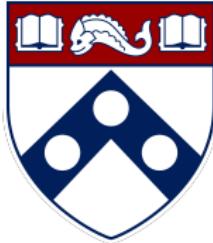


Estimation and Inference for Heteroskedastic PCA with Missing Data



Yuxin Chen

Wharton Statistics & Data Science

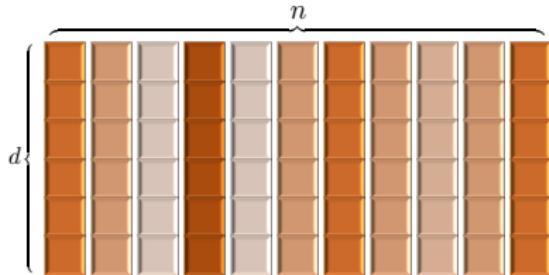


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Principal component analysis



$$\mathbf{X} = [\mathbf{x}_1, \dots, \mathbf{x}_n]$$

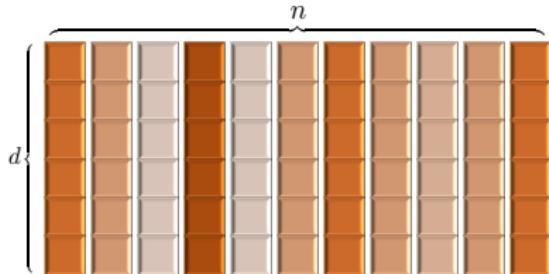
- Ground-truth data

$$\mathbf{X} = [\mathbf{x}_1, \dots, \mathbf{x}_n] \in \mathbb{R}^{d \times n}, \quad \mathbf{x}_i \stackrel{\text{ind.}}{\sim} \mathcal{N}(\mathbf{0}, \mathbf{S}^*)$$

$$\text{where } \mathbf{S}^* = \mathbf{U}^* \boldsymbol{\Lambda}^* \mathbf{U}^{*\top} \in \mathbb{R}^{d \times d}$$

Principal component analysis

$\text{span}\{\mathbf{x}_1, \dots, \mathbf{x}_n\} \subseteq \mathbf{U}^*$ (r -dimensional)



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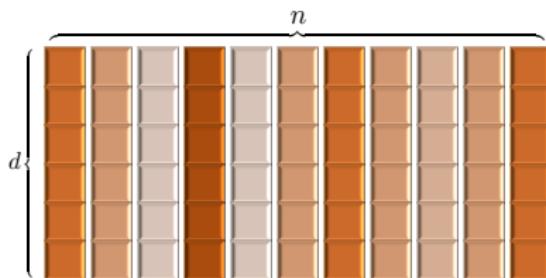
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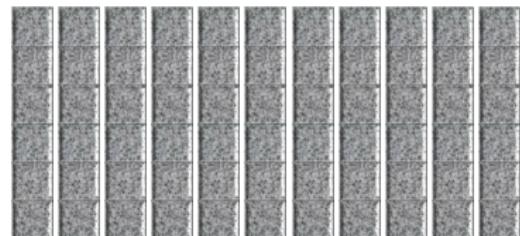
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noise matrix: \mathbf{E}

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- Noisy observations: $\mathbf{X} + \mathbf{E}$ (a.k.a. spiked covariance model)

Principal component analysis

$$\text{span}\{x_1, \dots, x_n\} \subseteq U^\star \text{ (r-dimensional)}$$

The diagram illustrates a 2D convolutional layer. It shows an input grid of size $n \times n$ composed of n^2 cells. A kernel of size $d \times d$ is applied to the input with a stride of 1. The kernel slides across the input, and the output is a smaller grid of size $(n-d+1) \times (n-d+1)$. The diagram uses orange and grey colors to represent different input and output units respectively.

$$X = [x_1, \dots, x_n]$$



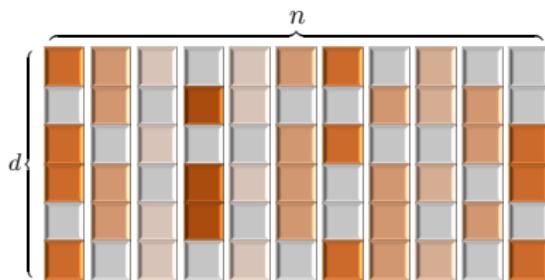
noise matrix: E

- Incomplete observations \rightarrow sampling set Ω :

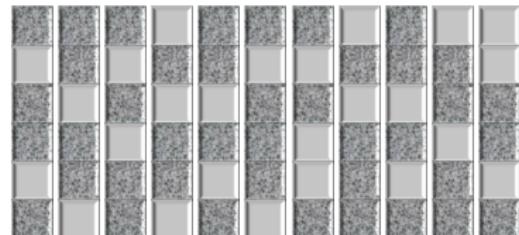
$$Y_{i,j} = \begin{cases} X_{i,j}^* + E_{i,j}, & (i,j) \in \Omega \\ 0, & \text{else} \end{cases} \quad \text{or} \quad \mathbf{Y} = \mathcal{P}_\Omega(\mathbf{X} + \mathbf{E})$$

Principal component analysis

$\text{span}\{\mathbf{x}_1, \dots, \mathbf{x}_n\} \subseteq \mathbf{U}^*$ (r -dimensional)



$$\mathbf{X} = [\mathbf{x}_1, \dots, \mathbf{x}_n]$$



$$\text{noise matrix: } \mathbf{E}$$

- **Goal:**

- Construct confidence regions for principal subspace \mathbf{U}^*
- Construct entrywise confidence intervals for covariance matrix \mathbf{S}^*

What we consider here . . .

- **Heteroskedastic noise:** $\{E_{i,j}\}$ are ind. sub-Gaussian obeying

$$\mathbb{E}[E_{i,j}] = 0, \quad \mathbb{E}[E_{i,j}^2] = \omega_i^{*2} \in [\omega_{\min}^2, \omega_{\max}^2], \quad \underbrace{\|E_{i,j}\|_{\psi_2}}_{\text{sub-Gaussian norm}} = O(\omega_i^*)$$

- noise variance $\{\omega_i^{*2}\}$: **unknown**, location-varying

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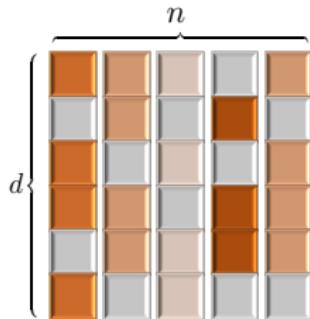
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- **Random sampling:** $(i, j) \in \Omega$ independently with prob. p

What we consider here . . .

Our focus: estimating/inferring column subspace when $\underbrace{n \gg d}_{\text{more challenging regime}}$

What we consider here ...

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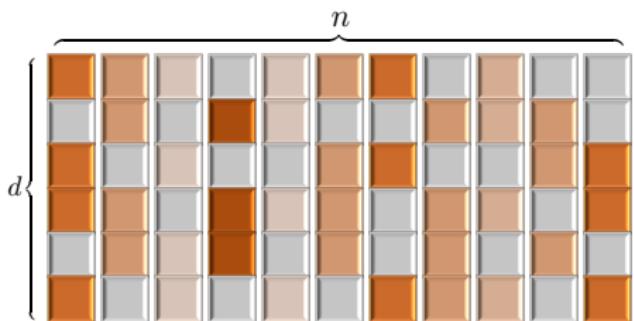
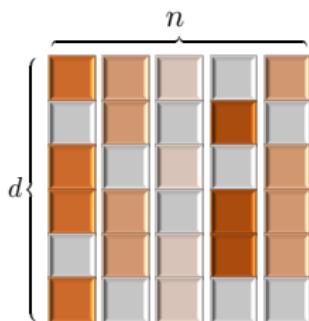


$n \lesssim d$: solvable via *matrix completion* methods

(e.g., Chen, Fan, Ma, Yan '19)

What we consider here ...

Our focus: estimating/inferring column subspace when $n \gg d$
more challenging regime

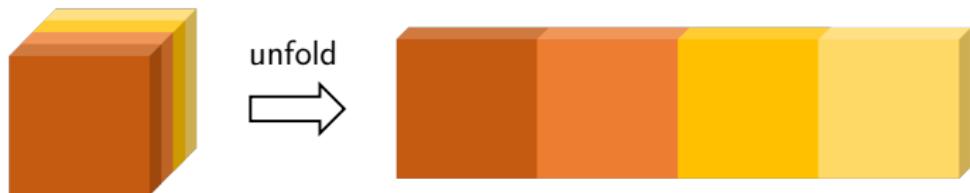


$n \lesssim d$: solvable via *matrix completion* methods
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$n \gg d$: sometimes it's only feasible to estimate col-space instead of whole matrix

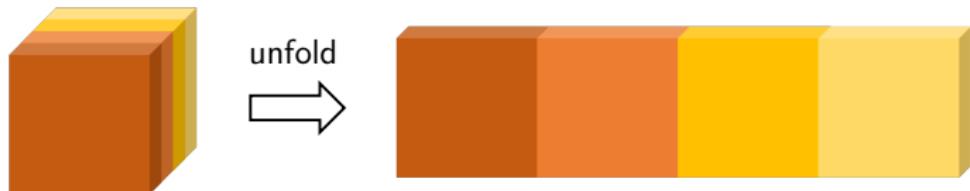
Applications beyond PCA

- Tensor completion

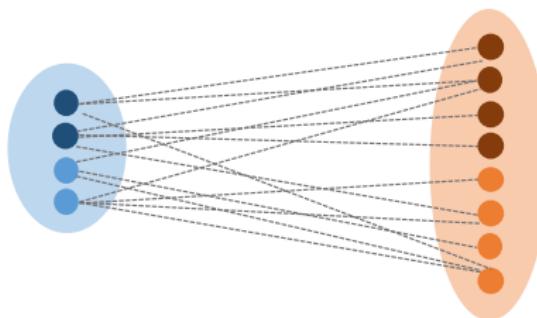


Applications beyond PCA

- Tensor completion



- One-sided community recovery in bipartite random graphs



A natural SVD-based algorithm

- **Compute:** rank- r SVD $\mathbf{U}\Sigma\mathbf{V}^\top$ of $\mathbf{Y} = \mathcal{P}_\Omega(\mathbf{X} + \mathbf{E})$
- **Output:** \mathbf{U} \longrightarrow estimate of \mathbf{U}^*

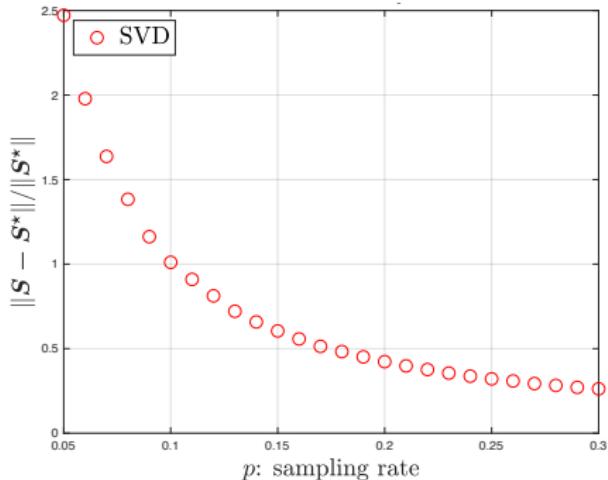
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Rationale: under zero-mean noise and random sampling, we have

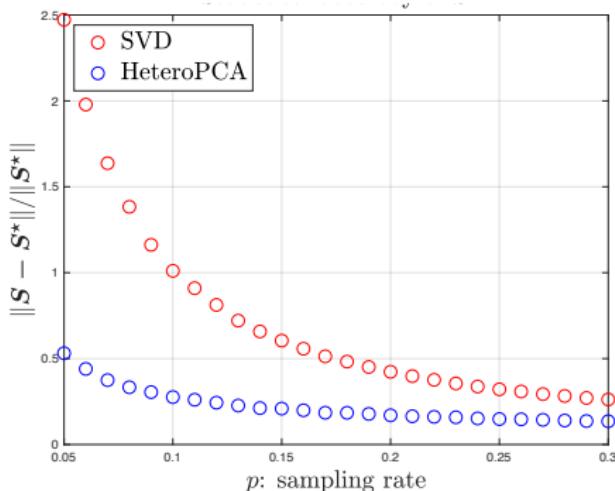
$$\text{col-space}(\mathbb{E}[\mathbf{Y}]) = \text{col-space}(\mathbf{X}) = \mathbf{U}^*$$

Numerical suboptimality of SVD-based approach



$n = 2000, \ d = 100, \ r = 3, \ \omega_1^*, \dots, \omega_d^* \stackrel{\text{i.i.d.}}{\sim} \text{Unif}[0.025, 0.1]$

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Plain SVD is suboptimal in the presence of missing data if $n \gg d$

Diagnosis: diagonal entries need special treatment

$$\text{col-space}(\mathbf{Y}) = \text{eig-space}(\mathbf{Y}\mathbf{Y}^T)$$

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Large bias in diagonal entries:

$$\frac{1}{p^2} \mathbb{E}[\mathbf{Y}\mathbf{Y}^\top] = \underbrace{\mathbf{X}\mathbf{X}^\top}_{\checkmark} + \underbrace{\left(\frac{1}{p} - 1\right) \mathcal{P}_{\text{diag}}(\mathbf{X}\mathbf{X}^\top)}_{\text{potentially large diagonal matrix!}} + \frac{n}{p} \text{diag}\left\{ [\omega_i^{*2}] \right\}$$

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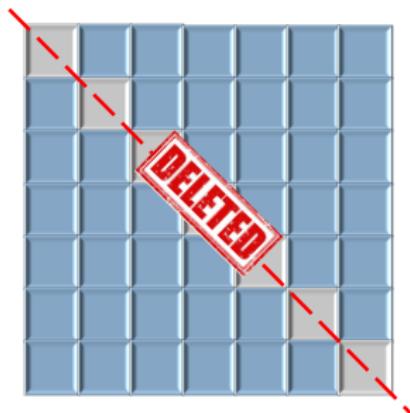
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- a common issue under missing data or heteroskedastic noise

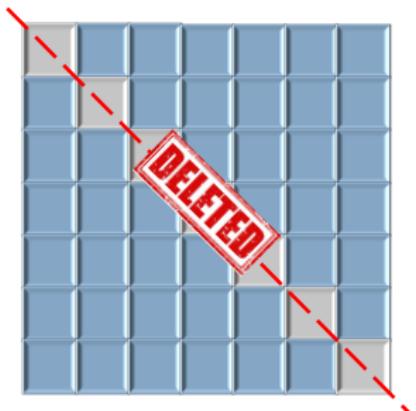
Two spectral algorithms that take care of diagonals



diagonal-deleted/reweighted PCA

- remove/reweight $\text{diag}(\mathbf{Y}\mathbf{Y}^\top)$

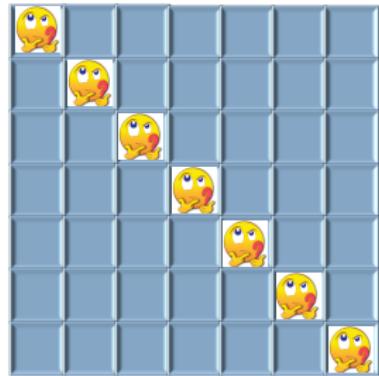
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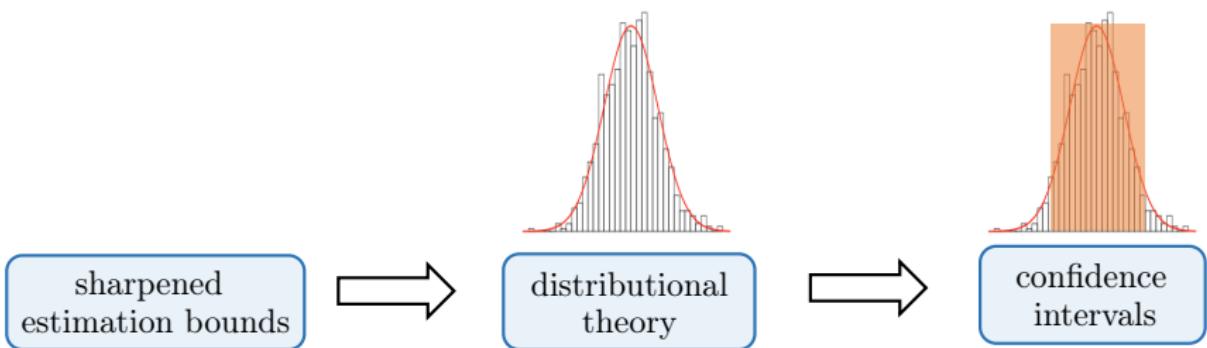
— Loh, Wainwright '12
— Lounici '13 '14
— Florescu and Perkins '16
— Montanari and Sun '18
— Zhu, Wang, Samworth '19
— Cai, Li, Chi, Poor, Chen '19
— ...



HeteroPCA (Zhang et al '18)

- iteratively estimate $\text{diag}(\mathbf{Y}\mathbf{Y}^\top)$

Our contributions: estimation and inference based on HeteroPCA

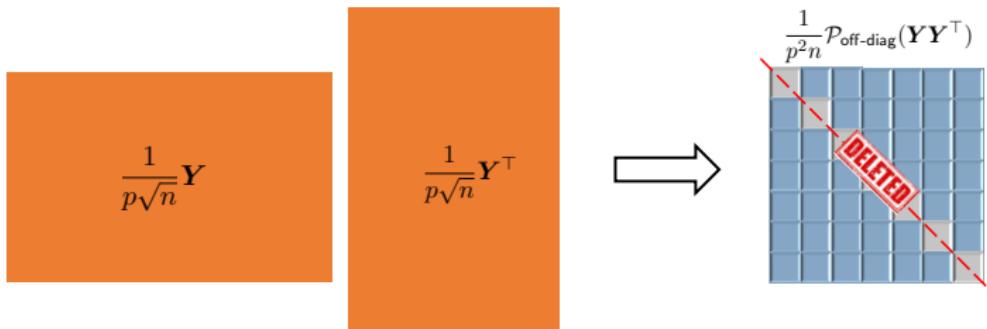


HeteroPCA (Zhang, Cai, Wu '18)

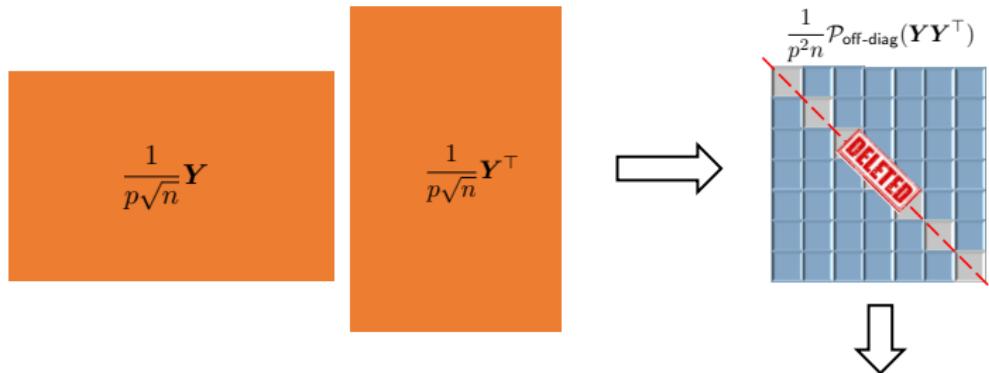
$$\frac{1}{p\sqrt{n}} \mathbf{Y}$$

$$\frac{1}{p\sqrt{n}} \mathbf{Y}^\top$$

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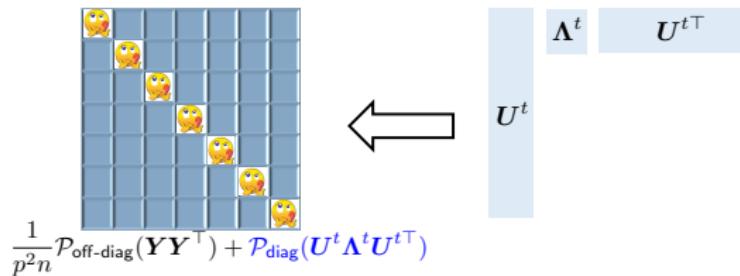
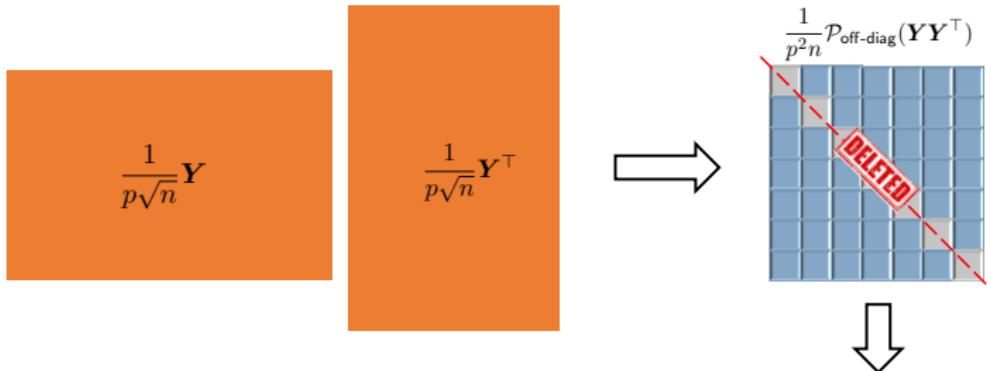


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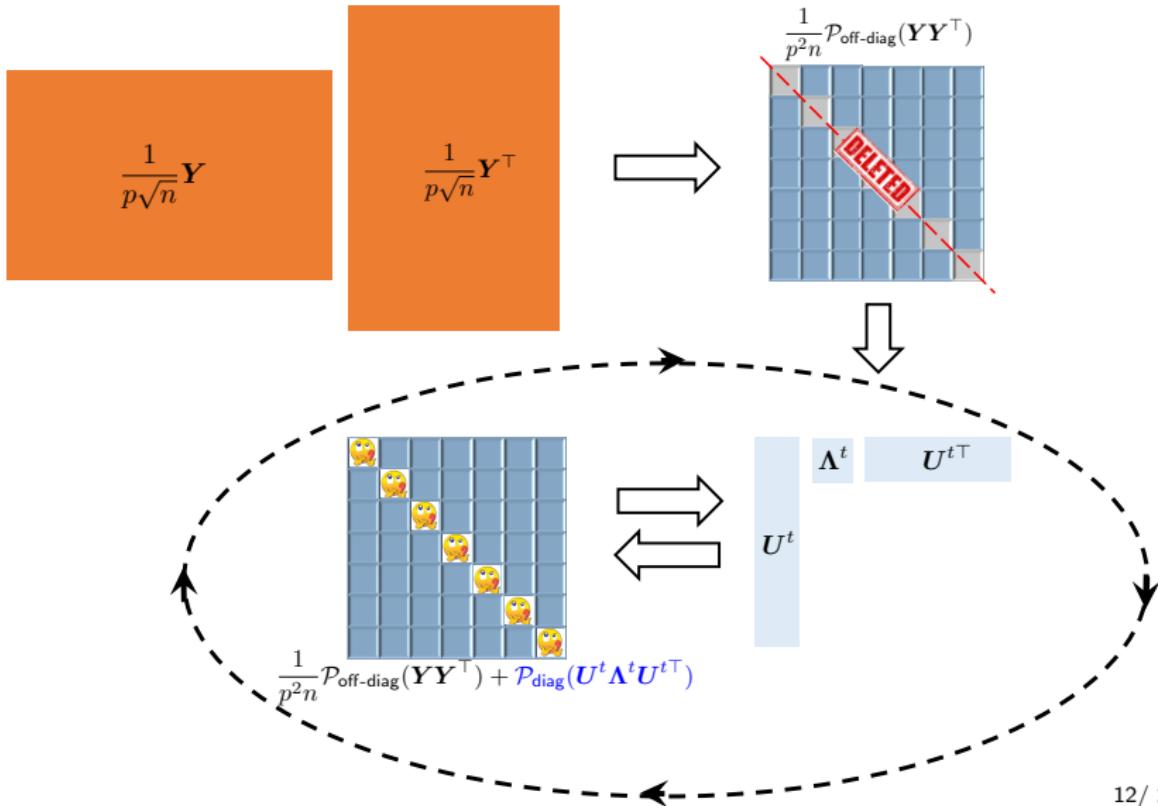


$$\begin{matrix} & \Lambda^t & U^{t\top} \\ U^t & & \end{matrix}$$

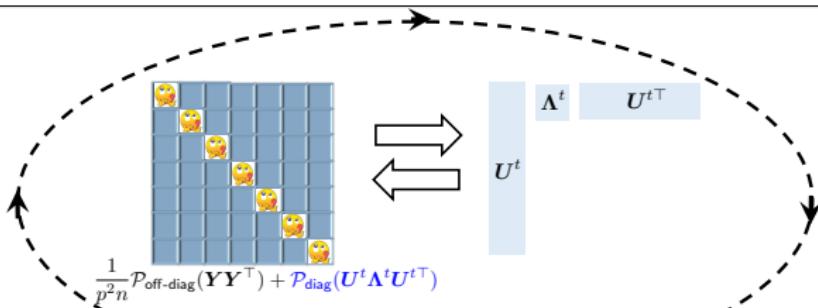
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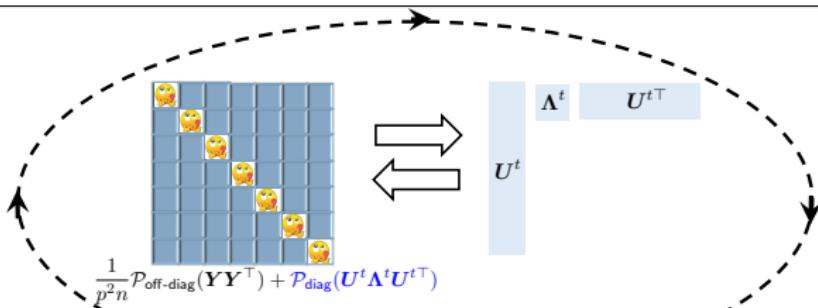


HeteroPCA (Zhang, Cai, Wu '18)



- **Initialize:** $\mathbf{G}^0 = \frac{1}{np^2} \mathcal{P}_{\text{off-diag}}(\mathbf{Y} \mathbf{Y}^\top)$
- **Iterative update:** for $t = 0, 1, \dots, t_0$
 $(\mathbf{U}^t, \Lambda^t) = \text{eigs}(\mathbf{G}^t, r)$
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- **Output:** $\mathbf{U} := \mathbf{U}^{t_0} \longrightarrow \text{estimate of } \mathbf{U}^*$
 $\mathbf{S} := \mathbf{U}^{t_0} \boldsymbol{\Lambda}^{t_0} \mathbf{U}^{t_0\top} \longrightarrow \text{estimate of } \mathbf{S}^* = \mathbf{U}^* \boldsymbol{\Lambda}^* \mathbf{U}^{*\top}$

Sharpened estimation guarantees for HeteroPCA

Assumptions (omitting log factors)

- rank $r = O(1)$, incoherence $\mu = O(1)$, cond. number $\kappa = O(1)$
- sampling rate exceeds certain threshold

$$p \gtrsim \max \left\{ \frac{1}{\sqrt{nd}}, \frac{1}{n} \right\}$$

- per-entry signal-to-noise ratio (SNR) cannot be too low:

$$\frac{\omega_{\max}^2}{\lambda_r(\mathbf{S}^\star)/d} \lesssim \min \left\{ pn, p\sqrt{nd} \right\}$$

Sharpened estimation guarantees for HeteroPCA

Theorem 1 (Yan, Chen, Fan '21)

With high prob., we have

$$\|\mathbf{U} \text{sgn}(\mathbf{U}^\top \mathbf{U}^*) - \mathbf{U}^*\| \lesssim \zeta_{\text{op}}, \quad \|\mathbf{U} \text{sgn}(\mathbf{U}^\top \mathbf{U}^*) - \mathbf{U}^*\|_{2,\infty} \lesssim \frac{1}{\sqrt{d}} \zeta_{\text{op}}$$
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where $\zeta_{\text{op}} := \frac{1}{\sqrt{ndp}} + \frac{\omega_{\max}^2}{p \lambda_r^*} \sqrt{\frac{d}{n}} + \sqrt{\frac{1}{np}} + \frac{\omega_{\max}}{\sqrt{\lambda_r^*}} \sqrt{\frac{d}{np}}$

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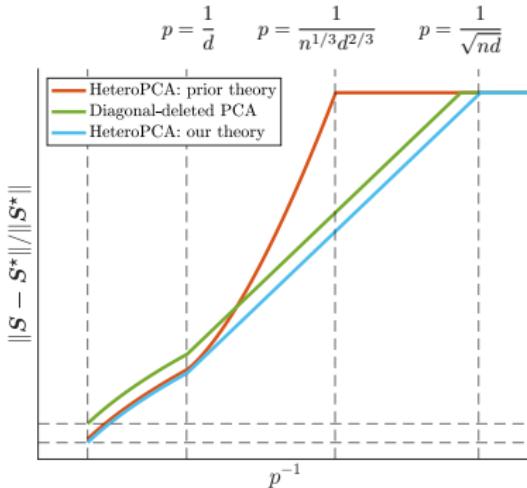
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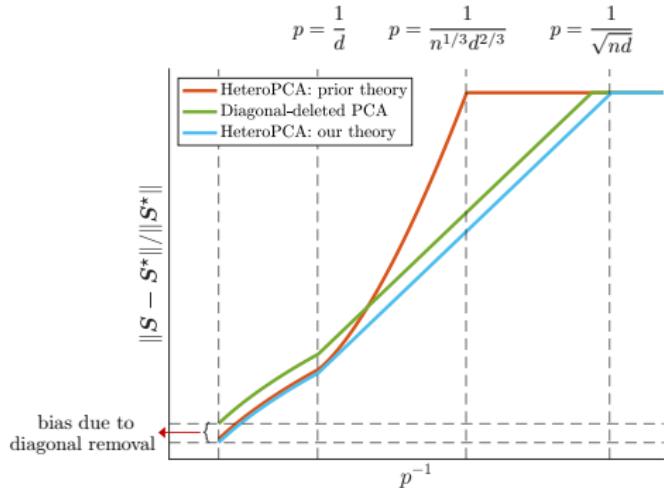
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- fine-grained estimation guarantees ($\ell_{2,\infty}$ and ℓ_∞ bounds)
- estimation errors are spread out across entries
- our sample size and SNR conditions are **minimax-optimal**
(in terms of achieving **consistent estimation**)

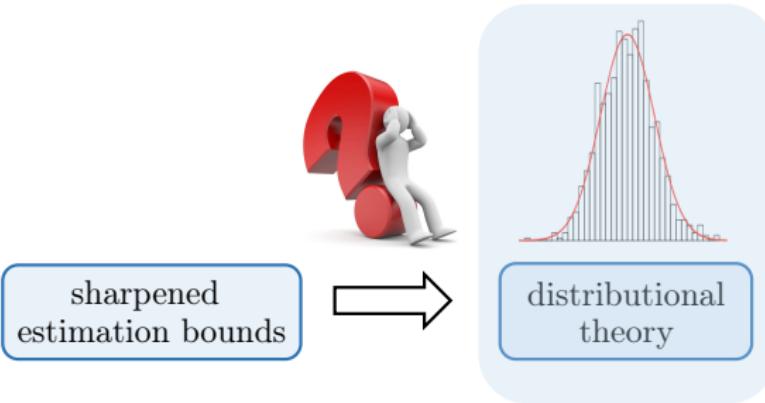
Sharpened estimation guarantees for HeteroPCA



Sharpened estimation guarantees for HeteroPCA



- diagonal-deleted PCA incurs some bias due to diagonal deletion
- HeteroPCA achieves bias correction via iterative refinement
method of choice
- first $\ell_{2,\infty}$ and ℓ_∞ theory for HeteroPCA



Given HeteroPCA is an appealing estimator, can we take one step further to obtain distributional characterizations?

Distributional theory for \mathbf{U}

Theorem 2 (Yan, Chen, Fan '21)

Consider any $1 \leq l \leq d$ s.t. $\|\mathbf{U}_{l,\cdot}^*\|_2$ is not too small. Under previous assumptions, we have

$$\sup_{\text{cvx set } \mathcal{C}} \left| \mathbb{P}\left(\left[\mathbf{U} \underbrace{\text{sgn}(\mathbf{U}^\top \mathbf{U}^*)}_{\text{global rotation}} - \mathbf{U}^* \right]_{l,\cdot} \in \mathcal{C} \right) - \mathcal{N}(\mathbf{0}, \Sigma_{U,l}^*) \{ \mathcal{C} \} \right| = o(1)$$

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- Each row of \mathbf{U} is approximately Gaussian
 - nearly unbiased + tractable covariance

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$$\Sigma_{U,l}^* := \left(\frac{1-p}{np} S_{l,l}^* + \frac{\omega_l^{*2}}{np} \right) (\Lambda^*)^{-1} + \frac{2(1-p)}{np} \mathbf{U}_{l,\cdot}^* \mathbf{U}_{l,\cdot}^*$$

$$+ (\Lambda^*)^{-1} \mathbf{U}^{*\top} \text{diag} \left\{ [d_{l,i}^*]_{1 \leq i \leq d} \right\} \mathbf{U}^* (\Lambda^*)^{-1}$$

$$d_{l,i}^* := \frac{1}{np^2} \left[\omega_l^{*2} + (1-p) S_{l,l}^{*2} \right] \left[\omega_i^{*2} + (1-p) S_{i,i}^{*2} \right] + \frac{2(1-p)^2}{np^2} S_{l,i}^{*2}$$

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- Key observations:

$$\mathbf{U} \text{sgn}(\mathbf{U}^\top \mathbf{U}^*) - \mathbf{U}^* \approx \left[\underbrace{\mathbf{E} \mathbf{X}^\top}_{\text{linear term}} + \underbrace{\mathcal{P}_{\text{off-diag}}(\mathbf{E} \mathbf{E}^\top)}_{\text{quadratic term}} \right] \mathbf{U}^* (\Lambda^*)^{-1}$$

Distributional theory for S

Theorem 3 (Yan, Chen, Fan '21)

Consider any (i, j) s.t. $\|U_{i,\cdot}^{\star}\|_2$ and $\|U_{j,\cdot}^{\star}\|_2$ are not too small. Under previous assumptions, we have

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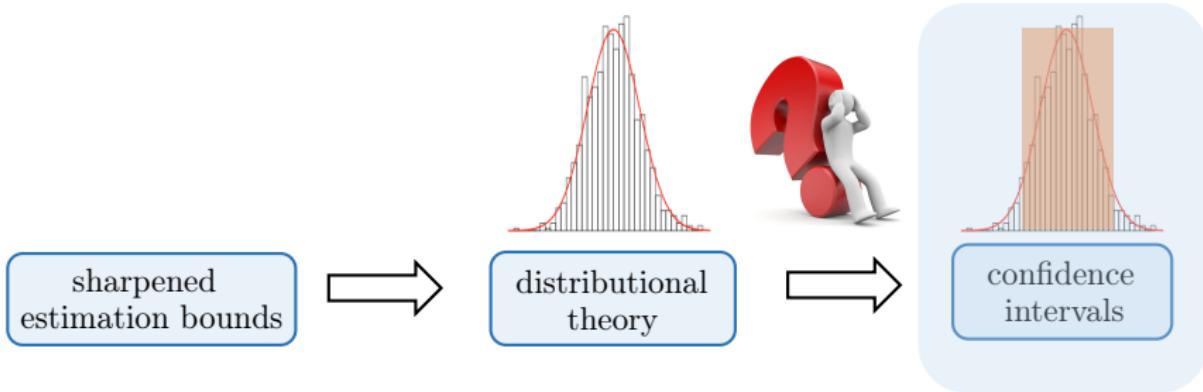
- Each entry of S is approximately Gaussian
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For any $i \neq j$:

$$v_{i,j}^{\star} := \frac{2-p}{np} S_{i,i}^{\star} S_{j,j}^{\star} + \frac{4-3p}{np} S_{i,j}^{\star 2} + \frac{1}{np} (\omega_i^{\star 2} S_{j,j}^{\star} + \omega_j^{\star 2} S_{i,i}^{\star}) + \frac{2(1-p)^2}{np^2} \left[\sum_{k=1}^d S_{i,k}^{\star 2} (U_{k,i}^{\star} U_{j,i}^{\star \top})^2 + S_{j,k}^{\star 2} (U_{k,j}^{\star} U_{i,k}^{\star \top})^2 \right] + \frac{1}{np^2} \sum_{k=1}^d [\omega_i^{\star 2} + (1-p) S_{i,i}^{\star}] [\omega_k^{\star 2} + (1-p) S_{k,k}^{\star}] (U_{k,i}^{\star} U_{j,k}^{\star \top})^2 + \frac{1}{np^2} \sum_{k=1}^d [\omega_j^{\star 2} + (1-p) S_{j,j}^{\star}] [\omega_k^{\star 2} + (1-p) S_{k,k}^{\star}] (U_{k,j}^{\star} U_{i,k}^{\star \top})^2$$

For any $1 \leq i \leq d$:

$$v_{i,i}^{\star} := \frac{12-9p}{np} S_{i,i}^{\star 2} + \frac{4}{np} \omega_i^{\star 2} S_{i,i}^{\star} + \frac{8(1-p)^2}{np^2} \sum_{k=1}^d S_{i,k}^{\star 2} (U_{k,i}^{\star} U_{i,i}^{\star \top})^2 + \frac{4}{np^2} \sum_{k=1}^d [\omega_i^{\star 2} + (1-p) S_{i,i}^{\star}] [\omega_k^{\star 2} + (1-p) S_{k,k}^{\star}] (U_{k,i}^{\star} U_{i,i}^{\star \top})^2$$



*How to compute confidence intervals in a data-driven manner
(e.g., without prior knowledge of noise levels)?*

Estimating unknown model parameters

- Compute estimate $(\mathbf{U}, \Lambda, \mathbf{S})$ for $(\mathbf{U}^*, \Lambda^*, \mathbf{S}^*)$ via HeteroPCA

¹ $\{y_{i,j} : (i, j) \in \Omega\}$ are zero-mean r.v.s with common variance $S_{i,i}^* + \omega_i^{*2}$

Estimating unknown model parameters

- Compute estimate $(\mathbf{U}, \Lambda, \mathbf{S})$ for $(\mathbf{U}^*, \Lambda^*, \mathbf{S}^*)$ via HeteroPCA
- Estimate noise variances $\{\omega_i^{*2}\}_{i=1}^d$ in a data-driven manner¹

$$\omega_i^2 := \frac{\sum_{j=1}^n y_{i,j}^2 \mathbb{1}_{(i,j) \in \Omega}}{\sum_{j=1}^n \mathbb{1}_{(i,j) \in \Omega}} - S_{i,i}$$

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- Compute “plug-in” estimate $v_{i,j}$ for $v_{i,j}^*$

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Entrywise confidence intervals for S^*

For any target coverage level $1 - \alpha$ and each (i, j) , compute

$$\text{CI}_{i,j}^{1-\alpha} := \left[S_{i,j} \pm \Phi^{-1}(1 - \alpha/2) \sqrt{v_{i,j}} \right]$$

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Suppose previous conditions hold and $\frac{\omega_{\max}}{\omega_{\min}} = O(1)$. Then we have

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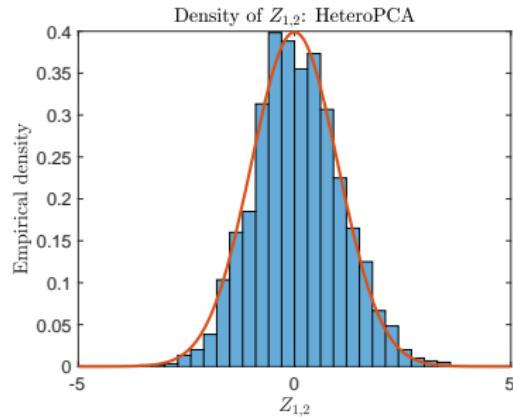
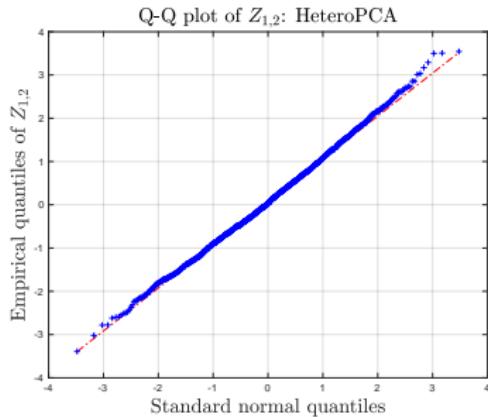
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- adaptive to unknown noise levels
- adaptive to noise heteroskedasticity

Numerical verification



$n = 2000, d = 100, p = 0.6, r = 3, \omega_1^*, \dots, \omega_d^* \stackrel{\text{i.i.d.}}{\sim} \text{Unif}[0.025, 0.1],$

$$Z_{1,2} = \frac{S_{1,2} - S_{1,2}^*}{\sqrt{v_{1,2}}}$$

Concluding remarks

- Missing data and heterogeneous noise require special treatment
- HeteroPCA is $\underbrace{\text{provably effective}}_{\text{minimax optimal in some sense}}$ for estimation & inference

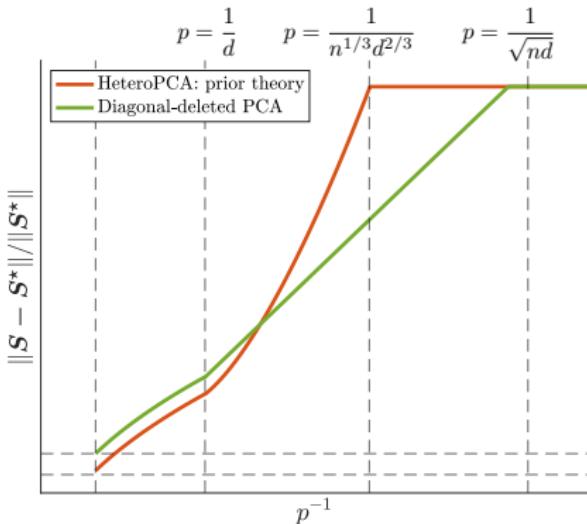
papers:

Y. Yan, Y. Chen, J. Fan, “Inference for Heteroskedastic PCA with Missing Data,” arxiv:2107.12365, 2021

C. Cai, G. Li, Y. Chi, H. V. Poor, Y. Chen, “Subspace Estimation from Unbalanced and Incomplete Data Matrices: $\ell_{2,\infty}$ Statistical Guarantees,” *Annals of Statistics*, 2021

Backup slides

prior theory
(noiseless, $n > d$)



	$\ \cdot\ $ estimation error bounds	min sample size requirement
HeteroPCA (Zhang et al. '18)	$\frac{1}{\sqrt{nd^2p^3}} + \frac{1}{\sqrt{np}}$	$n^{\frac{2}{3}}d^{\frac{1}{3}}$
diagonal-deleted PCA (Cai et al. 19)	$\frac{1}{\sqrt{ndp^2}} + \frac{1}{\sqrt{np}} + \frac{1}{d}$	\sqrt{nd}