Python Code

Your Name

December 20, 2024

1 Task 1: Implementing Computational Graphs

Q1 :Implement the forward and backward passes for the computational graph f3 below.

```
def f3(s1, s2, y):
     Computes the forward and backward pass through the computational graph f3
     from the homework PDF.
     A few clarifications about the graph:
     - The input y is an integer with y == 1 or y == 2; you do not need to
       compute a gradient for this input.
     - The division nodes compute p1 = e1 / d and p2 = e2 / d
9
     - The choose(p1, p2, y) node returns p1 if y is 1, or p2 if y is 2.
10
     Inputs:
12
     - s1, s2: Python floats
13
     - y: Python integer, either equal to 1 or 2
14
16
     Returns a tuple of:
     - L: Python scalar giving the output of the graph
17
     - grads: A tuple (grad_s1, grad_s2) giving the derivative of the output L
18
    with respect to the inputs s1 and s2.
19
     assert y == 1 or y == 2
21
22
     # Forward pass: Compute loss
23
    L = None
     24
     # TODO: Implement the forward pass for the computational graph f3 shown
     # in the homework description. Store the loss in the variable L.
26
     27
    e1 = math.exp(s1)
28
    e2 = math.exp(s2)
29
    e11 = e1
30
     e12 = e1
31
     e21 = e2
32
     e22 = e2
33
     d = e11 + e21
34
     d1 = d
35
     d2 = d
36
     p1 = e12 / d1
37
    p2 = e22 / d2
38
     p_plus = p1*(2-y) - p2*(1-y)
39
     L = -1 * math.log(p_plus)
40
41
     42
                              END OF YOUR CODE
43
     45
     # Backward pass: Compute gradients
46
47
     grad_s1, grad_s2 = None, None
     48
     # TODO: Implement the backward pass for the computational graph f3 shown #
     \mbox{\tt\#} in the homework description. Store the gradients for each input
50
     # variable in the corresponding grad variagbles defined above. You do not #
     # need to compute a gradient for the input y since it is an integer.
52
53
     # HINT: You may need an if statement to backprop through the choose node #
```

```
55
    grad_L = 1
56
57
    grad_p_plus = -1*(grad_L / p_plus)
    grad_p1 = grad_p_plus * (2-y)
58
59
    grad_p2 = grad_p_plus * (y-1)
    grad_e12 = grad_p1 / d1
60
    grad_e22 = grad_p2 / d2
61
    grad_d1 = grad_p1 * e12 * -1 * (1 / d1**2)
62
    grad_d2 = grad_p2 * e22 * -1 * (1 / d2**2)
63
    grad_d = grad_d1 + grad_d2
   grad_e11 = grad_d
65
    grad_e21 = grad_d
66
67
    grad_e1 = grad_e11 + grad_e12
    grad_e2 = grad_e21 + grad_e22
68
   grad_s1 = math.exp(s1) * grad_e1
69
   grad_s2 = math.exp(s2) * grad_e2
70
    grad_y = grad_p_plus * (-p1 + p2)
71
    72
                          END OF YOUR CODE
73
    74
75
76
    grads = (grad_s1, grad_s2)
return L, grads
```

2 Task 2: Modular Backprop API

Q1 :Fully-connected layer: fc_forward and fc_backward.

```
def fc_forward(x, w, b):
1
2
    Computes the forward pass for a fully-connected layer.
3
    The input x has shape (N, Din) and contains a minibatch of N
    examples, where each example x[i] has shape (Din,).
6
8
   Inputs:
    - x: A numpy array of shape (N, Din) giving input data
9
10
    - w: A numpy array of shape (Din, Dout) giving weights
    - b: A numpy array of shape (Dout,) giving biases
11
12
   Returns a tuple of:
13
14
    - out: output, of shape (N, Dout)
15
    - cache: (x, w, b)
16
    out = None
17
   18
   # TODO: Implement the forward pass. Store the result in out.
   20
    out = x @ w + b
21
    22
                        END OF YOUR CODE
23
   cache = (x, w, b)
25
26
   return out, cache
27
```

```
def fc_backward(grad_out, cache):
2
      Computes the backward pass for a fully-connected layer.
3
5
      - grad_out: Numpy array of shape (N, Dout) giving upstream gradients
6
      - cache: Tuple of:
       - x: A numpy array of shape (N, Din) giving input data
        - w: A numpy array of shape (Din, Dout) giving weights
9
       - b: A numpy array of shape (Dout,) giving biases
10
11
     Returns a tuple of downstream gradients:
12
      - grad_x: A numpy array of shape (N, Din) of gradient with respect to x
13
- grad_w: A numpy array of shape (Din, Dout) of gradient with respect to w
```

```
15
   - grad_b: A numpy array of shape (Dout,) of gradient with respect to b
16
17
   x, w, b = cache
   grad_x , grad_w , grad_b = None , None , None
18
19
   20
   # TODO: Implement the backward pass for the fully-connected layer
   21
   grad_x = grad_out @ w.T
22
   grad_w = x.T @ grad_out
23
   grad_b = np.sum(grad_out,axis=0)
24
25
   26
                   END OF YOUR CODE
27
   28
  return grad_x, grad_w, grad_b
29
30
```

Q2 :relu_forward and relu_backward

A2:

```
def relu_forward(x):
1
2
   Computes the forward pass for the Rectified Linear Unit (ReLU) nonlinearity
3
   Input:
5
6
   - x: A numpy array of inputs, of any shape
7
   Returns a tuple of:
8
   - out: A numpy array of outputs, of the same shape as x
9
   - cache: x
10
11
   out = None
12
   13
   # TODO: Implement the ReLU forward pass.
14
   15
   out = np.maximum(0,x)
16
17
   18
                    END OF YOUR CODE
19
   20
21
   cache = x
   return out, cache
22
23
```

```
def relu_backward(grad_out, cache):
1
2
   Computes the backward pass for a Rectified Linear Unit (ReLU) nonlinearity
3
4
5
   - grad_out: Upstream derivatives, of any shape
6
   - cache: Input x, of same shape as dout
7
8
9
   - grad_x: Gradient with respect to x
10
11
   grad_x , x = None , cache
   13
   # TODO: Implement the ReLU backward pass.
14
   15
16
   grad_x = grad_out * (x > 0)
   17
                     END OF YOUR CODE
18
19
   return grad_x
20
21
```

Q3 :Softmax Loss Function:softmax_loss

A3 :

```
def softmax_loss(x, y):
1
2
     Computes the loss and gradient for softmax (cross-entropy) loss function.
3
4
5
6
     - x: Numpy array of shape (N, C) giving predicted class scores, where
7
      x[i, c] gives the predicted score for class c on input sample i
      y: Numpy array of shape (N,) giving ground-truth labels, where
8
      y[i] = c means that input sample i has ground truth label c, where
9
     0 <= c < C.
10
    Returns a tuple of:
12
13
     - loss: Scalar giving the loss
     - grad_x: Numpy array of shape (N, C) giving the gradient of the loss with
14
      with respect to x
15
16
    loss, grad_x = None, None
17
    18
     # TODO: Implement softmax loss
19
     20
    M = np.max(x,axis = 1,keepdims=True)
21
22
     x_minus_M = x - M
     exp_x = np.exp(x_minus_M)
23
24
     exp_x_each_row_sum = np.sum(exp_x,axis=1, keepdims=True)
25
    p_x = exp_x / exp_x_each_row_sum
26
    n = y.shape[0]
28
    loss = 0
29
    for i in range(n):
30
        true_label = y[i]
31
        p_true_label = p_x[i][true_label]
32
        log_p_true_label = np.log(p_true_label)
33
       loss += log_p_true_label
    loss = loss * -1 / n
35
36
37
    grad_x = p_x.copy() # Make a copy of p_x
38
    grad_x[np.arange(n), y] -= 1
     grad_x /= n
40
     41
                             END OF YOUR CODE
42
    43
    return loss, grad_x
44
45
```

Q4 :L2 Regularization: l2_regularization which implements the L2 regularization loss

A4:

```
def 12_regularization(w, reg):
1
2
   Computes loss and gradient for L2 regularization of a weight matrix:
3
   loss = (reg / 2) * sum_i w_i^2
5
6
   Where the sum ranges over all elements of w.
8
9
   Inputs:
   - w: Numpy array of any shape
    - reg: float giving the regularization strength
11
13
   Returns:
14
   loss, grad_w = None, None
15
   16
17
   # TODO: Implement L2 regularization.
   18
19
   sum_Wi_squre = np.sum(w**2)
   loss = (reg / 2) * sum_Wi_squre
20
   grad_w = reg * w
21
   22
23
                      END OF YOUR CODE
  24
```

```
return loss, grad_w
26
27
```

3 Task 3: Implement a Two-Layer Network

Q1 :Complete the implementation of the TwoLayerNet class. Your implementations for the forward and backward methods should use the modular forward and backward functions that you implemented in the previous task.

```
class TwoLayerNet(Classifier):
1
    A neural network with two layers, using a ReLU nonlinearity on its one
3
    hidden layer. That is, the architecture should be:
4
5
    input -> FC layer -> ReLU layer -> FC layer -> scores
6
    def __init__(self, input_dim=3072, num_classes=10, hidden_dim=512,
8
9
             weight_scale=1e-3):
11
       Initialize a new two layer network.
12
       Inputs:
13
14
       - input_dim: The number of dimensions in the input.
       - num_classes: The number of classes over which to classify
15
       - hidden_dim: The size of the hidden layer
16
17
       - weight_scale: The weight matrices of the model will be initialized
18
        from a Gaussian distribution with standard deviation equal to
        weight_scale. The bias vectors of the model will always be
19
        initialized to zero.
20
21
       22
       # TODO: Initialize the weights and biases of a two-layer network.
23
       24
       self.W1 = weight_scale * np.random.randn(input_dim, hidden_dim)
25
       self.b1 = np.zeros(hidden_dim)
       self.W2 = weight_scale * np.random.randn(hidden_dim, num_classes)
27
       self.b2 = np.zeros(num_classes)
28
       29
                          END OF YOUR CODE
30
       31
32
33
    def parameters(self):
       params = None
34
       35
       # TODO: Build a dict of all learnable parameters of this model.
36
       37
       params = {
38
          'W1': self.W1,
39
          'b1': self.b1,
40
          'W2': self.W2,
41
          'b2': self.b2,
42
       }
43
44
45
       END OF YOUR CODE
46
       47
       return params
48
49
    def forward(self, X):
50
       scores, cache = None, None
51
       52
       # TODO: Implement the forward pass to compute classification scores
53
       # for the input data X. Store into cache any data that will be needed #
54
       # during the backward pass.
55
       56
       W1 = self.W1
57
       W2 = self.W2
58
       b1 = self.b1
59
60
       b2 = self.b2
61
```

```
#first fc layer
62
        fc1_out, fc1_cache = fc_forward(X,W1,b1)
63
        #apply the Relu layer
64
        relu_out, relu_cache = relu_forward(fc1_out)
65
66
        #second fc layer
67
        fc2_out, fc2_cache = fc_forward(relu_out, W2, b2)
        cache = (fc1_cache, relu_cache, fc2_cache)
68
        scores = fc2\_out
69
70
71
        72
                            END OF YOUR CODE
73
        74
        return scores, cache
75
     def backward(self, grad_scores, cache):
77
        grads = None
        79
        # TODO: Implement the backward pass to compute gradients for all
80
81
        # learnable parameters of the model, storing them in the grads dict
        \mbox{\tt\#} above. The grads dict should give gradients for all parameters in
                                                             #
82
83
        # the dict returned by model.parameters().
        84
85
        W1 = self.W1
        W2 = self.W2
86
        b1 = self.b1
87
        b2 = self.b2
89
        fc1_cache, relu_cache, fc2_cache = cache
90
        grad_relu, grads_W2, grads_b2 = fc_backward(grad_scores, fc2_cache)
91
92
        grad_fc1 = relu_backward(grad_relu,relu_cache)
93
94
        trash, grads_W1, grads_b1 = fc_backward(grad_fc1,fc1_cache)
96
        grads = {
           'W1' : grads_W1,
97
           'b1' : grads_b1,
98
           'W2' : grads_W2,
99
           'b2' : grads_b2,
        }
102
        104
                            END OF YOUR CODE
105
        106
        return grads
107
108
```

4 Task4: Training Two-Layer Networks

Q1: Implement the training_step function in the file neuralnettrainpy

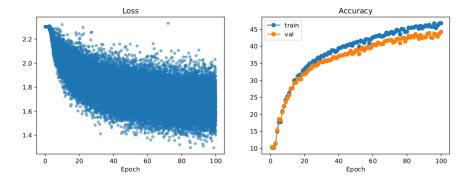
```
def training_step(model, X_batch, y_batch, reg):
1
2
      Compute the loss and gradients for a single training iteration of a model
3
      given a minibatch of data. The loss should be a sum of a cross-entropy loss
      between the model predictions and the ground-truth image labels, and
      an L2 regularization term on all weight matrices in the fully-connected
6
      layers of the model. You should not regularize the bias vectors.
8
     Inputs:
9
      - model: A Classifier instance
10
      - X_batch: A numpy array of shape (N, D) giving a minibatch of images
11
       y_batch: A numpy array of shape (N,) where 0 <= y_batch[i] < C is the
12
        ground-truth label for the image X_batch[i]
13
      - reg: A float giving the strength of L2 regularization to use.
14
15
      Returns a tuple of:
16
      - loss: A float giving the loss (data loss + regularization loss) for the
17
18
       model on this minibatch of data
```

```
- grads: A dictionary giving gradients of the loss with respect to the
19
      parameters of the model. In particular grads[k] should be the gradient
20
21
      of the loss with respect to model.parameters()[k].
22
23
    loss, grads = None, None
     24
     # TODO: Compute the loss and gradient for one training iteration.
25
     26
     prediction, cache = model.forward(X_batch)
27
     #compute the data loss
29
     data_loss, grad_x = softmax_loss(prediction,y_batch)
30
31
     #compute the regularization loss
32
    reg_loss = 0
33
     for param_name, param in model.parameters().items():
34
        if param_name.startswith('W'):
           reg_loss += 12_regularization(param, reg)[0]
36
     #calculate the total loss
37
38
     loss = data_loss + reg_loss
39
40
     grads = model.backward(grad_x,cache)
41
42
    for param_name in grads:
        if param_name.startswith('W'):
43
           grads[param_name] += reg * model.parameters()[param_name]
44
     46
                            END OF YOUR CODE
47
     48
     return loss, grads
49
50
```

Q2 :include the loss / accuracy plot for your best model, describe the hyperparameter settings you used, and give the final test-set performance of your model.

A2: the parameter I use here is:

```
# How much data to use for training
      num_train = 20000
2
3
      # Model architecture hyperparameters.
      hidden_dim = 64
6
      # Optimization hyperparameters.
      batch\_size = 64
      num_epochs = 100
9
10
      learning_rate = 0.005
      reg = 0.01
11
12
```



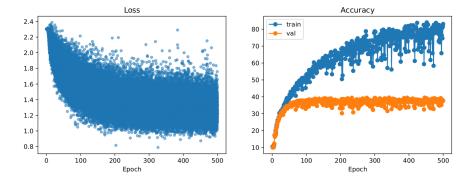
Q3: include the loss / accuracy plot for your overfit model and describe the hyperparameter settings you used.

A3: the parameter I use here is:

```
# How much data to use for training
num_train = 3000

# Model architecture hyperparameters.
hidden_dim = 64

# Optimization hyperparameters.
batch_size = 32
num_epochs = 500
learning_rate = 0.01
reg = 0.01
```



5 Task 5: Train Your Own Classification Model

Q1 :Submit the notebook (with outputs) that trains with your best combination of model architecture, optimizer and training parameters, and evaluates on the test set to report an accuracy at the end.

EECS442 HW4 task5 report

March 19, 2024

1 EECS 442 Homework 4: Fashion-MNIST Classification

In this part, you will implement and train Convolutional Neural Networks (ConvNets) in PyTorch to classify images. Unlike HW4 Secion 1, backpropagation is automatically inferred by PyTorch, so you only need to write code for the forward pass.

Before we start, please put your name and UMID in following format Firstname LASTNAME, #00000000 // e.g.) David FOUHEY, #12345678

Your Answer:

Hello EECS442 #12345678

1.1 Setup

```
[]: # Run the command in the terminal if it failed on local Jupyter Notebook, useremove "!" before each line
!pip install torchsummary
```

```
[]: import numpy as np
  import matplotlib.pyplot as plt
  from tqdm import tqdm # Displays a progress bar

import torch
  from torch import nn
  from torch import optim
  import torch.nn.functional as F
  from torchsummary import summary
  from torchvision import datasets, transforms
  from torch.utils.data import Dataset, Subset, DataLoader, random_split
```

```
[]: if torch.cuda.is_available():
    print("Using the GPU. You are good to go!")
    device = 'cuda'
else:
    print("Using the CPU. Overall speed may be slowed down")
    device = 'cpu'
```

Using the CPU. Overall speed may be slowed down

1.2 Loading Dataset

The dataset we use is Fashion-MNIST dataset, which is available at https://github.com/zalandoresearch/fashion-mnist and in torchvision.datasets. Fashion-MNIST has 10 classes, 60000 training+validation images (we have splitted it to have 50000 training images and 10000 validation images, but you can change the numbers), and 10000 test images.

Loading datasets...
Done!

Now, we will create the dataloder for train, val and test dataset. You are free to experiment with different batch sizes.

1.3 Model

Initialize your model and experiment with with different optimizers, parameters (such as learning rate) and number of epochs.

```
[]: class Network(nn.Module):
    def __init__(self):
        super().__init__()
```

```
# TODO: Design your own network, define layers here.
    # Here We provide a sample of two-layer fc network from HW4 Part3.
    # Your solution, however, should contain convolutional layers.
    # Refer to PyTorch documentations of torch.nn to pick your layers.
    # (https://pytorch.org/docs/stable/nn.html)
                                                     ш
    # Some common choices: Linear, Conv2d, ReLU, MaxPool2d, AvqPool2d,
\hookrightarrow Dropout
    # If you have many layers, use nn. Sequential() to simplify your code
self.conv1 = nn.
Gonv2d(in channels=1,out_channels=16,kernel_size=3,stride=1,padding=1)
    self.conv2 = nn.Conv2d(in_channels=16, out_channels=32,kernel_size=3,__
⇒stride=1, padding=1)
    self.relu = nn.ReLU()
    self.pool = nn.MaxPool2d(kernel_size=2,stride=2)
    self.fc1 = nn.Linear(32*7*7, 128)
    self.fc2 = nn.Linear(128, 10)
END OF YOUR CODE
    #
    #
def forward(self, x):
# TODO: Design your own network, implement forward pass here
    #
x = self.pool(self.relu(self.conv1(x)))
    x = self.pool(self.relu(self.conv2(x)))
    x = x.view(-1,32*7*7)
```

```
x = self.relu(self.fc1(x))
    x = self.fc2(x)
    return x
END OF YOUR CODE
    #
model = Network().to(device)
criterion = nn.CrossEntropyLoss() # Specify the loss layer
print('Your network:')
print(summary(model, (1,28,28), device=device)) # visualize your model
# TODO: Modify the lines below to experiment with different optimizers,
# parameters (such as learning rate) and number of epochs.
# Set up optimization hyperparameters
learning_rate, weight_decay, num_epoch = 0.001, 0.001, 10
optimizer = optim.Adam(model.parameters(), lr = learning_rate,_
⇒weight decay=weight decay)
END OF YOUR CODE
```

Your network:

Layer (type) Output Shape ______ [-1, 16, 28, 28] Conv2d-1 160 [-1, 16, 28, 28] ReLU-2 0 MaxPool2d-3 [-1, 16, 14, 14] 0 Conv2d-4 [-1, 32, 14, 14]4,640 [-1, 32, 14, 14] ReLU-5 0 MaxPool2d-6 [-1, 32, 7, 7]0 200,832 Linear-7 [-1, 128] [-1, 128]ReLU-8 Linear-9 [-1, 10]1,290

Total params: 206,922 Trainable params: 206,922 Non-trainable params: 0

Input size (MB): 0.00

Forward/backward pass size (MB): 0.33

Run the cell below to start your training, we expect you to achieve over 85% on the test set. A valid solution that meet the requirement take no more than 10 minutes on normal PC Intel core CPU setting. If your solution takes too long to train, try to simplify your model or reduce the number of epochs.

```
[]: |%%time
    def train(model, trainloader, valloader, num_epoch=10): # Train the model
        print("Start training...")
        trn loss hist = []
        trn_acc_hist = []
        val acc hist = []
        model.train() # Set the model to training mode
        for i in range(num_epoch):
            running loss = []
            print('-----' % (i+1))
            for batch, label in tqdm(trainloader):
                batch = batch.to(device)
                label = label.to(device)
                optimizer.zero_grad() # Clear gradients from the previous iteration
                # This will call Network.forward() that you implement
                pred = model(batch)
                loss = criterion(pred, label) # Calculate the loss
                running_loss.append(loss.item())
                loss.backward() # Backprop gradients to all tensors in the network
                optimizer.step() # Update trainable weights
            print("\n Epoch {} loss:{}".format(i+1, np.mean(running_loss)))
            # Keep track of training loss, accuracy, and validation loss
            trn_loss_hist.append(np.mean(running_loss))
            trn_acc_hist.append(evaluate(model, trainloader))
            print("\n Evaluate on validation set...")
            val_acc_hist.append(evaluate(model, valloader))
        print("Done!")
        return trn_loss_hist, trn_acc_hist, val_acc_hist
    def evaluate (model, loader): # Evaluate accuracy on validation / test set
        model.eval() # Set the model to evaluation mode
        correct = 0
        with torch.no_grad(): # Do not calculate grident to speed up computation
            for batch, label in tqdm(loader):
                batch = batch.to(device)
                label = label.to(device)
```

```
pred = model(batch)
          correct += (torch.argmax(pred, dim=1) == label).sum().item()
       acc = correct/len(loader.dataset)
       print("\n Evaluation accuracy: {}".format(acc))
       return acc
trn_loss_hist, trn_acc_hist, val_acc_hist = train(model, trainloader,
                                         valloader, num epoch)
# TODO: Note down the evaluation accuracy on test set
print("\n Evaluate on test set")
evaluate(model, testloader)
Start training...
-----Epoch = 1-----
100%|
        | 1000/1000 [00:11<00:00, 88.20it/s]
Epoch 1 loss:0.45427982886135576
100%|
        | 1000/1000 [00:08<00:00, 116.68it/s]
Evaluation accuracy: 0.88322
Evaluate on validation set...
100%|
        | 200/200 [00:01<00:00, 112.52it/s]
Evaluation accuracy: 0.8756
-----Epoch = 2-----
100%|
        | 1000/1000 [00:14<00:00, 68.83it/s]
Epoch 2 loss:0.3132331562563777
100%|
        | 1000/1000 [00:13<00:00, 75.81it/s]
Evaluation accuracy: 0.90188
Evaluate on validation set...
100%|
        | 200/200 [00:02<00:00, 76.01it/s]
```

Evaluation accuracy: 0.8898

-----Epoch = 3-----| 1000/1000 [00:20<00:00, 47.72it/s] Epoch 3 loss:0.27816830180585383 100%| | 1000/1000 [00:20<00:00, 48.48it/s] Evaluation accuracy: 0.90692 Evaluate on validation set... 100%| | 200/200 [00:04<00:00, 48.26it/s] Evaluation accuracy: 0.8909 -----Epoch = 4-----100%| | 1000/1000 [00:32<00:00, 30.58it/s] Epoch 4 loss:0.25694305121526123 100%| | 1000/1000 [00:23<00:00, 43.44it/s] Evaluation accuracy: 0.9169 Evaluate on validation set... 100%| | 200/200 [00:04<00:00, 42.62it/s] Evaluation accuracy: 0.8977 -----Epoch = 5-----100%| | 1000/1000 [00:33<00:00, 29.63it/s] Epoch 5 loss:0.24221466190367938 100% | 1000/1000 [00:26<00:00, 38.06it/s] Evaluation accuracy: 0.92516 Evaluate on validation set... 100%| | 200/200 [00:05<00:00, 35.77it/s] Evaluation accuracy: 0.906 -----Epoch = 6-----

| 1000/1000 [00:34<00:00, 28.83it/s]

Epoch 6 loss:0.22939964060112833

100% | 1000/1000 [00:26<00:00, 37.96it/s]

Evaluation accuracy: 0.92846

Evaluate on validation set...

100% | 200/200 [00:04<00:00, 42.81it/s]

Evaluation accuracy: 0.906

-----Epoch = 7-----

100% | 1000/1000 [00:35<00:00, 28.18it/s]

Epoch 7 loss:0.21812415209040045

100% | 1000/1000 [00:26<00:00, 38.35it/s]

Evaluation accuracy: 0.93176

Evaluate on validation set...

100%| | 200/200 [00:04<00:00, 43.88it/s]

Evaluation accuracy: 0.9114

-----Epoch = 8-----

100% | 1000/1000 [00:33<00:00, 30.26it/s]

Epoch 8 loss:0.21002072999626398

100% | 1000/1000 [00:24<00:00, 41.14it/s]

Evaluation accuracy: 0.93376

Evaluate on validation set...

100%| | 200/200 [00:04<00:00, 41.02it/s]

Evaluation accuracy: 0.9128

-----Epoch = 9-----

100% | 1000/1000 [00:35<00:00, 28.40it/s]

Epoch 9 loss:0.20510010103322565

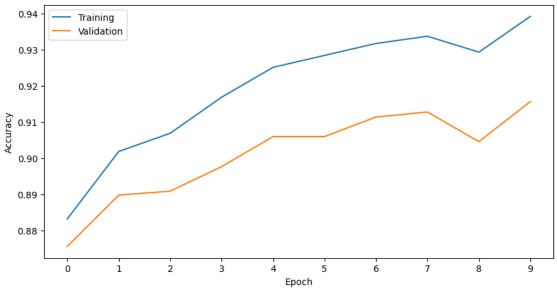
```
100%|
            | 1000/1000 [00:25<00:00, 39.44it/s]
    Evaluation accuracy: 0.92936
    Evaluate on validation set...
   100%|
            | 200/200 [00:04<00:00, 41.56it/s]
    Evaluation accuracy: 0.9046
   -----Epoch = 10-----
   100%|
            | 1000/1000 [00:36<00:00, 27.54it/s]
    Epoch 10 loss:0.19699719595909118
   100%|
            | 1000/1000 [00:22<00:00, 44.43it/s]
    Evaluation accuracy: 0.93926
    Evaluate on validation set...
   100%|
            | 200/200 [00:04<00:00, 43.24it/s]
    Evaluation accuracy: 0.9157
   Done!
    Evaluate on test set
   100%|
            | 200/200 [00:04<00:00, 43.46it/s]
    Evaluation accuracy: 0.9112
   CPU times: user 2h 1min 28s, sys: 2.4 s, total: 2h 1min 31s
   Wall time: 9min 11s
[]: 0.9112
   Once your training is complete, run the cell below to visualize the training and validation accuracies
   across iterations.
# TODO: Submit the accuracy plot
    # visualize the training / validation accuracies
    x = np.arange(num_epoch)
```

train/val accuracies for MiniVGG

plt.figure()

```
plt.plot(x, trn_acc_hist)
plt.plot(x, val_acc_hist)
plt.legend(['Training', 'Validation'])
plt.xticks(x)
plt.xlabel('Epoch')
plt.ylabel('Accuracy')
plt.title('fashion MNIST Classification')
plt.gcf().set_size_inches(10, 5)
plt.savefig('part1.png', dpi=300)
plt.show()
```

fashion MNIST Classification



Q2 :Report the detailed architecture of your best model. Include information on hyperparameters chosen for training and a plot showing both training and validation accuracy across iterations.

A2:

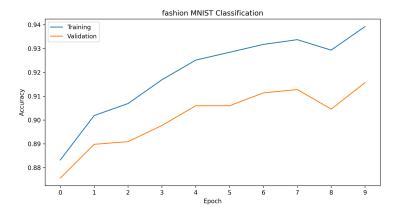
The detialed architecture of my best model:

The hyperparameters i chosen to build this cnn:

```
#set up the batch_size
batch_size = 50

# Set up optimization hyperparameters
learning_rate, weight_decay, num_epoch = 0.001, 0.001, 10
optimizer = optim.Adam(model.parameters(), lr = learning_rate, weight_decay=weight_decay)
```

plot showing both training and validation accuracy:



Q3 : Report the accuracy of your best model on the test set.

A3: My model final test accuracy is 91.12%

```
Evaluate on test set

100%| 200/200 [00:04<00:00, 43.46it/s]

Evaluation accuracy: 0.9112
```

6 Task 6: Pre-trained NN

Q1 :One image (img1) where the pretrained model gives reasonable predictions, and produces a category label that seems to correctly describe the content of the image

Predicted Class: convertible



Q2: One image (img2) where the pretrained model gives unreasonable predictions, and produces a category label that does not correctly describe the content of the image.

A2:



