Informative projections

Dimensionality reduction

Why reduce the number of features in a data set?

- 1 It reduces storage and computation time.
- 2 High-dimensional data often has a lot of redundancy.
- 3 Remove noisy or irrelevant features.

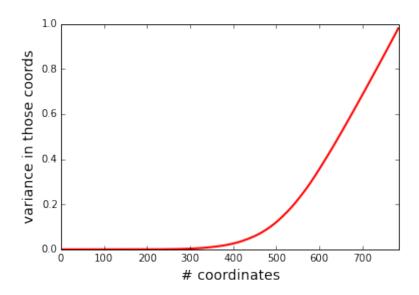
Example: are all the pixels in an image equally informative?



If we were to choose a few pixels to discard, which would be the prime candidates?

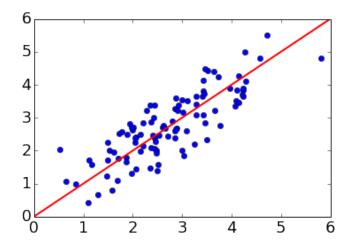
Eliminating low variance coordinates

MNIST: what fraction of the total variance lies in the 100 (or 200, or 300) coordinates with lowest variance?



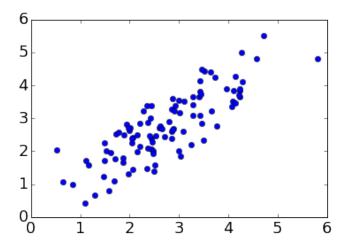
The effect of correlation

Suppose we wanted just one feature for the following data.



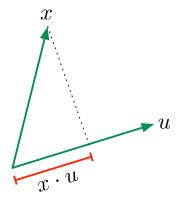
This is the direction of maximum variance.

Comparing projections



Projection: formally

What is the projection of $x \in \mathbb{R}^d$ in the **direction** $u \in \mathbb{R}^d$? Assume u is a unit vector (i.e. ||u|| = 1).



Projection is

$$x \cdot u = u \cdot x = u^T x = \sum_{i=1}^d u_i x_i.$$

Examples

What is the projection of $x = \begin{pmatrix} 2 \\ 3 \end{pmatrix}$ along the following directions?

- 1 The x_1 -axis?
- **2** The direction of $\begin{pmatrix} 1 \\ -1 \end{pmatrix}$?

The best direction

Suppose we need to map our data $x \in \mathbb{R}^d$ into just **one** dimension:

$$x \mapsto u \cdot x$$
 for some unit direction $u \in \mathbb{R}^d$

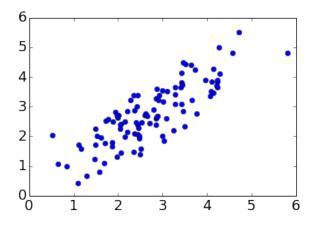
What is the direction u of maximum variance?

Useful fact 1:

- Let Σ be the $d \times d$ covariance matrix of X.
- The variance of X in direction u (the variance of $X \cdot u$) is:

$$u^T \Sigma u$$
.

Best direction: example



Here covariance matrix
$$\boldsymbol{\Sigma} = \begin{pmatrix} 1 & 0.85 \\ 0.85 & 1 \end{pmatrix}$$

The best direction

Suppose we need to map our data $x \in \mathbb{R}^d$ into just **one** dimension:

$$x \mapsto u \cdot x$$
 for some unit direction $u \in \mathbb{R}^d$

What is the direction u of maximum variance?

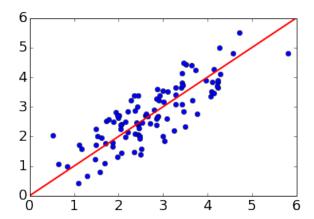
Useful fact 1:

- Let Σ be the $d \times d$ covariance matrix of X.
- The variance of X in direction u is given by $u^T \Sigma u$.

Useful fact 2:

- $u^T \Sigma u$ is maximized by setting u to the first **eigenvector** of Σ .
- The maximum value is the corresponding eigenvalue.

Best direction: example



Direction: first eigenvector of the 2×2 covariance matrix of the data.

Projection onto this direction: the top **principal component** of the data

Projection onto multiple directions

Projecting $x \in \mathbb{R}^d$ into the k-dimensional subspace defined by vectors $u_1, \ldots, u_k \in \mathbb{R}^d$.

This is easiest when the u_i 's are **orthonormal**:

- They have length one.
- ullet They are at right angles to each other: $u_i \cdot u_j = 0$ when i
 eq j

The projection is a k-dimensional vector:

$$(x \cdot u_1, x \cdot u_2, \dots, x \cdot u_k) = \underbrace{\begin{pmatrix} \longleftarrow & u_1 & \longrightarrow \\ \longleftarrow & u_2 & \longrightarrow \\ & \vdots & & \\ \longleftarrow & u_k & \longrightarrow \end{pmatrix}}_{\text{call this } U^T} \begin{pmatrix} \uparrow \\ x \\ \downarrow \end{pmatrix}$$

U is the $d \times k$ matrix with columns u_1, \ldots, u_k .

Projection onto multiple directions: example

E.g. project data in \mathbb{R}^4 onto the first two coordinates.

Take vectors
$$u_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \\ 0 \end{pmatrix}, \quad u_2 = \begin{pmatrix} 0 \\ 1 \\ 0 \\ 0 \end{pmatrix}$$
 (notice: orthonormal)

Write $U^T = \begin{pmatrix} \longleftarrow & u_1 & \longrightarrow \\ \longleftarrow & u_2 & \longrightarrow \end{pmatrix} = \begin{pmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \end{pmatrix}$

The projection of
$$x \in \mathbb{R}^4$$
 is $U^T x = \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}$

The best *k*-dimensional projection

Let Σ be the $d \times d$ covariance matrix of X. In $O(d^3)$ time, we can compute its **eigendecomposition**, consisting of

- real **eigenvalues** $\lambda_1 \geq \lambda_2 \geq \cdots \geq \lambda_d$
- corresponding **eigenvectors** $u_1, \ldots, u_d \in \mathbb{R}^d$ that are orthonormal (unit length and at right angles to each other)

Fact: Suppose we want to map data $X \in \mathbb{R}^d$ to just k dimensions, while capturing as much of the variance of X as possible. The best choice of projection is:

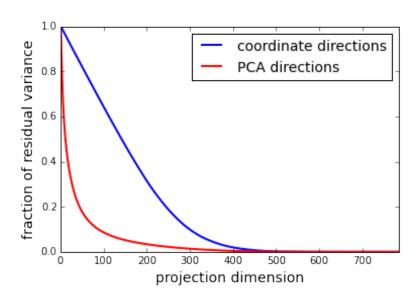
$$x \mapsto (u_1 \cdot x, u_2 \cdot x, \dots, u_k \cdot x),$$

where u_i are the eigenvectors described above.

This projection is called **principal component analysis** (PCA).

Example: MNIST

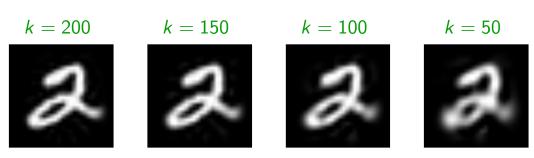
Contrast coordinate projections with PCA:



Applying PCA to MNIST: examples

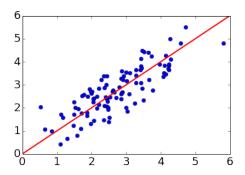


Reconstruct this original image from its PCA projection to k dimensions.

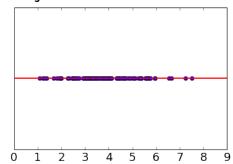


How do we get these **reconstructions**?

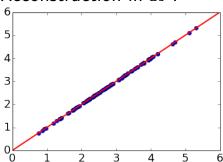
Reconstruction from a 1-d projection



Projection onto \mathbb{R} :



Reconstruction in \mathbb{R}^2 :



Reconstruction from multiple projections

Projecting into the k-dimensional subspace defined by **orthonormal** $u_1, \ldots, u_k \in \mathbb{R}^d$.

The projection of x is a k-dimensional vector:

$$(x \cdot u_1, x \cdot u_2, \dots, x \cdot u_k) = \underbrace{\begin{pmatrix} \longleftarrow & u_1 & \longrightarrow \\ \longleftarrow & u_2 & \longrightarrow \\ & \vdots & & \\ \longleftarrow & u_k & \longrightarrow \end{pmatrix}}_{\text{call this } U^T} \begin{pmatrix} \uparrow \\ \chi \\ \downarrow \end{pmatrix}$$

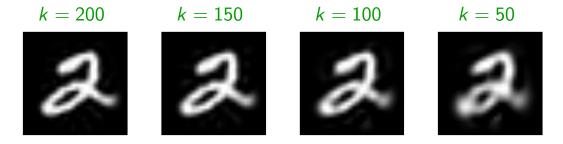
The reconstruction from this projection is:

$$(x \cdot u_1)u_1 + (x \cdot u_2)u_2 + \cdots + (x \cdot u_k)u_k = UU^Tx.$$

MNIST: image reconstruction

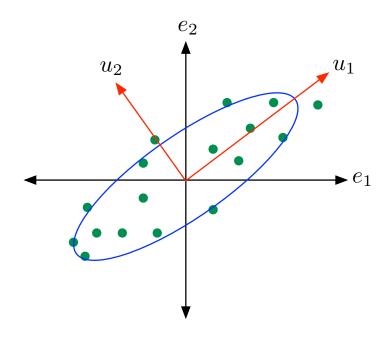


Reconstruct this original image x from its PCA projection to k dimensions.



Reconstruction UU^Tx , where U's columns are top k eigenvectors of Σ .

Linear algebra: eigenvalues and eigenvectors



The linear function defined by a matrix

- Any matrix M defines a linear function, $x \mapsto Mx$. If M is a $d \times d$ matrix, this maps \mathbb{R}^d to \mathbb{R}^d .
- This function is easy to understand when *M* is **diagonal**:

$$\underbrace{\begin{pmatrix} 2 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 10 \end{pmatrix}}_{M} \underbrace{\begin{pmatrix} x_1 \\ x_2 \\ x_3 \end{pmatrix}}_{x} = \underbrace{\begin{pmatrix} 2x_1 \\ -x_2 \\ 10x_3 \end{pmatrix}}_{Mx}$$

In this case, M simply scales each coordinate separately.

 General symmetric matrices also just scale coordinates separately... but in a different coordinate system!

Eigenvector and eigenvalue: definition

Let M be a $d \times d$ matrix. We say $u \in \mathbb{R}^d$ is an **eigenvector** of M if

$$Mu = \lambda u$$

for some scaling constant λ . This λ is the **eigenvalue** associated with u.

Key point: *M* maps eigenvector *u* onto the same direction.

Question: What are the eigenvectors and eigenvalues of:

$$M = \begin{pmatrix} 2 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 10 \end{pmatrix} ?$$

Eigenvectors of a real symmetric matrix

Fact: Let M be any real symmetric $d \times d$ matrix. Then M has

- d eigenvalues $\lambda_1, \ldots, \lambda_d$
- corresponding eigenvectors $u_1,\ldots,u_d\in\mathbb{R}^d$ that are orthonormal

Can think of u_1, \ldots, u_d as the axes of the natural coordinate system for M.

Example

$$M=egin{pmatrix} 1 & -2 \ -2 & 1 \end{pmatrix}$$
 has eigenvectors $u_1=rac{1}{\sqrt{2}} egin{pmatrix} 1 \ 1 \end{pmatrix}, \ u_2=rac{1}{\sqrt{2}} egin{pmatrix} -1 \ 1 \end{pmatrix}$

- Are these orthonormal?
- 2 What are the corresponding eigenvalues?

Spectral decomposition

Fact: Let M be any real symmetric $d \times d$ matrix. Then M has orthonormal eigenvectors $u_1, \ldots, u_d \in \mathbb{R}^d$ and corresponding eigenvalues $\lambda_1, \ldots, \lambda_d$.

Spectral decomposition: Another way to write *M*:

$$M = \underbrace{\begin{pmatrix} \uparrow & \uparrow & \uparrow \\ u_1 & u_2 & \cdots & u_d \\ \downarrow & \downarrow & \downarrow \end{pmatrix}}_{U: \text{ columns are eigenvectors}} \underbrace{\begin{pmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & \lambda_d \end{pmatrix}}_{\Lambda: \text{ eigenvalues on diagonal}} \underbrace{\begin{pmatrix} \leftarrow & u_1 & \longrightarrow \\ \leftarrow & u_2 & \longrightarrow \\ \vdots & \vdots & \ddots & \vdots \\ \leftarrow & u_d & \longrightarrow \end{pmatrix}}_{U^T}$$

Thus $Mx = U\Lambda U^Tx$:

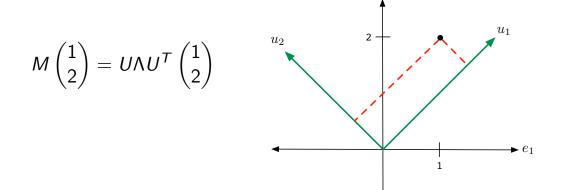
- U^T rewrites x in the $\{u_i\}$ coordinate system
- ullet Λ is a simple coordinate scaling in that basis
- *U* sends the scaled vector back into the usual coordinate basis

Apply spectral decomposition to the matrix we saw earlier:

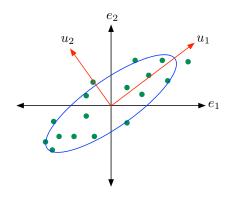
$$M = \begin{pmatrix} 1 & -2 \\ -2 & 1 \end{pmatrix}$$

- Eigenvectors $u_1 = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \ u_2 = \frac{1}{\sqrt{2}} \begin{pmatrix} -1 \\ 1 \end{pmatrix}$
- Eigenvalues $\lambda_1 = -1, \ \lambda_2 = 3.$

$$M = \begin{pmatrix} 1 & -2 \\ -2 & 1 \end{pmatrix} = \underbrace{\frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -1 \\ 1 & 1 \end{pmatrix}}_{U} \underbrace{\begin{pmatrix} -1 & 0 \\ 0 & 3 \end{pmatrix}}_{\Lambda} \underbrace{\frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ -1 & 1 \end{pmatrix}}_{U^{T}}$$



Principal component analysis revisited



Data vectors $X \in \mathbb{R}^d$

- $d \times d$ covariance matrix Σ is symmetric.
- Eigenvalues $\lambda_1 \geq \lambda_2 \geq \cdots \geq \lambda_d$ Eigenvectors u_1, \ldots, u_d .
- u_1, \ldots, u_d : another basis for data.
- Variance of X in direction u_i is λ_i .
- Projection to k dimensions: $x \mapsto (x \cdot u_1, \dots, x \cdot u_k)$.

What is the covariance of the projected data?

Case study: Quantifying personality

What are the dimensions along which personalities differ?

- Lexical hypothesis: most important personality characteristics have become encoded in natural language.
- Allport and Odbert (1936): identified 4500 words describing personality traits.
- Group these words into (approximate) synonyms, by manual clustering.

E.g. Norman (1967):

Spirit Talkativeness Sociability Spontaneity Boisterousness Adventure Energy Conceit Vanity Indiscretion Sensuality Jolly, merry, witty, lively, peppy Talkative, articulate, verbose, gossipy Companionable, social, outgoing Impulsive, carefree, playful, zany Mischievous, rowdy, loud, prankish Brave, venturous, fearless, reckless Active, assertive, dominant, energetic Boastful, conceited, egotistical Affected, vain, chic, dapper, jaunty Nosey, snoopy, indiscreet, meddlesome Sexy, passionate, sensual, flirtatious

• Data collection: subjects whether these words describe them.

Personality assessment: the data

Matrix of data (1 = strongly disagree, 5 = strongly agree)

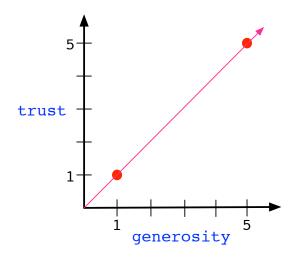
		Ę	. S	, z	10 stal	
	125	170	to)	900	LO LA	96/19
Person 1	4	1	1	2	5	5
Person 2	1	4	4	5	2	1
Person 3	2	4	5	4	2	2
		÷				

How to extract important directions?

- Treat each column as a data point, find tight clusters
- Treat each row as a data point, apply PCA
- Or factor analysis, independent component analysis, etc.

What would PCA accomplish?

E.g.: Suppose two traits (generosity, trust) are so highly correlated that each person either answers "1" to both or "5" to both.



A single PCA dimension would entirely account for both traits.

Personality assessment: the data

Matrix of data (1 = strongly disagree, 5 = strongly agree)

	345	mer	tense	90904	10, chu/	8mist on b
Person 1	4	1	1	2	5	5
Person 2	1	4	4	5	2	1
Person 3	2	4	5	4	2	2
		:				

Methodology: apply PCA to the rows of this matrix.

The "Big Five" taxonomy

Extraversion

- -: quiet (-.83), reserved (-.80), shy (-.75), silent (-.71)
- +: talkative (.85), assertive (.83), active (.82), energetic (.82)

Agreeableness

- -: fault-finding (-.52), cold (-.48), unfriendly (-.45), quarrelsome (-.45)
- +: sympathetic (.87), kind (.85), appreciative (.85), affectionate (.84)

Conscientousness

- -: careless (-.58), disorderly (-.53), frivolous (-.50), irresponsible (-.49)
- +: organized (.80), thorough (.80), efficient (.78), responsible (.73)

Neuroticism

- -: stable (-.39), calm (-.35), contented (-.21)
- +: tense (.73), anxious (.72), nervous (.72), moody (.71)

Openness

- -: commonplace (-.74), narrow (-.73), simple (-.67), shallow (-.55)
- +: imaginative (.76), intelligent (.72), original (.73), insightful (.68)