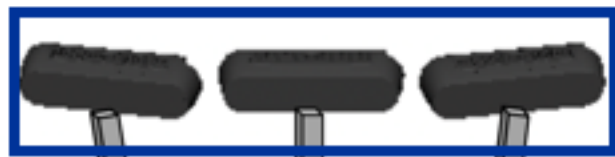


Cameras



LiDAR



Deep Learning

Training



Dataset

ROS navigation

Motor

Target angular velocity

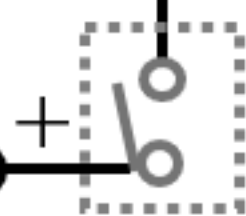
Action

Action

Exit Check



DOL Storage



$| \text{Difference} | < 0.05$

ON

Odometry

