

# **Untold Gifts of Statistical Asymmetry to Eigen-analysis**



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Electrical Engineering, Princeton University



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Stanford



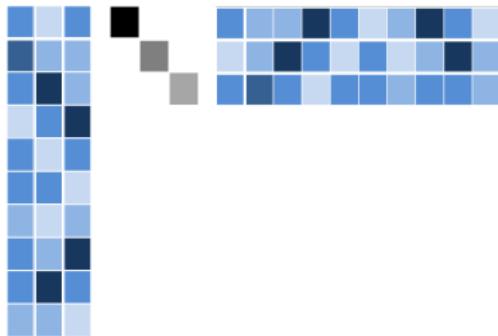
Yuting Wei  
CMU



Jianqing Fan  
Princeton

# Eigen-analysis in high dimension

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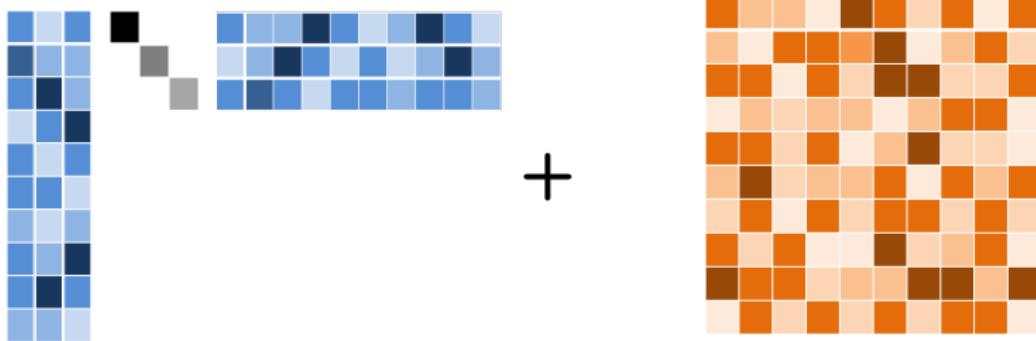


$M^*$ : low-rank matrix

- Rank- $r$  matrix:  $M^* = \sum_{l=1}^r \lambda_l^* \mathbf{u}_l^* \mathbf{u}_l^{*\top} \in \mathbb{R}^{n \times n}$

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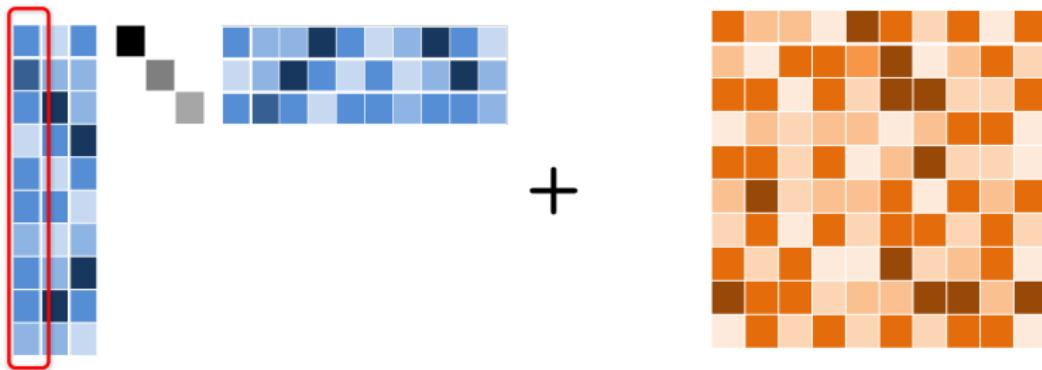


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$\mathbf{H} = [H_{ij}]_{1 \leq i,j \leq n}$ : independent noise

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- Observed noisy data:  $\mathbf{M} = \mathbf{M}^* + \mathbf{H}$
- **Goal:** estimate / infer unknown eigenvector  $\mathbf{u}_l^*$  ( $1 \leq l \leq r$ )

## A small sample of prior work

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- Davis, Kahan '70
- Wedin '72
- Péché '06
- Vu '11
- Yu, Wang, Samworth '14
- Chen, Wainwright '15
- Wang '15
- Cai, Zhang '18
- Zhong '17
- Keshavan, Montanari, Oh '09
- O'Rourke, Vu, Wang '18
- Bryc, Silverstein '18
- Zhang, Cai, Wu '18
- Cai, Li, Chi, Poor, Chen '19
- ...

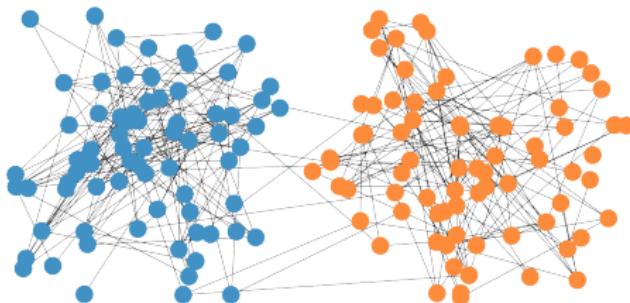
A large body of prior work focused on  $\ell_2$  analysis (e.g.  $\|\mathbf{u}_l - \mathbf{u}_l^*\|_2$ )

# Beyond $\ell_2$ analysis: “fine-grained” statistical analysis

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**Entrywise** eigenvector analysis:

- estimation and inference for each entry of  $u_l^*$



graph clustering (stochastic block model)

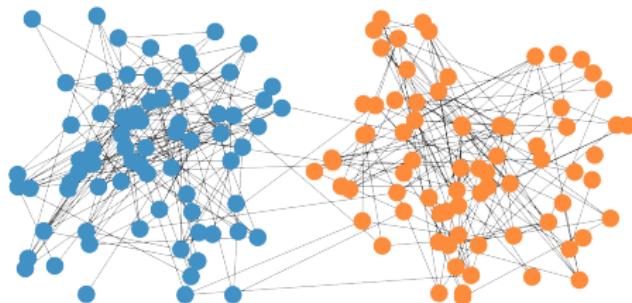
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ranking from pairwise comparisons

- Chen, Fan, Ma, Wang '17

## Beyond $\ell_2$ analysis: “fine-grained” statistical analysis

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More generally, estimate & infer **linear functions of eigenvectors**

$$\mathbf{a}^\top \mathbf{u}_l^*, \text{ with } \mathbf{a} \text{ a fixed vector}$$

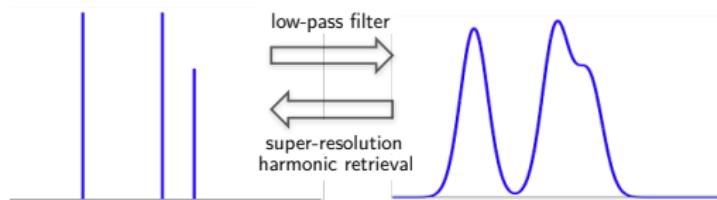
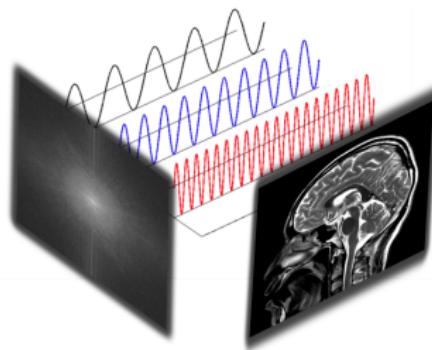
- e.g. entrywise analysis:  $\mathbf{a} = \mathbf{e}_i$  (i.e.  $\mathbf{a}^\top \mathbf{u}_l^* = u_{l,i}^*$ )

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$$\mathbf{a}^\top \mathbf{u}_l^*, \text{ with } \mathbf{a} \text{ a fixed vector}$$

- e.g. entrywise analysis:  $\mathbf{a} = \mathbf{e}_i$  (i.e.  $\mathbf{a}^\top \mathbf{u}_l^* = u_{l,i}^*$ )
- e.g. Fourier coefficients of eigenvectors:  $\mathbf{a} = \mathbf{f}_i$  (Fourier basis)



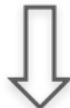
— Hua, Sarkar '90, Candès, Fernandez-Granda '12, Chen, Chi '14

# Challenge: plug-in estimator?

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— goal: estimate  $a^\top u_l^*$

compute an estimator  $\hat{u}_l$  for  $u_l^*$

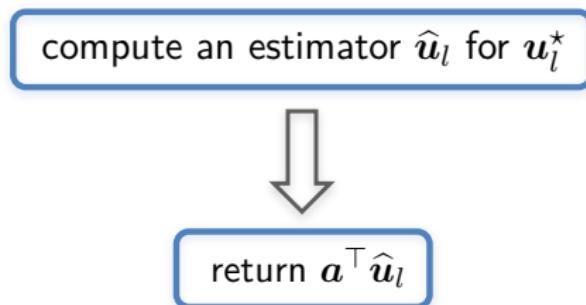


return  $a^\top \hat{u}_l$

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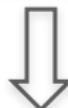
**Issue:** insufficiency of  $\ell_2$  analysis

$$\underbrace{|\mathbf{a}^\top \hat{\mathbf{u}}_l - \mathbf{a}^\top \mathbf{u}_l^*|}_{\text{target estimation risk}} \leq \|\mathbf{a}\|_2 \cdot \underbrace{\|\hat{\mathbf{u}}_l - \mathbf{u}_l^*\|_2}_{\text{invoke prior } \ell_2 \text{ bounds}}$$

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- highly suboptimal (could be  $\tilde{O}(\sqrt{n})$  times larger than true risk)!

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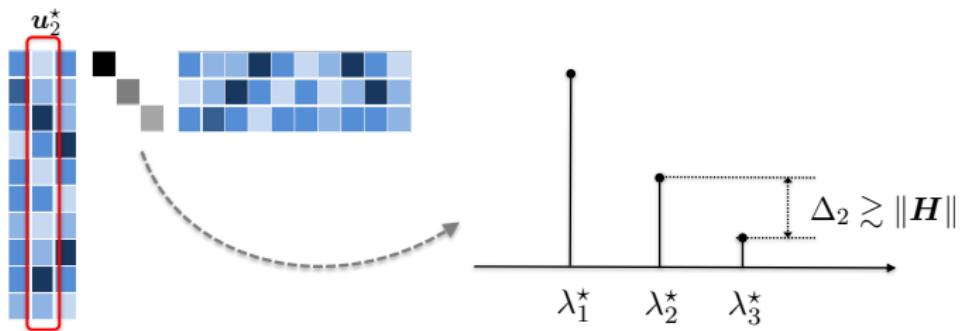


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**Issue:** non-negligible bias

- even when *each entry of  $\hat{u}_l$*  is nearly unbiased, the plug-in estimator might suffer from systematic bias

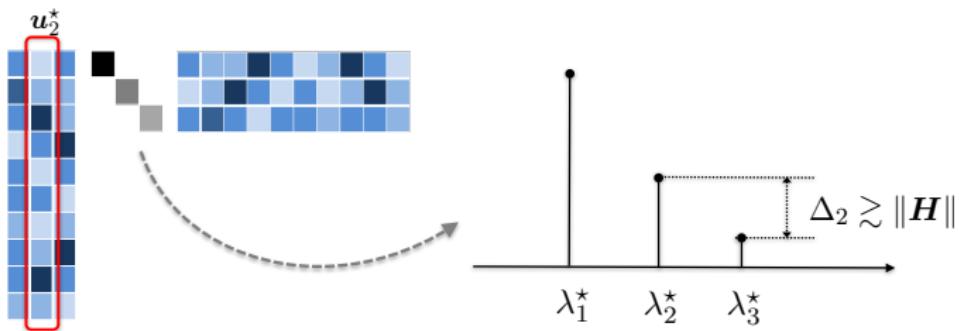
# Challenge: stringent e-value separation requirement



To faithfully estimate  $u_l^*$ , generic linear algebra typically requires

$$\text{(eigenvalue separation)} \quad \Delta_l := \min_{k:k \neq l} |\lambda_l^* - \lambda_k^*| \gtrsim \|H\|$$

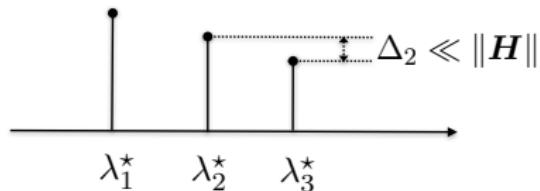
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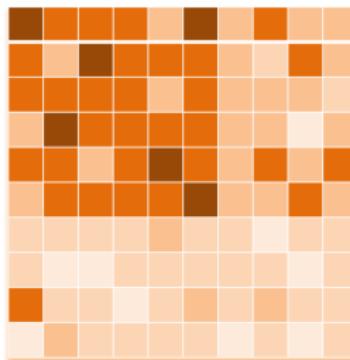
What if  $\Delta_l \ll \|\mathbf{H}\|$ ?



## Challenge: noise heteroscedasticity

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$$\begin{bmatrix} \text{Var}(H_{11}) & \cdots & \text{Var}(H_{1n}) \\ \vdots & \ddots & \vdots \\ \text{Var}(H_{n1}) & \cdots & \text{Var}(H_{nn}) \end{bmatrix}$$



Noise variance might vary across locations, which are *a priori* unknown

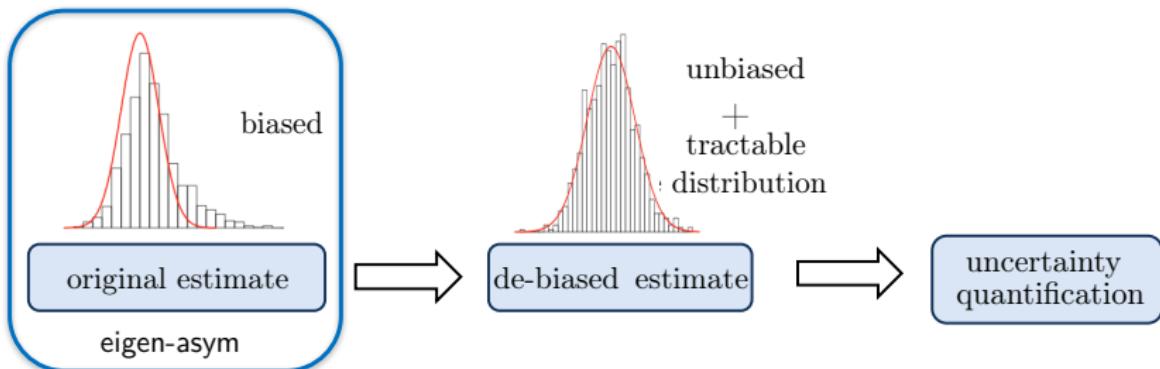
*This talk: estimation & inference for linear forms of eigenvectors  
(& eigenvalues) under independent noise*

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- effective under minimal eigenvalue separation
- distribution-free
- adaptive to noise heteroscedasticity
- optimal (in some sense)

# Outline

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- **Estimation (eigen-decomposition w/o symmetrization)**
- Inference (de-biasing and confidence intervals)

# Model: independent noise

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$$M = \underbrace{\sum_{l=1}^r \lambda_l^* u_l^* u_l^{*\top}}_{\text{symmetric low-rank}} + H$$

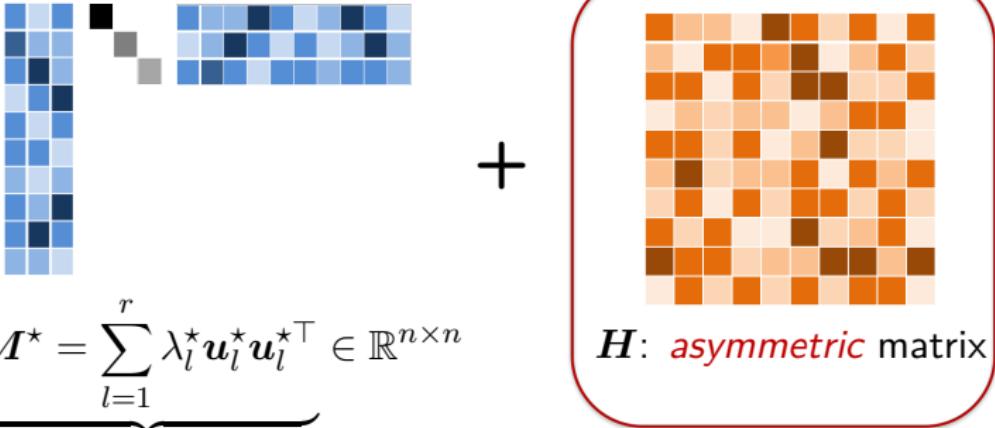
The diagram illustrates the matrix decomposition. On the left, a tall, narrow matrix  $M$  is shown as a vertical column of blue and dark blue squares. To its right is a plus sign. Next is a horizontal row of three matrices: a small 2x2 matrix with one black square and one grey square, followed by a larger 8x8 matrix with a similar pattern of black and grey squares, and finally a 16x16 matrix where each 4x4 block contains a 2x2 pattern of orange and brown squares. To the right of the plus sign is the label  $H$ : noise matrix.

- **independent entries:**  $\{H_{i,j}\}$  are independent
- **zero mean:**  $\mathbb{E}[H_{i,j}] = 0$
- **variance:**  $\sigma_{\min}^2 \leq \text{Var}(H_{i,j}) \leq \sigma_{\max}^2$

# Model: independent noise $\rightarrow$ asymmetric data

$$M = \underbrace{M^* + H}_{\text{symmetric low-rank}} + H$$

$M^* = \sum_{l=1}^r \lambda_l^* u_l^* u_l^{*\top} \in \mathbb{R}^{n \times n}$



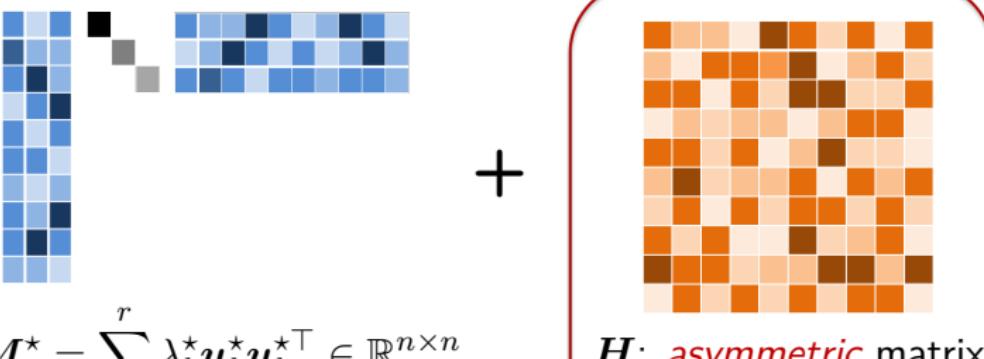
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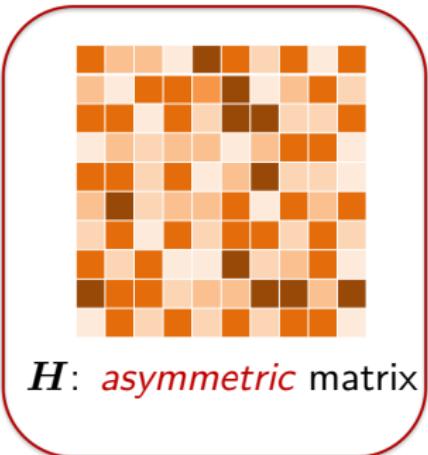
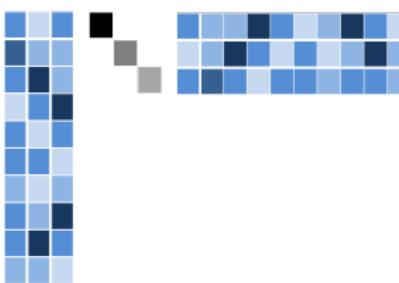
where  $M^* = \sum_{l=1}^r \lambda_l^* u_l^* u_l^{*\top} \in \mathbb{R}^{n \times n}$

$H$ : **asymmetric** matrix



This may arise when, e.g., we have 2 samples for each entry of  $M^*$  and arrange them asymmetrically

# A natural strategy: symmetrization + eigen-decomposition

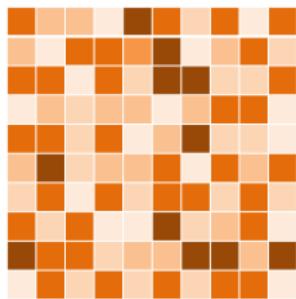
$$M = \underbrace{M^*}_{\text{symmetric}} + H$$
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- Use  $l^{\text{th}}$  eigenvector of  $\frac{1}{2}(M + M^\top)$  to estimate  $u_l^*$
- Use  $l^{\text{th}}$  eigenvalue of  $\frac{1}{2}(M + M^\top)$  to estimate  $\lambda_l^*$

# A less popular strategy: eigen-decomposition w/o symmetrization

$$M = \underbrace{\sum_{l=1}^r \lambda_l^* u_l^* u_l^{*\top}}_{\text{symmetric}} + H$$

+



$H$ : **asymmetric** matrix

- Use  $l^{\text{th}}$  eigenvector of  $\frac{1}{2}(M + M^\top)$   $M$  to estimate  $u_l^*$
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# Symmetrize or not?

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eigen-sym: eigen-decomposition w/ symmetrization

eigen-asym: eigen-decomposition w/o symmetrization

- Numerical stability

eigen-sym > eigen-asym

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$$\text{eigen-sym} \quad > \quad \text{eigen-asym}$$

- **(Folklore?)** Statistical accuracy

$$\text{eigen-sym} \quad \asymp \quad \text{eigen-asym}$$

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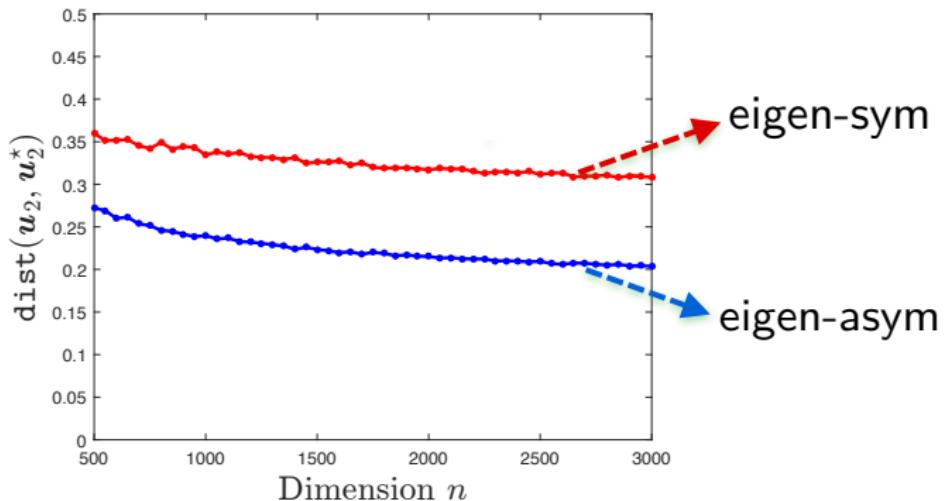
- **(Folklore?)** Statistical accuracy

eigen-sym  $\asymp$  eigen-asym

Shall we always symmetrize data before eigen-decomposition?

## Numerical experiments: heteroscedastic Gaussian noise

- $M = \mathbf{u}_1^* \mathbf{u}_1^{*\top} + 0.95 \mathbf{u}_2^* \mathbf{u}_2^{*\top} + \mathbf{H}$
- $\mathbf{u}_1^* = \frac{1}{\sqrt{n}} \begin{bmatrix} \mathbf{1}_{n/2} \\ \mathbf{1}_{n/2} \end{bmatrix}; \mathbf{u}_2^* = \frac{1}{\sqrt{n}} \begin{bmatrix} \mathbf{1}_{n/2} \\ -\mathbf{1}_{n/2} \end{bmatrix}$
- $[\text{Var}(H_{ij})]_{i,j} \approx \frac{1}{2n \log n} \left( \begin{bmatrix} \mathbf{1}\mathbf{1}^\top & \mathbf{0} \\ \mathbf{0} & \mathbf{0} \end{bmatrix} + \frac{1}{100} \mathbf{1}\mathbf{1}^\top \right)$



# Numerical experiments: matrix completion

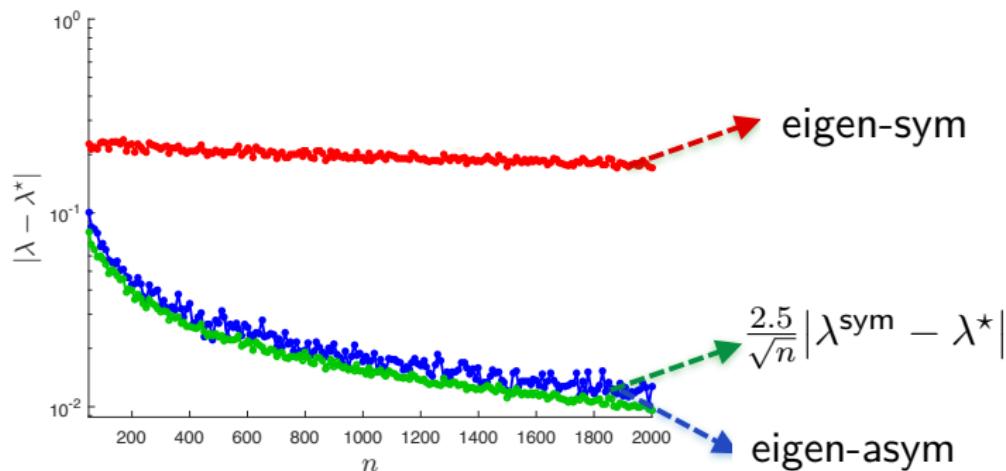
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$$M^* = \mathbf{u}^* \mathbf{u}^{*\top}; \quad M_{i,j} = \begin{cases} \frac{1}{p} M_{i,j}^* & \text{with prob. } p, \\ 0, & \text{else,} \end{cases} \quad p = \frac{3 \log n}{n}$$

$$\begin{bmatrix} \checkmark & ? & ? & ? & \checkmark & ? \\ ? & ? & \checkmark & \checkmark & ? & ? \\ \checkmark & ? & ? & \checkmark & ? & ? \\ ? & ? & \checkmark & ? & ? & \checkmark \\ \checkmark & ? & ? & ? & ? & ? \\ ? & \checkmark & ? & ? & \checkmark & ? \end{bmatrix}$$

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*Why does eigen-decomposition w/o symmetrization work better?*

# Problem setup

---

observed:  $\mathbf{M} = \underbrace{\sum_{l=1}^r \lambda_l^* \mathbf{u}_l^* \mathbf{u}_l^{*\top}}_{\mathbf{M}^*} + \mathbf{H} \in \mathbb{R}^{n \times n}$

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  - **magnitudes:**  $|H_{i,j}| \leq \sigma_{\max} \sqrt{n / \log n}$  with high prob.
- $\mathbf{M}^*$  obeys incoherence condition

$$\max_{1 \leq l \leq r} \|\mathbf{u}_l^*\|_\infty \leq \sqrt{\mu/n}$$

## Review: classical *eigenvalue* perturbation results

---

$$|\lambda_l^{\text{sym}} - \lambda_l^*| \leq \left\| \frac{1}{2}(\mathbf{H} + \mathbf{H}^\top) \right\| \quad (\text{Weyl})$$

$$|\lambda_l^{\text{asym}} - \lambda_l^*| \leq \|\mathbf{H}\| \quad (\text{Bauer-Fike})$$

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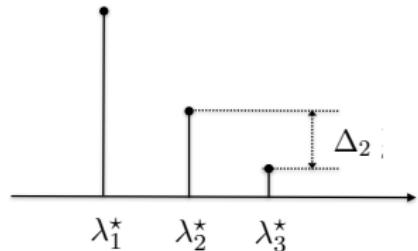
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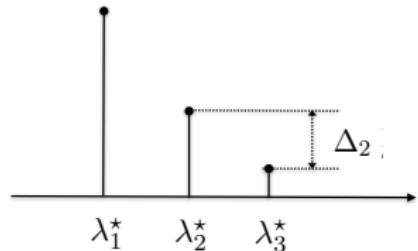
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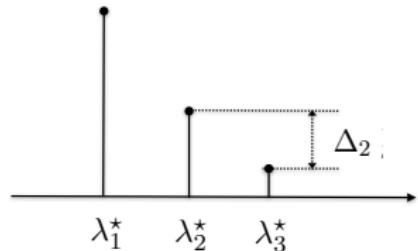


$$\min \|u_l^{\text{sym}} \pm u_l^*\|_2 \lesssim \frac{\|\mathbf{H} + \mathbf{H}^\top\|}{\Delta_l} \quad (\text{Davis-Kahan})$$

$$\min \|u_l^{\text{asym}} \pm u_l^*\|_2 \lesssim ??$$

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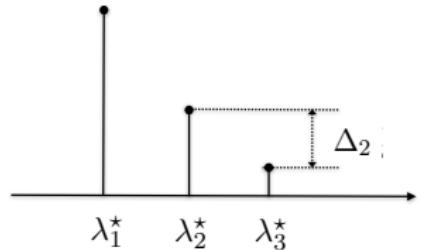
↓ matrix concentration inequality

$$\min \|u_l^{\text{sym}} \pm u_l^*\|_2 \lesssim \frac{\sigma_{\max} \sqrt{n}}{\Delta_l} \quad (\text{requires } \Delta_l \gtrsim \|\mathbf{H} + \mathbf{H}^\top\|)$$

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# Main results: eigenvalue / eigenvector perturbation

(eigenvalue separation)  $\Delta_l := \min_{k:k \neq l} |\lambda_l^* - \lambda_k^*|$



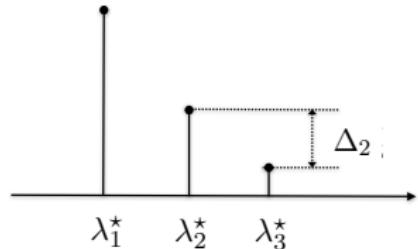
## Theorem 1 (Cheng, Wei, Chen '20)

Suppose  $M^*$  is well-conditioned, incoherent, and  $r = O(1)$ . Assume

$$\Delta_l > 2c_0\sigma_{\max}\sqrt{\log n} \quad \text{for some const } c_0 > 0 \quad (1)$$

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With high prob.,  $l^{th}$  largest e-value  $\lambda_l^{\text{asym}}$  & e-vector  $u_l^{\text{asym}}$  of  $M$  obey

$$|\lambda_l^{\text{asym}} - \lambda_l^*| \leq c_0\sigma_{\max}\sqrt{\log n}$$

$$\min \|u_l^{\text{asym}} \pm u_l^*\|_2 \lesssim \frac{\sigma_{\max}\sqrt{\log n}}{\Delta_l^*} + \frac{\sigma_{\max}\sqrt{n \log n}}{\|M^*\|}$$

## Eigen-sym vs. eigen-asym

---

1. **eigenvalue estimation:** eigen-asym is  $\tilde{O}(\sqrt{n})$  times more accurate

$$|\lambda_l^{\text{sym}} - \lambda_l^*| \lesssim \sigma_{\max} \sqrt{n} \quad (\text{Weyl})$$

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2. **eigenvector estimation:** eigen-asym works under  $\tilde{O}(\sqrt{n})$  times smaller eigenvalue separation

$$\min \|u_l^{\text{sym}} \pm u_l^*\| = o(1) \quad \text{if } \Delta_l \gtrsim \sigma_{\max} \sqrt{n} \quad (\text{Davis-Kahan})$$

$$\min \|u_l^{\text{asym}} \pm u_l^*\| = o(1) \quad \text{if } \Delta_l \gtrsim \sigma_{\max} \sqrt{\log n} \quad (\text{ours})$$

## Main results: entrywise eigenvector perturbation

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### Theorem 2 (Cheng, Wei, Chen '20)

*Under same assumptions as in Theorem 1, with high prob. one has*

$$\min \|\mathbf{u}_l^{\text{asym}} \pm \mathbf{u}_l^{\star}\|_{\infty} \lesssim \frac{\sigma_{\max} \sqrt{\log n}}{\|\mathbf{M}^{\star}\|} + \frac{\sigma_{\max}}{\Delta_l} \sqrt{\frac{\log n}{n}}$$

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- $\ell_\infty$  perturbation is well-controlled (i.e.  $\frac{\min \|\mathbf{u}_l^{\text{asym}} \pm \mathbf{u}_l^*\|_\infty}{\|\mathbf{u}_l^*\|_\infty} \ll 1$ ) even under very small eigenvalue separation (i.e.  $\Delta_l \asymp \sigma_{\max} \sqrt{\log n}$ )

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- no available  $\ell_{\infty}$  guarantees for  $\mathbf{u}_l^{\text{sym}}$  if  $\Delta_l \ll \sigma_{\max} \sqrt{n}$

# Intuition: asymmetry reduces bias (rank-1, i.i.d. noise)

---

From Neumann series one can verify

some sort of Taylor expansion

$$|\lambda_1 - \lambda_1^*| \asymp \left| \frac{\mathbf{u}_1^{*\top} \mathbf{H} \mathbf{u}_1^*}{\lambda} + \frac{\mathbf{u}_1^{*\top} \mathbf{H}^2 \mathbf{u}_1^*}{\lambda^2} + \frac{\mathbf{u}_1^{*\top} \mathbf{H}^3 \mathbf{u}_1^*}{\lambda^3} + \dots \right|$$

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- if  $\mathbf{H}$  is symmetric,

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- if  $\mathbf{H}$  is asymmetric,

$$\underbrace{\mathbb{E}[\mathbf{u}_1^{*\top} \mathbf{H}^2 \mathbf{u}_1^*] = \mathbb{E}[\langle \mathbf{H}^\top \mathbf{u}_1^*, \mathbf{H} \mathbf{u}_1^* \rangle]}_{\text{significantly smaller bias than symmetric case}} = \sigma^2$$

## Summary of main features of eigen-asym

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- much higher e-value estimation accuracy
- faithful e-vector estimation under much smaller e-value separation
- distribution-free
- adaptive to heteroscedastic noise

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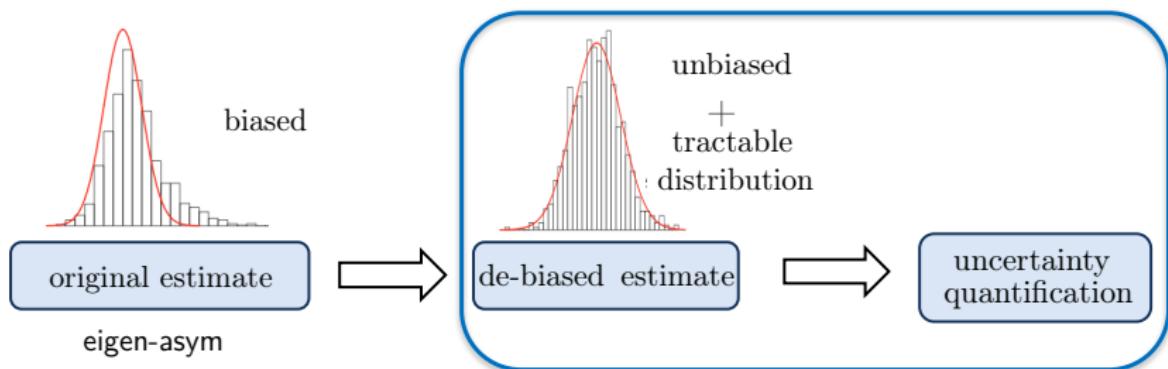
---

- much higher e-value estimation accuracy
- faithful e-vector estimation under much smaller e-value separation
- distribution-free
- adaptive to heteroscedastic noise

Statistical asymmetry implicitly **suppresses estimation bias**,  
which empowers eigen-decomposition!

# Outline

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- Estimation (eigen-decomposition w/o symmetrization)
- **Inference (de-biasing and confidence intervals)**

# Notation

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— let's drop superscript "asym" to simplify notation

- $\lambda_l$ :  $l^{\text{th}}$  eigenvalue of  $M$
- $u_l$ :  $l^{\text{th}}$  **right** eigenvector of  $M$  obeying  $u_l^\top u_l^* \geq 0$
- $w_l$ :  $l^{\text{th}}$  **left** eigenvector of  $M$  obeying  $w_l^\top u_l^* \geq 0$

As we shall see, it's crucial to employ  $u_l$  and  $w_l$  simultaneously

# Which estimator shall we use?

---

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## Issues:

- **bias aggregation:** even though  $\mathbf{u}_l$  is nearly unbiased estimate of  $\mathbf{u}_l^*$  in every entry, it does NOT mean  $\mathbf{a}^\top \mathbf{u}_l$  is nearly unbiased
- **optimality?** it is unclear whether  $\mathbf{a}^\top \mathbf{u}_l$  incurs minimal uncertainty

## Key observations (rank-1 case)

---

From Neumann's series:

$$\mathbf{a}^\top \mathbf{u}_1 \approx (\mathbf{u}_1^{\star\top} \mathbf{u}_1) \left\{ \mathbf{a}^\top \mathbf{u}_1^\star + \frac{1}{\lambda_1^\star} \mathbf{a}^\top \mathbf{H} \mathbf{u}_1^\star + \frac{1}{\lambda_1^{\star 2}} \mathbf{a}^\top \mathbf{H}^2 \mathbf{u}_1^\star + \cdots \right\}$$

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$$\Downarrow \quad (\mathbf{u}_1^{\star\top} \mathbf{u}_1 \approx 1)$$

- If  $\mathbf{a}^\top \mathbf{u}_1^\star$  is small, then

$$\mathbf{a}^\top \mathbf{u}_1 \approx \mathbf{a}^\top \mathbf{u}_1^\star + \frac{\mathbf{a}^\top \mathbf{H} \mathbf{u}_1^\star}{\lambda_1^\star} + (\mathbf{u}_1^{\star\top} \mathbf{u}_1 - 1) \left\{ \mathbf{a}^\top \mathbf{u}_1^\star + \frac{\mathbf{a}^\top \mathbf{H} \mathbf{u}_1^\star}{\lambda_1^\star} \right\}$$

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$\implies \mathbf{a}^\top \mathbf{u}_1$  is nearly unbiased estimate of  $\mathbf{a}^\top \mathbf{u}_1^{\star}$

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- **problem:**  $\mathbf{a}^\top \mathbf{u}_1$  significantly under-estimates  $\mathbf{a}^\top \mathbf{u}_1^\star$ ;
- **bias correction:** estimate  $\mathbf{u}_1^{\star\top} \mathbf{u}_1$  and use it to adjust  $\mathbf{a}^\top \mathbf{u}_1$

## Our estimator for $\mathbf{a}^\top \mathbf{u}_l^*$

---

$$\left\{ \begin{array}{l} \mathbf{a}^\top \mathbf{u}_l \approx \mathbf{a}^\top \mathbf{u}_l^* + \frac{\mathbf{a}^\top \mathbf{H} \mathbf{u}_l^*}{\lambda_l^*} \end{array} \right.$$

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$$\hat{u}_{\mathbf{a},l} = \underbrace{\frac{1}{2}(\mathbf{a}^\top \mathbf{u}_l + \mathbf{a}^\top \mathbf{w}_l)}_{\text{average them to reduce uncertainty}}$$

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$$\hat{u}_{\mathbf{a},l} = \sqrt{\frac{1}{\mathbf{u}_l^\top \mathbf{w}_l} (\mathbf{a}^\top \mathbf{u}_l)(\mathbf{a}^\top \mathbf{w}_l)} \quad (\text{use } \mathbf{u}_l^\top \mathbf{w}_l \text{ to estimate } (\mathbf{u}_l^{*\top} \mathbf{u}_l)(\mathbf{u}_l^{*\top} \mathbf{w}_l))$$

## Problem setup

---

observed:  $\mathbf{M} = \underbrace{\sum_{l=1}^r \lambda_l^* \mathbf{u}_l^* \mathbf{u}_l^{*\top}}_{\mathbf{M}^*} + \mathbf{H} \in \mathbb{R}^{n \times n}$

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- $\mathbf{H}$ : noise matrix
  - **independent entries:**  $\{H_{i,j}\}$  are independent
  - **zero mean:**  $\mathbb{E}[H_{i,j}] = 0$
  - **variance:**  $\sigma_{\min}^2 \leq \text{Var}(H_{i,j}) \leq \sigma_{\max}^2 \ll \frac{(\lambda_{\min}^*)^2}{n \log n}$  with  $\frac{\sigma_{\max}}{\sigma_{\min}} = O(1)$
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  - **magnitudes:**  $|H_{i,j}| \leq \sigma_{\max} \sqrt{n / \log n}$  with high prob.
- $\mathbf{M}^*$  obeys incoherence condition

$$\max_{1 \leq l \leq r} \|\mathbf{u}_l^*\|_\infty \leq \sqrt{\mu/n}$$

# Main results: distributional theory

---

- $M^*$  is well-conditioned, incoherent, and  $r = O(1)$
- $\left\{ \frac{1}{\|\mathbf{a}\|_2} |\mathbf{a}^\top \mathbf{u}_l^*| = o\left(\frac{1}{\sqrt{\log n}} \min\left\{\frac{\Delta_l^*}{|\lambda_l^*|}, 1\right\}\right) \text{ (size of target quantity)} \right.$
- $\left. \frac{1}{\|\mathbf{a}\|_2} |\mathbf{a}^\top \mathbf{u}_k^*| = o\left(\frac{1}{\sqrt{\log n}} \frac{|\lambda_l^* - \lambda_k^*|}{|\lambda_l^*|}\right), \quad \forall k \neq l \quad \text{(size of "interferers")} \right.$
- $\sigma_{\max} \log n = o(\Delta_l^*) \quad \text{(minimal e-value separation)}$

## Theorem 3 (Cheng, Wei, Chen '20)

Under above assumptions, with high prob. one has

$$\hat{u}_{\mathbf{a},l} \approx \mathbf{a}^\top \mathbf{u}_l^* + \frac{1}{2\lambda_l^*} \mathbf{a}^\top (\mathbf{H} + \mathbf{H}^\top) \mathbf{u}_l^*$$

# Distributional theory → confidence intervals

---

$$\hat{u}_{\mathbf{a},l} \approx \mathbf{a}^\top \mathbf{u}_l^* + \underbrace{\frac{1}{2\lambda_l^*} \mathbf{a}^\top (\mathbf{H} + \mathbf{H}^\top) \mathbf{u}_l^*}_{\text{approximately } \mathcal{N}(0, v_{\mathbf{a},l}^*)}$$

- $\hat{u}_{\mathbf{a},l}$ : unbiased estimator for  $\mathbf{a}^\top \mathbf{u}_l^*$

# Distributional theory → confidence intervals

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$$\hat{u}_{\mathbf{a},l} \approx \mathbf{a}^\top \mathbf{u}_l^* + \underbrace{\frac{1}{2\lambda_l^*} \mathbf{a}^\top (\mathbf{H} + \mathbf{H}^\top) \mathbf{u}_l^*}_{\text{approximately } \mathcal{N}(0, v_{\mathbf{a},l}^*)}$$

- $\hat{u}_{\mathbf{a},l}$ : unbiased estimator for  $\mathbf{a}^\top \mathbf{u}_l^*$
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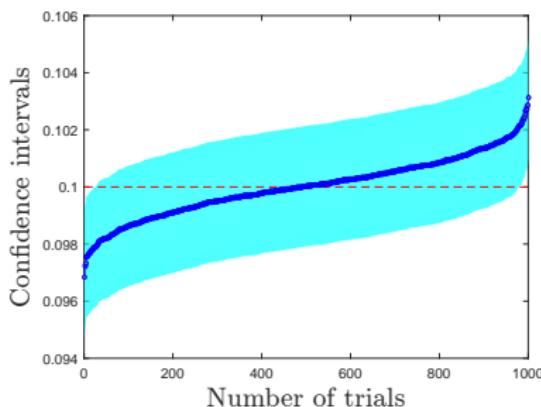
# Numerics: estimating $\mathbf{a}^\top \mathbf{u}_2^*$

- rank-2:  $\lambda_1^* = 1$ ,  $\lambda_2^* = 0.95$ ,  $\mathbf{a}^\top \mathbf{u}_1^* = 0$ ,  $\mathbf{a}^\top \mathbf{u}_2^* = 0.1$

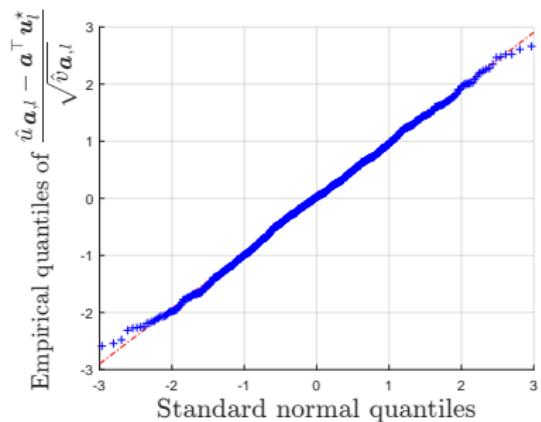
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$$\begin{bmatrix} \sigma_1^2 \\ (\sigma_1 + \delta_\sigma)^2 \\ \vdots \\ (\sigma_1 + (n-1)\delta_\sigma)^2 \end{bmatrix} \mathbf{1}_n^\top$$



95% confidence intervals



Q-Q (quantile-quantile) plot

## Numerics: estimating $a^\top u_2^*$

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Recall that our theory requires control of the “interferers”  $\{a^\top u_k^*\}_{k \neq l}$

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Numerically, it does seem that these “interferers” cannot be too large

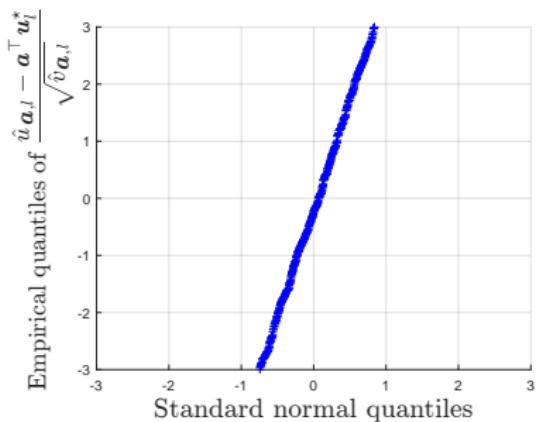
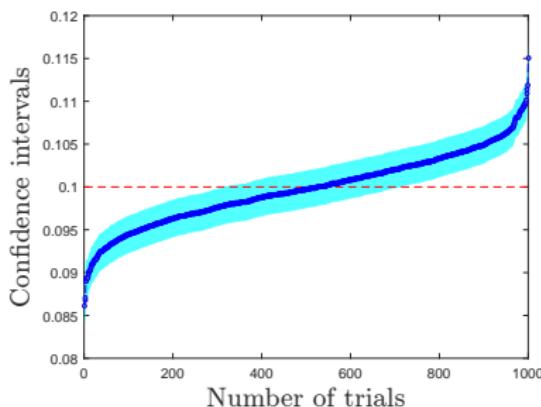
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- $M^*$  is well-conditioned, incoherent, and  $r = O(1)$
- $\sigma_{\max} \log n = o(\Delta_l^*)$  (minimal e-value separation)

## Theorem 4 (Cheng, Wei, Chen '20)

*Under above assumptions, with high prob. one has*

$$\lambda_l \approx \lambda_l^* + \mathbf{u}_l^{*\top} \mathbf{H} \mathbf{u}_l^*$$

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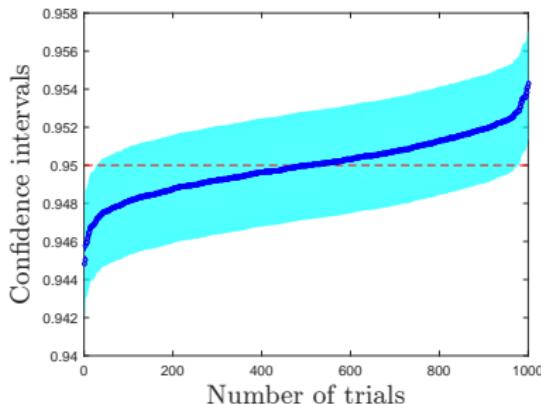
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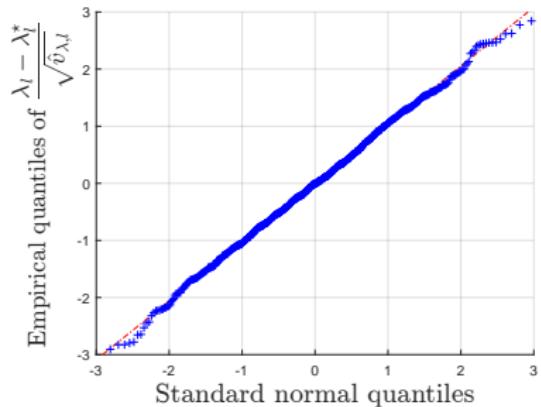
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numerical coverage



Q-Q (quantile-quantile) plot

*Can we further shorten our confidence intervals?*

# Cramer-Rao lower bound

- $H_{ij} \stackrel{\text{i.i.d.}}{\sim} \mathcal{N}(0, \sigma^2)$
- $\mathbf{a}^\top \mathbf{u}_l^* = o(1)$

## Theorem 5 (Cheng, Wei, Chen '20)

Any unbiased estimator  $\hat{U}_{\mathbf{a}}$  of  $\mathbf{a}^\top \mathbf{u}_l^*$  obeys

$$\text{Var}[\hat{U}_{\mathbf{a}}] \geq (1 - o(1)) \text{Var}\left(\frac{1}{2\lambda_l^*} \mathbf{a}(\mathbf{H} + \mathbf{H}^\top) \mathbf{u}_l^*\right)$$

- in comparison, our estimator obeys

$$\hat{u}_{\mathbf{a},l} \approx \mathbf{a}^\top \mathbf{u}_l^* + \frac{1}{2\lambda_l^*} \mathbf{a}(\mathbf{H} + \mathbf{H}^\top) \mathbf{u}_l^* \quad \xrightarrow{\underbrace{\text{optimal!}}_{\text{including pre-constant}}}$$

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Any unbiased estimator  $\hat{\Lambda}$  of  $\lambda_l^*$  obeys

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- in comparison, our estimator obeys

$$\lambda_l \approx \lambda_l^* + \mathbf{u}_l^{*\top} \mathbf{H} \mathbf{u}_l^* \quad \longrightarrow \quad \underbrace{\text{optimal!}}_{\text{including pre-constant}}$$

## Concluding remarks

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Eigen-decomposition (without symmetrization) could be very powerful when dealing with non-symmetric data matrices

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Eigen-decomposition (without symmetrization) could be very powerful when dealing with non-symmetric data matrices

- effective under minimal eigenvalue separation
- distribution-free
- adaptive to heteroscedastic noise
- enables “fine-grained” inference
- statistically optimal

C. Cheng, Y. Wei, Y. Chen, “Inference for linear forms of eigenvectors under minimal eigenvalue separation: asymmetry and heteroscedasticity”, 2020

Y. Chen, C. Cheng, J. Fan, “Asymmetry helps: Eigenvalue and eigenvector analyses of asymmetrically perturbed low-rank matrices”, [arXiv:1811.12804](https://arxiv.org/abs/1811.12804), 2018