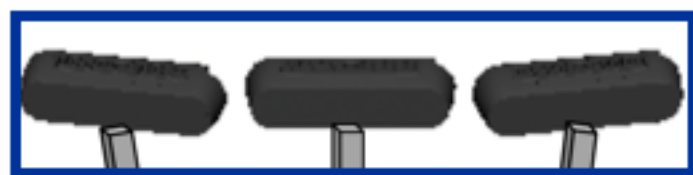
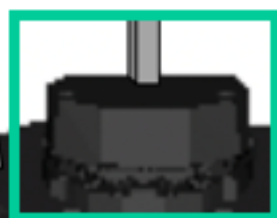


Cameras



LiDAR



Deep Learning

Training



Dataset

Action

ROS
navigation

Motor

Odometry

Target angular velocity

Action

