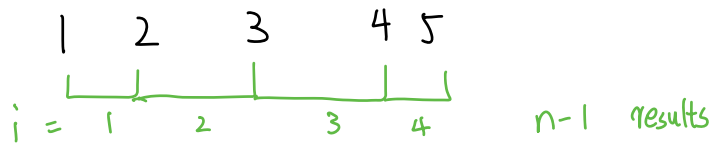


Consecutive



Big Matrix

$$① \quad x_0^{(2)} = x_0^{(1)} \cos(\Delta\theta) + y_0^{(1)} \sin(\Delta\theta)$$

$$② \quad y_0^{(2)} = -x_0^{(1)} \sin(\Delta\theta) + y_0^{(1)} \cos(\Delta\theta)$$

$$③ \quad x_0^{(2)} = \frac{x_i^{(2)}(sOD + y_0^{(2)})}{sOD + tOD}$$

$$④ \quad x_0^{(1)} = \frac{x_i^{(1)}(sOD + y_0^{(1)})}{sOD + tOD}$$

$$⑤ \quad z_0 = z_{i1} \cdot \frac{sOD + y_0^{(1)}}{ODD + sOD} \rightarrow z_0 - \frac{z_i^{(1)} y_0^{(1)}}{ODD + sOD} = z_i^{(1)} \left(\frac{sOD}{ODD + sOD} \right)$$

$$⑥ \quad z_0 = z_{i2} \cdot \frac{sOD + y_0^{(2)}}{ODD + sOD} \rightarrow z_0 - \frac{z_i^{(2)} y_0^{(2)}}{ODD + sOD} = z_i^{(2)} \left(\frac{sOD}{ODD + sOD} \right)$$

Unknowns: $z_0, x_0^{(1)}, y_0^{(1)}, x_0^{(2)}, y_0^{(2)}$

$$A = \begin{bmatrix} ① & 1 & 0 & -\frac{z_i^{(1)}}{ODD + sOD} & 0 & 0 \\ ② & 0 & -1 & \frac{x_i^{(1)}}{sOD + tOD} & 0 & 0 \\ ③ & 1 & 0 & 0 & 0 & -\frac{z_i^{(2)}}{ODD + sOD} \\ ④ & 0 & 0 & 0 & -1 & \frac{x_i^{(2)}}{sOD + tOD} \\ ⑤ & 0 & \cos\theta & \sin\theta & -1 & 0 \\ ⑥ & 0 & -\sin\theta & \cos\theta & 0 & -1 \end{bmatrix} \quad b = \begin{bmatrix} \frac{z_i^{(1)} sOD}{ODD + sOD} \\ -\frac{x_i^{(1)} sOD}{sOD + tOD} \\ \frac{z_i^{(2)} sOD}{ODD + sOD} \\ -\frac{x_i^{(2)} sOD}{sOD + tOD} \\ 0 \\ 0 \end{bmatrix}$$

Unknowns: $z_0, x_0^{(1)}, y_0^{(1)}, x_0^{(2)}, y_0^{(2)}, x_0^{(3)}, y_0^{(3)}$

2. shots: size (A) = 6×5

3: size = 10×7

4: size = 14×9

z will give
 xy will give

1 more eqs
3 more eqs

magnification

2 from Transformation
1 from magnification

col position of $x_0^{(j)} = 2*j$ of $y_0^{(j)} = 2*j+1$

Unknowns: $z_0, x_0^{(1)}, y_0^{(1)}, x_0^{(2)}, y_0^{(2)}, x_0^{(3)}, y_0^{(3)}$

I.	①	1	0	$-\frac{z_1^{(1)}}{\sin\theta + \cos\theta}$	0	0	0	0
A =	②	0	-1	$\frac{x_1^{(1)}}{\sin\theta + \cos\theta}$	0	0	0	0
II.	③	1	0	0	$-\frac{z_1^{(2)}}{\sin\theta + \cos\theta}$	0	0	0
	④	0	0	0	-1	$\frac{x_1^{(2)}}{\sin\theta + \cos\theta}$	0	0
	⑤	0	$\cos\theta$	$\sin\theta$	-1	0	0	0
	⑥	0	$-\sin\theta$	$\cos\theta$	0	-1	0	0
III.	⑦	1	0	0	$-\frac{z_1^{(3)}}{\sin\theta}$	0	0	0
	⑧	0	0	0	0	0	-1	$\frac{x_1^{(3)}}{\sin\theta}$
	⑨	0	0	0	$\cos\theta$	$\sin\theta$	-1	0
	⑩	0	0	0	$-\sin\theta$	$\cos\theta$	0	-1

Big Matrix 2

Unknowns: z_0 , $x_0^{(1)}, y_0^{(1)}, x_0^{(2)}, y_0^{(2)}, x_0^{(3)}, y_0^{(3)}$

$$A = \begin{bmatrix} \text{shot ①} \left\{ \begin{array}{l} \text{magnification} \\ \text{equation} \end{array} \right. & 1 & 0 & -\frac{z_i^{(1)}}{SDD + SOD} & 0 & 0 & 0 & 0 \\ & 0 & -1 & \frac{x_i^{(1)}}{SOD + SDD} & 0 & 0 & 0 & 0 \\ \text{shot ②} \left\{ \begin{array}{l} \text{mag} \end{array} \right. & 1 & 0 & 0 & 0 & -\frac{z_i^{(2)}}{SOD + SDD} & 0 & 0 \\ & 0 & 0 & 0 & -1 & \frac{x_i^{(2)}}{SOD + SDD} & 0 & 0 \\ \text{shot ③} \left\{ \begin{array}{l} \text{mag} \end{array} \right. & 1 & 0 & 0 & 0 & -\frac{z_i^{(3)}}{SDD} & 0 & 0 \\ & 0 & 0 & 0 & 0 & 0 & -1 & \frac{x_i^{(3)}}{SDD} \\ \text{trans} \left\{ \begin{array}{l} \text{①} \rightarrow \text{②} \end{array} \right. & 0 & \cos \theta & \sin \theta & -1 & 0 & 0 & 0 \\ & 0 & -\sin \theta & \cos \theta & 0 & -1 & 0 & 0 \\ \text{trans} \left\{ \begin{array}{l} \text{②} \rightarrow \text{③} \end{array} \right. & 0 & 0 & 0 & \cos \theta & \sin \theta & -1 & 0 \\ & 0 & 0 & 0 & -\sin \theta & \cos \theta & 0 & -1 \\ \text{trans} \left\{ \begin{array}{l} \text{①} \rightarrow \text{③} \end{array} \right. & 0 & \cos 2\theta & \sin 2\theta & 0 & 0 & -1 & 0 \\ & 0 & -\sin 2\theta & \cos 2\theta & 0 & 0 & 0 & -1 \end{bmatrix}$$

angle I II III IV

If N angles, then

C_2^N combinations

$$= \frac{N!}{(N-2)! \cdot 2}$$

for $k = 2: NGS$

if now it's k th shot, then we have $k-1$ transformations

$\therefore 2(k-1) =$ the # of rows taken up

Phase 3

Big Matrix Sections:

Sec 1: Magnifications, # = $NGS \times 2$ (one from x , one from z)

original code from phase 1
moving z coordinate equation

Sec 2: Transformation, # = NGS_2 original code from phase 1
added columns for u, v and a_x, a_y

moving z coordinate equation

$$z_{0,k+1} = z_{i2} \cdot \frac{SOD + y_0^{(2)}}{ODD + SOD} \rightarrow z_{0,k+1} = \frac{z_{i2} y_0^{(2)}}{ODD + SOD} = z_{i,2} \left(\frac{SOD}{ODD + SOD} \right) \quad (1)$$

$$z_{0,k+1} = z_{0,k} + Wt + \frac{1}{2} a_z t^2 \quad (2)$$

substitute (2) to (1):

$$Wt + \frac{1}{2} a_z t^2 + z_{0,k} = \frac{z_{i2} y_{0,k+1}^{(2)}}{ODD + SOD} = z_{i,2} \left(\frac{SOD}{ODD + SOD} \right)$$

same as phase 1

If $\vec{a} = \vec{0}$:

Unknowns: z_0

$x_0^{(1)}, y_0^{(1)}, x_0^{(2)}, y_0^{(2)}, u, v, w$

$A =$ shot ① magnification equation

1	0	$\frac{-z_i^{(1)}}{sOD + sOD}$	0	0	0	0	0
0	-1	$\frac{x_i^{(1)}}{sOD + sOD}$	0	0	0	0	0

shot ② mag

1	0	0	0	$\frac{-z_i^{(2)}}{sOD + sOD}$	0	0	Δt
0	0	0	-1	$\frac{x_i^{(2)}}{sOD + sOD}$	0	0	0

trans ① → ②

0	$\cos \theta$	$\sin \theta$	-1	0	$\Delta t \cos \theta$	$\Delta t \sin \theta$	
0	$-\sin \theta$	$\cos \theta$	0	-1	$\Delta t (-\sin \theta)$	$\Delta t \cos \theta$	

$$① \quad x_{0,k+1}^{(2)} = \left(x_0^{(1)} + u t + \frac{1}{2} a t^2 \right) \cos(\Delta \theta) + \left(y_0^{(1)} + v t + \frac{1}{2} a t^2 \right) \sin(\Delta \theta)$$

$$② \quad y_{0,k+1}^{(2)} = x_{k+1}^{(1)} \sin(\Delta \theta) + y_{k+1}^{(1)} \cos(\Delta \theta)$$

$$③ \quad x_{0,k+1}^{(2)} = \frac{x_i^{(2)} (sOD + y_{0,k+1}^{(2)})}{sOD + sOD} \Rightarrow \frac{x_0^{(2)} (sOD + sOD)}{x_i^{(2)}} - sOD = y_0^{(2)}$$

$$④ \quad x_{0,k}^{(1)} = \frac{x_i^{(1)} (sOD + y_{0,k}^{(1)})}{sOD + sOD}$$

$$⑤ \quad z_{0,k} = z_{i1} \cdot \frac{sOD + y_0^{(1)}}{sOD + sOD} \rightarrow z_{0,k} = \frac{z_{i1} y_0^{(1)}}{sOD + sOD} = z_{i1} \left(\frac{sOD}{sOD + sOD} \right)$$

$$⑥ \quad z_{0,k+1} = z_{i2} \cdot \frac{sOD + y_0^{(2)}}{sOD + sOD} \rightarrow z_{0,k+1} = \frac{z_{i2} y_0^{(2)}}{sOD + sOD} = z_{i2} \left(\frac{sOD}{sOD + sOD} \right)$$