

Recap: Homogeneous eqn  $\vec{x}'(t) = A\vec{x}(t)$ ,  $A \in M_{n \times n}(\mathbb{R})$ .

- A matrix-valued fun  $X(t)$  is a fundamental matrix if its columns  $\{\vec{x}_1(t), \dots, \vec{x}_n(t)\}$  is a l.i. set of sol<sup>ns</sup>.
  - $\vec{x}(t)$  is a sol<sup>n</sup>  $\Leftrightarrow \vec{x}'(t) = X(t)\vec{c}$  for some  $c \in \mathbb{R}^n$ .
  - If two fundamental matrices  $X(t)$  and  $Y(t)$ ,  $\exists! M \in M_{n \times n}(\mathbb{R})$  invertible s.t.  $X(t) \cdot M = Y(t) \Leftrightarrow I + tA + \frac{t^2}{2}A^2 + \dots \in M_{n \times n}(\mathbb{R})$
  - the matrix exponential  $e^{tA}$  is a fundamental matrix.
- e.g. When  $A = PDP^{-1}$ , where  $P = [\vec{v}_1 \dots \vec{v}_n]$  invertible,  $D = \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & \lambda_n \end{bmatrix}$ . We proved that  $\{e^{\lambda_1 t} \vec{v}_1, \dots, e^{\lambda_n t} \vec{v}_n\}$  is a l.i. set of sol<sup>ns</sup>.

Hence

$$\begin{bmatrix} e^{\lambda_1 t} \vec{v}_1 & \dots & e^{\lambda_n t} \vec{v}_n \end{bmatrix}$$

Rmk: Since  $e^{tA}$  is a fundamental matrix of  $\vec{x}' = A\vec{x}$ ,

In principle, we can get all the sol<sup>ns</sup> from the columns of  $e^{tA}$ .

Issue:  $e^{tA}$  is hard to compute in general.

Fact: If  $A\vec{v} = \lambda\vec{v}$ , then

$$e^{tA}\vec{v} =$$

$$e^{\lambda t}\vec{v}$$

When  $A = PDP^{-1}$ ,

$\{\vec{v}_1, \dots, \vec{v}_n\}$  orthon

$$e^{tA}[\vec{v}_1 \dots \vec{v}_n] = [e^{\lambda_1 t} \vec{v}_1 \dots e^{\lambda_n t} \vec{v}_n]$$

$P$

$P$

also a fundamental matrix.

$$\begin{aligned} e^{tA}\vec{v} &= (I + tA + \frac{t^2}{2}A^2 + \dots)\vec{v} \\ &= \vec{v} + tA\vec{v} + \frac{t^2}{2}A^2\vec{v} + \dots \\ &\quad \downarrow \quad \downarrow \quad \downarrow \quad \dots \\ &\quad \vec{v} \quad \lambda\vec{v} \quad \lambda^2\vec{v} \quad \dots \\ &= \vec{v} + t\lambda\vec{v} + \frac{t^2}{2}\lambda^2\vec{v} + \dots \\ &= e^{\lambda t}\vec{v} \end{aligned}$$

pf2)  $\underline{e^{tA} \vec{v}} = e^{t\lambda} \underline{\boxed{e^{t(A-\lambda\mathbb{I})} \vec{v}}} \quad //$

$A = \lambda \mathbb{I} + (A - \lambda \mathbb{I})$

$e^{tA} = \underline{\boxed{e^{t\lambda\mathbb{I}}}} \cdot e^{t(A-\lambda\mathbb{I})}$

$e^{t\lambda} \cdot \underline{\boxed{\mathbb{I} + t(A-\lambda\mathbb{I}) + \frac{t^2}{2}(A-\lambda\mathbb{I})^2 + \dots}} \vec{v} \quad //$

$e^{t\lambda} \cdot \vec{v}$

②  $e^{t\lambda\mathbb{I}} \cdot A = \underline{\boxed{e^{t\lambda}}} A \quad //$

$\rightarrow 1 + t\lambda + \frac{1}{2}(t\lambda)^2 + \dots$

Recall

Def (generalized eigenvector). If  $\lambda$  is an eigenvalue of  $A$ ,  
say  $\vec{v} \neq \vec{0}$  is a generalized eigenvector if

$(A - \lambda\mathbb{I})^k \vec{v} = \vec{0} \quad \text{for some } k \geq 1.$

We proved: ④ for any  $A$ ,  $\exists$  generalized eigenbasis.

$\{\vec{v}_1, \dots, \vec{v}_n\}$ .

Idem:  $e^{tA} \vec{v}$  is not hard to compute for  
any generalized eigenvector  $\vec{v}$ .

If  $(A - \lambda\mathbb{I})^k \vec{v} = \vec{0}$ . then

$$\begin{aligned} e^{tA} \vec{v} &= e^{t\lambda} e^{t(A-\lambda\mathbb{I})} \vec{v} \\ &= e^{tA} \left( \mathbb{I} + t(A-\lambda\mathbb{I}) + \frac{t^2}{2}(A-\lambda\mathbb{I})^2 + \dots + \frac{t^{k-1}}{(k-1)!} (A-\lambda\mathbb{I})^{k-1} \right. \\ &\quad \left. + \frac{t^k}{k!} (A-\lambda\mathbb{I})^k + \dots \right) \vec{v} \\ &= \underline{e^{tA} \left( \mathbb{I} + t(A-\lambda\mathbb{I}) + \frac{t^2}{2}(A-\lambda\mathbb{I})^2 + \dots + \frac{t^{k-1}}{(k-1)!} (A-\lambda\mathbb{I})^{k-1} \right) \vec{v}} \end{aligned}$$

$$\boxed{e^{tA} \begin{bmatrix} \vec{v}_1 & \dots & \vec{v}_n \end{bmatrix}} = \begin{bmatrix} e^{tA}\vec{v}_1 & \dots & e^{tA}\vec{v}_n \end{bmatrix}$$

↑    ↑    ↑    ↑

fund. matrix.
not hard to compute

Strategy for finding a fundamental matrix of  $\vec{x}' = A\vec{x}_0$ :

- ① Find all the eigenvalues and their multiplicities  
 $\{\lambda_i\}$        $\{m_i\}$

$$\prod_i (\lambda_i - \lambda)^{m_i} = \det(A - \lambda \mathbb{I})$$

- ② Generalized eigenspace of  $\lambda_i = \text{Nul}((A - \lambda_i \mathbb{I})^{m_i})$

(Reason:  $A = P \begin{pmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{pmatrix} P^{-1}$ )

$$\left( \begin{pmatrix} \lambda_1 & & \\ & \ddots & \\ & & \lambda_n \end{pmatrix} - \lambda \mathbb{I} \right)^l = 0$$

- ③ Find a generalized eigenbasis  $\{\vec{v}_1, \dots, \vec{v}_n\}$   
 (pick a basis for each generalized eigenspace.)

- ④ Compute  $e^{tA} \vec{v}_i$  for each  $i$ .

- ⑤ Get a fund. matrix  $\boxed{\begin{bmatrix} e^{tA}\vec{v}_1 & \dots & e^{tA}\vec{v}_n \end{bmatrix}}$

Rmk To get the matrix exponential,  $e^{tA}$ ,

$$e^{tA} \vec{v}_1 \dots e^{tA} \vec{v}_n \quad \vec{v}_1 \dots \vec{v}_n$$

e.g. find a fundamental matrix of  $\vec{x}' = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 3 & 0 \\ 0 & 1 & 1 \end{bmatrix} \cdot \vec{x}$

①  $\lambda = 1 \text{ or } 3$ ,  
 $\uparrow \quad \uparrow$   
mult 2, mult 1,

② Eigenvectors of 3:  $\text{Nul} \begin{bmatrix} -2 & 0 & 0 \\ 1 & 0 & 0 \\ 0 & 1 & -2 \end{bmatrix} = \text{Span} \left\{ \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix} \right\}$ ,

Eigenvectors of 1:  $\text{Nul} \begin{bmatrix} 0 & 0 & 0 \\ 1 & 2 & 0 \\ 0 & 1 & 0 \end{bmatrix} = \text{Span} \left\{ \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right\}$

A not diagonalizable.

Generalized eigenspace of 1:

$\text{Nul}((A - 1\text{II})^2) = \text{Nul} \underbrace{\begin{bmatrix} 0 & 0 & 0 \\ 2 & 4 & 0 \\ 1 & 2 & 0 \end{bmatrix}}_{\text{Nul}(A - 1\text{II})} = \text{Span} \left\{ \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -2 \\ 1 \\ 6 \end{bmatrix} \right\}$

$$\begin{pmatrix} 0 & 0 & 0 \\ 1 & 2 & 0 \\ 0 & 1 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 & 0 \\ 1 & 2 & 0 \\ 0 & 1 & 0 \end{pmatrix}$$

eigenv 3

gen. eigenkum

$$\left\{ \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix}, \begin{bmatrix} -2 \\ 1 \\ 6 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \right\}$$

1            1            3

$\downarrow v_1 \quad \downarrow v_2 \quad \downarrow v_3$

$$e^{tA} \begin{bmatrix} \vec{v}_1 & \vec{v}_2 & \vec{v}_3 \end{bmatrix}$$

$$\boxed{e^{tA} \vec{v}_1} = e^{1t} \vec{v}_1 = e^t \vec{v}_1$$

$$e^{tA} \vec{v}_3 = e^{3t} \vec{v}_3$$

$$\underline{e^{tA} \vec{v}_2} = e^t e^{t(A-\mathbb{I})} \vec{v}_2$$

$$= e^t \left( \mathbb{I} + t(A-\mathbb{I}) + \frac{t^2}{2} (A-\mathbb{I})^2 + \dots \right) \vec{v}_2$$

$$= e^t \left( \vec{v}_2 + t \underbrace{(A-\mathbb{I}) \vec{v}_2}_{\downarrow} \right)$$

$$\begin{bmatrix} 0 & 0 & 0 \\ 1 & 2 & 0 \\ 0 & 1 & 0 \end{bmatrix} \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix}$$

$$= e^t \left( \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} + t \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right)$$

$\Rightarrow$  a fund. matrix

$$\begin{bmatrix} 0 & -2e^t & 0 \\ 0 & e^t & 2e^{3t} \\ e^t & te^t & e^{3t} \end{bmatrix}$$

$$\vec{x}' = \begin{bmatrix} 1 & 0 & 0 \\ 1 & 3 & 0 \\ 0 & 1 & 1 \end{bmatrix} \vec{x}$$

$$\left. \begin{array}{l} x_1(t) = -2e^t \\ x_2(t) = e^t \\ x_3(t) = te^t \end{array} \right\} \rightarrow \text{and "t"}$$

$$x_1'(t) = -2e^t = x_1(t)$$

$$x_2'(t) = e^t = \frac{x_1(t) + 3x_2(t)}{-2e^t + 3e^t}$$

$$x_3'(t) = e^t + te^t = x_2 + x_3$$

Rank: We saw " $te^t$ " when we consider  $y'' + by' + cy = 0$

where  $r^2 + br + c = 0$  has a double root.

$$\text{e.g. } y'' - 4y' + 4y = 0$$

$$r^2 - 4r + 4r = 0, \text{ double root } 2$$

$$\text{Define } x_1(t) = y(t), \quad x_1' = y' = x_2$$

$$x_2(t) = y'(t), \quad x_2' = y'' = 4y' - 4y$$

$$= -4x_1 + 4x_2$$

$$\vec{x}'(t) = \begin{bmatrix} 0 & 1 \\ -4 & 4 \end{bmatrix} \vec{x}(t)$$

$$\text{char poly} = \det \begin{pmatrix} -\lambda & 1 \\ -4 & 4-\lambda \end{pmatrix} = \underline{\lambda^2 - 4\lambda + 4}$$

$\lambda = 2$  eigenvalues w/ mult = 2.

$$\text{Nuk} \begin{pmatrix} -2 & 1 \\ -4 & 2 \end{pmatrix} = \text{Span} \left\{ \begin{pmatrix} 1 \\ 2 \end{pmatrix} \right\}$$

Generalized eigenvectors

$$(A - 2I)^2 = 0$$

$$\left\{ \begin{pmatrix} 1 \\ 2 \end{pmatrix}, \begin{pmatrix} 0 \\ 1 \end{pmatrix} \right\}$$

$$e^{tA} \begin{pmatrix} 1 & 0 \\ 2 & 1 \end{pmatrix} \cancel{\times}$$

$$e^{tA} \begin{pmatrix} 1 \\ 2 \end{pmatrix} = e^{2t} \begin{pmatrix} 1 \\ 2 \end{pmatrix}$$

$$e^{tA} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = e^{2t} e^{t(A-2I)} \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$= e^{2t} \left( I + t(A-2I) \cancel{+ \dots} \right) \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$e^{2t} \left( \begin{pmatrix} 0 \\ 1 \end{pmatrix} + t \begin{pmatrix} 1 \\ 2 \end{pmatrix} \right)$$

→ fund. matrix

Sol<sup>ks</sup> to

$$y'' - 4y' + 4y = 0$$

$$\begin{bmatrix} e^{2t} & te^{2t} \\ 2e^{2t} & e^{2t} + 2te^{2t} \end{bmatrix}$$

$$\vec{x}^1 = \underbrace{A \vec{x}}_{\vec{v}} \quad \vec{x}^2$$

$$\begin{cases} \bar{\lambda} = \alpha - i\beta \\ \bar{v} = \vec{x} - i\vec{y} \end{cases} \quad A\bar{v} = \bar{\lambda}\bar{v}$$

$\beta \neq 0$ .

has complex eigenvalues

$$\begin{cases} \lambda = \alpha + i\beta \\ \vec{v} = \vec{x} + i\vec{y} \end{cases} \text{ s.t. } A\vec{v} = \lambda\vec{v}$$

$\Rightarrow$  we know

$$e^{t\lambda} \vec{v}$$

is a sol<sup>2</sup>

$$e^{t(\alpha+i\beta)} (\vec{x}+i\vec{y})$$

Complex conjugate

$$e^{t\bar{\lambda}} \vec{v}$$

$$= e^{t\alpha} (\cos(\beta t) + i \sin(\beta t)) (\vec{x}+i\vec{y})$$

$$= \left( e^{t\alpha} \cos(\beta t) \vec{x} - e^{t\alpha} \sin(\beta t) \vec{y} \right)$$

$$+ i \left( e^{t\alpha} \sin(\beta t) \vec{x} + e^{t\alpha} \cos(\beta t) \vec{y} \right)$$

& its cpx conjugate

u+iV, u-iV  
 $\Downarrow$  sol<sup>2</sup>s

are both sol<sup>2</sup>s to  $\vec{x}' = A\vec{x}$ . u, v sol<sup>2</sup>s

$\Rightarrow$

$$\begin{cases} e^{t\alpha} \cos(\beta t) \vec{x} - e^{t\alpha} \sin(\beta t) \vec{y} \\ e^{t\alpha} \sin(\beta t) \vec{x} + e^{t\alpha} \cos(\beta t) \vec{y} \end{cases}$$

are both sol<sup>2</sup>s

L.C.F.

$$\vec{x}' = \begin{bmatrix} -1 & 2 \\ -1 & -3 \end{bmatrix} \vec{x}$$

$$(\lambda+1)(\lambda+3)+2=0 \Rightarrow \lambda^2+4\lambda+5=0 \Rightarrow \lambda = \frac{-4 \pm \sqrt{16-20}}{2}$$

$$\lambda = -2+i$$

$$\begin{aligned} \alpha &= -2 & \vec{x} &= \begin{bmatrix} -2 \\ 1 \end{bmatrix} \\ \beta &= 1 & \vec{y} &= \begin{bmatrix} 0 \\ -1 \end{bmatrix} \end{aligned}$$

$$-2+i$$

$$\text{Nul} \begin{bmatrix} 1-i & 2 \\ -1 & -1-i \end{bmatrix} = \text{Span} \left\{ \begin{bmatrix} -2 \\ 1-i \end{bmatrix} \right\}$$

$$\Rightarrow \begin{cases} e^{-2t} \cos t \begin{bmatrix} -2 \\ 1 \end{bmatrix} - e^{-2t} \sin t \begin{bmatrix} 0 \\ -1 \end{bmatrix} \\ e^{-2t} \sin t \begin{bmatrix} -2 \\ 1 \end{bmatrix} + e^{-2t} \cos t \begin{bmatrix} 0 \\ -1 \end{bmatrix} \end{cases} \text{ are soln.}$$

Non-homogeneous case,

$$\vec{x}' = A\vec{x} + \vec{f}(t)$$

$$\vec{f}: \mathbb{R} \rightarrow \mathbb{R}^n$$

$$A \in M_{n \times n}(\mathbb{R})$$

Variation of parameters:

- General sol<sup>n</sup> of homog eq<sup>n</sup>  $\vec{x}' = A\vec{x}$ .

$\vec{X}(t)$  fund matrix

const. vect

$\Rightarrow$  general sol<sup>n</sup>

$$\vec{X}(t) \vec{c}$$

- Let  $\vec{x}(t) = \vec{X}(t) \vec{c}(t)$

Goal: Find  $\vec{c}(t)$  s.t.  $\vec{x}'(t) = A\vec{x}(t) + \vec{f}(t)$

$$\vec{x}'(t) = \boxed{\vec{X}'(t)} \vec{c}(t) + \vec{X}(t) \vec{c}'(t)$$

$$= A \boxed{\vec{X}(t) \vec{c}(t)} + \vec{X}(t) \vec{c}'(t)$$

$$= A\vec{x}(t) + \vec{X}(t) \vec{c}'(t)$$

i.e. want to find  $\vec{c}(t)$

so,  $\underline{X(t)} \vec{c}'(t) = \vec{f}(t)$

$$\Rightarrow \vec{c}'(t) = \underline{X(t)}^{-1} \vec{f}(t)$$

So we can find  $\vec{c}(t)$

by integrating each components of  
the vector-valued fcn  $\underline{X(t)}^{-1} \vec{f}(t)$ .

Ex.  $\vec{x}'(t) = \begin{bmatrix} 2 & -3 \\ 1 & -2 \end{bmatrix} \vec{x}(t) + \begin{bmatrix} e^{2t} \\ 1 \end{bmatrix}, \quad \vec{x}(0) = \begin{bmatrix} 1 \\ 0 \end{bmatrix}$

① find a fund. matrix

$$\begin{bmatrix} 3e^t & e^{-t} \\ e^t & e^{-t} \end{bmatrix} = \underline{X(t)}$$

②

$$\begin{aligned} \underline{X(t)}^{-1} \vec{f}(t) &= \begin{bmatrix} 3e^t & e^{-t} \\ e^t & e^{-t} \end{bmatrix}^{-1} \begin{bmatrix} e^{2t} \\ 1 \end{bmatrix} \\ &= \frac{1}{8e^t} \begin{bmatrix} e^{-t} & -e^{-t} \\ -e^t & 3e^t \end{bmatrix} \begin{bmatrix} e^{2t} \\ 1 \end{bmatrix} \end{aligned}$$

$$= \begin{bmatrix} \frac{1}{2}e^t - \frac{1}{2}e^{-t} \\ -\frac{1}{2}e^{-t} + \frac{3}{2}e^t \end{bmatrix}$$

③

get  $\vec{c}(t)$  by

$\int$

$2t$

$e^t$

④ get a particular sol<sup>b</sup>

$$\vec{x}(t) = \vec{X}(t) \vec{c}(t)$$

⑤ general sol<sup>b</sup>

$$\vec{x}(t) = \vec{X}(t) \vec{d} + \vec{x}_0(t)$$

any const. vector

⑥ Plug in to  $\vec{x}(0) = \begin{bmatrix} -1 \\ 0 \end{bmatrix}$  & solve for  $\vec{d}$ .