

Last time:

Linear system \rightsquigarrow associated augmented matrix.

they won't change
the solution set.

elementary row operations.

$$\left[\begin{array}{cccc|c} * & * & * & * & 1 \\ * & * & * & * & * \\ * & * & * & * & * \\ * & * & * & * & * \end{array} \right]$$

reduced echelon form.

How to read the sol's of a reduced echelon form?

Case 1: The last column has a pivot.

$$\left[\begin{array}{cccc|c} 0 & 0 & 1 & 2 & 0 & 3 & 0 \\ 0 & 0 & 0 & 0 & 1 & 4 & 0 \\ 0 & 0 & 0 & 0 & 0 & 0 & 1 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right] \rightarrow 0 \cdot x_1 + 0 \cdot x_2 + \dots + 0 \cdot x_6 = 1 \rightarrow \text{No sol}^n !!$$

Case 2: The last column has no pivots.

$$\begin{aligned} &\rightarrow \left[\begin{array}{cccc|c} 0 & 1 & 0 & 2 & 0 & 4 & 7 \\ 0 & 0 & 1 & 3 & 0 & 5 & 8 \\ 0 & 0 & 0 & 0 & 1 & 6 & 9 \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right] \\ &\rightarrow \left[\begin{array}{cccc|c} x_1 & x_2 & x_3 & x_4 & x_5 & x_6 \\ \uparrow & \uparrow & \uparrow & \uparrow & \uparrow & \uparrow \end{array} \right] \end{aligned}$$

$$x_2 + 2x_4 + 4x_6 = 7$$

$$x_3 + 3x_4 + 5x_6 = 8$$

$$x_5 + 6x_6 = 9$$

$$x_2 = 7 - 2x_4 - 4x_6$$

$$x_3 = 8 - 3x_4 - 5x_6$$

$$x_5 = 9 - 6x_6$$

Observe:

- for the "non-pivot variables" (x_1, x_4, x_6). we can assign them to be any real number.
- for any choice of $x_1, x_4, x_6 \in \mathbb{R}$, there is a unique choice

of x_2, x_3, x_5 that makes $\begin{bmatrix} x_1 \\ \vdots \\ x_6 \end{bmatrix}$ a solⁿ. of the system.

In other words, the solⁿ set of the system is given by:

$$\left\{ \vec{v} = \begin{bmatrix} x_1 \\ \vdots \\ x_6 \end{bmatrix} \in \mathbb{R}^6 \mid \begin{array}{l} x_1, x_4, x_6 \text{ any real number, and} \\ x_2 = 7 - 2x_4 - 4x_6 \\ x_3 = 8 - 3x_4 - 5x_6 \\ x_5 = 9 - 6x_6 \end{array} \right\}$$

Summary:

- a linear system has a solⁿ \Leftrightarrow the last column of its augmented matrix has no pivots.
- when it has a solⁿ, the solⁿ is unique \Leftrightarrow each column in the coefficient matrix has a pivot.

$$\left[\begin{array}{ccc|c} 1 & 0 & 0 & * \\ 0 & 1 & 0 & * \\ 0 & 0 & 1 & * \\ 0 & 0 & 0 & 0 \\ 0 & ; & ; & ; \\ \downarrow & \downarrow & \downarrow & \downarrow \end{array} \right]$$

↑
has a unique solⁿ

$$\left[\begin{array}{cccc|c} 1 & 0 & 0 & * & x \\ 0 & 1 & * & 0 & x \\ 0 & 0 & 1 & * & x \\ 0 & 0 & 0 & 0 & 0 \\ 0 & ; & ; & ; & ; \\ \downarrow & \downarrow & \downarrow & \downarrow & \downarrow \end{array} \right]$$

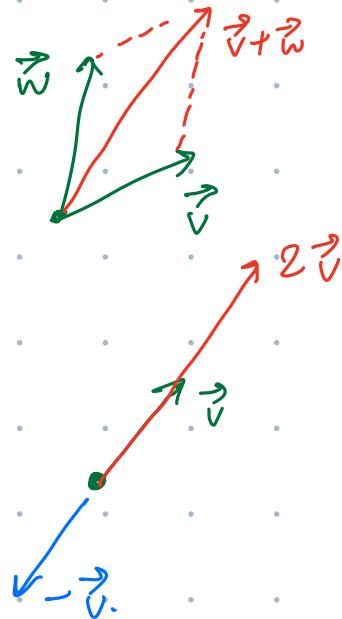
↑
solⁿ is not unique

Q: How do we characterize the vector \vec{b} s.t. $[A | \vec{b}]$ has a solⁿ?

§ Linear combinations of vectors.

Def: $\vec{v} = \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix}, \vec{w} = \begin{bmatrix} w_1 \\ \vdots \\ w_n \end{bmatrix} \in \mathbb{R}^n$

Sum: $\vec{v} + \vec{w} = \begin{bmatrix} v_1 + w_1 \\ \vdots \\ v_n + w_n \end{bmatrix} \in \mathbb{R}^n$



Scalar multiplication: $c \in \mathbb{R}$,

$$c \cdot \vec{v} = \begin{bmatrix} cv_1 \\ \vdots \\ cv_n \end{bmatrix} \in \mathbb{R}^n$$

Def: $\vec{v}_1, \dots, \vec{v}_k \in \mathbb{R}^n$.

Then, for any $c_1, \dots, c_k \in \mathbb{R}$, the vector

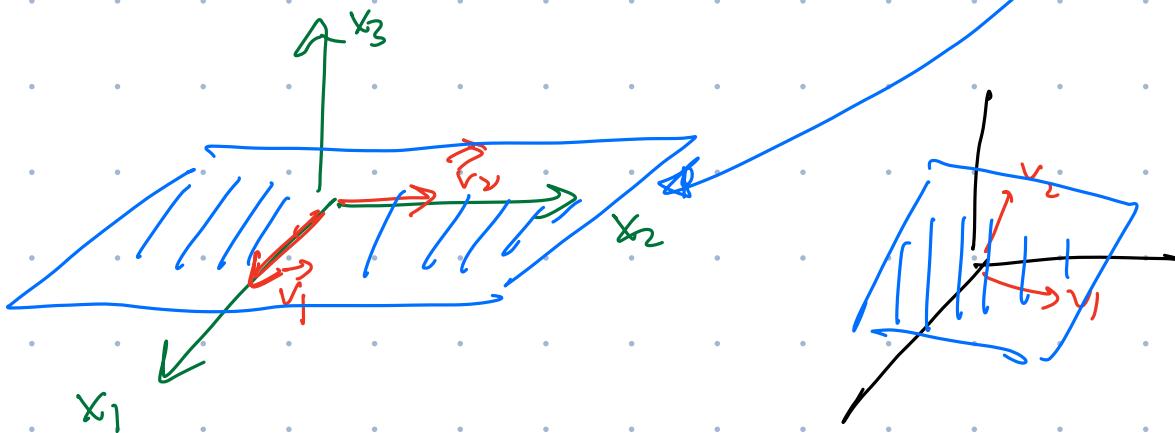
$$c_1 \vec{v}_1 + \dots + c_k \vec{v}_k$$

is a linear combination of $\vec{v}_1, \dots, \vec{v}_k$ (of weights c_1, \dots, c_k)

e.g. $\vec{v}_1 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}, \vec{v}_2 = \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} \in \mathbb{R}^3$

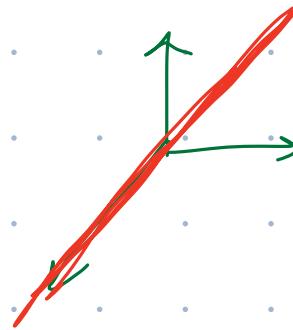
Q: What are all the linear combinations of \vec{v}_1, \vec{v}_2 ?

$$c_1 \vec{v}_1 + c_2 \vec{v}_2 = \begin{bmatrix} c_1 \\ 0 \\ 0 \end{bmatrix} + \begin{bmatrix} 0 \\ c_2 \\ 0 \end{bmatrix} = \begin{bmatrix} c_1 \\ c_2 \\ 0 \end{bmatrix}, \quad c_1, c_2 \in \mathbb{R}$$



Q: What are all the linear combinations of \vec{v}_1 ?

$$c_1 \vec{v}_1 = \begin{bmatrix} c_1 \\ 0 \\ 0 \end{bmatrix}, c_1 \in \mathbb{R}$$



Def: $\text{Span} \{ \vec{v}_1, \dots, \vec{v}_k \} := \{ \text{linear combinations of } \vec{v}_1, \dots, \vec{v}_k \}$
 $= \{ c_1 \vec{v}_1 + \dots + c_k \vec{v}_k \mid c_1, \dots, c_k \in \mathbb{R} \}$

e.g. $\vec{v}_1 = \begin{bmatrix} 1 \\ -2 \\ -5 \end{bmatrix}, \vec{v}_2 = \begin{bmatrix} 2 \\ 5 \\ 6 \end{bmatrix}, \vec{b} = \begin{bmatrix} 7 \\ 4 \\ -3 \end{bmatrix}$.

Q: Is $\vec{b} \in \text{Span} \{ \vec{v}_1, \vec{v}_2 \}$?



$\exists ? c_1, c_2 \in \mathbb{R}$ s.t. $c_1 \vec{v}_1 + c_2 \vec{v}_2 = \vec{b}$.

$$\begin{bmatrix} 7 \\ 4 \\ -3 \end{bmatrix}$$

$$c_1 \begin{bmatrix} 1 \\ -2 \\ -5 \end{bmatrix} + c_2 \begin{bmatrix} 2 \\ 5 \\ 6 \end{bmatrix}$$



$$\begin{bmatrix} c_1 \\ -2c_1 \\ -5c_1 \end{bmatrix} + \begin{bmatrix} 2c_2 \\ 5c_2 \\ 6c_2 \end{bmatrix} = \begin{bmatrix} c_1 + 2c_2 \\ -2c_1 + 5c_2 \\ -5c_1 + 6c_2 \end{bmatrix}$$



$$\text{Does } \begin{cases} c_1 + 2c_2 = 7 \\ -2c_1 + 5c_2 = 4 \\ -5c_1 + 6c_2 = -3 \end{cases}$$

have a sol'??

↑
augmented matrix

$$\left[\begin{array}{ccc|c} 1 & 2 & 7 \\ -2 & 5 & 4 \\ -5 & 6 & -3 \end{array} \right] \quad \begin{matrix} \vec{v}_1 \\ \vec{v}_2 \\ \vec{v}_3 \end{matrix}$$

Observation: $\vec{b} \in \text{Span}\{\vec{v}_1, \dots, \vec{v}_k\}$

$$\iff \left[\begin{array}{ccc|c} 1 & & & | \\ \vec{v}_1 & \cdots & \vec{v}_k & | \\ & & 1 & | \\ & & \vec{b} & | \end{array} \right] \text{ has a sol.}$$

Def: (matrix-vector product).

$$A: m \times n \text{ matrix.} = \left[\begin{array}{c|c|c} 1 & & \\ \vec{a}_1 & \cdots & \vec{a}_n \\ \hline \end{array} \right] \quad \vec{a}_i \in \mathbb{R}^m$$

$$\vec{x} \in \mathbb{R}^n \quad \vec{x} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix}$$

Define: $A \vec{x} := x_1 \vec{a}_1 + \dots + x_n \vec{a}_n \in \mathbb{R}^m$.

$$\text{e.g. } \left[\begin{array}{ccc} 1 & 3 & 5 \\ 2 & 4 & 6 \end{array} \right] \left[\begin{array}{c} 7 \\ 8 \\ 9 \end{array} \right] = 7 \begin{bmatrix} 1 \\ 2 \end{bmatrix} + 8 \begin{bmatrix} 3 \\ 4 \end{bmatrix} + 9 \begin{bmatrix} 5 \\ 6 \end{bmatrix}$$

$$= \begin{bmatrix} 7 \cdot 1 + 8 \cdot 3 + 9 \cdot 5 \\ 7 \cdot 2 + 8 \cdot 4 + 9 \cdot 6 \end{bmatrix} \in \mathbb{R}^2$$

e.g. $\left[\begin{array}{cc} 1 & 2 \\ 3 & 4 \\ 5 & 6 \end{array} \right] \left[\begin{array}{c} 7 \\ 8 \\ 9 \end{array} \right]$ doesn't make sense!

Rmk: Given a $A \in \mathbb{R}^{m \times n}$, $\vec{b} \in \mathbb{R}^m$.

Then

$$\left[\begin{array}{c|c} \vec{a}_1 & \cdots & \vec{a}_n \\ \hline \vec{b} & \end{array} \right] \text{ has a sol}^n$$

$$\Leftrightarrow \vec{b} \in \text{Span}\{\vec{a}_1, \dots, \vec{a}_n\}.$$

$$\Leftrightarrow \exists \vec{x} \in \mathbb{R}^n \text{ s.t. } A\vec{x} = \vec{b}.$$

Given an $m \times n$ matrix A , we can define a function

$$T_A: \mathbb{R}^n \longrightarrow \mathbb{R}^m$$

$$\vec{x} \longmapsto A\vec{x}.$$

Rmk: The map T_A encodes the info of the solvability of linear eq's, $A\vec{x} = \vec{b}$.

$[A | \vec{b}]$ has solⁿ $\Leftrightarrow \vec{b}$ is in the image of T_A .

We'll be studying criterions of injectivity and surjectivity of T_A .

For a function $f: X \rightarrow Y$.

• f is injective if $\forall x_1, x_2 \in X, x_1 \neq x_2$, we have

$$\left(\begin{array}{ccc} x_1 & \xrightarrow{f} & f(x_1) \\ x_2 & \xrightarrow{f} & f(x_2) \end{array} \right) \text{ doesn't happen} \quad f(x_1) \neq f(x_2)$$

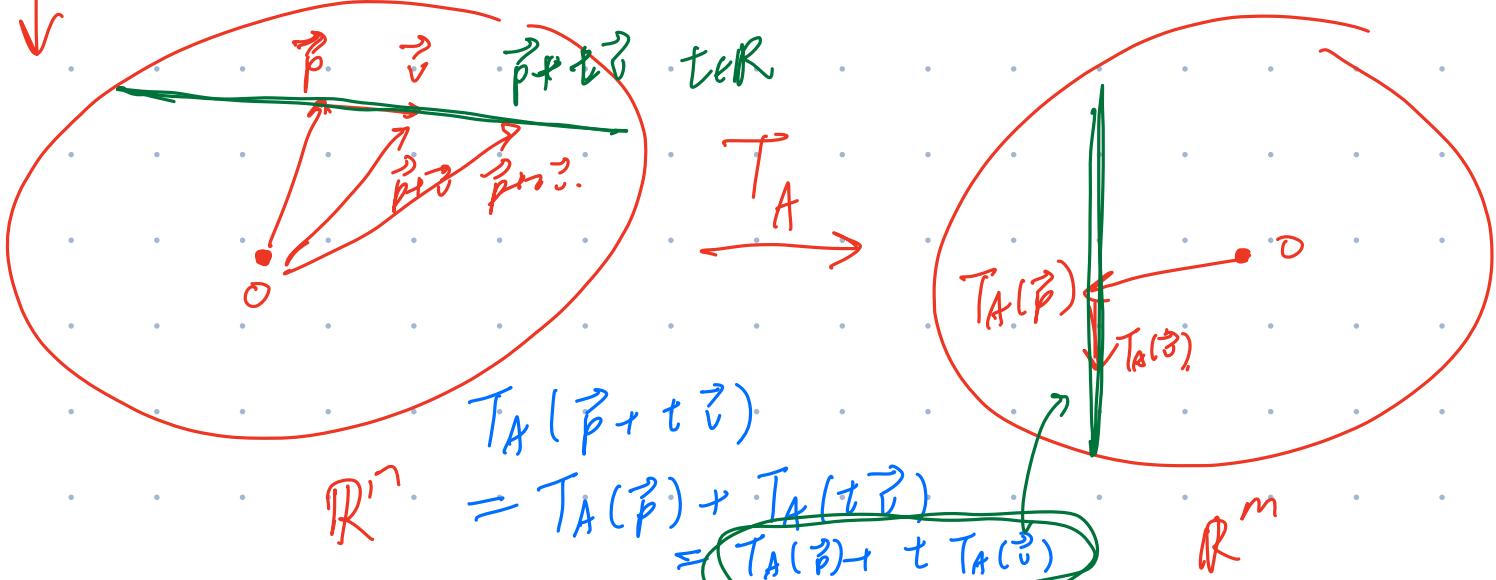
- f is surjective if $\forall y \in Y, \exists x \in X$ st. $f(x) = y$.

Prop: $A: m \times n$, $T_A: \mathbb{R}^n \rightarrow \mathbb{R}^m$

- If $\vec{u}, \vec{v} \in \mathbb{R}^n$, we have $T_A(\vec{u} + \vec{v}) = T_A(\vec{u}) + T_A(\vec{v})$.
 - If $c \in \mathbb{R}$, we have $T_A(c\vec{v}) = cT_A(\vec{v})$.

(iii. T_A is a linear transformation)

$$\begin{aligned}
 \text{Rf: } T_A(\vec{u} + \vec{v}) &= A(\vec{u} + \vec{v}) = A \begin{bmatrix} u_1 + v_1 \\ \vdots \\ u_n + v_n \end{bmatrix} \\
 &\quad \parallel \quad \parallel \\
 &= \begin{bmatrix} a_1 & \cdots & a_n \end{bmatrix} \begin{bmatrix} u_1 \\ \vdots \\ u_n \end{bmatrix} + \begin{bmatrix} u_1 \\ \vdots \\ u_n \end{bmatrix} \begin{bmatrix} v_1 \\ \vdots \\ v_n \end{bmatrix} \\
 &\quad \parallel \\
 &= (\vec{u}_1 + v_1) \vec{a}_1 + \cdots + (\vec{u}_n + v_n) \vec{a}_n
 \end{aligned}$$



Q: When is $T_A: \mathbb{R}^n \rightarrow \mathbb{R}^m$ surjective?

$\Leftrightarrow \forall \vec{b} \in \mathbb{R}^m, \exists \vec{x} \in \mathbb{R}^n$ st. $A\vec{x} = \vec{b}$.

$\Leftrightarrow \forall \vec{b} \in \mathbb{R}^m$, the system $[A | \vec{b}]$ has a solⁿ.

e.g. $A = \begin{bmatrix} 1 & 1 & 2 & 3 \\ 2 & 3 & 5 & 8 \\ 3 & 5 & 8 & 13 \end{bmatrix}$ Is T_A surjective?

whether $\forall \vec{b} \in \mathbb{R}^3$, $[A | \vec{b}]$ has a solⁿ?

$$\left[\begin{array}{cccc|c} 1 & 1 & 2 & 3 & b_1 \\ 2 & 3 & 5 & 8 & b_2 \\ 3 & 5 & 8 & 13 & b_3 \end{array} \right] \rightsquigarrow \left[\begin{array}{cccc|c} 1 & 1 & 2 & 3 & b_1 \\ 0 & 1 & 1 & 2 & b_2 - 2b_1 \\ 0 & 2 & 2 & 4 & b_3 - 3b_1 \end{array} \right]$$

$$\rightsquigarrow \left[\begin{array}{cccc|c} 1 & 1 & 2 & 3 & b_1 \\ 0 & 1 & 1 & 2 & b_2 - 2b_1 \\ 0 & 0 & 0 & 0 & b_3 - 2b_1 - 2(b_2 - 2b_1) \end{array} \right]$$

$0x_1 + 0x_2 + 0x_3 + 0x_4$

$$\exists b_1, b_2, b_3 \text{ st. } b_3 - 2b_1 - 2(b_2 - 2b_1) \neq 0$$

so, T_A is not surjective.

More generally,

$$\left[\begin{array}{cccccc|c} & 1 & & & & & \\ & & 1 & & & & \\ & & & 1 & & & \\ 0 & 0 & 0 & 0 & 0 & 0 & 0 & \end{array} \right] \quad \#$$

Observation: If A doesn't have pivot in each row, then $\exists \vec{b} \in \mathbb{R}^n$ st. $A\vec{x} = \vec{b}$ has no solⁿ.
 $(\Leftrightarrow T_A$ is not surjective).

Conversely, if A has pivots in each row,

$$\left[\begin{array}{cccccc|c} 0 & 0 & 1 & & & & \\ 0 & 0 & 0 & 1 & & & \\ 0 & 0 & - & - & - & 0 & 1 \end{array} \right]$$

then $[A | \vec{b}]$ doesn't have pivot in the last column.
 $\nexists \vec{b} \in \mathbb{R}^m$

$\Rightarrow [A | \vec{b}]$ has a solⁿ. $\forall \vec{b} \in \mathbb{R}^m$.

$\Leftarrow T_A$ is surjective.

Conclusion: T_A is surjective $\Leftrightarrow A$ has pivot in each row.

Thm: $A: m \times n$. Then the following are equivalent:

- $T_A: \mathbb{R}^n \rightarrow \mathbb{R}^m$ is surjective.
 $\vec{x} \mapsto A\vec{x}$
- $A\vec{x} = \vec{b}$ has a solⁿ $\forall \vec{b} \in \mathbb{R}^m$
- A has pivot in each row.
- $\forall \vec{b} \in \mathbb{R}^m$, \vec{b} is a linear combination of the columns $\vec{a}_1, \dots, \vec{a}_n$ of A .
- $\text{Span}\{\vec{a}_1, \dots, \vec{a}_n\} = \mathbb{R}^m$