Convex

2023年5月22日

Affine sets

$$\begin{split} & \boldsymbol{x} = (\xi_1,...,\xi_n) \subset \mathbb{R}^n \\ & \langle x,x^* \rangle = \sum_{i=1}^n \xi_i \cdot \xi_i^* \\ & A: m \times n \text{ real matrix and linear operator from } \mathbb{R}^n \text{ to } \mathbb{R}^m \end{split}$$

 $f: \mathbb{R}^n \to \mathbb{R}^m \colon x \mapsto Ax$

 $A^* = \overline{A}^{\top}$: adjoint matrix (随伴行列、エルミート転置行列)

(the transpose matrix and the corresponding adjoint linear transformation from \mathbb{R}^n to \mathbb{R}^m)

 $\langle Ax, y^* \rangle = \langle x, A^*y^* \rangle$

Definition 1.1 (affine set). A subset M of \mathbb{R}^n is called affine set if

$$\theta x + (1 - \theta)y \in M, \quad \forall x, y \in M, \forall \theta \in \mathbb{R}$$

The empty set \emptyset and the space \mathbb{R}^n itself are affine sets. Also coverd by the definition is the case where M consists of a solitary point. (一点集合も Affine set) An affine set has to contain, along with any two different points, the entire line through those points.

Theorem 1.1. The subspaces of \mathbb{R}^n are the affine sets which contain the origin.

Definition 1.2. For $M \subset \mathbb{R}^n$ and $a \in \mathbb{N}$, the translate (平行移動) of M by a is defined to be the set

$$M+a=\{x+a\,|\,x\in M\}$$

An affine set M is said to be parallel to an affine set L if L = M + a for some a.

Theorem 1.2. Each non-empty affine set M is parallel to a unique subspace L. This L is given by

$$L = C - C = \{x - y \,|\, x, y \in C\}$$

The dimension of a non-empty affine set is defined as the dimension of the subspace parallel to it. (The dimension of \emptyset is -1 by convention.)

空でないアフィン集合の次元は、それに平行な部分空間の次元と定義される。(∅ の次元は慣習的に −1) Affine sets of dimension 0, 1 and 2 are called points, lines and planes, respectively.

Definition 1.3 (Affine combination). Let $x_1, ..., x_n \in \mathbb{R}^n$, and $\theta_1, ..., \theta_n \in \mathbb{R}(n \in \mathbb{N})$. $\sum_{i=1}^n \theta_i x_i$ is an affine combination of $x_1, ..., x_n$ if $\sum_{i=1}^n \theta_i = 1$

Theorem 1.3 (Hyperplane). Given $\beta \in \mathbb{R}$ and a non-zero $\mathbf{b} \in \mathbb{R}^n$, the set

$$H = \{x \in \mathbb{R}^n \mid \langle \boldsymbol{x}, \boldsymbol{b} \rangle = \boldsymbol{\beta} \}$$

is a hyperplane in \mathbb{R}^n .

The vector \boldsymbol{b} is called a normal to the hyperplane H.

Every hyper plane has "two sides," loke one's picture of alne in \mathbb{R}^2 or a plane in \mathbb{R}^3 .

Theorem 1.4. Given $b \in \mathbb{R}^m$ and an $m \times n$ real matrix B, the set

$$M = \{ x \in \mathbb{R}^n \, | \, \boldsymbol{B}\boldsymbol{x} = \boldsymbol{b} \}$$

is an affine set in \mathbb{R}^n . Moreover, every affine set may be represented in this way.

Let b_i is the *i*th row of B, β_i is the *i*-th component of b, and

$$H_i = \{ \boldsymbol{x} \mid \langle \boldsymbol{x}, \boldsymbol{b_i} \rangle = \beta_i, \}.$$

Then,

$$M = \{ \boldsymbol{x} \mid \langle \boldsymbol{x}, \boldsymbol{b_i} \rangle = \beta_i, i = 1, ..., m \} = \bigcap_{i=1}^m H_i.$$

Each H_i is a hyperplane $(b_i \neq 0)$.

The affine set M in Theorem can be expressed in terms of the vebtors $b'_1, ..., b'_n$ which form the columns of B by

$$M = \{ \boldsymbol{x} = (\xi_1, ..., \xi_n) \mid \sum_{i=1}^n \xi_i b_i' = \boldsymbol{b} \}$$

任意の集合 $S \in \mathbb{R}^n$ に対し、S を含む(唯一で)最小のアフィン集合が存在する。これをアフィン包 (affinehull) という。

Definition 1.4 (affine hull). A subset C of \mathbb{R}^n is callded affine hull if

aff
$$S = \{ \sum_{i=1}^{n} \theta_i x_i \mid x_i \in S(i=1,...,n), \sum_{i=1}^{n} \theta_i = 1 \}.$$

Definition 1.5. A set of k + 1 points b_0, b_1, \ldots, b_k is said affinely independent if the set

is k-dimensional.

定理 1.1 より、L は b_1-b_0,\ldots,b_k-b_0 を含む最小の部分集合と同じになる。L の次元が k になる必要十分条件は b_1-b_0,\ldots,b_k-b_0 が、線形独立になることである。従って、 b_0,b_1,\ldots,b_k がアフィン独立である必要十分条件は b_1-b_0,\ldots,b_k-b_0 が線形独立であることである。

よって x_0, x_1, \ldots, x_k がアフィン独立であれば、 $x \in \text{aff}\{b_0, b_1, \ldots, b_k\}$ は次のように表せる。

$$x = \sum_{i=0}^{k} \theta_i x_i, \quad \sum_{i=0}^{k} \theta_i = 1.$$

Definition 1.6 (affine transform). $T: x \to Tx$ from \mathbb{R}^n to \mathbb{R}^m is called affine transformation if

$$T((1-\lambda)x + \lambda y) = (1-\lambda)Tx + \lambda Ty, \quad \forall x, y \in \mathbb{R}^n, \forall \lambda \in \mathbb{R}$$

2 Convex Sets and Cones

Definition 2.1 (convex set). A subset C of \mathbb{R}^n is called *convex* if

$$\theta x + (1 - \theta)y \in C, \quad \forall x, y \in C, \forall \theta \in [0, 1]$$

All affine sets are convex.

Definition 2.2 (convex combination). An affine combination with a coefficient $\theta_i \in [0,1]$ is called a *convex combination*, i.e.

let $x_1,...,x_n \in \mathbb{R}^n$, and $\theta_1,...,\theta_n \in \mathbb{R} (n \in \mathbb{N})$. $\sum_{i=1}^n \theta_i \cdot x_i$ is an combex combination of $x_1,...,x_n$ if

$$\sum_{i=1}^{n} \theta_i x_i \quad (\theta_i \in [0, 1] (i = 1, ..., n)), \qquad \sum_{i=1}^{n} \theta_i = 1,$$

Definition 2.3 (Half-spaces(半空間)). For any non-zero $b \in \mathbb{R}^n$ and any β in \mathbb{R} , the sets

$$\{x \mid \langle x, b \rangle \leq \beta\}, \qquad \{x \mid \langle x, b \rangle \geq \beta\}$$

are called *closed half-spaces*. The sets

$$\{x \mid \langle x, b \rangle < \beta\}, \qquad \{x \mid \langle x, b \rangle > \beta\}$$

are called open half-spaces. All four sets are plainly non-empty and convex.

Theorem 2.1. The intersection of an arbitrary collection of convex sets is convex.

A set which can be expressed as the inter section of finitely many closed half spaces of \mathbb{R}^n is called a polyhedral convex set. (凸多面体)

$$H = \{x \in \mathbb{R}^n \mid \langle x, b \rangle = \beta\}, a \in H$$
とするとき、半空間 $(\{x \in \mathbb{R}^n \mid \langle x, b \rangle \leq \beta\})$ は

$$C = \{ x \in \mathbb{R}^n \, | \, \langle \boldsymbol{x} - \boldsymbol{a}, \boldsymbol{b} \rangle \le \boldsymbol{0} \}$$

と表せる。b は点 a における法線ベクトルである。

これは点 a から半空間 ($\{x \in \mathbb{R}^n \mid \langle x, b \rangle \leq \beta\}$) 上の点 a に向かうベクトルが超平面の法線ベクトル b と鈍角をなすことを意味している。

よって、半空間 $(\{x \in \mathbb{R}^n \mid \langle x, b \rangle \leq \beta\})$ は b の反対側に位置する。

一方、半空間 $(\{x \in \mathbb{R}^n \mid \langle x, b \rangle \geq \beta\})$ は b の同じ側に位置する。

Corollary 2.1.1. Let $b_i \in \mathbb{R}^n$ and $\beta_i \in \mathbb{R}$ for $i \in I$, where I is an arbitrary index set, and consider the set

$$C = \{ x \in \mathbb{R}^n \, | \, \langle \boldsymbol{x}, \boldsymbol{b_i} \rangle \le \boldsymbol{\beta_i}, \forall i \in I \}.$$

It is crealy convex.

Theorem 2.2. A set $C \in \mathbb{R}^n$ is convex if and only if it contains all the convex combinations of its elements.

$$(C \in \mathbb{R}^n)$$
 が凸集合 $\iff C$ の元からなる全ての凸結合を C 自身が含む)

Theorem 2.3 (convex hull). The convex hull of a given set $X \subset \mathbb{R}^n$ may be defined as the set satisfying any one (and hence all) of the following equivalence conditions.

- 1. The (unique) minimal convex set containing X. (X を含む (唯一の) 最小の凸集合)
- 2. The intersection of all convex sets containing X.

$$convX = \cap \{C : C \text{ is convex set}, X \subset C\}$$

3. The set of all the convex combinations of points in X. (X に属する点から得られる凸結合全体の成す集合)

$$convX = \{ \sum_{i=1}^{n} \theta_{i} x_{i} \in \mathbb{R}^{n} \mid \exists m \in \mathbb{N}, \exists x_{1}, ..., x_{m} \in X, \exists \theta_{1}, ..., \theta_{m} \in [0, 1], \sum_{i=1}^{n} \theta_{i} = 1 \}$$

4. (Carathéodory's Theorem) The union of all simplices with vertices in X. (X に属する点を頂点とする単体全ての合併)

$$convX = \{\sum_{i=1}^{n+1} \theta_i x_i \mid n \in \mathbb{N}, x_i \in X, \theta_i > 0, \sum_{i=1}^{n+1} \theta_i = 1\}$$

A set which is a convex hull of a finite number of points is called a polytope(超多面体).

Definition 2.4. A subset K of \mathbb{R}^n is called *cone* if it is closed under positive scalar multiplication, i.e. $\lambda x \in K$ for $x \in K$ and $\lambda > 0$.

Definition 2.5. A subset K of \mathbb{R}^n is called *convex cone* if it is closed under positive scalar multiplication, i.e. $\lambda x + (1 - \lambda)y \in K$ for $x, y \in K$ and $\lambda > 0$.

If K contains the origin, we call it a convex cone.

A convex cone should not necessarily be considered "pointed". A subspace of \mathbb{R}^n is a particularly convex cones. The same is true is the open and closed half-space corresponding to a hyperplane through the origin.

Non-negative orthant of \mathbb{R}^n is convex cone.

$$\mathbb{R}^{n}_{+} = \{ x = (\xi_{1}, \dots, \xi_{n}) \in \mathbb{R}^{n} \mid \xi_{i} \geq 0 \text{ for } i = 1, \dots, n \} = \{ x \in \mathbb{R}^{n} \mid x \geq 0 \}$$
$$\mathbb{R}^{n}_{>0} = \{ x = (\xi_{1}, \dots, \xi_{n}) \in \mathbb{R}^{n} \mid \xi_{i} > 0 \text{ for } i = 1, \dots, n \} = \{ x \in \mathbb{R}^{n} \mid x > 0 \}$$

Theorem 2.4. The intersection of an arbitrary collection of convex cones is a convex cone.

Corollary 2.4.1. Let $b_i \in \mathbb{R}^n$ for $i \in I$, where I is an arbitrary index set. Then

$$K = \{x \in \mathbb{R}^n \mid \langle \boldsymbol{x}, \boldsymbol{b_i} \rangle \le 0, i \in I\}$$

is a convex cone.

3 Convex Functions

This note is excluded the value $f(x) = -\infty$.

Definition 3.1. A function $f: C \to \mathbb{R}$, where C is a convex set. Then f is convex on C if and only if

$$f((1-\lambda)x + \lambda y) \le (1-\lambda)f(x) + \lambda f(y), \quad \forall x, y \in C, \quad \lambda \in [0,1].$$

Let f: convex function, $f \in C \neq \emptyset$. Extending f to \mathbb{R}^n by setting $f(x) = +\infty$ for $x \notin C \subset \mathbb{R}^n$. Then the above definition is equivalent to the following definition.

Definition 3.2. A function $f: \mathbb{R}^n \to \mathbb{R} \cup \{+\infty\}$, not identically $+\infty$, is convex if and only if

$$f((1-\lambda)x + \lambda y) \le (1-\lambda)f(x) + \lambda f(y), \quad \forall x, y \in \mathbb{R}^n, \quad \lambda \in [0,1].$$

 $f:\mathbb{R}^n \to \mathbb{R}: concave \Leftrightarrow -f$ is convex.

Definition 3.3. $f: \mathbb{R}^n \to \mathbb{R} \cup \{+\infty\}, C \subset \mathbb{R}^n$. We define epigraph of f as

$$epif := \{(\boldsymbol{x}, y) \mid \boldsymbol{x} \in C, y \in \mathbb{R}, y \ge f(\boldsymbol{x})\}.$$

Note that $f(x) = +\infty$ for $x \notin C$.

In othe words,

 $f:\mathbb{R}^n\to\mathbb{R}\cup\{+\infty\}$, not identically equal to $+\infty$. We define epigraph of f is the non-empty set

$$epif := \{(\boldsymbol{x}, y) \mid \boldsymbol{x} \in \mathbb{R}^n, y \in \mathbb{R}, y \ge f(\boldsymbol{x})\}.$$

Definition 3.4. The *effective domain* of function f on C is the set

$$\operatorname{dom} f = \{ \boldsymbol{x} \in \mathbb{R}^n \mid \exists y, (\boldsymbol{x}, y) \in \operatorname{epi} f \} = \{ \boldsymbol{x} \in \mathbb{R}^n \mid f(\boldsymbol{x}) < +\infty \}.$$

Definition 3.5. A convex function f is said to be *proper* if $f(x) < +\infty$ at least one $x \in C$ and $f(x) > -\infty$ for all $x \in C$.

In other words, f is proper if its epigraph is non-empty and does not contain "vertical lines".

Let f: convex function, $C \subset \mathbb{R}^n$ is non-empty convex set.

 $f \in C$ is proper \Leftrightarrow

dom f = C where $f \in C$ is finite.

 $f \in \mathbb{R}^n$ is proper \Leftrightarrow

$$f \in \mathbb{R}^n$$
 is convex function and $f \in C$ is finite. $\Rightarrow f(x) = \begin{cases} f(x) & (x \in C) \\ +\infty & (x \notin C) \end{cases}$

In this note, we excluded the value $f(x) = -\infty$, so from the definition 3.2, every convex function f is "proper".

Theorem 3.1. $f: \mathbb{R}^n \to \mathbb{R} \cup \{+\infty\}$.

f is a convex funciton if and only if epi f is convex set.

Theorem 3.2. Let $f: \mathbb{R}^n \to (-\infty, +\infty], \lambda_i \geq 0$ and $\sum_{i=0}^k \lambda_i = 1$. Then f is convex if and only if

$$f(\sum_{i=0}^{k} \lambda_i x_i) \le \sum_{i=0}^{k} \lambda_i f(x_i).$$

Neighborhood of x' is defined by

$$B(x', \delta) := \{ \bar{x} \mid d(x', x) < \delta \}.$$

 $V \in \mathcal{N}(x') :=$ the collection of all neiborhoods of x'.

Definition 3.6. (lower limits) Let $f: \mathbb{R}^n \to \mathbb{R} \cup \{+\infty\}$ and let x' is a limit point of f. Then the lower limit of function f is defined by

$$\begin{split} \liminf_{x \to x'} f(x) &= \lim_{\delta \, \searrow \, 0} \left[\inf_{x \in B(x',\delta)} f(x) \right] \\ &= \sup_{\delta \, > \, 0} \left[\inf_{x \in B(x',\delta)} f(x) \right] = \sup_{V \in \mathcal{N}(x')} \left[\inf_{x \in V} f(x) \right]. \end{split}$$

Definition 3.7. (lower semi-continuous) Let $f: \mathbb{R}^n \to \mathbb{R} \cup \{+\infty\}$ and let x' is a limit point of f. Then f is lower semi-continuous at x' if and only if

$$\liminf_{x\to x'} f(x) \geq f(x'), \ \text{or} \ \liminf_{x\to x'} f(x) = f(x')$$

Definition 3.8. (level set) The lower level sets $lev_{\leq \alpha}f$ is defined by

$$lev_{\leq \alpha}f := \{x \in \mathbb{R}^n \mid f(x) \leq \alpha\}$$

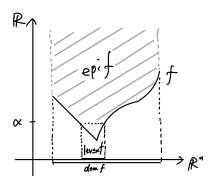


図 1 Level set

Proposition 3.3. Let arbitrary function $f: \mathbb{R}^n \to [-\infty, +\infty]$, the following are equivalent:

- (i) f is lower semi-continuous at all $x' \in \mathbb{R}^n$;
- (ii) $lev_{\alpha}f := \{x^{s'} \in \mathbb{R}^n \mid f(x') \leq \alpha\}$ is closed for every α ;
- (iii) epif is a closed set in \mathbb{R}^{n+1} .

Definition 3.9. (level boundedness) A function $f: \mathbb{R}^n \to \mathbb{R} \cup \{+\infty\}$ is lower level bounded if the set $lev_{\leq \alpha}f$ is bounded (possibly empty) for every $\alpha \in \mathbb{R}$.

Theorem 3.4. (conditions inf $f = \min f$) Suppose $f : \mathbb{R}^n \to \mathbb{R} \cup \{+\infty\}$ is lower semi-continuous, level-bounded and proper. Then the set argminf is nonenpty and compact and the value inf f is finite. In other words, inf $f = \min f$.

Corollary 3.4.1. (lower bounds) Suppose $f: \mathbb{R}^n \to \mathbb{R} \cup \{+\infty\}$ is lsc and proper. Then it is bounded from below on each bounded subset of \mathbb{R}^n . Actually, it is minimum with respect to any compact subset of \mathbb{R}^n that satisfies dom f.

4