```
cur_{\overline{t}}
\begin{array}{l} \frac{\underline{\underline{b}}}{\langle m,Q,r,P,\lambda,R,\Delta,\delta\rangle} \\ Q,r,P,\lambda,R,\Delta \\ \delta \\ state \\ pred-\\ \vdots \\ cate \\ P \\ \eta \\ a \vDash \end{array}
                \begin{array}{l} q \models \\ \eta \\ \eta \\ \eta \\ ini_{\overline{l}} \\ \overline{q_0} \\ \overline{q_1} \\ \dots \\ 0 \\ \overline{q_k} \\ \lambda \geq \\ \rho(h) \leq \\ \rho(h) \leq \\ \rho(h) \\ \rho(h
```