

Data Quality-Aware Graph Machine Learning



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University of Notre Dame²

Snap Research³

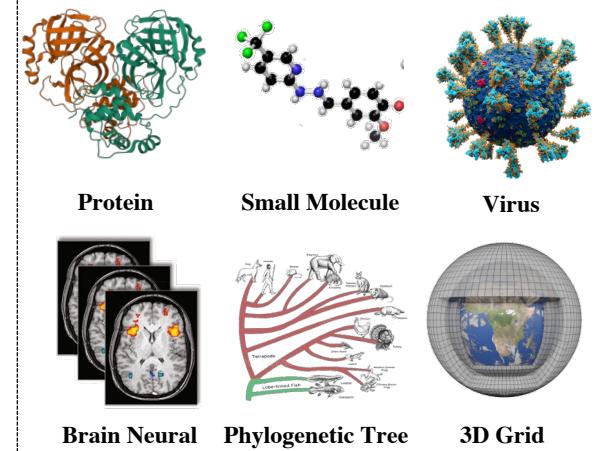
North Carolina State University⁴

University of Rochester⁵

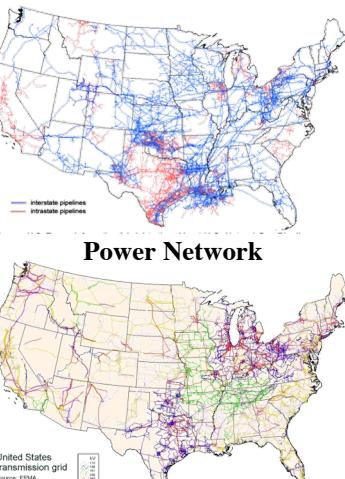
University of Oregon⁶

Introduction and Background - Graph-Structured Data is Everywhere

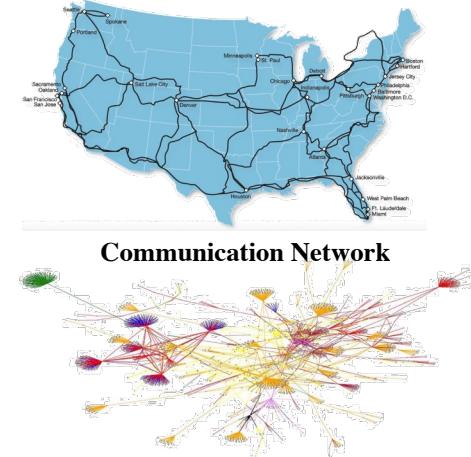
Scientific Graph



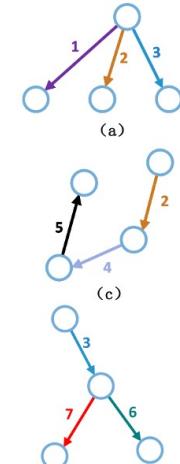
Gas Network



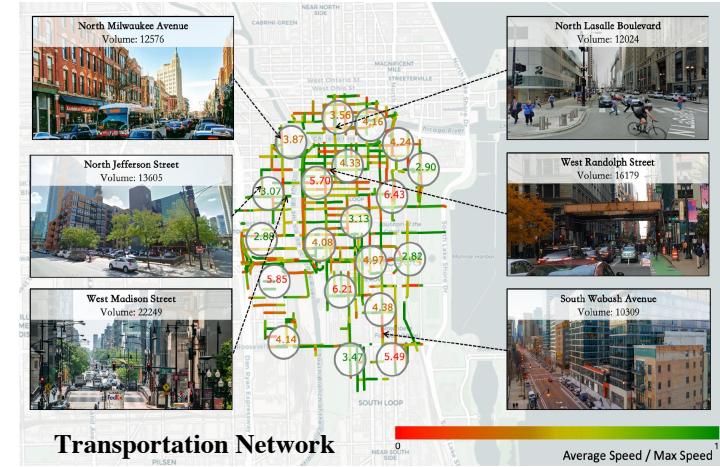
Comcast Nationwide Fiber Optic Network



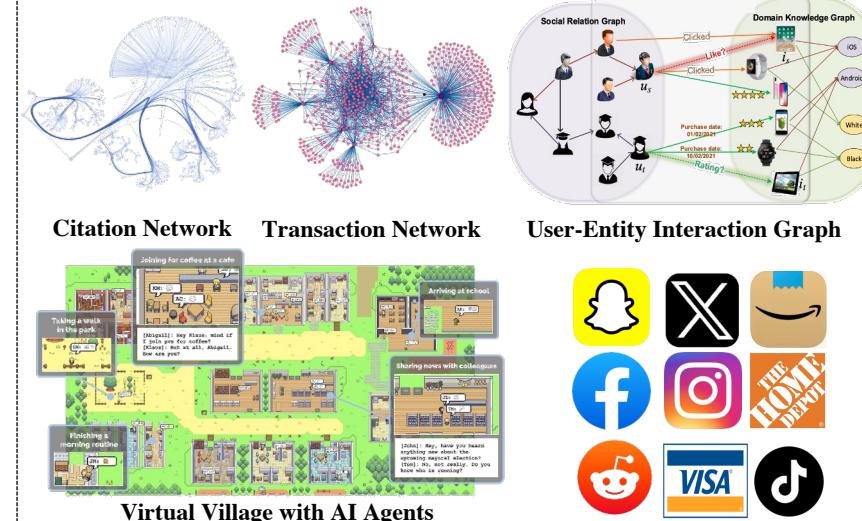
Traffic Trace



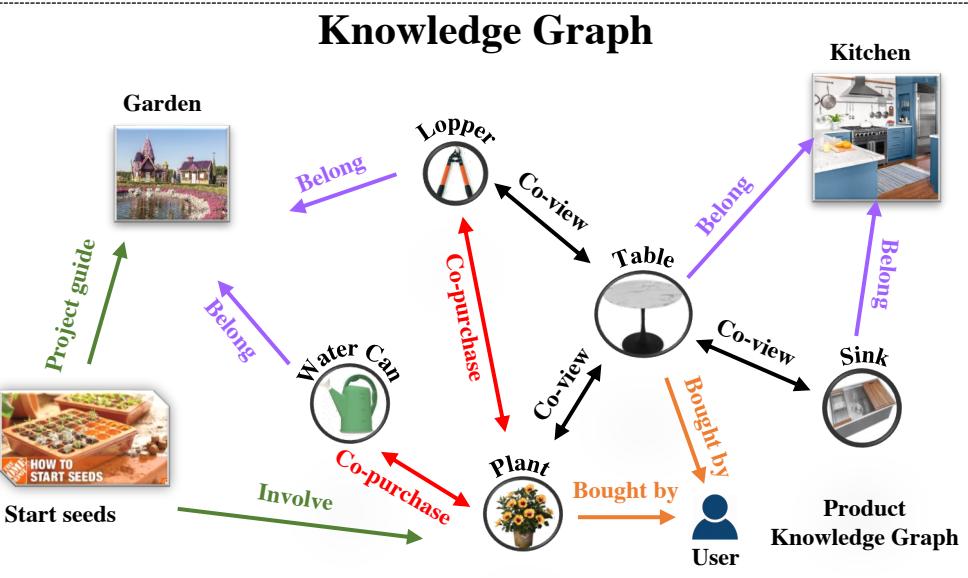
Infrastructure Graph



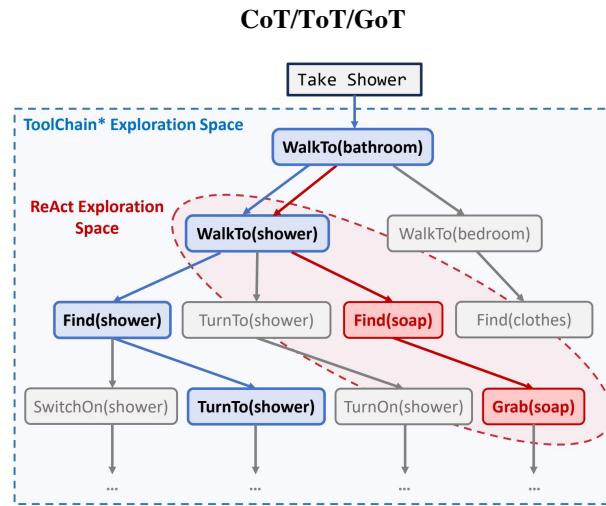
Social Interaction Graph



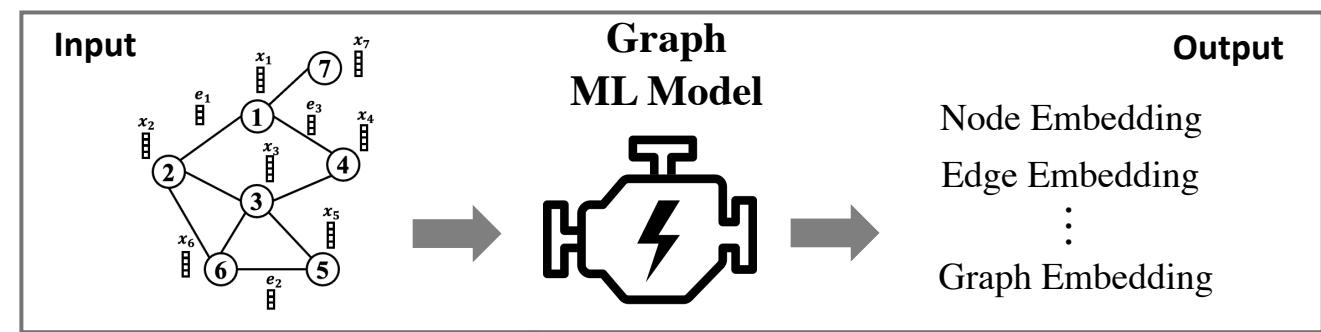
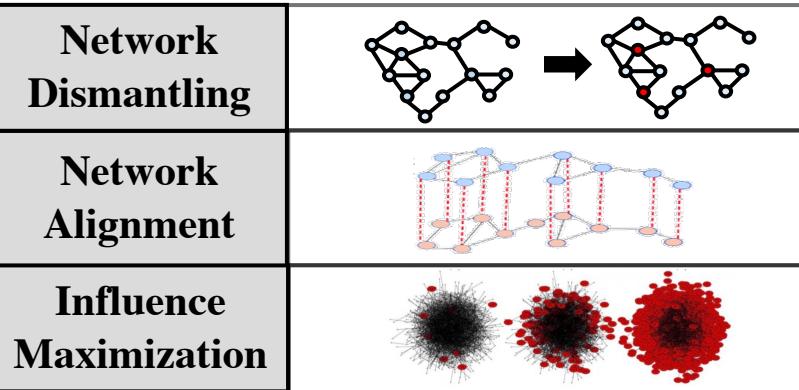
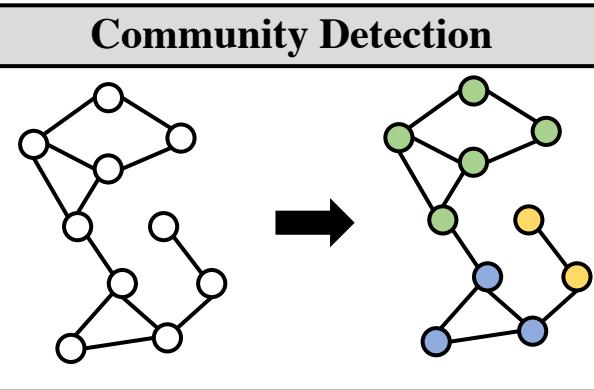
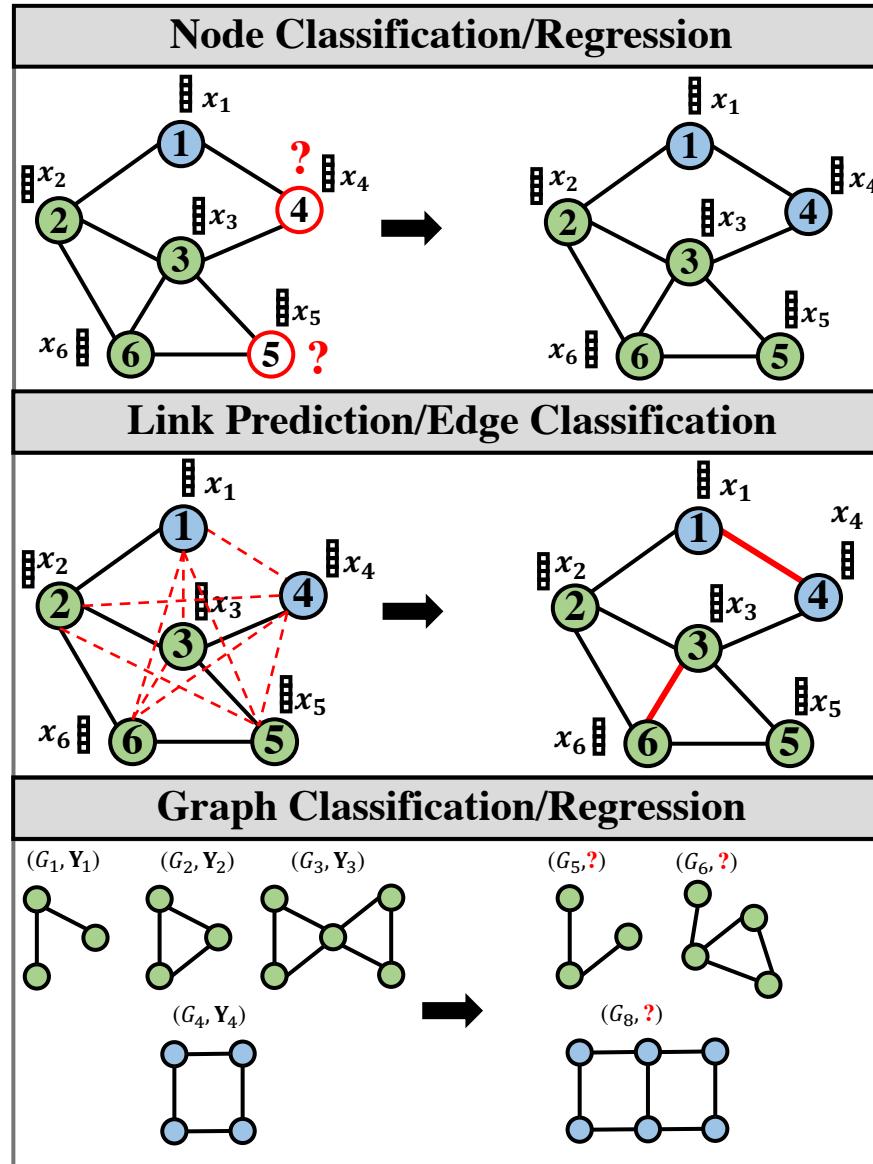
Knowledge Graph



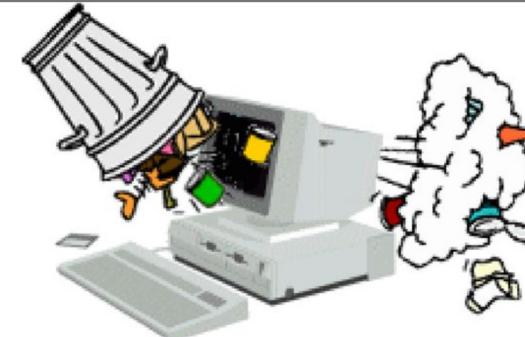
Reasoning / Planning Graph



Introduction and Background - Graph-based Tasks and Graph Machine Learning



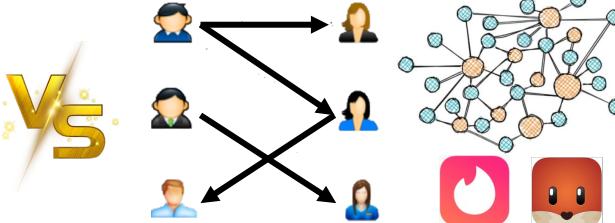
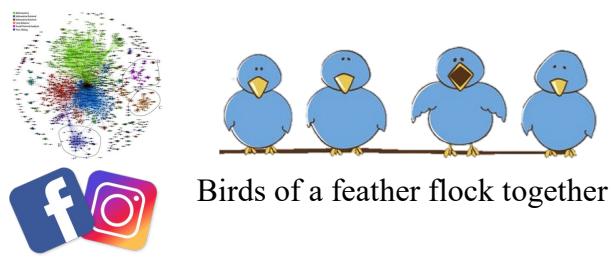
*Real-world
graph data
can have
data quality
challenges...*



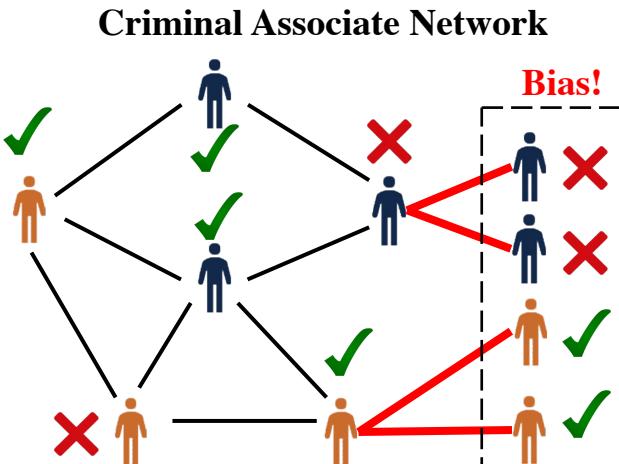
Garbage in, garbage out

Introduction and Background – Real-world Graphs have Data Quality Issues

Topological Issues e.g., Homophily vs Heterophily

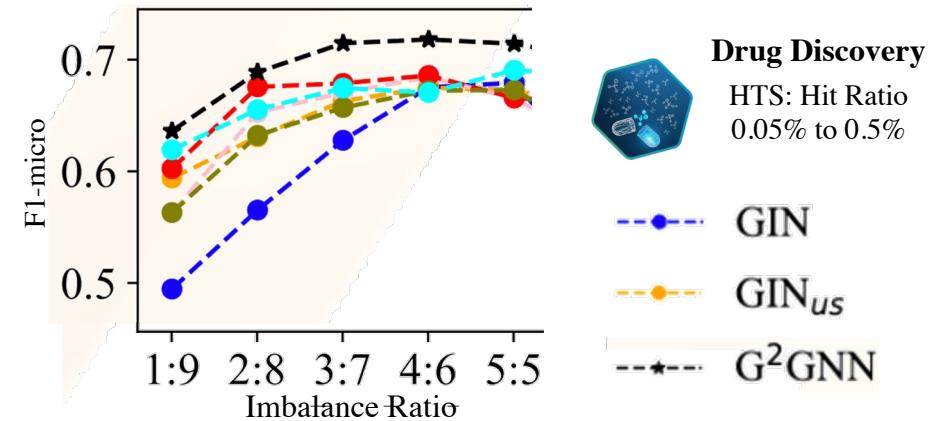


Bias Issues e.g., bail decision making



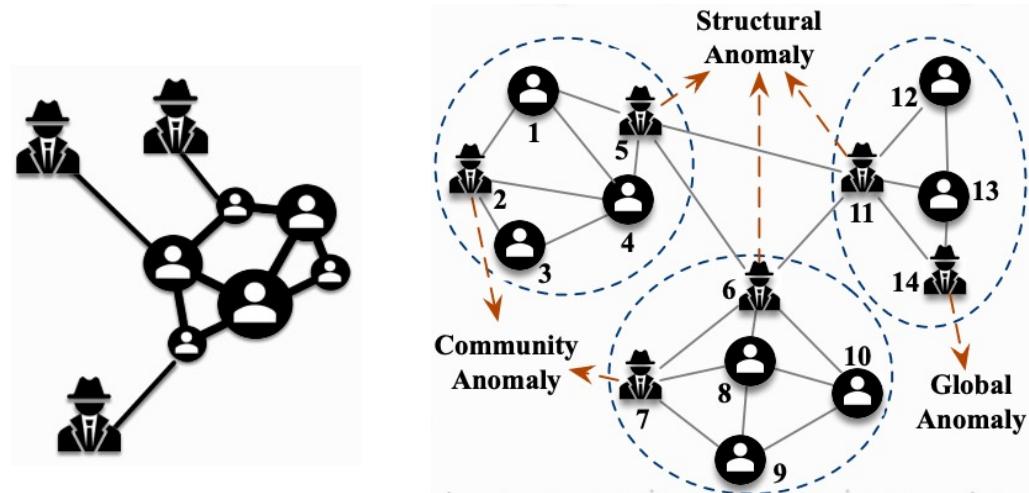
Imbalance Issues

e.g., labeled data in chemistry



- Drug Discovery
HTS: Hit Ratio
0.05% to 0.5%
- GIN
- GIN_{us}
- G²GNN

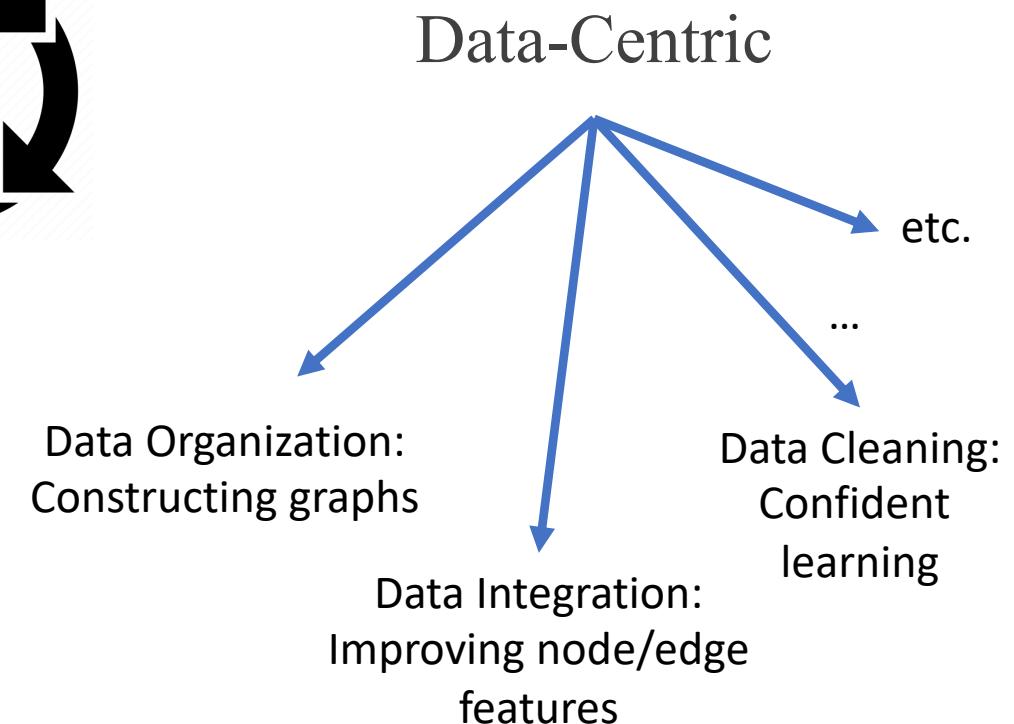
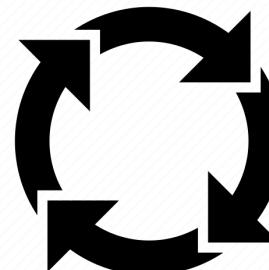
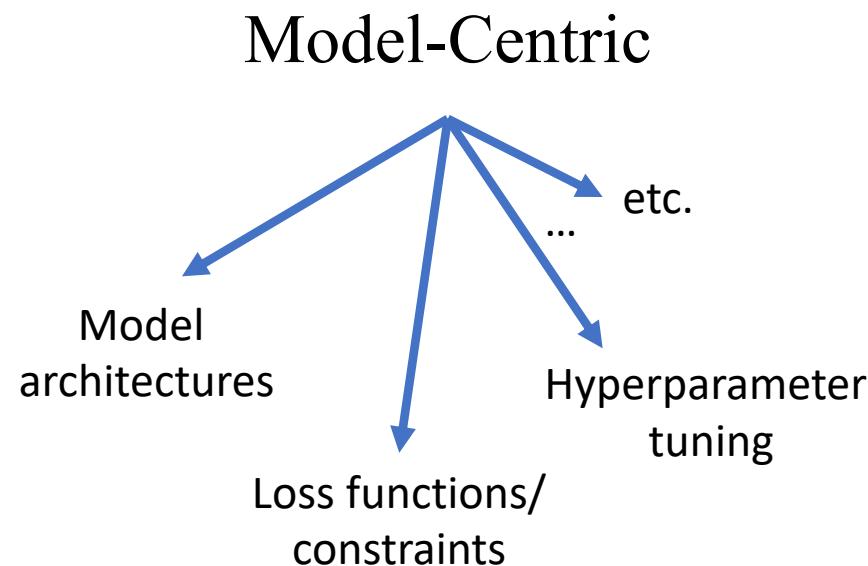
Abnormal Graph Data



Introduction and Background – Model- vs. Data-Centric Methods

Find the *best model* for
the given *fixed dataset*

Realize the *best dataset* for
the given *prediction task*



Introduction and Background – Model- vs. Data-Centric Methods



Credit: MIT Introduction to Data-Centric AI course & Inspired by XKCD 2494 “Flawed Data”

Data Quality-Aware Graph Machine Learning

- Introduction and Background
- Topology Issues
- Imbalance Issues
- Short Break
- Bias and Fairness Issues
- Limited Labeled Data Issues
- Abnormal Graph Data Issues
- Summary

Outline

- **Introduction and Background**
- Topology Issues
- Imbalance Issues
- Short Break
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Outline

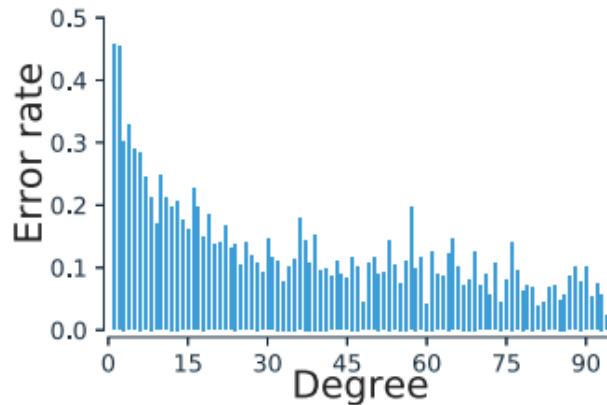
- Introduction and Background
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Topology Issues

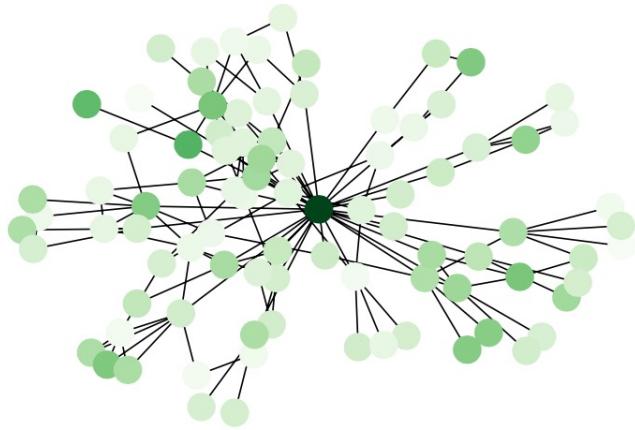
- Global Positional Issues
- Local Topology Issues
- Missing Graph Issues
- Future Directions and Q&A

Topology Issues – Global Topology Issues – Labeled Node Influence

Degree -> Influence

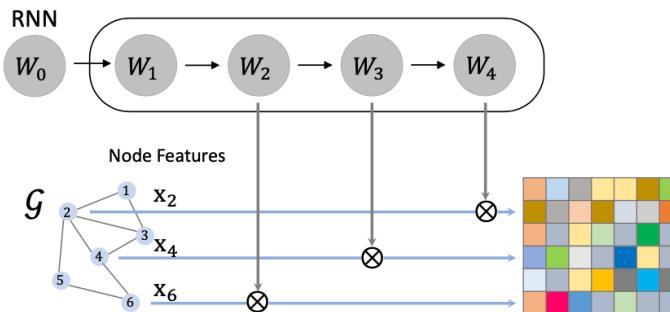


If $d_i > d_j$, v_i has higher influence than v_j on training GNNs

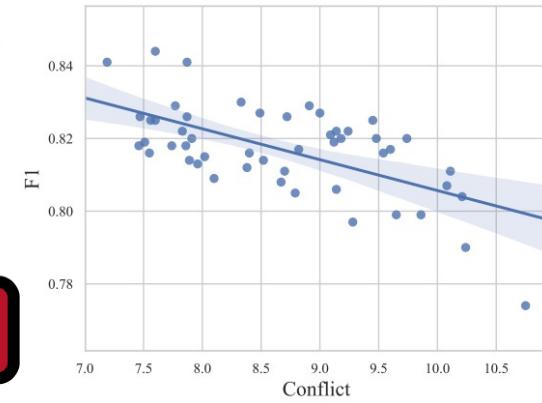
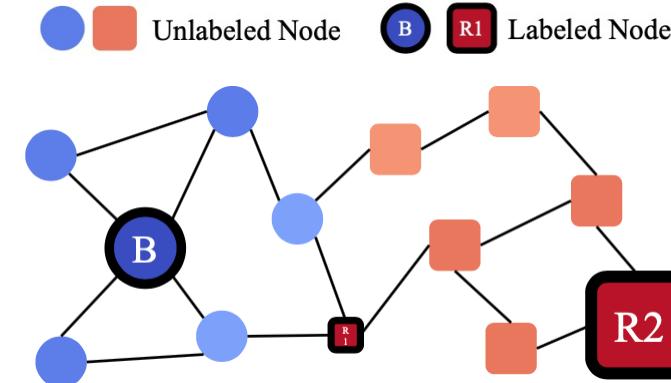


$$\mathbf{x}_i^{l+1} = \sigma \left(\sum_{j \in \mathcal{N}_i} a_{ij} \left(\mathbf{W}^l + \boxed{\mathbf{W}_{d_j}^l} \right) \mathbf{x}_j^l \right)$$

Degree-dependent!



Position -> Influence



$$\mathbf{P} = \alpha(\mathbf{I} - (1 - \alpha)\mathbf{A}')^{-1}$$

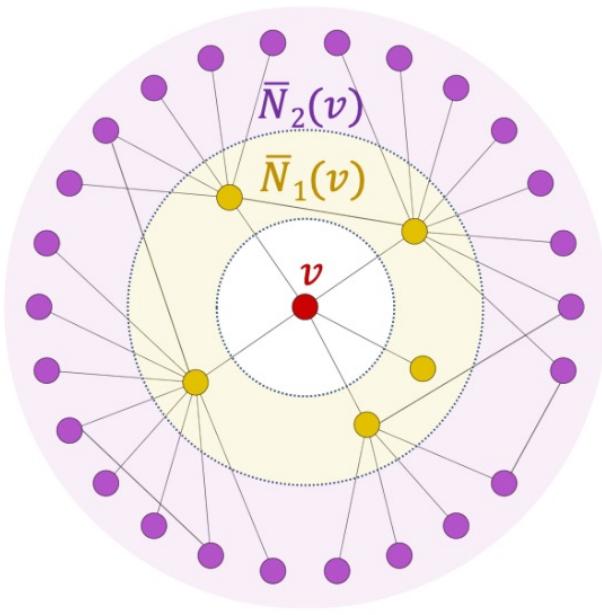
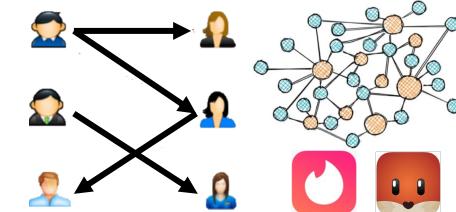
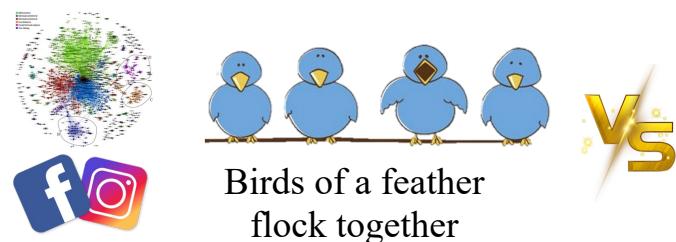
$$\boxed{\mathbf{T}_v} = \mathbb{E}_{\mathbf{x} \sim \mathbf{P}_{\mathbf{v}}} \left(\sum_{j \in [1, k], j \neq y_v} |\mathcal{C}_j|^{-1} \sum_{i \in \mathcal{C}_j} \mathbf{P}_{i, x} \right)$$

$$L = -|\mathcal{L}|^{-1} \sum_{v \in \mathcal{L}} \boxed{w_v} \sum_{c=1}^k y_v^c \log p_v^c$$

High T
High Conflicts,
low weight

Topology Issue – Local Topology Issues – Heterophily/Homophily

Homophily vs Heterophily



Graph-level Homophily

$$h(\mathcal{G}, \{y_i; i \in \mathcal{V}\}) = \frac{1}{|\mathcal{E}|} \sum_{(j,k) \in \mathcal{E}} \mathbb{1}(y_j = y_k)$$

Ego-Neighbor Separation

$$\mathbf{r}_v^k = \text{COMBINE}(\mathbf{r}_v^{k-1}, \text{AGGR}(\{\mathbf{r}_u^{k-1}: u \in \mathcal{N}_v\}))$$

Higher-order Neighbor

$$\mathbf{r}_v^k = \text{COMBINE}(\mathbf{r}_v^{k-1}, \text{AGGR}_1(\{\mathbf{r}_u^{k-1}: u \in \mathcal{N}_v^1\}), \text{AGGR}_2(\{\mathbf{r}_u^{k-1}: u \in \mathcal{N}_v^2\} \dots))$$

Combination of Intermediate Representation

$$\mathbf{r}_v^k = \text{COMBINE}(\mathbf{r}_v^1, \mathbf{r}_v^2, \dots, \mathbf{r}_v^K)$$

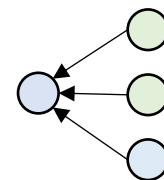
Class belief propagation

$$\mathbf{B}^k = \mathbf{B}^0 + \underbrace{\mathbf{AB}^{k-1}\mathbf{H}}$$

Transition
among Graph

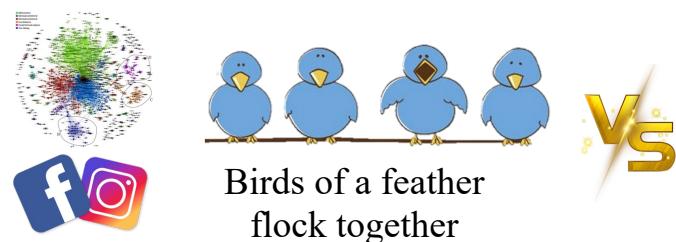
$$\mathbf{H} \in \mathbb{R}^{|Y| \times |Y|}$$

$$\mathbf{B} \in \mathbb{R}^{|V| \times |Y|}$$

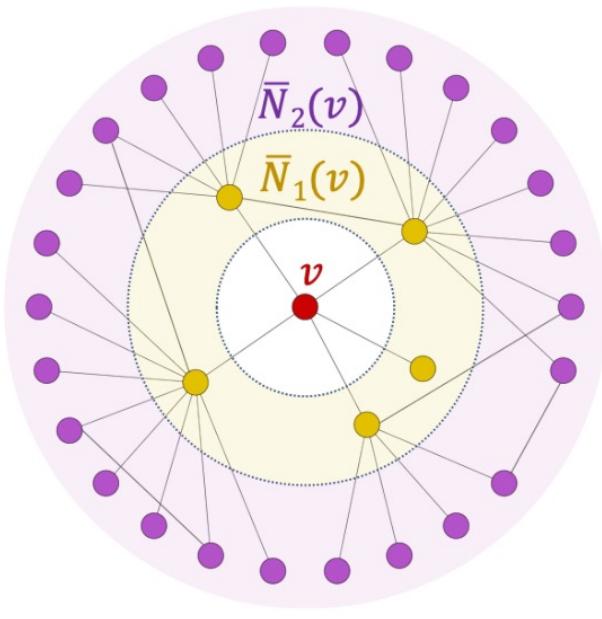
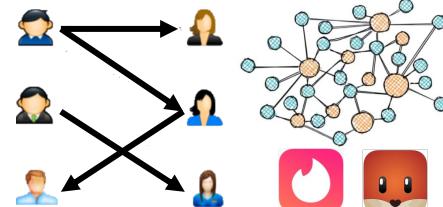


Topology Issue – Local Topology Issues – Heterophily/Homophily

Homophily vs Heterophily



VS.



Graph-level Homophily

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Class belief propagation

$$\mathbf{B}^k = \mathbf{B}^0 + \underbrace{\mathbf{AB}^{k-1}\mathbf{H}}$$

Graph Transition
Class Transition

$$\mathbf{AB}^{k-1} [0.1|0.1|0.8]$$

$$\begin{bmatrix} 0.1 & 0.3 & 0.6 \\ 0.8 & 0.1 & 0.1 \\ 0.7 & 0.3 & 0 \end{bmatrix}$$

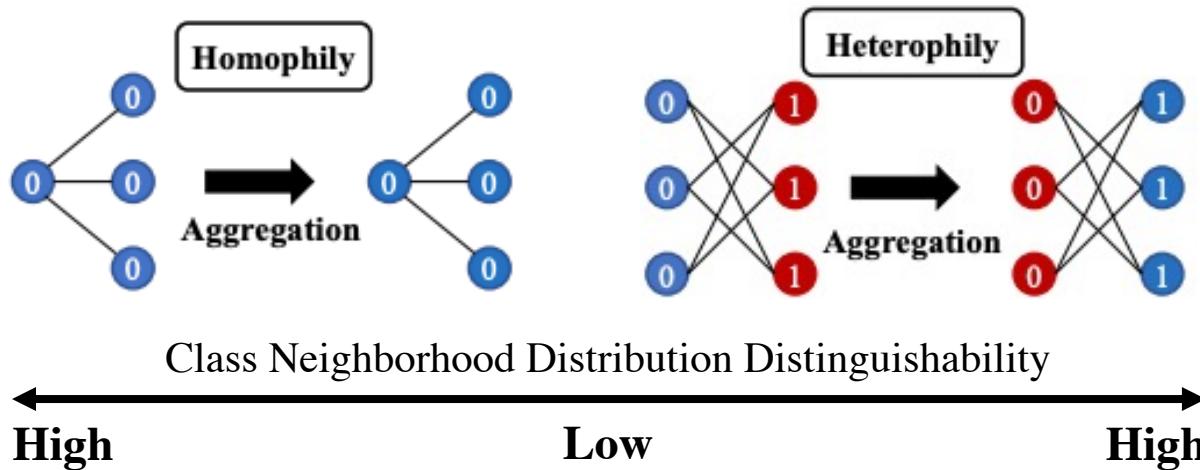
\mathbf{H}

$$\mathbf{H} \in \mathbb{R}^{|Y| \times |Y|}$$

$$\mathbf{B} \in \mathbb{R}^{|V| \times |Y|}$$

Topology Issue – Local Topology Issues – Heterophily/Homophily

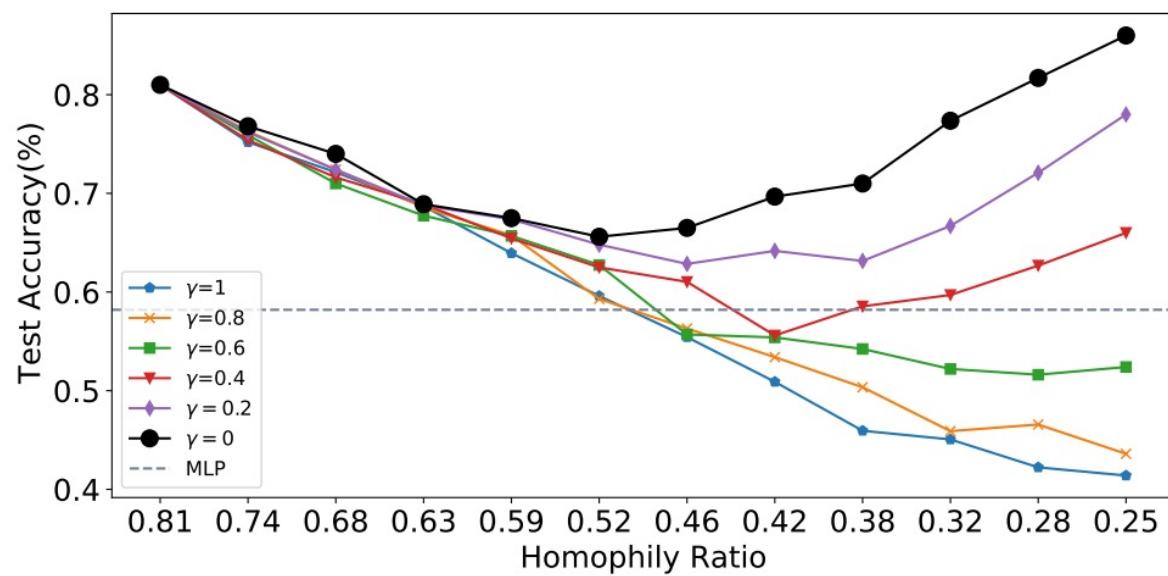
Across Different Graphs



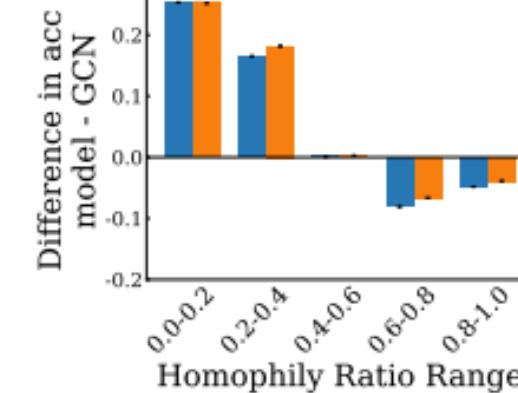
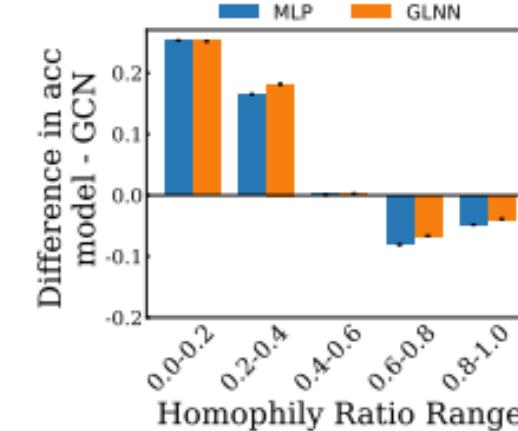
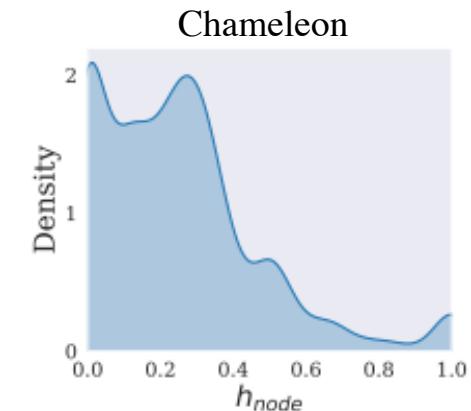
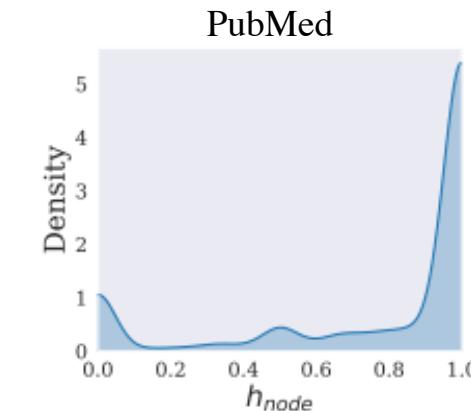
High

Low

High



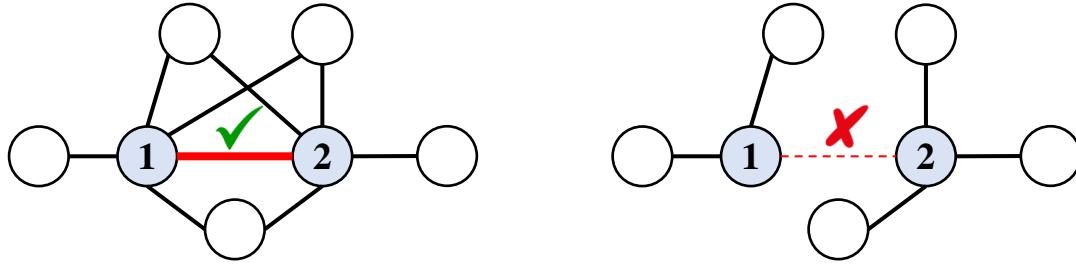
Within the Same Graph



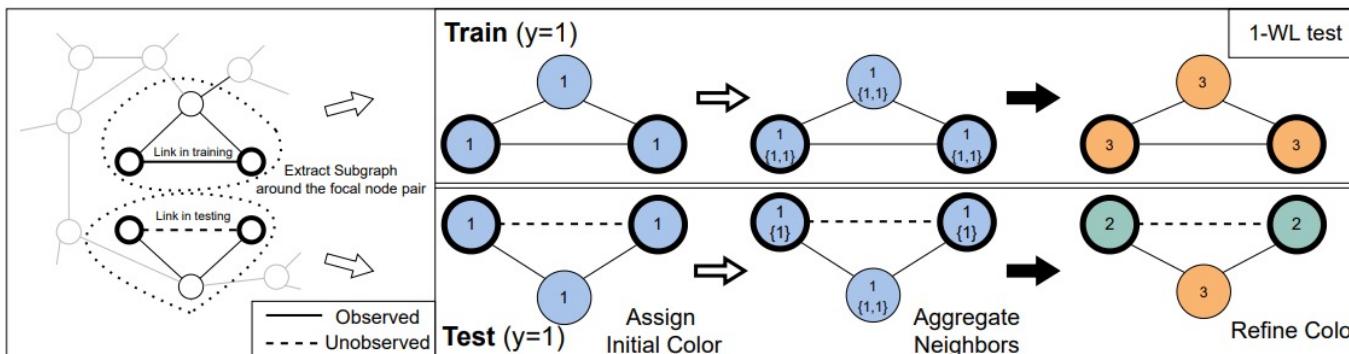
In **homophily** graph, GNNs > MLP on **homophily** nodes
In **heterophily** graph, GNNs > MLP on **heterophily** nodes

Topology Issue – Local Topology Issues – Training-to-Testing Topology Shift

Link Prediction

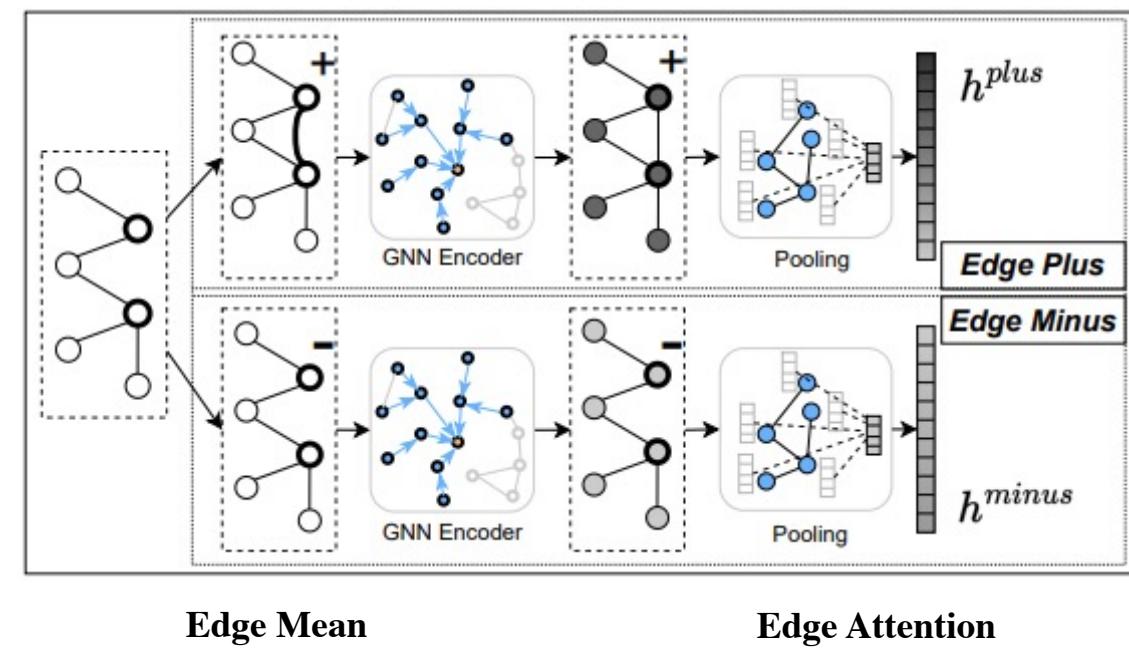
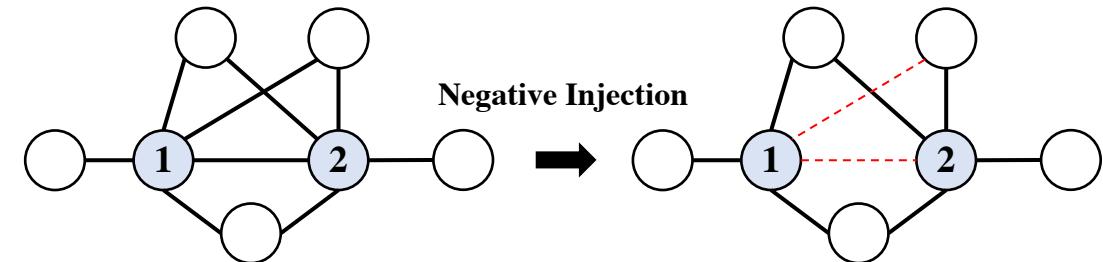


Local Subgraph → Predictor → Link



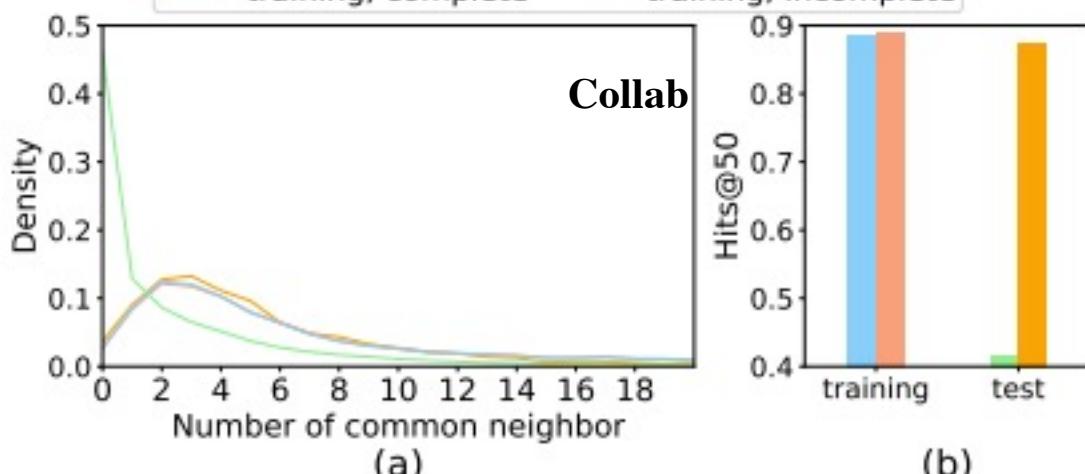
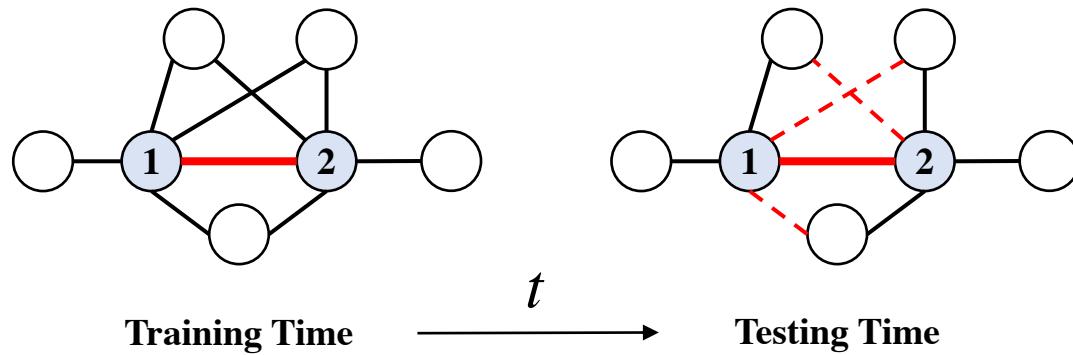
Focal Link is missing from training subgraph to testing subgraph

Distribution Shift



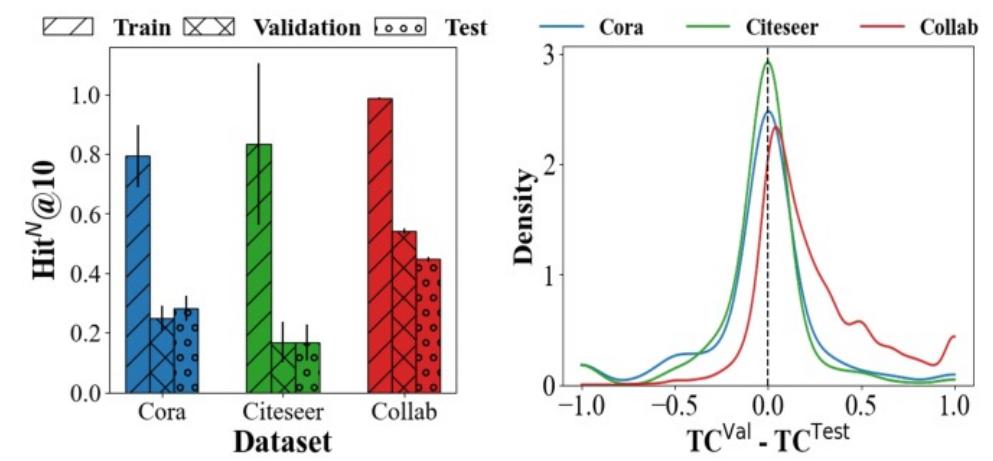
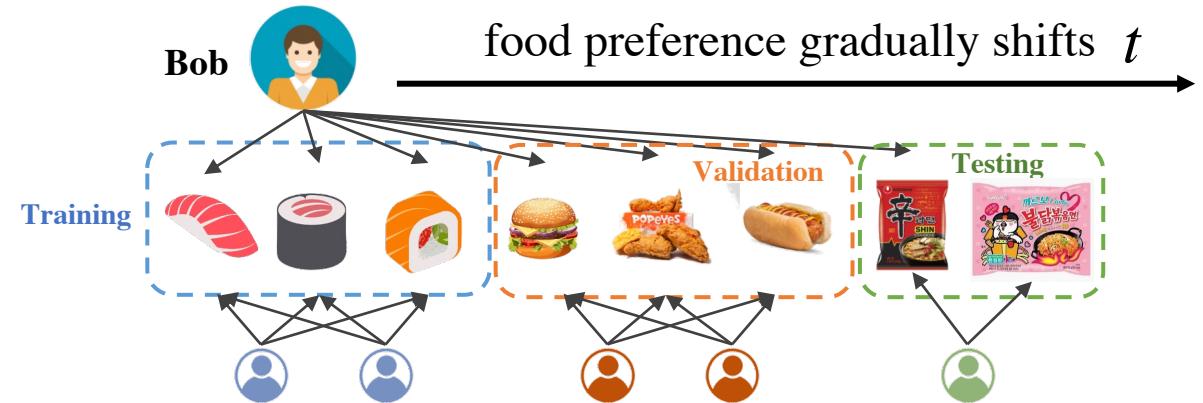
Topology Issue – Local Topology Issues – # of Common Neighbor Shift

Link-centric Perspective



Time-based Split
Testing edges have more testing edges around

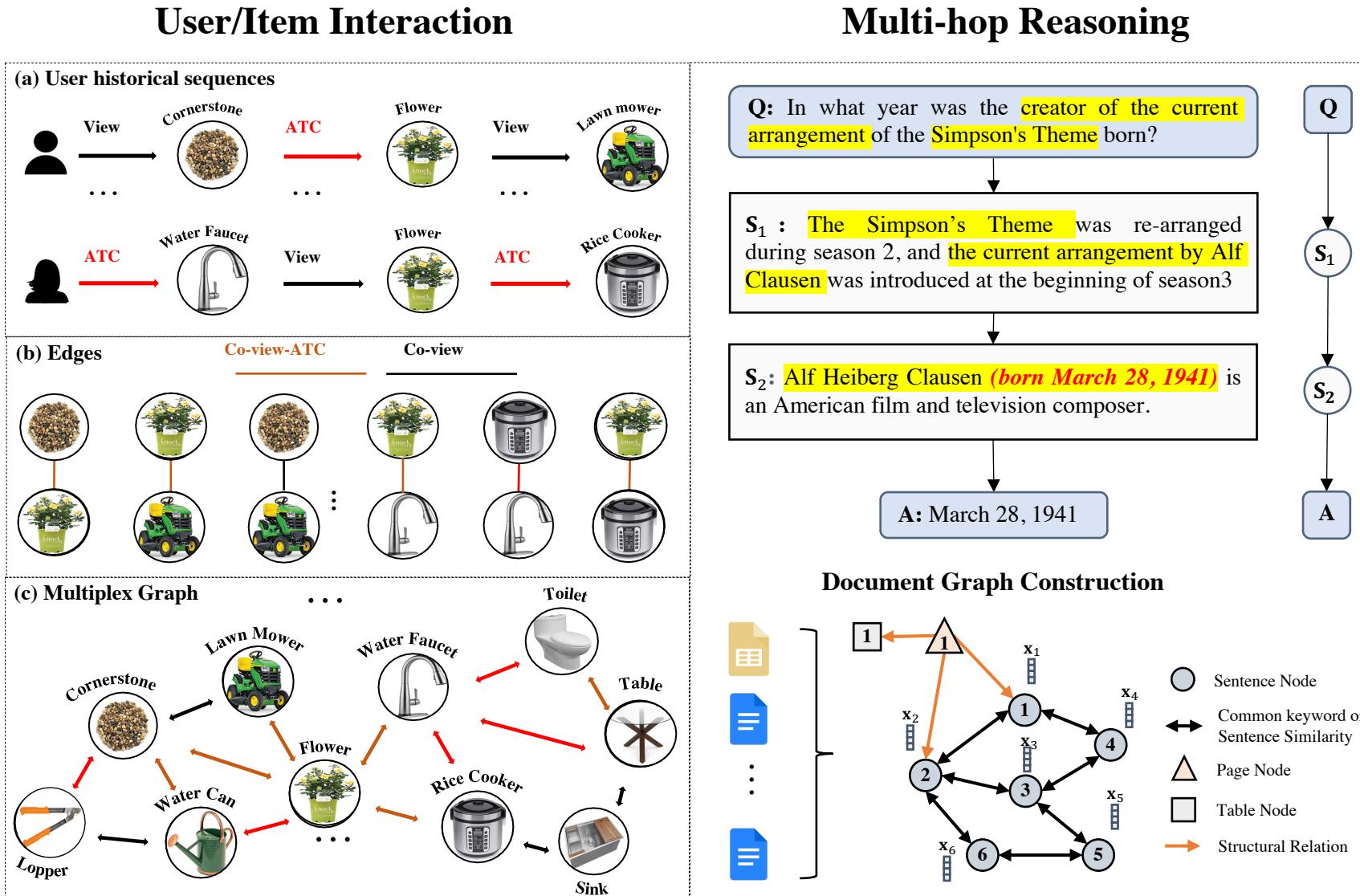
Node-centric Perspective



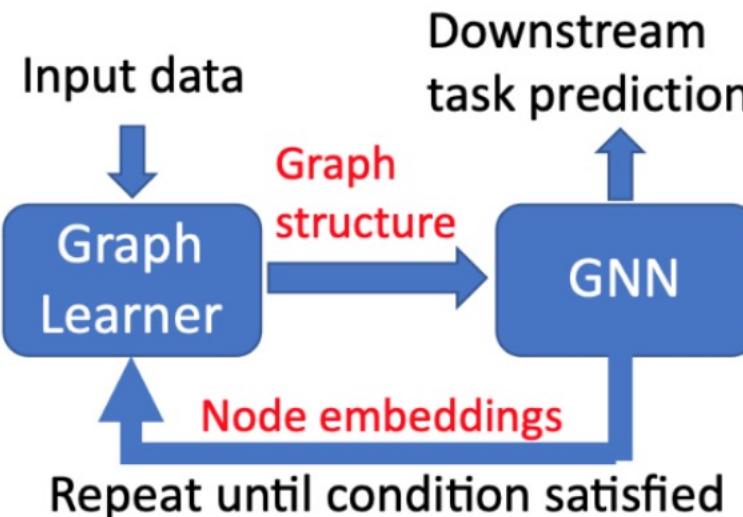
Topology Issue – Missing Topology Issues

Sometimes Real-world Applications do not have Graphs!

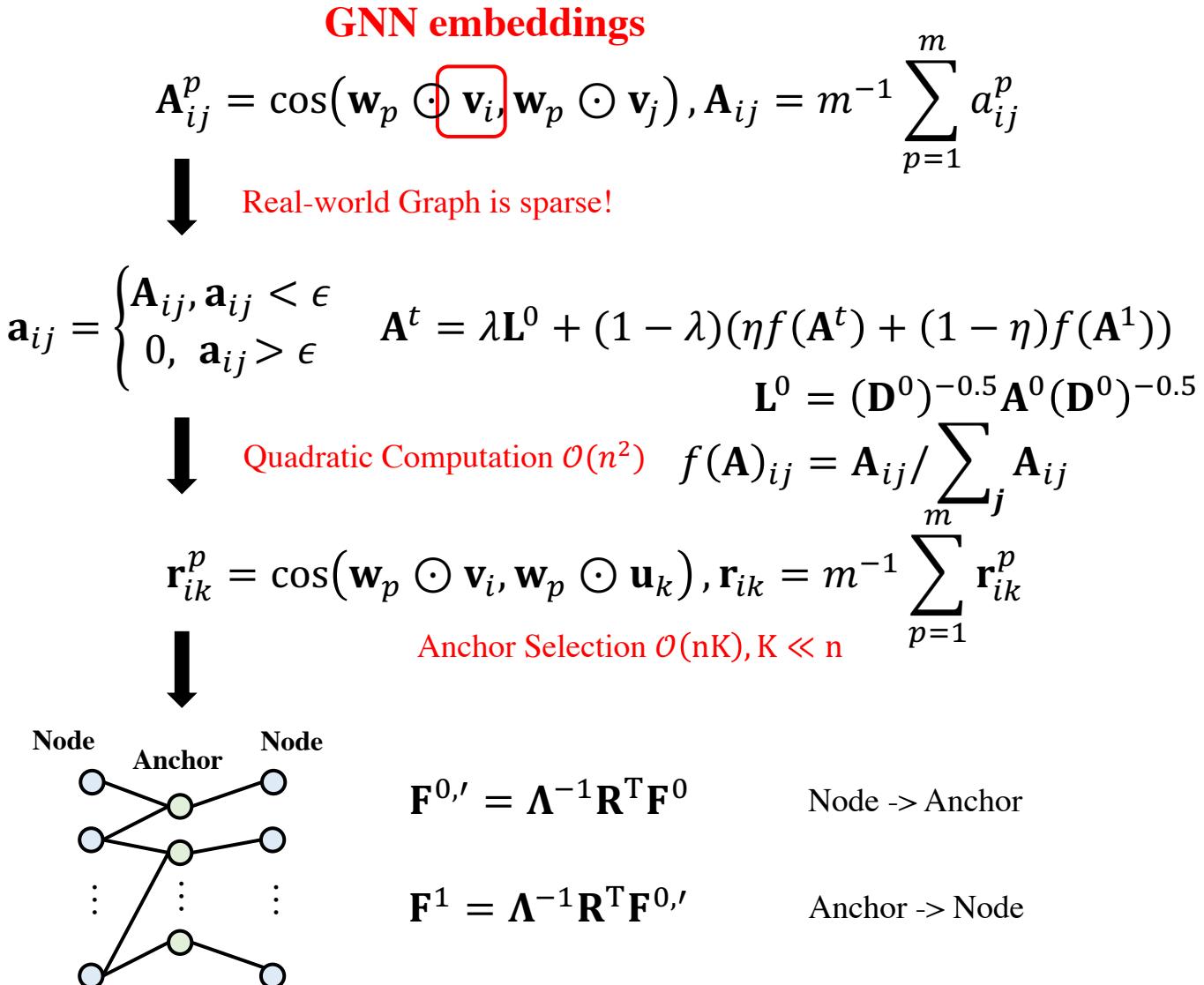
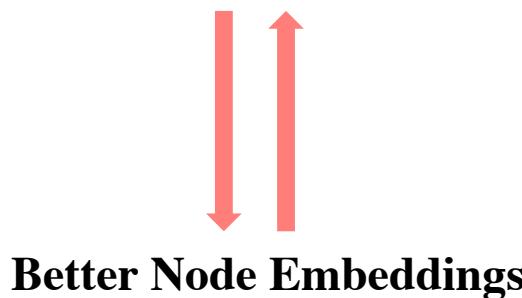
But Graph can actually encode some useful information



Topology Issue – Missing Topology Issues

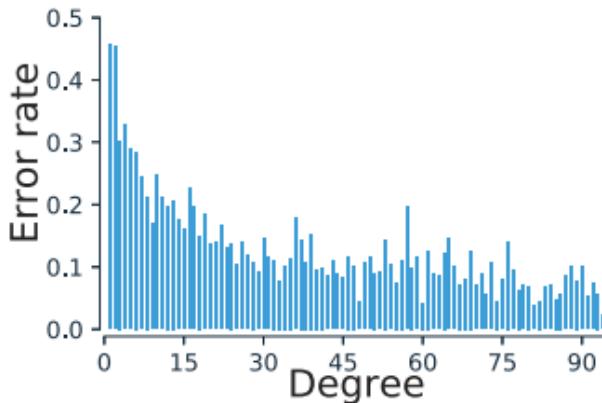


Better Graph Structure

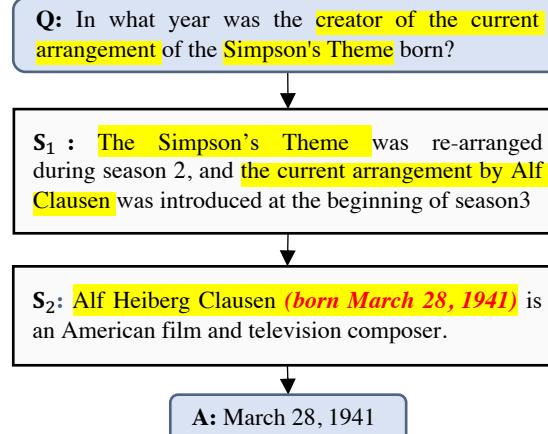


Q&A and Future Work – Topology Issue

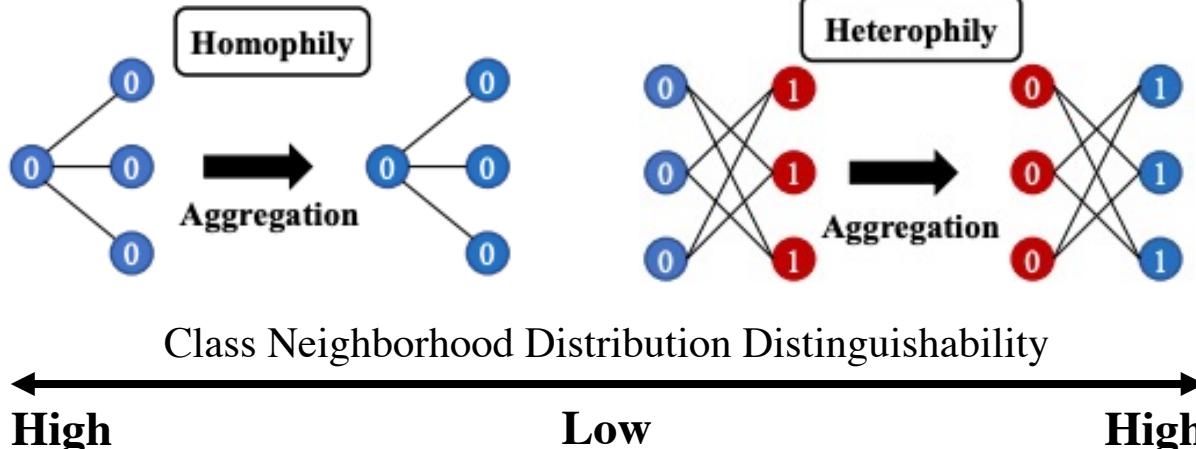
Global Topology Issue



Missing Topology Issue

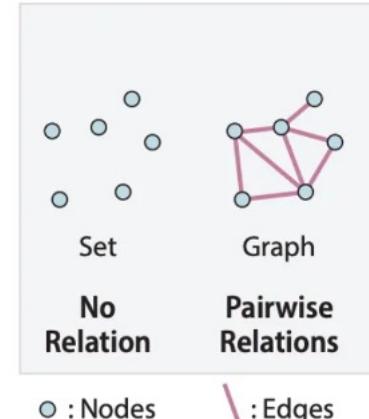


Local Topology Issue



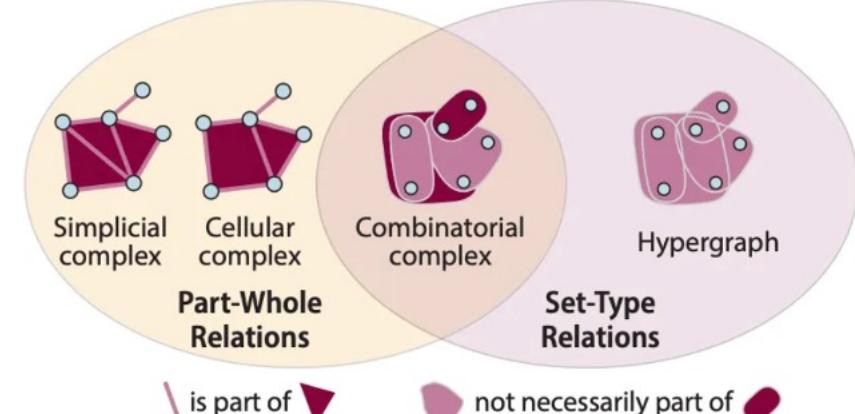
Topology Issue of Complex Graphs

Traditional Discrete Domains



○ : Nodes ↗ : Edges

Domains of Topological Deep Learning



Outline

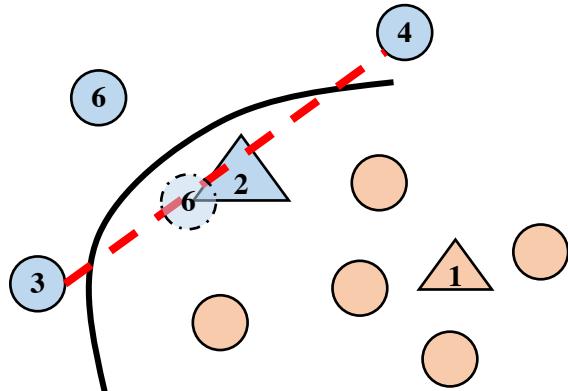
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Imbalance Issues

- Node-level Imbalance
- Graph-level Imbalance
- Edge-level Imbalance
- Future Directions and Q&A

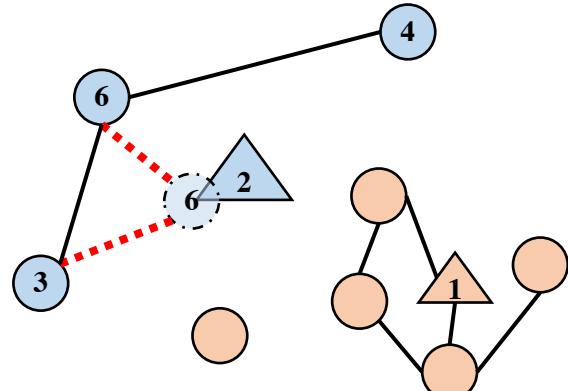
Imbalance Issues – Node-level imbalance

SMOTE



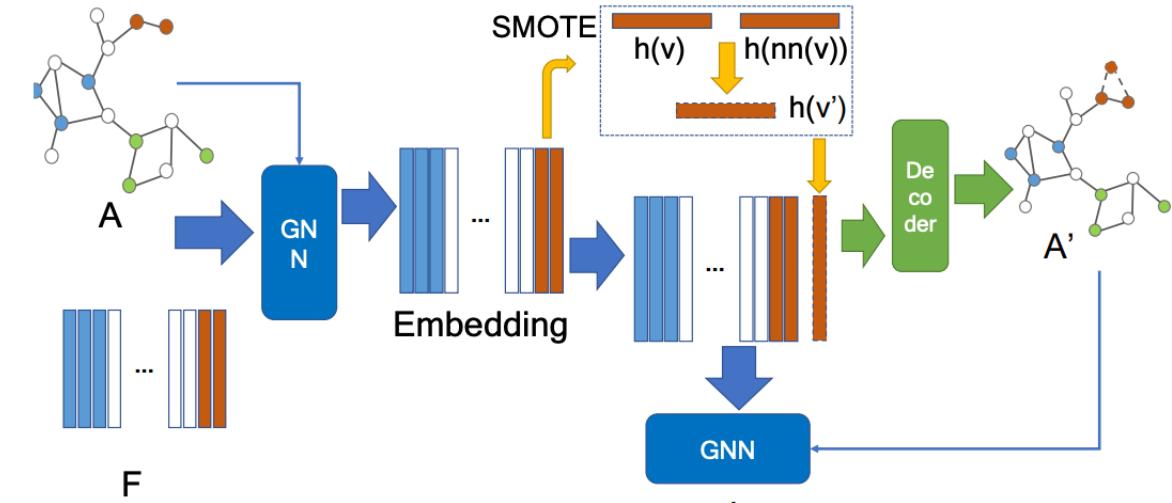
- Feature Interpolation
- Train – Major
- Train – Minor
- △ Test – Major
- △ Test – Minor

Graph-structured data has both feature and edge



- Feature Interpolation
- Edge Generation

GraphSMOTE



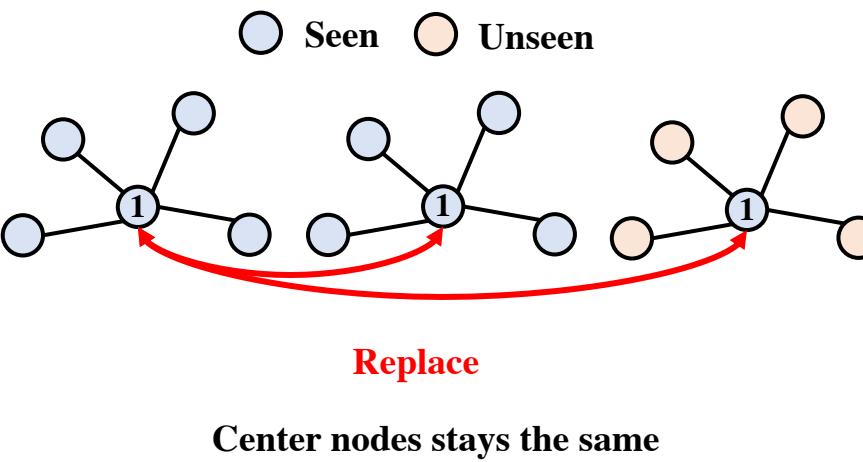
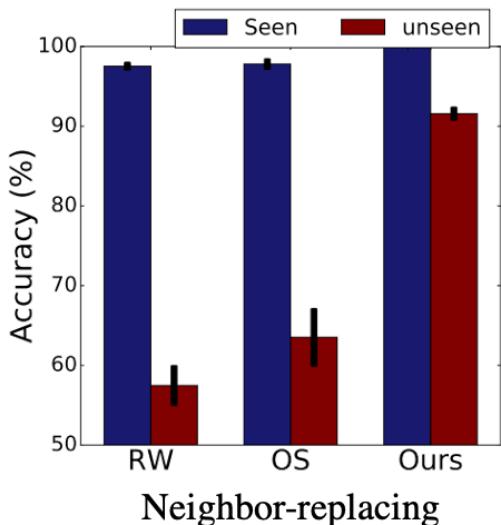
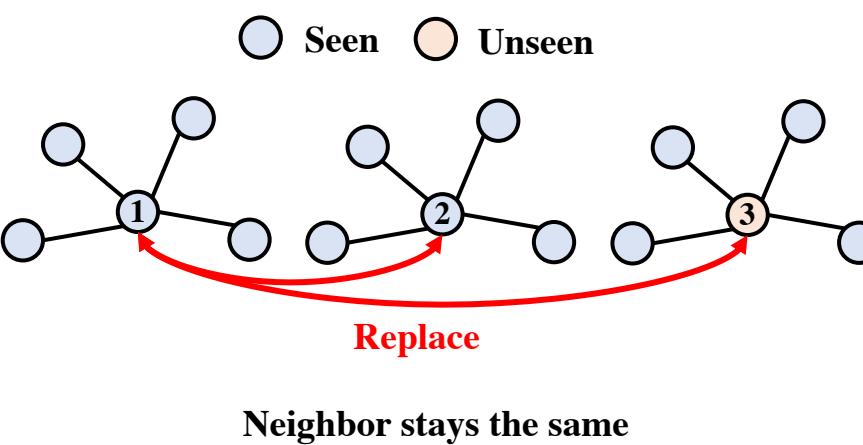
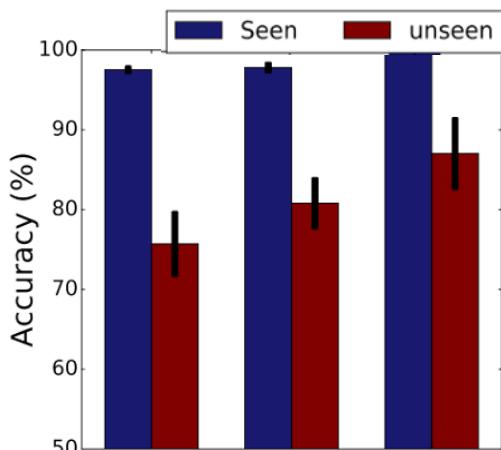
$$nn(v) = \operatorname{argmin}_u \| \mathbf{h}_u^1 - \mathbf{h}_v^1 \|, \text{ s.t. } \mathbf{Y}_u = \mathbf{Y}_v$$

$$\mathbf{h}_{v'}^1 = (1 - \delta) \mathbf{h}_v^1 + \delta \mathbf{h}_{nn(v)}^1$$

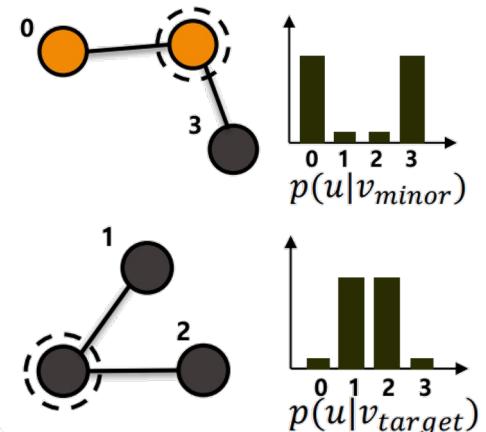
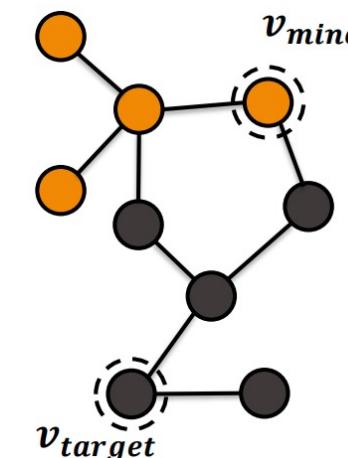
$$\mathbf{A}_{v'u} = \begin{cases} 1, & \text{if } \mathbf{E}_{v'u} \geq \eta \\ 0, & \text{otherwise} \end{cases} \quad \mathcal{L}_{edge} = \|\mathbf{E} - \mathbf{A}\|_F^2$$

$$\mathbf{E}_{vu} = \operatorname{softmax}(\sigma(\mathbf{h}_v^1 \mathbf{S} \mathbf{h}_u^1))$$

Imbalance Issues – Node-level imbalance



Neighborhood Memorization



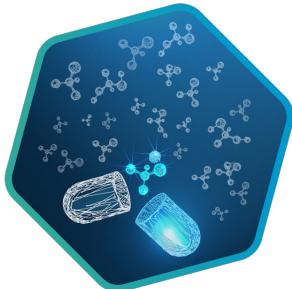
$$p(u|v_{mixed}) = \hat{\phi}p(u|v_{minor}) + (1 - \hat{\phi})p(u|v_{target})$$

$$0.5 < \hat{\phi} = \frac{1}{1 + e^{-\phi}} < 1 \quad \phi = KL(\sigma(\mathbf{o}_{minor}) || \sigma(\mathbf{o}_{target}))$$

$$\mathbf{o}_{minor} = |\mathcal{N}_v|^{-1} \sum_{u \in \mathcal{N}_v} \mathbf{o}_{minor}$$

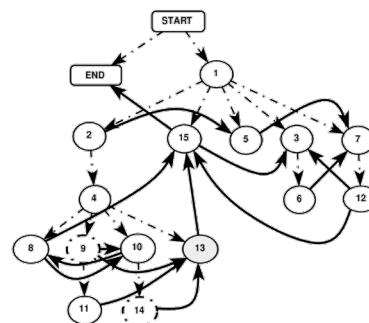
Imbalance Issues – Graph-level imbalance

Drug Discovery



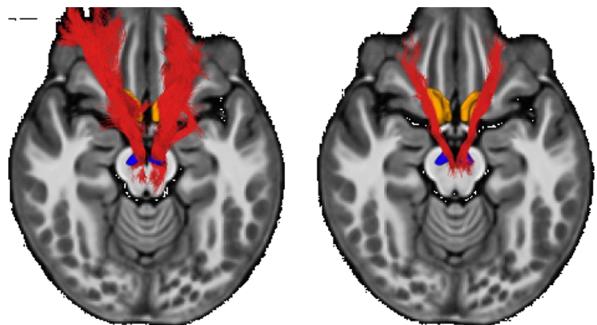
HTS Hit Ratio
0.05% to 0.5%

Malware Detection



0.01% Google, 2% Android,

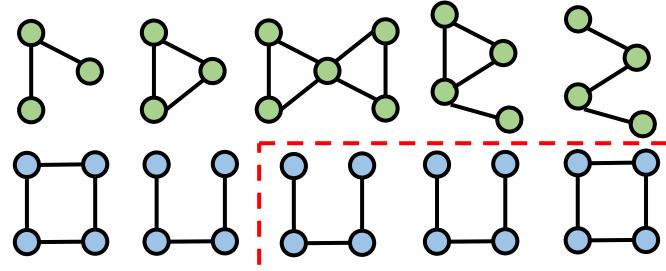
ASD Brain Classification



Normal : Autism
36 : 1

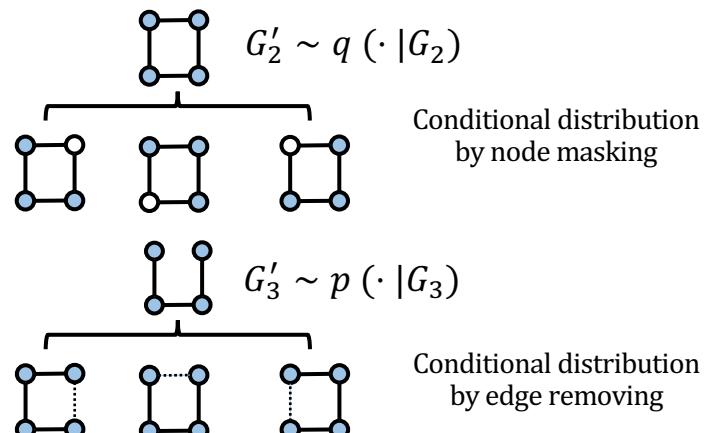
Autism Statistics. 2023

Quantity Augmentation

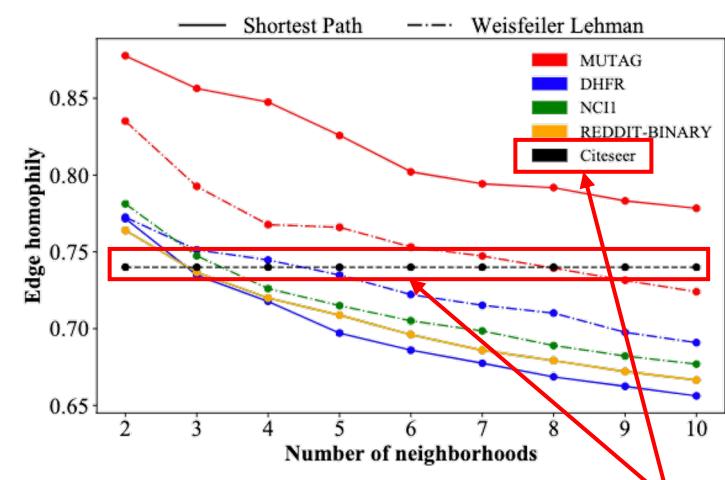
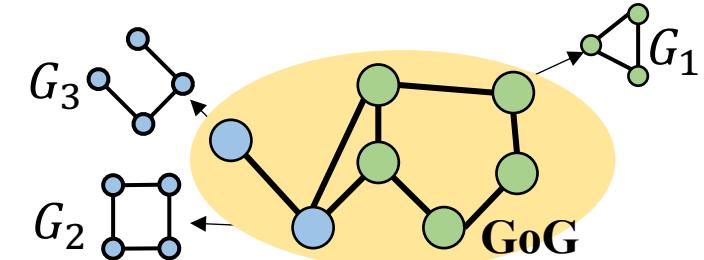


Structure Augmentation

SPP - Structurally Similar Molecules tend to have similar properties

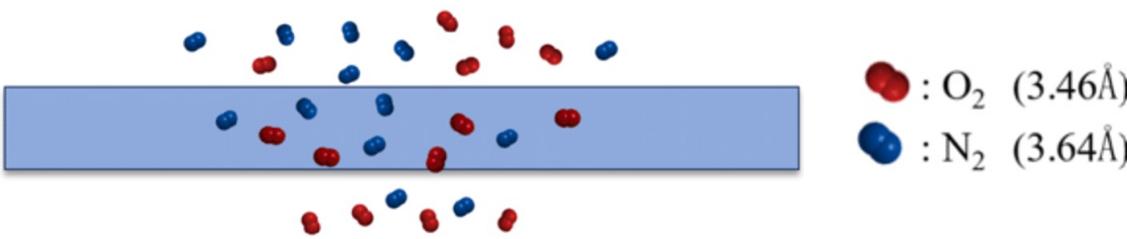


Graph-of-Graphs (GoG)



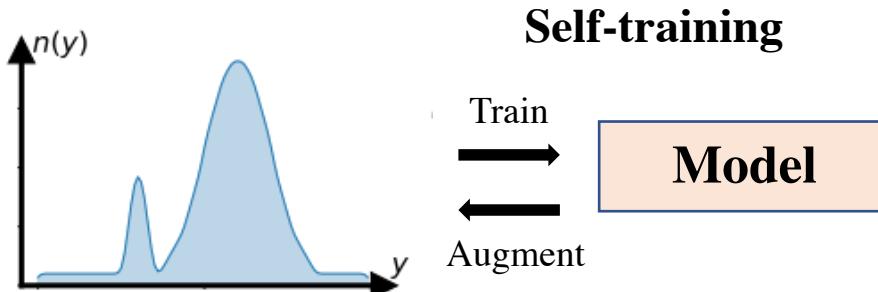
Constructed GoG demonstrates high homophily!

Imbalance Issues – Graph-level imbalance



70 years, ~600 polymers, oxygen permeability ,
Polymer Gas Separation Membrane Database

Imbalance Graph
Regression!



Self-training

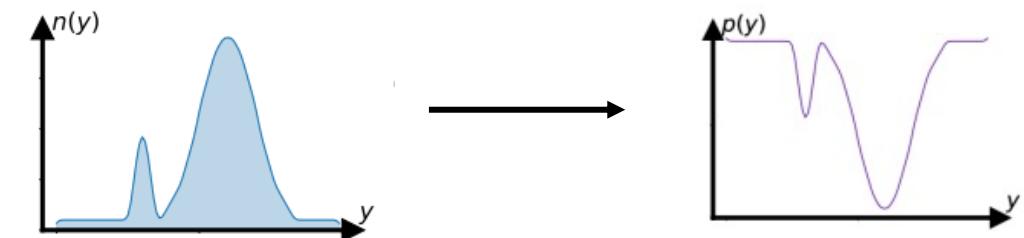
Train
Augment

Model

(1) Use Model to predict on unlabeled graphs and
select those high-quality-one

$$\sigma_i = \frac{1}{\text{Var} \left(\{f(g(G_{(i,j)}))\}_{j=1,2,\dots,B} \right)}.$$

(2) Sample more for label interval with less training samples



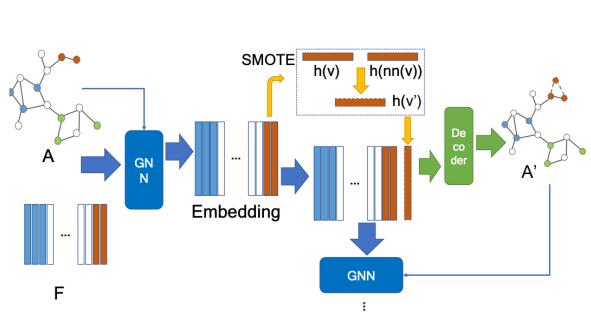
(3) Anchor-based Mix-up

a_i, \mathbf{z}_i : anchor-label
and embedding

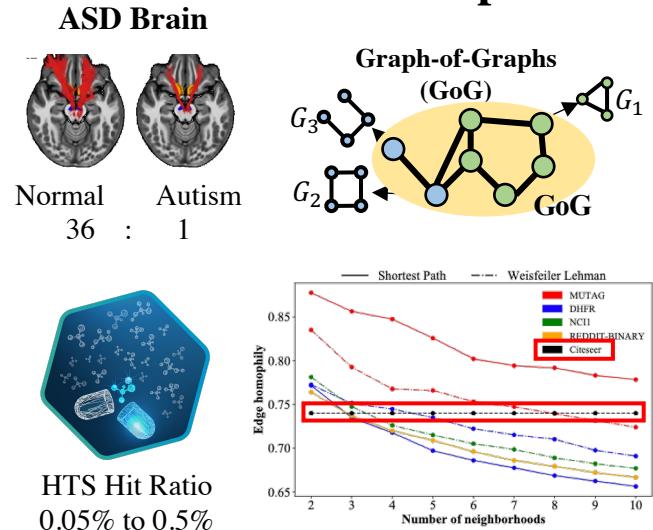
$$\begin{cases} \tilde{\mathbf{h}}_{(i,j)} &= \lambda \cdot \mathbf{z}_i + (1 - \lambda) \cdot \mathbf{h}_j, \\ \tilde{y}_{(i,j)} &= \lambda \cdot a_i + (1 - \lambda) \cdot y_j, \end{cases}$$

Q&A and Future Work – Imbalance Issues

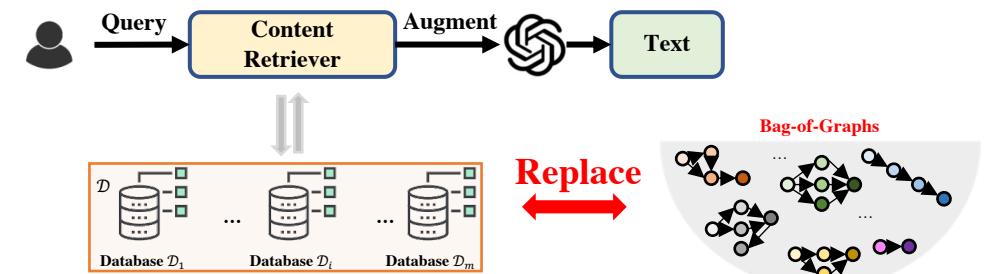
Node-level Imbalance



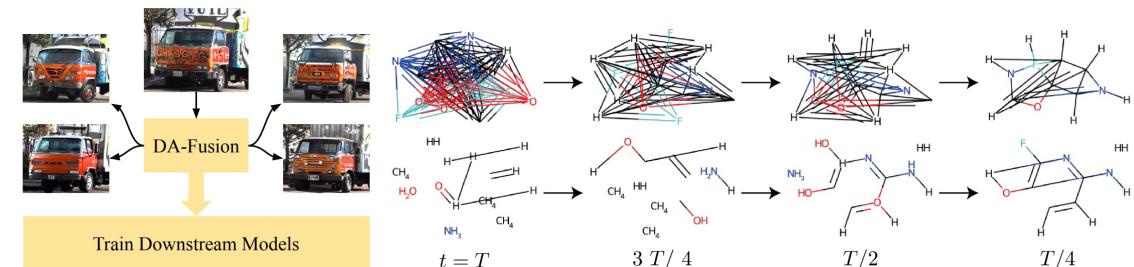
Graph-level Imbalance



Retrieval Additional Supervision



Generate Additional Supervision



Short Break (4 min)

Outline

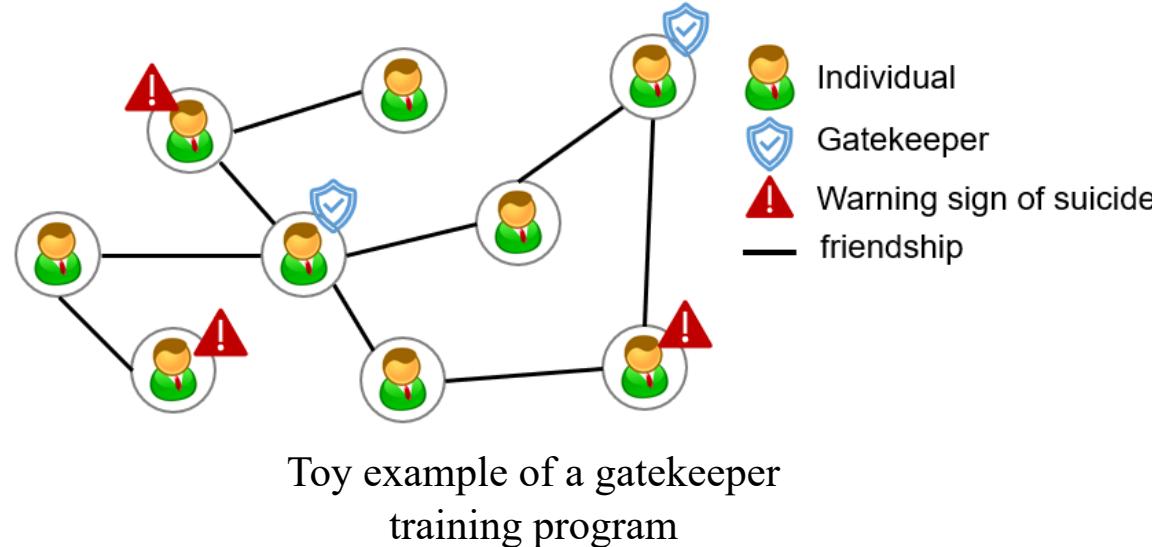
- Introduction and Background
- Topology Issues
- Imbalance Issues
- Short Break
- **Bias and Fairness Issues**
- Limited Labeled Data Issues
- Abnormal Graph Data Issues
- Summary

Bias and Fairness Issues - Suicide Prevention

- Why suicide prevention?



Gatekeeper training
programs



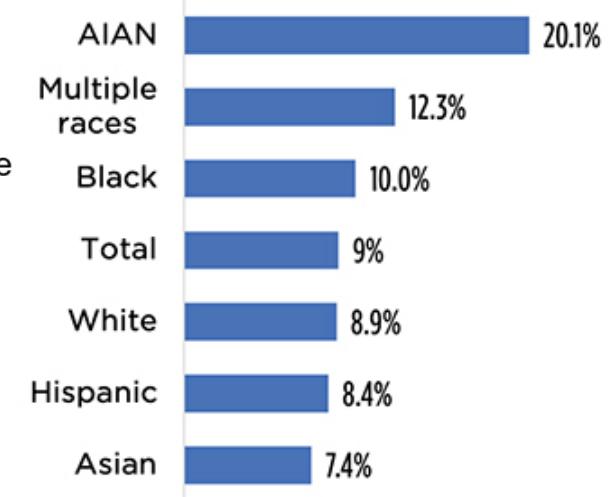
Toy example of a gatekeeper training program

- Existing prevention strategies **disproportionately** affect different groups

- Key question

- How to correct the bias and ensure fairness on graphs?

Percentage of high schoolers reporting a suicide attempt in the past 12 months, by race/ethnicity



Suicide attempts
by race/ethnicity

Bias and Fairness Issues - Fairness Definition

- **Principle**
 - Lack of favoritism from one side or another
- **Rich fairness definitions**
 - Group fairness
 - Statistical parity
 - Equal opportunity
 - Equalized odds
 - Accuracy parity
 - ...
 - Individual fairness
 - Counterfactual fairness
 - Degree fairness (on graphs)



Fairness definition

Group fairness

Individual fairness

Counterfactual fairness

Degree fairness

Two sides

Two demographic groups

Two data points

A data point and its counterfactual version

Two group of nodes with same degree

- **Group Fairness on Graphs**
- Individual Fairness on Graphs
- Degree Fairness on Graphs
- Future Directions and Q&A

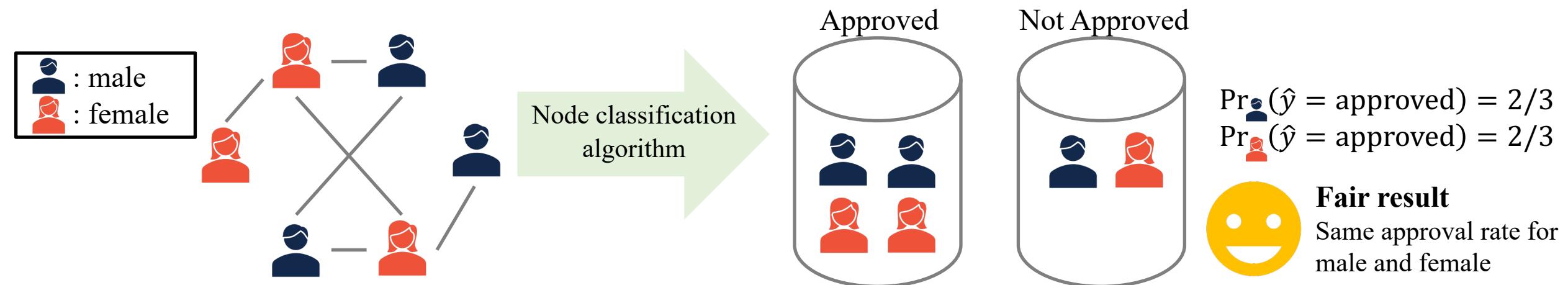
Group Fairness: Statistical Parity

- Statistical parity = equal acceptance rate

$$\Pr_+(\hat{y} = c) = \Pr_-(\hat{y} = c)$$

- \hat{y} : model prediction
- \Pr_+ : probability for the protected group
- \Pr_- : probability for the unprotected group
- Also known as demographic parity, disparate impact

- Example: clinical trial participation



Group Fairness: Equal Opportunity

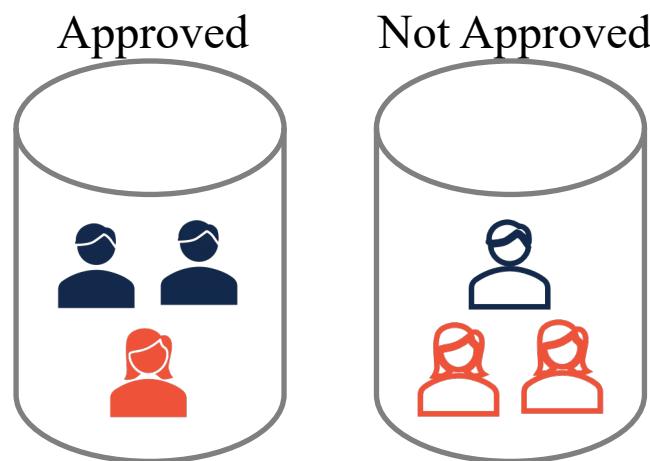
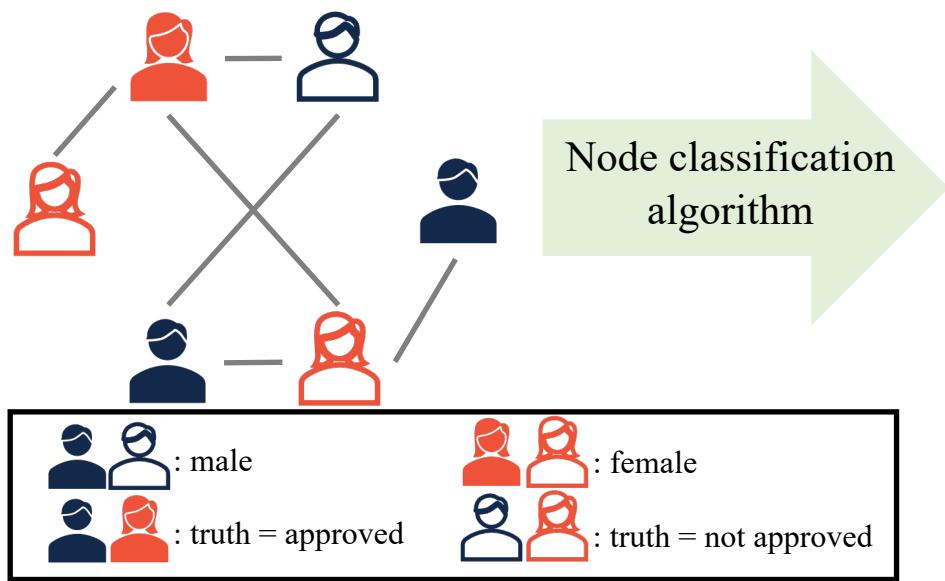
- Equal opportunity = equal true positive rate

$$\Pr_+(\hat{y} = c | y = c) = \Pr_-(\hat{y} = c | y = c)$$

- y : true label
- \hat{y} : model prediction
- \Pr_+ : probability for the protected group
- \Pr_- : probability for the unprotected group

If hold for all classes, it is called **equalized odds**

- Example: clinical trial participation



$$\Pr_{\text{blue}}(\hat{y} = \text{approved} | \text{blue}) = 1$$
$$\Pr_{\text{red}}(\hat{y} = \text{approved} | \text{red}) = 1$$



Fair result

Same true positive rate for male and female

Adversarial Learning for Fair Representation Learning

- **Statistical parity**

- Independence between the learned embedding \mathbf{z} and a sensitive attribute a
 $\mathbf{z}_u \perp a_u, \forall \text{ node } u$

where a_u is the sensitive value of node u

- **Formulation**

- Mutual information minimization

$$I(\mathbf{z}_u, a_u) = 0, \forall \text{ node } u$$

- Analogous to statistical parity in classification task
- Fail to predict a_u using \mathbf{z}_u  ← no information about a_u in \mathbf{z}_u

- **Solution**

- Adversarial learning
- Encoder: encode node into low-dimensional embedding space for downstream tasks
- Discriminator: fail to predict a_u using \mathbf{z}_u

Corresponding to
'adversarial'

Limitation #1: Full Access to Sensitive Attribute Information

- **Adversarial learning**

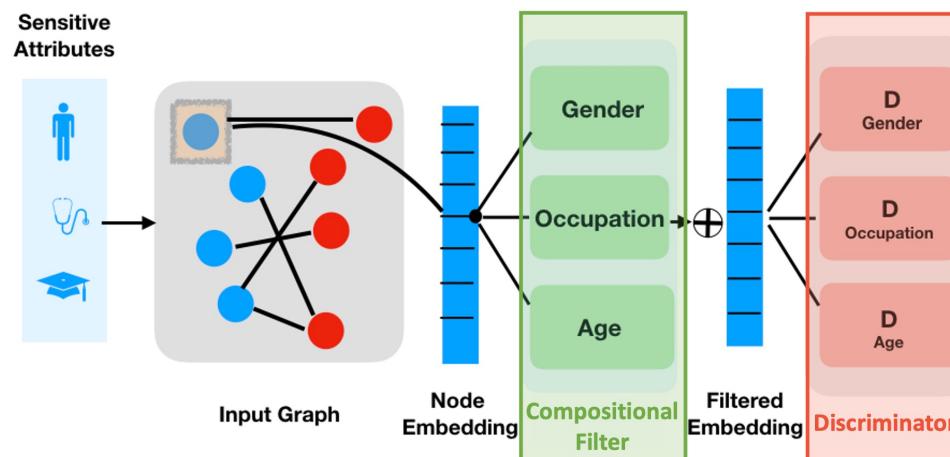
- Minimize a task-specific loss function to learn ‘**good**’ representations
- Maximize the error of predicting sensitive feature to learn ‘**fair**’ representations

- **Limitations**

- Require the sensitive attribute of all training nodes to train a good discriminator
- Ignore the fact that sensitive information is hard to obtain due to privacy

- **Question**

- What if we only have **limited** sensitive attribute information?



FairGNN: Additional Supervision Signal

• Observation

- Adversarial learning is unstable to train \leftarrow even worse with limited sensitive attribute
- Failure to converge may also cause discrimination

• Key idea

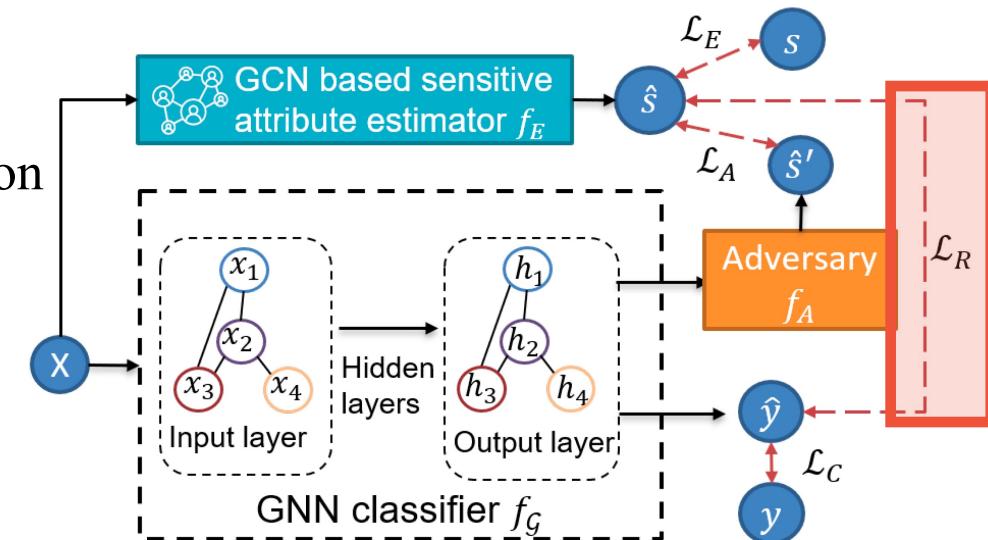
- Additional prerequisite of independence for additional supervision
- Independence \rightarrow zero covariance

• Solution

- Pseudo sensitive attribute from a sensitive attribute estimator
 - Not embedding from encoder
 - Offer pseudo-label for covariance minimization
- Absolute covariance minimizer to minimize absolute covariance between model prediction \hat{y} and pseudo sensitive attribute \hat{s}

$$\mathcal{L}_R = |\text{cov}(\hat{s}, \hat{y})| = |\mathbb{E}[(\hat{s} - \mathbb{E}[\hat{s}])(\hat{y} - \mathbb{E}[\hat{y}])]|$$

- Absolute covariance to avoid minimizing negative covariance



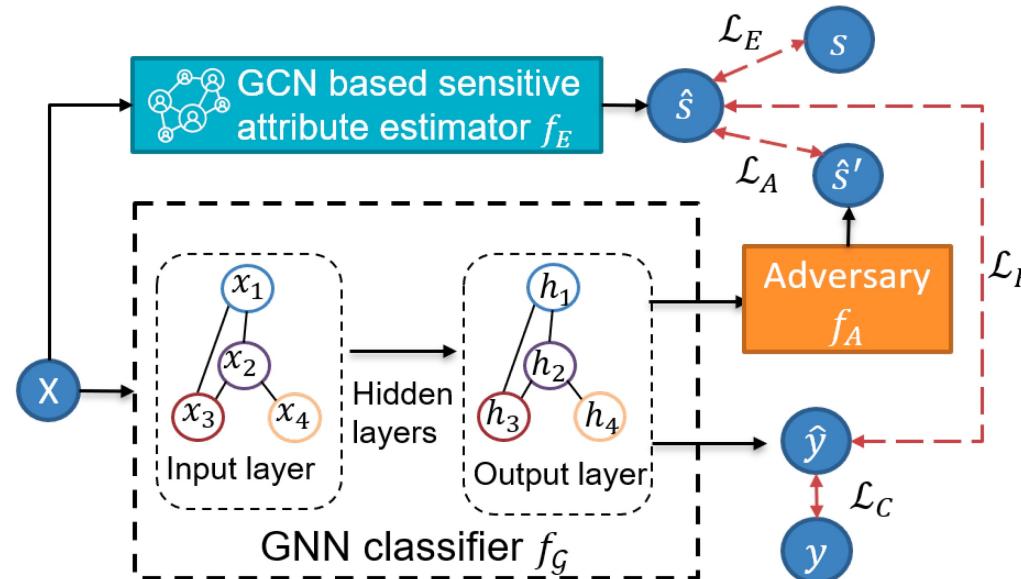
FairGNN: Overall Framework

- Overall loss function

$$\mathcal{L} = \mathcal{L}_C + \mathcal{L}_E - \alpha \mathcal{L}_A + \beta \mathcal{L}_R$$

- Intuition

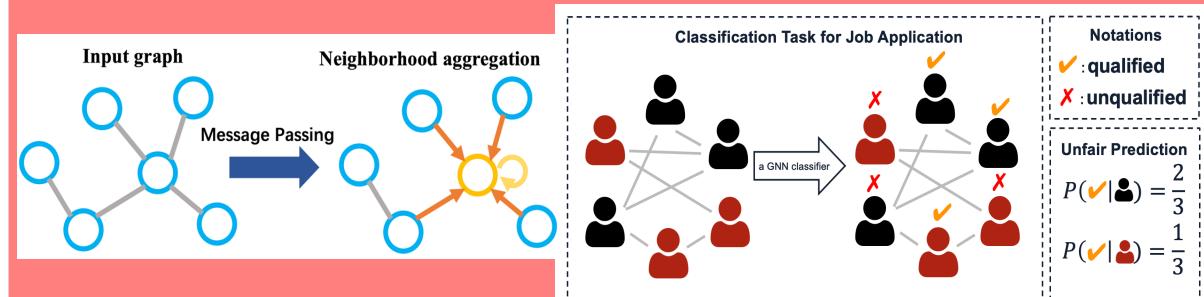
- \mathcal{L}_C : classification loss (e.g., cross entropy) for learning representative node representation
- \mathcal{L}_E : sensitive attribute estimation loss for generating accurate pseudo sensitive attribute information
- \mathcal{L}_A : adversarial loss for debiasing the learned node representation
- \mathcal{L}_R : covariance minimizer to stabilize the adversary training



BeMap: Fair Topology View Generation

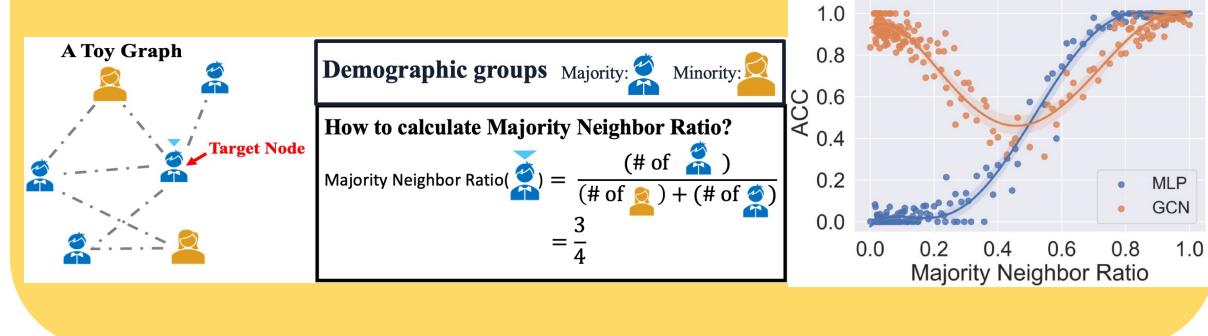
• Motivation

- Message passing could be unfair



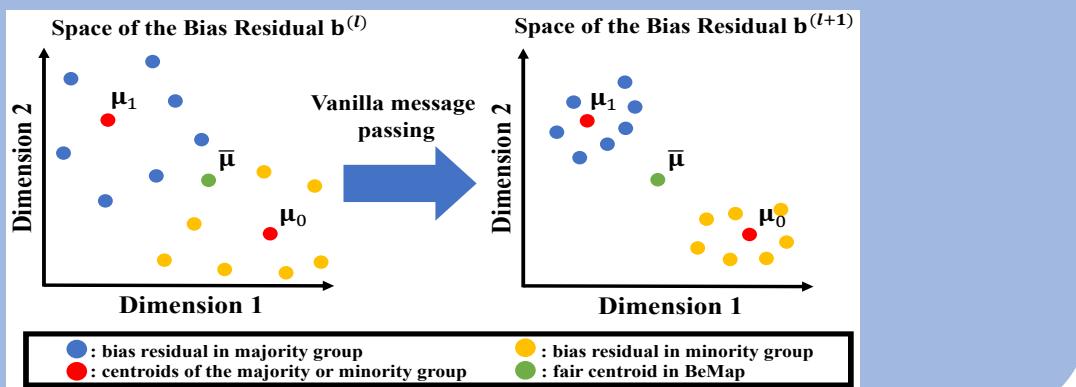
• Empirical evidence

- Predict node sensitive attribute using embeddings learned from GCN and MLP (no MP)



• Theoretical analysis

node embedding = fair embedding + bias residual



• Method: BeMap

- (In every training epoch) neighbor sampling for balanced neighborhood and MP on it
- Up to 80% bias reduction
- Comparable or even better classification accuracy
- More details in the paper

Bias and Fairness Issues

- Group Fairness on Graphs
- **Individual Fairness on Graphs**
- Degree Fairness on Graphs
- Future Directions and Q&A

Individual Fairness

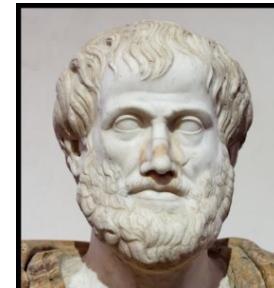
- **Definition**

- Similar individuals should have similar outcomes
- Rooted in Aristotle's conception of justice as consistency

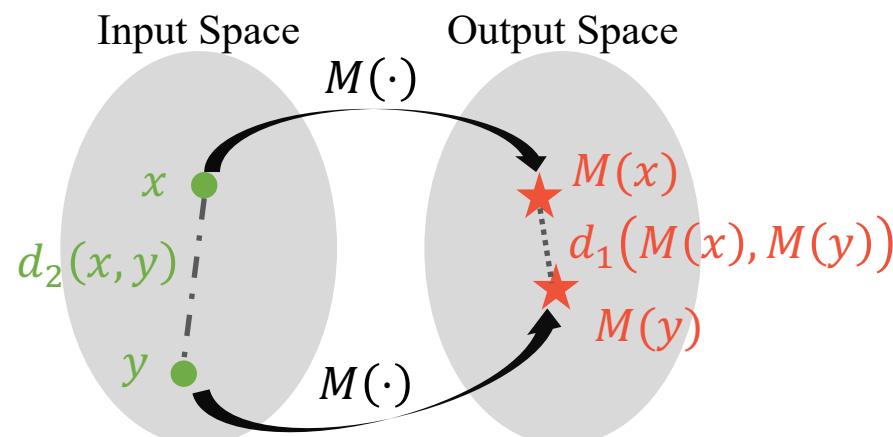
- **Formulation: Lipschitz inequality (most common)**

$$d_1(M(x), M(y)) \leq L d_2(x, y)$$

- M : a mapping from input to output
- d_1 : distance metric for output
- d_2 : distance metric for input
- L : a constant scalar



"Equality consists in the same treatment of similar persons, and no government can stand which is not founded upon justice."



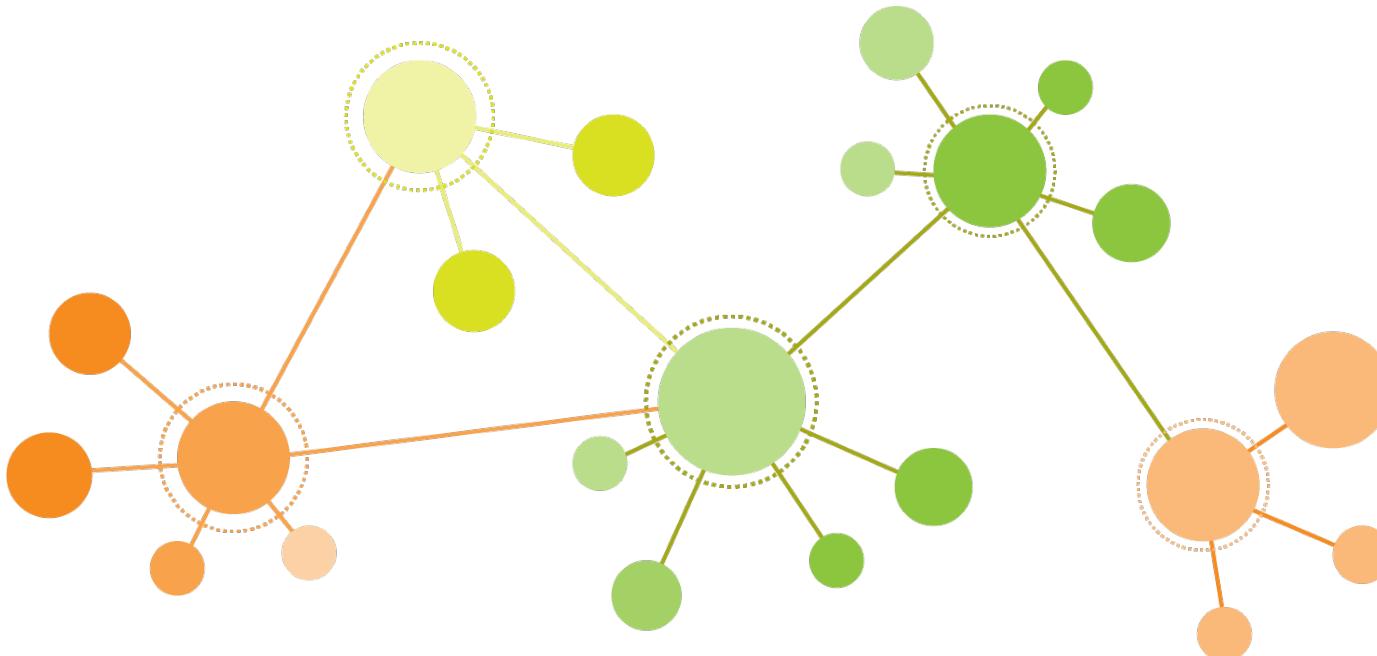
InFoRM: Individual Fairness on Graph Mining

- Research questions

RQ1. Measure: how to quantitatively measure individual bias?

RQ2. Algorithms: how to ensure individual fairness?

RQ3. Cost: what is the cost of individual fairness?



InFoRM Measure: Quantifying Individual Bias

- **Principle**

- Similar nodes → similar mining results

- **Mathematical formulation**

$$\|\mathbf{Y}[i, :] - \mathbf{Y}[j, :]\|_F^2 \leq \frac{\epsilon}{\mathbf{S}[i, j]} \quad \forall i, j = 1, \dots, n$$

Similarity between node i and node j

(1) For any node pair (i, j)
 $\|\mathbf{Y}[i, :] - \mathbf{Y}[j, :]\|_F^2 \mathbf{S}[i, j] \leq \epsilon$

(2) Sum it up for all node pairs

- If $\mathbf{S}[i, j]$ is high, $\frac{\epsilon}{\mathbf{S}[i, j]}$ is small → push $\mathbf{Y}[i, :]$ and $\mathbf{Y}[j, :]$ to be more similar
- Inequality should hold for **every** pairs of nodes i and j → too restrictive

- **Relaxed criteria**

$$\sum_{i=1}^n \sum_{j=1}^n \|\mathbf{Y}[i, :] - \mathbf{Y}[j, :]\|_F^2 \mathbf{S}[i, j] \leq m\epsilon$$

||

$$2\text{Tr}(\mathbf{Y}^T \mathbf{L}_S \mathbf{Y}) \leq \delta$$

Overall individual bias of the graph

- m : number of edges in the graph
- $\delta = m\epsilon$

Alternative Measure: Ranking-Based Individual Fairness

- Key challenge in InFoRM measure

- Lipschitz condition (used in InFoRM)

$$d_1(M(x), M(y)) \leq L d_2(x, y)$$

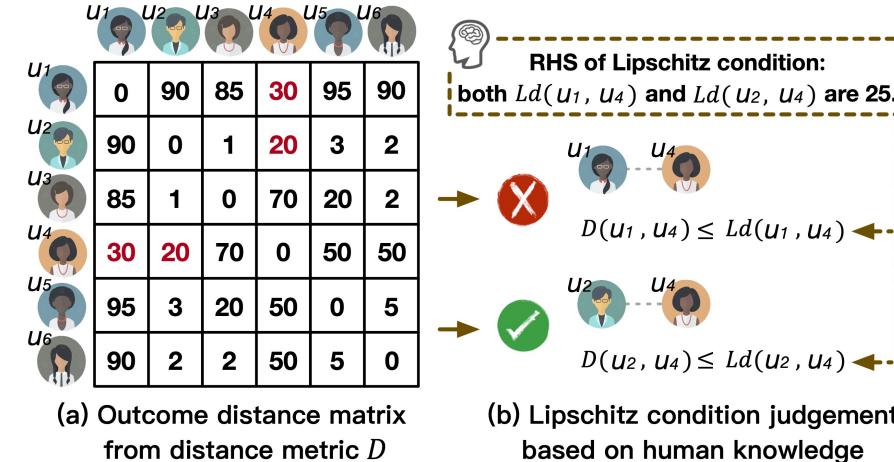
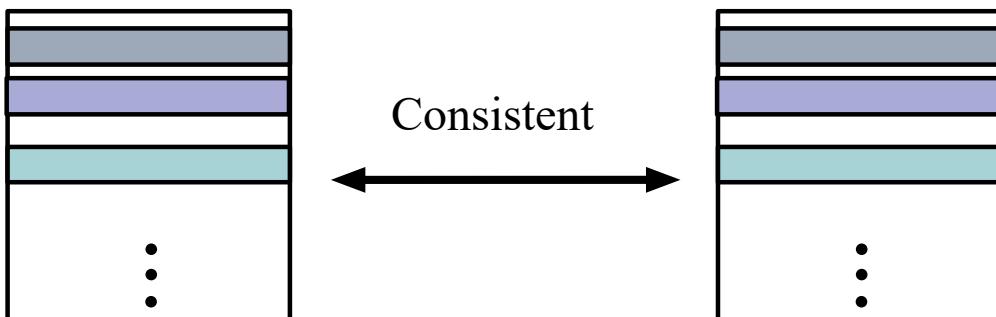
- Distance comparison fails to calibrate between different individuals

- Definition

- Given

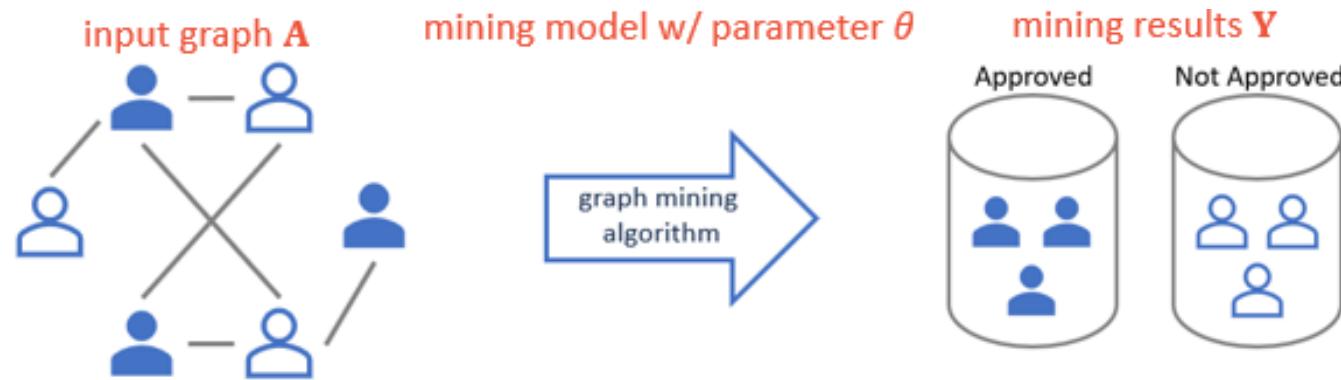
- (1) the node similarity matrix \mathbf{S}_G of the input graph G
- (2) the similarity matrix $\mathbf{S}_{\hat{\mathbf{Y}}}$ of the GNN output $\hat{\mathbf{Y}}$
- $\hat{\mathbf{Y}}$ is individually fair if, for each node i , it satisfies that

ranking list derived by $\mathbf{S}_G[i, :] =$ ranking list derived by $\mathbf{S}_{\hat{\mathbf{Y}}}[i, :]$



InFoRM Measure: Mitigating Individual Bias

- Graph mining workflow



- Debiasing methods

- Debiasing the input graph: $\min_{\mathbf{Y}} J = \frac{\|\tilde{\mathbf{A}} - \mathbf{A}\|_F^2 + \alpha \text{Tr}(\mathbf{Y}^T \mathbf{L}_S \mathbf{Y})}{\text{topology consistency}}$
s. t. $\partial_{\mathbf{Y}} l(\tilde{\mathbf{A}}, \mathbf{Y}, \theta) = 0$
- Debiasing the mining model: $\min_{\mathbf{Y}} J = \frac{l(\mathbf{A}, \mathbf{Y}, \theta) + \alpha \text{Tr}(\mathbf{Y}^T \mathbf{L}_S \mathbf{Y})}{\text{task-specific loss function}}$
- Debiasing the mining results: $\min_{\mathbf{Y}} J = \frac{\|\mathbf{Y} - \bar{\mathbf{Y}}\|_F^2 + \alpha \text{Tr}(\mathbf{Y}^T \mathbf{L}_S \mathbf{Y})}{\text{mining results consistency}}$

Individual bias
(InFoRM measure)

InFoRM Cost: Characterizing Individual Bias

- **Main focus**
 - Debiasing the mining results (model-agnostic)

- **Given**
 - A graph with n nodes and adjacency matrix \mathbf{A}
 - A node-node similarity matrix \mathbf{S}
 - Vanilla mining results $\bar{\mathbf{Y}}$
 - Debiased mining results $\mathbf{Y}^* = (\mathbf{I} + \alpha\mathbf{S})^{-1}\bar{\mathbf{Y}}$
- If $\|\mathbf{S} - \mathbf{A}\|_F = \Delta$, we have

$$\|\bar{\mathbf{Y}} - \mathbf{Y}^*\|_F \leq 2\alpha\sqrt{n} \left(\textcolor{green}{\Delta} + \textcolor{blue}{\sqrt{\text{rank}(\mathbf{A})}} \textcolor{orange}{\sigma_{\max}(\mathbf{A})} \right) \|\bar{\mathbf{Y}}\|_F$$

- **Key factors**
 - The number of nodes n (i.e., size of the input graph)
 - The difference Δ between \mathbf{A} and \mathbf{S}
 - The rank of \mathbf{A} → could be small due to (approximate) low-rank structures in real-world graphs
 - The largest singular value of \mathbf{A} → could be small if \mathbf{A} is normalized

Bias and Fairness Issues

- Group Fairness on Graphs
- Individual Fairness on Graphs
- **Degree Fairness on Graphs**
- Future Directions and Q&A

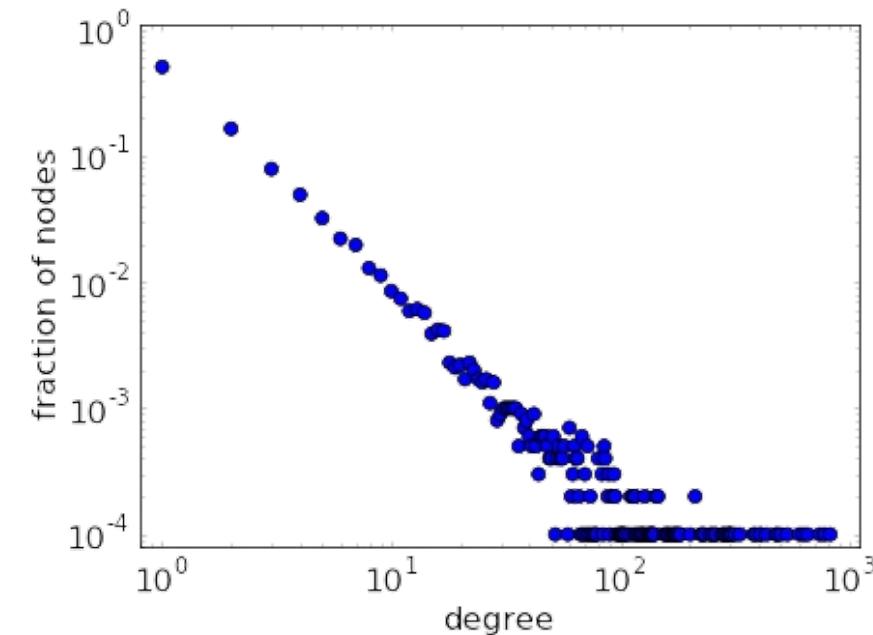
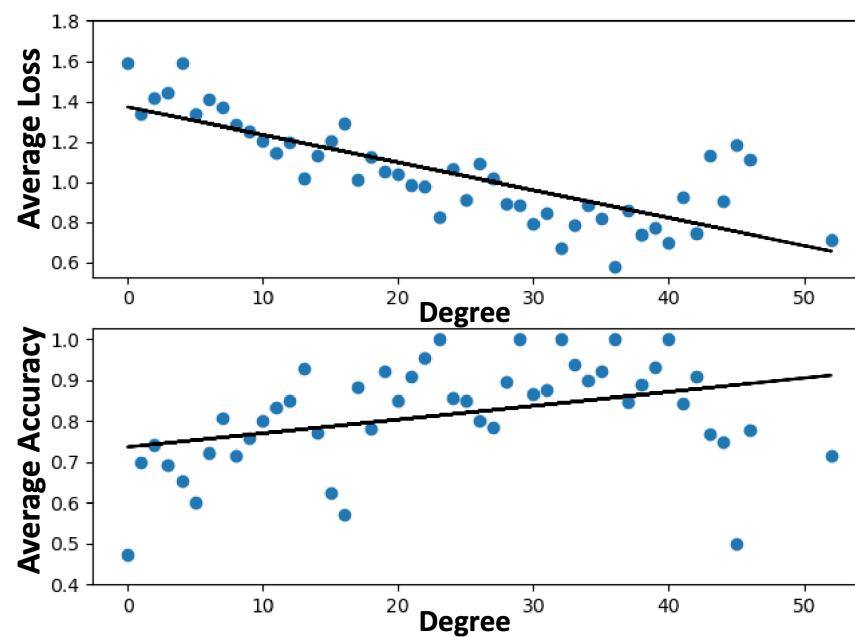
Degree Fairness: Definition and Motivation

- **Definition**

- Nodes of different degrees should have balanced utility on a graph mining task

- **Example: online advertising**

- (A small portion of) celebrities often enjoy high-quality model performance
- (A large portion of) grassroot users often suffer from bad model performance



Degree Unfairness: Pitfall of Graph Neural Networks

- Given

- (1) $\mathcal{G} = (\mathbf{A}, \mathbf{X})$
- (2) Any test node i in \mathcal{G} with label c
- (3) A graph learning model M which output (before softmax) \mathbf{Z}
- (4) Any wrong prediction $c' \neq c$

- Our results

- Misclassification rate

$$\Pr(\Pr(\hat{y} = c|i, M) > \Pr(\hat{y} = c'|M, i)) \leq \frac{1}{1 + R_{i,c'}}$$

where $R_{i,c'} = \frac{(\mathbb{E}[\mathbf{Z}[i,c'] - \mathbf{Z}[i,c]])^2}{\text{Var}[\mathbf{Z}[i,c'] - \mathbf{Z}[i,c]]}$ (reciprocal of measure of dispersion from economics)

- $R_{i,c'}$ is positively correlated with the degree of node i

- Conclusion

- high-degree nodes often have **lower misclassification rate!**

Causes #1: High-Degree Nodes with High Influence in Node Embeddings

- **Given**

- $\mathcal{V}_{\text{labeled}}$: a set of labeled nodes $\mathcal{V}_{\text{labeled}}$
- $\mathbf{W}^{(L)}$: the weight of L -th layer in an L -layer GCN
- d_i : degree of node i
- \mathbf{x}_i : input node feature of node i
- $\mathbf{h}_i^{(L)}$: output embeddings of node i learned by the L -layer GCN

- **Influence of node i on GCN training**

$$S(i) = \sum_{k \in \mathcal{V}_{\text{labeled}}} \left\| \mathbb{E} \left[\frac{\partial \mathbf{h}_i^{(L)}}{\partial \mathbf{x}_k} \right] \right\| \propto \sqrt{d_i} \|\mathbf{W}^{(L)}\| \sum_{k \in \mathcal{V}_{\text{labeled}}} \sqrt{d_k}$$

- **Remark**

- For two nodes i and j , if $d_i > d_j$, then $S(i) > S(j)$
→ Node with higher degree will have higher influence on GCN training

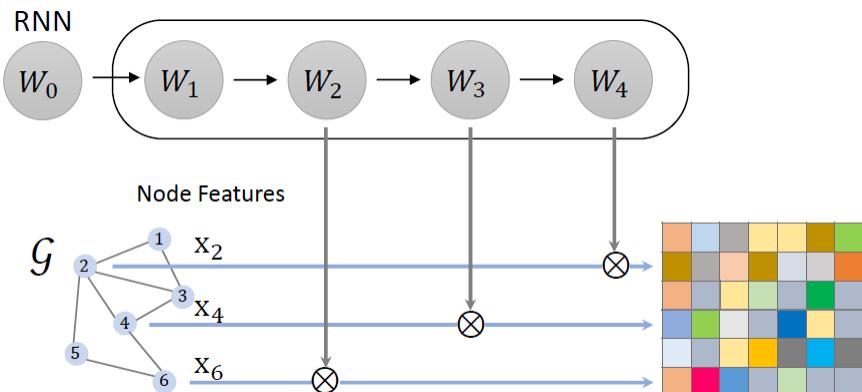
Solution #1: Degree-Specific Graph Convolution

- Key idea
 - Degree-specific weights to encode degree information
- Given
 - d_i : the degree of node i
 - $\mathbf{W}_{d_j}^{(l)}$: the degree-specific weight w.r.t. degree of node j

Degree-specific graph convolution

$$\mathbf{h}_i^{(l+1)} = \sigma \left(\sum_{j \in \mathcal{N}_i \cup \{i\}} a_{ij} \left(\mathbf{W}^{(l)} + \mathbf{W}_{d_j}^{(l)} \right) \mathbf{h}_j^{(l)} \right)$$

- DEMO-Net $\rightarrow \mathbf{W}_{d_j}^{(l)}$ is generated randomly
- SL-DSGCN $\rightarrow \mathbf{W}_{d_j}^{(l)}$ is generated using a recurrent neural network



Causes #2: High-Degree Nodes with High Influence in Gradient

- **Gradient of loss w.r.t. weight**

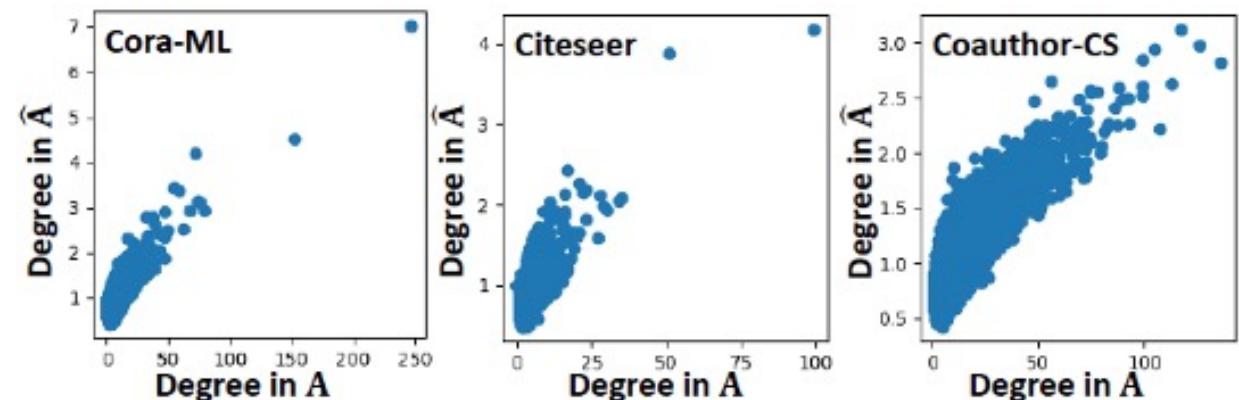
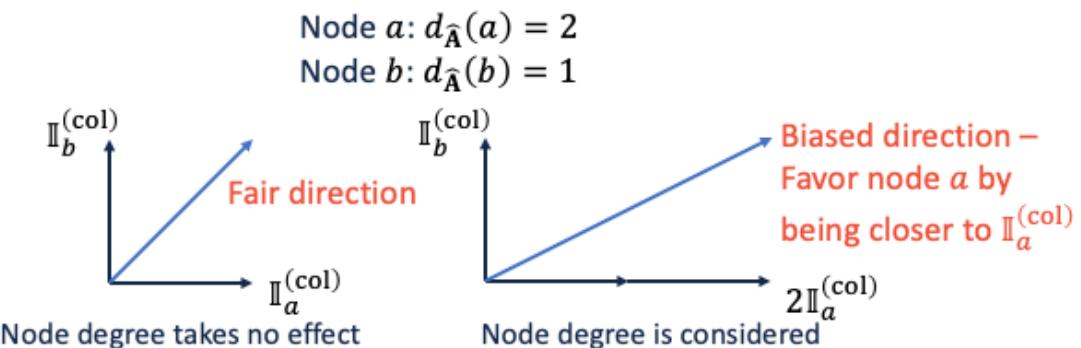
$$\frac{\partial J}{\partial \mathbf{W}^{(l)}} = \sum_{i=1}^n d_{\hat{\mathbf{A}}}(i) \mathbb{I}_i^{(\text{col})} = \sum_{j=1}^n d_{\hat{\mathbf{A}}}(j) \mathbb{I}_j^{(\text{row})}$$

Row sum in $\hat{\mathbf{A}}$ Column sum in $\hat{\mathbf{A}}$

- $\hat{\mathbf{A}} = \tilde{\mathbf{D}}^{-\frac{1}{2}}(\mathbf{A} + \mathbf{I})\tilde{\mathbf{D}}^{-\frac{1}{2}} \rightarrow$ symmetric normalization kernel
- $\mathbb{I}_i^{(\text{col})}$ and $\mathbb{I}_j^{(\text{row})} \rightarrow$ the directions for gradient descent
- $d_{\hat{\mathbf{A}}}(i)$ and $d_{\hat{\mathbf{A}}}(j) \rightarrow$ the importance of the direction
- High degree \rightarrow more focus on that direction

- **Symmetric normalization**

- Normalize the largest eigenvalue but not degree
- High degree in $\mathbf{A} \rightarrow$ high degree in $\hat{\mathbf{A}}$



Solution #2: Graph Normalization

- **Key idea**

- Mitigate impacts of node degree by normalizing it to constant (i.e., 1)
- Normalize the graph to a doubly stochastic graph

- **Sinkhorn-Knopp (SK) algorithm**

- Iteratively normalize row and columns
- **(Our result)** SK always finds the **unique** doubly stochastic form of symmetric normalization kernel

- **Fair gradient computation**

$$\left(\frac{\partial J}{\partial \mathbf{W}^{(l)}} \right)_{\text{fair}} = (\mathbf{H}^{(l-1)})^T \hat{\mathbf{A}}_{\text{DS}}^T \frac{\partial J}{\partial \mathbf{E}^{(l)}}$$

- $\hat{\mathbf{A}}_{\text{DS}}$ → doubly-stochastic normalization of $\hat{\mathbf{A}}$

- **RawlsGCN family**

- RawlsGCN-Graph: during **data pre-processing**, compute $\hat{\mathbf{A}}_{\text{DS}}$ and treat it as the input of GCN
- RawlsGCN-Grad: during **optimization (in-processing)**, treat $\hat{\mathbf{A}}_{\text{DS}}$ as a normalizer to equalize the importance of node influence

Bias and Fairness Issues

- Group Fairness on Graphs
- Individual Fairness on Graphs
- Degree Fairness on Graphs
- **Future Directions and Q&A**

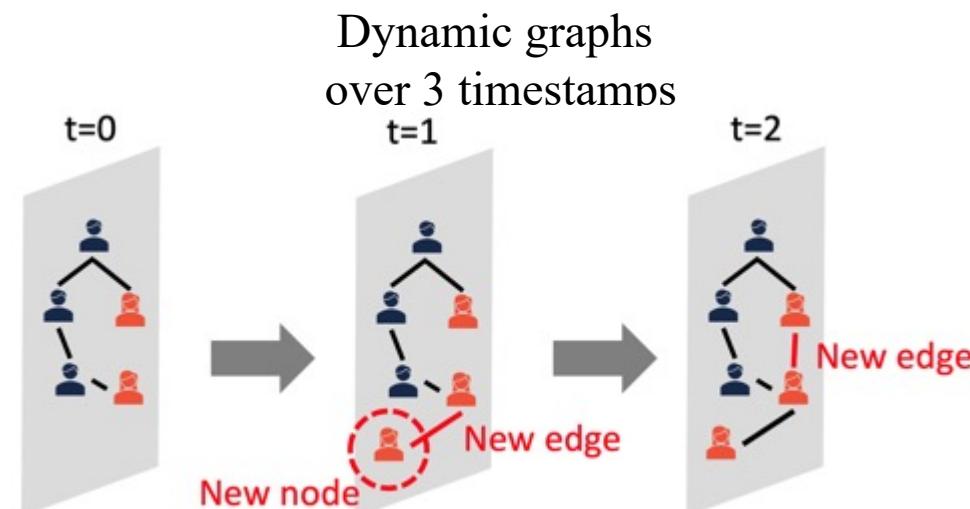
Future Direction #1: Fairness beyond Plain and Static Graphs

- **Observation**

- Real-world graphs are often dynamic and/or multi-sourced

- **Research questions**

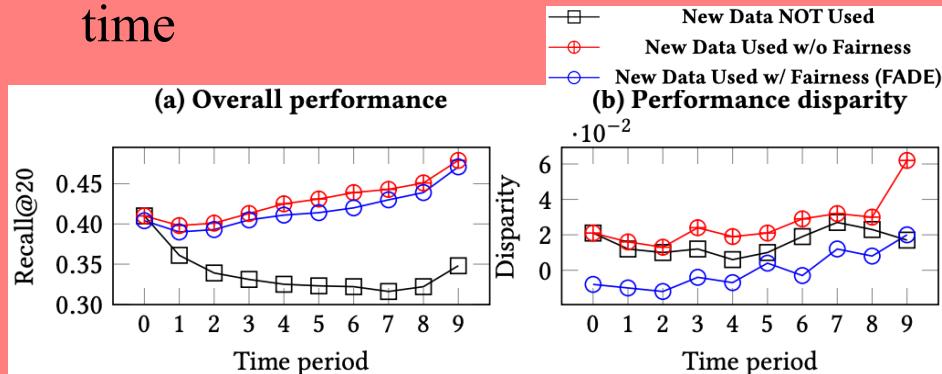
- How to ensure fairness for multiple type of nodes/edges or multi-graphs?
- How to efficiently update the fair mining results at each timestamp?
- How to characterize the impact of graph dynamics and multiple sources over the bias measure?



Preliminary Work: Dynamic Group Fairness in Recommender Systems

• Observation

- performance disparity is getting larger over time



• Theory

- Fine-tuning is better than re-training for fairness over time

Re-training

- (1) $L_{t_{\text{test}}}^{\text{rt}}$ = real loss of re-training at test time; (2) $L_{t_{\text{test}}}^*$ = optimal loss at time t_{test} ; (3) m_0 = #. edges at time 0; (4) m_t = #. edge changes at time t ; (5) $0 < \gamma < 1$

$$L_{t_{\text{test}}}^{\text{rt}} \leq L_{t_{\text{test}}}^* + 2 \frac{m_0 d_{0,t_{\text{test}}} + \sum_{t=1}^{t_{\text{test}}-1} m_t d_{1,t_{\text{test}}}}{m_0 + (t_{\text{test}} - 1)m_1} + 4 \sqrt{\frac{1}{m_0 + (t_{\text{test}} - 1)m_1} \log \frac{2}{\delta}}$$

Fine-tuning

- Similar settings as re-training but $L_{t_{\text{test}}}^{\text{ft}}$ = real loss of fine-tuning at test time

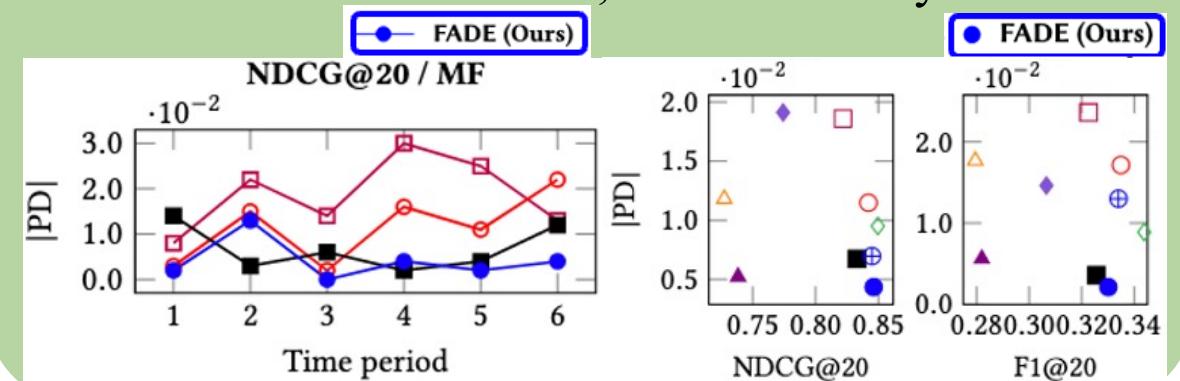
$$L_{t_{\text{test}}}^{\text{ft}} \leq L_{t_{\text{test}}}^* + 2 \frac{(1-\gamma) \left(2 \sum_{t=0}^{t_{\text{test}}-1} \gamma^{t_{\text{test}}-t-1} d_{t,t_{\text{test}}} + 4 \sqrt{\left(\frac{\gamma^{2t_{\text{test}}-2}}{m_0} + \frac{1-\gamma^{2t_{\text{test}}-2}}{(1-\gamma^2)m_1} \right) \log \frac{2}{\delta}} \right)}{1 - \gamma^{t_{\text{test}}}}$$

• Method: FADE

- Model-agnostic
- Fine-tuning with newly observed data
- Periodically re-training to keep historical information
- Linear complexity w.r.t. # new data

• Results

- Fairness over time, small accuracy decrease



Future Direction #2: Fairness on Graphs → Fairness with Graphs

- **Fairness on graphs**

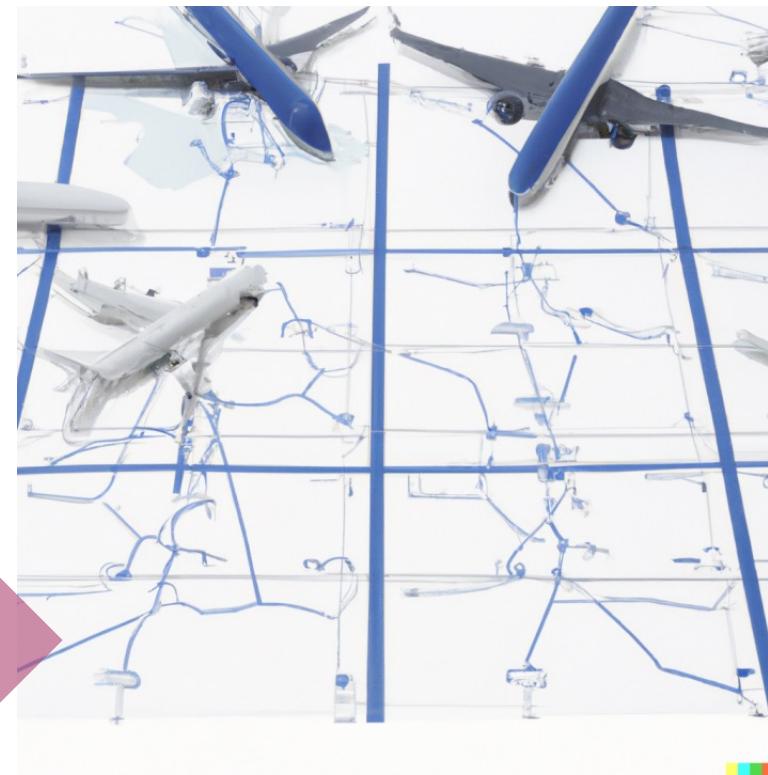
- Graph as data
- Nodes = entities
- Social networks → nodes = users
- Citation networks → nodes = papers
- Web graph → nodes = webpages

- **Fairness with graphs**

- Graph as context
- Nodes = models/datasets/modalities

- **Example: supply chain**

1. Demand + supply for medical resources
2. Models to allocate medical resources



- How can we leverage demand + supply + model collectively for fair supply chain?

Future Direction #3: Benchmark and Evaluation Metrics

- **Observation**

- No consensus on the experimental settings for fair graph learning
- Which data to compare? What sensitive attribute to consider?
- Which evaluation metrics for each type of fairness?

- **Consequences**

- Different settings for different research works
- Hardly fair comparison among fair graph learning methods
- Hardly deployable methods in real-world scenarios

- **Call for community effort**

- Evaluation benchmark for consistent experimental settings and fair comparison
- Collection of large-scale, realistic, but challenging dataset for evaluation

Outline

- Introduction and Background
- Topology Issues
- Imbalance Issues
- Short Break
- Bias and Fairness Issues
- **Limited Labeled Data Issues**
- Abnormal Graph Data Issues
- Summary

Limited Labeled Data Issues

- Graph Data Augmentations
- Self-supervised Learning on Graphs

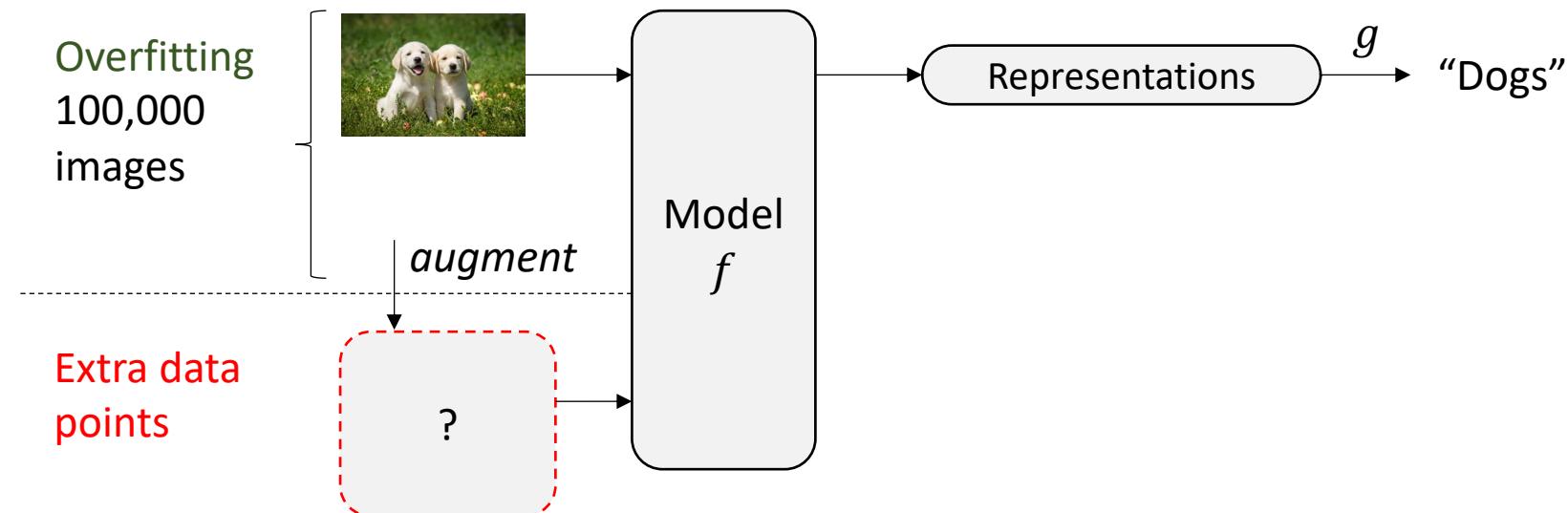
Data Augmentation

Wikipedia: Techniques used to *increase the amount of data by adding *slightly modified* copies of already existing data or *newly created* synthetic data from existing data.*

- Why data augmentation?
 - It helps reduce overfitting when training a machine learning model.
 - The acquisition of labeled graph data can be expensive.

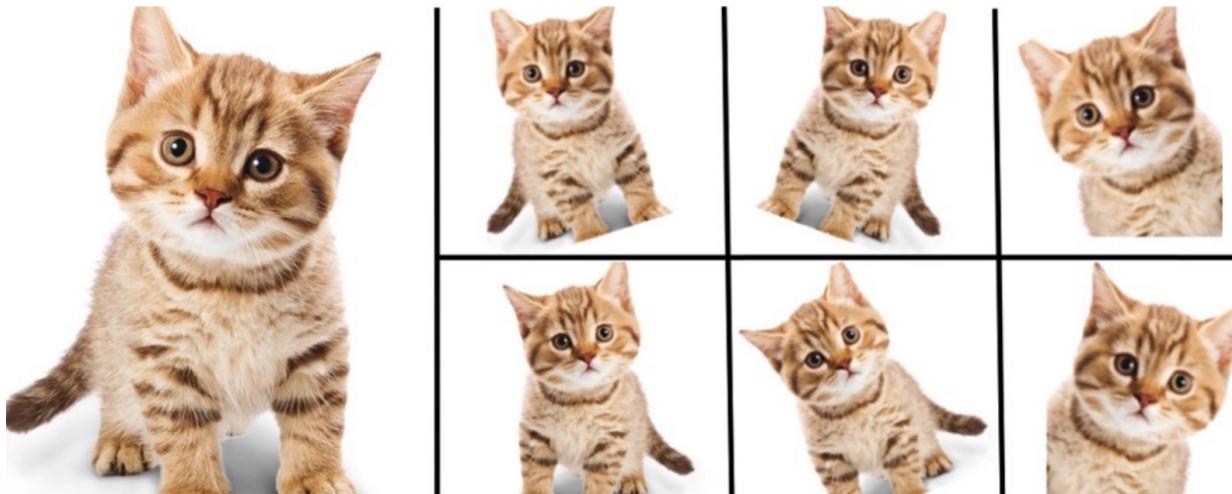
Data Augmentation

Wikipedia: Techniques used to **increase the amount of data** by adding *slightly modified* copies of already existing data or *newly created* synthetic data from existing data.



Data Augmentation

Wikipedia: Techniques used to **increase the amount of data** by adding *slightly modified* copies of already existing data or *newly created* synthetic data from existing data.



It is awesome → WordNet → It is amazing

amazing
awe-inspiring
awing
synonyms

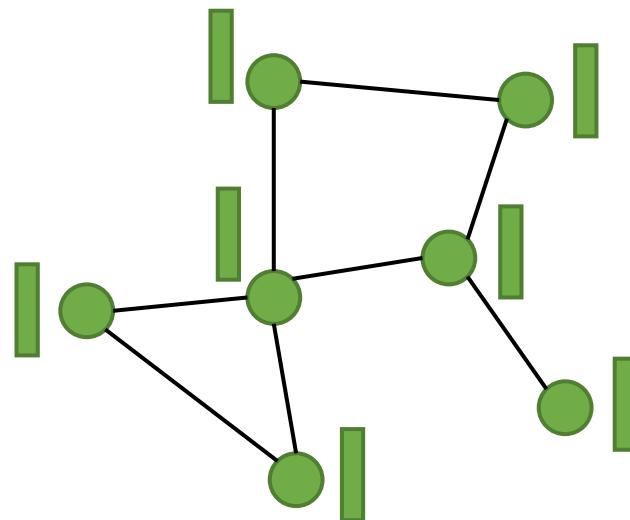
Image sources:

<https://www.kdnuggets.com/2018/05/data-augmentation-deep-learning-limited-data.html>

<https://amitness.com/2020/05/data-augmentation-for-nlp/>

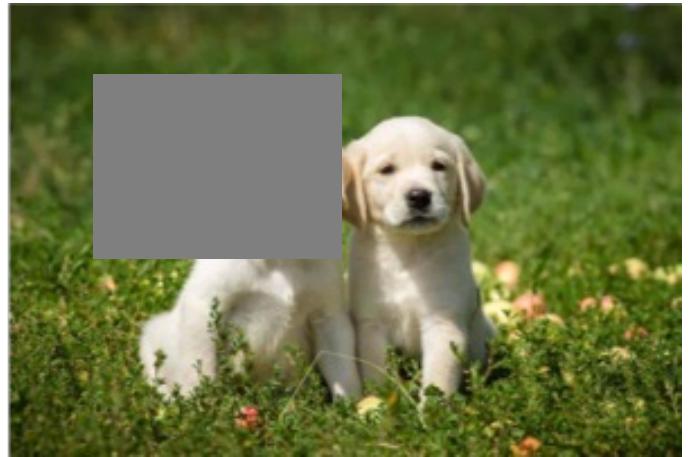
Graph Data Augmentation

- Structure Augmentation
 - Drop/add nodes/edges, etc.
- Feature Augmentation
 - Mask off features, etc.
- Label Augmentation
 - Label propagation, etc.



Graph Data Augmentation

- Rule-based augmentations
 - Designed based on heuristic rules
 - Usually efficient and scalable
 - Simple and easy to implement
 - Commonly used in self-supervised learning
- Learned augmentations
 - Involve learning during augmentation
 - Augmented data better fits GML models
 - Better performances in supervised learning



Rule-based Graph Data Augmentation Approaches

Methodology	Representative Works	Task Level			Augmented Data		
		Node	Graph	Edge	Structure	Feature	Label
Rule-based GDA	Stochastic Dropping/Masking	DropEdge [87]	✓			✓	
		DropNode [27]		✓			✓
		NodeDropping [127]		✓		✓	
		Feature Masking [100]	✓				✓
		Feature Shuffling [106]	✓				✓
		DropMessage [23]	✓	✓			✓
		Subgraph Masking [127]		✓	✓		✓
	Subgraph Cropping/Substituting	GraphCrop [111]		✓		✓	
		M-Evolve [145]		✓		✓	
		MoCL [97]		✓		✓	✓
	Virtual Node	Graphomer [125]		✓		✓	
		GNN-CM ⁺ /CM [45]			✓	✓	
	Mixup	Graph Mixup [115]	✓	✓			✓
		ifMixup [37]		✓		✓	✓
		Graph Transparent [85]		✓		✓	✓
		G-Mixup [39]		✓		✓	✓
	SMOTE	GraphSMOTE [140]	✓			✓	
		GATSMOTE [75]	✓			✓	
		GNN-CL [70]	✓			✓	
	Diffusion	GDA [60]	✓			✓	
	Counterfactual Augmentation	CFLP [141]		✓		✓	✓
	Attribute Augmentation	LA-GNN [74]	✓			✓	
		SR+DR [93]	✓			✓	
	Pseudo-labeling	Label Propagation [147]	✓				✓
		PTA [21]	✓				✓

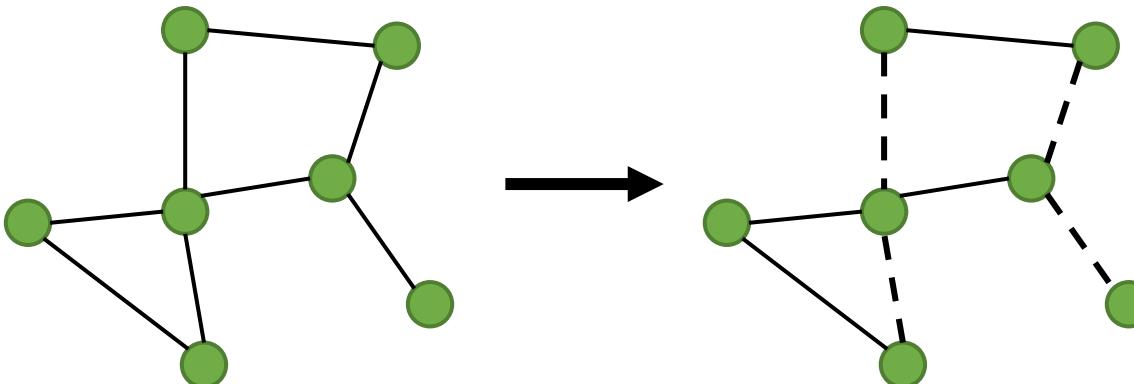
DropEdge

- Dropout on edges: randomly remove some edges at the beginning of every training epoch.

$$\tilde{\mathbf{A}} = \mathbf{M} \odot \mathbf{A}$$

$$\mathbf{M} \in \{0, 1\}^{N \times N} \text{ s.t. } M_{i,j} = \text{Bernoulli}(\varepsilon)$$

- Prevents overfitting and over-smoothing.



Other Stochastic Masking/Dropping Methods

- Node Dropping
 - Randomly removing part of the nodes.
- Feature Masking
 - Randomly mask off node features.
 - Random row-shuffling on node feature matrix \mathbf{X} .
- Subgraph Masking
 - Randomly mask off a connected subgraph.

Feng, et al. Graph Random Neural Networks for Semi-supervised Learning on Graphs. NeurIPS 2020.

You, et al. Graph Contrastive Learning with Augmentations. NeurIPS 2020.

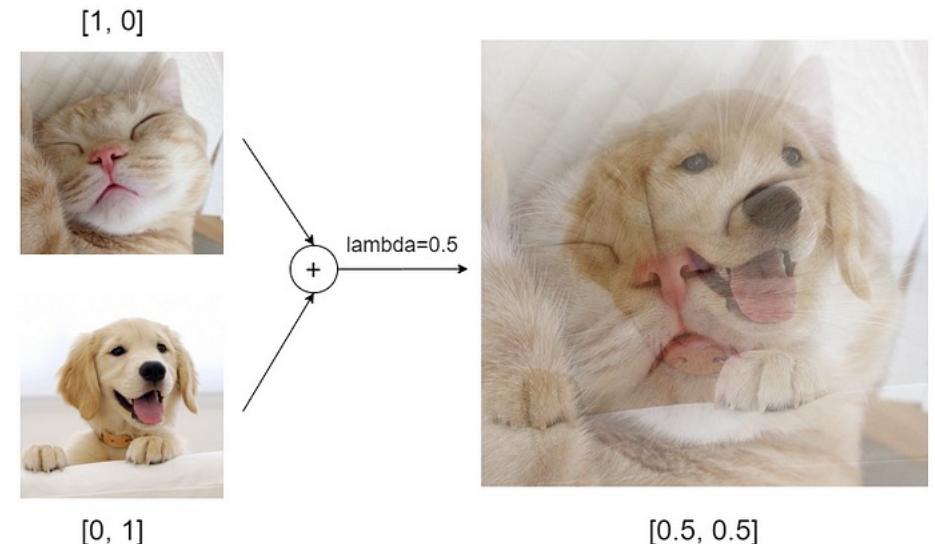
Thakoor, et al. Large-scale Representation Learning on Graphs via Bootstrapping. ICLR 2022.

Velickovic, et al. Deep Graph Infomax. ICLR 2019.

Mixup

- Mixup: generates a weighted combination of random pairs from the training data.

$$\begin{aligned}\tilde{\mathbf{x}} &= \lambda \mathbf{x}_i + (1 - \lambda) \mathbf{x}_j, \\ \tilde{\mathbf{y}} &= \lambda \mathbf{y}_i + (1 - \lambda) \mathbf{y}_j.\end{aligned}$$



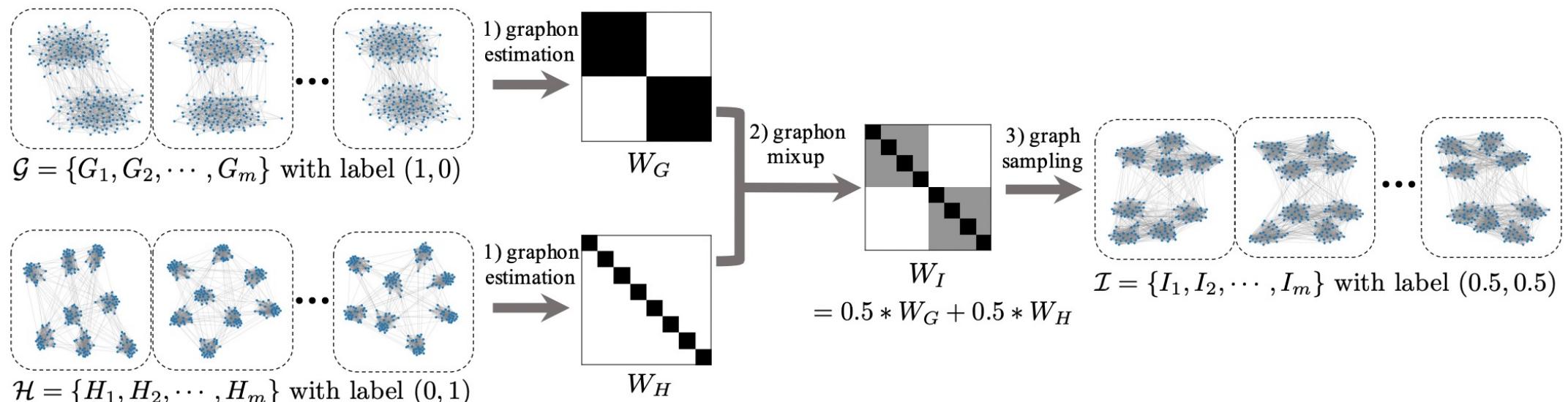
- Manifold Mixup: interpolating hidden states.

Zhang, et al. Mixup: Beyond Empirical Risk Minimization. ICLR 2018.

Verma, et al. Manifold Mixup: Better Representations by Interpolating Hidden States. ICML 2019.

Image source: <https://medium.com/@wolframalphav1.0/easy-way-to-improve-image-classifier-performance-part-1-mixup-augmentation-with-codes-33288db92de5>

G-Mixup



1. Graphon estimation:
2. Graphon Mixup:
3. Graph Generation:
4. Label Mixup:

$$\mathcal{G} \rightarrow W_{\mathcal{G}}, \mathcal{H} \rightarrow W_{\mathcal{H}}$$

$$W_{\mathcal{I}} = \lambda W_{\mathcal{G}} + (1 - \lambda) W_{\mathcal{H}}$$

$$\{I_1, I_2, \dots, I_m\} \stackrel{\text{i.i.d}}{\sim} \mathbb{G}(K, W_{\mathcal{I}})$$

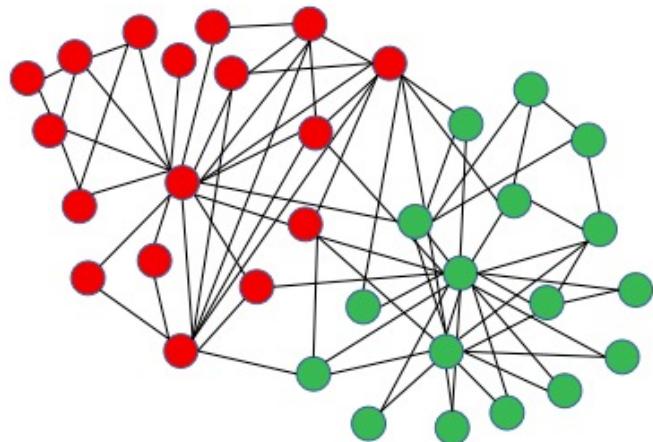
$$\mathbf{y}_{\mathcal{I}} = \lambda \mathbf{y}_{\mathcal{G}} + (1 - \lambda) \mathbf{y}_{\mathcal{H}}$$

Learned Graph Data Augmentation Approaches

Learned GDA	Graph Structure Learning	GAug [140] GLCN [47] LDS [28] ProGNN [50] Eland [141]	✓ ✓ ✓ ✓ ✓		✓ ✓ ✓ ✓ ✓
	Graph Adversarial Training	RobustTraining [125] AdvT [18] FLAG [63] GraphVAT [25]	✓ ✓ ✓ ✓	✓ ✓ ✓	✓ ✓ ✓
	Graph Rationalization	GREA [71] AdvCA [97]		✓ ✓	✓ ✓
	Automated Augmentation	AutoGDA [144] GraphAug [79] JOAO [130] MolCLE [116]	✓ ✓ ✓		✓ ✓ ✓ ✓

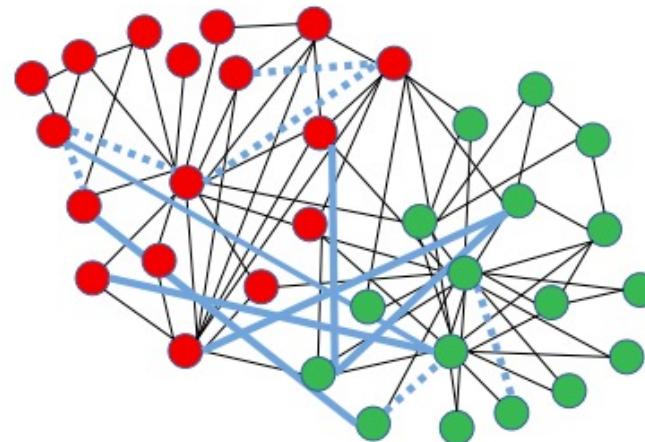
Limitations of Rule-based Approaches

Do not leverage task information and could hurt the downstream performance



(a) Original graph.

F1 Score: 92.4



(b) Random mod.

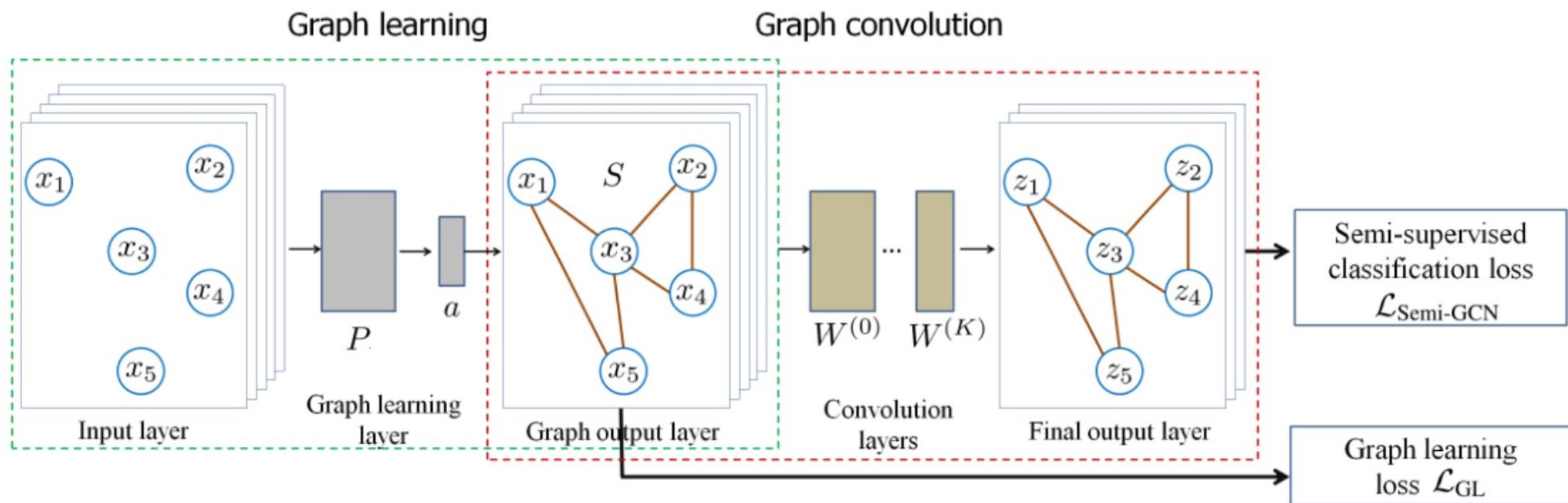
F1 Score: 91.0

Learned Graph Data Augmentation Approaches

- Graph Structure Learning
 - Augment data with good graph structures
- Adversarial Training
 - Augment data with adversarial examples
- Rationalization
 - Augment data by changing graph environment
- Automated Augmentation
 - Automatically combine different augmentations

Graph Structure Learning

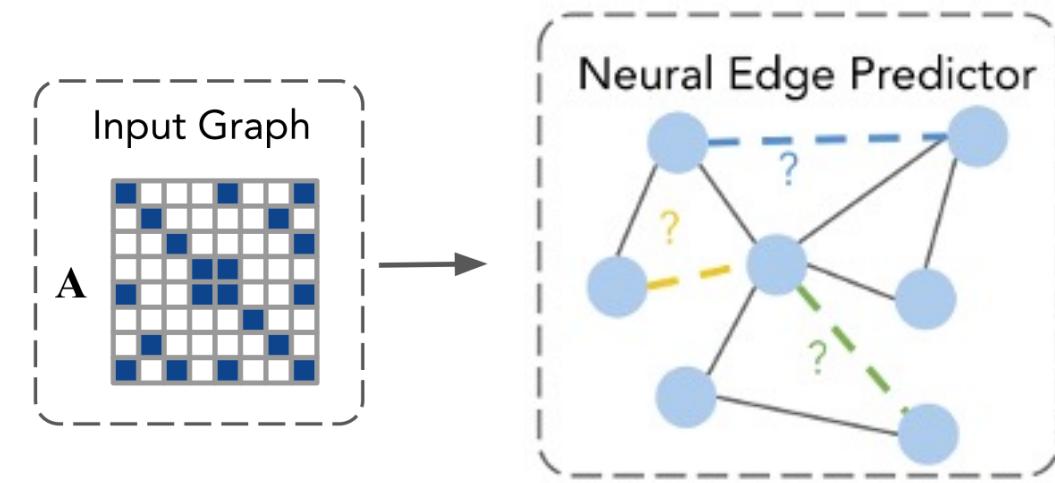
Graph Learning + Graph Convolution



GAug: Neural Edge Predictor

What are better graph structures?

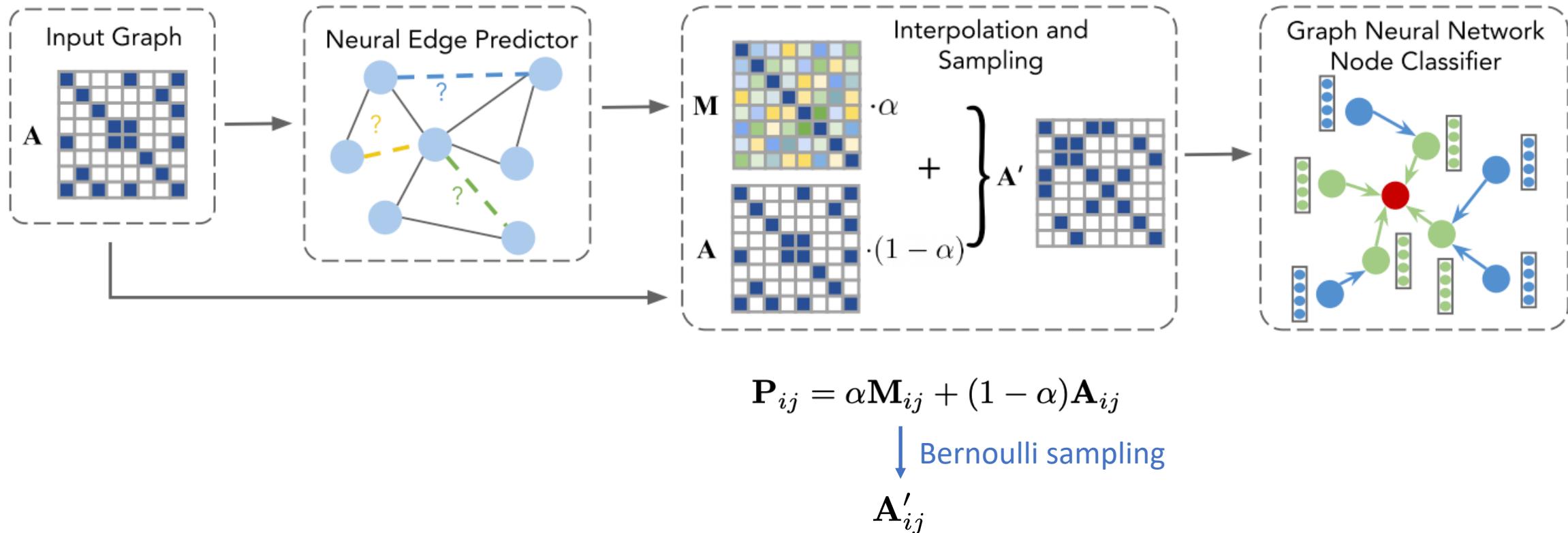
- “Noisy” edges should be removed
Inter-class edges
- “Missing” edges should be added
Intra-class edges



$$\mathbf{M} = \sigma(\mathbf{Z}\mathbf{Z}^T), \text{ where } \mathbf{Z} = f_{GCL}^{(1)}\left(\mathbf{A}, f_{GCL}^{(0)}(\mathbf{A}, \mathbf{X})\right)$$

M models node similarities

GAug: Interpolation and Sampling



$$\mathbf{P}_{ij} = \alpha \mathbf{M}_{ij} + (1 - \alpha) \mathbf{A}_{ij}$$

Bernoulli sampling
 \downarrow
 \mathbf{A}'_{ij}

Graph Self-supervised Learning

- Graph Self-Supervised Learning aims to learn generalizable node/edge/graph representations without using any human-annotated labels
 - Graph Generative Modeling
 - Learn generalizable representations by reconstructing the node features or/and graph structure

Graph Self-supervised Learning

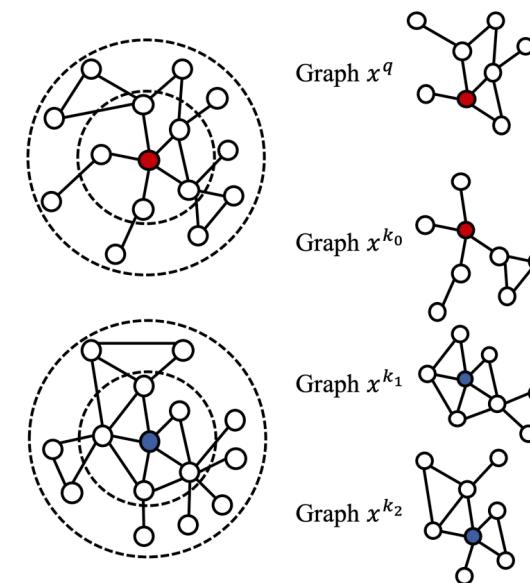
- Graph Self-Supervised Learning aims to learn generalizable node/edge/graph representations **without** using any human-annotated labels

- Graph Generative Modeling

- Learn generalizable representations by **reconstructing** the node features or/and graph structure

- Graph Contrastive Learning (GCL)

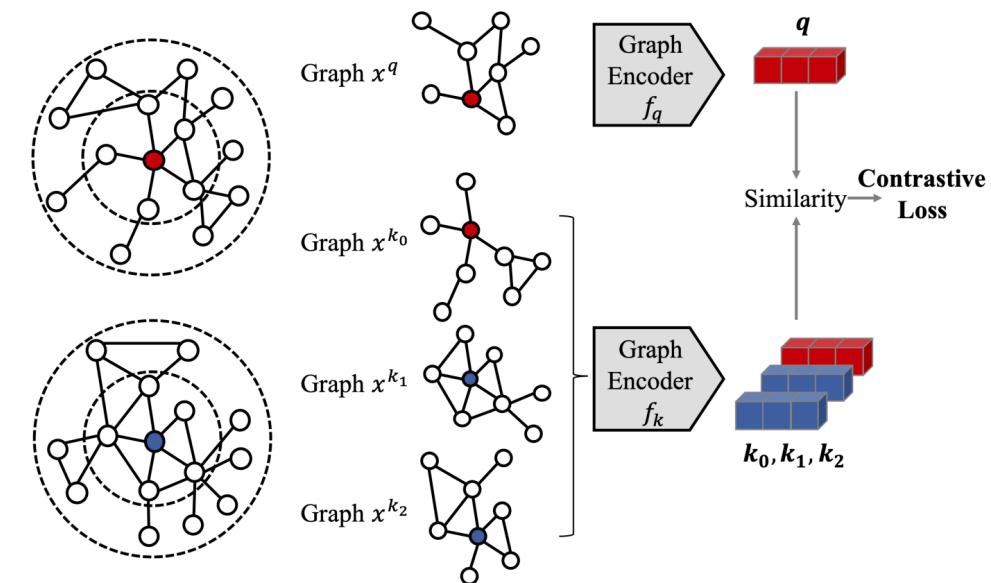
- Create different views from the unlabeled input graph via data augmentation



Graph Self-supervised Learning

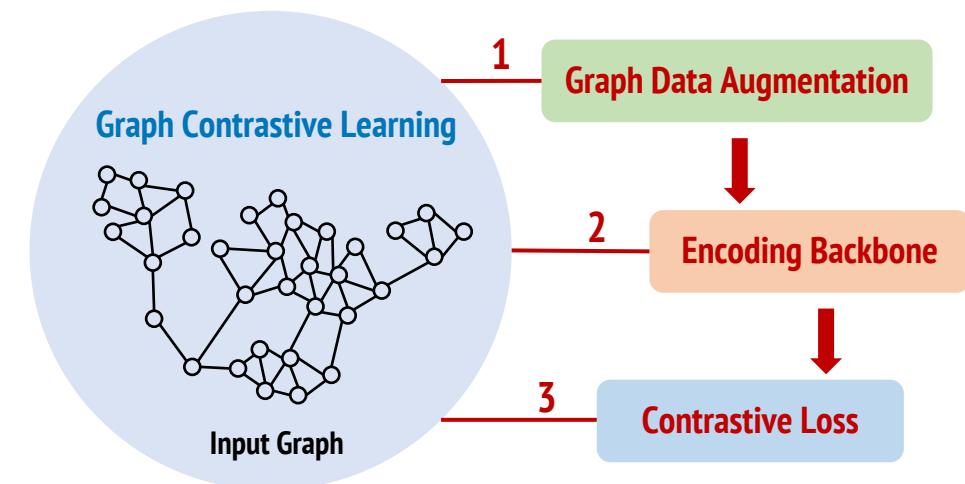
- Graph Self-Supervised Learning aims to learn generalizable node/edge/graph representations **without** using any human-annotated labels

- Graph Generative Modeling
 - Learn generalizable representations by **reconstructing** the node features or/and graph structure
- Graph Contrastive Learning (GCL)
 - Create different views from the unlabeled input graph via data augmentation
 - Maximize the agreement between representations of different augmented views of the same instance



Typical Unsupervised Graph Contrastive Learning

- **Graph Data Augmentation**
 - Create different views of each instance (e.g., node, subgraph)
 - Arbitrary graph data augmentation (e.g., edge dropping, feature masking)
- **Encoding Backbone**
 - Encode different augmented views
 - Shallow GNNs (e.g., 2-layer GCN)
- **Contrastive Loss**
 - Maximize the agreement between representations learned from different augmented views
 - Instance-level contrastive learning



Outline

- Introduction and Background
- Topology Issues
- Imbalance Issues
- Short Break
- Bias Issue
- Limited Labeled Data Issues
- **Abnormal Graph Data Issues**
- Summary

Abnormal Graph Data Issues

- Missing Data
- Adversarial Attacked Data

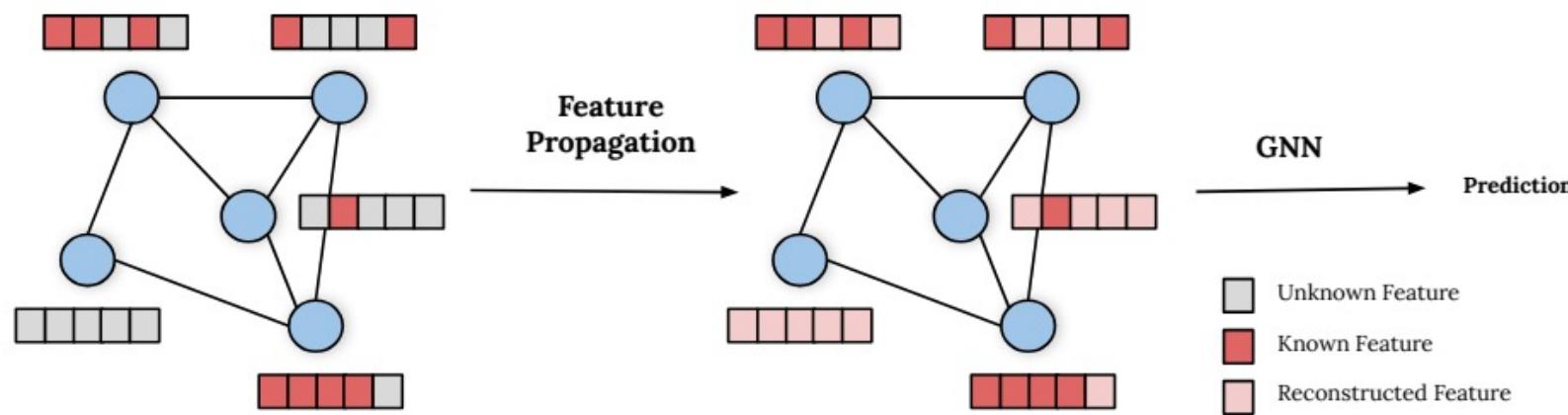
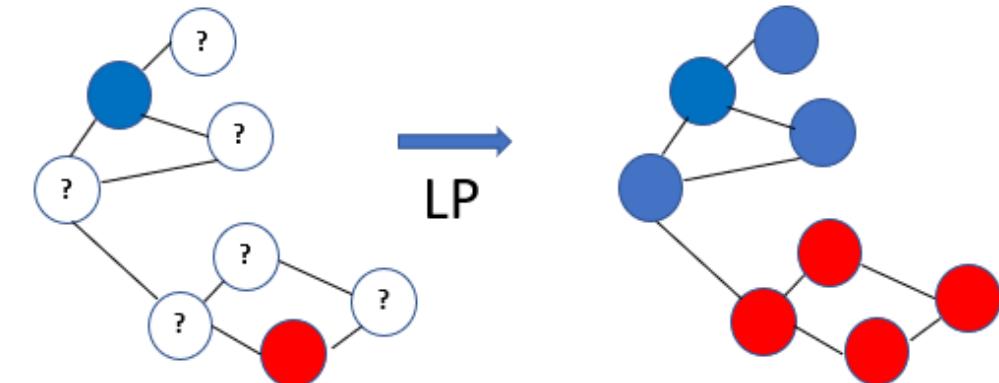
Missing Data

There are various solutions to deal with **missing labels**:

- Label propagation (LP)
- Self-supervised learning
- Unsupervised learning
- ...

What if we have **missing features**?

- Feature propagation



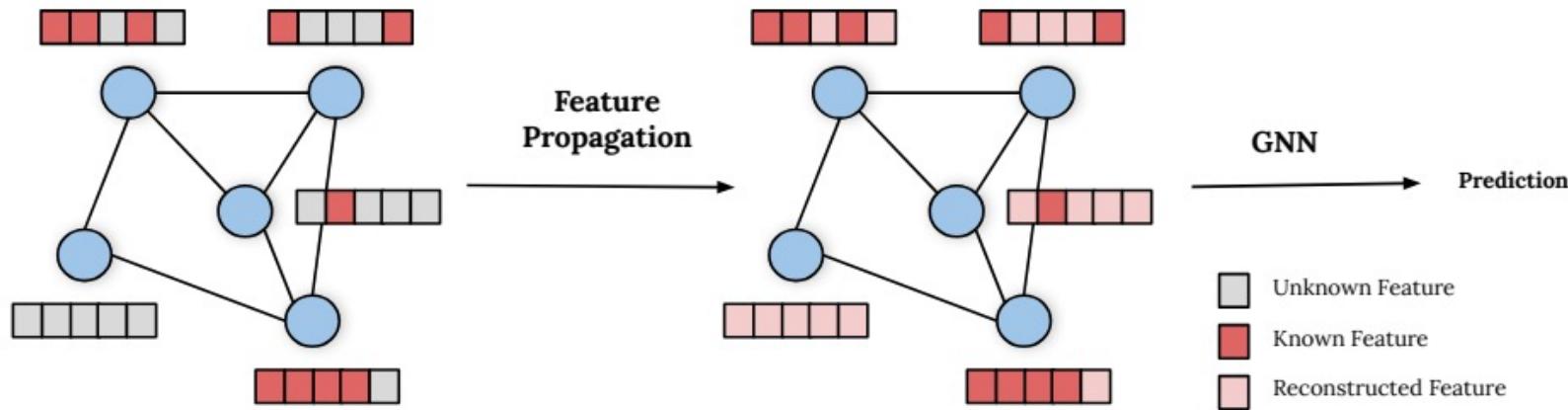
Missing Data

What if we have **missing features**?

- Feature propagation

Algorithm 1 Feature Propagation

```
1: Input: feature vector  $\mathbf{x}$ , diffusion matrix  $\tilde{\mathbf{A}}$ 
2:  $\mathbf{y} \leftarrow \mathbf{x}$ 
3: while  $\mathbf{x}$  has not converged do
4:    $\mathbf{x} \leftarrow \tilde{\mathbf{A}}\mathbf{x}$             $\triangleright$  Propagate features
5:    $\mathbf{x}_k \leftarrow \mathbf{y}_k$           $\triangleright$  Reset known features
6: end while
```



Missing Data

Comparison of Feature Propagation to Label Propagation

Feature Propagation:

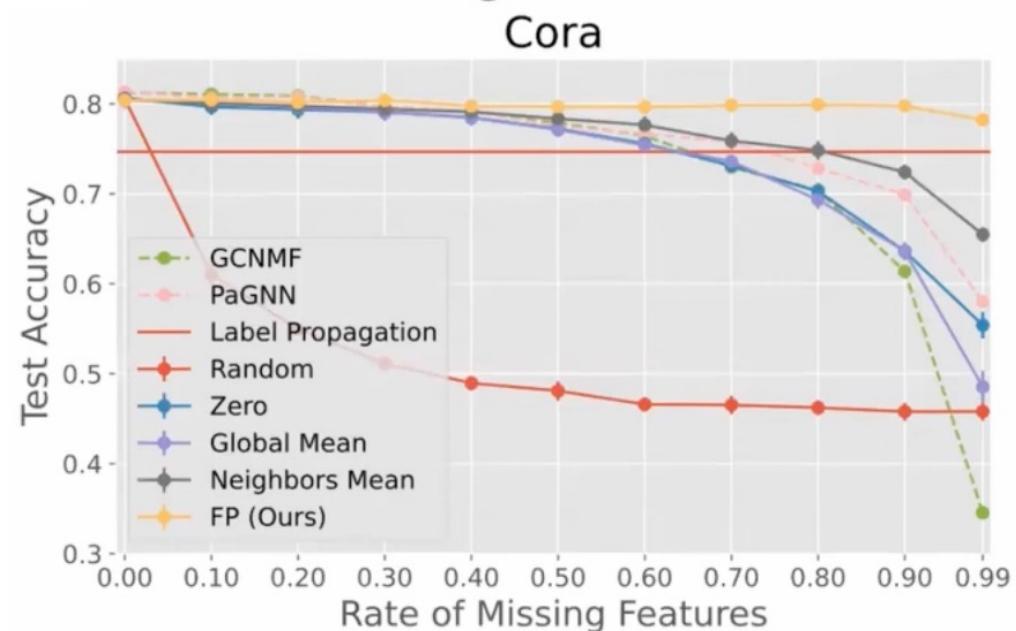
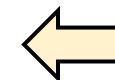
- Propagates features (continuous)
- Prediction is made by a GNN on top of the propagated features
- Uses features, and a low % of them being present is enough for good performance

Label Propagation:

- Propagates class labels (discrete)
- Prediction is obtained directly from propagating class labels
- Feature-agnostic

Experiment Results

Across different levels of missing features,
Feature Propagation achieves the best performance



Missing Data

Beyond missing features on graphs, can we solve the general missing data problem?

Data Matrix with Missing Values					Labels
	F_1	F_2	F_3	F_4	Y
O_1	0.3	0.5	NA	0.1	y_1
O_2	NA	NA	0.6	0.2	y_2
O_3	0.3	NA	NA	0.5	?

Two ways of approaching missing data problems:

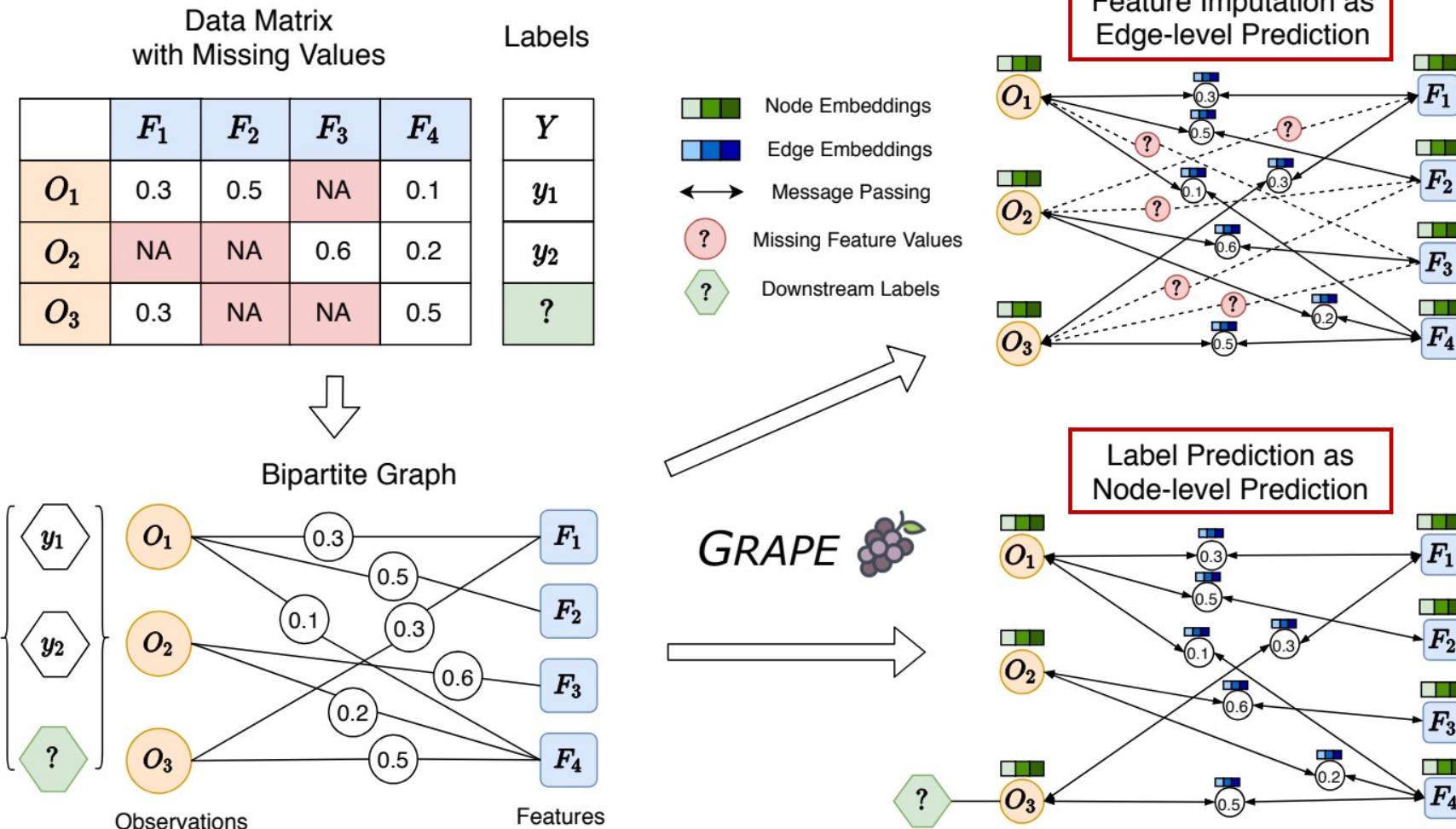
- **Feature imputation:** missing feature values are estimated based on observed values
- **Label prediction:** downstream labels are learned directly from incomplete data

Issues:

- Existing methods fail to make full use of feature values from other observations
- Existing methods tend to make biased assumptions about the missing values by initializing them with special default values

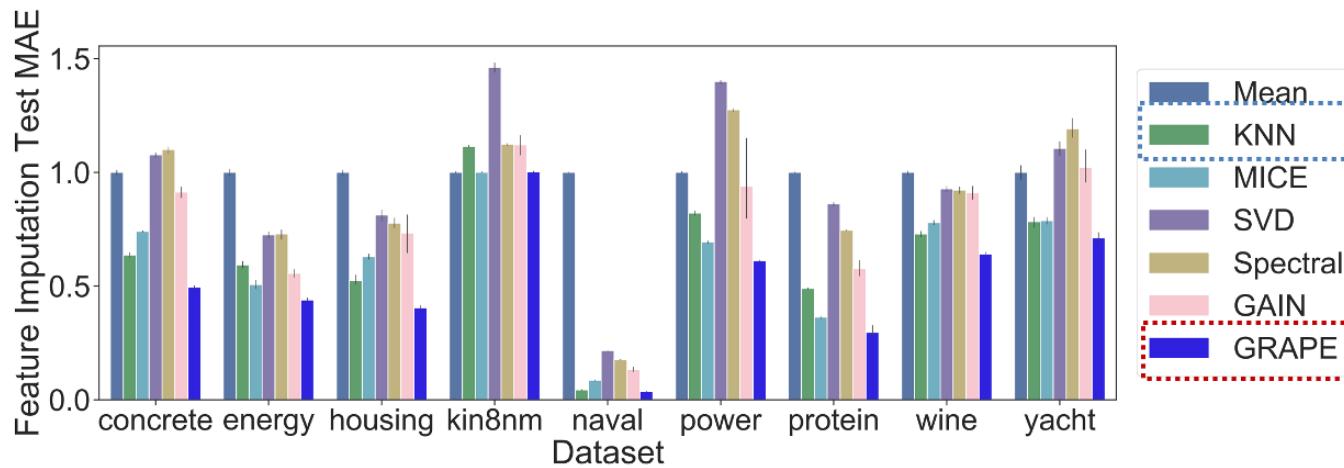
Missing Data

GRAPE: reformulate the tasks as graph tasks

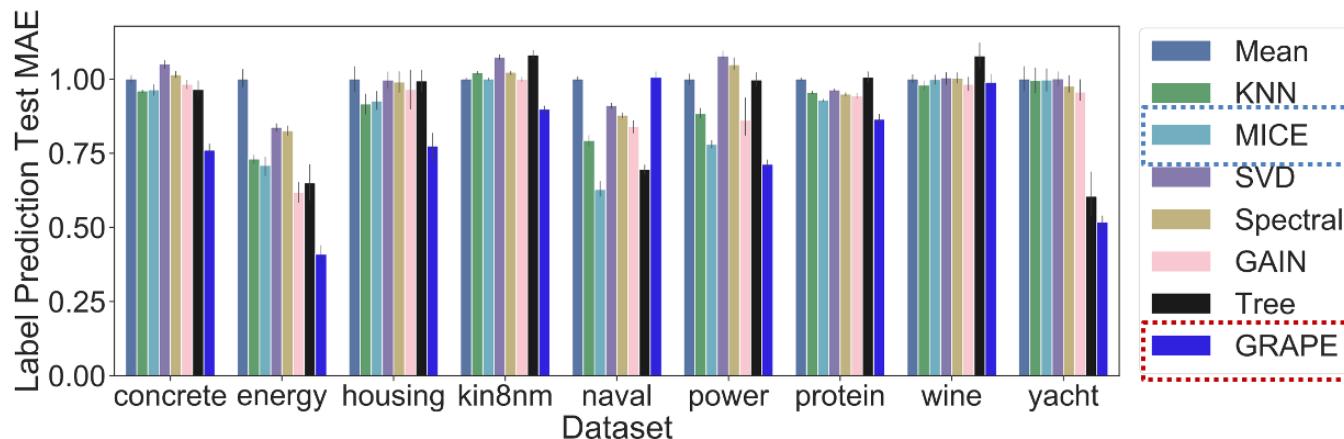


Missing Data

GRAPE yields 20% lower mean absolute error for feature imputation,
and 10% lower MAE for label prediction



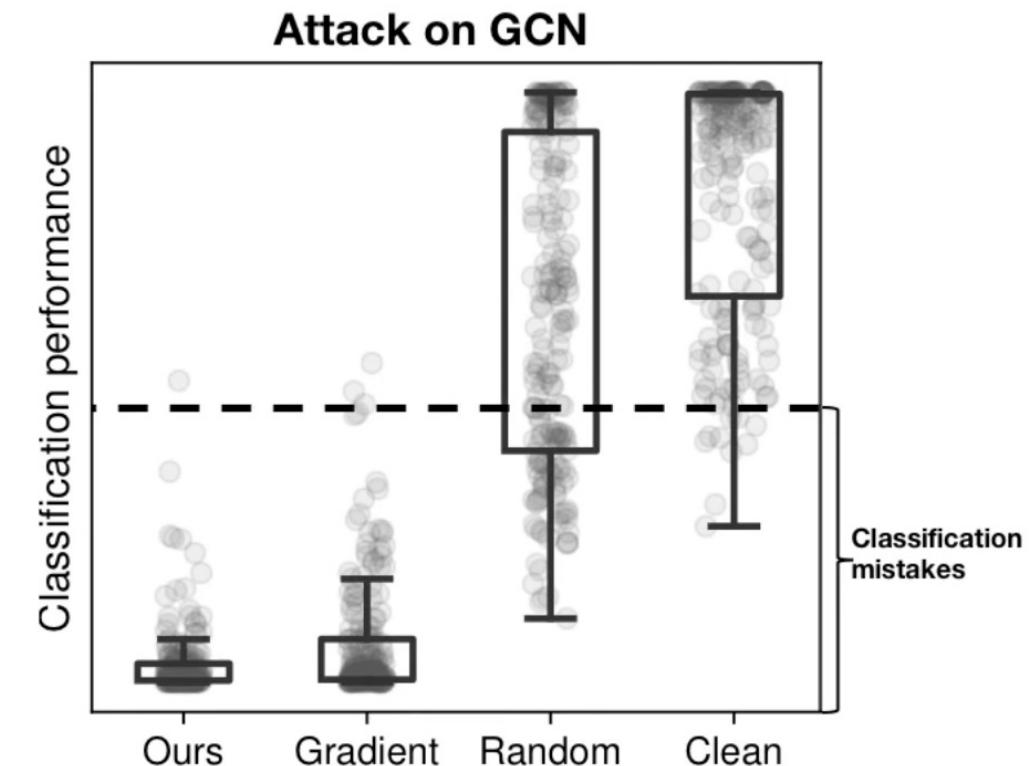
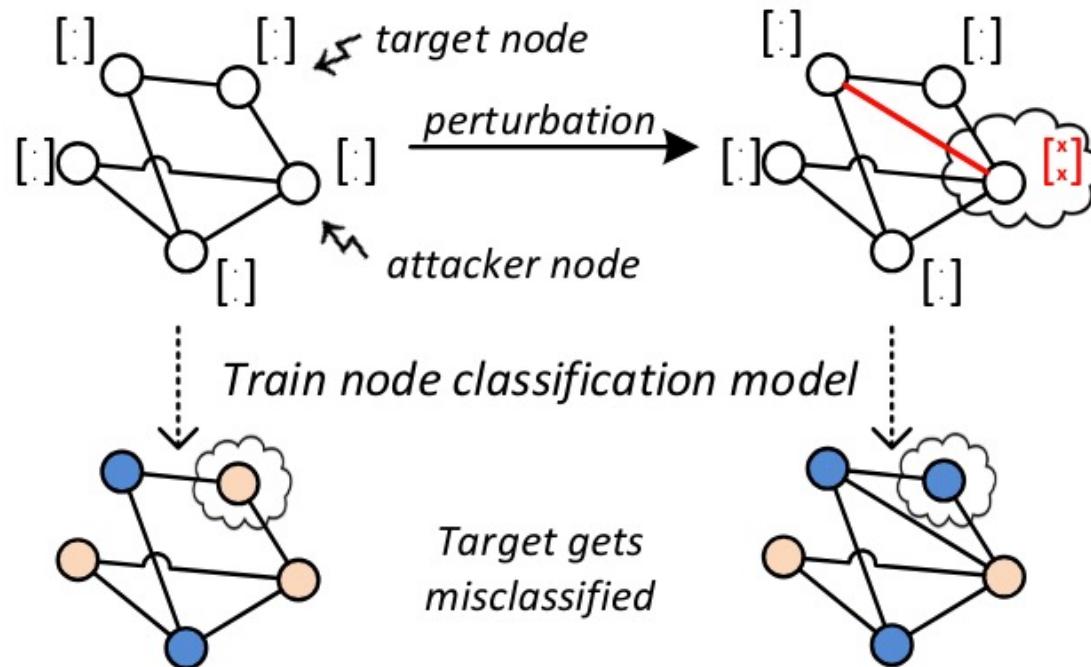
Feature
imputation:
**20% lower
MAE than best
baseline (KNN)**



Label
prediction:
**10% lower
MAE than best
baseline (MICE)**

Adversarial Attacked Data

Observation: Small perturbations of the graph structure and node features lead to misclassification of the target



Adversarial Attacked Data

Can we leverage small data perturbations to **improve performance?**

Yes, adversarial training

Adversarial training is the process of crafting adversarial data points, and then injecting them into training data

$$\min_{\theta} \quad E_{(x,y) \sim \mathcal{D}} \left[\max_{\|\delta\|_p \leq \epsilon} L(f_{\theta}(x + \delta), y) \right]$$

↓

Find the optimal perturbation sample to achieve maximum loss

Find the optimal model parameters to resist the attack of perturbation sample

D: distribution

$\|\cdot\|_p$: l_p -norm distance metric

ϵ : perturbation budget

Adversarial Attacked Data

Can we leverage small data perturbations to **improve performance?**
Yes, adversarial training

Node Classification

Backbone	ogbn-products			ogbn-proteins			ogbn-arxiv		
	Test Acc	-	-	Test ROC-AUC	-	-	Test Acc	-	-
GCN	-	-	-	72.51 ±0.35	-	-	71.74±0.29	-	-
+FLAG	-	-	-	71.71±0.50	-	-	72.04 ±0.20	-	-
GraphSAGE	78.70±0.36	-	-	77.68 ±0.20	-	-	71.49±0.27	-	-
+FLAG	79.36 ±0.57	-	-	76.57±0.75	-	-	72.19 ±0.21	-	-
GAT	79.45±0.59	-	-	-	-	-	73.65±0.11	-	-
+FLAG	81.76 ±0.45	-	-	-	-	-	73.71 ±0.13	-	-
DeeperGCN	80.98±0.20	-	-	85.80±0.17	-	-	71.92±0.16	-	-
+FLAG	81.93 ±0.31	-	-	85.96 ±0.27	-	-	72.14 ±0.19	-	-

Adversarial Attacked Data

Can we leverage small data perturbations to **improve robustness?**

Yes, adversarial training

A **use case**: training an MLP on graphs

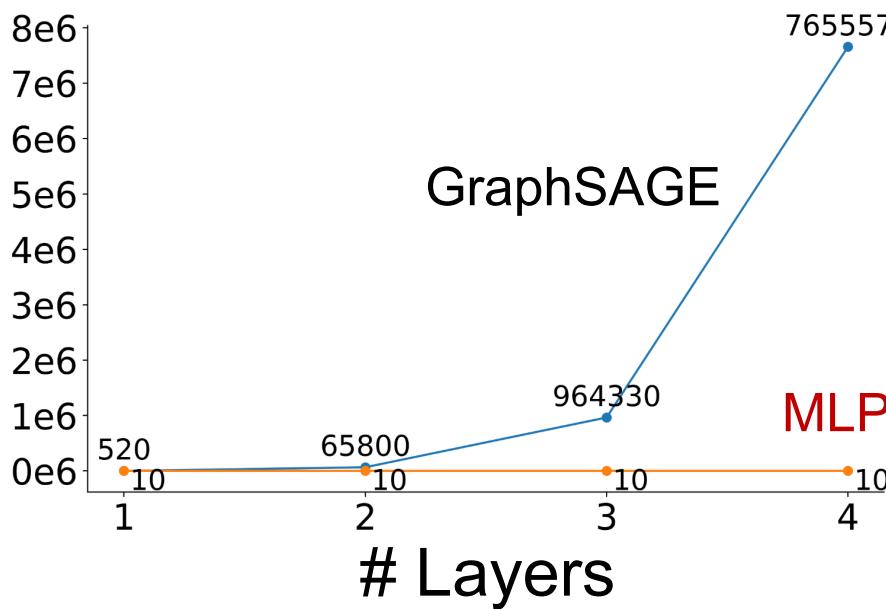
Reason: to avoid the computation-intensive message passing mechanism

GNN

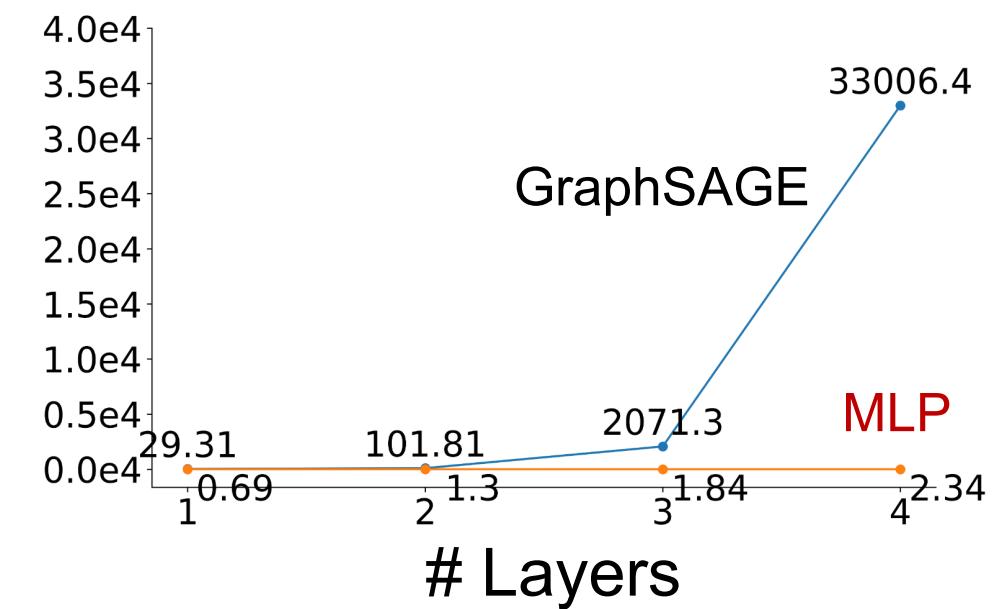


MLP

Nodes Fetched



Inference Time (ms)

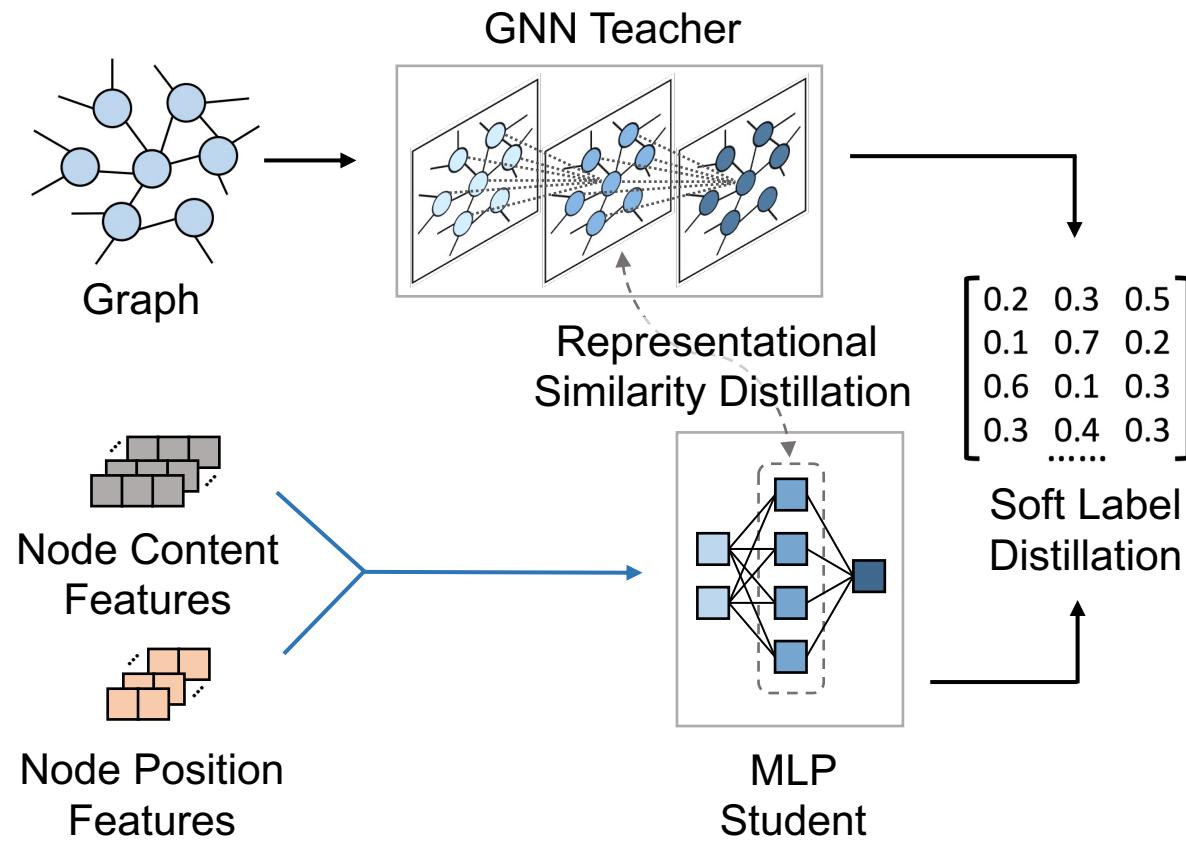


Adversarial Attacked Data

Can we leverage small data perturbations to **improve robustness?**

Yes, adversarial training

A use case: training an MLP on graphs

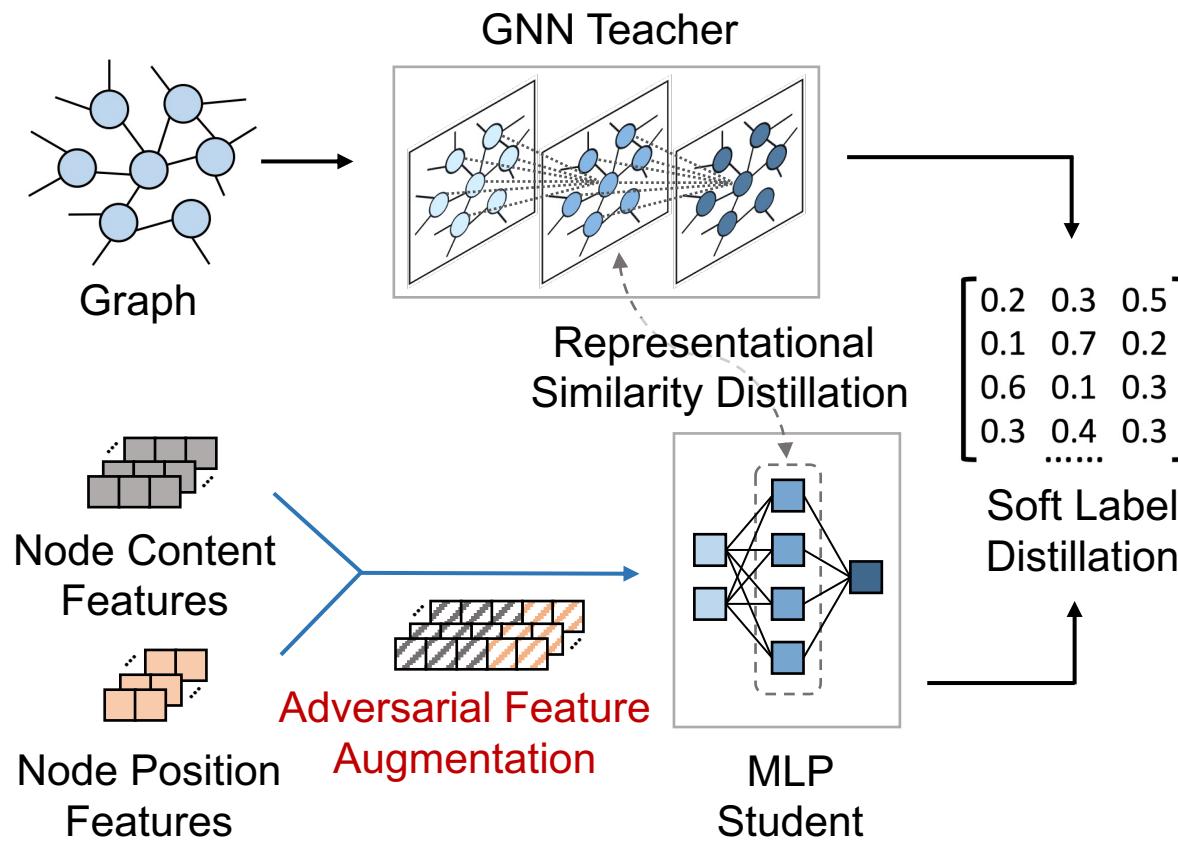


The problem of training an MLP on graphs:
sensitive to features

Adversarial Attacked Data

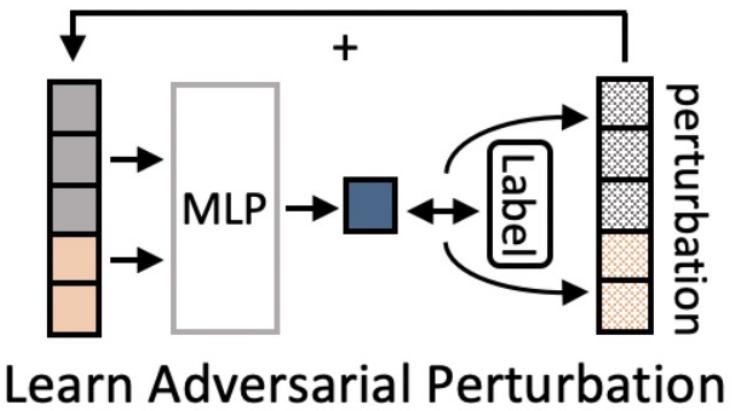
Can we leverage small data perturbations to **improve robustness**?
Yes, adversarial training

A use case: training an MLP on graphs



The problem of training an MLP on graphs:
sensitive to features

Overcome this problem with adversarial training



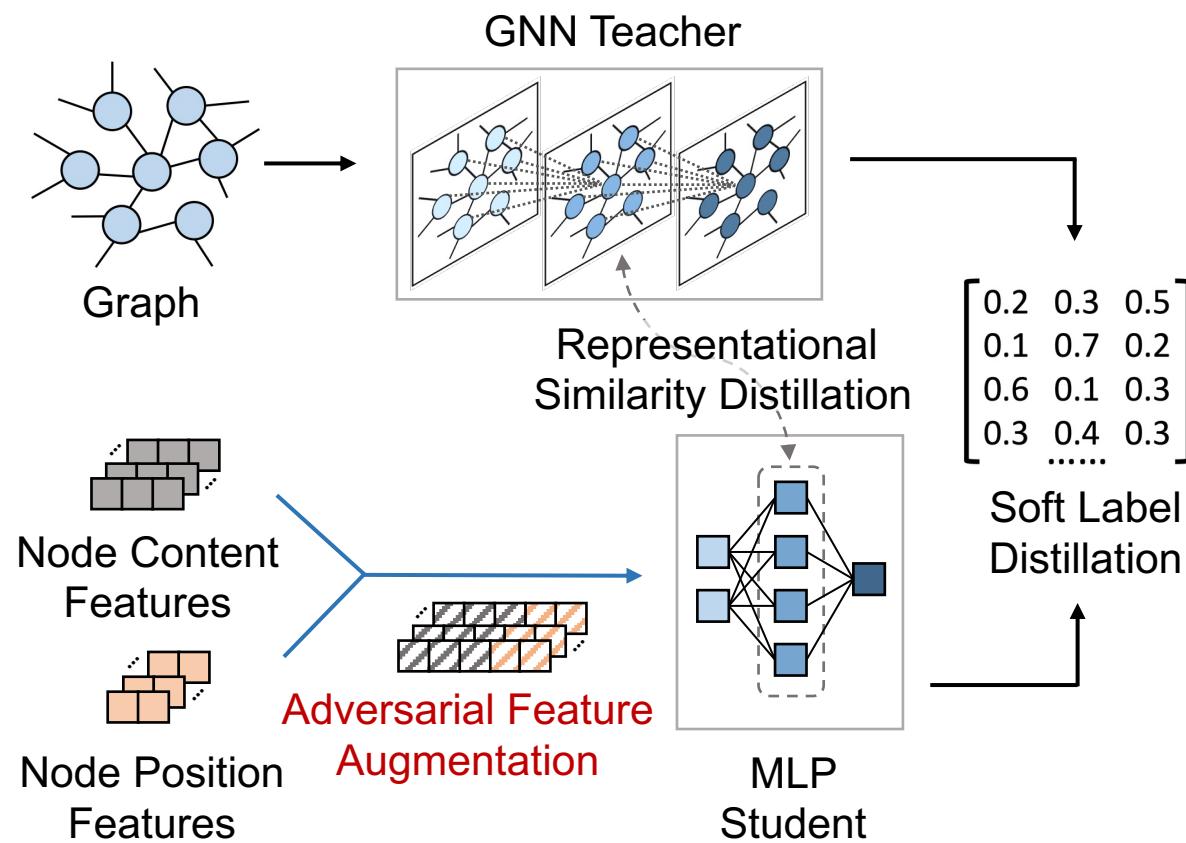
Learn Adversarial Perturbation

Adversarial Attacked Data

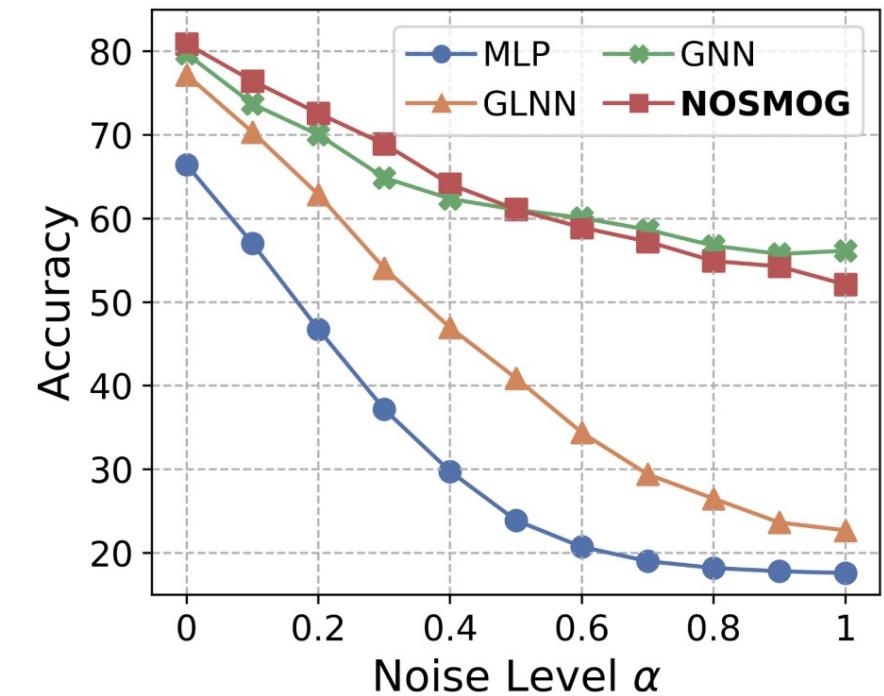
Can we leverage small data perturbations to **improve robustness**?

Yes, adversarial training

A use case: training an MLP on graphs



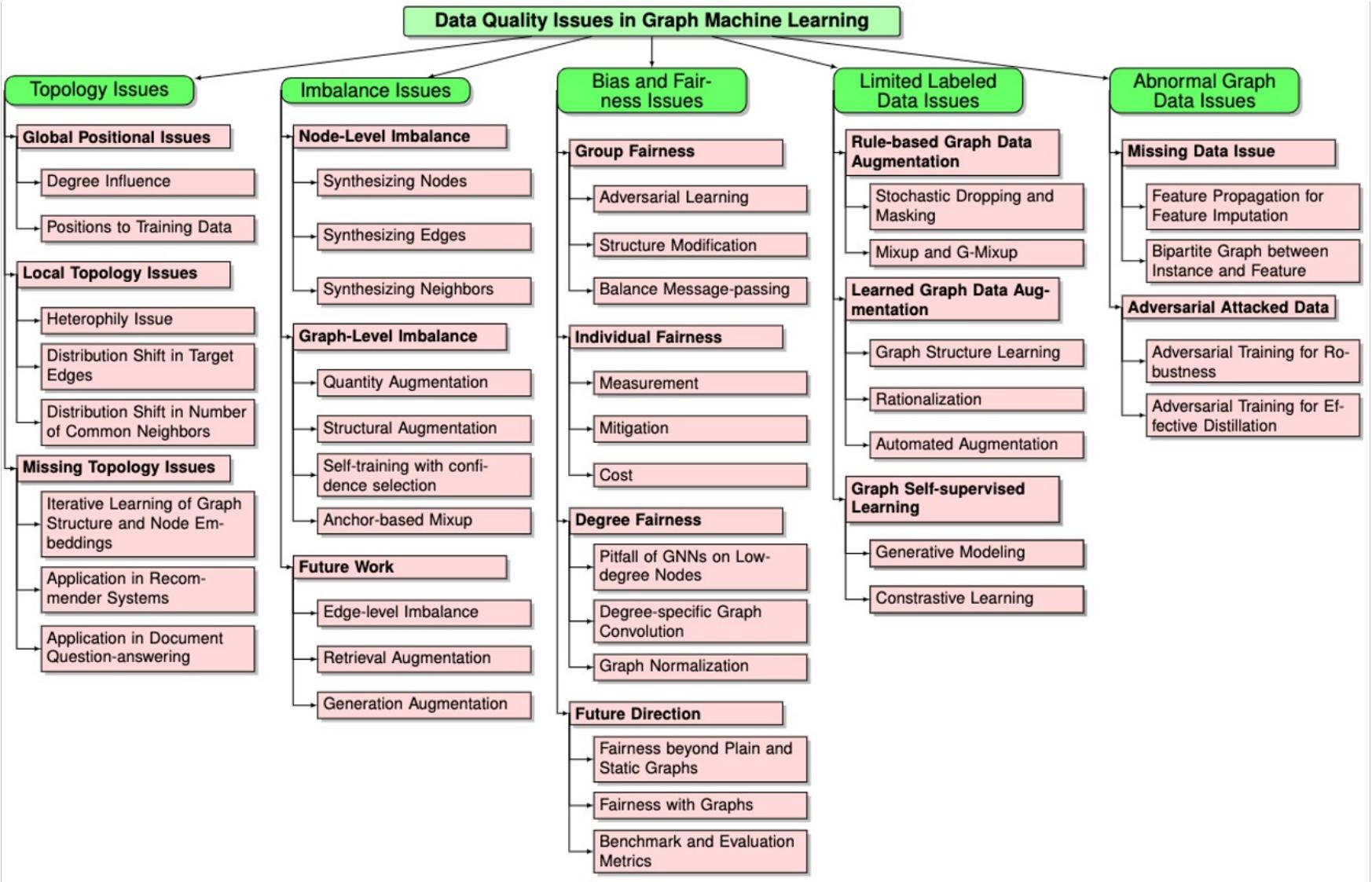
NOSMOG is as robust as GNNs



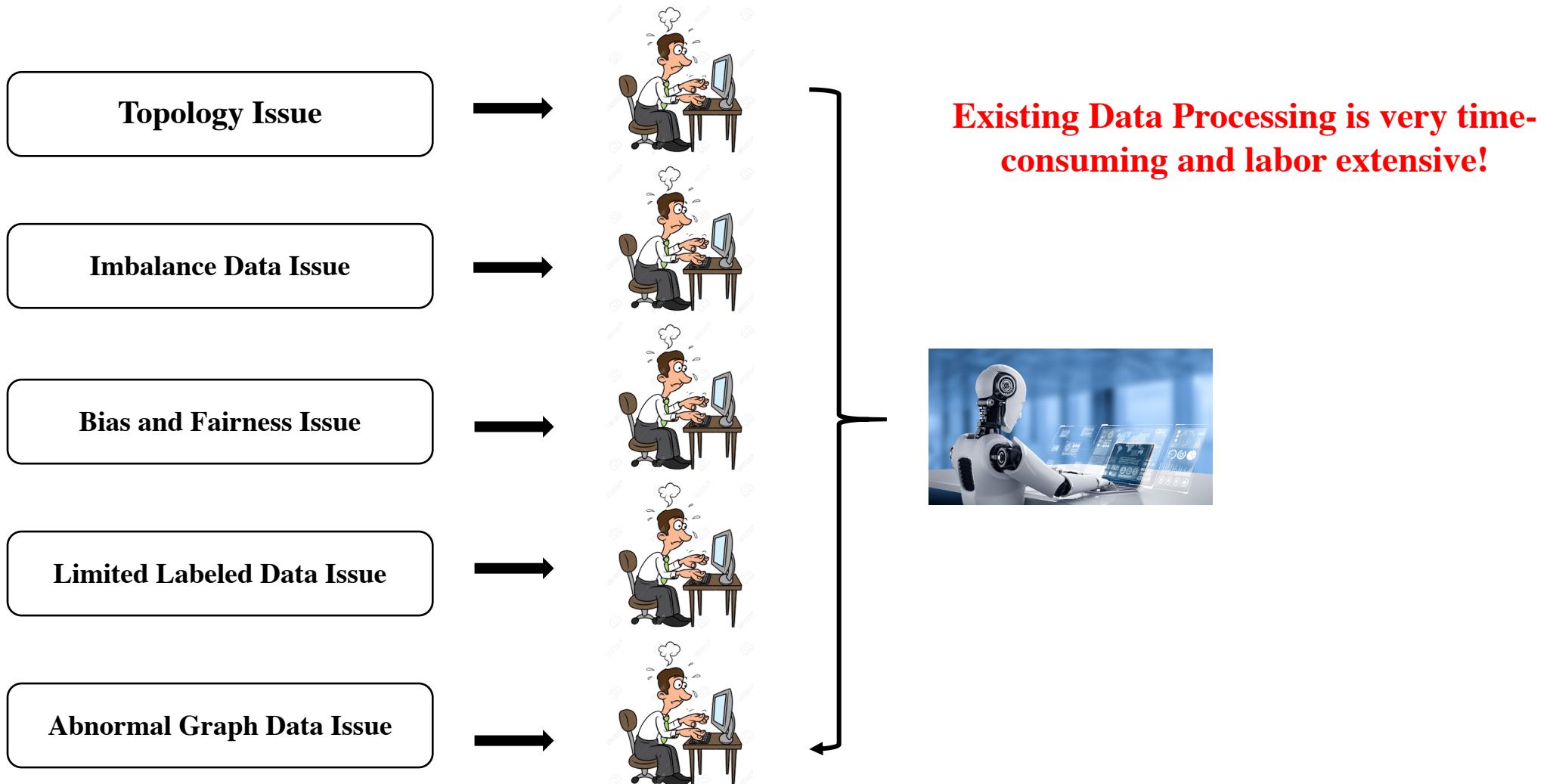
Summary

- Introduction and Background
- Topology Issues
- Imbalance Issues
- Short Break
- Bias Issue
- Limited Labeled Data Issues
- Abnormal Graph Data Issues
- **Summary**

Summary

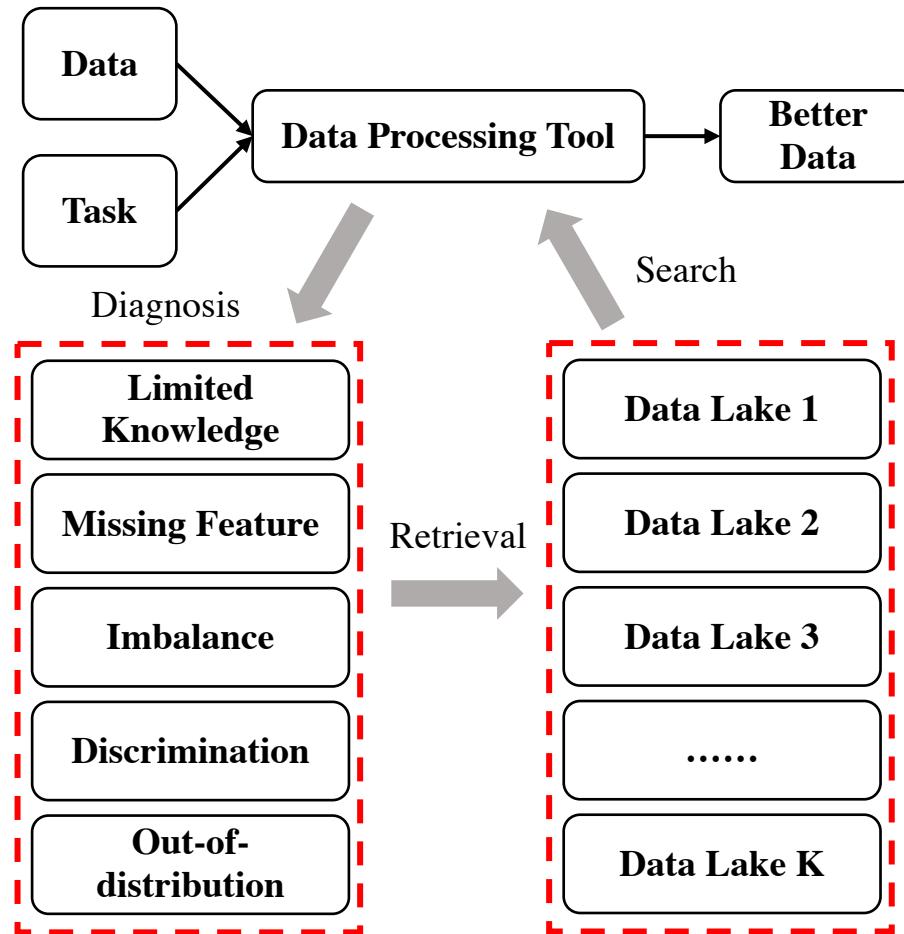


Future Directions

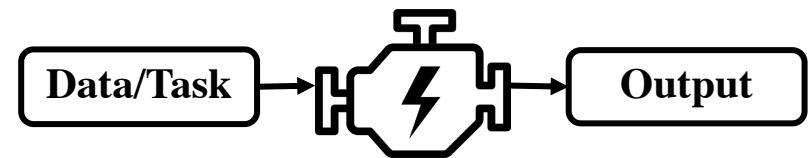


Summary

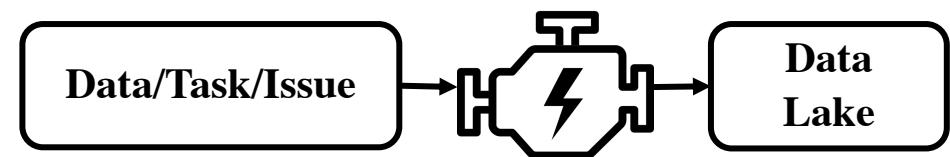
Intelligent Data Processing Tool



Diagnose



Retrieval



Search

