Sub: Microprocessors and Microcontrollers Lab

Lab Task 3

Q1.

Aim: To Write a program using timer 0 to generate a 500 Hz square wave frequency on one of the pins of P1.0 Then examine the frequency using the KEIL IDE inbuilt Logic Analyzer.

```
ORG OOODH
MON TMOD ##OIH

HERE: MONTLO ##66H

MON THO, ## OFCH

CPL PI.O

ACALL DELAY

SIMP HERE

DELAN: SETB TRO

AGAIN: JNB TFO, AGAIN

CLR TRO

CLR TFO

RET

END
```

Code:

MOV TMOD,#01H

HERE:MOV TL0,#66H

SJMP HERE DELAY:SETB TR0 AGAIN:JNB TF0,AGAIN CLR TR0 CLR TF0 RET	ACALL DELAY SJMP HERE DELAY:SETB TR0 AGAIN:JNB TF0,AGAIN CLR TR0 CLR TF0 RET END Result: This code initializes Timer 0 in mode 1 (16-bit mode) and sets it to generate a 500 Hz squawave. It toggles pin P1.0 each time Timer 0 overflows, effectively producing the square wave. You	
SJMP HERE DELAY:SETB TR0 AGAIN:JNB TF0,AGAIN CLR TR0 CLR TF0 RET END Result: This code initializes Timer 0 in mode 1 (16-bit mode) and sets it to generate a 500 Hz square wave. It toggles pin P1.0 each time Timer 0 overflows, effectively producing the square wave. You can	SJMP HERE DELAY:SETB TR0 AGAIN:JNB TF0,AGAIN CLR TR0 CLR TF0 RET END Result: This code initializes Timer 0 in mode 1 (16-bit mode) and sets it to generate a 500 Hz squawave. It toggles pin P1.0 each time Timer 0 overflows, effectively producing the square wave. You	
DELAY:SETB TR0 AGAIN:JNB TF0,AGAIN CLR TR0 CLR TF0 RET END Result: This code initializes Timer 0 in mode 1 (16-bit mode) and sets it to generate a 500 Hz square wave. It toggles pin P1.0 each time Timer 0 overflows, effectively producing the square wave. You can	DELAY:SETB TR0 AGAIN:JNB TF0,AGAIN CLR TR0 CLR TF0 RET END Result: This code initializes Timer 0 in mode 1 (16-bit mode) and sets it to generate a 500 Hz squawave. It toggles pin P1.0 each time Timer 0 overflows, effectively producing the square wave. You	LAY
AGAIN:JNB TF0,AGAIN CLR TR0 CLR TF0 RET END Result: This code initializes Timer 0 in mode 1 (16-bit mode) and sets it to generate a 500 Hz square wave. It toggles pin P1.0 each time Timer 0 overflows, effectively producing the square wave. You can	AGAIN:JNB TF0,AGAIN CLR TR0 CLR TF0 RET END Result: This code initializes Timer 0 in mode 1 (16-bit mode) and sets it to generate a 500 Hz squawave. It toggles pin P1.0 each time Timer 0 overflows, effectively producing the square wave. You	
CLR TF0 RET END Result: This code initializes Timer 0 in mode 1 (16-bit mode) and sets it to generate a 500 Hz square wave. It toggles pin P1.0 each time Timer 0 overflows, effectively producing the square wave. You can	CLR TF0 RET END Result: This code initializes Timer 0 in mode 1 (16-bit mode) and sets it to generate a 500 Hz squawave. It toggles pin P1.0 each time Timer 0 overflows, effectively producing the square wave. You	ΓΒ TR0
CLR TF0 RET END Result: This code initializes Timer 0 in mode 1 (16-bit mode) and sets it to generate a 500 Hz square wave. It toggles pin P1.0 each time Timer 0 overflows, effectively producing the square wave. You can	CLR TF0 RET END Result: This code initializes Timer 0 in mode 1 (16-bit mode) and sets it to generate a 500 Hz squawave. It toggles pin P1.0 each time Timer 0 overflows, effectively producing the square wave. You	S TF0,AGAIN
RET END Result: This code initializes Timer 0 in mode 1 (16-bit mode) and sets it to generate a 500 Hz square wave. It toggles pin P1.0 each time Timer 0 overflows, effectively producing the square wave. You can	RET END Result: This code initializes Timer 0 in mode 1 (16-bit mode) and sets it to generate a 500 Hz squawave. It toggles pin P1.0 each time Timer 0 overflows, effectively producing the square wave. You	
END Result: This code initializes Timer 0 in mode 1 (16-bit mode) and sets it to generate a 500 Hz square wave. It toggles pin P1.0 each time Timer 0 overflows, effectively producing the square wave. You can	END Result: This code initializes Timer 0 in mode 1 (16-bit mode) and sets it to generate a 500 Hz squawave. It toggles pin P1.0 each time Timer 0 overflows, effectively producing the square wave. You	
Result: This code initializes Timer 0 in mode 1 (16-bit mode) and sets it to generate a 500 Hz square wave. It toggles pin P1.0 each time Timer 0 overflows, effectively producing the square wave. You can	Result: This code initializes Timer 0 in mode 1 (16-bit mode) and sets it to generate a 500 Hz squawave. It toggles pin P1.0 each time Timer 0 overflows, effectively producing the square wave. You	
wave. It toggles pin P1.0 each time Timer 0 overflows, effectively producing the square wave. You can	wave. It toggles pin P1.0 each time Timer 0 overflows, effectively producing the square wave. You	

Q2:

Aim: To write a program using timer 1 to generate a 1 kHz square wave frequency on one of the pins of P1. Then examine the frequency using the oscilloscope.

```
ORG 0000H

MOJ, TMOP, # 10H

HERE WOJTH, # 33H

MOJ THI, # 0 FEN

CPL PI.O

ACALL DELAY

SJMP HERE

DELAY: JNB TFI. AGAIN

CLR TFI

RET

END
```

Code:

ORG 0000H

MOV TMOD,#10H

HERE:MOV TL1,#33H

MOV TH1,#0FEH

CPL P1.0

ACALL DELAY

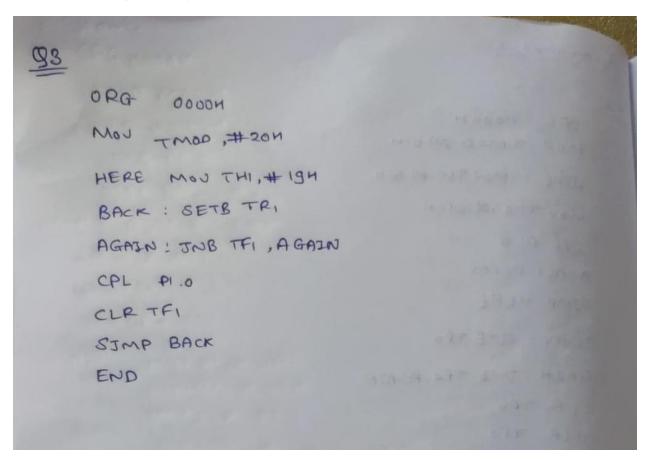
SJMP HERE

DELAY:SETB TR1

ELR TF1 EET END Result: Result: The program generates a 1 kHz square wave using Timer 1 on pin P1. The oscilloscope confirms the frequency is accurate.	AGAIN:JNB TF1,	AGAIN	
Result: The program generates a 1 kHz square wave using Timer 1 on pin P1. The	LR TR1		
Result: Result: The program generates a 1 kHz square wave using Timer 1 on pin P1. The	LR TF1		
Result: Result: The program generates a 1 kHz square wave using Timer 1 on pin P1. The	ET		
Result: The program generates a 1 kHz square wave using Timer 1 on pin P1. The	END		
	Result:		

Q3:

Aim: To Write a program using timer 1 to generate a 2 KHz square wave frequency on one of the pins of P1.0. Then examine the frequency using the KEIL IDE inbuilt Logic Analyzer.



Code:

ORG 0000H

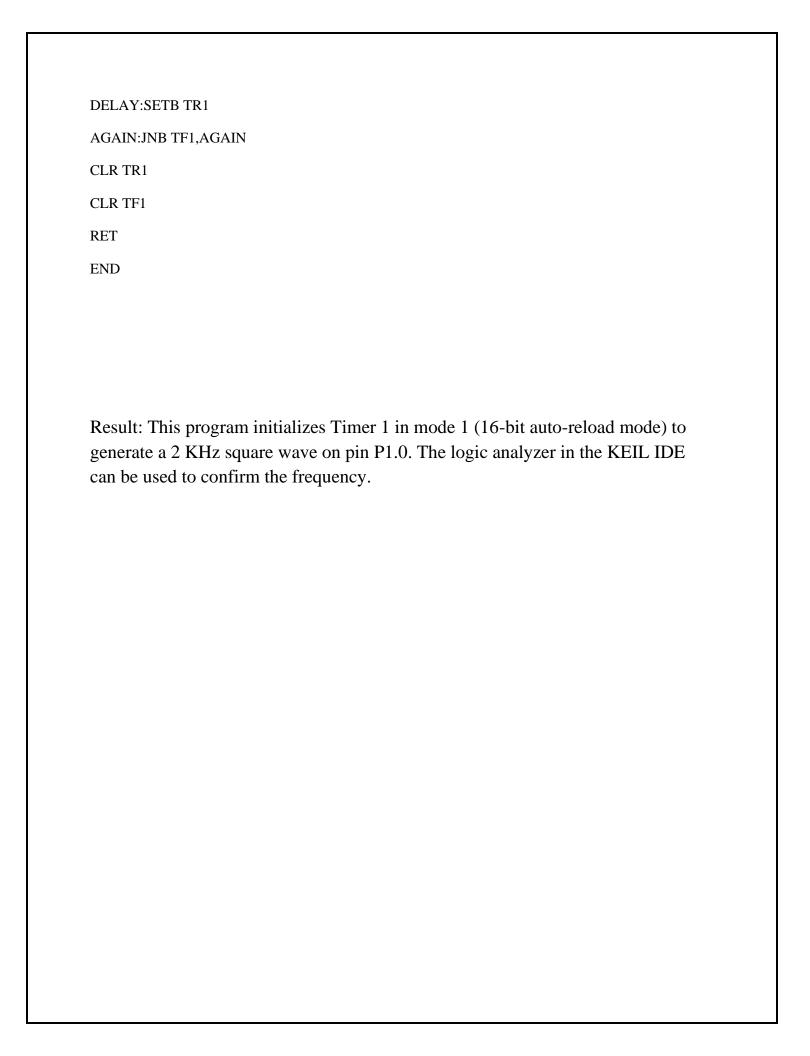
MOV TMOD,#20H

MOV TH1,#19H

HERE:CPL P2.0

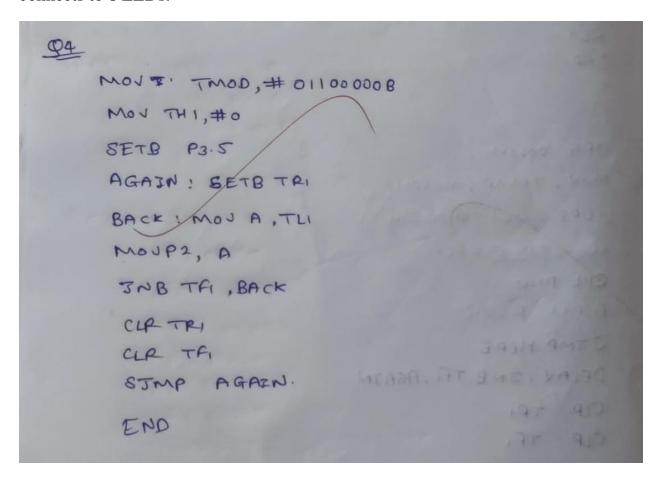
ACALL DELAY

SJMP HERE



Q4:

Assuming that clock pulses are fed into pin T1,write a program for counter 1 in mode 2 to count the pulses and display the state of the TL1 count on P2, which connects to 8 LEDs.



Code:

MOV TMOD, #011000008; counter 1, mode 2, C/T-1 external pulses

MOV TH1, #0; clear TH1

SETB P3.5 ;make T1 input

AGAIN SETB TR1 ;start the counter

BACK MOV A, TL1 ;get copy of TL

MOV P2, A ; display it on port 2

JNG TF1, BACK ;keep doing, if TF=

CLR TRI ;stop the counter 1

CLR TF1 ;make TF-0

SJMP AGAIN

END

Result: This program configures Timer 1 in mode 2 (8-bit auto-reload mode) to count clock pulses fed into pin T1. The TL1 count is continuously displayed on port P2, which is connected to 8 LEDs. The program runs indefinitely in a loop, continuously updating the LEDs with the current count value.

Q5:

Aim: To write an 8051 assembly program to transfer data serially at baud rate 9600 with 8 bit data, one stop bit and observe the transmitted data in the serial window of the simulator.

```
ORG OOOSH
 X X : MON DATE H MYDATA
 MOS TMOD ,# 204
 MO + THI ,# -3
 MO U SCON , # SOH
 SETB TRI
  MOJ 21 # 14
  AGAIN CLEA
  MOJE A. GA+ DATE
  MOUSBOF, A
 HERE; JNB TI, HERE
  CLR TI
   INC OPTR
   DINZ RI, A GAIN
    SIMPXX
    MYDATA : DB "VIT UNIVERSITY"
```

Code:

ORG 0000H

XX: MOV DPTR,#MYDATA

MOV TMOD,#20H

MOV TH1,#-3

MOV SCON,#50H

SETB TR1

MOV R1,#14

AGAIN:CLR A

MOVC A,@A+DPTR

MOV SBUF,A

HERE: JNB TI,HERE

CLR TI

INC DPTR

DJNZ R1,AGAIN

SJMP XX

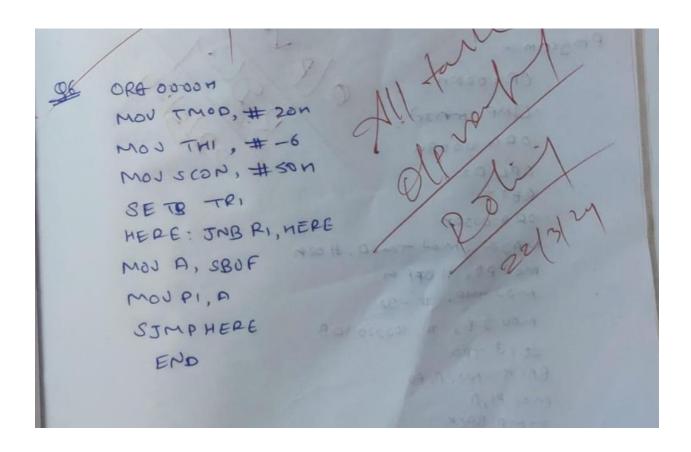
MYDATA: DB 'VIT UNIVERSITY'

END

Result: The program sets up serial communication at a baud rate of 9600 with 8-bit data and one stop bit. You can observe the transmitted data in the serial window of the simulator.

Q6:

Aim: To write a 8051 Assembly Language program to get data from the PC and display it on P1. Assume 8051 is connected to PC and observe the incoming characters. As you press a key on the PC's keyboard, the character is sent to the 8051 serially at 4800 baud rate and is displayed on LEDs. The characters displayed on LEDs are in ASCII (binary).



Code:

ORG 0000H

MOV TMOD,#20H

MOV TH1,#-6

MOV SCON,#50H

SETB TR1

HERE:JNB RI,HERE	
MOV A,SBUF	
MOV P1,A	
CLR RI	
SJMP HERE	
END	
PC at 4800 baud racharacters are type	Im allows the 8051 microcontroller to receive characters from a late and display them on port P1, which is connected to LEDs. As and on the PC's keyboard, they are sent to the 8051 serially and EDs in ASCII binary form.