

STAT 5010: Advanced Statistical Inference

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Lecture #1
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Different disciplines:

- Networks, images, recordings, ...
- Economics, Finance, ...
- Biology (Genetic), medical, earth science,

} → Data $\xrightarrow{\text{Statistics}}$ Inference/Conclusions

Question Concerned:

- Modelling How to build a mathematical/statistical model that captures the *uncertainty* in our data?
- Methodology tools that allows us to deduce these statistical conclusions.
- Analysis: Optimal inference

e.g. Mode: sample mean, sample median.

* Finite sample optionality

1. Given observations (x_1, x_2, \dots, x_n) .
2. Asymptotic properties $(n \rightarrow \infty)$.

1 Decision Theory (Wald, 1939)

Random element X takes values in a sample space χ . X can also be a vector (or matrix).

$$(X_1, X_2, \dots, X_n) \stackrel{i.i.d}{\sim} f \text{ (distribution)}$$

- I • A statistical model is a family of distribution \mathbb{P} indexed by a parameter θ . we denote

$$\mathbb{P} = \{P_\theta : \theta \in \Omega\},$$

where θ is the parameter, $\Omega \in \mathbb{R}^k$ is the parameter space and P_θ is a distribution.

- We assume that the data X come from some $P_\theta \in \mathbb{P}$ but the true value of θ is unknown.

Example 1 Observe a sequence of coin flips $x_1, x_2, \dots, x_n \in \{0, 1\}$. The objective is to estimate the probability of heads given the observations. (with 1 denotes a head). One can write

$$\mathbb{P} = \left\{ \text{Bernoulli}(\theta) : \theta \in [0, 1] \triangleq \Omega \right\}$$

$$P_\theta(X_i = 1) = \theta.$$

Estimating Procedure:

$$\left. \begin{array}{l} \text{Estimator} \xrightarrow{\text{Observations}} \text{Estimates} \\ \text{+ Testing} \end{array} \right\} \rightarrow \text{Inference}$$

II A Decision Procedure

δ (estimator) is a map from χ to the decision space \mathbb{D} .

Example: Take $\mathbb{P} = \{\text{Bernoulli}(\theta)\}$ as shown above, we may be interested in estimating θ or testing θ based on:

(a) Estimating θ

The decision space is $\mathbb{D} = [0, 1]$ and the decision procedure might be

$$\delta(X) = \frac{1}{n} \sum_{i=1}^n X_i = \bar{X}_n.$$

(b) Hypothesis Testing

Accepting/rejecting the hypothesis that $\theta = 0.5$; The corresponding decision space is $\mathbb{D} = \{\text{accept, reject}\}$, one possible decision procedure is

$$\delta(X) = \text{"Reject if } \bar{X}_n > 0.5 \text{" and accept otherwise.}$$

(c) A loss function is a mapping $L : \Omega \times \mathbb{D} \rightarrow \mathbb{R}^+$, $L(\theta, d)$ represents the penalty for making the decision d when θ is in fact the true parameter for the distribution generating the data.

Example 2 : [Squared-error Loss] For estimating θ with decision $d \in \mathbb{R} = \mathbb{D}$, a common loss function is the squared-error loss: $L(\theta, d) = (\theta - d)^2$.

Risk Function:

$$\text{Average loss incurred} \rightarrow R(\theta, \delta) = E_{\theta}(L(\theta, \delta(X)))$$

Admissibility:

δ is inadmissible if there exists δ' such that $R(\theta, \delta') \leq R(\theta, \delta)$ for all θ and $R(\theta', \delta') < R(\theta', \delta)$ for some θ' .