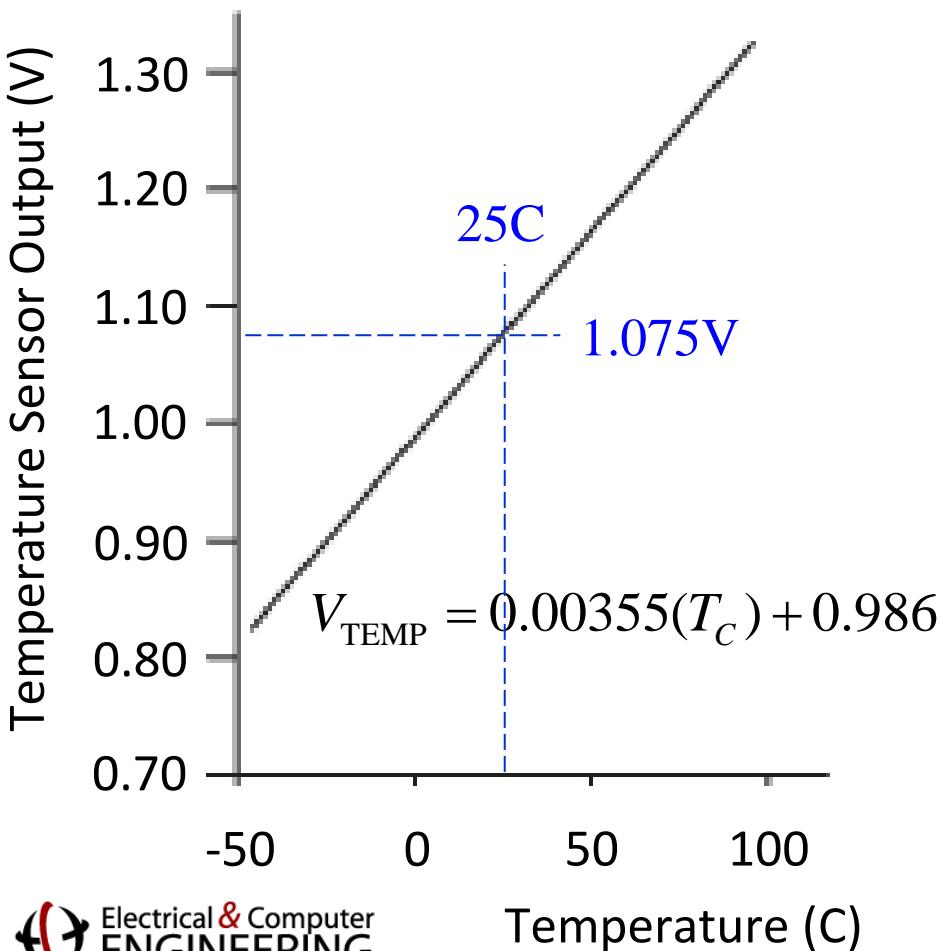


- Converting voltage to ADC counts (N_{ADC})

$$N_{ADC} = 4095 \left(\frac{V_{IN} - V_{r-}}{V_{r+} - V_{r-}} \right) = 4095 \left(\frac{1.075V - 0V}{1.500V - 0V} \right) = 2,934 \text{ steps}$$

Example: Converting ADC Counts into Engineering Units

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- Converting voltage to ADC counts (N_{ADC})
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- Converting ADC counts (N_{ADC}) to temperature
- $$V_{IN} = \left(\frac{N_{ADC}}{4095} \right) \left(V_{r+} - V_{r-} \right) + V_{r-}$$
- $$V_{IN} = \left(\frac{2934}{4095} \right) \left(1.5V \right) + 0V = 1.075V$$
- Converting voltage back into temperature
- $$T_c = \frac{V_{TEMP} - 0.986}{0.00355} = \frac{1.075 - 0.986}{0.00355} = 25C$$

Example: Converting ADC Counts into Engineering Units

- Sensor: $0.8V < V_{OUT} < 1.35V$
- Choose $V_{r+} = 1.500V$ and $V_{r-} = 0.000V$
- $T_C = 25C \rightarrow V_{OUT} = 1.075V$
- $V_{OUT} = 1.075V \rightarrow N_{ADC} = 2,934$ steps
- Program converts 2,934 steps back to 25C

$$V_{IN} = \left(\frac{2934}{4095} \right) (1.5V) + 0V = 1.075V$$

$$T_c = \frac{V_{TEMP} - 0.986}{0.00355} = \frac{1.075 - 0.986}{0.00355} = 25C$$

```

int main() {
    int adccount = 2934;
    float range = 1.5;
    float vtemp;
    float tempc;

    vtemp = adccount/4095 * range;
    tempc = (vtemp-0.986)/0.00355;
    printf("vtemp: %f\n", vtemp);
    printf("tempc: %f\n", tempc);
}

```

Example: Converting ADC Counts into Engineering Units

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    vtemp = adccount/4095 * range;
    tempc = (vtemp-0.986)/0.00355;
    printf("vtemp: %f\n", vtemp);
    printf("tempc: %f\n", tempc);
}
```

```
$ gcc arithmetic.c
```

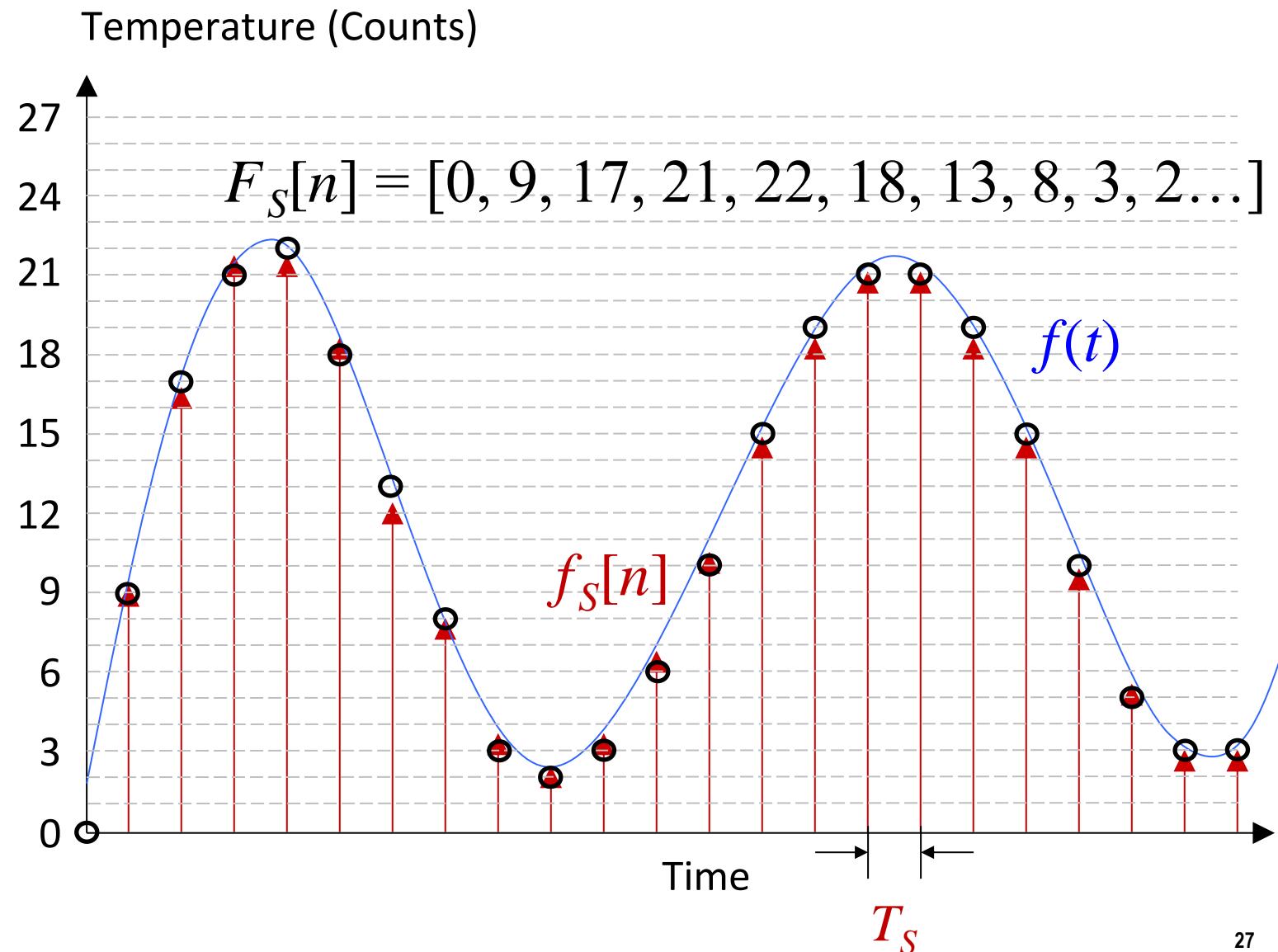
```
$ ./a.out
vtemp: 0.000000
tempc: -277.746490
```

Final Thoughts on Amplitude

- Sensor provides a range of voltages for inputs of interest to us
- Use op amps to convert those voltages into a desired ADC range of voltages
- Use the full range of the ADC, perhaps with a small margin
- Choose an ADC with enough bits to provide the resolution required ($Cost \propto e^{\# \text{ of bits}}$)
- Understand ADC and DAC errors will be a fact-of-life
- Carefully write your code to manipulate values without losing resolution of your data
- Be careful about each arithmetic operation
- Be careful about software emulation of floating-point numbers

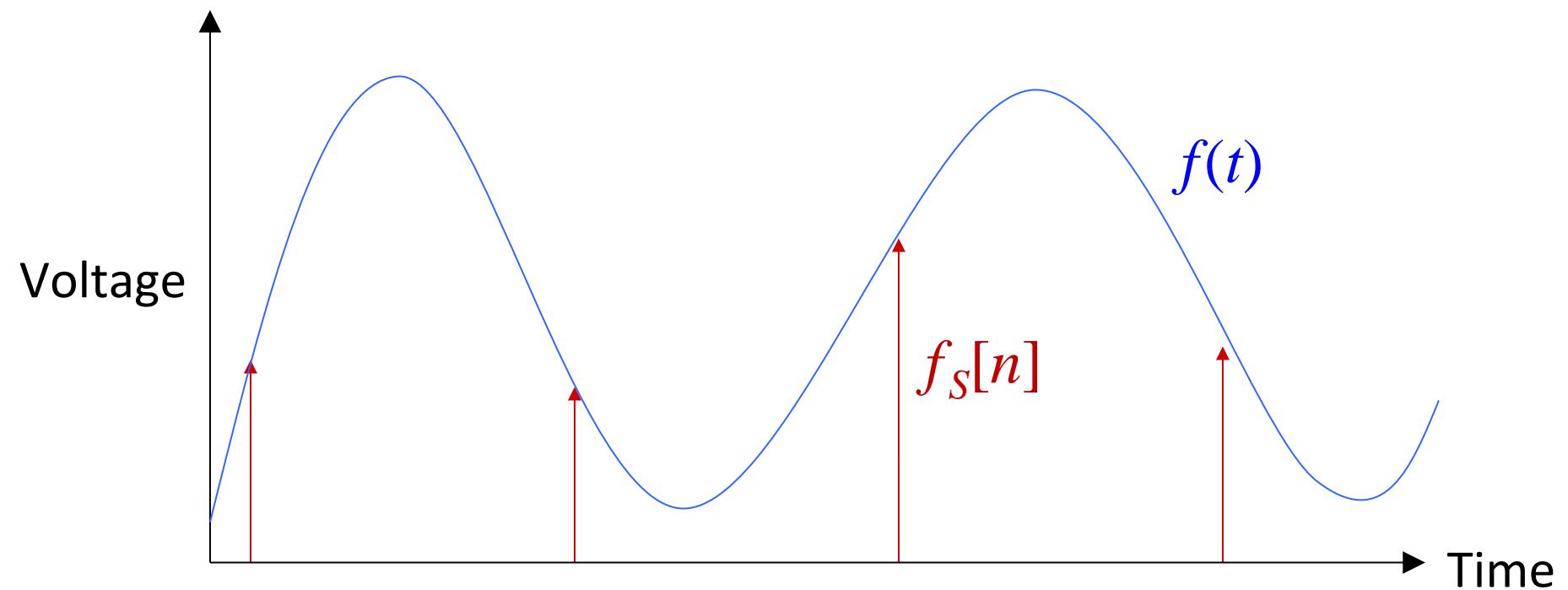
Continuous-Time Data and Discrete-Time Sampling

- x-axis is often time
- y-axis is often amplitude
- Both are often analog and continuous signals
- Sample every T_S seconds to create a discrete-time signal
- Sample amplitude with a finite step-size to create a digital, discrete-value signal



Choosing a Sampling Rate

- ADC peripherals have a maximum sampling rate
- In addition, your program may be limited in how often it can read an ADC sample
- Sample too slowly: We can't reconstruct the signal we care about
- Sample too quickly: Waste computation, energy, resources



Nyquist-Shannon Sampling Theorem

- If a continuous-time signal contains no frequencies higher than f_{max} , it can be completely determined by discrete samples taken at a rate of

$$f_{sampling} > 2f_{max}$$

- For example, most people can “hear” audio signals between 20Hz and 20kHz
- Audio CDs: Sampled at 44.1kHz



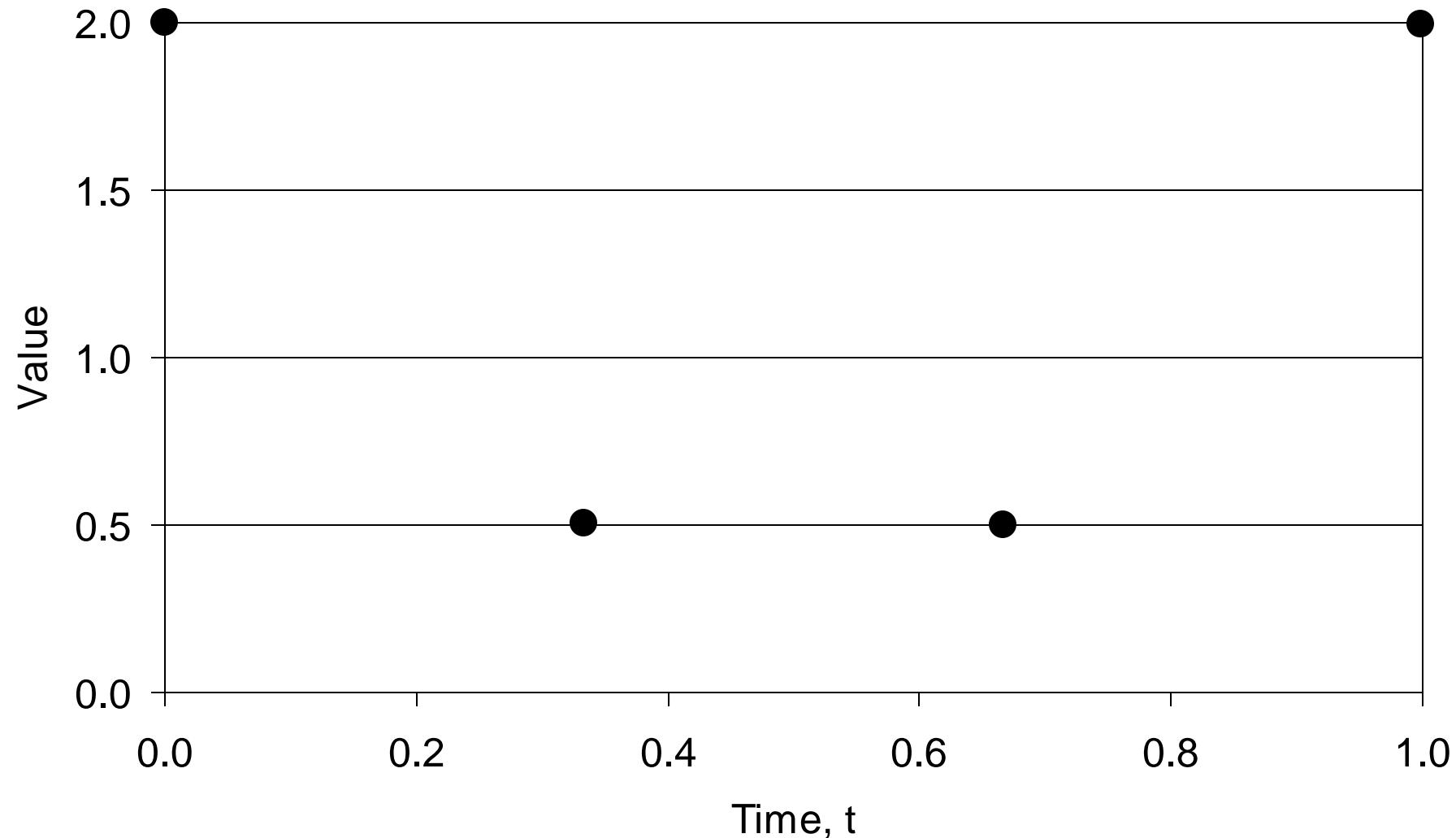
Song sampled at 44.1kHz



Same song sampled at 1,024Hz (distorts frequencies above 512Hz)

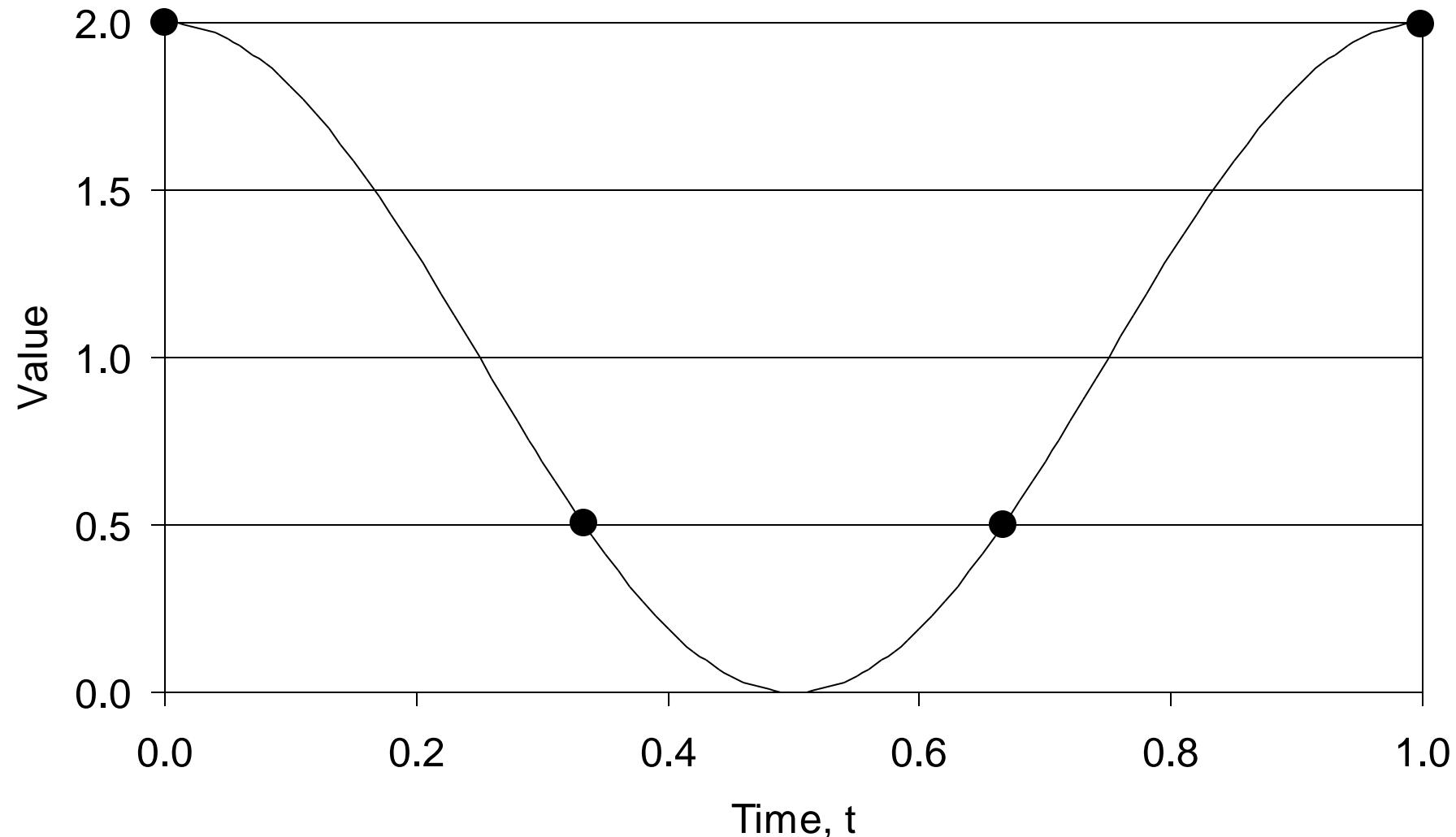
Aliasing

Samples of Different Signals Have the Same Sampled Values



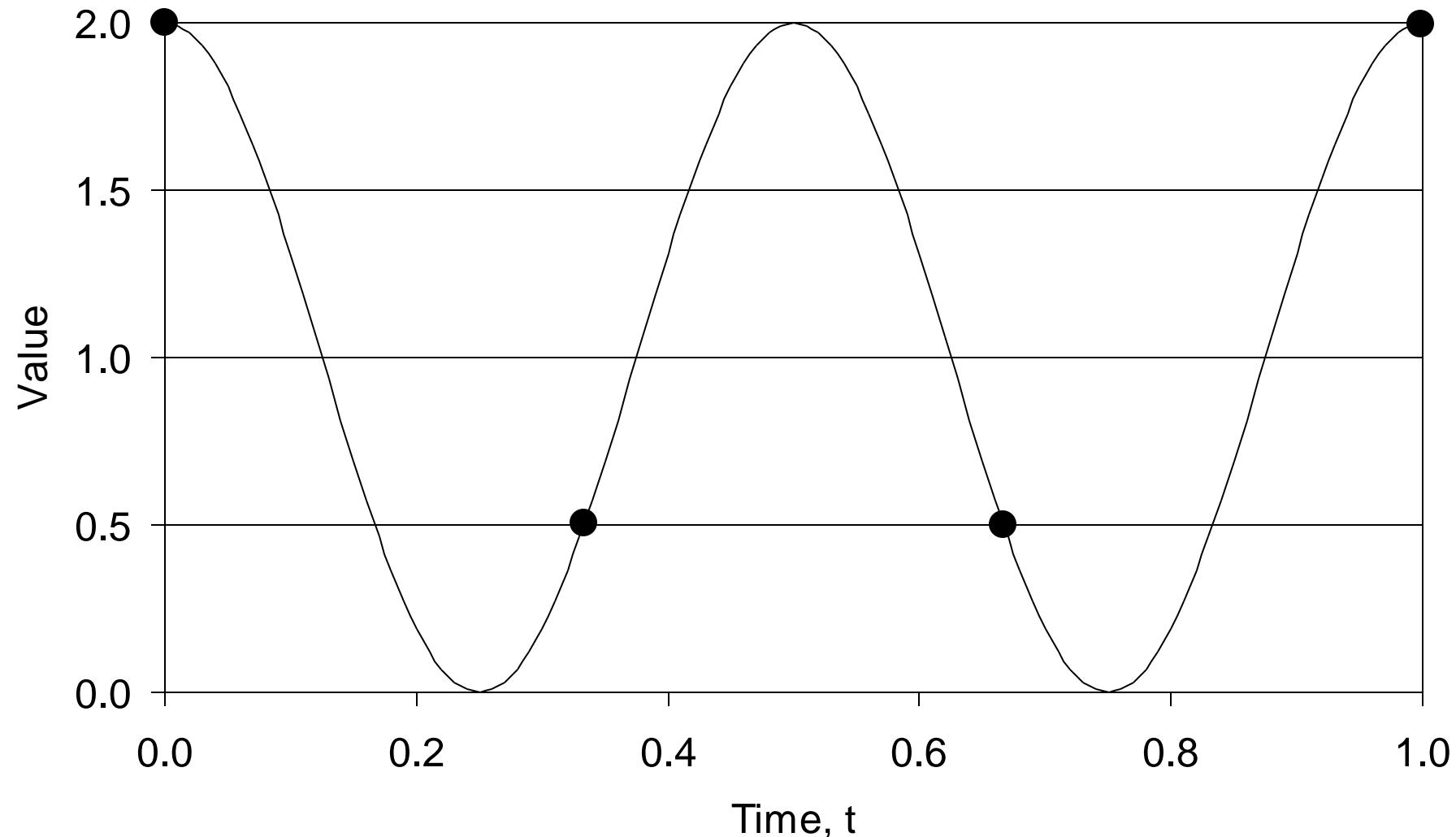
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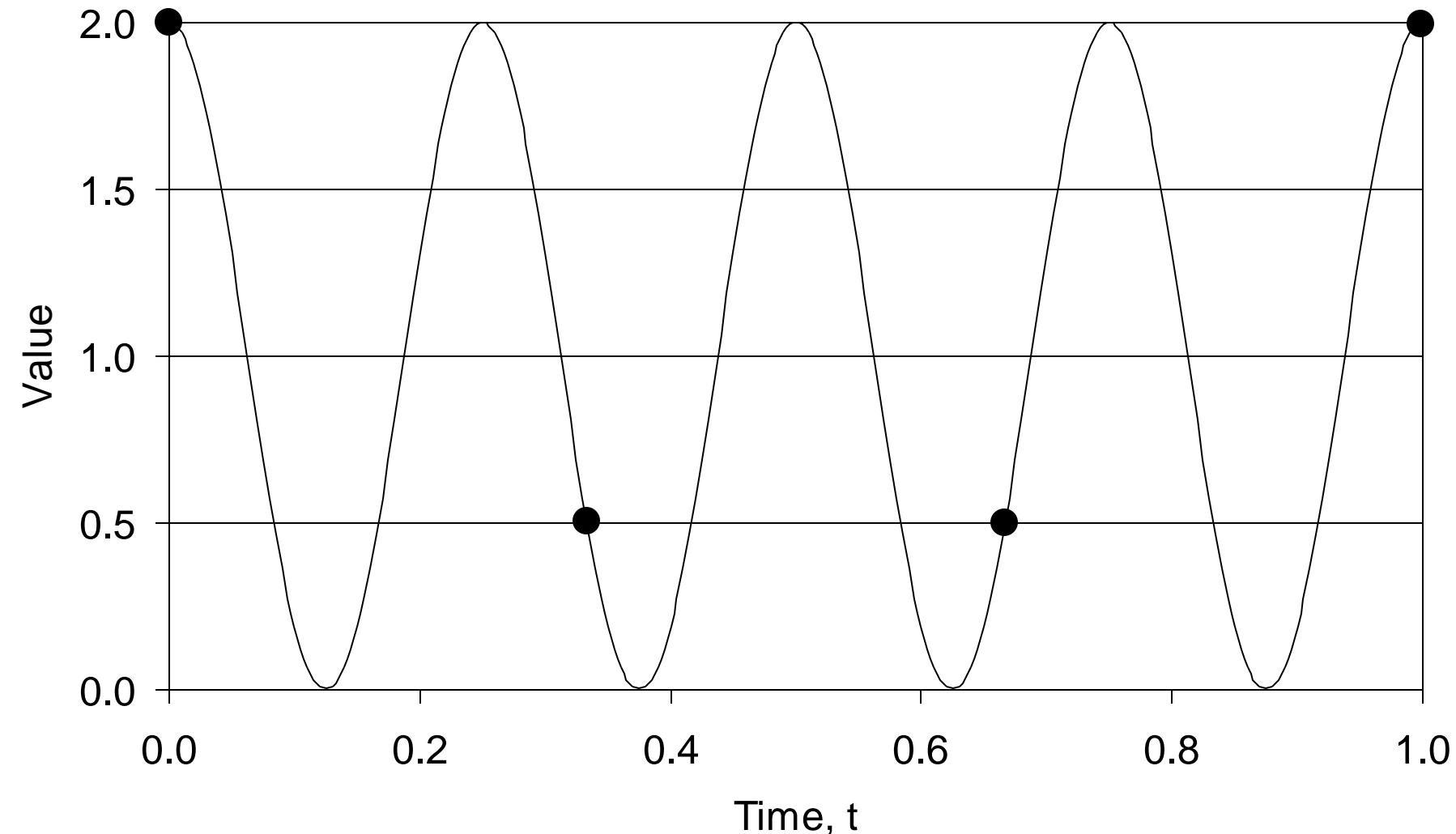
Aliasing

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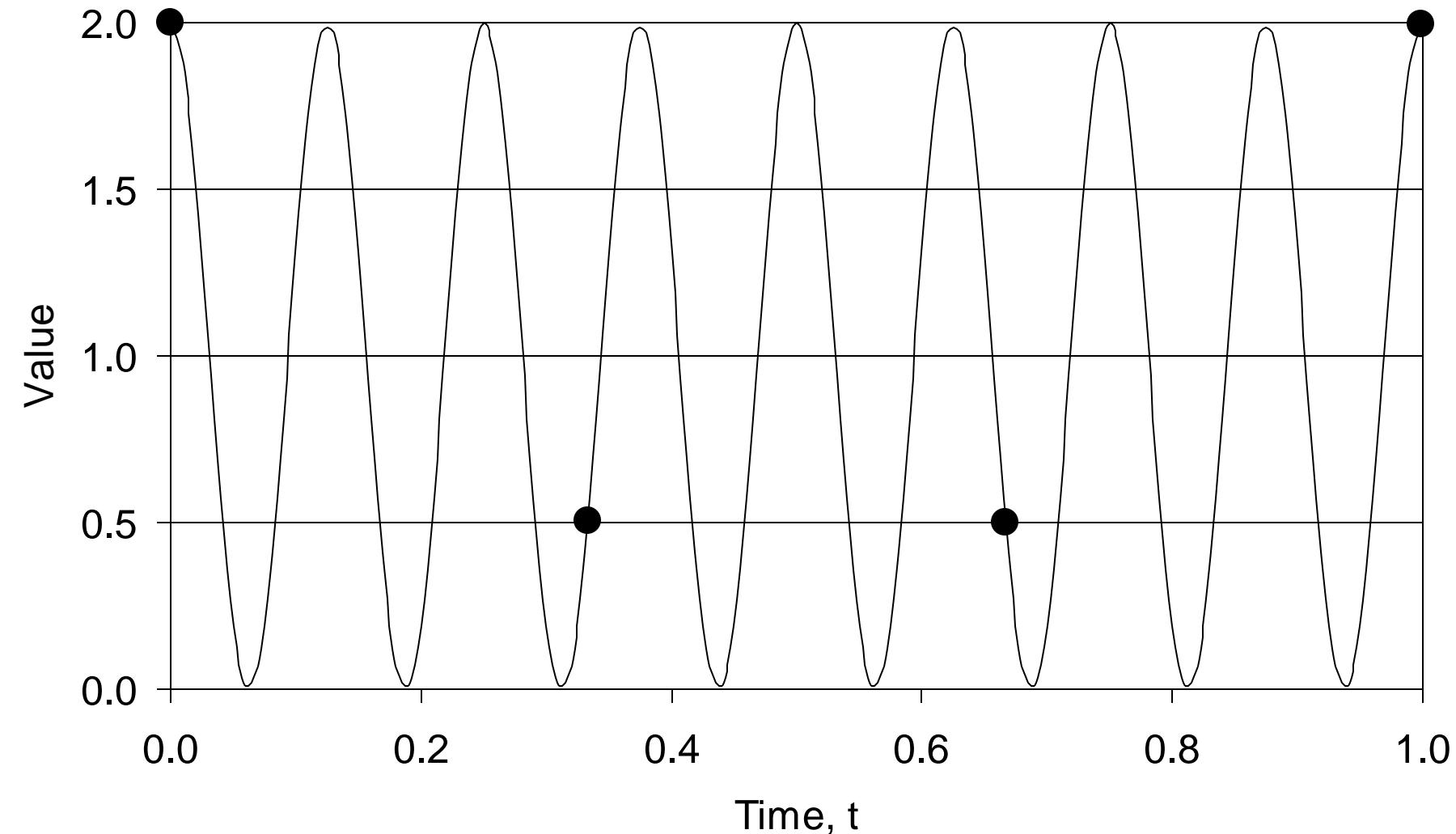
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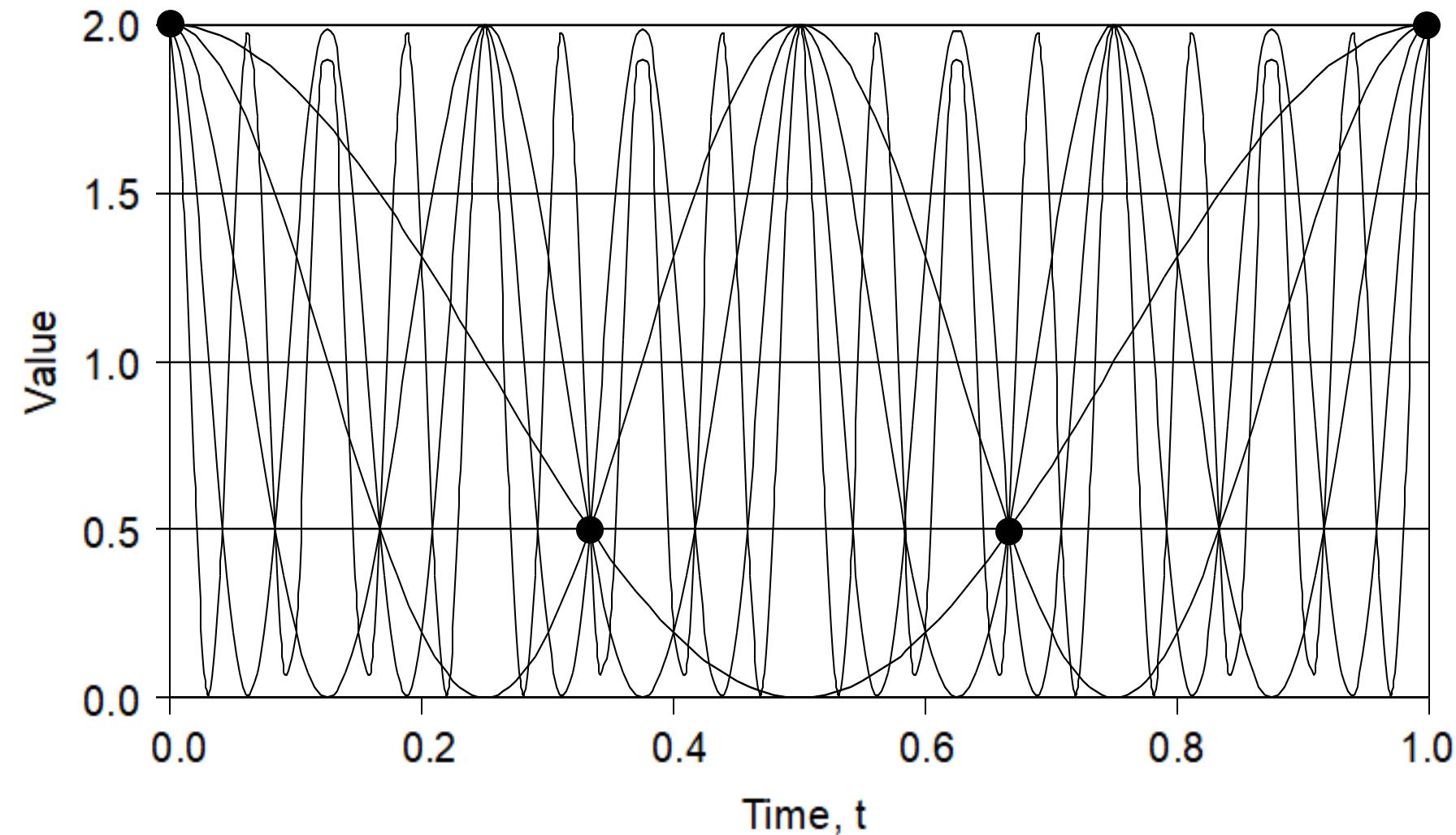
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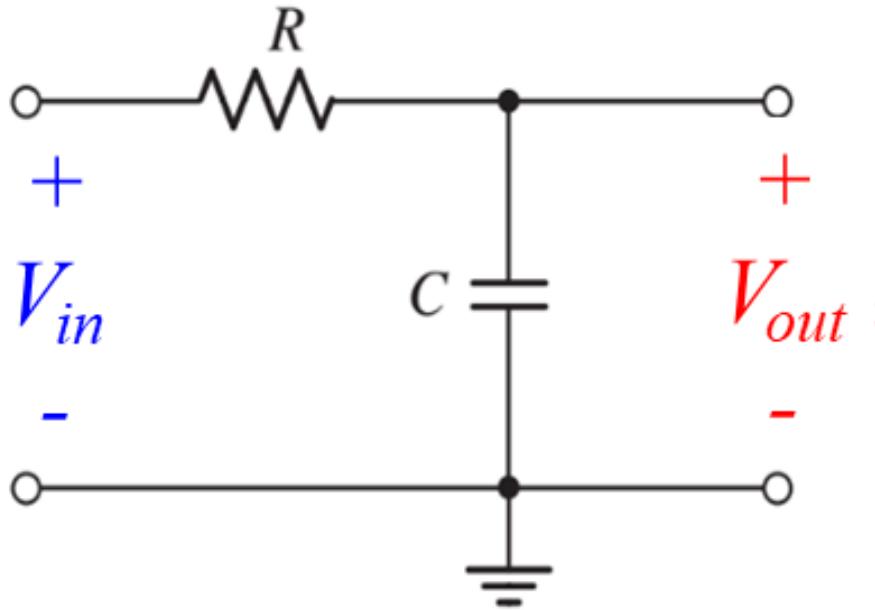
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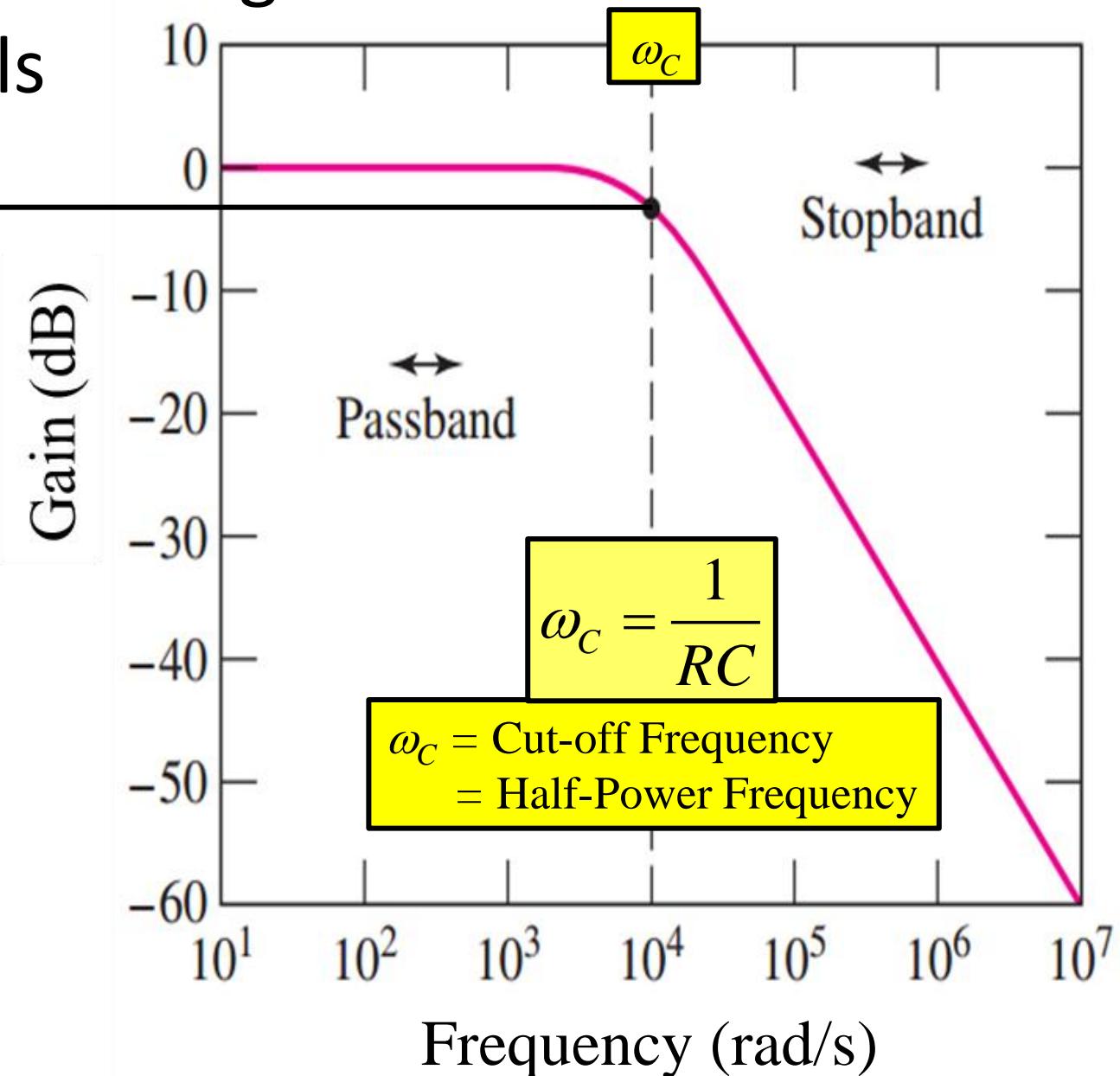
COMING ATTRACTIONS: Anti-Aliasing Filter:

Reduce High Frequency Signals

$$Gain(\text{dB}) = 20 \log_{10} \left| \frac{V_{out}}{V_{in}} \right|$$



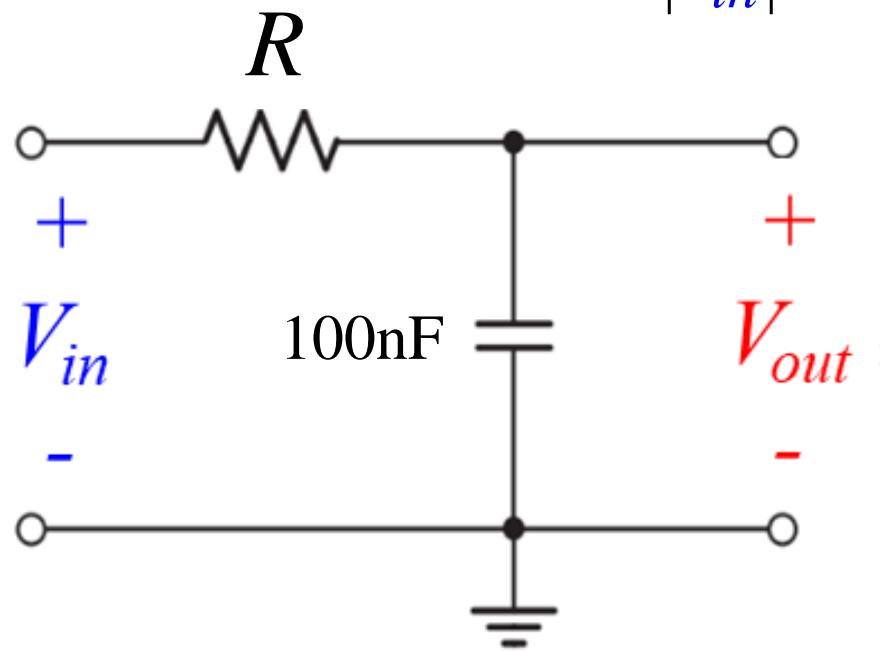
-3dB
70.7%



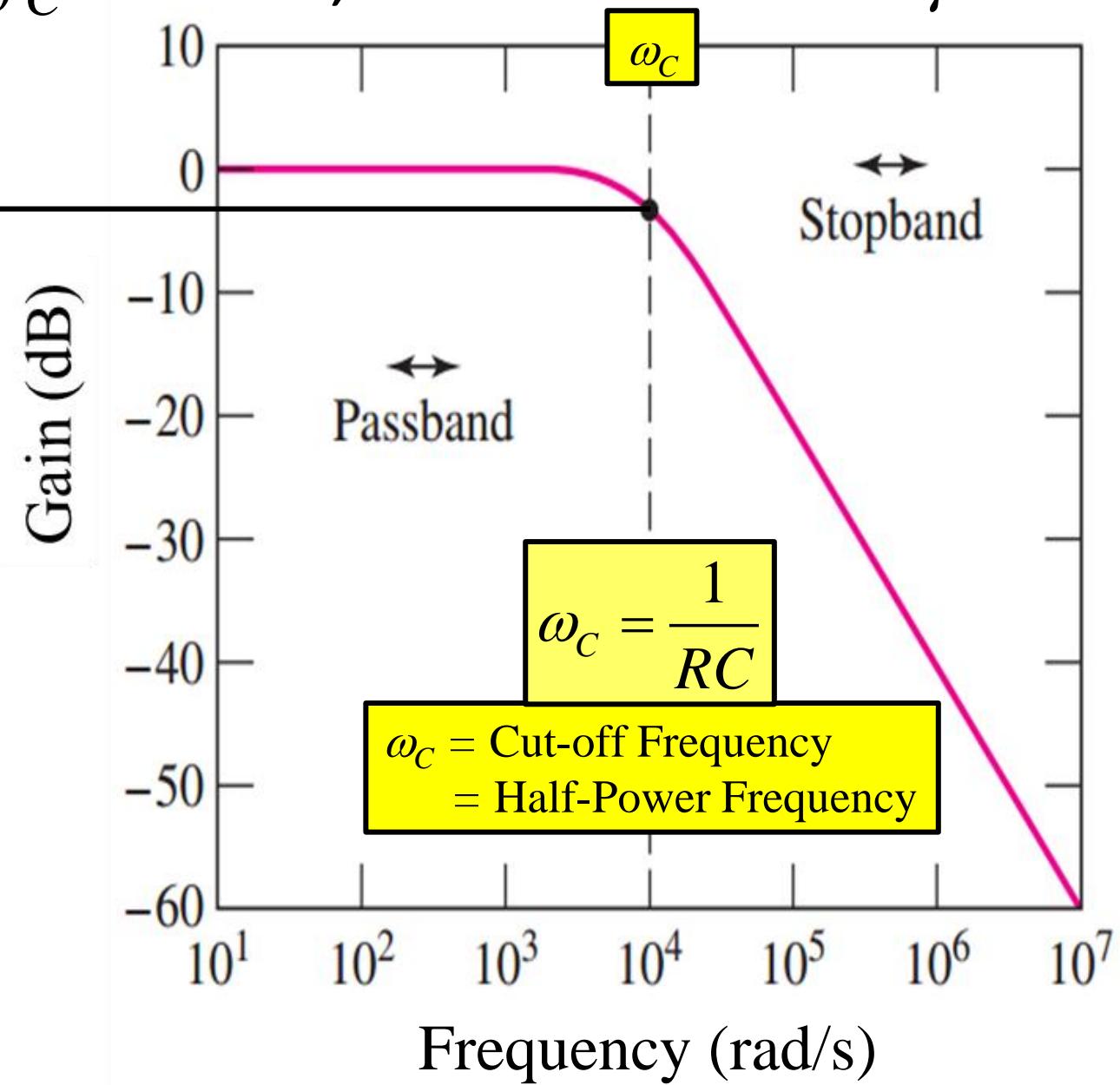
Anti-Aliasing Filter: Example, $f_C = 30\text{Hz}$, $C = 100\text{nF} = 0.1\mu\text{F}$

Find R

$$Gain(\text{dB}) = 20 \log_{10} \left| \frac{V_{out}}{V_{in}} \right|$$



-3dB
70.7%



Do I Really Need to Add a Signal Conditioning Circuit in Front of an ADC Input?

- Short answer: Yes
- Long answer: Yes, but sometimes it's already done for you.
- Many ADCs have a pretty good analog filter built in
 - Integrated filters typical have f_C near 50% of their maximum sampling rate (Nyquist-Shannon)
 - Works well if you are sampling at maximum rate (max power, max busy....)
 - Does not work well if you are sampling below the maximum rate
- An additional filter will only further reduce higher frequency components

Agenda

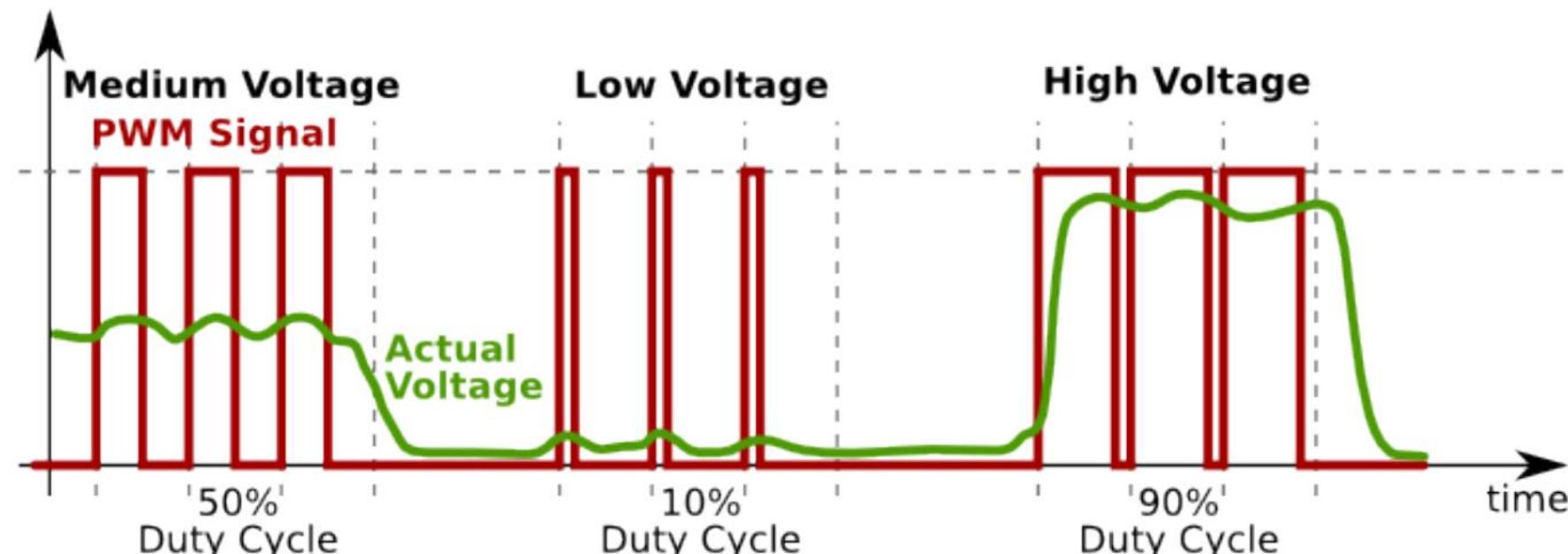
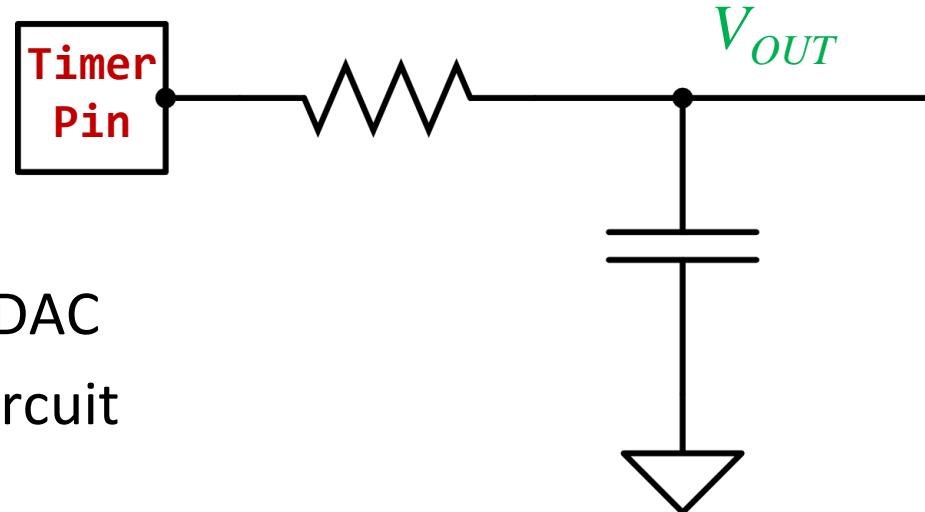
- Analog and Digital Worlds – The Problem with Pizza
- Analog to Digital Converters (ADCs)
- Digital to Analog Converters (DACs)

Do It Yourself DAC

- DACs are expensive circuits
- Very rare for a MCU to have a DAC
- Usually, they are an external circuit you have to purchase

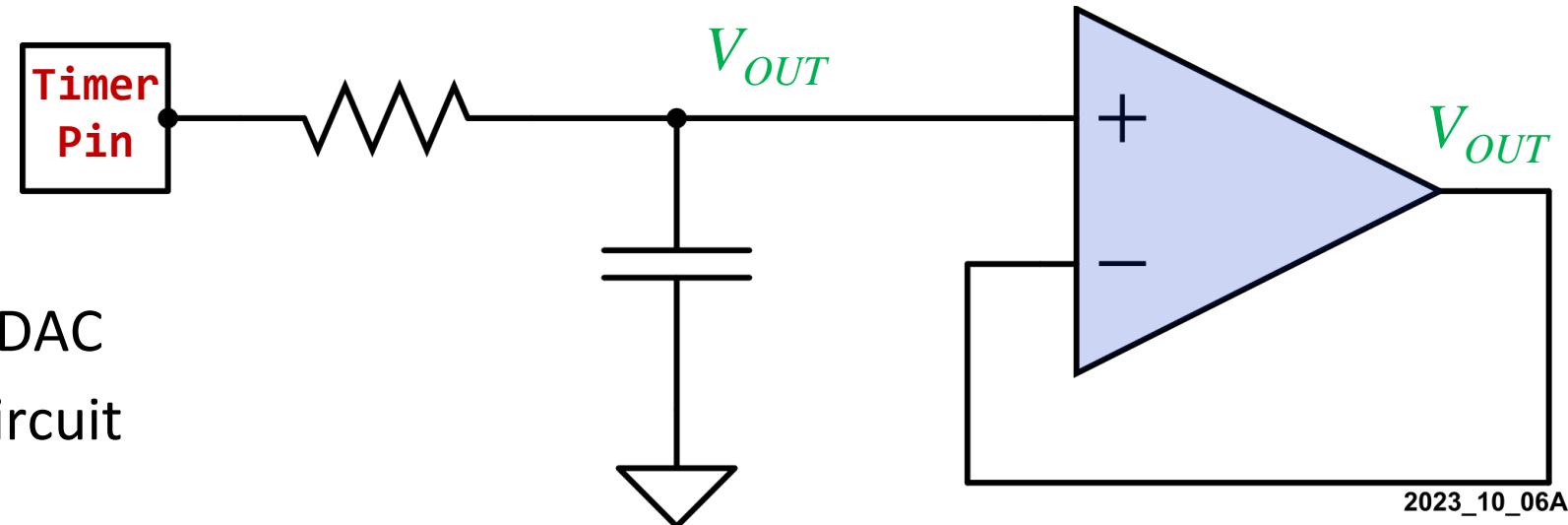
Do It Yourself DAC

- DACs are expensive circuits
- Very rare for a MCU to have a DAC
- Usually, they are an external circuit you have to purchase
- You can make a low-quality DAC with just a PWM timer and an RC circuit

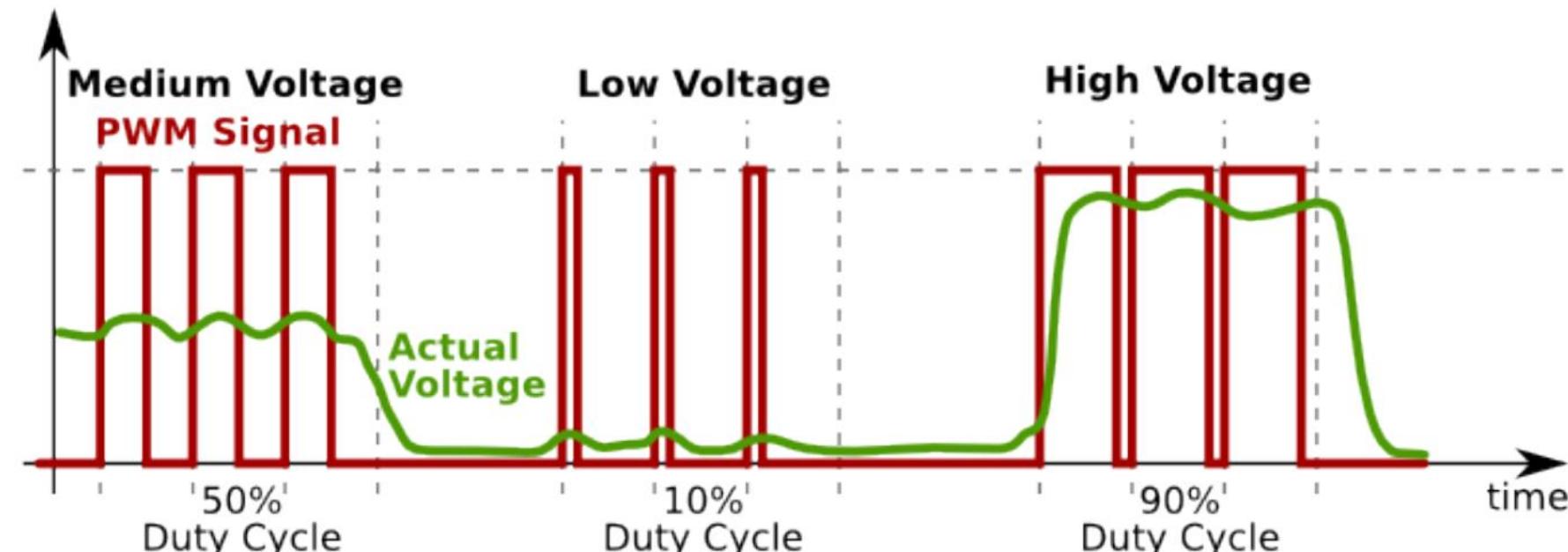


Do It Yourself DAC

- DACs are expensive circuits
- Very rare for a MCU to have a DAC
- Usually, they are an external circuit you have to purchase
- You can make a low-quality DAC with just a PWM timer and an RC circuit
- **Use an op amp to increase output current**



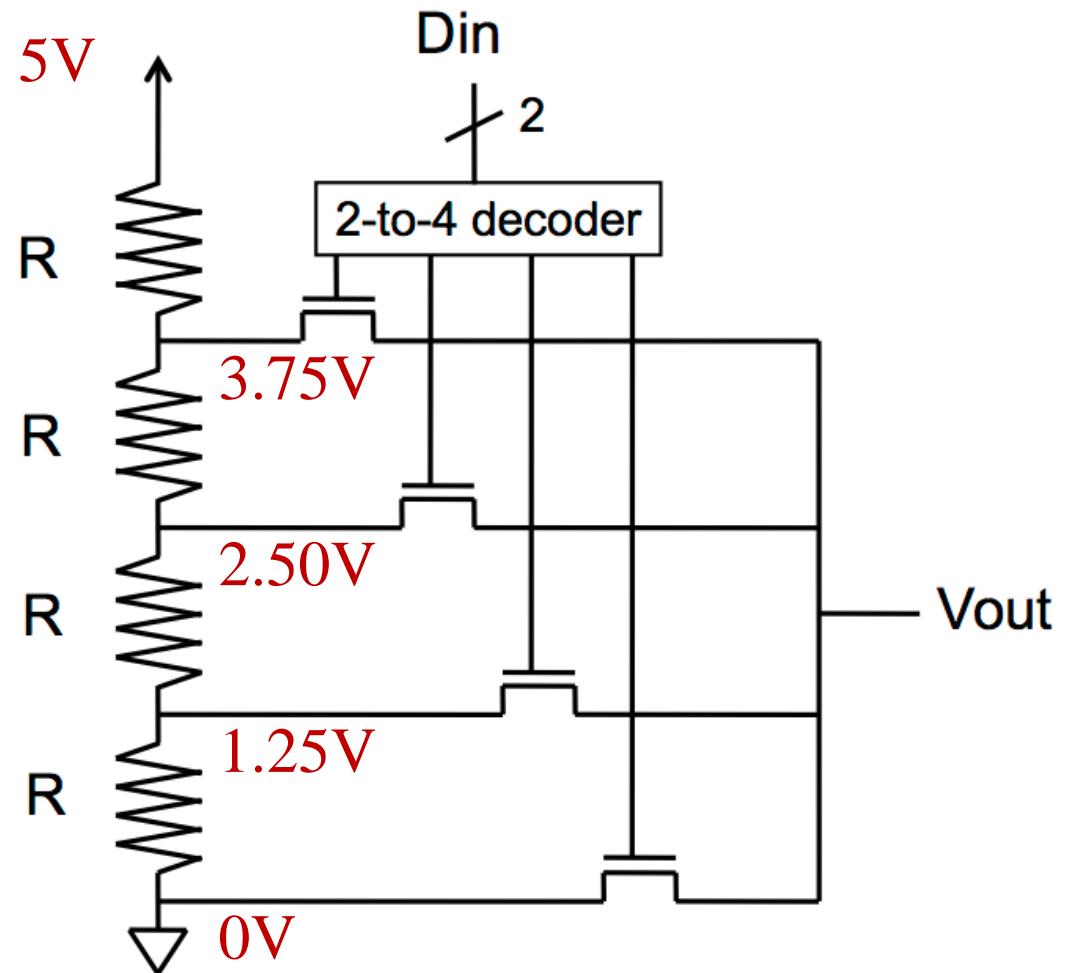
2023_10_06A



Resistance Ladder DAC

■ Advantages

- Extremely Fast!
- Monotonic: Output voltage always increases with DAC step count



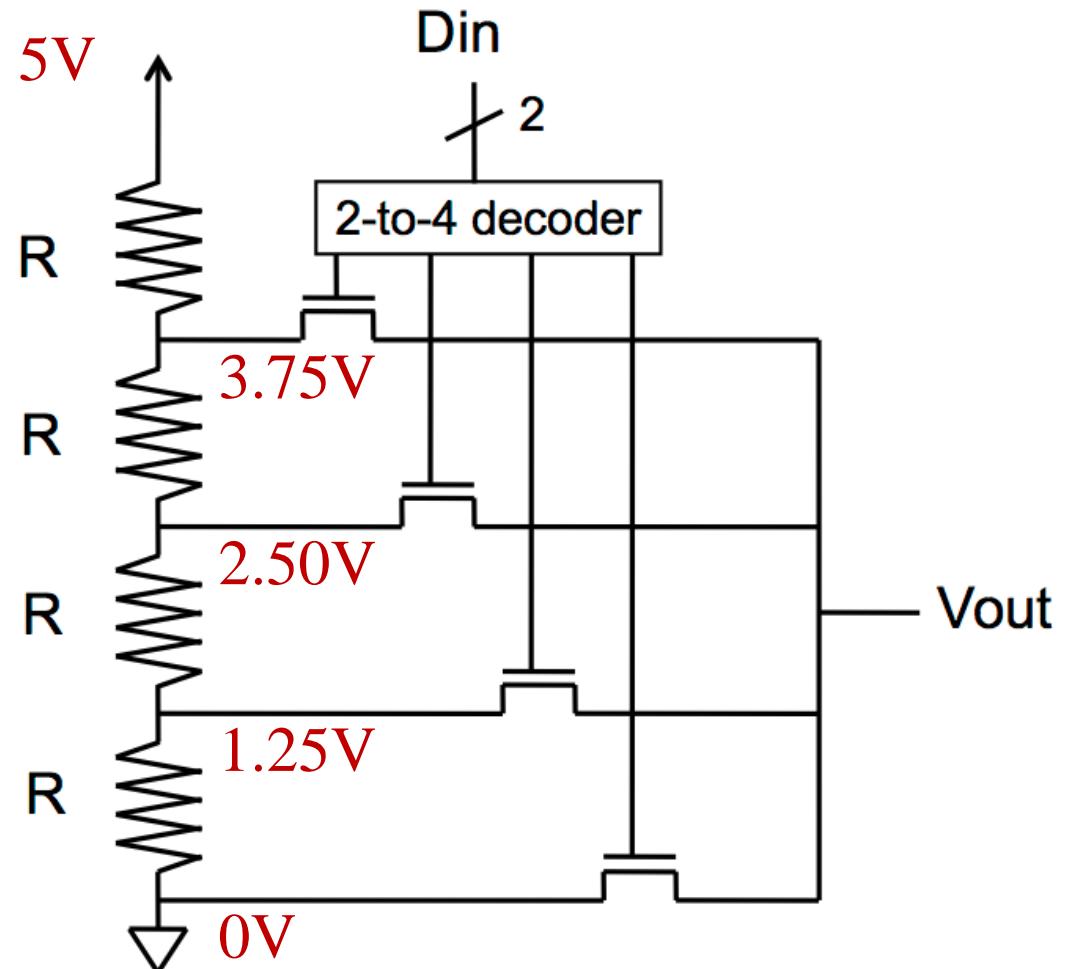
Resistance Ladder DAC

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■ Disadvantages

- One resistor and one transistor required per each output voltage level (N-bit DAC requires 2^N resistors and transistors)
- Large decoder needed $\log_2 N$ -to-N
- Each extra bit doubles the size



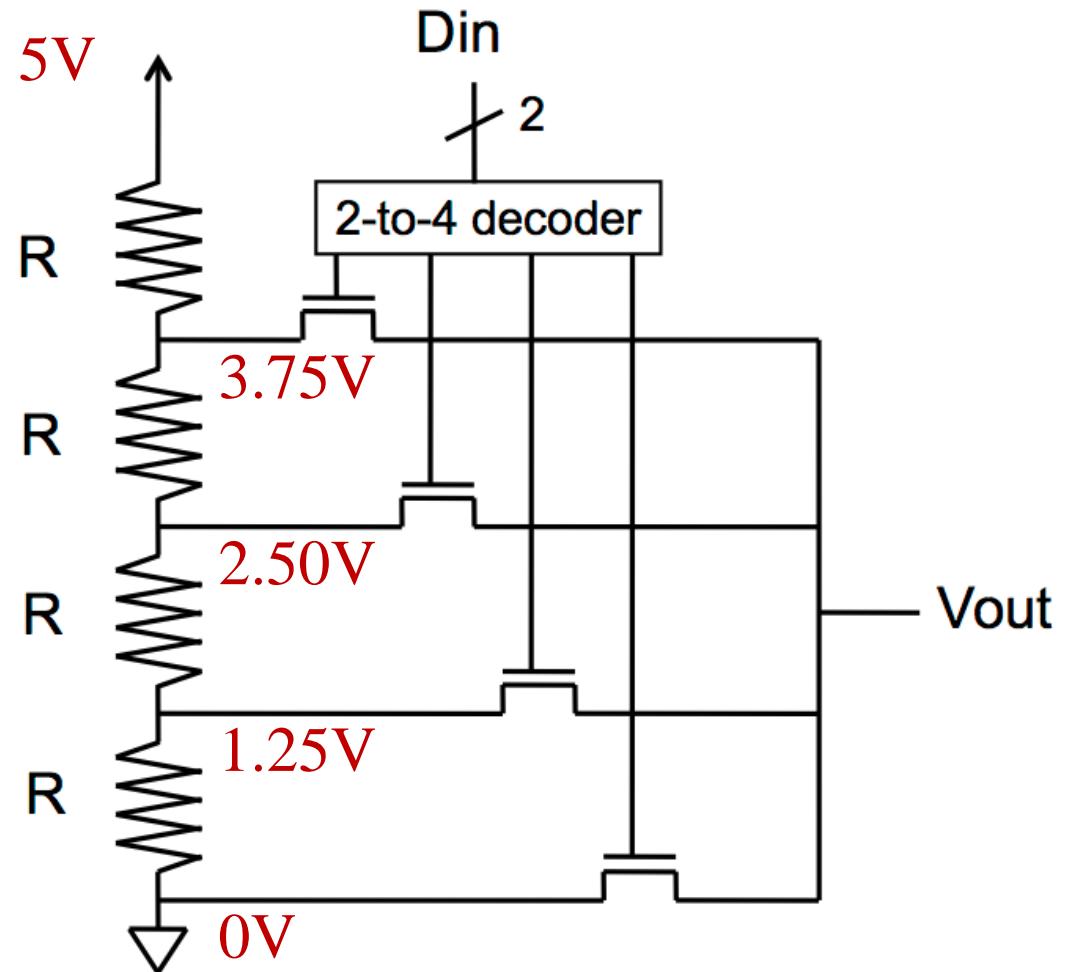
Resistance Ladder DAC

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■ Disadvantages

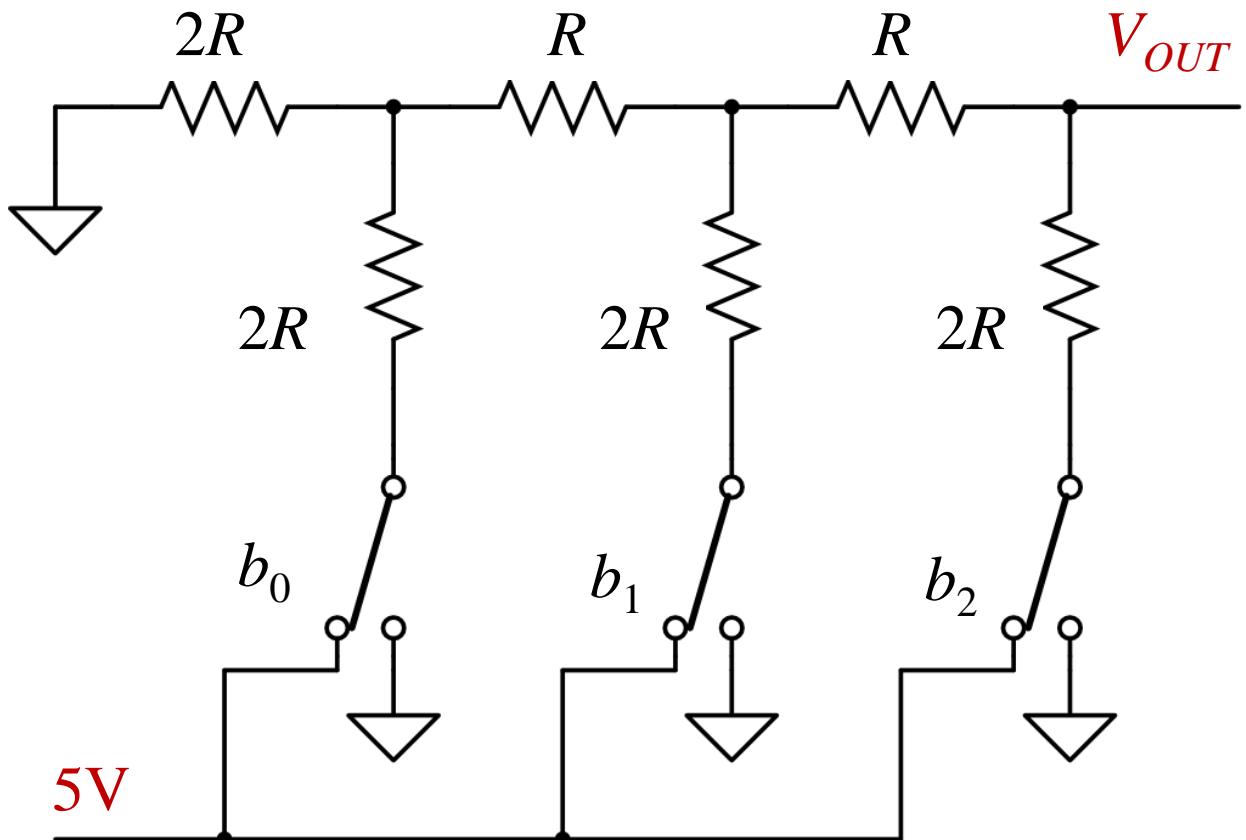
- One resistor and one transistor required per each output voltage level (N-bit DAC requires 2^N resistors and transistors)
- Large decoder needed $\log_2 N$ -to-N
- Each extra bit doubles the size
- Accuracy requires matched resistors
- Use an op amp buffer to increase current drive



$R-2R$ Ladder DAC

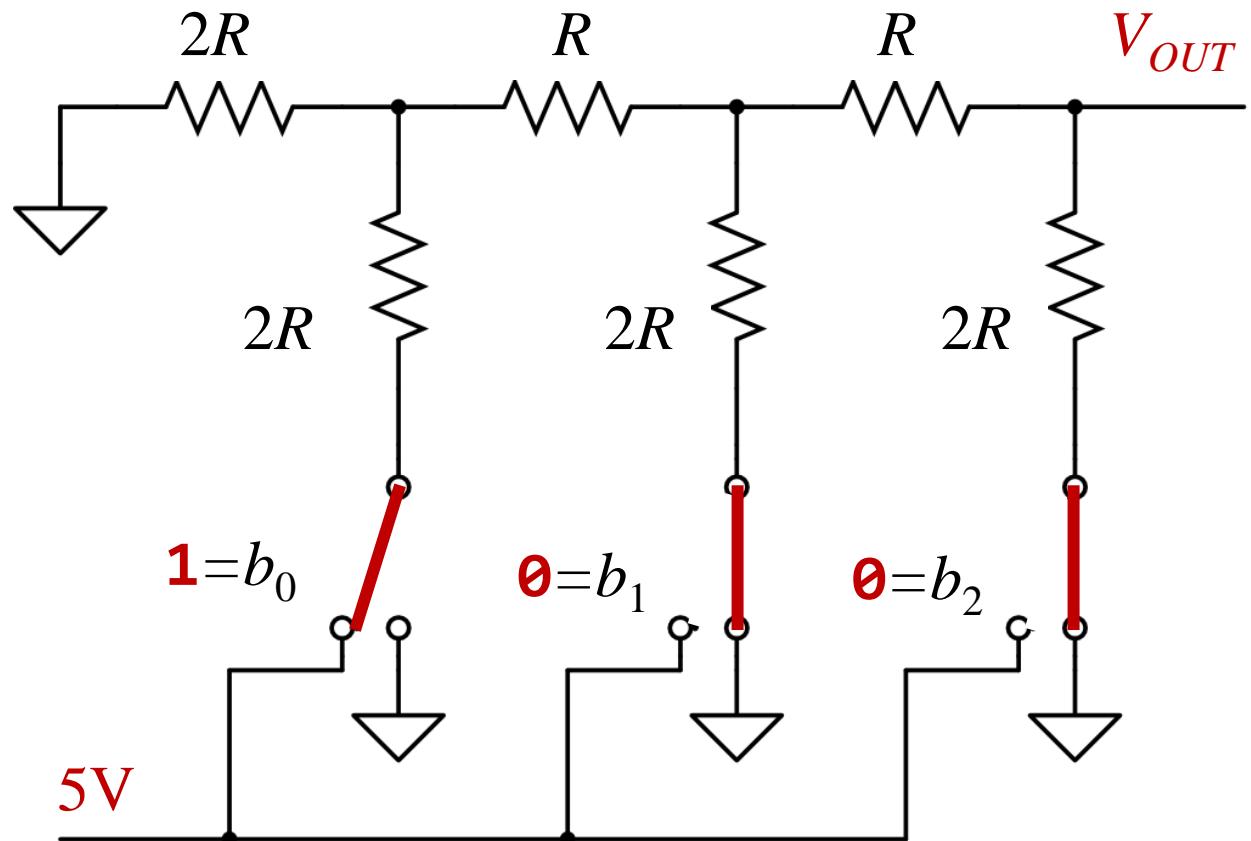
- Resistive ladder constructed from R and $2R$ resistor values
- Switch positions controlled by the DAC's N-bits of inputs (3-bit DAC shown)

- $b_X = 1$ Switch to $+5V$
 - $b_X = 0$ Switch to $0V$
- 3-bit DAC shown has input **111**



$R-2R$ Ladder DAC

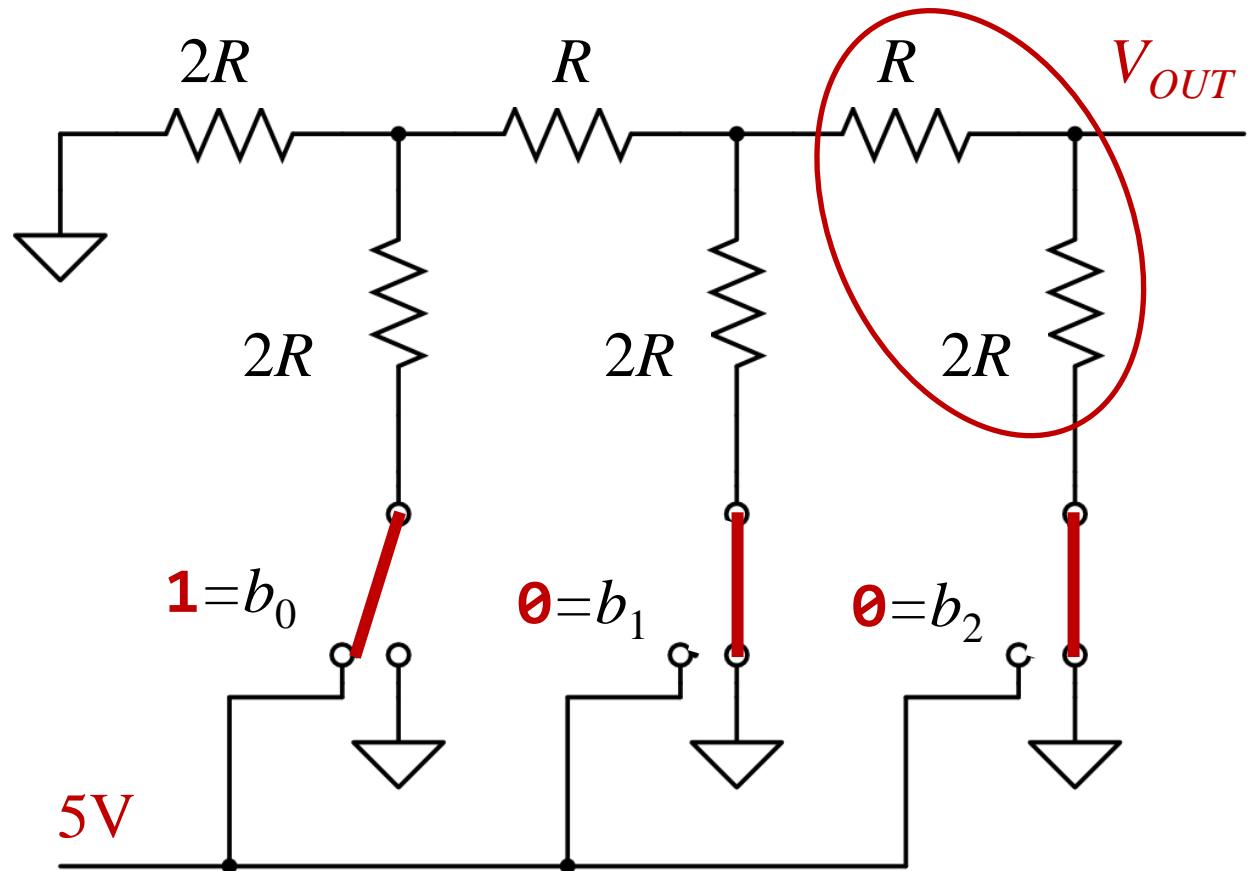
■ Consider input **001**



2023_10_06B

$R-2R$ Ladder DAC

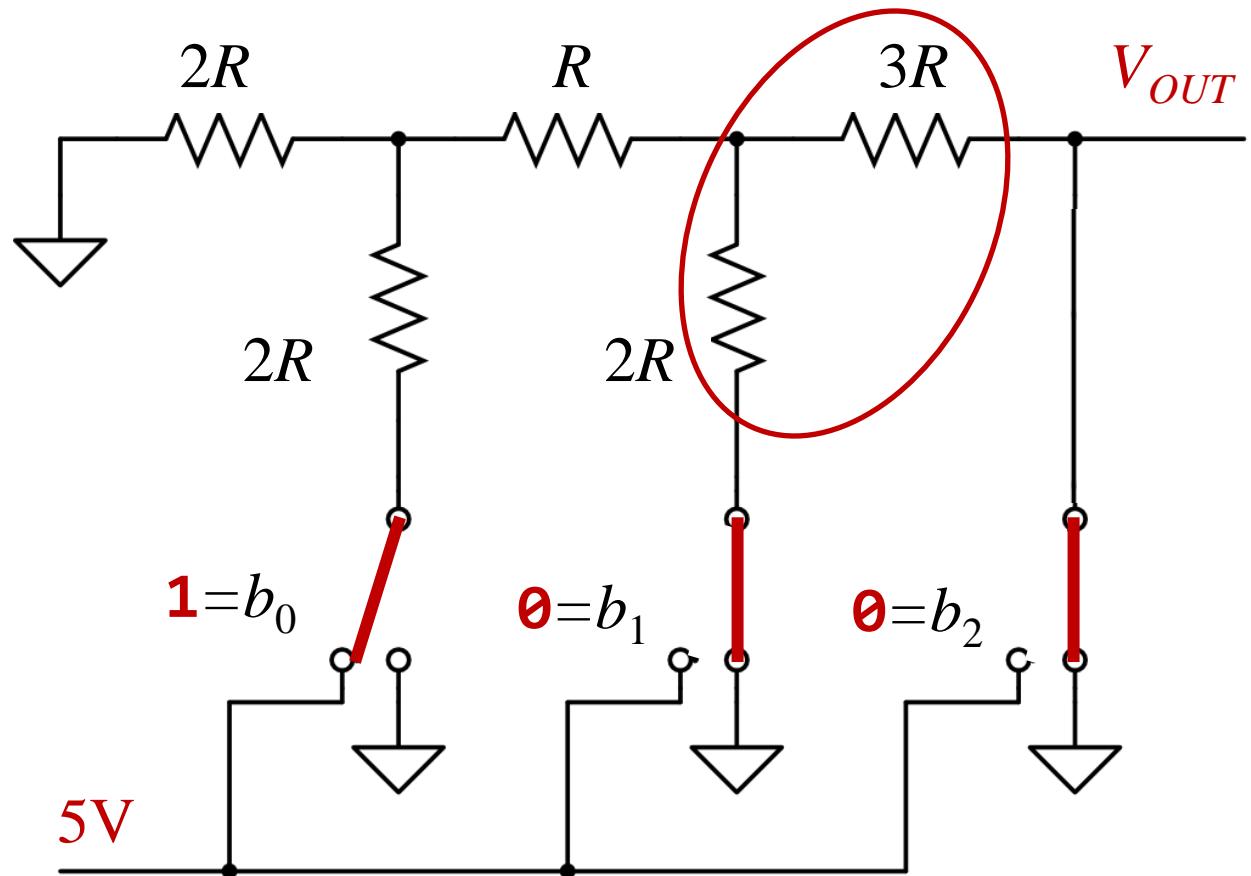
■ Consider input **001**



2023_10_06B

$R-2R$ Ladder DAC

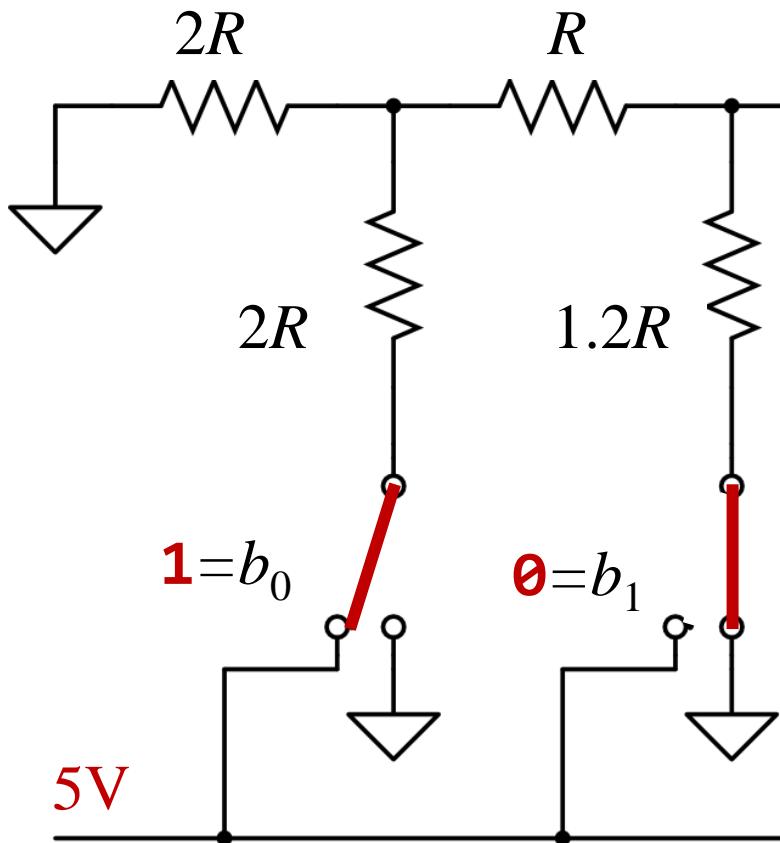
■ Consider input **001**



2023_10_06B

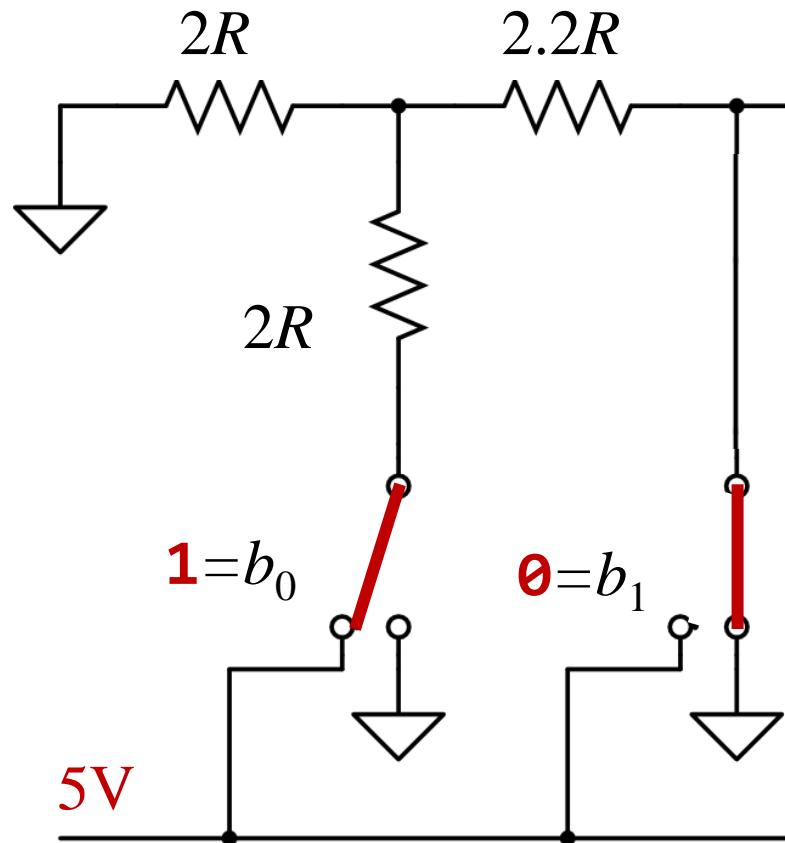
$R-2R$ Ladder DAC

■ Consider input **001**



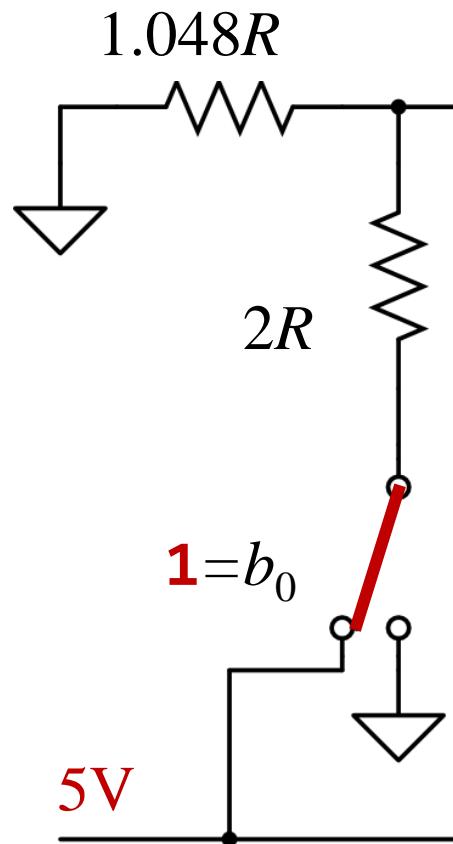
$R-2R$ Ladder DAC

■ Consider input **001**



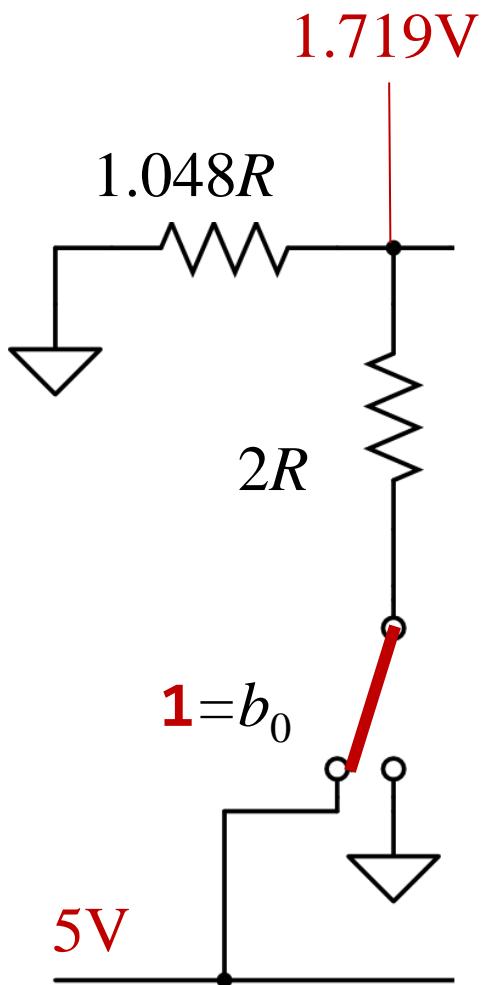
$R-2R$ Ladder DAC

■ Consider input **001**



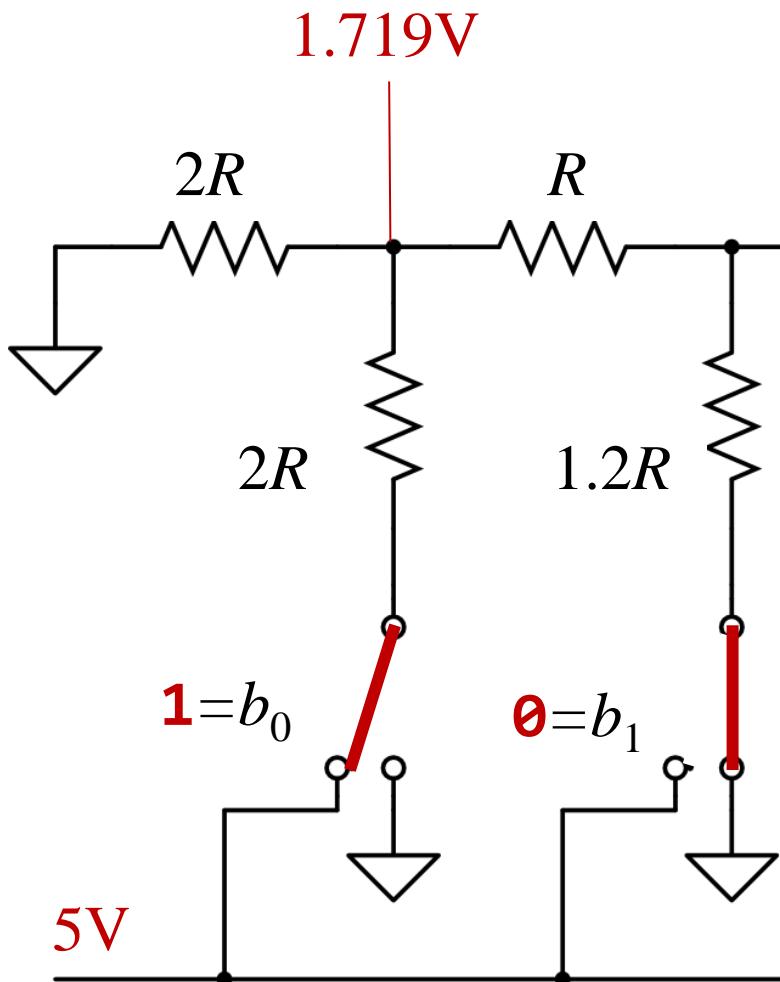
$R-2R$ Ladder DAC

■ Consider input **001**



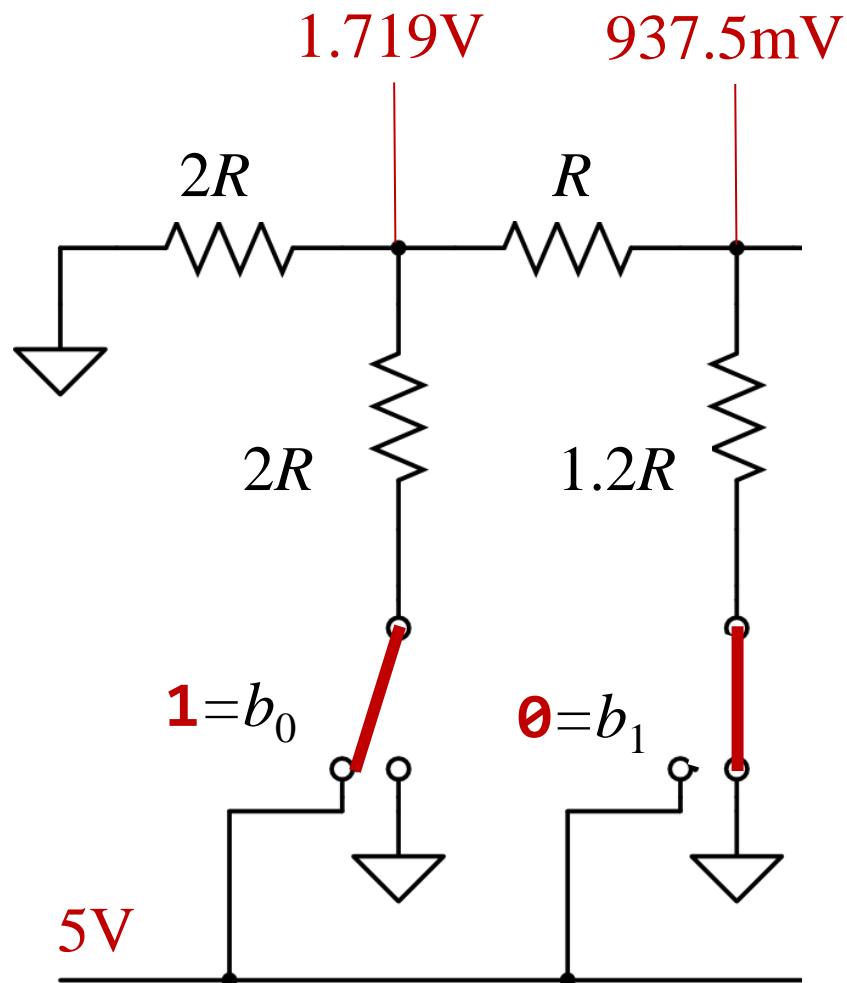
$R-2R$ Ladder DAC

■ Consider input **001**



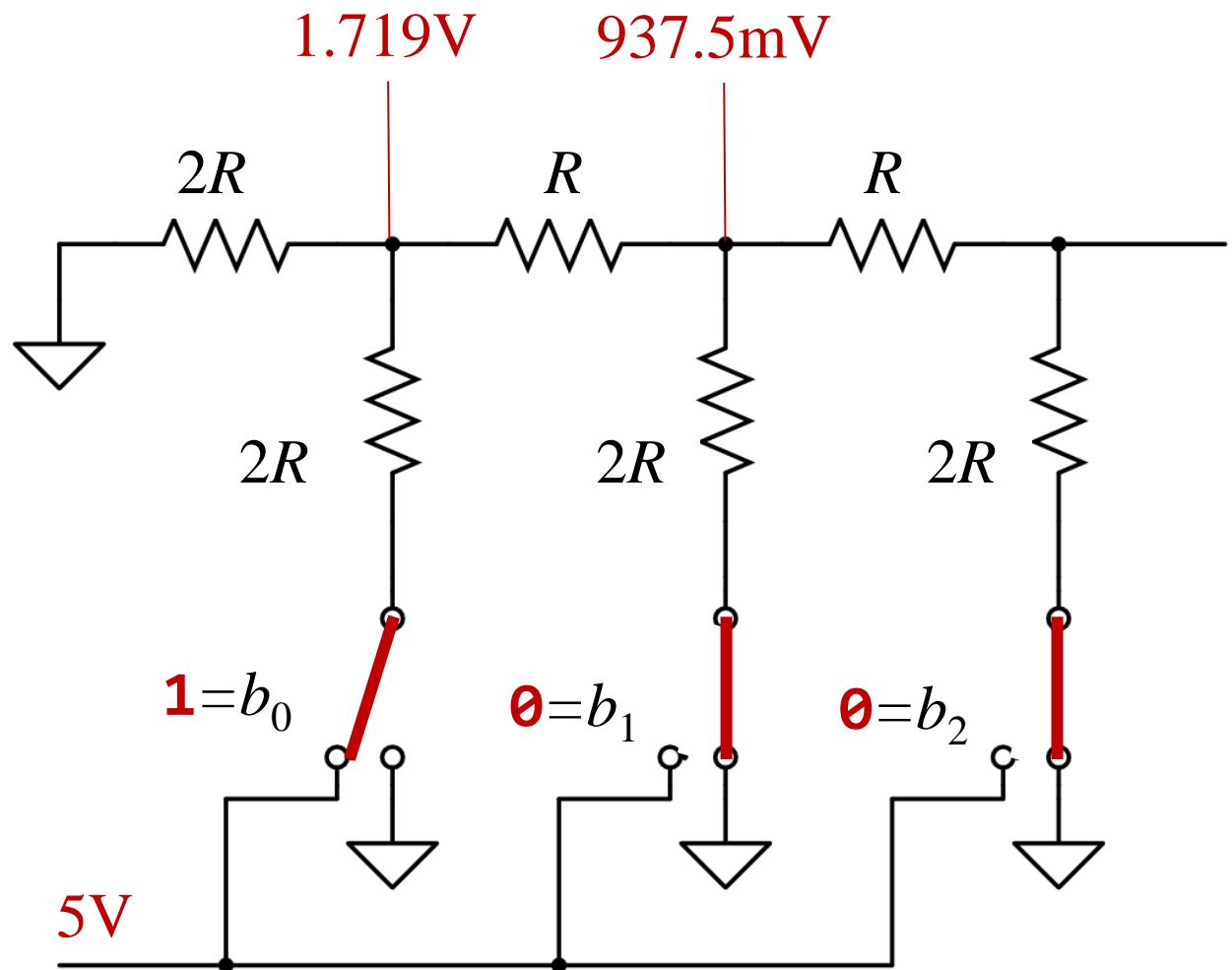
$R-2R$ Ladder DAC

■ Consider input **001**



$R-2R$ Ladder DAC

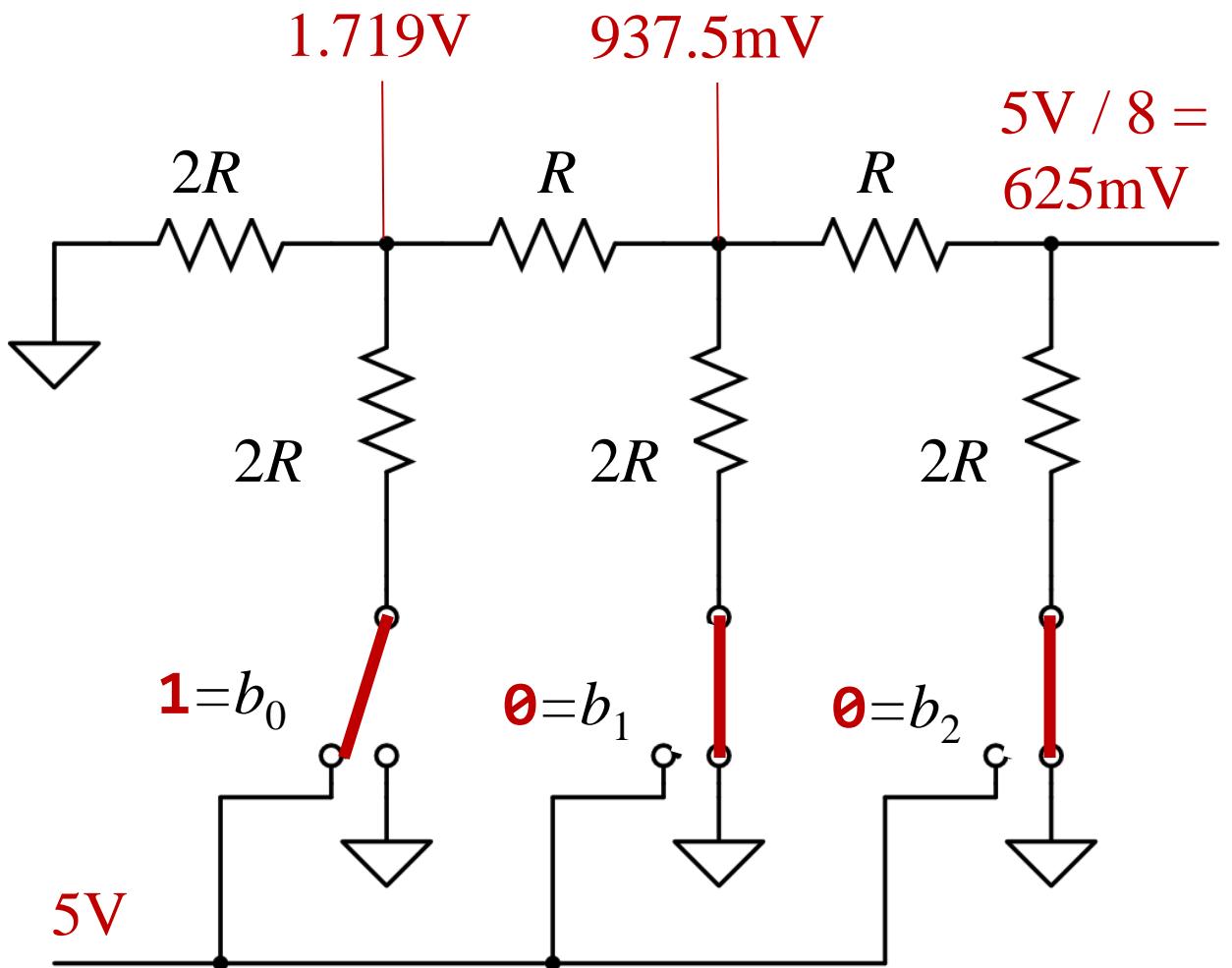
■ Consider input **001**



2023_10_06B

$R-2R$ Ladder DAC

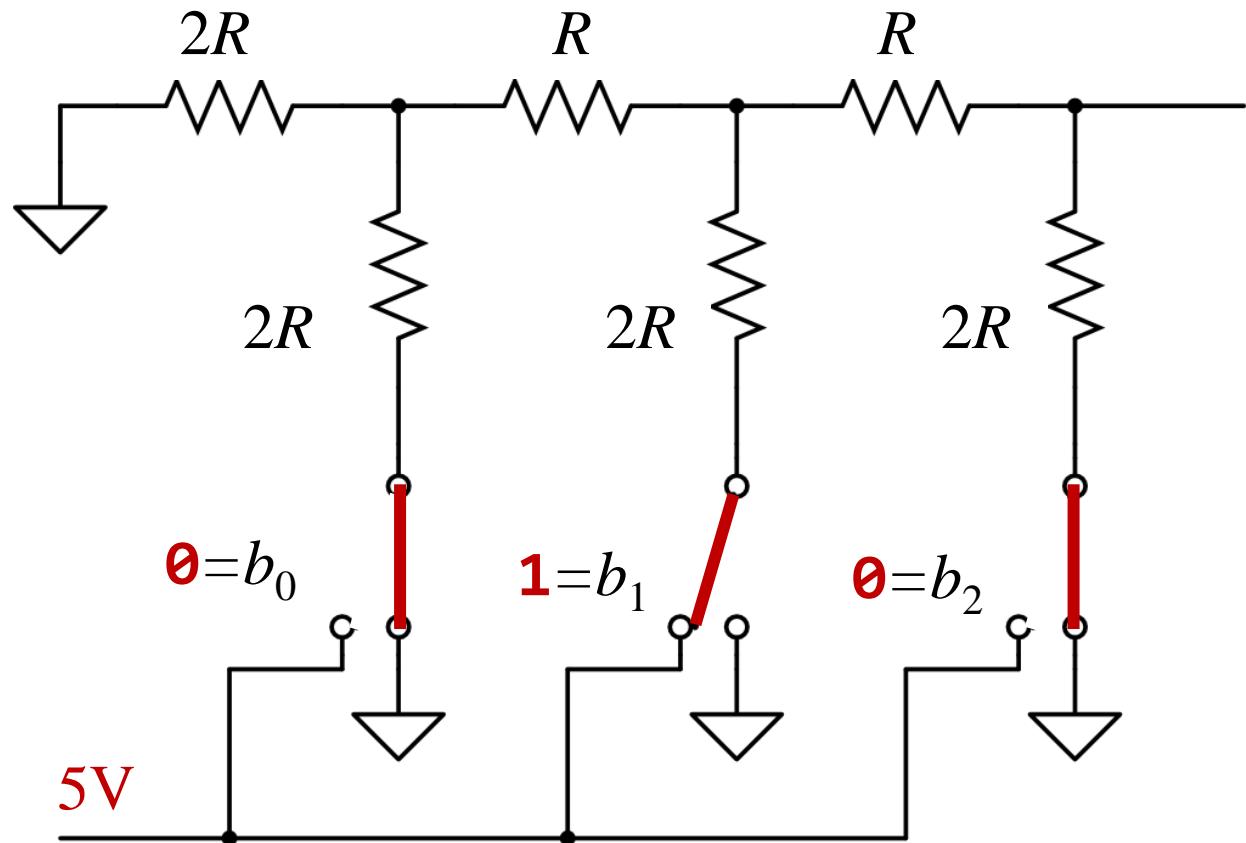
■ Consider input **001**



2023_10_06B

$R-2R$ Ladder DAC

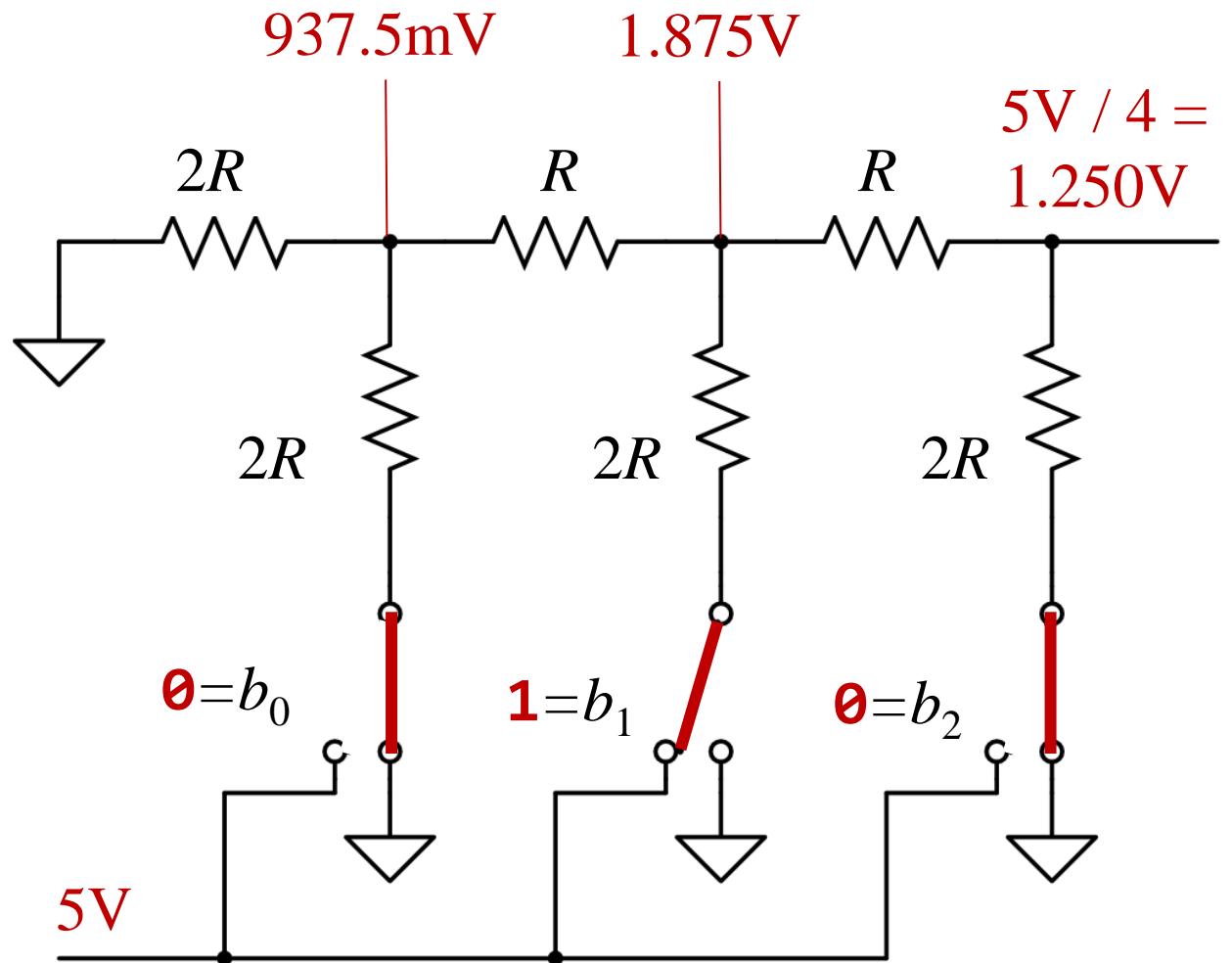
■ Consider input **010**



2023_10_06B

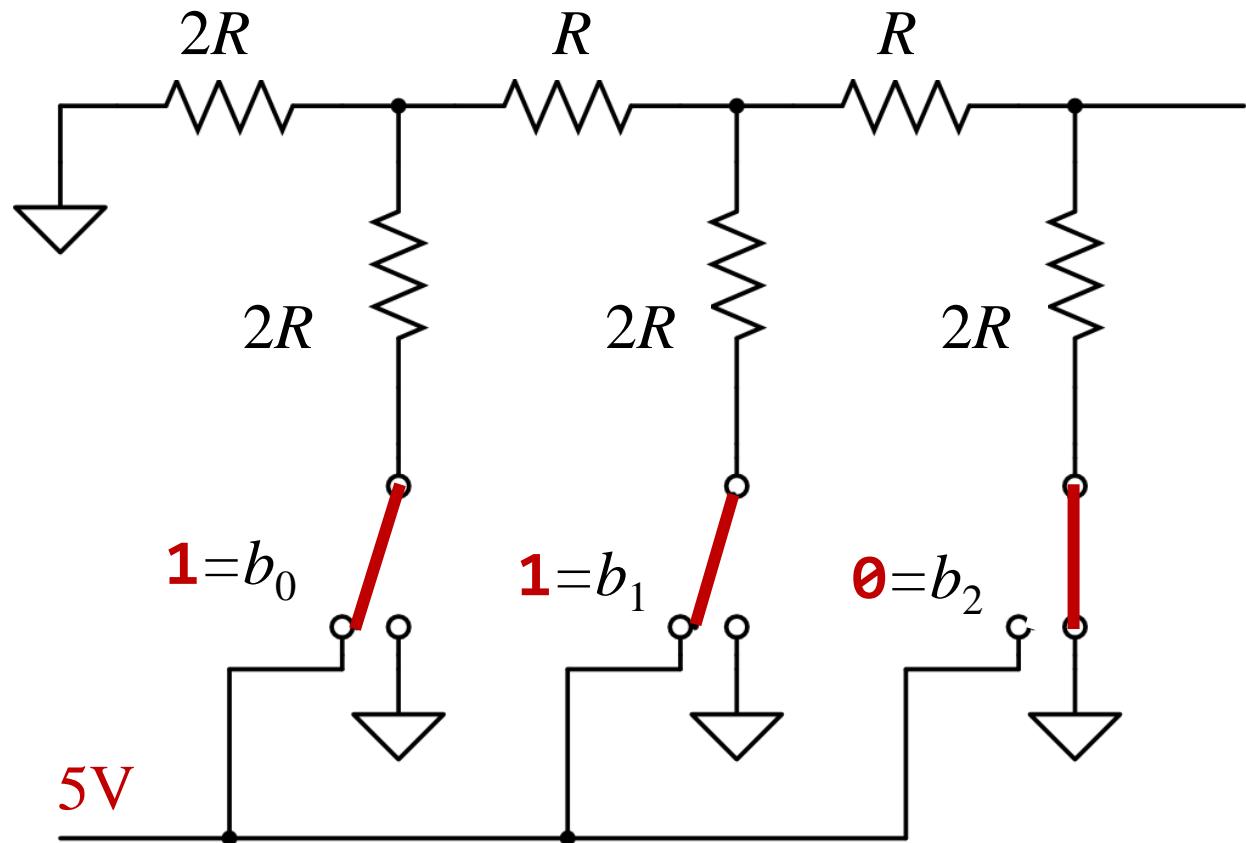
$R-2R$ Ladder DAC

■ Consider input **010**



$R-2R$ Ladder DAC

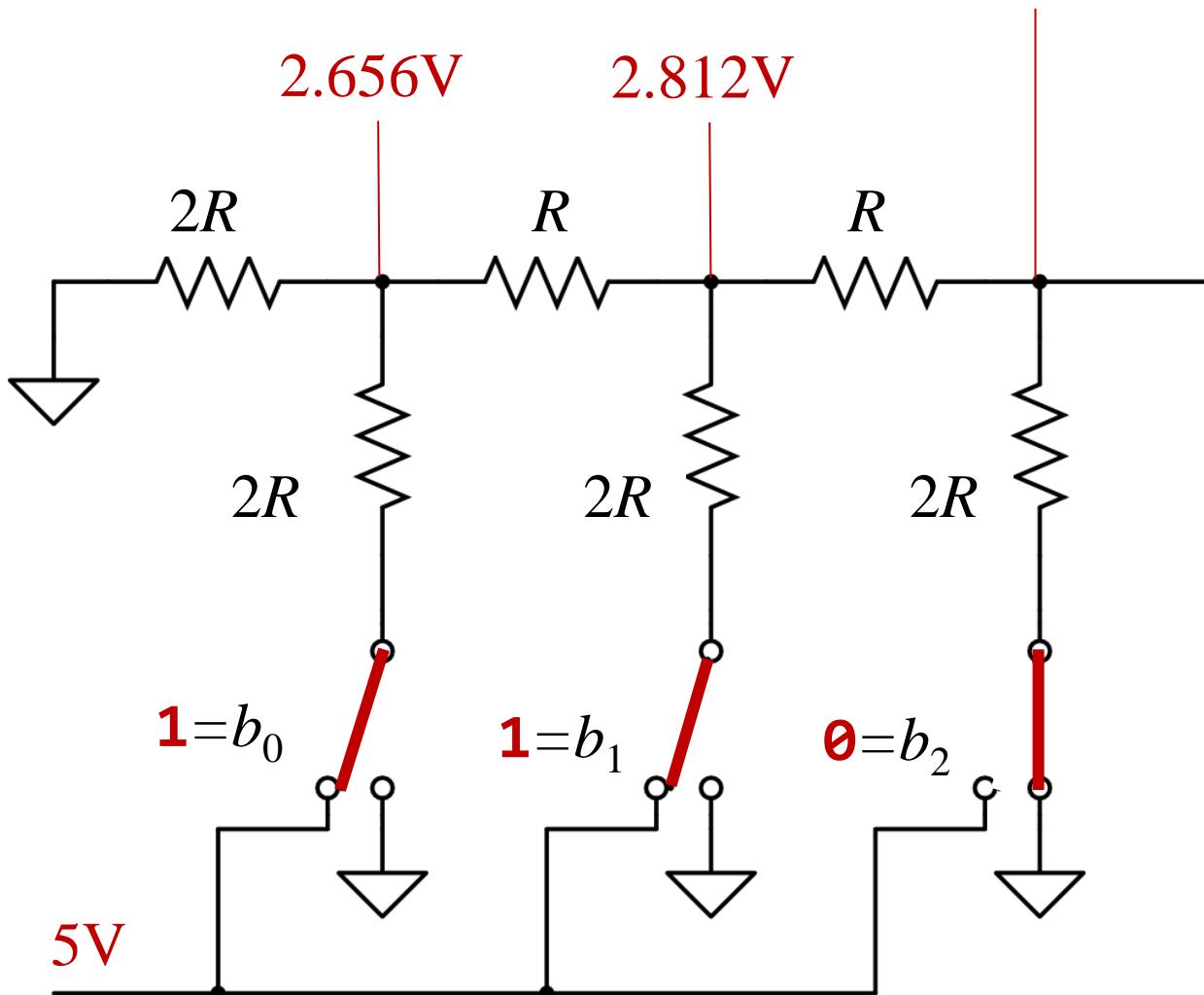
■ Consider input **011**



R-2R Ladder DAC

$$5V(1/8 + 1/4) = 1.875V$$

■ Consider input 011



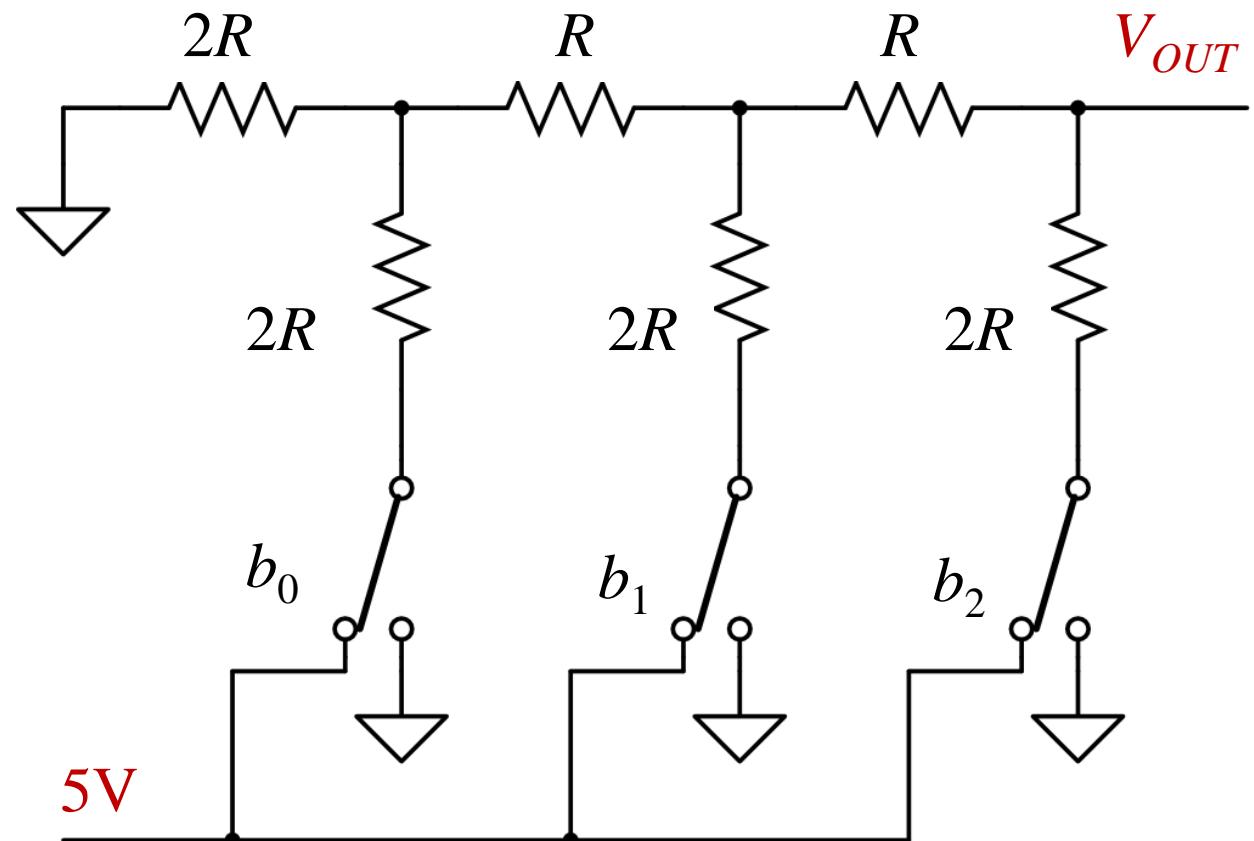
$R-2R$ Ladder DAC

■ Advantages

- Fast!
- Easy to manufacture for low-bit counts

■ Disadvantages

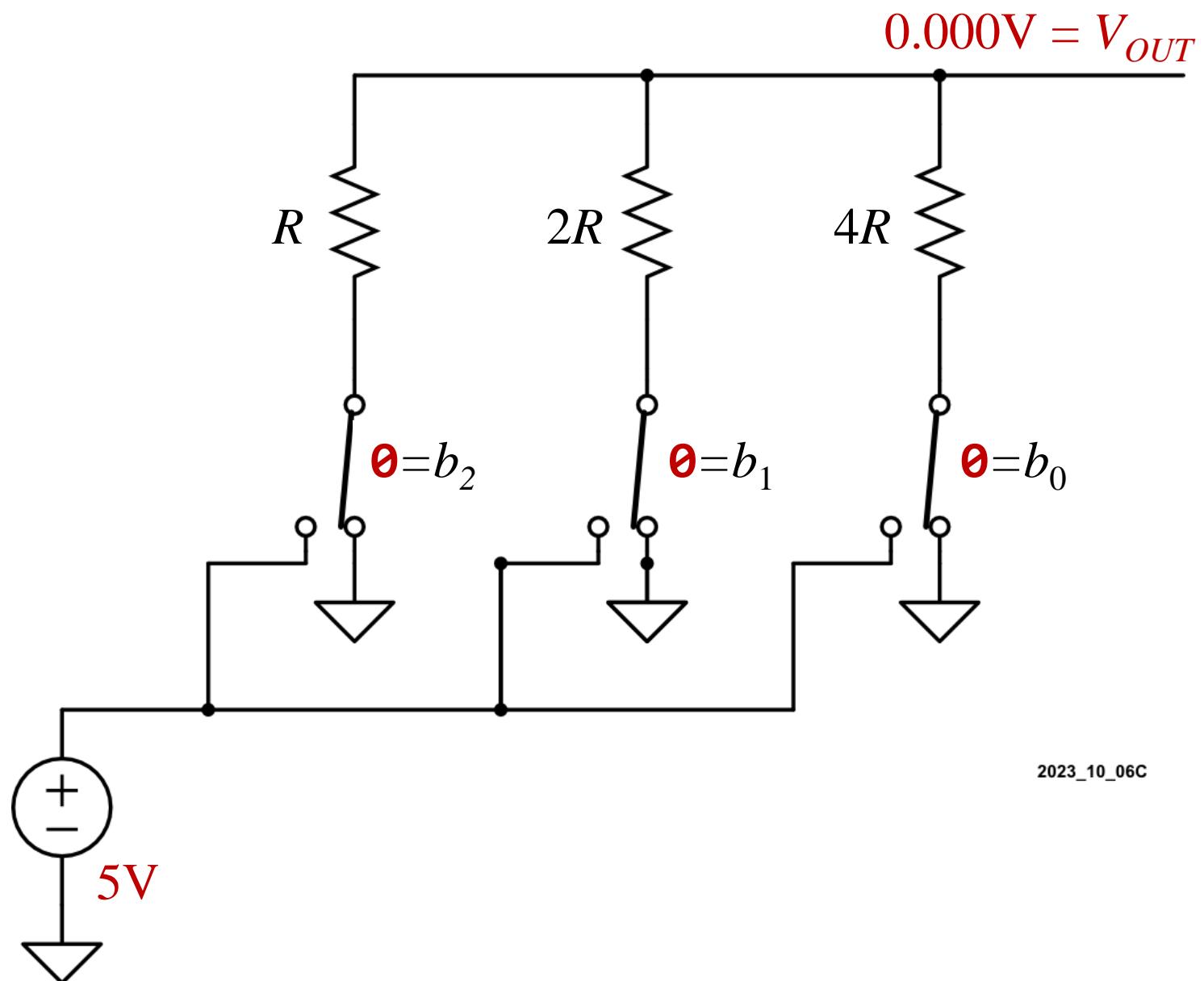
- Monotonicity problems
- If resistors aren't completely accurate, increasing the input across 2^x boundaries can decrease the output voltage ($01111111 \rightarrow 10000000$)
- Use an op amp buffer to increase current drive



2023_10_06B

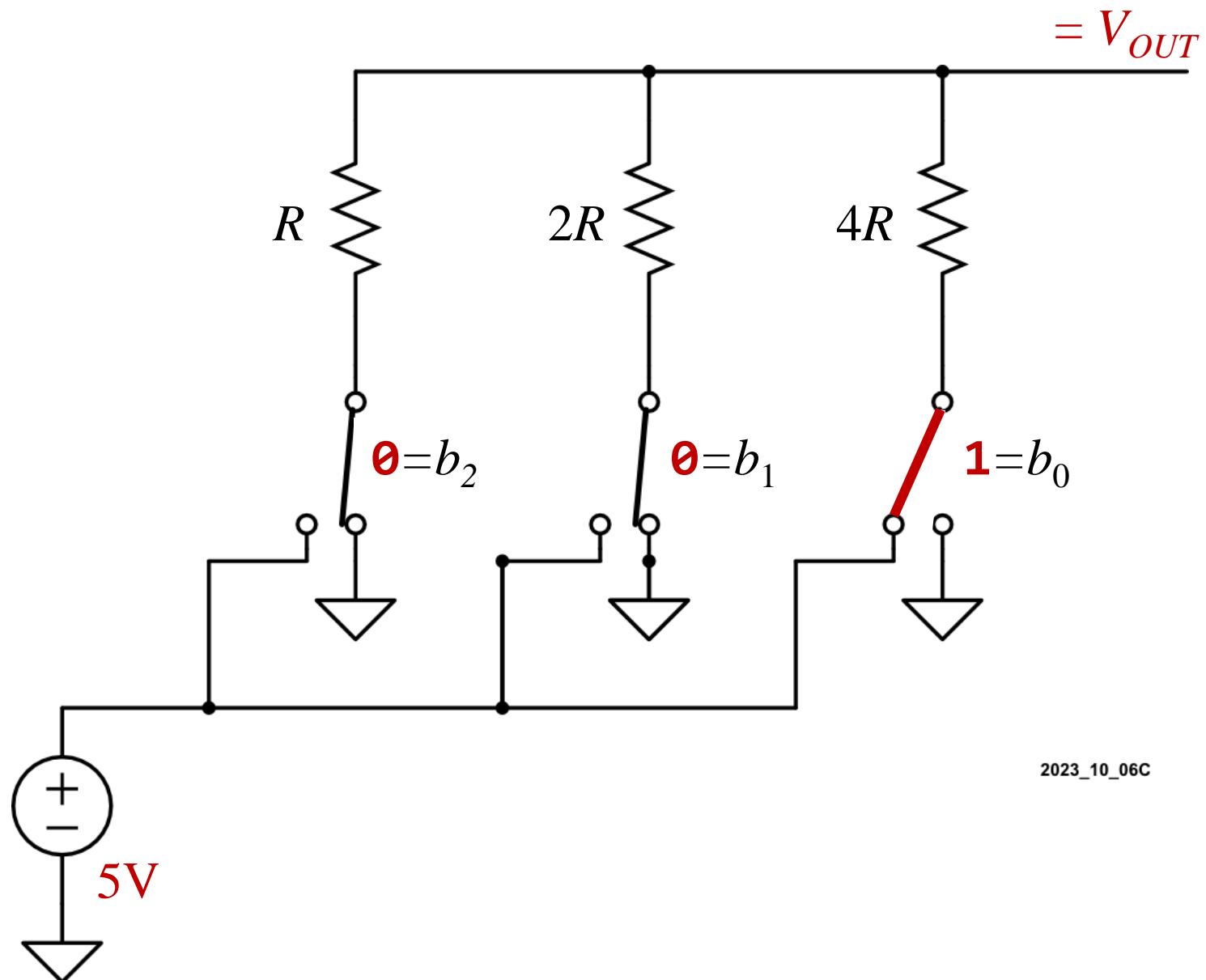
Binary-Scaled DAC

- Similar to a R-2R DAC, but resistors are weighted



Binary-Scaled DAC

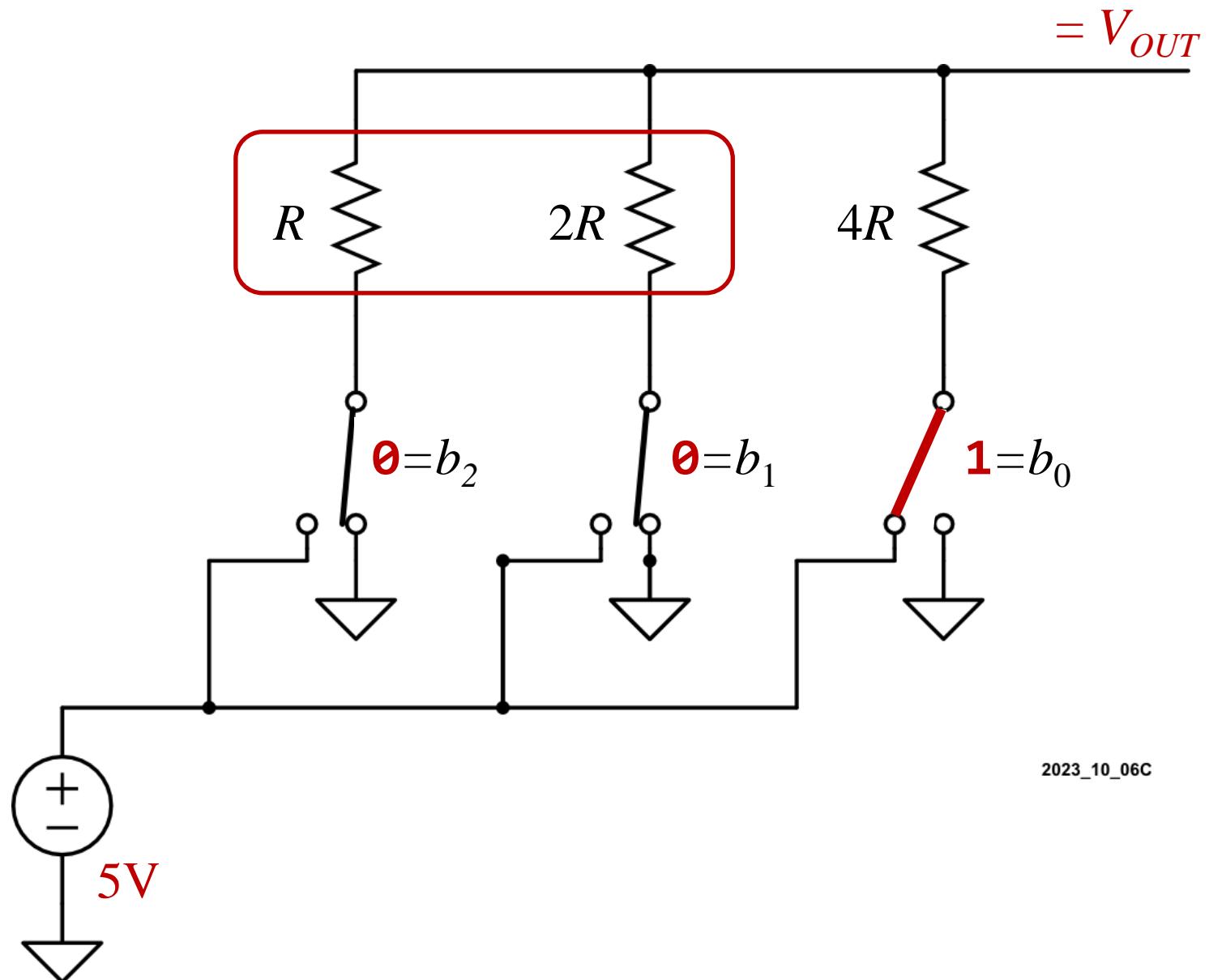
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2023_10_06C

Binary-Scaled DAC

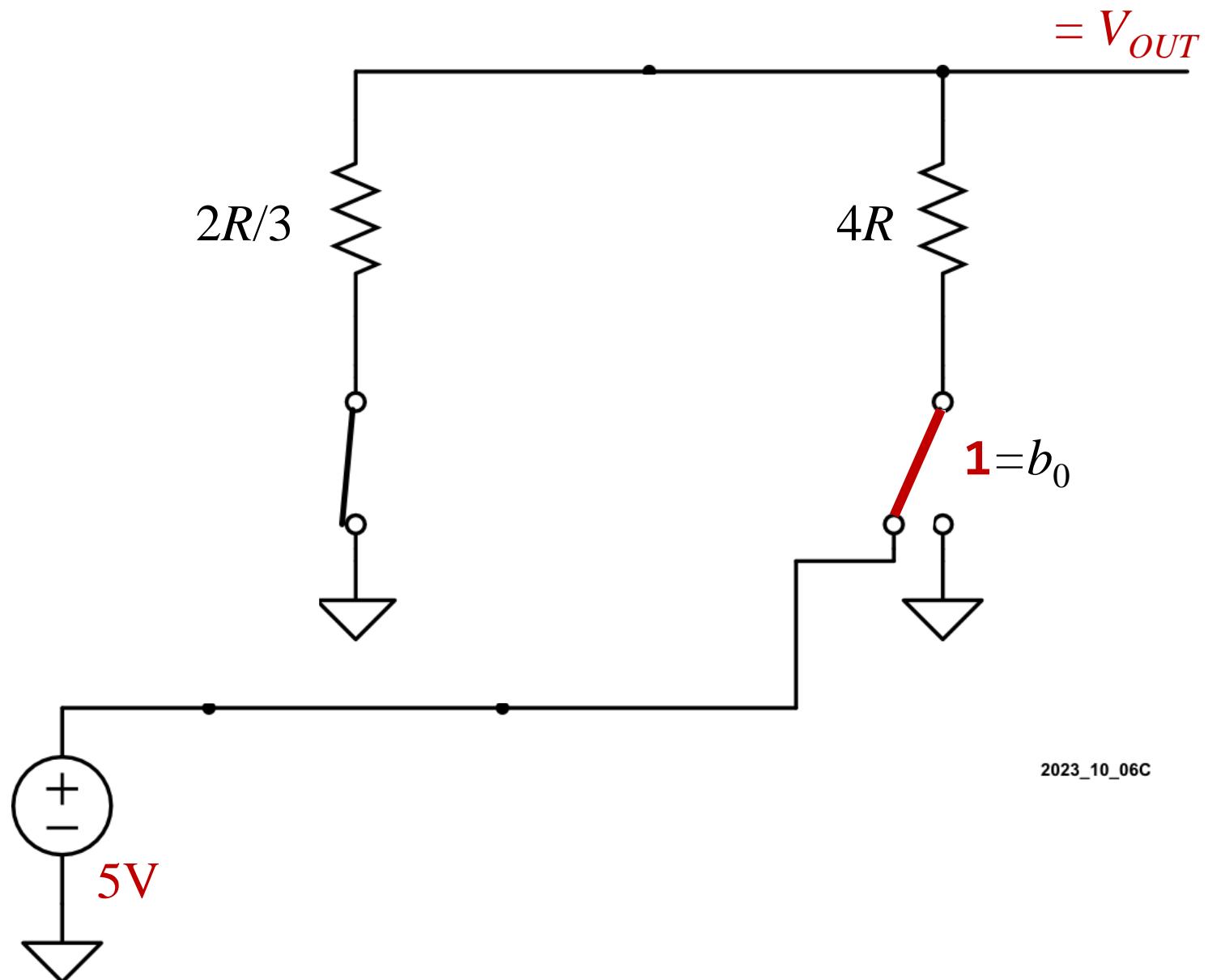
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2023_10_06C

Binary-Scaled DAC

- Similar to a R-2R DAC, but resistors are weighted

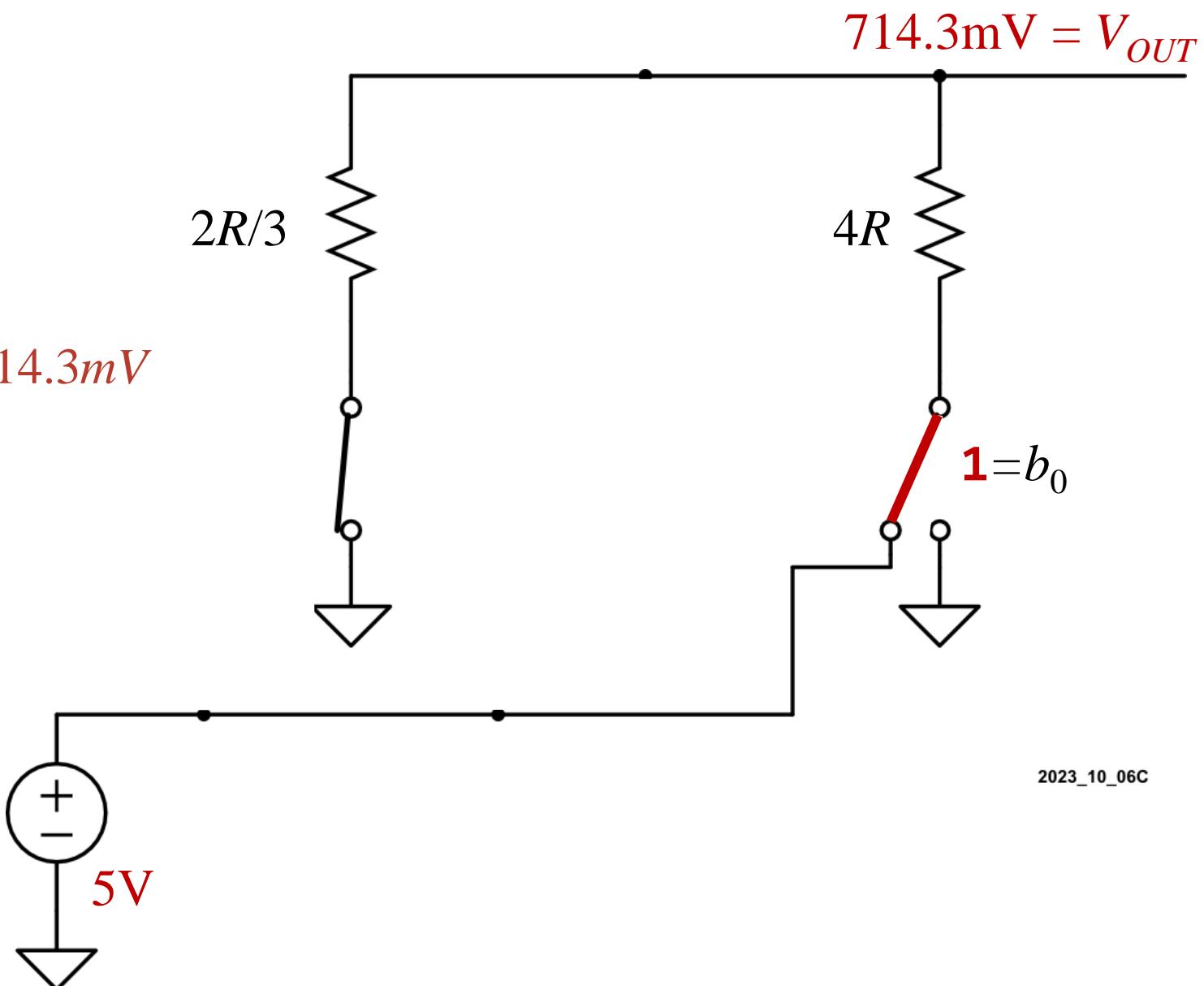


2023_10_06C

Binary-Scaled DAC

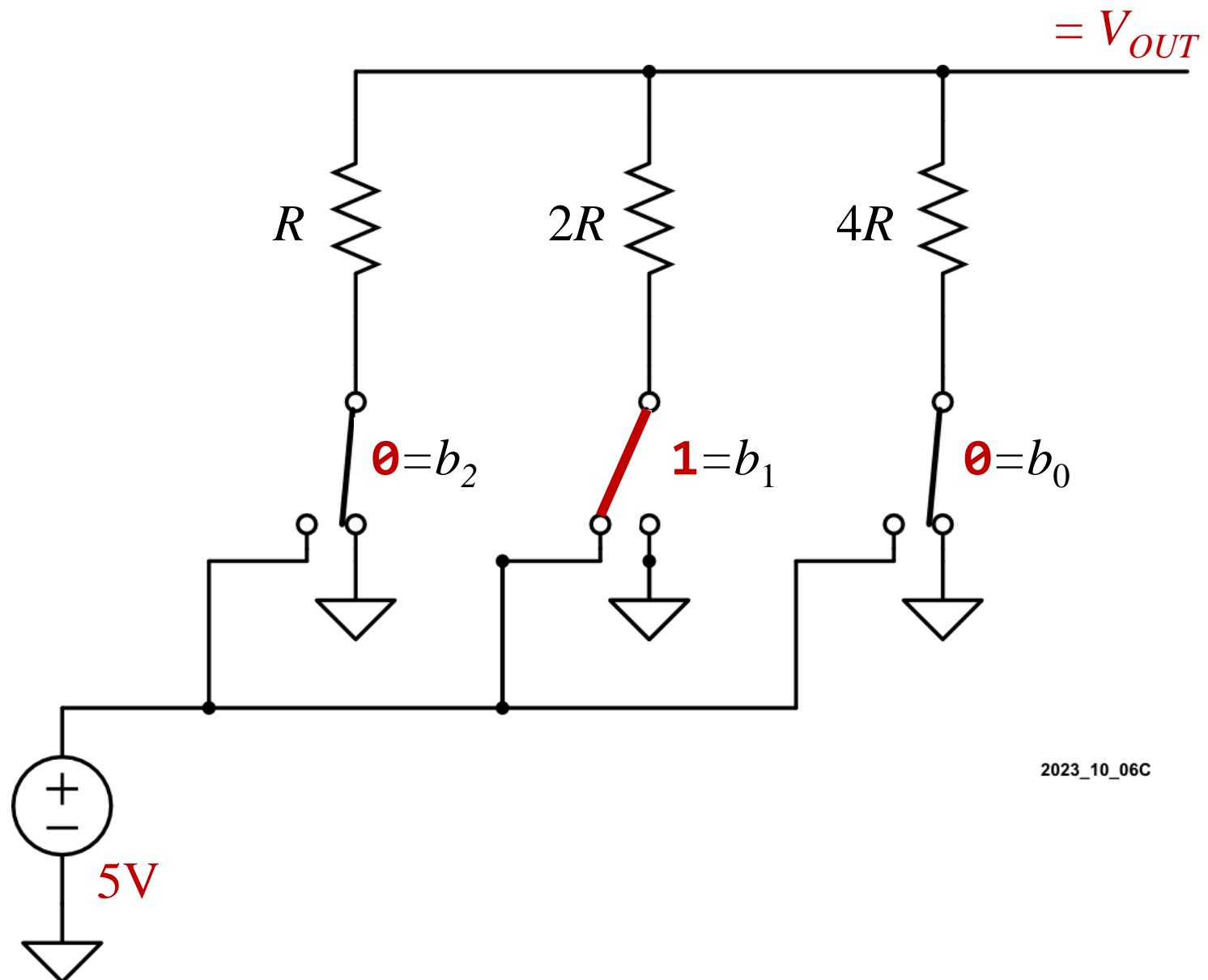
- Similar to a R-2R DAC, but resistors are weighted

$$V_{OUT} = 5V \left(\frac{2R/3}{4R + 2R/3} \right) = 5V \left(\frac{1}{7} \right) = 714.3mV$$



Binary-Scaled DAC

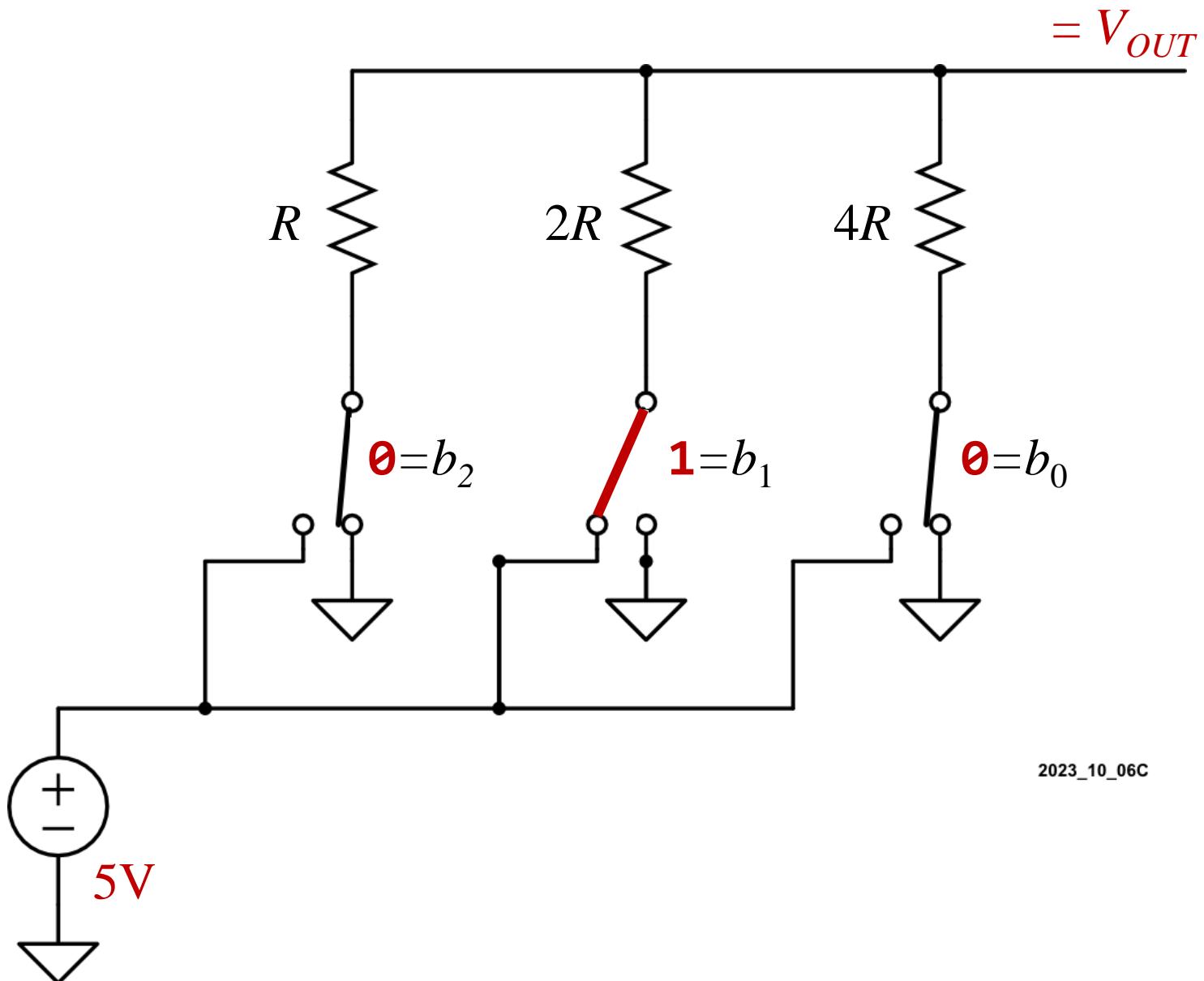
- Similar to a R-2R DAC, but resistors are weighted



2023_10_06C

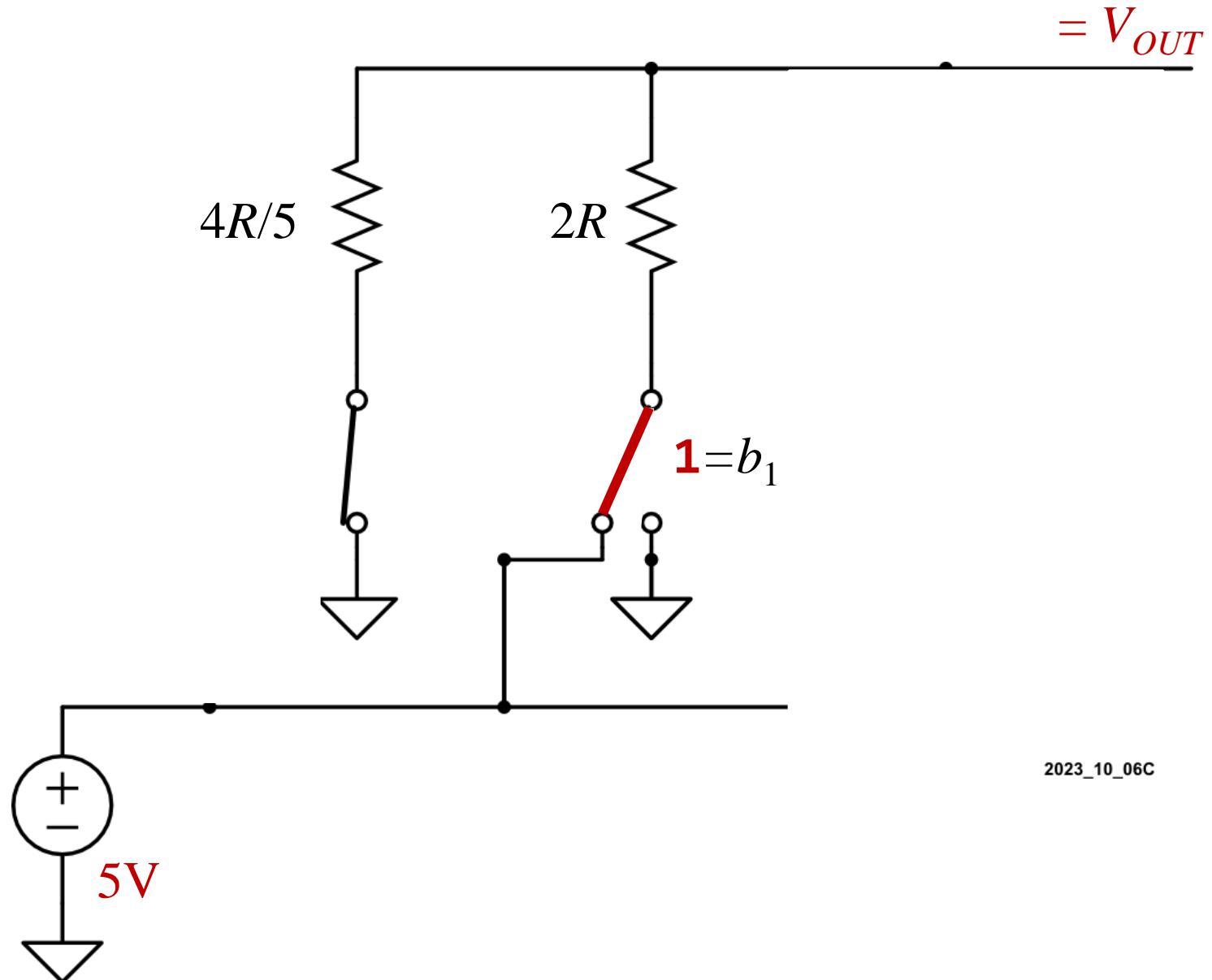
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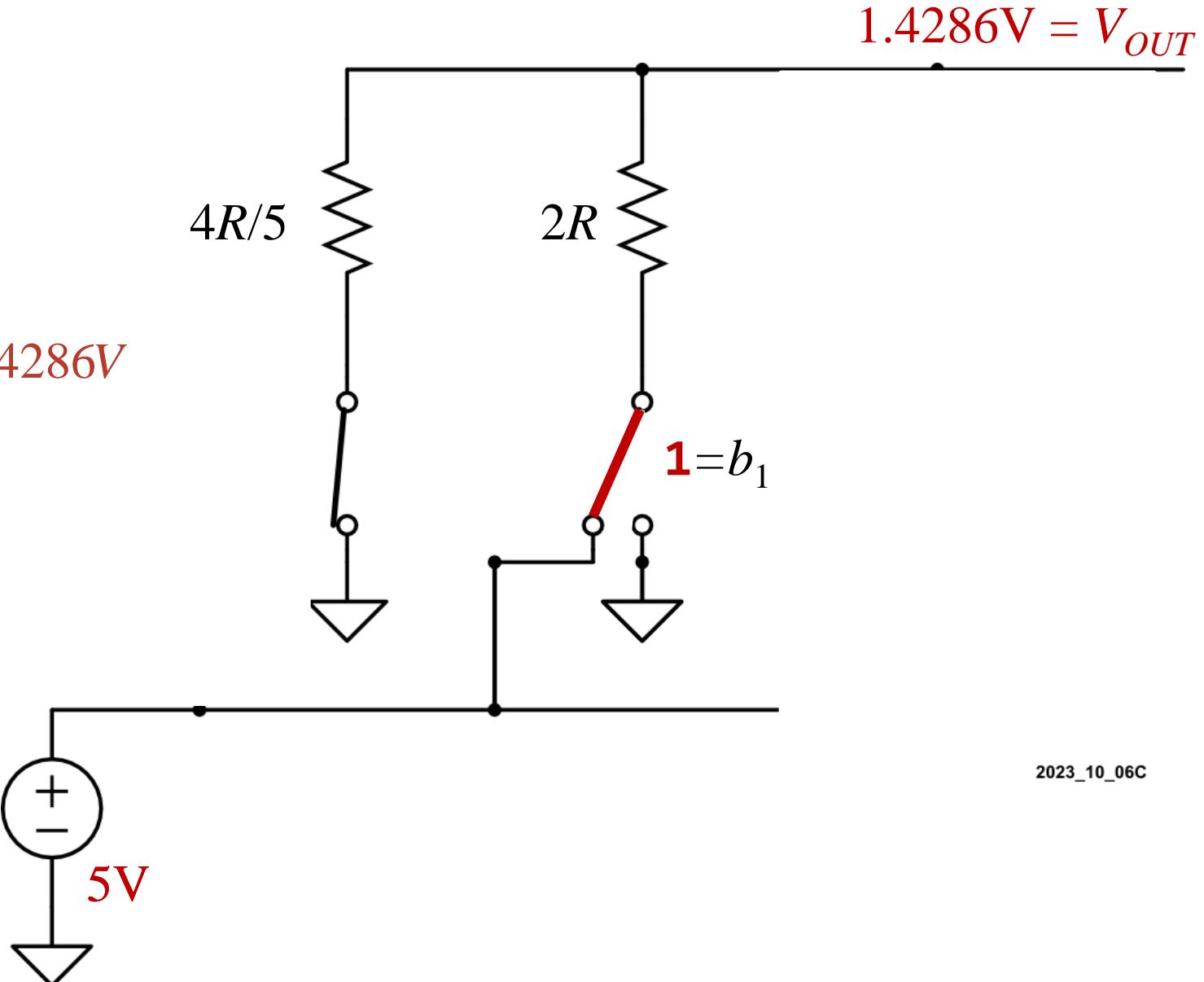


2023_10_06C

Binary-Scaled DAC

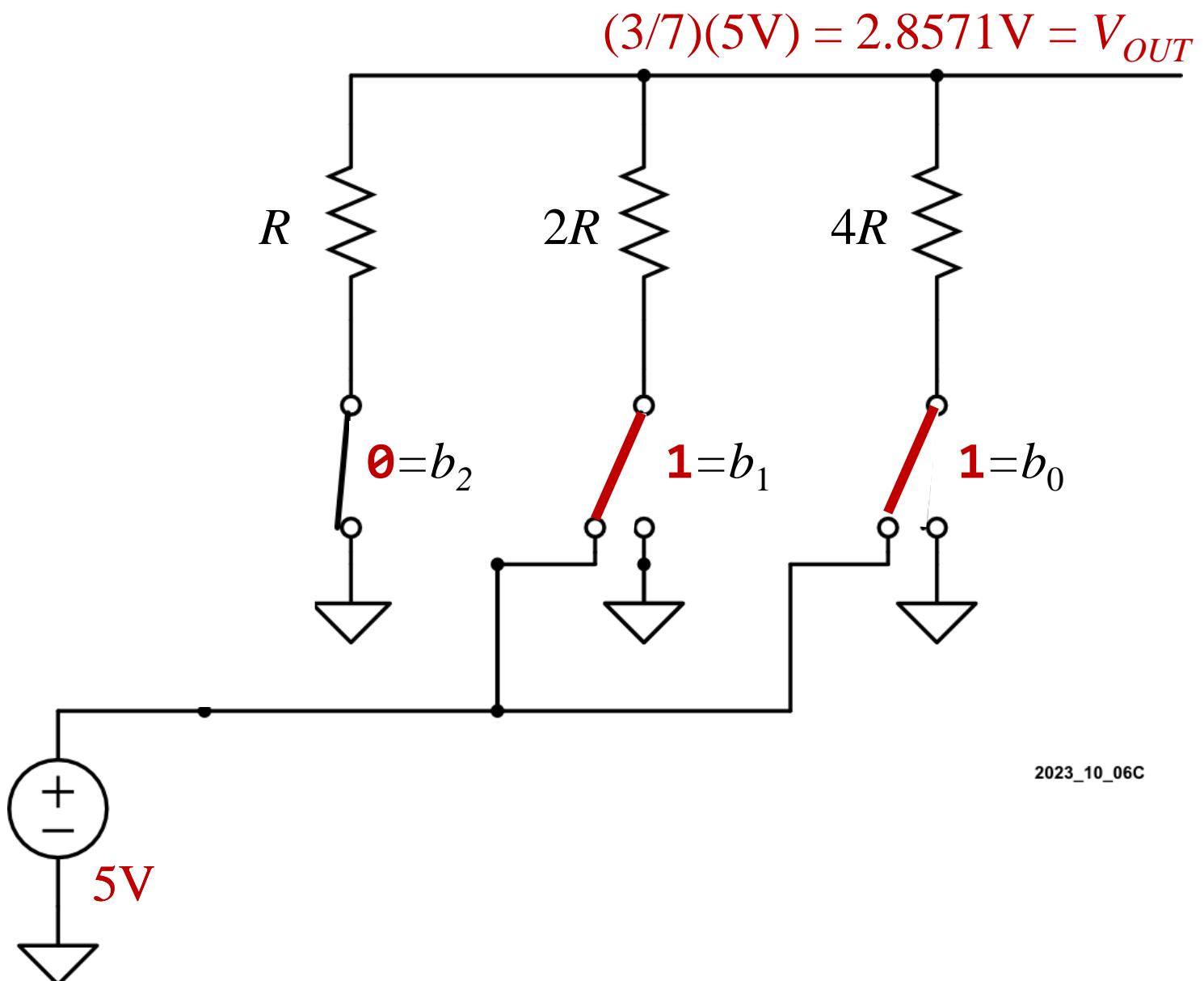
- Similar to a R-2R DAC, but resistors are weighted

$$V_{OUT} = 5V \left(\frac{4R/5}{2R + 4R/5} \right) = 5V \left(\frac{2}{7} \right) = 1.4286V$$



Binary-Scaled DAC

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2023_10_06C

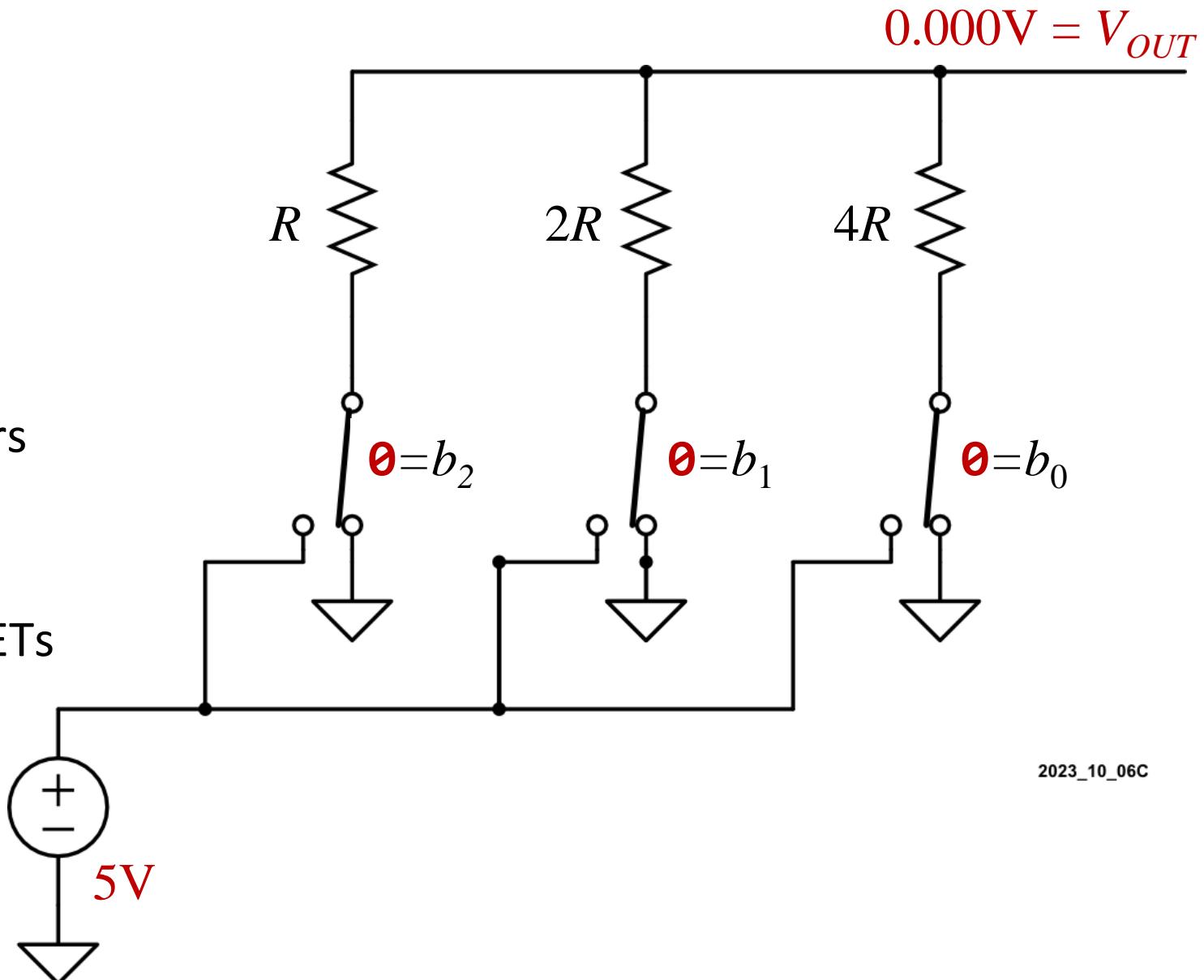
Binary-Scaled DAC

■ Advantages:

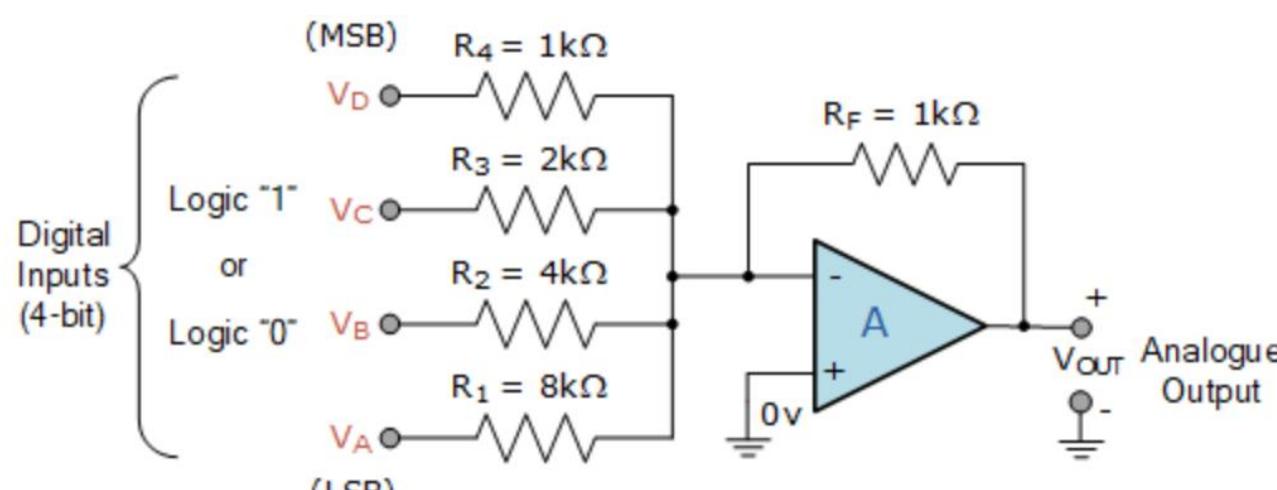
- It is simple in construction
 - It provides fast conversion

■ Disadvantages:

- Requires large range of resistors
 - Requires high precision for low value resistors.
 - Requires low resistance MOSFETs
 - Can be expensive
 - Use an op amp buffer to increase current drive



Binary-Scaled DAC



$$V_{OUT} = - \left[\frac{R_F}{R_4} V_D + \frac{R_F}{R_3} V_C + \frac{R_F}{R_2} V_B + \frac{R_F}{R_1} V_A \right]$$

$$V_{OUT} = - \left[\frac{1\text{k}\Omega}{1\text{k}\Omega} V_D + \frac{1\text{k}\Omega}{2\text{k}\Omega} V_C + \frac{1\text{k}\Omega}{4\text{k}\Omega} V_B + \frac{1\text{k}\Omega}{8\text{k}\Omega} V_A \right]$$

$$V_{OUT} = - \left[1V_D + \frac{1}{2}V_C + \frac{1}{4}V_B + \frac{1}{8}V_A \right]$$

<https://www.electronics-tutorials.ws/combination/digital-to-analogue-converter.html>

Remember, for All DACs

- Almost always will need an op amp buffer to increase current drive ($I_{OUT,MAX} < 1\text{mA}$)

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011 $\rightarrow (3/8)(5V) = 1.875V$
111 $\rightarrow (7/8)(5V) = 4.375V$
110 $\rightarrow (6/8)(5V) = 3.750V$
100 $\rightarrow (4/8)(5V) = 2.500V$