

Consider the set of distributions  $\{P_{Y|X}(\bullet|x) : x \in \mathbb{X}\}$  lying in a transformation model  $\mathcal{P}_{\mathbb{G}} = \{g_*P_0 : g \in \mathbb{G}\} \subseteq \mathcal{P}(\mathbb{Y})$ . For each  $x \in \mathbb{X}$ , there exists an element  $g_x$  of the group  $\mathbb{G}$  such that  $P_{Y|X}(\bullet|\phi x) = g_x * P_0$ . When transforming  $x$  with  $\phi$ , there is also an element  $g_{\phi x}$  such that  $P_{Y|X}(\bullet|x) = g_{\phi x} * P_0$ . This enables direct transition from  $P_{Y|X}(\bullet|x)$  to  $P_{Y|X}(\bullet|\phi x)$  via the coboundary  $c(\phi, x) : (\phi, x) \mapsto g_{\phi x}g_x^{-1} \in \mathbb{G}$ . The coboundary  $c(\phi, x)$  does not depend on  $P_0$  and thus applies to (infinitely) many other conditional distributions. Modelling the coboundary instead of  $P_{Y|X}$  helps improve robustness against model mis-specification.

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