```
In [2]: # This mounts your Google Drive to the Colab VM.
        from google.colab import drive
        drive.mount('/content/drive')
        # TODO: Enter the foldername in your Drive where you have saved the unzipped
        # assignment folder, e.g. 'cs231n/assignments/assignment1/'
        FOLDERNAME = 'cs231n/assignments/assignment1/'
        assert FOLDERNAME is not None, "[!] Enter the foldername."
        # Now that we've mounted your Drive, this ensures that
        # the Python interpreter of the Colab VM can load
        # python files from within it.
        import sys
        sys.path.append('/content/drive/My Drive/{}'.format(FOLDERNAME))
        # This downloads the CIFAR-10 dataset to your Drive
        # if it doesn't already exist.
        %cd /content/drive/My\ Drive/$FOLDERNAME/cs231n/datasets/
        !bash get_datasets.sh
        %cd /content/drive/My\ Drive/$FOLDERNAME
```

Mounted at /content/drive /content/drive/My Drive/cs231n/assignments/assignment1/cs231n/datasets /content/drive/My Drive/cs231n/assignments/assignment1

Image features exercise

Complete and hand in this completed worksheet (including its outputs and any supporting code outside of the worksheet) with your assignment submission. For more details see the assignments page on the course website.

We have seen that we can achieve reasonable performance on an image classification task by training a linear classifier on the pixels of the input image. In this exercise we will show that we can improve our classification performance by training linear classifiers not on raw pixels but on features that are computed from the raw pixels.

All of your work for this exercise will be done in this notebook.

```
import random
import numpy as np
from cs231n.data_utils import load_CIFAR10
import matplotlib.pyplot as plt

// wmatplotlib inline
plt.rcParams['figure.figsize'] = (10.0, 8.0) # set default size of plots
plt.rcParams['image.interpolation'] = 'nearest'
plt.rcParams['image.cmap'] = 'gray'

# for auto-reloading extenrnal modules
# see http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipytho
%load_ext autoreload
%autoreload 2
```

Load data

Similar to previous exercises, we will load CIFAR-10 data from disk.

```
In [4]: from cs231n.features import color_histogram_hsv, hog_feature
         def get_CIFAR10_data(num_training=49000, num_validation=1000, num_test=1000):
             # Load the raw CIFAR-10 data
             cifar10_dir = 'cs231n/datasets/cifar-10-batches-py'
             # Cleaning up variables to prevent loading data multiple times (which may ca
                del X_train, y_train
                del X_test, y_test
                print('Clear previously loaded data.')
             except:
                pass
            X train, y train, X test, y test = load CIFAR10(cifar10 dir)
            # Subsample the data
             mask = list(range(num_training, num_training + num_validation))
            X_val = X_train[mask]
            y_val = y_train[mask]
            mask = list(range(num_training))
            X_train = X_train[mask]
            y_train = y_train[mask]
            mask = list(range(num_test))
            X_{\text{test}} = X_{\text{test}}[mask]
            y_{\text{test}} = y_{\text{test}}[mask]
             return X_train, y_train, X_val, y_val, X_test, y_test
         X_train, y_train, X_val, y_val, X_test, y_test = get_CIFAR10_data()
```

Extract Features

For each image we will compute a Histogram of Oriented Gradients (HOG) as well as a color histogram using the hue channel in HSV color space. We form our final

feature vector for each image by concatenating the HOG and color histogram feature vectors.

Roughly speaking, HOG should capture the texture of the image while ignoring color information, and the color histogram represents the color of the input image while ignoring texture. As a result, we expect that using both together ought to work better than using either alone. Verifying this assumption would be a good thing to try for your own interest.

The hog_feature and color_histogram_hsv functions both operate on a single image and return a feature vector for that image. The extract_features function takes a set of images and a list of feature functions and evaluates each feature function on each image, storing the results in a matrix where each column is the concatenation of all feature vectors for a single image.

```
In [5]: from cs231n.features import *
        num_color_bins = 10 # Number of bins in the color histogram
        feature_fns = [hog_feature, lambda img: color_histogram_hsv(img, nbin=num_color_
        X_train_feats = extract_features(X_train, feature_fns, verbose=True)
        X_val_feats = extract_features(X_val, feature_fns)
        X_test_feats = extract_features(X_test, feature_fns)
        # Preprocessing: Subtract the mean feature
        mean_feat = np.mean(X_train_feats, axis=0, keepdims=True)
        X_train_feats -= mean_feat
        X_val_feats -= mean_feat
        X_test_feats -= mean_feat
        # Preprocessing: Divide by standard deviation. This ensures that each feature
        # has roughly the same scale.
        std_feat = np.std(X_train_feats, axis=0, keepdims=True)
        X train feats /= std feat
        X_val_feats /= std_feat
        X_test_feats /= std_feat
        # Preprocessing: Add a bias dimension
        X_train_feats = np.hstack([X_train_feats, np.ones((X_train_feats.shape[0], 1))])
        X_val_feats = np.hstack([X_val_feats, np.ones((X_val_feats.shape[0], 1))])
        X_test_feats = np.hstack([X_test_feats, np.ones((X_test_feats.shape[0], 1))])
```

```
Done extracting features for 1000 / 49000 images
Done extracting features for 2000 / 49000 images
Done extracting features for 3000 / 49000 images
Done extracting features for 4000 / 49000 images
Done extracting features for 5000 / 49000 images
Done extracting features for 6000 / 49000 images
Done extracting features for 7000 / 49000 images
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Done extracting features for 10000 / 49000 images
Done extracting features for 11000 / 49000 images
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Done extracting features for 46000 / 49000 images
Done extracting features for 47000 / 49000 images
Done extracting features for 48000 / 49000 images
Done extracting features for 49000 / 49000 images
```

Train SVM on features

Using the multiclass SVM code developed earlier in the assignment, train SVMs on top of the features extracted above; this should achieve better results than training SVMs directly on top of raw pixels.

```
from cs231n.classifiers.linear_classifier import LinearSVM
 learning_rates = [1e-9, 1e-8, 1e-7]
 regularization_strengths = [5e4, 5e5, 5e6]
 results = {}
 best_val = -1
 best svm = None
 # Use the validation set to set the learning rate and regularization strength. #
 # This should be identical to the validation that you did for the SVM; save
 # the best trained classifer in best_svm. You might also want to play
                                                                           #
 # with different numbers of bins in the color histogram. If you are careful
 # you should be able to get accuracy of near 0.44 on the validation set.
 # *****START OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE)****
 for lr in learning_rates:
   for reg_strength in regularization_strengths:
    svm = LinearSVM()
    svm.train(X_train_feats, y_train, learning_rate=lr, reg=reg_strength)
    y_train_pred = svm.predict(X_train_feats)
    train_accuracy = np.mean(y_train_pred == y_train)
    y_val_pred = svm.predict(X_val_feats)
    val_accuracy = np.mean(y_val_pred == y_val)
    if val accuracy > best val:
        best_val = val_accuracy
        best svm = svm
     results[(lr, reg_strength)] = (train_accuracy, val_accuracy)
 # *****END OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE)****
 # Print out results.
 for lr, reg in sorted(results):
    train accuracy, val accuracy = results[(lr, reg)]
     print('lr %e reg %e train accuracy: %f val accuracy: %f' % (
                lr, reg, train_accuracy, val_accuracy))
 print('best validation accuracy achieved: %f' % best_val)
lr 1.000000e-09 reg 5.000000e+04 train accuracy: 0.095755 val accuracy: 0.079000
lr 1.000000e-09 reg 5.000000e+05 train accuracy: 0.127531 val accuracy: 0.122000
lr 1.000000e-09 reg 5.000000e+06 train accuracy: 0.098571 val accuracy: 0.089000
lr 1.000000e-08 reg 5.000000e+04 train accuracy: 0.081020 val accuracy: 0.086000
lr 1.000000e-08 reg 5.000000e+05 train accuracy: 0.085020 val accuracy: 0.093000
lr 1.000000e-08 reg 5.000000e+06 train accuracy: 0.337367 val accuracy: 0.333000
lr 1.000000e-07 reg 5.000000e+04 train accuracy: 0.092224 val accuracy: 0.091000
lr 1.000000e-07 reg 5.000000e+05 train accuracy: 0.409163 val accuracy: 0.406000
lr 1.000000e-07 reg 5.000000e+06 train accuracy: 0.336980 val accuracy: 0.331000
best validation accuracy achieved: 0.406000
```

```
In [8]: # Evaluate your trained SVM on the test set: you should be able to get at least
y_test_pred = best_svm.predict(X_test_feats)
```

```
test_accuracy = np.mean(y_test == y_test_pred)
print(test_accuracy)
```

0.405

```
In [9]: # An important way to gain intuition about how an algorithm works is to
        # visualize the mistakes that it makes. In this visualization, we show examples
        # of images that are misclassified by our current system. The first column
        # shows images that our system labeled as "plane" but whose true label is
        # something other than "plane".
        examples_per_class = 8
        classes = ['plane', 'car', 'bird', 'cat', 'deer', 'dog', 'frog', 'horse', 'ship'
        for cls, cls_name in enumerate(classes):
            idxs = np.where((y_test != cls) & (y_test_pred == cls))[0]
            idxs = np.random.choice(idxs, examples_per_class, replace=False)
            for i, idx in enumerate(idxs):
                 plt.subplot(examples_per_class, len(classes), i * len(classes) + cls + 1
                 plt.imshow(X_test[idx].astype('uint8'))
                 plt.axis('off')
                if i == 0:
                     plt.title(cls_name)
        plt.show()
        plane
                         bird
                                                                            ship
                  car
                                  cat
                                          deer
                                                   dog
                                                           frog
                                                                   horse
                                                                                    truck
```

Inline question 1:

Describe the misclassification results that you see. Do they make sense?

YourAnswer: The misclassified results often share similarities with the correct class either in color or shape.

For example, in many misclassified images labeled as planes, elements resembling plane wings appear; additionally, 6 out of 8 of these images have a sky background, characterized by a blue color.

Neural Network on image features

Earlier in this assignment we saw that training a two-layer neural network on raw pixels achieved better classification performance than linear classifiers on raw pixels. In this notebook we have seen that linear classifiers on image features outperform linear classifiers on raw pixels.

For completeness, we should also try training a neural network on image features. This approach should outperform all previous approaches: you should easily be able to achieve over 55% classification accuracy on the test set; our best model achieves about 60% classification accuracy.

```
In [10]: # Preprocessing: Remove the bias dimension
        # Make sure to run this cell only ONCE
        print(X_train_feats.shape)
        X_train_feats = X_train_feats[:, :-1]
        X_val_feats = X_val_feats[:, :-1]
        X_test_feats = X_test_feats[:, :-1]
        print(X_train_feats.shape)
       (49000, 155)
       (49000, 154)
In [27]: from cs231n.classifiers.fc_net import TwoLayerNet
        from cs231n.solver import Solver
        input_dim = X_train_feats.shape[1]
        hidden_dim = 500
        num classes = 10
        data = {
           'X_train': X_train_feats,
           'y_train': y_train,
           'X_val': X_val_feats,
           'y val': y val,
           'X_test': X_test_feats,
           'y_test': y_test,
        net = TwoLayerNet(input_dim, hidden_dim, num_classes)
        best net = None
        # TODO: Train a two-layer neural network on image features. You may want to
        # cross-validate various parameters as in previous sections. Store your best
        # model in the best net variable.
        # *****START OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE)*****
```

```
best_val_acc = -1
         for reg_strength in [0.001, 0.01]:
             for lr in [1e-2, 5e-2, 7e-2, 1e-1]:
               net = TwoLayerNet(input_dim, hidden_dim, num_classes, reg=reg_strength)
               solver = Solver(net, data,
                           update rule='sgd',
                           optim_config={
                             'learning_rate': lr,
                           },
                           lr_decay=0.95,
                           num_epochs=50, batch_size=200,
                           print every=1000000, verbose=False)
               solver.train()
               train_acc = solver.train_acc_history[-1]
               val_acc = solver.val_acc_history[-1]
               print(f"Params: reg={reg_strength}, lr={lr} | Train acc: {train_acc:.4f},
               if val_acc > best_val_acc:
                   best_val_acc = val_acc
                   best_net = net
         print("Best validation accuracy achieved during tuning:", best_val_acc)
         # *****END OF YOUR CODE (DO NOT DELETE/MODIFY THIS LINE)****
        Params: reg=0.001, lr=0.01 | Train acc: 0.5040, Val acc: 0.4940
        Params: reg=0.001, lr=0.05 | Train acc: 0.6150, Val acc: 0.5680
        Params: reg=0.001, lr=0.07 | Train acc: 0.6440, Val acc: 0.5940
        Params: reg=0.001, lr=0.1 | Train acc: 0.6990, Val acc: 0.6070
        Params: reg=0.01, lr=0.01 | Train acc: 0.4740, Val acc: 0.4840
        Params: reg=0.01, lr=0.05 | Train acc: 0.5270, Val acc: 0.5360
        Params: reg=0.01, lr=0.07 | Train acc: 0.5550, Val acc: 0.5410
        Params: reg=0.01, lr=0.1 | Train acc: 0.6280, Val acc: 0.5540
        Best validation accuracy achieved during tuning: 0.607
In [28]: # Run your best neural net classifier on the test set. You should be able
         # to get more than 55% accuracy.
         y_test_pred = np.argmax(best_net.loss(data['X_test']), axis=1)
         test_acc = (y_test_pred == data['y_test']).mean()
```