

1 Below, we present our responses that contain extra experiments.

2 **Experimental results on real-world datasets (Rev. sjzc)**

3 We explore the performance of standard COFUL algorithms and the proposed TS-MR and Greedy-
 4 MR algorithms on real-world datasets. We consider three datasets for classification tasks on the
 5 OPENML platform, Cardiotocography, JapaneseVowels and Segment. They focus on healthcare,
 6 pattern recognition, and computer vision problems respectively.

7 *Setup:* We follow the standard approach in the literature that converts classification tasks to contex-
 8 tual bandit problems, and then embeds it into linear bandit problems in the same way as Example 2
 9 in Section 6. Specifically, we regard each class as an action so that at each time, the decision-maker
 10 assigns a class to the feature observed and receives a binary reward, namely 1 for assigning the
 11 correct class and 0 otherwise, plus a Gaussian noise.

12 We plot the cumulative regret (averaged over 50 duplicates) for all algorithms. Figure 1 shows that
 13 for all real-world datasets: OFUL and TS-Freq perform poorly due to their conservative exploration;
 14 LinTS and Greedy are achieving empirical success even though they don't have theoretical guaran-
 15 tees; TS-MR and Greedy-MR retains the desirable empirical performance of LinTS and Greedy,
 16 while enjoying the minimax optimal frequentist regret bound.

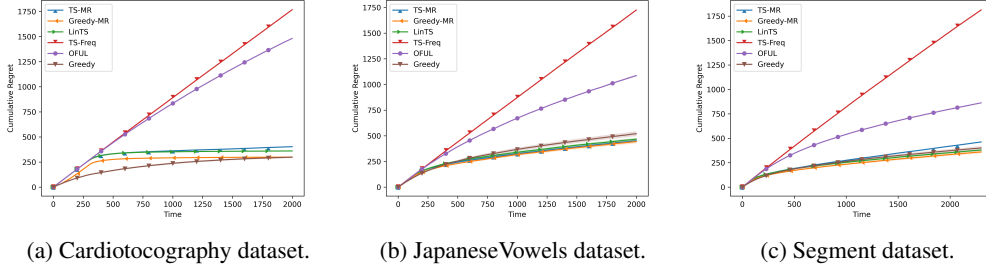


Figure 1: Cumulative regret of all algorithms on real-world datasets.

17 **Empirically validation of Case 2 in Section 5.1 (Rev. RqoU & Q5EJ)**

18 To empirically validate that Case 2 isn't vacant, we check the condition presented in Proposition 4.

19 We track the ratio $\zeta_t := \frac{\|\hat{\theta}_t\|_{V_t}^2 / \|\hat{\theta}_t\|^2}{\lambda_1(V_t)}$, which is a proxy that measures how close $\hat{\theta}_t$ is aligned with
 20 the top eigenspace of V_t . Specifically, $\zeta_t = 1$ implies that $\hat{\theta}_t$ lies in the top eigenspace. We rerun
 21 Example 1 in Section 6 and plot the empirical $\{\zeta_t\}$ sequence.

22 As we see in Figure 2, for all bandit algorithms, ζ_t is already very high (above 0.9) at the very early
 23 stage of the implementation and tends to 1 eventually. This validates the tendency in Case 2. (We
 24 remark that the sharp decrease at the beginning is due to the behavior of the regularized least square
 25 estimator in over-parameterized regimes when the time t is smaller than the dimension d .)

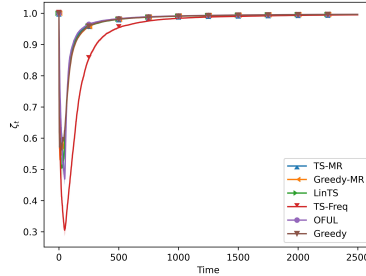


Figure 2: Involvement of the alignment proxy ζ_t in Example 1.