

#1: Find the solution set of:

$$\begin{cases} 2x_1 + 2x_2 + 2x_3 + 8x_4 = 2 \\ 2x_1 + x_2 + x_3 + 8x_4 = 2 \\ 2x_1 + 6x_2 + 3x_3 + 11x_4 = 1 \end{cases}$$

Sol<sup>n</sup>:

$$\begin{bmatrix} 2 & 2 & 2 & 8 & | & 2 \\ 2 & 1 & 1 & 8 & | & 2 \\ 2 & 6 & 3 & 11 & | & 1 \end{bmatrix} \xrightarrow{\text{row operations}} \begin{bmatrix} 1 & 1 & 1 & 4 & | & 1 \\ 2 & 1 & 1 & 8 & | & 2 \\ 2 & 6 & 3 & 11 & | & 1 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 1 & 1 & 1 & 4 & | & 1 \\ 0 & -1 & -1 & 0 & | & 0 \\ 0 & 4 & 1 & 3 & | & -1 \end{bmatrix} \rightarrow \begin{bmatrix} 1 & 0 & 0 & 4 & | & 1 \\ 0 & 1 & 1 & 0 & | & 0 \\ 0 & 0 & -3 & 3 & | & -1 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} 1 & 0 & 0 & 4 & | & 1 \\ 0 & 1 & 0 & 1 & | & -\frac{1}{3} \\ 0 & 0 & 1 & -1 & | & \frac{1}{3} \end{bmatrix}$$

$$\text{Sol<sup>n</sup> set} = \left\{ \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 1-4t \\ -\frac{1}{3}-t \\ \frac{1}{3}+t \\ t \end{bmatrix} : t \in \mathbb{R} \right\} \quad \square$$

#2: Find all possible values of  $a \in \mathbb{R}$  s.t. the following vectors form a linearly dependent set:

$$\begin{bmatrix} 1 \\ 0 \\ a \end{bmatrix}, \begin{bmatrix} 0 \\ 2 \\ 1 \end{bmatrix}, \begin{bmatrix} a \\ 2 \\ 10 \end{bmatrix}.$$

Sol<sup>n</sup>:

They're linearly dependent  $\Leftrightarrow$  the matrix

$$\begin{bmatrix} 1 & 0 & a \\ 0 & 2 & 2 \\ a & 1 & 10 \end{bmatrix}$$

doesn't have pivot in each column.

row  
operations  $\rightarrow$

$$\begin{bmatrix} 1 & 0 & a \\ 0 & 1 & 1 \\ 0 & 1 & 10-a^2 \end{bmatrix}$$

$$\rightarrow \begin{bmatrix} \textcircled{1} & 0 & a \\ 0 & \textcircled{1} & 1 \\ 0 & 0 & 9-a^2 \end{bmatrix}$$

The matrix doesn't have pivot in each column

$$\Leftrightarrow 9-a^2=0.$$

$$\Leftrightarrow a = \pm 3. \quad \square$$

#3: Prove that  $\{\vec{v}_1, \dots, \vec{v}_k\} \subseteq \mathbb{R}^n$  is linearly independent  
if and only if the following statement holds:

"for any  $1 \leq i \leq k$ ,  $\text{Span}\{\vec{v}_1, \dots, \vec{v}_k\} \neq \text{Span}\{\vec{v}_1, \dots, \vec{v}_{i-1}, \vec{v}_{i+1}, \dots, \vec{v}_k\}$ "

pf:  $(\Rightarrow)$ : Since  $\{\vec{v}_1, \dots, \vec{v}_k\}$  is l.i., we have

$$\vec{v}_i \notin \text{Span}\{\vec{v}_1, \dots, \vec{v}_{i-1}, \vec{v}_{i+1}, \dots, \vec{v}_k\} \quad \forall 1 \leq i \leq k.$$

(Otherwise, suppose  $\vec{v}_i \in \text{Span}\{\vec{v}_1, \dots, \vec{v}_{i-1}, \vec{v}_{i+1}, \dots, \vec{v}_k\}$ ,

$$\text{then } \vec{v}_i = a_1 \vec{v}_1 + \dots + a_{i-1} \vec{v}_{i-1} + a_{i+1} \vec{v}_{i+1} + \dots + a_k \vec{v}_k$$

for some  $a_i \in \mathbb{R}$ .

Then  $\{\vec{v}_1, \dots, \vec{v}_k\}$  is l.d., contradiction.)

On the other hand, it's clear that  $\vec{v}_i \in \text{Span}\{\vec{v}_1, \dots, \vec{v}_k\}$ .

Hence  $\text{Span}\{\vec{v}_1, \dots, \vec{v}_k\} \neq \text{Span}\{\vec{v}_1, \dots, \vec{v}_{i-1}, \vec{v}_{i+1}, \dots, \vec{v}_k\} \forall i$ .

( $\Leftarrow$ ) Assume the contrary that  $\{\vec{v}_1, \dots, \vec{v}_k\}$  is l.d.

i.e.,  $\exists c_1, \dots, c_k$  not all zero s.t.

$$c_1 \vec{v}_1 + \dots + c_k \vec{v}_k = \vec{0}.$$

Choose  $i$  s.t.  $c_i \neq 0$ . Then

$$\vec{v}_i = \frac{1}{c_i} (c_1 \vec{v}_1 + \dots + c_{i-1} \vec{v}_{i-1} + c_{i+1} \vec{v}_{i+1} + \dots + c_k \vec{v}_k)$$

$$\in \text{Span}\{\vec{v}_1, \dots, \vec{v}_{i-1}, \vec{v}_{i+1}, \dots, \vec{v}_k\}.$$

It's then clear that

$$\text{Span}\{\vec{v}_1, \dots, \vec{v}_k\} = \text{Span}\{\vec{v}_1, \dots, \vec{v}_{i-1}, \vec{v}_{i+1}, \dots, \vec{v}_k\}.$$

Contradiction.

