## 1 Convexity and linear classification

1. Convexity.

- (a) f''(x) = 2: convex
- (b) f''(x) = -2: concave
- (c) f''(x) = 2: convex
- (d) f''(x) = 0: both convex and concave
- (e) f''(x) = 6x and  $x \in \mathbb{R}$ : neither convex nor concave
- (f)  $f''(x) = 12x^2$  and  $x \in \mathbb{R}$ : convex
- (g)  $f''(x) = -\frac{1}{x^2}$  and  $x \in \mathbb{R}$ : concave
- 2.  $M = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$ . For any vector  $x = (x_1, x_2)$ , we have  $x^T M x = 2x_1 x_2$ . This is not always  $\geq 0$ ; for instance, take  $x_1 = 1$  and  $x_2 = -1$ . Thus M is not PSD.
- 3.  $M = \begin{pmatrix} 1 & -1 \\ -1 & 1 \end{pmatrix}$ . For any vector  $x = (x_1, x_2)$ , we have  $x^T M x = x_1^2 2x_1 x_2 + x_2^2 = (x_1 x_2)^2 \ge 0$ . Thus M is PSD.
- 4. Let U be the matrix where the *i*th row is  $v_i$ . I.e.

$$U = \begin{pmatrix} \cdots & v_1 & \cdots \\ - & v_2 & \cdots \\ \vdots & & & \\ - & v_n & \cdots \end{pmatrix}$$

Then  $(UU^T)_{ij} = v_i \cdot v_j = M_{ij}$ . Thus M can be written as  $UU^T$  and is positive semidefinite.

5. F(x) is convex. To see this, we take double partial derivatives to get

$$\frac{\partial F}{\partial x_i} = 2(x_i - u_i)$$

and

$$\frac{\partial^2 L}{\partial x_i \partial x_j} = \begin{cases} 2 & \text{if } i = j \\ 0 & \text{if } i \neq j \end{cases}$$

Thus the Hessian H of F is a diagonal matrix with every diagonal entry set to 2. This is positive semidefinite since  $z^T H z = 2||z||^2 \ge 0$  for all  $z \in \mathbb{R}^d$ .

- 6. Recall  $F(x) = e^{u \cdot x}$ .
  - (a) We have  $dF/dx_j = e^{u \cdot x}u_j$  and  $d^2F/dx_i dx_j = e^{u \cdot x}u_i u_j$ . Thus the Hessian matrix is  $H(x) = e^{u \cdot x}u u^T$ .

1

(b) For any  $z \in \mathbb{R}^d$ , and any  $x \in \mathbb{R}^d$ , we have

$$z^T H(x)z = e^{u \cdot x} z^T u u^T z = e^{u \cdot x} (u \cdot z)^2 \ge 0.$$

Thus H(x) is positive semidefinite, and F is convex.

7. We want to analyze  $F(p) = -\sum_{i=1}^{m} p_i \ln p_i$ . We will show that F is concave by demonstrating that G(x) = -F(x) is convex.

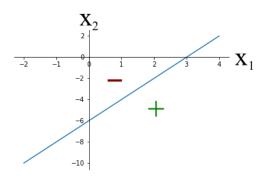
$$\frac{\partial G}{\partial p_i} = \ln p_i + \frac{p_i}{p_i} = 1 + \ln p_i$$

and

$$\frac{\partial^2 G}{\partial p_i \partial p_k} = \begin{cases} \frac{1}{p_i} & \text{if } i = k \\ 0 & \text{if } i \neq k \end{cases}$$

Since the Hessian is a diagonal matrix with nonnegative entries, it is positive semidefinite, and thus G is convex and F is concave.

8. The decision boundary plot should look something like the plot below.



- 9. (a) **Definitely true.** If the data set were not linearly separable, Perceptron would never converge.
  - (b) **Definitely true.** Since the data is linearly separable, Perceptron is guaranteed to converge, no matter what the ordering of the points might be.
  - (c) **Possibly false.** Different orderings of the data can produce different numbers of updates before convergence. We saw examples of this in class.
  - (d) **Possibly false.** There could be several updates on any given data point, and thus k is not necessarily upper-bounded by n.
- 10. Each time the Perceptron algorithm performs an update a point with label y, it updates its offset b as b = b + y. Thus if we start with b = 0 and perform p updates on points with y = -1 and q updates on points with y = +1, then the final value of b is b = q p.

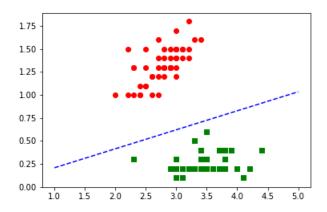
## 2 Programming exercise

(a) The classification code can be written as follows.

The perceptron algorithm can be written as follows.

```
def perceptron(data, labels):
n = len(labels)
inds = np.random.permutation(n)
data = data[inds,:]
labels = labels[inds]
n_{correct} = 0
w = np.zeros(np.shape(data)[1])
b = 0
while(n_correct < n):</pre>
    n_{correct} = 0
    for i in range(n):
        if (classify(w, b, data[i,:]) == labels[i]):
            n_{correct} += 1
        else:
             w = w + labels[i]*data[i,:]
             b = b + labels[i]
return(w,b)
```

(c) The perceptron boundary should look something like the following plot.



(d) The histogram should look something like the following.

