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WORK EXPERIENCE / LEADERSHIP

Huawei Technologies | Deep Learning Research Engineer Intern

May 2019 - Aug 2019

- Wireless communications team
- Utilized generative models for 5G Technologies and wireless applications
- Worked with models such as Normalizing Flows and Variational Autoencoders

Robokids Richmond, B.C., And Vancouver, B.C | Robotics Instructor

June 2018 - Aug 2018

Educated over 30 students on programming concepts using Scratch, Lego Mindstorm, VEX IQ

University of Toronto's Robotics Association | Sponsorships & Finance Director

Dec 2018 - Current

- Led the sponsorships team to organize UtraHacks to accommodate over 250 students in the event
- Acquired sponsorship from Solidworks, Particle, Leapmotion, Nvidia totaling over \$4000 in value

PROJECTS / COMPETITIONS

TurnDownForWhat | React-native App at TreeHacks (Stanford University)

Feb 2018

- Detected movement using the smartphone accelerometer to lower music volume when falling asleep
- Interfaced the back-end with React-Native with HTML 5 and hosted on Expo.io
- Architected a Node.js server to convert form data voice input to streams to integrate Houndify and Expo.io

EtherRide | BlockChain Car Rental at UofTHacks VI (University of Toronto)

Jan 2019

- Received the Best Aragon App by ChainSafe award out of 102 team submissions
- Developed two React.js apps to communicate with the Aragon API and SmartCar API
- Monitored back-end Solidity smart contracts using Ethers.js and interfaced with SmartCar through HTTP

Personal Website | URL: yuxuanyyx.com

Dec 2018 - Current

- Designed and implemented the interface using React.js
- Utilized React's state, props, and event handling to enable parallax scrolling and on-scroll animation
- Deployed the website using Heroku and linked with an individual domain

Avacancy | Computer Vision at HackPrinceton (Princeton University)

Nov 2018

- Processed video footage of parking lot surveillance camera through perspective transform and binarization
- Utilized openCV to identify locations of vacant parking space within video footage
- Converted data into parking space map for real-time representation of parking availability

Autonomous Robot | SUMO competition

Oct 2017 - Apr 2018

- Placed first out of 40 teams entered in the competition
- Designed an Arduino algorithm by employing ultrasonic sensors to increase detection range to 4m

TECHNICAL SKILLS

Programming Languages C/C++, Python, MATLAB, Arduino, Bash, Swift

Web Development HTML/CSS/Javascript, JSX, Django, Flask, MongoDB, Node.js, React.js

Others Git, Linux, Scikit-learn, Keras, OpenCV, Verilog HDL, Solidity, MS Office

EDUCATION / AWARDS

BASc in Computer Engineering (2nd Year) | University of Toronto

Sep 2017 - Apr 2021

- CGPA: 3.52 / 4.0
- Awards: B.C. Achievement Scholarship, National AP Scholar (Canada)
- Dean's List Award: Fall '17, Winter '18, Fall '18