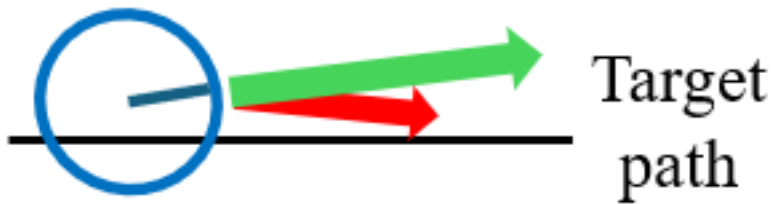


Robot Linear velocity * 2



$| \text{Target angular velocity} | < 0.1$