

CONTACT INFORMATION	Senior Research Scientist NVIDIA Research (Robotics) 4545 Roosevelt Way, 6th Floor Seattle, WA 98105	yux@nvidia.com http://yuxng.github.io/ Google Scholar GitHub
RESEARCH INTERESTS	Robotics, Computer Vision, Machine Learning, Deep Learning	
EDUCATION	University of Michigan , Ann Arbor, Michigan, USA Ph.D. in Electrical Engineering: Systems Dissertation: 3D Object Representations for Recognition Advisor: Prof. Silvio Savarese Sep 2010 – Dec 2015	
	Fudan University , Shanghai, China M.S. in Computer Science Dissertation: Graphic Models for Semantic Context Modeling in Automatic Image Annotation Advisor: Prof. Xiangdong Zhou Sep 2007 – Jul 2010	
	Fudan University , Shanghai, China B.S. in Computer Science Sep 2003 – Jul 2007	
EXPERIENCE	NVIDIA Research , Seattle, Washington, USA <i>Senior Research Scientist</i> Jun 2018 – present	
	NVIDIA Research , Seattle, Washington, USA <i>Postdoctoral Researcher</i> Jan 2018 – May 2018	
	University of Washington , Seattle, Washington, USA <i>Postdoctoral Researcher</i> • Advisor: Prof. Dieter Fox Aug 2016 – Dec 2017	
	Stanford University , Stanford, California, USA <i>Postdoctoral Researcher</i> • Advisor: Prof. Silvio Savarese Jan 2016 – Jul 2016	
	Stanford University , Stanford, California, USA <i>Visiting Student Researcher</i> • Advisor: Prof. Silvio Savarese Sep 2013 – Dec 2015	
	NEC Laboratories America, Inc. , Cupertino, California, USA <i>Summer Research Intern</i> • Department: Media Analytics Jun 2015 – Sep 2015 May 2014 – Aug 2014	
PUBLICATIONS	Goal-Auxiliary Actor-Critic for 6D Robotic Grasping with Point Clouds Lirui Wang, Yu Xiang and Dieter Fox In <i>arXiv</i> , 2020.	
	Unseen Object Instance Segmentation for Robotic Environments Christopher Xie, Yu Xiang , Arsalan Mousavian and Dieter Fox In <i>arXiv</i> , 2020.	
	Learning RGB-D Feature Embeddings for Unseen Object Instance Segmentation Yu Xiang , Christopher Xie, Arsalan Mousavian and Dieter Fox In <i>Conference on Robot Learning (CoRL)</i> , 2020.	
	Manipulation Trajectory Optimization with Online Grasp Synthesis and Selection Lirui Wang, Yu Xiang and Dieter Fox In <i>Robotics: Science and Systems (RSS)</i> , 2020.	
	LatentFusion: End-to-End Differentiable Reconstruction and Rendering for Unseen Object Pose Estimation	

Keunhong Park, Arsalan Mousavian, **Yu Xiang** and Dieter Fox
In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, 2020.

Scaling Local Control to Large-Scale Topological Navigation
Xiangyun Meng, Nathan Ratliff, **Yu Xiang** and Dieter Fox
In *International Conference on Robotics and Automation (ICRA)*, 2020.

Self-supervised 6D Object Pose Estimation for Robot Manipulation
Xinke Deng, **Yu Xiang**, Arsalan Mousavian, Clemens Eppner, Timothy Bretl and Dieter Fox
In *International Conference on Robotics and Automation (ICRA)*, 2020.

The Best of Both Modes: Separately Leveraging RGB and Depth for Unseen Object Instance Segmentation
Christopher Xie, **Yu Xiang**, Arsalan Mousavian and Dieter Fox
In *Conference on Robot Learning (CoRL)*, 2019.

PoseRBPF: A Rao-Blackwellized Particle Filter for 6D Object Pose Tracking
Xinke Deng, Arsalan Mousavian, **Yu Xiang**, Fei Xia, Timothy Bretl and Dieter Fox
In *Robotics: Science and Systems (RSS)*, 2019.

Object Discovery in Videos as Foreground Motion Clustering
Christopher Xie, **Yu Xiang**, Dieter Fox and Zaid Harchaoui
In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, 2019.

Neural Autonomous Navigation with Riemannian Motion Policy
Xiangyun Meng, Nathan Ratliff, **Yu Xiang** and Dieter Fox
In *International Conference on Robotics and Automation (ICRA)*, 2019.

Deep Object Pose Estimation for Semantic Robotic Grasping of Household Objects
Jonathan Tremblay, Thang To, Balakumar Sundaralingam, **Yu Xiang**, Dieter Fox and Stan Birchfield
In *Conference on Robot Learning (CoRL)*, 2018.

DeepIM: Deep Iterative Matching for 6D Pose Estimation
Yi Li, Gu Wang, Xiangyang Ji, **Yu Xiang** and Dieter Fox
In *European Conference on Computer Vision (ECCV)*, 2018 **-Oral**.

PoseCNN: A Convolutional Neural Network for 6D Object Pose Estimation in Cluttered Scenes
Yu Xiang, Tanner Schmidt, Venkatraman Narayanan and Dieter Fox
In *Robotics: Science and Systems (RSS)*, 2018.

Recurrent Autoregressive Networks for Online Multi-Object Tracking
Kuan Fang, **Yu Xiang**, Xiaocheng Li and Silvio Savarese
In *IEEE Winter Conference on Applications of Computer Vision (WACV)*, 2018.

DA-RNN: Semantic Mapping with Data Associated Recurrent Neural Networks
Yu Xiang and Dieter Fox
In *Robotics: Science and Systems (RSS)*, 2017.

Subcategory-aware Convolutional Neural Networks for Object Proposals and Detection
Yu Xiang, Wongun Choi, Yuanqing Lin and Silvio Savarese
In *IEEE Winter Conference on Applications of Computer Vision (WACV)*, pp. 924–933, 2017.

Anticipating Accidents in Dashcam Videos
Fu-Hsiang Chan, Yu-Ting Chen, **Yu Xiang** and Min Sun
In *Asian Conference on Computer Vision (ACCV)*, pp. 136–153, 2016 **-Oral**.

ObjectNet3D: A Large Scale Database for 3D Object Recognition
Yu Xiang, Wonhui Kim, Wei Chen, Jingwei Ji, Christopher Choy, Hao Su, Roozbeh Mottaghi, Leonidas Guibas and Silvio Savarese
In *European Conference on Computer Vision (ECCV)*, pp. 160–176, 2016 **-Spotlight Oral**.

Pose Estimation Errors, the Ultimate Diagnosis
Carolina Redondo-Cabrera, Roberto López-Sastre, **Yu Xiang**, Tinne Tuytelaars and Silvio Savarese
In *European Conference on Computer Vision (ECCV)*, pp. 118–134, 2016.

Deep Metric Learning via Lifted Structured Feature Embedding

Hyun Oh Song, **Yu Xiang**, Stefanie Jegelka and Silvio Savarese

In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, pp. 4004–4012, 2016 - **Spotlight Oral**.

Learning to Track: Online Multi-Object Tracking by Decision Making

Yu Xiang, Alexandre Alahi and Silvio Savarese

In *International Conference on Computer Vision (ICCV)*, pp. 4705–4713, 2015 -**Oral**.

Data-Driven 3D Voxel Patterns for Object Category Recognition

Yu Xiang, Wongun Choi, Yuanqing Lin and Silvio Savarese

In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, pp. 1903–1911, 2015 -**Oral**.

A Coarse-to-Fine Model for 3D Pose Estimation and Sub-category Recognition

Roozbeh Mottaghi, **Yu Xiang** and Silvio Savarese

In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, pp. 418–426, 2015.

Monocular Multiview Object Tracking with 3D Aspect Parts

Yu Xiang*, Changkyu Song*, Roozbeh Mottaghi and Silvio Savarese (*equal contribution)

In *European Conference on Computer Vision (ECCV)*, pp. 220–235, 2014.

Beyond PASCAL: A Benchmark for 3D Object Detection in the Wild

Yu Xiang, Roozbeh Mottaghi and Silvio Savarese

In *IEEE Winter Conference on Applications of Computer Vision (WACV)*, pp. 75–82, 2014.

Object Detection by 3D Aspectlets and Occlusion Reasoning

Yu Xiang and Silvio Savarese

In *IEEE Workshop on 3D Representation and Recognition (3dRRR)*, pp. 530–537, 2013.

Object Co-detection

Sid Yingze Bao, **Yu Xiang** and Silvio Savarese

In *European Conference on Computer Vision (ECCV)*, vol. 7572, pp. 86–101, 2014.

Estimating the Aspect Layout of Object Categories

Yu Xiang and Silvio Savarese

In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, pp. 3410–3417, 2012.

Semantic Context Modeling with Maximal Margin Conditional Random Fields for Automatic Image Annotation

Yu Xiang, Xiangdong Zhou, Zuotao Liu, Tat-Seng Chua and Chong-Wah Ngo

In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, pp. 3368–3375, 2010.

Learning Contextual Metrics for Automatic Image Annotation

Zuotao Liu, Xiangdong Zhou, **Yu Xiang** and Yan-Tao Zheng

In *Advances in Multimedia Information Processing - PCM*, vol. 6297, pp. 124–135, 2010.

A Revisit of Generative Model for Automatic Image Annotation using Markov Random Fields

Yu Xiang, Xiangdong Zhou, Zuotao Liu, Tat-Seng Chua and Chong-Wah Ngo

In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, pp. 1153–1160, 2009.

Adaptive Model for Web Image Semantic Automatic Image Annotation

Hongtao Xu, Xiangdong Zhou, **Yu Xiang** and Baile Shi

In *Journal of Software (in Chinese)*, vol. 21, no. 9, pp. 2183–2195, 2009.

Exploiting Flickr’s Related Tags for Semantic Annotation of Web Images

Hongtao Xu, Xiangdong Zhou, **Yu Xiang** and Baile Shi

In *ACM International Conference on Image and Video Retrieval (CIVR)*, no. 46, 2009.

Automatic Web Image Annotation via Web-Scale Image Semantic Space Learning

Hongtao Xu, Xiangdong Zhou, Lan Lin, **Yu Xiang** and Baile Shi

In *Advances in Data and Web Management*, vol. 5446, pp. 211–222, 2009.

TEACHING EXPERIENCE	Artificial Intelligence , University of Washington, Seattle, Washington, USA	2017
	<i>Guest Lectures</i> for Prof. Dieter Fox	
	Computer Vision , University of Washington, Seattle, Washington, USA	2017
	<i>Guest Lecture</i> for Prof. Linda Shapiro	
	Computer Vision , Stanford University, Stanford, California, USA	2016
	<i>Guest Lectures</i> for Prof. Silvio Savarese	
	The C Programming Language , Fudan University, Shanghai, China	Sep 2009 – Jan 2010
	<i>Teaching Assistant</i>	
STUDENT MENTORSHIP	Lirui Wang, Master Student, University of Washington	Sep 2017 – present
	NVIDIA Research Internship Program:	
	Luyang Zhu, PhD Student, University of Washington	2020
	Xinke Deng, PhD Student, UIUC	2018, 2019
	Keunhong Park, PhD Student, University of Washington	2019
	Corinne Jones, PhD Student, University of Washington	2019
	Raluca Scona, PhD Student, Edinburgh Center for Robotics	2019
	Fei Xia, PhD Student, Stanford University	2018
	Rui Wang, PhD Student, TUM	2018
	Christopher Xie, PhD Student, University of Washington	2018
AWARDS AND HONORS	Outstanding Master's Thesis Award of Shanghai	2012
PROFESSIONAL SERVICE	Journal Reviewer	
	<ul style="list-style-type: none"> • International Journal of Robotics Research (IJRR) • IEEE Robotics and Automation Letters (RA-L) • IEEE Transactions on Pattern Analysis and Machine Intelligence (TPAMI) • International Journal of Computer Vision (IJCV) • Computer Vision and Image Understanding (CVIU) • IEEE Transactions on Circuits and Systems for Video Technology (TCSVT) • IEEE Transactions on Multimedia (TMM) • IEEE Transactions on Signal Processing (TSP) 	
	Conference Reviewer	
	<ul style="list-style-type: none"> • Robotics: Science and Systems Conference (RSS) • IEEE International Conference on Robotics and Automation (ICRA) • International Conference on Intelligent Robots and Systems (IROS) • IEEE International Conference on Robot and Human Interactive Communication (ROMAN) • IEEE Conference on Computer Vision and Pattern Recognition (CVPR) • International Conference on Computer Vision (ICCV) • European Conference on Computer Vision (ECCV) • Asian Conference on Computer Vision (ACCV) • British Machine Vision Conference (BMVC) • International Conference on 3D Vision (3DV) • Neural Information Processing Systems (NIPS) 	
	Program Chair	
	<ul style="list-style-type: none"> • The Visual Learning and Reasoning for Robotic Manipulation workshop at RSS, 2020 	
	Program Chair	
	<ul style="list-style-type: none"> • 5th International IEEE Workshop on 3D Representation and Recognition, 2015 	
	Program Committee	
	<ul style="list-style-type: none"> • 4th International IEEE Workshop on 3D Representation and Recognition, 2013 	
	Tutorial Organizer	
	<ul style="list-style-type: none"> • 3D Object Geometry from Single Image Tutorial at International Conference on 3D Vision, 2016 	

Learning RGB-D Feature Embeddings for Unseen Object Instance Segmentation

In NVIDIA Research, Seattle, Washington, 10/12/2020.

PoseRBPF: A Rao-Blackwellized Particle Filter for 6D Object Pose Tracking

In University of Washington, Seattle, Washington, 9/27/2019.

Object Perception for Robot Manipulation

In Toyota Research Institute, Cambridge, Massachusetts, 7/12/2019.

PoseCNN: A Convolutional Neural Network for 6D Object Pose Estimation in Cluttered Scenes

In Robotics: Science and Systems (RSS), CMU, Pittsburgh, Pennsylvania, 6/26/2018.

Perceiving the 3D World from Images and Videos

In Nvidia Research, Redmond, Washington, 11/07/2017; University of Michigan, 3/15/2018.

3D Object Recognition and Scene Understanding from RGB-D Videos

In GRASP Lab at University of Pennsylvania, 10/11/2017; Microsoft Research, Redmond, 10/17/2017; Vision Lab at Stanford University, 10/23/2017.

3D Object Recognition and Scene Understanding

In Mitsubishi Electric Research Laboratories, Boston, Massachusetts, 7/14/2017.

DA-RNN: Semantic Mapping with Data Associated Recurrent Neural Networks

In Robotics: Science and Systems, Massachusetts Institute of Technology, Massachusetts, 7/13/2017.

Subcategory-aware Convolutional Neural Networks for Object Proposals and Detection

In IEEE Winter Conference on Applications of Computer Vision, Santa Rosa, California, 3/29/2017.

Tutorial on 3D Object Recognition

In International Conference on 3D Vision, Stanford University, 10/28/2016.

3D Object Representations for Recognition

In Carnegie Mellon University, 3/28/2016; University of Toronto, 4/4/2016; Massachusetts Institute of Technology, 4/12/2016; University of California, Berkeley, 4/21/2016; University of Illinois at Urbana-Champaign, 5/5/2016; University of Washington, 5/31/2016.

3D Object Detection and Pose Estimation

In the 1st International Workshop on Recovering 6D Object Pose in conjunction with ICCV, Santiago, Chile, 12/17/2015.

Learning to Track: Online Multi-Object Tracking by Decision Making

In International Conference on Computer Vision, Santiago, Chile, 12/16/2015.

Data-Driven 3D Voxel Patterns for Object Category Recognition

In IEEE Conference on Computer Vision and Pattern Recognition, Boston, Massachusetts, 06/08/2015.

Monocular Multiview Object Tracking with 3D Aspect Parts

In the 1st Stanford-SNU Workshop on Automated Driving, Stanford University, 02/24/2015.

Beyond PASCAL: A Benchmark for 3D Object Detection in the Wild

In IEEE Winter Conference on Applications of Computer Vision, Steamboat Springs, Colorado, 03/24/2014.

Object Detection by 3D Aspectlets and Occlusion Reasoning

In the 4th International IEEE Workshop on 3D Representation and Recognition in conjunction with ICCV, Sydney, Australia, 12/08/2013.

Estimating the Aspect Layout of Object Categories

In Midwest Vision Workshop, University of Illinois at Urbana-Champaign, 09/21/2012.

Programming Languages: Python, C/C++, CUDA

Libraries: PyTorch, Tensorflow, OpenCV, OpenGL, ROS

Operating Systems: Linux, Windows and Mac OS X

Languages: English, Chinese