Algebraic Structures and Polynomials

CS70 Summer 2016 - Lecture 7C

David Dinh 03 August 2016

UC Berkeley

Today

Review: Chinese Remainder Theorem and Blum Coin Flipping

Algebraic Structures: Groups, Rings, and Fields

Galois Fields

Polynomials

Applications: Secret Sharing and Erasure Codes

Motivation

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Define *algebraic structures* through axioms that define how they behave.

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Notice that there no commutativity requirement. "·" may be non-commutative! If it is commutative, we refer to the group as *abelian*. Formally, Abelian groups must satisfy requires another axiom:

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Also, note that + doesn't necessarily have to represent addition in the normal sense. Elements of G may not even be numbers!

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Examples: With addition and multiplication defined in the usual sense \mathbb{R} , \mathbb{Q} , and \mathbb{C} are fields. \mathbb{Z} is a commutative ring but not a field.

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A polynomial is said to contain a point (x,y) if p(x) = y.

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One way to do it: try plugging in the points and solving for the coefficients. Say I give you $(x_1, y_1), (x_2, y_1), \dots, (x_{d+1}, y_{d+1})$.

$$y_1 = a_0 + a_1 x_1 + a_2 x_1^2 + \dots + a_d x_1^d$$

$$\vdots$$

$$y_{d+1} = a_0 + a_1 x_{d+1} + a_2 x_{d+1}^2 + \dots + a_d x_{d+1}^d$$

Or in matrix form:

$$\begin{bmatrix} 1 & x_1 & x_1^2 & \dots & x_1^d \\ 1 & x_2 & x_2^2 & \dots & x_2^d \\ 1 & x_3 & x_3^2 & \dots & x_3^d \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & x_{d+1} & x_{d+1}^2 & \dots & x_{d+1}^d \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ \vdots \\ a_d \end{bmatrix} = \begin{bmatrix} y_1 \\ y_2 \\ y_3 \\ \vdots \\ y_{d+1} \end{bmatrix}$$

(This matrix is called the Vandermonde matrix.)

How do we know the system of equations on the previous slide has a solution? Unfortunately, we don't. (If you know linear algebra you can prove directly through determinants or through linear independence that the Vandermonde matrix is nonsingular, but that's beyond the scope of this course.)

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$$\Delta_1(x) := y_1 \frac{(x - x_2)(x - x_3) \dots (x - x_{d+1})}{(x_1 - x_2)(x_1 - x_3) \dots (x_1 - x_{d+1})}$$

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How do we know the system of equations on the previous slide has a solution? Unfortunately, we don't. (If you know linear algebra you can prove directly through determinants or through linear independence that the Vandermonde matrix is nonsingular, but that's beyond the scope of this course.)

Let's try another way to get the polynomial: set the value at each *x*-coordinate, one at a time.

Notice that $(x-x_2)(x-x_3)...(x-x_{d+1})$ is zero at $x_2,x_3,...,x_{d+1}$ (but not at x_1). What if we divide by its value at $x=x_1$ and then multiply by y_1 ?

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Value at x_1 ? y_1 . Value at $x_2, ..., x_{d+1}$? 0. General idea behind interpolation: make these polynomials for all i and add them together.

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We already know there is such a polynomial (we constructed one). Remains to show uniqueness.

Proof of Theorem 2

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Given a degree-d polynomial f(x) and a polynomial g(x) of degree at most d, we can use long division to write f(x) = g(x)q(x) + r(x) for some polynomials q(x), r(x) such that the degree of r(x) is strictly smaller than the degree of f(x). Method: same as elementary-school long division for numbers!

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So
$$x^3 - 2x^2 - 4 = (x-3)(x^2 + x + 3) + 5$$
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It immediately follows that a nonzero polynomial of degree d has at most d roots. Why? Suppose for contradiction that it has more than d. Take first d roots and write the polynomial as $c(x-a_1)...(x-a_d)$. Plug in the d+1st root, a_{d+1} . Since it's distinct from $a_1,...,a_d$ this polynomial must be nonzero, contradicting our assertion that a_{d+1} was a root. Therefore, we've proven Theorem 1.

Up next...

Counting polynomials.

Applications: Shamir's secret sharing and error-correcting codes.

Polynomial identity testing and the Schwartz-Zippel lemma