1.

(a)

Represent the operation using 4×4 matrices that shows the mapping between the nodes.

(b)

$$g_{123} = \begin{pmatrix} & & 1 & \\ 1 & & & \\ & 1 & & \\ & & & 1 \end{pmatrix}$$

$$g_{234} = \begin{pmatrix} 1 & & & \\ & & & 1 \\ & & & 1 \\ & & 1 & \end{pmatrix}$$

$$g_{234}g_{123} = \begin{pmatrix} & 1 & & \\ 1 & & & \\ & & & 1 \\ & & & 1 \end{pmatrix} = T_4$$

(180° rotation around the the axis connecting the middle of 1-2 and 3-4)

$$g_{123}g_{234} = \begin{pmatrix} & & 1 & \\ & & & 1 \\ 1 & & & \\ & 1 & & \end{pmatrix} = T_9 \neq T_4$$

(c)

See (a)

(d)

$$H = \begin{pmatrix} \varepsilon_0 & -t & -t & -t \\ -t & \varepsilon_0 & -t & -t \\ -t & -t & \varepsilon_0 & -t \\ -t & -t & -t & \varepsilon_0 \end{pmatrix}$$

Eigenvalues are $\varepsilon_0 - 3t$ for eigenvector $\left(\frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2}\right)$ and $\varepsilon_0 + t$ for eigenvectors, $\left(\frac{1}{2}, \frac{1}{2}, -\frac{1}{2}, -\frac{1}{2}\right)$, $\left(\frac{1}{2}, -\frac{1}{2}, \frac{1}{2}, -\frac{1}{2}, \frac{1}{2}\right)$.

- 2.
- (a)
- (b)
- (c)
- 3.
- 4.
- (a)
- (b)
- (c)
- (d)
- (e)
- **5.**
- (a)
- (b)
- (c)