

CH 6 학습 관련 기술들

- 01 매개변수 갱신
- 02 가중치의 초깃값
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- 04 바른 학습을 위해
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1. 매개변수 갱신

신경망 학습의 목적

: 손실함수의 값을 가능한 낮추는 매개변수를 찾는 것

→ 최적화

$$\mathbf{W} \leftarrow \mathbf{W} - \eta \frac{\partial L}{\partial \mathbf{W}}$$

확률적 경사 하강법

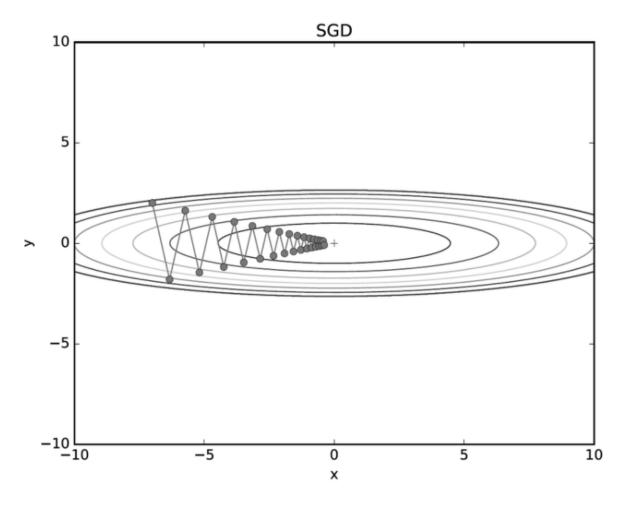
데이터를 무작위로 선정하여 경사 하강법을 적용하는 매개변수 갱신 방법 추출된 데이터 한 개에 대해서 그라디언트를 계산

```
class SGD:
    def __init__(self, lr=0.01):
        self.lr = lr

    def update(self, params, grads):
        for key in params.keys():
            params[key] -= self.lr * grads[key]
```

→ SGD 클래스 구현

→ 매개변수 갱신 진행

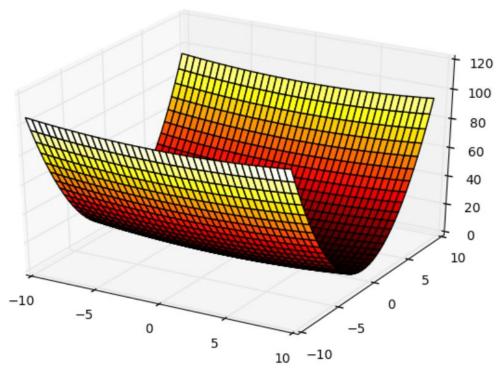


- 비등방성 함수에서 탐색 경로가 비효율적

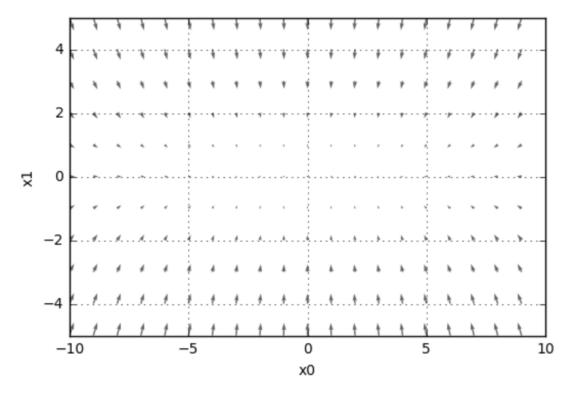
지그재그로 탐색하는 근본원인은 기울어진 방향이
 본래의 최솟값과 다른 방향을 가리켜서임.

* 비등방성 함수 : 방향에 따라 성질(기울기)가 달라지는 함수

$$f(x,y)=rac{1}{20}x^2+y^2$$

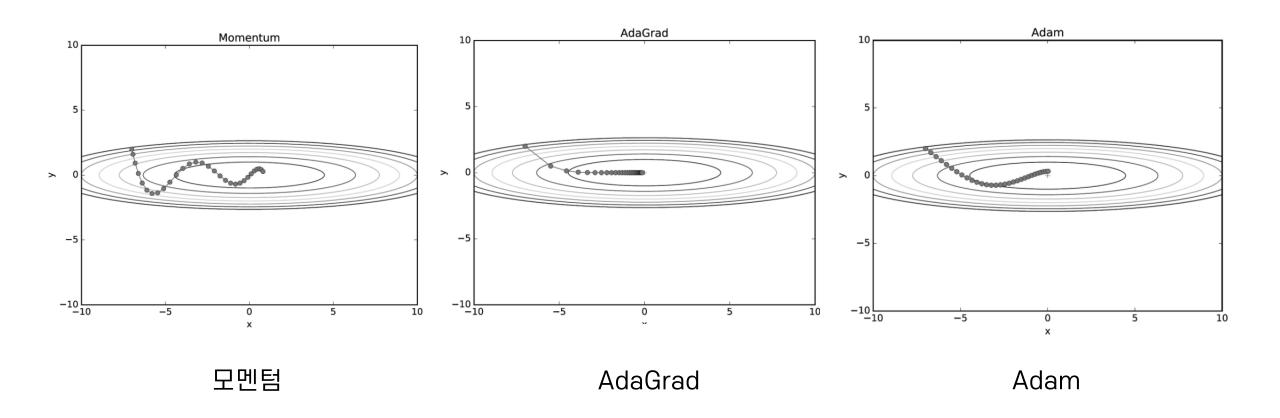


함수의 그래프



함수의 기울기

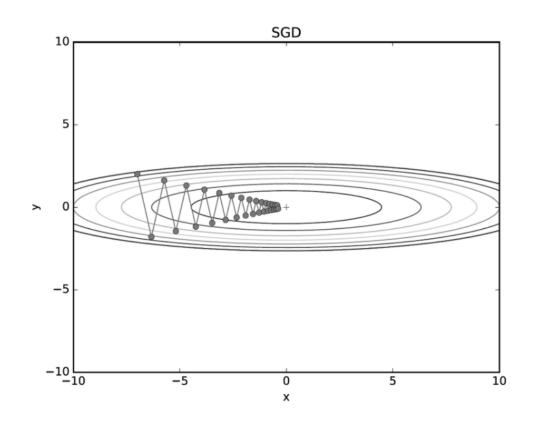
SGD의 단점을 개선한 방법

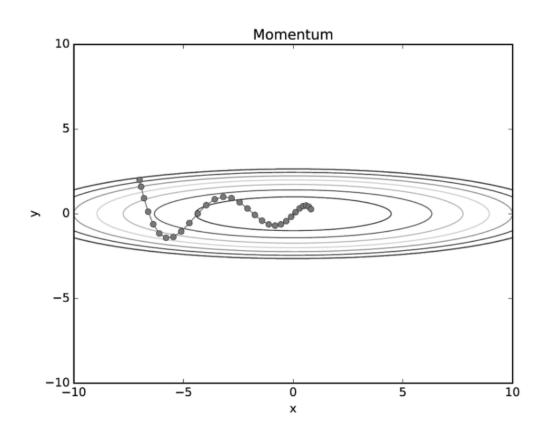


$$\mathbf{v} \leftarrow \alpha \mathbf{v} - \eta \, \frac{\partial L}{\partial \mathbf{W}}$$
$$\mathbf{W} \leftarrow \mathbf{W} + \mathbf{v}$$

모멘텀

확률적 경사 하강법에 속도의 개념의 더함





탐색 경로가 지그재그로 크게 변하는 SGD → 보다 빠르게 최적점으로 수렴하는 모멘텀

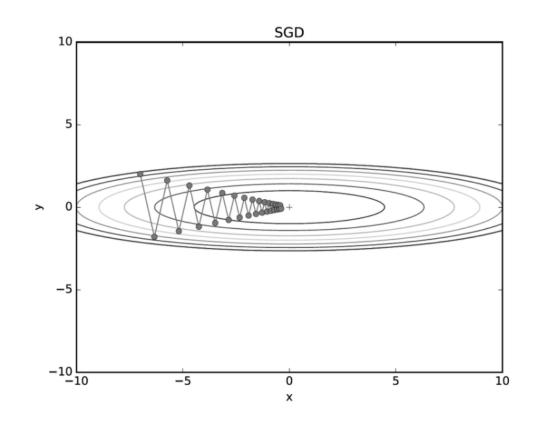
$$\mathbf{h} \leftarrow \mathbf{h} + \frac{\partial L}{\partial \mathbf{W}} \odot \frac{\partial L}{\partial \mathbf{W}}$$

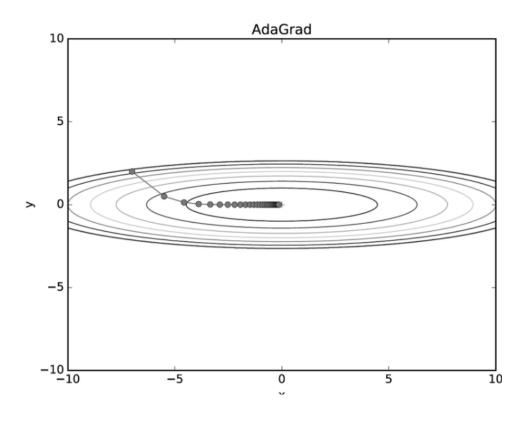
$$\mathbf{W} \leftarrow \mathbf{W} - \eta \, \frac{1}{\sqrt{\mathbf{h}}} \frac{\partial L}{\partial \mathbf{W}}$$

AdaGrad

학습을 진행하면서 학습률을 점차 줄이는 '학습률 감소 기법'을 적용.

개별 매개변수에 적응적으로 학습률을 조정하면서 학습 진행.

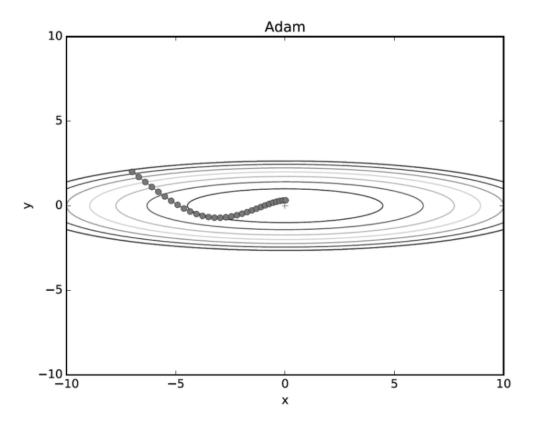


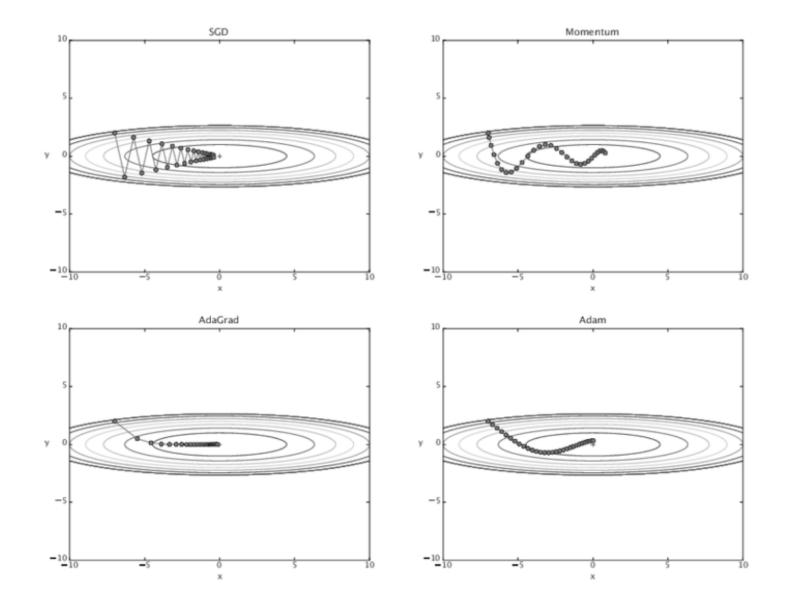


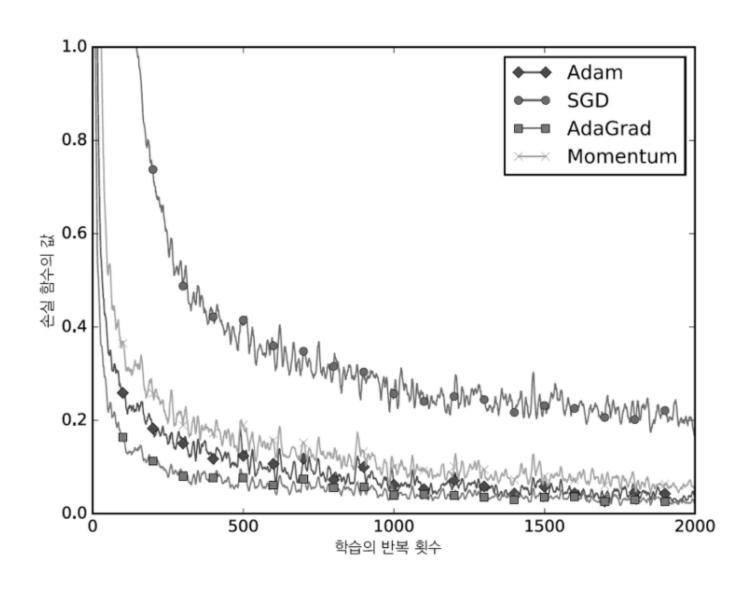
탐색 경로가 지그재그로 크게 변하는 SGD → 갱신 강도가 빠르게 약해지고 지그재그 움직임 감소

Adam

모멘텀 + AdaGrad







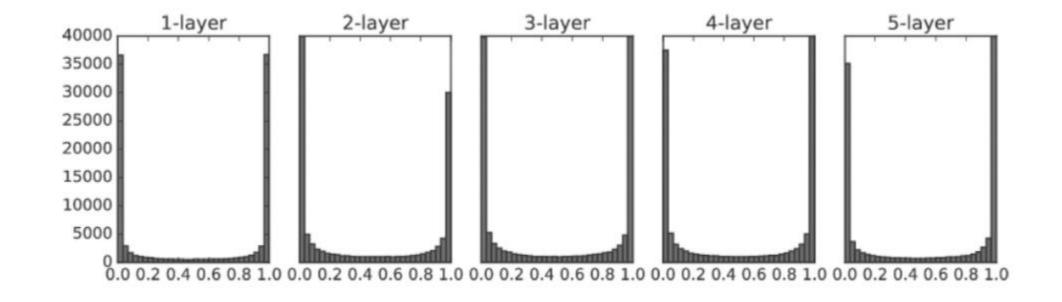
2. 가중치의 초깃값

가중치 초깃값을 0으로 하면?

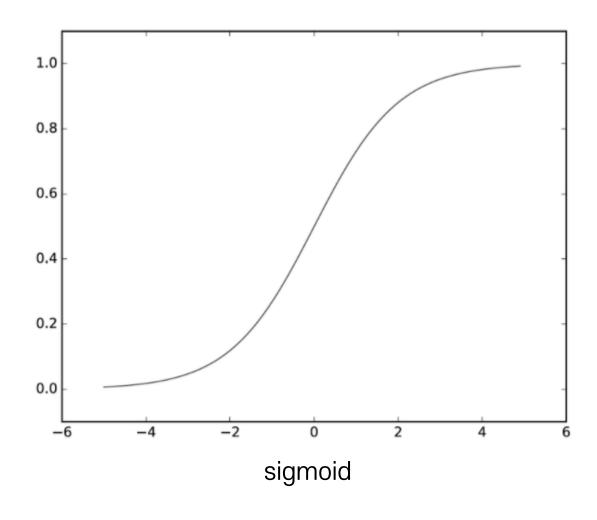
→ 학습이 올바르게 이루어지지 않는다.

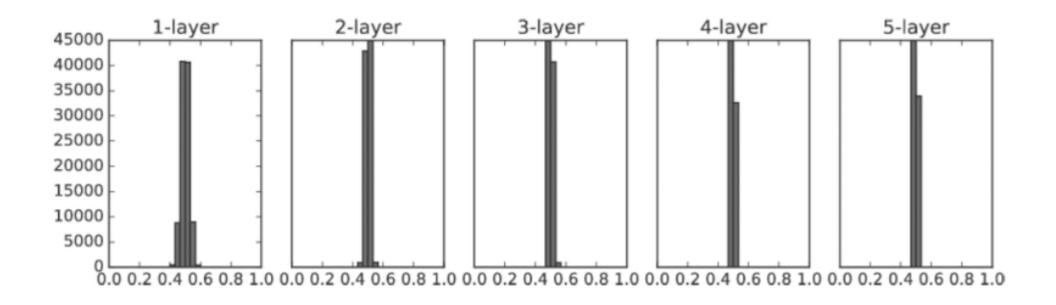
가중치를 균일하게 설정하면 오차역전파법에서 모든 가중치의 값이 똑같이 갱신되기 때문

⇒ 가중치의 초깃값은 무작위로 설정



가중치를 표준편차가 1인 정규분포로 초기화

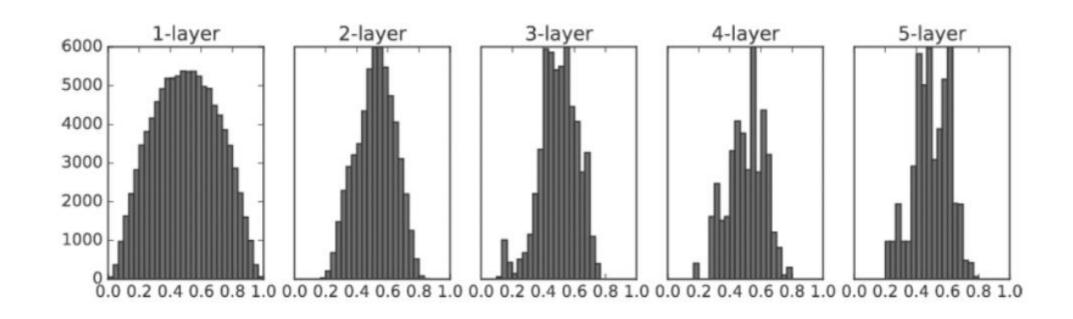




가중치를 표준편차가 0.01인 정규분포로 초기화

Xavier 초깃값

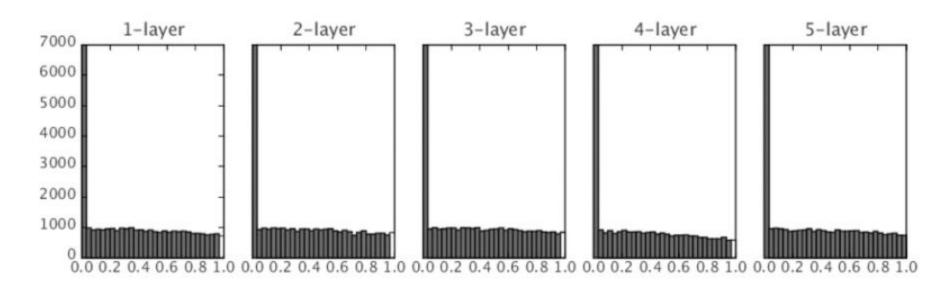
- 활성화 함수가 sigmoid, tanh함수일 때 사용
- 앞 계층의 노드 수가 n일 때 표준편차 $1/\sqrt{n}$ 인 가중치 분포



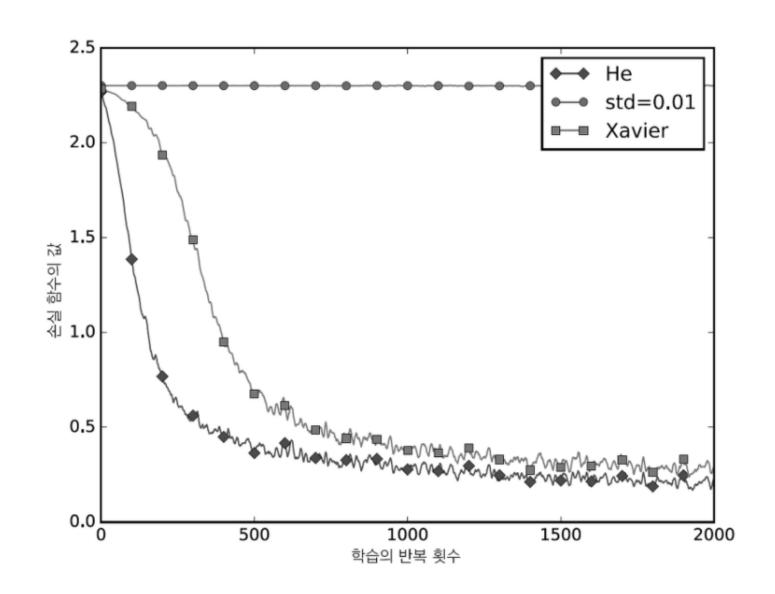
He 초깃값

- 활성화 함수가 ReLU일 때 사용

- 앞 계층의 노드 수가 n일 때 표준편차 $1/\sqrt{\frac{2}{n}}$ 인 가중치 분포



가중치의 초깃값



- MNIST 데이터셋

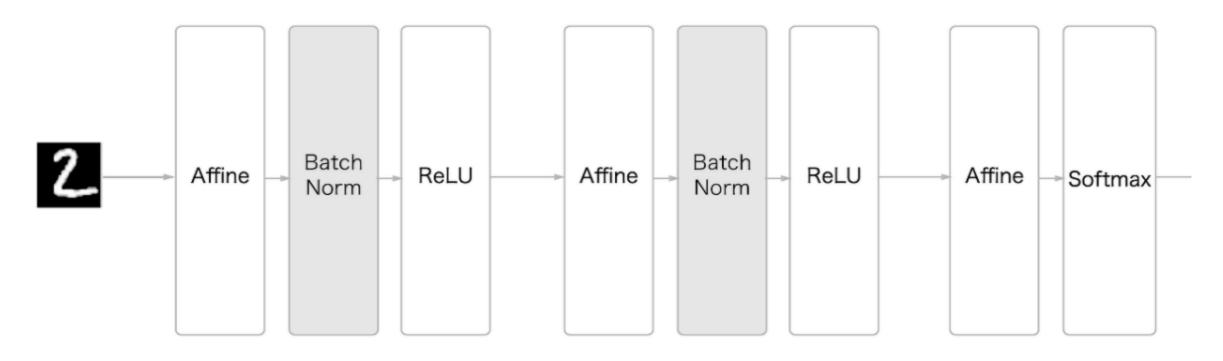
- 활성화 함수 : ReLU

3. 배치 정규화

$$egin{aligned} \mu_B &:= rac{1}{m} \sum_{i=1}^m x_i \ \sigma_B^2 &:= rac{1}{m} \sum_{i=1}^m (x_i - \mu_B)^2 \ x_i &:= rac{x_i - \mu_B}{\sqrt{\sigma_B^2 + \epsilon}} \end{aligned}$$

배치 정규화 (Batch Normalization) 란?

- 학습하는 과정을 전체적으로 안정화 시키는 방법
- 각 층이 활성화를 적당히 퍼뜨리도록 강제함



배치 정규화 계층을 신경망에 삽입한 모습

Normalize:

$$\widehat{x}^{(k)} = \frac{x^{(k)} - E[x^{(k)}]}{\sqrt{\text{Var}[x^{(k)}]}}$$

And then allow the network to squash the range if it wants to:

$$y^{(k)} = \gamma^{(k)} \widehat{x}^{(k)} + \beta^{(k)}$$

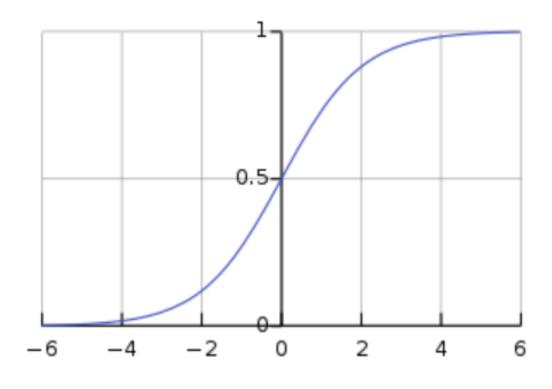
Note, the network can learn:

$$\gamma^{(k)} = \sqrt{\operatorname{Var}[x^{(k)}]}$$
$$\beta^{(k)} = \operatorname{E}[x^{(k)}]$$

to recover the identity mapping.

감마(scale)와 베타(shift) 조정이 가능하다.

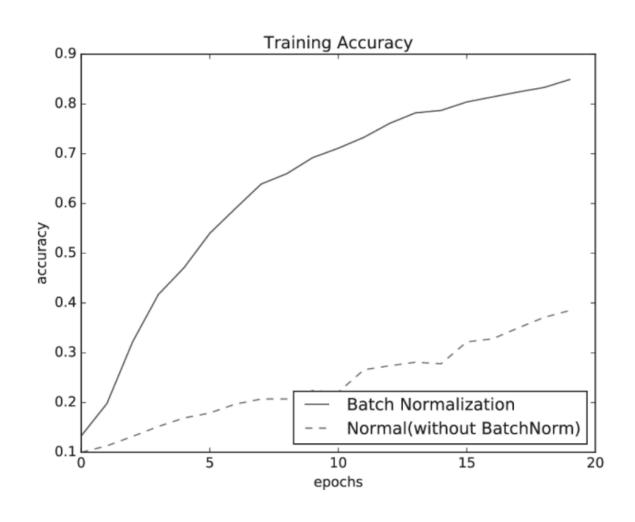
- → saturation 현상을 얼마나 일어나게 할 것인지 조절할 수 있음
- → 배치 정규화를 진행할 것인지, 안 할 것인지 결정 가능함.



Sigmoid 함수

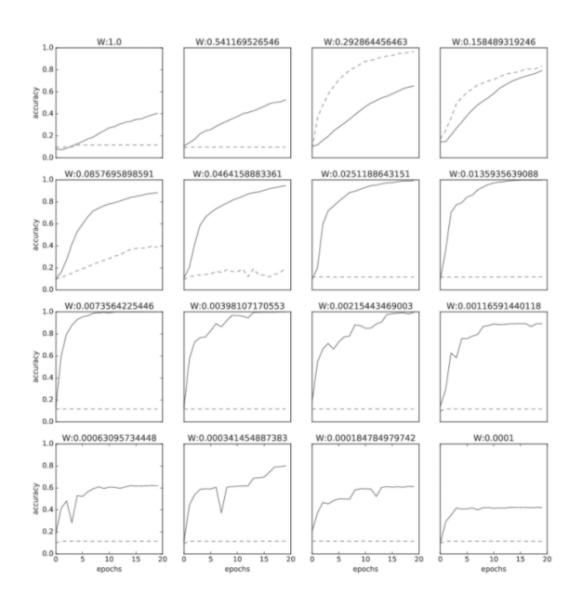
scale과 shift 사용 이유

- 비선형성을 잃는 함수의 비선형성을 유지
- saturation 현상의 조절



배치 정규화의 빠른 속도

- → 높은 학습률을 부여할 수 있음
- → 드롭아웃과 같은 규제를 적용하지 않아도 됨



가중치 초기값의 영향 감소

→ 원래 가중치 초기값을 계속해서 조절함

Batch Normalization

Input: Values of x over a mini-batch: $\mathcal{B} = \{x_{1...m}\}$;

Parameters to be learned: γ , β

Output: $\{y_i = BN_{\gamma,\beta}(x_i)\}$

$$\mu_{\mathcal{B}} \leftarrow \frac{1}{m} \sum_{i=1}^{m} x_i$$
 // mini-batch mean

$$\sigma_{\mathcal{B}}^2 \leftarrow \frac{1}{m} \sum_{i=1}^m (x_i - \mu_{\mathcal{B}})^2$$
 // mini-batch variance

$$\widehat{x}_i \leftarrow \frac{x_i - \mu_{\mathcal{B}}}{\sqrt{\sigma_{\mathcal{B}}^2 + \epsilon}}$$
 // normalize

$$y_i \leftarrow \gamma \hat{x}_i + \beta \equiv BN_{\gamma,\beta}(x_i)$$
 // scale and shift

summary

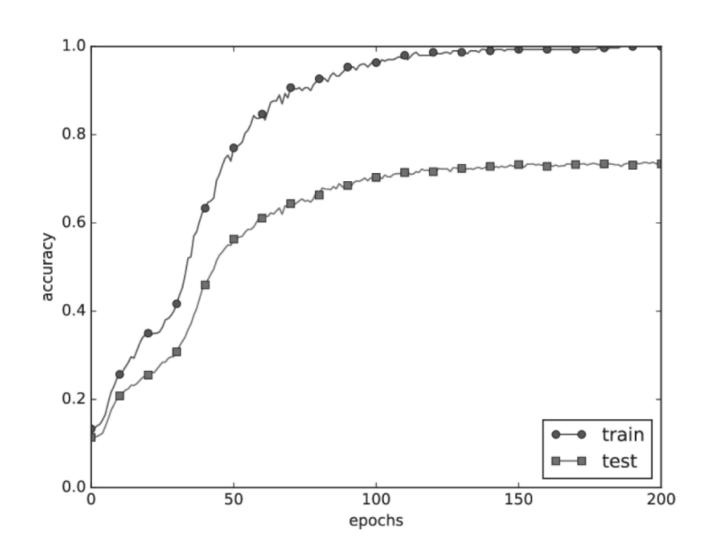
- 평균과 분산 계산
- 계산된 평균과 분산으로 정규화
- scale과 shift 지정

<장점>

- 학습 속도 개선
- 초기값에 크게 의존하지 않음
- 규제의 효과 → 오버피팅 억제
 (드롭아웃 등의 필요성 감소)

4. 바른 학습을 위해

바른 학습을 위해



오버피팅이란?

- 과적합
- 학습 데이터에 너무 과하게 학습이 됨
- 다른 데이터에 대한 정확도 감소

오버피팅이 일어나는 경우

- 매개변수가 많고 표현력이 높은 모델
- 훈련 데이터가 적음

→ 오버피팅 억제는 매우 중요. 아직 보지 못한 데이터를 바르게 식별하는 모델이 좋다.

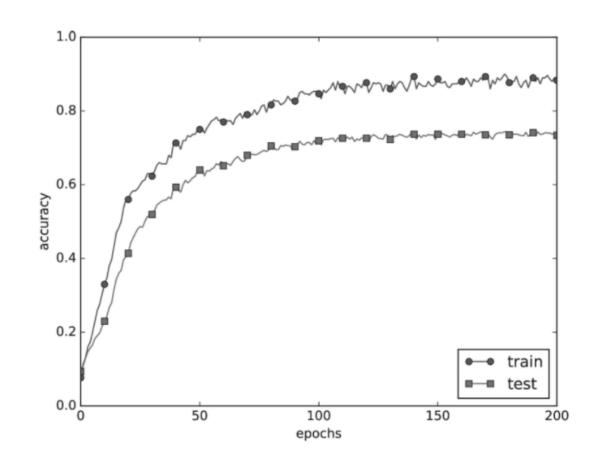
바른 학습을 위해

오버피팅을 억제하는 방법

1. 가중치 감소

: 큰 가중치에 대해서는 그에 상응하는 큰 페널티를 부과

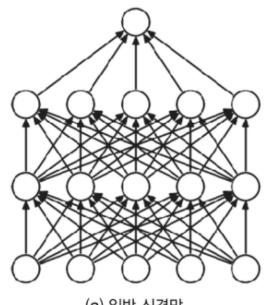
→ 가중치 감소에는 규제 사용



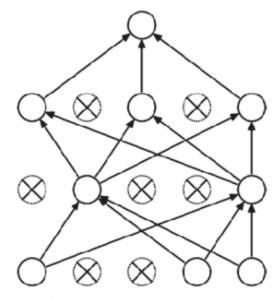
오버피팅을 억제하는 방법

2. 드롭아웃

: 뉴런을 임의로 삭제하면서 학습



(a) 일반 신경망



(b) 드롭아웃을 적용한 신경망

5. 적절한 하이퍼파라미터 값 찾기

• 하이퍼마라미터: 뉴런 수, 배치 크기, 학습률 등

• 훈련 데이터: 매개변수 학습

• 검증 데이터: 하이퍼파라미터 성능 평가

• 시험 데이터: 신경망의 범용 성능 평가

② 하이퍼파라미터 최적화

하이퍼파라미터의 최적값이 존재하는 범위를 조금씩 줄여나감

Double check that the loss is reasonable:

```
def init_two_layer_model(input_size, hidden_size, output_size):
    # initialize a model
    model = {}
    model['W1'] = 0.0001 * np.random.randn(input_size, hidden_size)
    model['b1'] = np.zeros(hidden_size)
    model['W2'] = 0.0001 * np.random.randn(hidden_size, output_size)
    model['b2'] = np.zeros(output_size)
    return model
```

```
model = init_two_layer_model(32*32*3, 50, 10) # input size, hidden size, number of classes loss, grad = two_layer_net(X_train, model, y_train 0.0) disable regularization

2.30261216167 loss ~2.3.

"correct " for returns the loss and the gradient for all parameters tanford
```

Lets try to train now...

Tip: Make sure that you can overfit very small portion of the training data

The above code:

- take the first 20 examples from CIFAR-10
- turn off regularization (reg = 0.0)
- use simple vanilla 'sgd'

Chantand

Lets try to train now...

Tip: Make sure that you can overfit very small portion of the training data

Very small loss, train accuracy 1.00, nice!

```
model = init two layer model(32*32*3, 50, 10) # input size, hidden size, number of classes
trainer = ClassifierTrainer()
X tiny = X train[:20] # take 20 examples
y tiny = y train[:20]
best model, stats = trainer.train(X tiny, y tiny, X tiny, y tiny,
                                   model, two layer net,
                                   num epochs=200, reg=0.0,
                                   update='sqd', learning rate decay=1,
                                   sample batches = False,
                                   learning rate=le-3, verbose=True)
Finished epoch 1 / 200: cost 2.302603, train: 0.400000, val 0.400000, lr 1.0000000e-03
Finished epoch 2 / 200: cost 2.302258, train: 0.450000, val 0.450000, lr 1.000000e-03
Finished epoch 3 / 200: cost 2.301849, train: 0.600000, val 0.600000, lr 1.000000e-03
Finished epoch 4 / 200: cost 2.301196, train: 0.650000, val 0.650000, lr 1.000000e-03
Finished epoch 5 / 200: cost 2.300044, train: 0.650000, val 0.650000, lr 1.000000e-03
Finished epoch 6 / 200: cost 2.297864, train: 0.550000, val 0.550000, lr 1.000000e-03
Finished epoch 7 / 200: cost 2.293595, train: 0.600000, val 0.600000, lr 1.000000e-03
Finished epoch 8 / 200: cost 2.285096, train: 0.550000, val 0.550000, lr 1.000000e-03
Finished epoch 9 / 200: cost 2.268094, train: 0.550000, val 0.550000, lr 1.000000e-03
Finished epoch 10 / 200: cost 2.234787, train: 0.500000, val 0.500000, lr 1.0000
Finished epoch 11 / 200: cost 2.173187, train: 0.500000, val 0.500000, lr 1.000000e-03
Finished epoch 12 / 200: cost 2.076862, train: 0.500000, val 0.500000, lr 1.000000e-03
Finished epoch 13 / 200: cost 1.974090, train: 0.400000, val 0.400000, lr 1.0000
Finished epoch 14 / 200: cost 1.895885, train: 0.400000, val 0.400000, lr 1.000000e-03
Finished epoch 15 / 200: cost 1.820876, train: 0.450000, val 0.450000, lr 1.000000e-03
Finished epoch 16 / 200: cost 1.737430, train: 0.450000, val 0.450000, lr 1.0000
Finished epoch 17 / 200: cost 1.642356, train: 0.500000, val 0.500000, lr 1.000000e-03
Finished epoch 18 / 200: cost 1.535239, train: 0.600000, val 0.600000, lr 1.0000
      Finished epoch 196 / 200: cost 0.002674, train: 1.000000, val 1.000000,
      Finished epoch 197 / 200: cost 0.002655, train: 1.000000, val 1.000000, lr 1.00
      Finished epoch 198 / 200: cost 0.002635, train: 1.000000, val 1.000000, lr 1.000000e-03
      Finished epoch 199 / 200: cost 0.002617, train: 1.000000, val 1.000000, lr 1.9000000 83
      Finished epoch 200 / 200: cost 0.002597, train: 1.000000, val 1.00 0.00
      finished optimization, best validation accuracy: 1.0000
```

Lets try to train now...

Start with small regularization and find learning rate that makes the loss go down.

loss not going down: learning rate too low loss exploding: learning rate too high

```
model = init two layer model(32*32*3, 50, 10) # input size, hidden size, number of classes
trainer = ClassifierTrainer()
best model, stats = trainer.train(X train, y train, X val, y val,
                                  model, two layer net,
                                  num epochs=10, reg=0.000001,
                                  update='sgd', learning rate decay=1,
                                  sample batches = True,
                                  learning rate=le6, verbose=True)
/home/karpathy/cs231n/code/cs231n/classifiers/neural net.py:50: RuntimeWarning: divide by zero en
countered in log
 data loss = -np.sum(np.log(probs[range(N), y])) / N
/home/karpathy/cs231n/code/cs231n/classifiers/neural net.py:48: RuntimeWarning: invalid value enc
ountered in subtract
 probs = np.exp(scores - np.max(scores, axis=1, keepdims=True))
Finished epoch 1 / 10: cost nan, train: 0.091000, val 0.087000, lr 1.0000000+06
Finished epoch 2 / 10: cost nan, train: 0.095000, val 0.087000, lr 1.000000e+06
Finished epoch 3 / 10: cost nan, train: 0.100000, val 0.087000, lr 1.0000000+06
```

cost: NaN almost always means high learning rate...

Stanford

Lets try to train now...

Start with small regularization and find learning rate that makes the loss go down.

loss not going down: learning rate too low loss exploding: learning rate too high

3e-3 is still too high. Cost explodes....

=> Rough range for learning rate we should be cross-validating is somewhere [1e-3 ... 1e-5]

Stanford

For example: run coarse search for 5 epochs

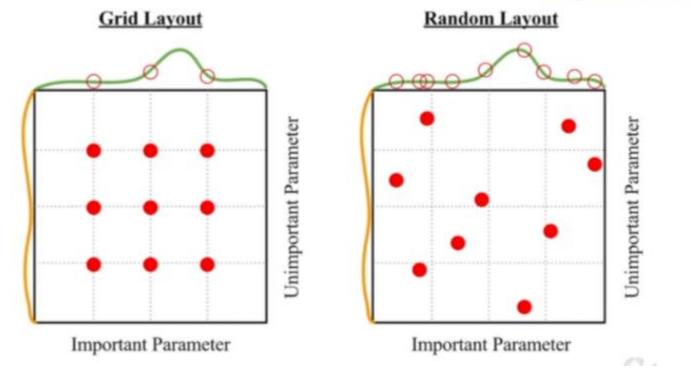
```
max count = 100
                                                           note it's best to optimize
   for count in xrange(max count):
         reg = 10**uniform(-5, 5)
         lr = 10**uniform(-3, -6)
                                                           in log space!
         trainer = ClassifierTrainer()
         model = init two layer model(32*32*3, 50, 10) # input size, hidden size, number of classes
         trainer = ClassifierTrainer()
         best model local, stats = trainer.train(X train, y train, X val, y val,
                                       model, two layer net,
                                       num epochs=5, reg=reg,
                                       update='momentum', learning rate decay=0.9,
                                       sample batches = True, batch size = 100,
                                       learning rate=lr, verbose=False)
            val acc: 0.412000, lr: 1.405206e-04, reg: 4.793564e-01, (1 / 100)
            val acc: 0.214000, lr: 7.231888e-06, reg: 2.321281e-04, (2 /
            val acc: 0.208000, lr: 2.119571e-06, reg: 8.011857e+01, (3 / 100
            val acc: 0.196000, lr: 1.551131e-05, req: 4.374936e-05, (4 /
            val acc: 0.079000, lr: 1.753300e-05, reg: 1.200424e+03, (5 / 100
            val acc: 0.223000, lr: 4.215128e-05, reg: 4.196174e+01, (6 / 100
            val acc: 0.441000, lr: 1.750259e-04, reg: 2.110807e-04, (7 / 100)
            val acc: 0.241000, lr: 6.749231e-05, reg: 4.226413e+01, (8 /
nice
            val acc: 0.482000, lr: 4.296863e-04, reg: 6.642555e-01, (9 / 100)
            val acc: 0.079000, lr: 5.401602e-06, reg: 1.599828e+04, (10 / 100)
            val acc: 0.154000, lr: 1.618508e-06, reg: 4.925252e-01, (11 / 100)
```

Now run finer search...

```
max count = 100
                                              adjust range
                                                                              max count = 100
for count in xrange(max count):
                                                                              for count in xrange(max count):
      reg = 10 ** uniform(-5, 5)
                                                                                    reg = 10**uniform(-4, 0)
      lr = 10**uniform(-3, -6)
                                                                                    lr = 10^{**}uniform(-3, -4)
                    val acc: 0.527000, lr: 5.340517e-04, reg: 4.097824e-01, (0 / 100)
                    val acc: 0.492000, lr: 2.279484e-04, reg: 9.991345e-04, (1 / 100)
                    val acc: 0.512000, lr: 8.680827e-04, reg: 1.349727e-02, (2 / 100)
                    val acc: 0.461000, lr: 1.028377e-04, reg: 1.220193e-02, (3 / 100)
                    val acc: 0.460000, lr: 1.113730e-04, reg: 5.244309e-02, (4 / 100)
                                                                                              53% - relatively good
                    val acc: 0.498000, lr: 9.477776e-04, reg: 2.001293e-03, (5 / 100)
                                                                                              for a 2-layer neural net
                    val acc: 0.469000, lr: 1.484369e-04, reg: 4.328313e-01, (6 / 100)
                    val acc: 0.522000, lr: 5.586261e-04, reg: 2.312685e-04, (7 / 100)
                                                                                              with 50 hidden neurons.
                    val acc: 0.530000, lr: 5.808183e-04, reg: 8.259964e-02, (8 / 100)
                    val acc: 0.489000, lr: 1.979168e-04, reg: 1.010889e-04, (9 / 100)
                    val acc: 0.490000, lr: 2.036031e-04, reg: 2.406271e-03, (10 / 100)
                                                                                              But this best
                    val acc: 0.475000, lr: 2.021162e-04, reg: 2.287807e-01, (11 / 100)
                    val acc: 0.460000, lr: 1.135527e-04, req: 3.905040e-02, (12 / 100)
                                                                                              cross-validation result is
                    val acc: 0.515000, lr: 6.947668e-04, reg: 1.562808e-02, (13 / 100)
                    val acc: 0.531000, lr: 9.471549e-04, reg: 1.433895e-03, (14 / 100)
                                                                                              worrying. Why?
                    val acc: 0.509000, lr: 3.140888e-04, reg: 2.857518e-01, (15 / 100
                    val acc: 0.514000, lr: 6.438349e-04, reg: 3.033781e-01, (16 / 100)
                    val acc: 0.502000, lr: 3.921784e-04, reg: 2.707126e-04, (17 / 100)
                    val acc: 0.509000, lr: 9.752279e-04, reg: 2.850865e-03, (18 / 100)
                    val acc: 0.500000, lr: 2.412048e-04, reg: 4.997821e-04, (19 / 100)
                                                                                                  Stanford
                    val acc: 0.466000, lr: 1.319314e-04, reg: 1.189915e-02, (20 / 100)
                    val acc: 0.516000, lr: 8.039527e-04, reg: 1.528291e-02, (21 / 100)
```

Random Search vs. Grid Search

Random Search for Hyper-Parameter Optimization Bergstra and Bengio, 2012



The End