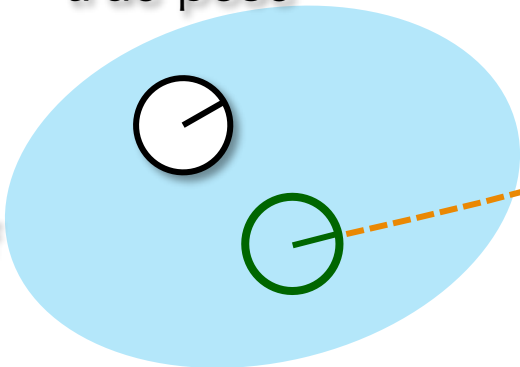


true pose



belief



estimated pose

path planning

