

1:

(\Leftarrow): If $A\vec{x} = \vec{0}$ for some $\vec{x} \in \mathbb{R}^n$,
if part. then $\vec{0} = B(A\vec{x}) = (BA)\vec{x} = \mathbb{I}_n \vec{x} = \vec{x}$.

This shows T_A is injective.

(\Rightarrow): T_A injective \Rightarrow the reduced echelon form of A is:
only if part.

$$\begin{bmatrix} 1 & & & & 0 \\ & 1 & & & 0 \\ & & 1 & & 0 \\ & & & \ddots & \\ & & & & 1 \\ 0 & & & & & 0 \end{bmatrix}$$

and $m \geq n$.

We showed in class that elementary row operations can be realized as left multiplication³ by invertible matrices.

Hence $\exists C: m \times m$ invertible matrix s.t.

$$CA = \begin{bmatrix} 1 & & & & 0 \\ & 1 & & & 0 \\ & & 1 & & 0 \\ & & & \ddots & \\ & & & & 1 \\ 0 & & & & & 0 \end{bmatrix}$$

Define an $n \times m$ matrix D as:

$$D = \begin{bmatrix} 1 & & & & 0 \\ & 1 & & & 0 \\ & & \ddots & & \\ 0 & & & 1 & 0 \end{bmatrix} = \left[\mathbb{I}_n \mid 0_{n \times (m-n)} \right]$$

One can easily check that

$$D \cdot \begin{bmatrix} 1 & & & & 0 \\ & 1 & & & 0 \\ & & 1 & & 0 \\ & & & \ddots & \\ & & & & 1 \\ 0 & & & & & 0 \end{bmatrix} = \mathbb{I}_n.$$

Hence we can take $B := DC$ and get: $BA = DCA = \mathbb{I}_n$. \square

#2:

(\Rightarrow) For each $\vec{e}_i = \begin{bmatrix} 0 \\ \vdots \\ 1 \\ \vdots \\ 0 \end{bmatrix}$ its component in \mathbb{R}^m , $\exists \vec{b}_i \in \mathbb{R}^n$ st. $A\vec{b}_i = \vec{e}_i$.

Take $B = \begin{bmatrix} | & | & & | \\ \vec{b}_1 & \vec{b}_2 & \dots & \vec{b}_m \\ | & | & & | \end{bmatrix}$, then $AB = I_m$.

(\Leftarrow) $\forall \vec{x} \in \mathbb{R}^m$, we have $\vec{x} = I_m \vec{x} = (AB)\vec{x} = A(B\vec{x})$.

Hence T_A is surjective. \square

#3: S can't be surjective: Let A be the unique 3×2 matrix such that $T_A = S$. It's obvious that A can't have pivot in each row.

Then $S \circ T$ can't be surjective, therefore can't be invertible. \square

(one can also show that T is NOT injective and get the same conclusion.)

#4:

Suppose that $a_0 \vec{v} + a_1 T(\vec{v}) + \dots + a_{k-1} T^{k-1}(\vec{v}) = \vec{0}$.

Apply T^{k-1} on both sides, gets:

$$\begin{aligned} \vec{0} &= T^{k-1}(\vec{0}) = T^{k-1}(a_0 \vec{v} + a_1 T(\vec{v}) + \dots + a_{k-1} T^{k-1}(\vec{v})) \\ &= a_0 T^{k-1}(\vec{v}) + a_1 T^k(\vec{v}) + \dots + a_{k-1} T^{2k-2}(\vec{v}) \\ &= a_0 \underbrace{T^{k-1}(\vec{v})}_{\neq \vec{0}} \quad \text{since } \underbrace{T^k(\vec{v})}_{= \vec{0}} = \vec{0}. \end{aligned}$$

$$\Rightarrow a_0 = 0.$$

$$\Rightarrow a_1 T(\vec{v}) + a_2 T^2(\vec{v}) + \dots + a_{k-1} T^{k-1}(\vec{v}) = \vec{0}.$$

Now apply T^{k-2} on both sides, by the same argument, one gets $a_1 = 0$.

One can iterate this argument and get $a_0 = a_1 = \dots = a_{k-1} = 0$. \square

#5: Let

$$A = \begin{bmatrix} a_{11} & \dots & a_{1n} \\ \vdots & & \vdots \\ a_{n1} & \dots & a_{nn} \end{bmatrix}.$$

• Take $B = \begin{bmatrix} c & & \\ & \ddots & \\ & & 1 \end{bmatrix}$. Then $c \neq 0$.

$$AB = BA$$

$$\begin{matrix} \parallel & \parallel \\ A \begin{bmatrix} c & & \\ & \ddots & \\ & & 1 \end{bmatrix} & \begin{bmatrix} c & & \\ & \ddots & \\ & & 1 \end{bmatrix} A \\ \parallel & \parallel \end{matrix}$$

$$\begin{bmatrix} c a_{11} & a_{12} & \dots & a_{1n} \\ c a_{21} & & & \\ \vdots & & & \\ c a_{n1} & & & \end{bmatrix}$$

$$\begin{bmatrix} c a_{11} & c a_{12} & \dots & c a_{1n} \\ a_{21} & & & \\ \vdots & & & \\ a_{n1} & & & \end{bmatrix}$$

Take any $c \neq 1$.

$$\Rightarrow a_{12} = a_{13} = \dots = a_{1n} = 0,$$

$$a_{21} = a_{31} = \dots = a_{n1} = 0.$$

By the same argument, one can show that any off-diagonal entry of A is zero. i.e.

$$A = \begin{bmatrix} a_{11} & & & \\ & a_{22} & & \\ & & \ddots & \\ & & & a_{nn} \end{bmatrix}$$

• Take $B = \begin{bmatrix} 0 & 1 & & \\ 1 & 0 & & \\ & & \ddots & \\ & & & 1 \end{bmatrix}$. Then

$$AB = BA$$

$$\begin{bmatrix} a_{11} & & & \\ & a_{22} & & \\ & & \ddots & \\ & & & a_{nn} \end{bmatrix} \begin{bmatrix} 0 & 1 & & \\ 1 & 0 & & \\ & & \ddots & \\ & & & 1 \end{bmatrix} = \begin{bmatrix} 0 & 1 & & \\ 1 & 0 & & \\ & & \ddots & \\ & & & 1 \end{bmatrix} \begin{bmatrix} a_{11} & & & \\ & a_{22} & & \\ & & \ddots & \\ & & & a_{nn} \end{bmatrix}$$

$$\begin{bmatrix} 0 & a_{11} & & \\ a_{22} & 0 & & \\ & & a_{33} & \\ & & & \ddots & \\ & & & & a_{nn} \end{bmatrix}$$

$$\begin{bmatrix} 0 & a_{22} & & \\ a_{11} & 0 & & \\ & & a_{33} & \\ & & & \ddots & \\ & & & & a_{nn} \end{bmatrix}$$

$$\Rightarrow a_{11} = a_{22}.$$

By the same argument, one sees that $a_{11} = a_{22} = \dots = a_{nn}$. \square

#6: The (i,j) -th entry of AB is:

$$(AB)_{ij} = \sum_{k=1}^n a_{ik} b_{kj}$$

Hence $\text{tr}(AB) = \sum_{l=1}^m \sum_{k=1}^n a_{lk} b_{kl}$.

Similarly, the (i,j) -th entry of BA is:

$$(BA)_{ij} = \sum_{k=1}^m b_{ik} a_{kj}$$

Hence $\text{tr}(BA) = \sum_{k=1}^n \sum_{l=1}^m b_{kl} a_{lk}$.

Therefore $\text{tr}(AB) = \text{tr}(BA)$. \square

#7: False.

e.g. $\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 2 & 0 \end{bmatrix} = \begin{bmatrix} 3 & 4 \\ 1 & 2 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 2 & 0 \end{bmatrix} = \begin{bmatrix} 8 & 3 \\ 4 & 1 \end{bmatrix} \text{tr} = 9$

$$\begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 1 \\ 2 & 0 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} = \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} = \begin{bmatrix} 2 & 4 \\ 3 & 4 \end{bmatrix} \text{tr} = 6.$$

#8: True.

If there were such A, B , then

$$\text{tr}(AB - BA) = \text{tr}(\mathbb{I}_n) = n$$

\parallel

$$\text{tr}(AB) - \text{tr}(BA) = 0 \text{ (by \#6). } \square$$

#9:

$$A = \begin{bmatrix} \cos \frac{2\pi}{n} & -\sin \frac{2\pi}{n} \\ \sin \frac{2\pi}{n} & \cos \frac{2\pi}{n} \end{bmatrix}$$

#10: These are straight forward computations.

eg:

$$\begin{pmatrix} a & -b \\ b & a \end{pmatrix} \begin{pmatrix} c & -d \\ d & c \end{pmatrix} = \begin{pmatrix} ac-bd & -(ad+bc) \\ ad+bc & ac-bd \end{pmatrix}$$

and

$$(a+bi)(c+di) = (ac-bd) + (ad+bc)i. \quad \square$$