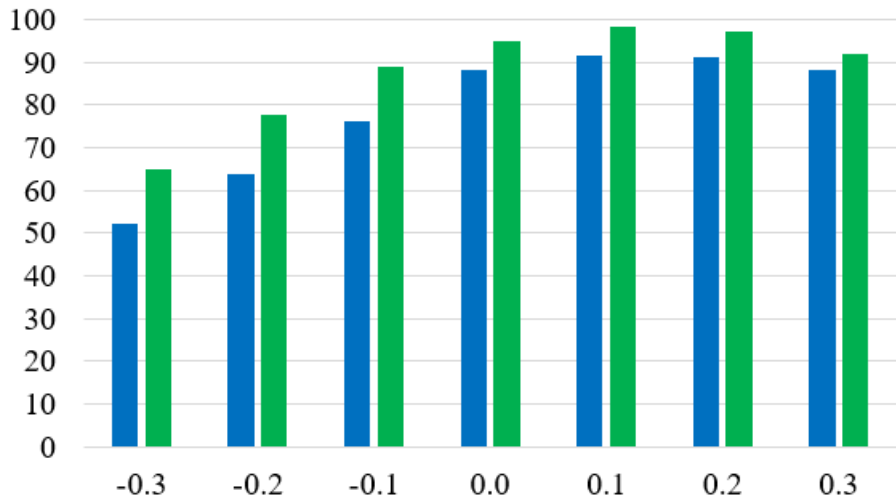


The probability of returning
to the target path[%]

■ Using learning machine output method
■ Enhanced return action method



Distance from target path[m]