



# Motion Retargeting for Grasping Tasks

Mapping synergies from humans to robotic hands with dissimilar  
kinematics

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Matteo Zamponi  
Luca Colamarino  
Giuseppe d'Addario  
Federico Tranzocchi  
*Sapienza University of Rome*

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# **Chapter 1**

## **Introduction**

### **1.1 Objective**

### **1.2 Structure**