

Appendix 5.2: Conditional Distributions and Implementation of MH Algorithm Related to SEMs with EFDs

It can be shown that the full conditional distribution of Ω is given by

$$p(\Omega|\mathbf{Y}, \boldsymbol{\theta}) = \prod_{i=1}^n p(\boldsymbol{\omega}_i|\mathbf{y}_i, \boldsymbol{\theta}) \propto \prod_{i=1}^n p(\mathbf{y}_i|\boldsymbol{\omega}_i, \boldsymbol{\theta}) p(\boldsymbol{\eta}_i|\boldsymbol{\xi}_i, \boldsymbol{\theta}) p(\boldsymbol{\xi}_i|\boldsymbol{\theta}),$$

where $p(\boldsymbol{\omega}_i|\mathbf{y}_i, \boldsymbol{\theta})$ is proportional to

$$\exp \left\{ \sum_{k=1}^p \left[y_{ik} \vartheta_{ik} - b(\vartheta_{ik}) \right] / \psi_{\epsilon k} \right. \\ \left. - \frac{1}{2} \left[(\boldsymbol{\eta}_i - \mathbf{B} \mathbf{d}_i - \boldsymbol{\Pi} \boldsymbol{\eta}_i - \boldsymbol{\Gamma} \mathbf{F}(\boldsymbol{\xi}_i))^T \boldsymbol{\Psi}_{\delta}^{-1} (\boldsymbol{\eta}_i - \mathbf{B} \mathbf{d}_i - \boldsymbol{\Pi} \boldsymbol{\eta}_i - \boldsymbol{\Gamma} \mathbf{F}(\boldsymbol{\xi}_i)) + \boldsymbol{\xi}_i^T \boldsymbol{\Phi}^{-1} \boldsymbol{\xi}_i \right] \right\}. \quad (5.A10)$$

Under the conjugate prior distributions given in (5.14), it can be shown that the full conditional distributions of the components of $\boldsymbol{\theta}$ are given by

$$\begin{aligned} p(\mathbf{A}_k|\mathbf{Y}, \Omega, \mathbf{A}_k, \psi_{\epsilon k}) &\propto \exp \left\{ \sum_{i=1}^n \frac{y_{ik} \vartheta_{ik} - b(\vartheta_{ik})}{\psi_{\epsilon k}} - \frac{1}{2} (\mathbf{A}_k - \mathbf{A}_{0k})^T \mathbf{H}_{0k}^{-1} (\mathbf{A}_k - \mathbf{A}_{0k}) \right\}, \\ p(\psi_{\epsilon k}|\mathbf{Y}, \Omega, \mathbf{A}_k, \mathbf{A}_k) &\propto \psi_{\epsilon k}^{-(\frac{n}{2} + \alpha_{0\epsilon k} - 1)} \exp \left\{ \sum_{i=1}^n \left[\frac{y_{ik} \vartheta_{ik} - b(\vartheta_{ik})}{\psi_{\epsilon k}} + c_k(y_{ik}, \psi_{\epsilon k}) \right] - \frac{\beta_{0k}}{\psi_{\epsilon k}} \right\}, \\ p(\mathbf{\Lambda}_k|\mathbf{Y}, \Omega, \mathbf{A}_k, \psi_{\epsilon k}) &\propto \exp \left\{ \sum_{i=1}^n \frac{y_{ik} \vartheta_{ik} - b(\vartheta_{ik})}{\psi_{\epsilon k}} - \frac{1}{2} \psi_{\epsilon k}^{-1} (\mathbf{\Lambda}_k - \mathbf{\Lambda}_{0k})^T \mathbf{H}_{0yk}^{-1} (\mathbf{\Lambda}_k - \mathbf{\Lambda}_{0k}) \right\}, \\ [\psi_{\delta k}^{-1}|\Omega, \mathbf{\Lambda}_{\omega k}] &\stackrel{D}{=} \text{Gamma}[n/2 + \alpha_{0\delta k}, \beta_{\delta k}], \\ [\mathbf{\Lambda}_{\omega k}|\Omega, \psi_{\delta k}] &\stackrel{D}{=} N[\boldsymbol{\mu}_{\omega k}, \psi_{\delta k} \boldsymbol{\Sigma}_{\omega k}], \\ [\boldsymbol{\Phi}|\Omega] &\stackrel{D}{=} IW_{q_2}[(\Omega_2 \Omega_2^T + \mathbf{R}_0^{-1}), n + \rho_0], \end{aligned} \quad (5.A11)$$

where $\boldsymbol{\Sigma}_{\omega k} = (\mathbf{H}_{0\omega k}^{-1} + \mathbf{G} \mathbf{G}^T)^{-1}$, $\boldsymbol{\mu}_{\omega k} = \boldsymbol{\Sigma}_{\omega k} (\mathbf{H}_{0\omega k}^{-1} \mathbf{\Lambda}_{0\omega k} + \mathbf{G} \Omega_{1k})$, and $\beta_{\delta k} = \beta_{0\delta k} + (\Omega_{1k}^T \Omega_{1k} - \boldsymbol{\mu}_{\omega k}^T \boldsymbol{\Sigma}_{\omega k}^{-1} \boldsymbol{\mu}_{\omega k} + \mathbf{\Lambda}_{0\omega k}^T \mathbf{H}_{0\omega k}^{-1} \mathbf{\Lambda}_{0\omega k})/2$, in which $\mathbf{G} = (\mathbf{G}(\boldsymbol{\omega}_1), \dots, \mathbf{G}(\boldsymbol{\omega}_n))$, $\Omega_1 = (\boldsymbol{\eta}_1, \dots, \boldsymbol{\eta}_n)$, $\Omega_2 = (\boldsymbol{\xi}_1, \dots, \boldsymbol{\xi}_n)$, and Ω_{1k}^T is the k th row of Ω_1 .

In simulating observations from $p(\boldsymbol{\omega}_i|\mathbf{y}_i, \boldsymbol{\theta})$ in (5.A10), we choose $N[\cdot, \sigma_{\omega}^2 \Omega_{\omega}]$ as the proposal distribution in the MH algorithm, where $\Omega_{\omega}^{-1} = \boldsymbol{\Sigma}_{\omega}^* + \boldsymbol{\Lambda}^T \boldsymbol{\Psi}_{\omega} \boldsymbol{\Lambda}$, in which

$$\boldsymbol{\Sigma}_{\omega}^* = \begin{bmatrix} \boldsymbol{\Pi}_0^T \boldsymbol{\Psi}_{\delta}^{-1} \boldsymbol{\Pi}_0 & -\boldsymbol{\Pi}_0^T \boldsymbol{\Psi}_{\delta}^{-1} \boldsymbol{\Gamma} \boldsymbol{\Delta} \\ -\boldsymbol{\Delta}^T \boldsymbol{\Gamma}^T \boldsymbol{\Psi}_{\delta}^{-1} \boldsymbol{\Pi}_0 & \boldsymbol{\Phi}^{-1} + \boldsymbol{\Delta}^T \boldsymbol{\Gamma}^T \boldsymbol{\Psi}_{\delta}^{-1} \boldsymbol{\Gamma} \boldsymbol{\Delta} \end{bmatrix},$$

with $\mathbf{\Pi}_0 = \mathbf{I}_{q_1} - \mathbf{\Pi}$, $\mathbf{\Delta} = (\partial \mathbf{F}(\boldsymbol{\xi}_i) / \partial \boldsymbol{\xi}_i)^T|_{\boldsymbol{\xi}_i=\mathbf{0}}$, and $\mathbf{\Psi}_\omega = \text{diag}(\ddot{b}(\vartheta_{i1})/\psi_{\epsilon 1}, \dots, \ddot{b}(\vartheta_{ip})/\psi_{\epsilon p})|_{\omega_i=\mathbf{0}}$.

In simulating observations from the conditional distributions $p(\mathbf{A}_k | \mathbf{Y}, \boldsymbol{\Omega}, \mathbf{A}_k, \psi_{\epsilon k})$, $p(\psi_{\epsilon k} | \mathbf{Y}, \boldsymbol{\Omega}, \mathbf{A}_k, \mathbf{A}_k)$, and $p(\mathbf{A}_k | \mathbf{Y}, \boldsymbol{\Omega}, \mathbf{A}_k, \psi_{\epsilon k})$, the proposal distributions are $N[\cdot, \sigma_a^2 \boldsymbol{\Omega}_{ak}]$, $N[\cdot, \sigma_\psi^2 \boldsymbol{\Omega}_{\psi k}]$, and $N[\cdot, \sigma_\lambda^2 \boldsymbol{\Omega}_{\lambda k}]$, respectively, where

$$\begin{aligned}\boldsymbol{\Omega}_{ak}^{-1} &= \sum_{i=1}^n \ddot{b}(\vartheta_{ik}) \mathbf{c}_{ik} \mathbf{c}_{ik}^T / \psi_{\epsilon k} \Big|_{\mathbf{A}_k=\mathbf{0}} + \mathbf{H}_{0k}^{-1}, \\ \boldsymbol{\Omega}_{\psi k}^{-1} &= 1 - n/2 - \alpha_{0\epsilon k} - 2 \sum_{i=1}^n [y_{ik} \vartheta_{ik} - b(\vartheta_{ik})] - \ddot{c}_k(y_{ik}, \psi_{\epsilon k}) \Big|_{\psi_{\epsilon k}=1} + 2\beta_{0\epsilon k}, \\ \boldsymbol{\Omega}_{\lambda k}^{-1} &= \sum_{i=1}^n \ddot{b}(\vartheta_{ik}) \boldsymbol{\omega}_i \boldsymbol{\omega}_i^T \Big|_{\mathbf{A}_k=\mathbf{0}} + \psi_{\epsilon k}^{-1} \mathbf{H}_{0yk}^{-1}.\end{aligned}$$

For improving efficiency, we respectively use $N[\boldsymbol{\mu}_{ak}, \boldsymbol{\Omega}_{ak}]$, $N[\mu_{\psi k}, \boldsymbol{\Omega}_{\psi k}]$, and $N[\boldsymbol{\mu}_{\lambda k}, \boldsymbol{\Omega}_{\lambda k}]$ as initial proposal distributions in the first few iterations, where

$$\begin{aligned}\boldsymbol{\mu}_{ak} &= \sum_{i=1}^n \left[y_{ik} - \dot{b}(\vartheta_{ik})|_{\mathbf{A}_k=\mathbf{0}} \right] \frac{\mathbf{c}_{ik}}{\psi_{\epsilon k}} + \mathbf{H}_{0k}^{-1} \mathbf{A}_{0k}, \\ \mu_{\psi k} &= 1 - n/2 - \alpha_{0\epsilon k} - \sum_{i=1}^n \left[y_{ik} \vartheta_{ik} - b(\vartheta_{ik}) \right] + \dot{c}_k(y_{ik}, \psi_{\epsilon k}) \Big|_{\psi_{\epsilon k}=1} + \beta_{0\epsilon k}, \\ \boldsymbol{\mu}_{\lambda k} &= \sum_{i=1}^n \left[y_{ik} - \dot{b}(\vartheta_{ik})|_{\mathbf{A}_k=\mathbf{0}} \right] \frac{\boldsymbol{\omega}_i}{\psi_{\epsilon k}} + \mathbf{H}_{0yk}^{-1} \mathbf{A}_{0k}.\end{aligned}$$

Let \mathbf{y}_k^{*T} be the k th row of \mathbf{Y} that is not directly observable, \mathbf{z}_k be the corresponding ordered categorical vector, and $\boldsymbol{\alpha}_k = (\alpha_{k,2}, \dots, \alpha_{k,b_k-1})$. It can be shown by similar derivation as in Appendix 5.1 that

$$\begin{aligned}p(\boldsymbol{\alpha}_k, \mathbf{y}_k^* | \mathbf{z}_k, \boldsymbol{\Omega}, \boldsymbol{\theta}) &= p(\boldsymbol{\alpha}_k | \mathbf{z}_k, \boldsymbol{\Omega}, \boldsymbol{\theta}) p(\mathbf{y}_k^* | \boldsymbol{\alpha}_k, \mathbf{z}_k, \boldsymbol{\Omega}, \boldsymbol{\theta}) \propto \\ &\prod_{i=1}^n \exp \left\{ [y_{ik}^* \vartheta_{ik} - b(\vartheta_{ik})] / \psi_{\epsilon k} + c_k(y_{ik}^*, \psi_{\epsilon k}) \right\} I_{[\alpha_k, z_{ik}, \alpha_k, z_{ik}+1)}(y_{ik}^*),\end{aligned}\tag{5.A12}$$

where $I_A(y)$ is an indicator function which takes 1 if $y \in A$, and 0 otherwise. The treatment of dichotomous variables is similar.

A multivariate version of the MH algorithm is used to simulate observations from $p(\boldsymbol{\alpha}_k, \mathbf{y}_k^* | \mathbf{z}_k, \boldsymbol{\Omega}, \boldsymbol{\theta})$ in (5.A12). Following Cowles (1996), for the joint proposal distribution

of α_k and \mathbf{y}_k^* given \mathbf{z}_k , Ω , and θ can be constructed according to the factorization $p(\alpha_k, \mathbf{y}_k^* | \mathbf{z}_k, \Omega, \theta) = p(\alpha_k | \mathbf{z}_k, \Omega, \theta) p(\mathbf{y}_k^* | \alpha_k, \mathbf{z}_k, \Omega, \theta)$. At the j th iteration, we generate a candidate vector of thresholds $(\alpha_{k,2}, \dots, \alpha_{k,b_k-1})$ from the following univariate truncated normal distribution

$$\alpha_{k,m} \sim N[\alpha_{k,m}^{(j)}, \sigma_{\alpha_k}^2] I_{(\alpha_{k,m-1}, \alpha_{k,m+1}^{(j)})}(\alpha_{k,m}), \quad \text{for } m = 2, \dots, b_k - 1,$$

where $\alpha_{k,m}^{(j)}$ is the current value of $\alpha_{k,m}$, and $\sigma_{\alpha_k}^2$ is chosen to obtain an average acceptance rate of approximately 0.25 or greater. The acceptance probability for a candidate vector $(\alpha_k, \mathbf{y}_k^*)$ as a new observation $(\alpha_k^{(j+1)}, \mathbf{y}_k^{*(j+1)})$ is $\min\{1, R_k\}$, where

$$R_k = \frac{p(\alpha_k, \mathbf{y}_k^* | \mathbf{z}_k, \Omega, \theta) p(\alpha_k^{(j)}, \mathbf{y}_k^{*(j)} | \alpha_k, \mathbf{y}_k^*, \mathbf{z}_k, \Omega, \theta)}{p(\alpha_k^{(j)}, \mathbf{y}_k^{*(j)} | \mathbf{z}_k, \Omega, \theta) p(\alpha_k, \mathbf{y}_k^* | \alpha_k^{(j)}, \mathbf{y}_k^{*(j)}, \mathbf{z}_k, \Omega, \theta)}.$$

For an accepted α_k , a new \mathbf{y}_k^* is simulated from the following univariate truncated distribution:

$$[y_{ik}^* | \alpha_k, z_{ik}, \omega_i, \theta] \stackrel{D}{=} \exp\{[y_{ik}^* \vartheta_{ik} - b(\vartheta_{ik})] / \psi_{\epsilon k} + c_k(y_{ik}^*, \psi_{\epsilon k})\} I_{[\alpha_k, z_{ik}, \alpha_k, z_{ik}+1)}(y_{ik}^*),$$

where y_{ik}^* and z_{ik} are the i th components of \mathbf{y}_k^* and \mathbf{z}_k , respectively, and $I_A(y)$ is an indicator function which takes 1 if y in A and zero otherwise.

Appendix 5.3: WinBUGS Code Related to Section 5.3.4

```
model {
  for(i in 1:N){
    #Measurement equation model
    for(j in 1:3){
      y[i,j] ~ dnorm(mu[i,j], 1) I(low[z[i,j]+1], high[z[i,j]+1])
    }
    for(j in 4:P){
      z[i,j] ~ dbin(pb[i,j], 1)
      pb[i,j] <- exp(mu[i,j]) / (1 + exp(mu[i,j]))
    }
    mu[i,1] <- uby[1] + eta[i]
    mu[i,2] <- uby[2] + lam[1] * eta[i]
  }
}
```