

CONTACT INFORMATION	Senior Research Scientist NVIDIA Research (Robotics) 4545 Roosevelt Way NE #400 Seattle, WA 98105	<a href="mailto:yux@nvidia.com">yux@nvidia.com</a> <a href="http://yuxng.github.io/">http://yuxng.github.io/</a> <a href="#">Google Scholar</a> <a href="#">GitHub</a>
RESEARCH INTERESTS	Robotics, Computer Vision, Machine Learning, Deep Learning	
EDUCATION	<b>University of Michigan</b> , Ann Arbor, Michigan, USA Ph.D. in <a href="#">Electrical Engineering: Systems</a> Dissertation: 3D Object Representations for Recognition Advisor: Prof. Silvio Savarese  <b>Fudan University</b> , Shanghai, China M.S. in <a href="#">Computer Science</a> Dissertation: Graphic Models for Semantic Context Modeling in Automatic Image Annotation Advisor: Prof. Xiangdong Zhou  <b>Fudan University</b> , Shanghai, China B.S. in <a href="#">Computer Science</a>	Sep 2010 – Dec 2015           Sep 2007 – Jul 2010           Sep 2003 – Jul 2007
EXPERIENCE	<b>NVIDIA Research</b> , Seattle, Washington, USA <i>Senior Research Scientist</i>  <b>NVIDIA Research</b> , Seattle, Washington, USA <i>Postdoctoral Researcher</i>  <b>University of Washington</b> , Seattle, Washington, USA <i>Postdoctoral Researcher</i> <ul style="list-style-type: none"><li>• Advisor: Prof. Dieter Fox</li></ul> <b>Stanford University</b> , Stanford, California, USA <i>Postdoctoral Researcher</i> <ul style="list-style-type: none"><li>• Advisor: Prof. Silvio Savarese</li></ul> <b>Stanford University</b> , Stanford, California, USA <i>Visiting Student Researcher</i> <ul style="list-style-type: none"><li>• Advisor: Prof. Silvio Savarese</li></ul> <b>NEC Laboratories America, Inc.</b> , Cupertino, California, USA <i>Summer Research Intern</i> <ul style="list-style-type: none"><li>• Department: Media Analytics</li></ul>	Jun 2018 – present           Jan 2018 – May 2018           Aug 2016 – Dec 2017           Jan 2016 – Jul 2016           Sep 2013 – Dec 2015           Jun 2015 – Sep 2015 May 2014 – Aug 2014
PUBLICATIONS	<b>Goal-Auxiliary Actor-Critic for 6D Robotic Grasping with Point Clouds</b> Lirui Wang, Yu Xiang and Dieter Fox In <i>arXiv</i> , 2020.  <b>Unseen Object Instance Segmentation for Robotic Environments</b> Christopher Xie, Yu Xiang, Arsalan Mousavian and Dieter Fox In <i>arXiv</i> , 2020.  <b>Learning RGB-D Feature Embeddings for Unseen Object Instance Segmentation</b> Yu Xiang, Christopher Xie, Arsalan Mousavian and Dieter Fox In <i>Conference on Robot Learning (CoRL)</i> , 2020.  <b>Manipulation Trajectory Optimization with Online Grasp Synthesis and Selection</b> Lirui Wang, Yu Xiang and Dieter Fox In <i>Robotics: Science and Systems (RSS)</i> , 2020.  <b>LatentFusion: End-to-End Differentiable Reconstruction and Rendering for Unseen Object Pose Estimation</b>	

Keunhong Park, Arsalan Mousavian, *Yu Xiang* and Dieter Fox  
In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, 2020.

**Scaling Local Control to Large-Scale Topological Navigation**  
Xiangyun Meng, Nathan Ratliff, *Yu Xiang* and Dieter Fox  
In *International Conference on Robotics and Automation (ICRA)*, 2020.

**Self-supervised 6D Object Pose Estimation for Robot Manipulation**  
Xinke Deng, *Yu Xiang*, Arsalan Mousavian, Clemens Eppner, Timothy Bretl and Dieter Fox  
In *International Conference on Robotics and Automation (ICRA)*, 2020.

**The Best of Both Modes: Separately Leveraging RGB and Depth for Unseen Object Instance Segmentation**  
Christopher Xie, *Yu Xiang*, Arsalan Mousavian and Dieter Fox  
In *Conference on Robot Learning (CoRL)*, 2019.

**PoseRBPF: A Rao-Blackwellized Particle Filter for 6D Object Pose Tracking**  
Xinke Deng, Arsalan Mousavian, *Yu Xiang*, Fei Xia, Timothy Bretl and Dieter Fox  
In *Robotics: Science and Systems (RSS)*, 2019.

**Object Discovery in Videos as Foreground Motion Clustering**  
Christopher Xie, *Yu Xiang*, Dieter Fox and Zaid Harchaoui  
In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, 2019.

**Neural Autonomous Navigation with Riemannian Motion Policy**  
Xiangyun Meng, Nathan Ratliff, *Yu Xiang* and Dieter Fox  
In *International Conference on Robotics and Automation (ICRA)*, 2019.

**Deep Object Pose Estimation for Semantic Robotic Grasping of Household Objects**  
Jonathan Tremblay, Thang To, Balakumar Sundaralingam, *Yu Xiang*, Dieter Fox and Stan Birchfield  
In *Conference on Robot Learning (CoRL)*, 2018.

**DeepIM: Deep Iterative Matching for 6D Pose Estimation**  
Yi Li, Gu Wang, Xiangyang Ji, *Yu Xiang* and Dieter Fox  
In *European Conference on Computer Vision (ECCV)*, 2018 (Oral).

**PoseCNN: A Convolutional Neural Network for 6D Object Pose Estimation in Cluttered Scenes**  
*Yu Xiang*, Tanner Schmidt, Venkatraman Narayanan and Dieter Fox  
In *Robotics: Science and Systems (RSS)*, 2018.

**Recurrent Autoregressive Networks for Online Multi-Object Tracking**  
Kuan Fang, *Yu Xiang*, Xiaocheng Li and Silvio Savarese  
In *IEEE Winter Conference on Applications of Computer Vision (WACV)*, 2018.

**DA-RNN: Semantic Mapping with Data Associated Recurrent Neural Networks**  
*Yu Xiang* and Dieter Fox  
In *Robotics: Science and Systems (RSS)*, 2017.

**Subcategory-aware Convolutional Neural Networks for Object Proposals and Detection**  
*Yu Xiang*, Wongun Choi, Yuanqing Lin and Silvio Savarese  
In *IEEE Winter Conference on Applications of Computer Vision (WACV)*, pp. 924–933, 2017.

**Anticipating Accidents in Dashcam Videos**  
Fu-Hsiang Chan, Yu-Ting Chen, *Yu Xiang* and Min Sun  
In *Asian Conference on Computer Vision (ACCV)*, pp. 136–153, 2016 (Oral).

**ObjectNet3D: A Large Scale Database for 3D Object Recognition**  
*Yu Xiang*, Wonhui Kim, Wei Chen, Jingwei Ji, Christopher Choy, Hao Su, Roozbeh Mottaghi, Leonidas Guibas and Silvio Savarese  
In *European Conference on Computer Vision (ECCV)*, pp. 160–176, 2016 (Spotlight Oral).

**Pose Estimation Errors, the Ultimate Diagnosis**  
Carolina Redondo-Cabrera, Roberto López-Sastre, *Yu Xiang*, Tinne Tuytelaars and Silvio Savarese  
In *European Conference on Computer Vision (ECCV)*, pp. 118–134, 2016.

**Deep Metric Learning via Lifted Structured Feature Embedding**

Hyun Oh Song, Yu Xiang, Stefanie Jegelka and Silvio Savarese

In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, pp. 4004–4012, 2016 (Spotlight Oral).

**Learning to Track: Online Multi-Object Tracking by Decision Making**

Yu Xiang, Alexandre Alahi and Silvio Savarese

In *International Conference on Computer Vision (ICCV)*, pp. 4705–4713, 2015 (Oral).

**Data-Driven 3D Voxel Patterns for Object Category Recognition**

Yu Xiang, Wngun Choi, Yuanqing Lin and Silvio Savarese

In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, pp. 1903–1911, 2015 (Oral).

**A Coarse-to-Fine Model for 3D Pose Estimation and Sub-category Recognition**

Roozbeh Mottaghi, Yu Xiang and Silvio Savarese

In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, pp. 418–426, 2015.

**Monocular Multiview Object Tracking with 3D Aspect Parts**

Yu Xiang\*, Changkyu Song\*, Roozbeh Mottaghi and Silvio Savarese (\*equal contribution)

In *European Conference on Computer Vision (ECCV)*, pp. 220–235, 2014.

**Beyond PASCAL: A Benchmark for 3D Object Detection in the Wild**

Yu Xiang, Roozbeh Mottaghi and Silvio Savarese

In *IEEE Winter Conference on Applications of Computer Vision (WACV)*, pp. 75–82, 2014.

**Object Detection by 3D Aspectlets and Occlusion Reasoning**

Yu Xiang and Silvio Savarese

In *IEEE Workshop on 3D Representation and Recognition (3dRRR)*, pp. 530–537, 2013.

**Object Co-detection**

Sid Yingze Bao, Yu Xiang and Silvio Savarese

In *European Conference on Computer Vision (ECCV)*, vol. 7572, pp. 86–101, 2014.

**Estimating the Aspect Layout of Object Categories**

Yu Xiang and Silvio Savarese

In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, pp. 3410–3417, 2012.

**Semantic Context Modeling with Maximal Margin Conditional Random Fields for Automatic Image Annotation**

Yu Xiang, Xiangdong Zhou, Zuotao Liu, Tat-Seng Chua and Chong-Wah Ngo

In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, pp. 3368–3375, 2010.

**Learning Contextual Metrics for Automatic Image Annotation**

Zuotao Liu, Xiangdong Zhou, Yu Xiang and Yan-Tao Zheng

In *Advances in Multimedia Information Processing - PCM*, vol. 6297, pp. 124–135, 2010.

**A Revisit of Generative Model for Automatic Image Annotation using Markov Random Fields**

Yu Xiang, Xiangdong Zhou, Zuotao Liu, Tat-Seng Chua and Chong-Wah Ngo

In *IEEE Conference on Computer Vision and Pattern Recognition (CVPR)*, pp. 1153–1160, 2009.

**Adaptive Model for Web Image Semantic Automatic Image Annotation**

Hongtao Xu, Xiangdong Zhou, Yu Xiang and Baile Shi

In *Journal of Software (in Chinese)*, vol. 21, no. 9, pp. 2183–2195, 2009.

**Exploiting Flickr’s Related Tags for Semantic Annotation of Web Images**

Hongtao Xu, Xiangdong Zhou, Yu Xiang and Baile Shi

In *ACM International Conference on Image and Video Retrieval (CIVR)*, no. 46, 2009.

**Automatic Web Image Annotation via Web-Scale Image Semantic Space Learning**

Hongtao Xu, Xiangdong Zhou, Lan Lin, Yu Xiang and Baile Shi

In *Advances in Data and Web Management*, vol. 5446, pp. 211–222, 2009.

TEACHING EXPERIENCE	<b>Artificial Intelligence</b> , University of Washington, Seattle, Washington, USA <i>Guest Lectures</i> for Prof. Dieter Fox	2017
	<b>Computer Vision</b> , University of Washington, Seattle, Washington, USA <i>Guest Lecture</i> for Prof. Linda Shapiro	2017
	<b>Computer Vision</b> , Stanford University, Stanford, California, USA <i>Guest Lectures</i> for Prof. Silvio Savarese	2016
	<b>The C Programming Language</b> , Fudan University, Shanghai, China <i>Teaching Assistant</i>	Sep 2009 – Jan 2010
STUDENT MENTORSHIP	Lirui Wang, Master Student, University of Washington	Sep 2017 – present
	NVIDIA Internship Program:	
	Luyang Zhu, PhD Student, University of Washington	2020
	Xinke Deng, PhD Student, UIUC	2018, 2019
	Keunhong Park, PhD Student, University of Washington	2019
	Fei Xia, PhD Student, Stanford University	2018
	Rui Wang, PhD Student, TUM	2018
AWARDS AND HONORS	Outstanding Master's Thesis Award of Shanghai	2012
	Journal Reviewer	
PROFESSIONAL SERVICE	<ul style="list-style-type: none"> <li>• International Journal of Robotics Research (IJRR)</li> <li>• IEEE Robotics and Automation Letters (RA-L)</li> <li>• IEEE Transactions on Pattern Analysis and Machine Intelligence (TPAMI)</li> <li>• International Journal of Computer Vision (IJCV)</li> <li>• Computer Vision and Image Understanding (CVIU)</li> <li>• IEEE Transactions on Circuits and Systems for Video Technology (TCSVT)</li> <li>• IEEE Transactions on Multimedia (TMM)</li> <li>• IEEE Transactions on Signal Processing (TSP)</li> </ul>	
	Conference Reviewer	
	<ul style="list-style-type: none"> <li>• Robotics: Science and Systems Conference (RSS)</li> <li>• IEEE International Conference on Robotics and Automation (ICRA)</li> <li>• International Conference on Intelligent Robots and Systems (IROS)</li> <li>• IEEE International Conference on Robot and Human Interactive Communication (ROMAN)</li> <li>• IEEE Conference on Computer Vision and Pattern Recognition (CVPR)</li> <li>• International Conference on Computer Vision (ICCV)</li> <li>• European Conference on Computer Vision (ECCV)</li> <li>• Asian Conference on Computer Vision (ACCV)</li> <li>• British Machine Vision Conference (BMVC)</li> <li>• International Conference on 3D Vision (3DV)</li> <li>• Neural Information Processing Systems (NIPS)</li> </ul>	
	Program Chair	
	<ul style="list-style-type: none"> <li>• The Visual Learning and Reasoning for Robotic Manipulation workshop at RSS, 2020</li> </ul>	
	Program Chair	
	<ul style="list-style-type: none"> <li>• 5th International IEEE Workshop on 3D Representation and Recognition, 2015</li> </ul>	
	Program Committee	
	<ul style="list-style-type: none"> <li>• 4th International IEEE Workshop on 3D Representation and Recognition, 2013</li> </ul>	
	Tutorial Organizer	
	<ul style="list-style-type: none"> <li>• 3D Object Geometry from Single Image Tutorial at International Conference on 3D Vision, 2016</li> </ul>	
	TALKS	
	<b>Learning RGB-D Feature Embeddings for Unseen Object Instance Segmentation</b> In NVIDIA Research, Seattle, Washington, 10/12/2020.	

**PoseRBPF: A Rao-Blackwellized Particle Filter for 6D Object Pose Tracking**

In University of Washington, Seattle, Washington, 9/27/2019.

**Object Perception for Robot Manipulation**

In Toyota Research Institute, Cambridge, Massachusetts, 7/12/2019.

**PoseCNN: A Convolutional Neural Network for 6D Object Pose Estimation in Cluttered Scenes**

In Robotics: Science and Systems (RSS), CMU, Pittsburgh, Pennsylvania, 6/26/2018.

**Perceiving the 3D World from Images and Videos**

In Nvidia Research, Redmond, Washington, 11/07/2017; University of Michigan, 3/15/2018.

**3D Object Recognition and Scene Understanding from RGB-D Videos**

In GRASP Lab at University of Pennsylvania, 10/11/2017; Microsoft Research, Redmond, 10/17/2017; Vision Lab at Stanford University, 10/23/2017.

**3D Object Recognition and Scene Understanding**

In Mitsubishi Electric Research Laboratories, Boston, Massachusetts, 7/14/2017.

**DA-RNN: Semantic Mapping with Data Associated Recurrent Neural Networks**

In Robotics: Science and Systems, Massachusetts Institute of Technology, Massachusetts, 7/13/2017.

**Subcategory-aware Convolutional Neural Networks for Object Proposals and Detection**

In IEEE Winter Conference on Applications of Computer Vision, Santa Rosa, California, 3/29/2017.

**Tutorial on 3D Object Recognition**

In International Conference on 3D Vision, Stanford University, 10/28/2016.

**3D Object Representations for Recognition**

In Carnegie Mellon University, 3/28/2016; University of Toronto, 4/4/2016; Massachusetts Institute of Technology, 4/12/2016; University of California, Berkeley, 4/21/2016; University of Illinois at Urbana-Champaign, 5/5/2016; University of Washington, 5/31/2016.

**3D Object Detection and Pose Estimation**

In the 1st International Workshop on Recovering 6D Object Pose in conjunction with ICCV, Santiago, Chile, 12/17/2015.

**Learning to Track: Online Multi-Object Tracking by Decision Making**

In International Conference on Computer Vision, Santiago, Chile, 12/16/2015.

**Data-Driven 3D Voxel Patterns for Object Category Recognition**

In IEEE Conference on Computer Vision and Pattern Recognition, Boston, Massachusetts, 06/08/2015.

**Monocular Multiview Object Tracking with 3D Aspect Parts**

In the 1st Stanford-SNU Workshop on Automated Driving, Stanford University, 02/24/2015.

**Beyond PASCAL: A Benchmark for 3D Object Detection in the Wild**

In IEEE Winter Conference on Applications of Computer Vision, Steamboat Springs, Colorado, 03/24/2014.

**Object Detection by 3D Aspectlets and Occlusion Reasoning**

In the 4th International IEEE Workshop on 3D Representation and Recognition in conjunction with ICCV, Sydney, Australia, 12/08/2013.

**Estimating the Aspect Layout of Object Categories**

In Midwest Vision Workshop, University of Illinois at Urbana-Champaign, 09/21/2012.

**SKILLS AND  
LANGUAGES**

Programming Languages: Python, C/C++, CUDA

Libraries: PyTorch, Tensorflow, OpenCV, OpenGL

Operating Systems: Linux, Windows and Mac OS X

Languages: English, Chinese