

Announcement:

- my OH today: ~~12-1:30 pm~~ → 5-6:30 pm PDT.
(this is an one-time change)

Recap:

- Define matrix product AB : $T_{AB} = T_A \circ T_B$. $T_{A^{-1}} \circ T_A = \text{id} = T_A \circ T_{A^{-1}}$
- Invertible matrix $A_{n \times n}$: $\exists A^{-1}$ s.t. $A^{-1}A = AA^{-1} = I_n$. (generalization of AGR)
 $a^{-1}a = 1 = a^{-1}$
- We proved last time that: If $A: n \times n$ is invertible, then $T_A: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is bijective (inj. & surj.)

$$\mathbb{R}^n \xrightleftharpoons[T_A]{T_{A^{-1}}} \mathbb{R}^n$$

Today:

- Prove the converse statement.
- Define determinant of a square matrix.

Some applications of determinant:

- check invertibility, linearly indep.
- compute volume of 
- change of variable formula in multivariable calculus.

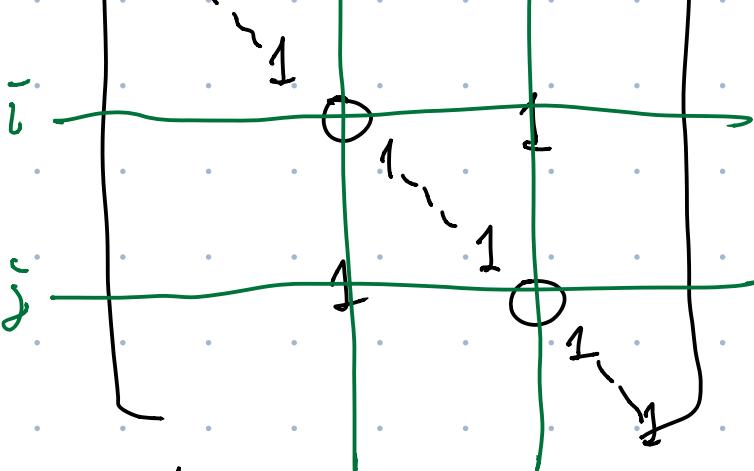
Recap: elementary matrices:

the effect of left multiplication by the matrices:

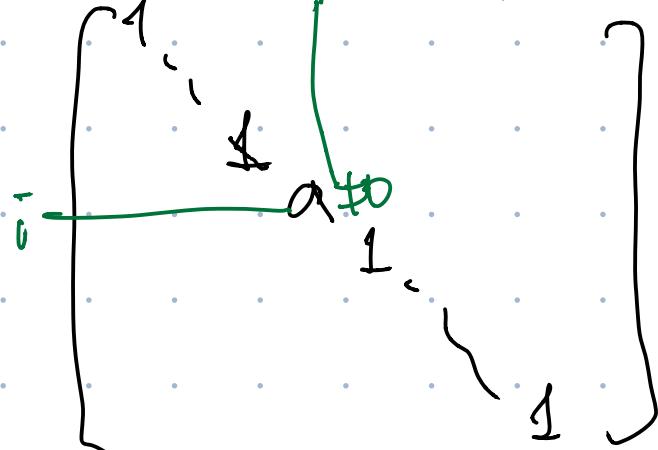
$$\left[\begin{array}{cccc|c} 1 & & & & \\ & \ddots & & & \\ & & 1 & & \\ & & & \textcircled{j} & \\ i & \cdots & a & \cdots & - \\ & & & & 1 \end{array} \right]$$

replace the i th row by
(i th row) + a (j th row)

$$\left[\begin{array}{ccc|c} 1 & & & \\ & 1 & & \\ & & 1 & \\ & & & \textcircled{j} \end{array} \right]$$



swap (ith row)
&
(jth row)



multiply the (ith row)
by a

Q: What happens if we multiply the elementary matrices on the right?

$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix} = \begin{bmatrix} a_{11} & 2a_{11} + a_{12} \\ a_{21} & 2a_{21} + a_{22} \end{bmatrix}$$

"column operation"

Fact: These elementary matrices are invertible.



$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 2 & 0 & 1 \end{bmatrix} \begin{bmatrix} M \end{bmatrix}$$

replace the 3rd row of M
by
3rd row of M + 2 (1st row of M)

Suppose $A \rightsquigarrow$ the inverse of

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ -2 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 2 & 0 & 1 \end{bmatrix} = A^{-1} I_3$$

$$\begin{bmatrix} 1 & & \\ & 1 & \\ 2 & & \end{bmatrix} \begin{bmatrix} 1 & & \\ & 1 & \\ -2 & & \end{bmatrix} \rightsquigarrow$$

$$\underbrace{\begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}}_2 = I, \text{ i.e. } \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}^{-1} = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 2 & & \\ & 1 & \\ & & 1 \end{bmatrix} \begin{bmatrix} \frac{1}{2} & & \\ & 1 & \\ & & 1 \end{bmatrix} = I_n$$

Thm $A: n \times n$ invertible $\Leftrightarrow A$ is row equivalent to I_n

$A \xrightarrow{\text{row operations}} \begin{bmatrix} 1 & & & \\ 1 & 1 & & \\ 1 & 1 & 1 & \\ \vdots & & & 1 \end{bmatrix}$

(\Leftrightarrow A has pivots in each column/row)
($\Leftrightarrow T_A$ is bijective)

pf \Rightarrow Last time

$\Leftarrow \exists E_1, \dots, E_k$ elements make AT.

$$E_1 \cdots E_k A = I_n$$

$$\Rightarrow \underbrace{E_1^{-1} E_1}_{I_n} E_2 \cdots E_k A = E_1^{-1} \cdot I_n = E_1^{-1}$$

$$E_2 \cdots E_k A$$

$$\Rightarrow E_3 \cdots E_k A = E_2^{-1} E_1^{-1}$$

$$E_1 E_2 \cdots E_k A = I_n$$

$$E_1 \cdots E_k I_n = A^{-1}$$

$$\Rightarrow A = E_k^{-1} E_{k-1}^{-1} \cdots E_2^{-1} E_1^{-1}$$

$\Rightarrow A$ is invertible,

and $A^{-1} = E_1 E_2 \cdots E_k$.

□

Theorem (Invertible Criteria). $A: n \times n$ matrix. The following

① A is invertible ($\exists B$ such that $BA = AB = I_n$) are equivalent

② T_A is surjective.

③ A has pivot in each row.

④ " $A \vec{x} = \vec{b}$ " has sol " $\mathbb{H}_n + \mathbb{R}$ "

⑤ T_A is injective

③' A has pivot in each column

③'' $A\vec{x} = \vec{0}$ has only the trivial sol'

③''' The columns of A are l.i.

{ ④ $\exists n \times n B$ st. $BA = I_n$

⑤ $\exists n \times n C$ st. $AC = I_n$

PF ① \Leftrightarrow ② \Leftrightarrow ③ proved.

① \Rightarrow ④, ⑤ clear.

④ \Rightarrow ③'':

We'd like to prove: $A\vec{x} = \vec{0} \Rightarrow \vec{x} = \vec{0}$

The condition we have: $BA = I_n$

$$\vec{x} = I_n \vec{x} = BA \vec{x} = B \vec{0} = \vec{0}$$

⑤ \Rightarrow ②'':

We'd like to prove: "If \vec{b} , $A\vec{x} = \vec{b}$ has a sol"

The cond' we have: $AC = I_n$

$$A\vec{c}_1 = \vec{e}_1 = \begin{bmatrix} 1 \\ 0 \\ \vdots \\ 0 \end{bmatrix}, \dots, A\vec{c}_n = \vec{e}_n$$

$$\begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix} = \vec{b} = b_1 \vec{e}_1 + \dots + b_n \vec{e}_n$$

$$A \left(\underbrace{b_1 \vec{c}_1 + \dots + b_n \vec{c}_n}_{C\vec{b}} \right) = b_1 \vec{e}_1 + \dots + b_n \vec{e}_n = \vec{b}$$

\vec{b}

$$AC\vec{b} = I_n \vec{b} = \vec{b}$$

$$A(C\vec{b}) \quad \vec{x} = C\vec{b} \rightarrow \text{as sol' to } A\vec{x} = \vec{b}$$

How to compute A^{-1} ??

$$\boxed{E_1 E_2 \dots E_k A = I_n}$$

$$E_1 \dots E_k I_n = A^{-1}$$

$$\boxed{[A \mid I_n]_{n \times 2n}}$$

\downarrow elem row opn $E_1 \dots E_k$

$$\boxed{[I_n \mid A^{-1}]}$$

e.g. $\begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix}$

$$\begin{bmatrix} 2 & 1 & | & 1 & 0 \\ 1 & 1 & | & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & | & 0 & 1 \\ 2 & 1 & | & 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & | & 0 & 1 \\ 0 & -1 & | & 1 & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 1 & | & 0 & 1 \\ 0 & 1 & | & -1 & 2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 0 & | & 1 & -1 \\ 0 & 1 & | & -1 & 2 \end{bmatrix} = \boxed{\begin{bmatrix} 2 & 1 \\ 1 & 1 \end{bmatrix}}$$

$$\text{e.g. } \left[\begin{array}{cc|cc} a & b & 1 & 0 \\ c & d & 0 & 1 \end{array} \right] \rightarrow \left[\begin{array}{cc|cc} 1 & \frac{b}{a} & \frac{1}{a} & 0 \\ c & d & 0 & 1 \end{array} \right]$$

Assume
 $a \neq 0$

$\left[\begin{array}{cc} a & b \\ c & d \end{array} \right]$ invertible

$$\Leftrightarrow ad - bc \neq 0$$

$$\left[\begin{array}{cc} a & b \\ c & d \end{array} \right]^{-1} = \frac{1}{ad - bc} \left[\begin{array}{cc} d & -b \\ -c & a \end{array} \right]$$

$$\left[\begin{array}{cc|cc} 1 & \frac{b}{a} & \frac{1}{a} & 0 \\ 0 & d - \frac{bc}{a} & -\frac{c}{a} & 1 \end{array} \right]$$

$$\left[\begin{array}{cc|cc} 1 & \frac{b}{a} & \frac{1}{a} & 0 \\ 0 & 1 & \frac{-c}{ad - bc} & \frac{a}{ad - bc} \end{array} \right]$$

$$\left[\begin{array}{cc|cc} 1 & 0 & \frac{d}{ad - bc} & \frac{-b}{ad - bc} \\ 0 & 1 & \frac{-c}{ad - bc} & \frac{a}{ad - bc} \end{array} \right]$$

In general, $\left[\begin{array}{cc} a & b \\ c & d \end{array} \right]$,

- $ad - bc = 0$, $\left\{ \left[\begin{array}{c} a \\ c \end{array} \right], \left[\begin{array}{c} b \\ d \end{array} \right] \right\}$ l.d.

- $\boxed{ad - bc \neq 0}$,

$$\det \left(\left[\begin{array}{cc} a & b \\ c & d \end{array} \right] \right)$$

$$\frac{1}{ad - bc} \left[\begin{array}{cc} d & -b \\ -c & a \end{array} \right]$$

is inverse of $\left[\begin{array}{cc} a & b \\ c & d \end{array} \right]$

Def A linear transformation is invertible if

$$T: \mathbb{R}^n \rightarrow \mathbb{R}^n$$

\exists a function $S: \mathbb{R}^n \rightarrow \mathbb{R}^n$

• $T(S(\vec{x})) = \vec{x} = S(T(\vec{x})) \quad \forall \vec{x} \in \mathbb{R}^n$
i.e. $T \circ S = \text{id}_{\mathbb{R}^n} = S \circ T.$

Thm. Suppose $T = T_A$ for $A: n \times n$

Then • T is invertible $\Leftrightarrow A$ is invertible.

• In this case, $S(\vec{x}) = A^{-1}\vec{x}$ is the unique function s.t. $S(T(\vec{x})) = \vec{x} = T(S(\vec{x})) \quad \forall \vec{x} \in \mathbb{R}^n$

Pf: (\Rightarrow) $T(\vec{x}) = T_A(\vec{x}) = A\vec{x}$.

$$\vec{x} = T(S(\vec{x})) = A(S(\vec{x})) \quad \forall \vec{x}$$

$\Rightarrow T_A$ is surjective $\Rightarrow A$ invertible.
(proven before)

(\Leftarrow) Define $S(\vec{x}) = A^{-1}\vec{x}$.

$$\text{Check } S(T(\vec{x})) = A^{-1}(A\vec{x}) = \vec{x}.$$

$$T(S(\vec{x})) = A(A^{-1}\vec{x}) = \vec{x}.$$

Uniqueness of S : Suppose S'

$$T(S(\vec{x})) = \vec{x} = S(T(\vec{x})) \Rightarrow \forall \vec{x}$$
$$T(S'(\vec{x})) = \vec{x} = S'(T(\vec{x})) \Rightarrow \forall \vec{x}$$

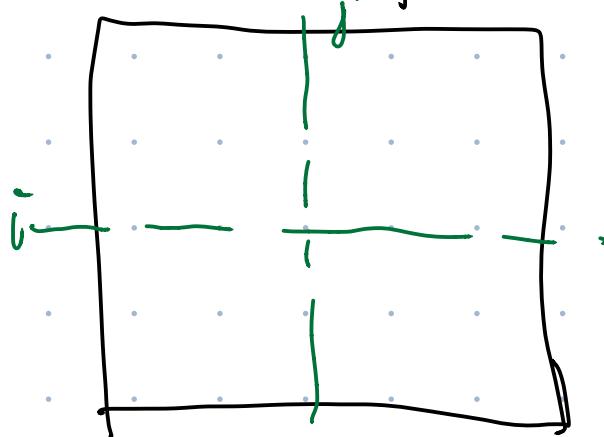
① each $\vec{v} \in \mathbb{R}^n$, $\exists \vec{w} \in \mathbb{R}^n$ s.t. $T(\vec{w}) = \vec{v}$

$$\begin{aligned} \textcircled{2} \quad \vec{w} &= S(T(\vec{v})) = S(\vec{v}) \Rightarrow S(\vec{v}) = S'(\vec{v}) + \vec{v} \\ \vec{w} &= S' (T(\vec{v})) = S'(\vec{v}) \Rightarrow S = S' \end{aligned}$$

Determinant (of a square matrix)

- 1×1 : $[a_{11}] \quad \det([a_{11}]) := a_{11}$
- 2×2 : $\det \begin{pmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{pmatrix} := a_{11}a_{22} - a_{12}a_{21}$

Def: $A: n \times n$, define A_{ij} to be the $(n-1) \times (n-1)$ matrix w/ the i -th row of A & j -th column of A removed.



e.g. $A = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}, \quad A_{21} = \begin{bmatrix} 2 & 3 \\ 8 & 9 \end{bmatrix}$

Def Determinant $\det(A)$ is defined inductively as follows:

Suppose we've defined $\det(\cdot)$ for any $(n-1) \times (n-1)$ matrix.

Now suppose $A: n \times n$

Define the (i,j) -cofactor of A as:

$$C_{ij} := (-1)^{i+j} \det A_{ij}$$

Pick any row

$$a_{i1}, \dots, a_{in} \quad \text{or}$$

any column

$$a_{ij}, \dots, a_{nj} \quad \text{of } A$$

Define

$$\det(A)_i = a_{i1} C_{i1} + \dots + a_{in} C_{in}$$

Or

$$\det(A) = a_{1j} C_{1j} + \dots + a_{nj} C_{nj}$$

(cofactor expression of the i th row or j th column)

Thm \det is well-defined, i.e. indep. of which column/row we choose to do the cofactor exp.

e.g:

$$\begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$$

$$a_{11}a_{22} - a_{12}a_{21}$$

//

$$\det(A) = a_{21} C_{21} + a_{22} C_{22}$$

↓

$$(-1)^{2+1} \det A_{21}$$

//

$$-a_{12}$$

$$(-1)^{2+2} \det A_{22}$$

//

$$a_{11}$$

ex-

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$

$$\det(A) = a_{11} C_{11} + a_{12} C_{12} + a_{13} C_{13}$$

$$= (-1)^{1+1} \det A_{11} + (-1)^{1+2} \det A_{12} + (-1)^{1+3} \det A_{13}$$

$$= a_{22}a_{33} - a_{23}a_{32} + a_{23}a_{31} - a_{21}a_{33} - a_{13}a_{21}a_{32} + a_{12}a_{23}a_{31}$$

Rule: "diagonal" "diagonal"

But this is NOT true if size $> 3!!$

In general,

$$\det(A) = \sum_{\sigma} (-1)^{\text{sgn}(\sigma)} a_{1\sigma(1)} a_{2\sigma(2)} \cdots a_{n\sigma(n)}$$

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix}$$

Where $\sigma: \{1, 2, \dots, n\} \rightarrow \{1, 2, \dots, n\}$ bij.