

# 實驗五 實驗結報

---

0316213 蒲郁文 & 0316323 薛世恩

## 實驗名稱

---

MAX7219 & 7-Seg LED

## 實驗目的

---

熟悉 output 跟 MAX7219 & 7-Seg LED

## 實驗步驟

---

**show1~9 A~F**

```
.syntax
unified

.cpu cortex-m4
.thumb

.data
    arr: .byte 0b01111110, 0b00110000, 0b01101101, 0b01111001,
    0b00110011, 0b01011011, 0b01011111, 0b01110000, 0b01111111,
    0b01111011, 0b01110111, 0b00011111, 0b01001110, 0b00111101,
    0b01001111, 0b01000111

    @ arr: a0, 1, 2, 3, 4, 5, 6, 7, 8, 9, A, b, C, d, E, F

.text
.global main
```

```
.equ RCC_AHB2ENR, 0x4002104C
```

```
.equ DECODE_MODE, 0x09
```

```
.equ DISPLAY_TEST, 0x0F
```

```
.equ SCAN_LIMIT, 0x0B
```

```
.equ INTENSITY, 0x0A
```

```
.equ SHUTDOWN, 0x0C
```

```
.equ MAX7219_DIN, 0x20 @ PA5
```

```
.equ MAX7219_CS, 0x40 @ PA6
```

```
.equ MAX7219_CLK, 0x80 @ PA7
```

```
.equ GPIOA_BASE, 0x48000000
```

```
.equ BSRR_OFFSET, 0x18 @ set bit
```

```
.equ BRR_OFFSET, 0x28 @ clear bit
```

```
main:
```

```
    bl    gpio_init
```

```
    bl    max7219_init
```

```
display_0_to_f:
```

```
    mov   r2, 0x0
```

```
    ldr   r3, =arr
```

```
    b     loop
```

```
gpio_init:
```

```
    mov   r0, 0b00000000000000000000000000000001
```

```
    ldr   r1, =RCC_AHB2ENR
```

```
    str   r0, [r1]
```

```
ldr r1, =GPIOA_BASE @ GPIOA_MODER
ldr r2, [r1]
and r2, 0b11111111111111111000000111111111
orr r2, 0b000000000000000010101000000000
str r2, [r1]
```

```
add r1, 0x4 @ GPIOA_OTYPER
ldr r2, [r1]
and r2, 0b11111111111111111111111110001111
str r2, [r1]
```

```
add r1, 0x4 @ GPIOA_SPEEDER
ldr r2, [r1]
and r2, 0b11111111111111111000000111111111
orr r2, 0b000000000000000010101000000000
str r2, [r1]
```

```
bx lr
```

```
loop:
```

```
mov r0, 0x1
ldrb r1, [r3, r2]
bl max7219_send
```

```
ldr r0, =4000000 @ delay 1s
movs r0, r0
bl delay
```

```
add r2, 0x1
cmp r2, 0x10
bne loop
```

```
mov r2, 0x0
```

```
b loop
```

```
max7219_send:
```

```
@ input parameter: r0 is ADDRESS , r1 is DATA
```

```
push {r0, r1, r2, r3, r4, r5, r6, r7, r8, lr}
```

```
lsl r0, r0, 0x8
```

```
add r0, r1
```

```
ldr r1, =GPIOA_BASE
```

```
ldr r2, =MAX7219_CS
```

```
ldr r3, =MAX7219_DIN
```

```
ldr r4, =MAX7219_CLK
```

```
ldr r5, =BSRR_OFFSET
```

```
ldr r6, =BRR_OFFSET
```

```
ldr r7, =0x0F @ currently sending r7-th bit
```

```
max7219_send_loop:
```

```
mov r8, 0x1
```

```
lsl r8, r8, r7
```

```
str r4, [r1, r6] @ clk -> 0
```

```
tst r0, r8 @ ANDS but discard result
```

```
beq max7219_send_clear_bit
```

```
str r3, [r1, r5] @ din -> 1
```

```
b max7219_send_check_done
```

```
max7219_send_clear_bit:
```

```
str r3, [r1, r6] @ din -> 0
```

```
max7219_send_check_done:
```

```
str r4, [r1, r5] @ clk -> 1
```

```
subs r7, 0x1
```

```
bge max7219_send_loop
```

```
str r2, [r1, r6] @ cs -> 0
str r2, [r1, r5] @ cs -> 1
pop {r0, r1, r2, r3, r4, r5, r6, r7, r8, pc}
```

max7219\_init:

```
push {r0, r1, r2, lr}
```

```
ldr r0, =DECODE_MODE
ldr r1, =0x0
bl max7219_send
```

```
ldr r0, =DISPLAY_TEST
ldr r1, =0x0
bl max7219_send
```

```
ldr r0, =SCAN_LIMIT
ldr r1, =0x0
bl max7219_send
```

```
ldr r0, =INTENSITY
ldr r1, =0xA
bl max7219_send
```

```
ldr r0, =SHUTDOWN
ldr r1, =0x1
bl max7219_send
```

```
pop {r0, r1, r2, pc}
```

delay:

	beq delay_end
	subs r0, 0x4
	b delay
	delay_end:
	bx lr

show student ID

	.syntax
	unified
	.cpu cortex-m4
	.thumb
	.data
	arr: .byte 0x0, 0x3, 0x1, 0x6, 0x2, 0x1, 0x3
	@ arr: .byte 0x0, 0x3, 0x1, 0x6, 0x3, 0x2, 0x3
	.text
	.global main
	.equ RCC_AHB2ENR, 0x4002104C
	.equ DECODE_MODE, 0x09
	.equ DISPLAY_TEST, 0x0F
	.equ SCAN_LIMIT, 0x0B
	.equ INTENSITY, 0x0A
	.equ SHUTDOWN, 0x0C

```

.equ MAX7219_DIN, 0x20 @ PA5
.equ MAX7219_CS, 0x40 @ PA6
.equ MAX7219_CLK, 0x80 @ PA7

.equ GPIOA_BASE, 0x48000000
.equ BSRR_OFFSET, 0x18 @ set bit
.equ BRR_OFFSET, 0x28 @ clear bit

```

```
main:
```

```

bl    gpio_init
bl    max7219_init

```

```
display_arr:
```

```

mov    r0, 0x7
mov    r2, 0x0
ldr    r3, =arr
b      loop

```

```
gpio_init:
```

```

mov    r0, 0b00000000000000000000000000000001
ldr    r1, =RCC_AHB2ENR
str    r0, [r1]

```

```

ldr    r1, =GPIOA_BASE @ GPIOA_MODER
ldr    r2, [r1]
and    r2, 0b11111111111111110000001111111111
orr    r2, 0b000000000000000010101000000000
str    r2, [r1]

```

```

add    r1, 0x4 @ GPIOA_OTYPER
ldr    r2, [r1]
and    r2, 0b11111111111111111111111100011111

```

```
str r2, [r1]
```

```
add r1, 0x4 @ GPIOA_SPEEDER
```

```
ldr r2, [r1]
```

```
and r2, 0b11111111111111110000001111111111
```

```
orr r2, 0b000000000000000010101000000000
```

```
str r2, [r1]
```

```
bx lr
```

```
loop:
```

```
ldrb r1, [r3, r2]
```

```
bl max7219_send
```

```
sub r0, 0x1
```

```
add r2, 0x1
```

```
cmp r2, 0x8
```

```
bne loop
```

```
mov r0, 0x7
```

```
mov r2, 0x0
```

```
b loop
```

```
max7219_send:
```

```
@ input parameter: r0 is ADDRESS , r1 is DATA
```

```
push {r0, r1, r2, r3, r4, r5, r6, r7, r8, lr}
```

```
lsl r0, r0, 0x8
```

```
add r0, r1
```

```
ldr r1, =GPIOA_BASE
```

```
ldr r2, =MAX7219_CS
```

```
ldr r3, =MAX7219_DIN
```

```
ldr r4, =MAX7219_CLK
```



```
ldr r5, =BSRR_OFFSET
ldr r6, =BRR_OFFSET
ldr r7, =0x0F @ currently sending r7-th bit
```

```
max7219_send_loop:
```

```
mov r8, 0x1
lsl r8, r8, r7
str r4, [r1, r6] @ clk -> 0
tst r0, r8 @ ANDS but discard result
beq max7219_send_clear_bit
str r3, [r1, r5] @ din -> 1
b max7219_send_check_done
```

```
max7219_send_clear_bit:
```

```
str r3, [r1, r6] @ din -> 0
```

```
max7219_send_check_done:
```

```
str r4, [r1, r5] @ clk -> 1
subs r7, 0x1
bge max7219_send_loop
str r2, [r1, r6] @ cs -> 0
str r2, [r1, r5] @ cs -> 1
pop {r0, r1, r2, r3, r4, r5, r6, r7, r8, pc}
```

```
max7219_init:
```

```
push {r0, r1, r2, lr}
```

```
ldr r0, =DECODE_MODE
ldr r1, =0xFF
bl max7219_send
```

```
ldr r0, =DISPLAY_TEST
```

	ldr r1, =0x0
	bl max7219_send
	ldr r0, =SCAN_LIMIT
	ldr r1, =0x6
	bl max7219_send
	ldr r0, =INTENSITY
	ldr r1, =0xA
	bl max7219_send
	ldr r0, =SHUTDOWN
	ldr r1, =0x1
	bl max7219_send
	pop {r0, r1, r2, pc}
	delay:
	beq delay_end
	subs r0, 0x4
	b delay
	delay_end:
	bx lr

# show 費伯納數列

```
.syn
tax
unif
ied
```

	.cpu cortex-m4
	.thumb
	.data
	ans: .asciz
	"01123581321345589144233377610987159725844181676510946177112865746368750
	251213931964183178115142298320401346269217830935245785702887922746514930
	352241578173908816963245986:1"
	len: .byte 0x1, 0x1, 0x1, 0x1, 0x1, 0x1, 0x1, 0x1, 0x2, 0x2, 0x2, 0x2,
	0x2, 0x3, 0x3, 0x3, 0x3, 0x3, 0x4, 0x4, 0x4, 0x4, 0x5, 0x5, 0x5, 0x5,
	0x5, 0x6, 0x6, 0x6, 0x6, 0x6, 0x7, 0x7, 0x7, 0x7, 0x7, 0x8, 0x8, 0x8,
	0x8, 0x2
	.text
	.global main
	.equ RCC_AHB2ENR, 0x4002104C
	.equ DECODE_MODE, 0x09
	.equ DISPLAY_TEST, 0x0F
	.equ SCAN_LIMIT, 0x0B
	.equ INTENSITY, 0x0A
	.equ SHUTDOWN, 0x0C
	.equ MAX7219_DIN, 0x20 @ PA5
	.equ MAX7219_CS, 0x40 @ PA6
	.equ MAX7219_CLK, 0x80 @ PA7
	.equ GPIOA_BASE, 0x48000000
	.equ GPIOC_BASE, 0x48000800
	.equ BSRR_OFFSET, 0x18 @ set bit
	.equ BRR_OFFSET, 0x28 @ clear bit

```
main:
```

```
bl gpio_init
```

```
b1 max7219_init
```

```
display_ans:
```

```
ldr    r2, =len
```

```
ldr r3, =ans
```

```
b    loop_init
```

```
gpio_init:
```

[illegible]

```
ldr    r1, =RCC_AHB2ENR
```

```
str r0, [r1]
```

```
ldr    r1, =GPIOA_BASE @ GPIOA_MODER
```

```
ldr  r2, [r1]
```

```
and r2, 0b11111111111111110000001111111111
```

```
orr    r2, 0b00000000000000000001010100000000
```

```
str r2, [r1]
```

```
add r1, 0x4 @ GPIOA_OTYPER
```

```
ldr  r2, [r1]
```

and r2, 0b111111111111111111111111111111110001111

```
str r2, [r1]
```

```
add r1, 0x4 @ GPIOA_SPEEDER
```

```
ldr  r2, [r1]
```

and r2, 0b11111111111111110000001111111111

```
orr r2, 0b00000000000000000010101000000000
```

```
str r2, [r1]
```

```
ldr r1, =GPIOC_BASE @ GPIOC_MODER
ldr r2, [r1]
and r2, 0b11110011111111111111111111111111
str r2, [r1]
```

```
add r10, r1, 0x10
bx lr
```

```
loop_init:
```

```
mov r0, 0x1
mov r1, 0x0F
bl max7219_send
```

```
mov r0, 0x2
mov r1, 0x0F
bl max7219_send
```

```
mov r0, 0x3
mov r1, 0x0F
bl max7219_send
```

```
mov r0, 0x4
mov r1, 0x0F
bl max7219_send
```

```
mov r0, 0x5
mov r1, 0x0F
bl max7219_send
```

```
mov r0, 0x6
```

```
mov r1, 0x0F
bl max7219_send
```

```
mov r0, 0x7
mov r1, 0x0F
bl max7219_send
```

```
mov r0, 0x8
mov r1, 0x0F
bl max7219_send
```

```
ldrb r0, [r2]
```

```
loop_inner:
    ldrb r1, [r3]
    sub r1, 0x30 @ char - '0' = digit
    bl max7219_send
```

```
subs r0, 0x1
add r3, 0x1
bne loop_inner
```

```
loop:
    ldr r0, =len
    add r0, 40
    cmp r2, r0
    it eq
    bleq loop_last
    add r2, 0x1
```

```
mov r11, 0x1
```

```
mov r12, 0x1
bl check_button_init
```

```
b loop_init
```

```
loop_last:
```

```
sub r2, 0x1
sub r3, 0x2
bx lr
```

```
max7219_send:
```

```
@ input parameter: r0 is ADDRESS , r1 is DATA
push {r0, r1, r2, r3, r4, r5, r6, r7, r8, lr}
lsl r0, r0, 0x8
add r0, r1
ldr r1, =GPIOA_BASE
ldr r2, =MAX7219_CS
ldr r3, =MAX7219_DIN
ldr r4, =MAX7219_CLK
ldr r5, =BSRR_OFFSET
ldr r6, =BRR_OFFSET
ldr r7, =0x0F @ currently sending r7-th bit
```

```
max7219_send_loop:
```

```
mov r8, 0x1
lsl r8, r8, r7
str r4, [r1, r6] @ clk -> 0
tst r0, r8 @ ANDS but discard result
beq max7219_send_clear_bit
str r3, [r1, r5] @ din -> 1
b max7219_send_check_done
```

```
max7219_send_clear_bit:
```

```
str r3, [r1, r6] @ din -> 0
```

```
max7219_send_check_done:
```

```
str r4, [r1, r5] @ clk -> 1
```

```
subs r7, 0x1
```

```
bge max7219_send_loop
```

```
str r2, [r1, r6] @ cs -> 0
```

```
str r2, [r1, r5] @ cs -> 1
```

```
pop {r0, r1, r2, r3, r4, r5, r6, r7, r8, pc}
```

```
max7219_init:
```

```
push {r0, r1, r2, lr}
```

```
ldr r0, =DECODE_MODE
```

```
ldr r1, =0xFF
```

```
bl max7219_send
```

```
ldr r0, =DISPLAY_TEST
```

```
ldr r1, =0x0
```

```
bl max7219_send
```

```
ldr r0, =SCAN_LIMIT
```

```
ldr r1, =0x7
```

```
bl max7219_send
```

```
ldr r0, =INTENSITY
```

```
ldr r1, =0xA
```

```
bl max7219_send
```

```
ldr r0, =SHUTDOWN
```

```
ldr r1, =0x1
```



```
b1 max7219_send
```

```
pop {r0, r1, r2, pc}
```

```
check_button_init:
```

```
ldr r0, =4000000 @ delay 1s
```

```
movs r0, r0
```

```
b check_button_delay
```

```
check_button_delay:
```

```
beq check_button_init
```

```
ldr r1, =0b1111111111111111
```

```
ands r1, r0
```

```
beq check_button @ branch every 32.768 ms
```

```
subs r0, 0x8
```

```
b check_button_delay
```

```
check_button:
```

```
@ r10 gpio button input
```

```
@ r11 latest button value
```

```
@ r12 confirmed button value
```

```
ldrh r1, [r10]
```

```
lsr r1, 13
```

```
mov r4, 1
```

```
and r1, r4
```

```
cmp r1, r11
```

```
mov r11, r1
```

```
beq check_button_confirmed
```

```
subs r0, 8
```

```
b check_button_delay
```

```
check_button_confirmed:
```

```
subs r1, r11, r12
```

	<code>cmp r1, 1</code>
	<code>mov r12, r11</code>
	<code>beq check_button_end</code>
	<code>subs r0, 8</code>
	<code>b check_button_delay</code>
	<code>check_button_end:</code>
	<code>bx lr</code>

## 實驗結果與問題回答

---

### Show1~9&A~F

- 首先先將它存成陣列
- 然後將它一個一個照著 `delay` 讀取
- 然將設定成對的輸出方式然後一直變換輸出
- 

### Show student id

- 將學生 ID 放在陣列一次一個讀
- 然後將其輸出

## 費伯納數列

依照前幾次作業將其組合，然後當它輸出超過，就顯示-1。

然後做好 **debounce**。

- 心得討論與應用聯想

真的超級難，然後又在期中考周出作業，寫超級久，BUG 也超級多。