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Outline

- Introduction and motivation
- Stochastic diffusion models
- Influence maximization
- Algorithms
- Conclusion

Social influence

 Wikipedia definition: Social influence occurs when one's opinions, emotions, or behaviors are affected by others, intentionally or unintentionally.

Booming of online social networks

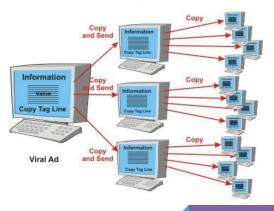


Hotmail: online viral marketing story

- Hotmail's viral climbed to the top spot (90s): 8 million users in 18 months
- Boosted brand awareness
- Far more effective than conventional advertising by rivals
 - and far cheaper

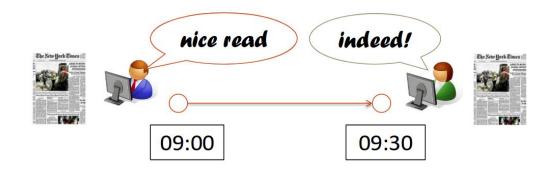
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Stochastic Diffusion Models

Influence propagation



People are **connected** and perform **actions**



comment, link, rate, like, retweet, post a message, photo, or video, etc.

Terminologies

- Directed graph G = (V, E)
 - Node v ∈ V represents an individual
 - Edge (u, v) ∈ E represents the influence relationship
- Discrete time t: 0, 1, 2, ...
- State of nodes: active or inactive
- S_t: set of active nodes at time t
 - So, seed set, initial nodes selected to start the diffusion

Stochastic diffusion models

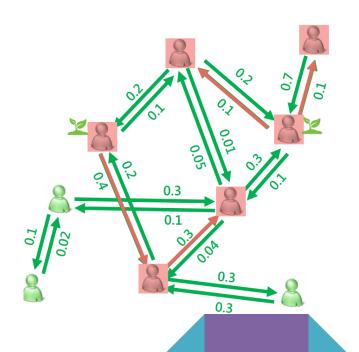
Definition: A stochastic diffusion model (with discrete time steps) for a social graph G = (V, E) specifies the randomized process of generating active sets s_t for all t > 0 given the initial seed set S_0 .

Progressive models: for all t > 0, $S_{t-1} \subseteq S_t$

- Once activated, always activated, e.g. once bought a product, cannot undo it.
- Influence spread $\sigma(S)$: expected number of activated nodes when the diffusion process starting from the seed set S ends

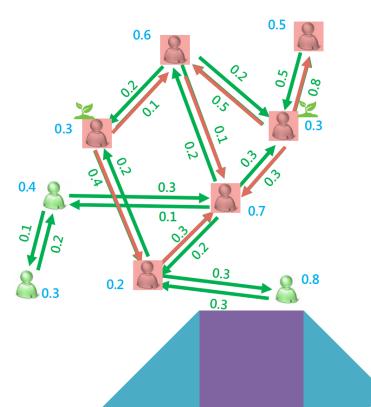
Independent cascade model

- Each edge (u, v) has a influence probability p(u, v)
- Initially seed nodes in S₀ are activated
- At each time step t, each node u activated at step t-1 activates its neighbor v independently with probability p(u, v)



Linear threshold model

- Each edge (u, v) has an influence weight w(u, v):
 - o if $(u, v) \notin E$, w(u, v)=0
 - $\Sigma_u w(u, v) \leq 1$
- Each node v selects a threshold θ_v ∈ [0,1] uniformly at random
- Initially seed nodes in S₀ are activated
- At each step, node v checks if the weighted sum of its activated in-neighbors is greater than or equal to its threshold θ_v, if so v is activated



Interpretation of IC and LT models

- IC model reflects simple contagion, e.g. information, virus
- LT model reflects complex contagion, e.g. product adoption, innovations (activation needs social affirmation from multiple sources [1])

General threshold model

Each node v has a threshold function

$$f_v: 2^V \to [0,1]$$

- Each node v selects a threshold $\theta_v \in [0, 1]$ uniformly at random
- If the set of active nodes at the end of step t-1 is S, and f_v(S) ≥ θ_v, v is activated at step t
- Reward function r(A(S)): if A(S) is the final set of active nodes given seed set
 S, r(A(S)) is the reward from this set
- Generalized influence spread:

$$\sigma(S) = E[r(A(S))]$$

Submodularity in the general threshold model

- Properties: submodularity and monotonicity
- Theorem
 - In the general threshold model,
 - o if for every $v \in V$, f is monotone and submodular with $f(\emptyset)=0$
 - o and the reward function r is monotone and submodular
 - \circ then the general influence spread funnction σ is monotone and submodular

Influence Maximization

Problem formulation

- Given a social network, a diffusion model with given parameters, and a number k, find a seed set S of at most k nodes such that the influence spread of S is maximized.
- May be further generalized:
 - Instead of k, given a budget constraint and each node has a cost of being selected as a seed
 - Instead of maximizing influence spread, maximizing a (submodular) function of the set of activated nodes.

Example



Hardness of influence maximization

- Influence maximization under both IC and LT models are NP hard
 - o IC model: reduced from k-max cover problem
 - LT model: reduced from vertex cover problem
- Need approximation algorithms

- Influence Spread
 - Given a seed set S, the influence spread of S means that
 - the expected number of influenced users after the propagation terminates if the users in S were selected as seed users
 - *f(S)*
- Marginal gain
 - The influence from users has overlap
 - Some of the users influenced by user u may be the same as the users influenced by the seed set S, where $u \notin S$
 - The Marginal gain of a user u means that
 - If user u was selected into the seed set, how much extra influence spread it would contribute
 - $\Delta(u|S) = f(S \cup \{u\}) f(S)$

Iteratively selects a node that provides the maximum marginal gain in each round

```
Algorithm 1 Greedy(k, f)

1: initialize S = \emptyset

2: for i = 1 to k do

3: select u = \arg\max_{w \in V \setminus S} (f(S \cup \{w\}) - f(S))

4: S = S \cup \{u\} marginal gain

6: output S
```

Submodular

$$\circ f(S_j \cup \{u\}) - f(S_j) \le f(S_i \cup \{u\}) - f(S_i) \text{ where } S_i \subseteq S_j$$

Monotone

$$\circ \quad f(S_i) < f(S_j)$$

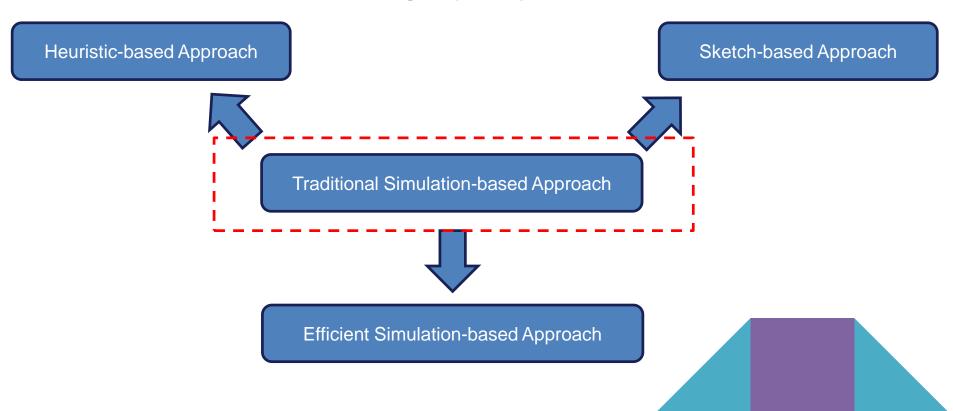
 The greedy-based approach solves the influence maximization problem with an approximation ratio of 1 – 1/e.[2]

How to estimate the influence spread?

Overview

Heuristic-based Approach Sketch-based Approach Traditional Simulation-based Approach Efficient Simulation-based Approach

Overview



Simulation-based approach

- The approach utilizes Monte Carlo(MC) simulations for estimating influence spread.
 - Starts from the seed set S
 - Simulates the activation process wrt. the corresponding diffusion model
 - Outputs the number of activated users

Algorithm 1 General Greedy (G, k)

```
1: initialize S = \emptyset and R = 20000

2: for i = 1 to k do

3: for each vertex v \in V \setminus S do

4: s_v = 0.

5: for i = 1 to R do

6: s_v += |RanCas(S \cup \{v\})|

7: end for

8: s_v = s_v/R

9: end for

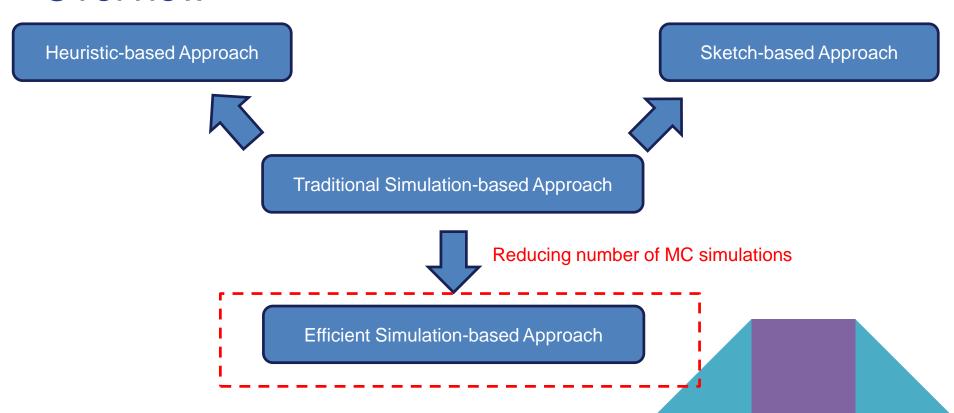
10: S = S \cup \{\arg\max_{v \in V \setminus S} \{s_v\}\}

11: end for

12: output S.
```

Time complexity: O(knRm)

Overview



```
Algorithm 1 General Greedy (G, k)
 1: initialize S = \emptyset and R = 20000
 2: for i = 1 to k do
     for each vertex v \in V \setminus S do
                                                                            Time complexity: O(knRm)
4:
         s_v = 0.
      for i=1 to R do
    s_v += |RanCas(S \cup \{v\})|
6:
    end for
                                                     Update the marginal gain of all unselected nodes
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                                                                                      No!!!
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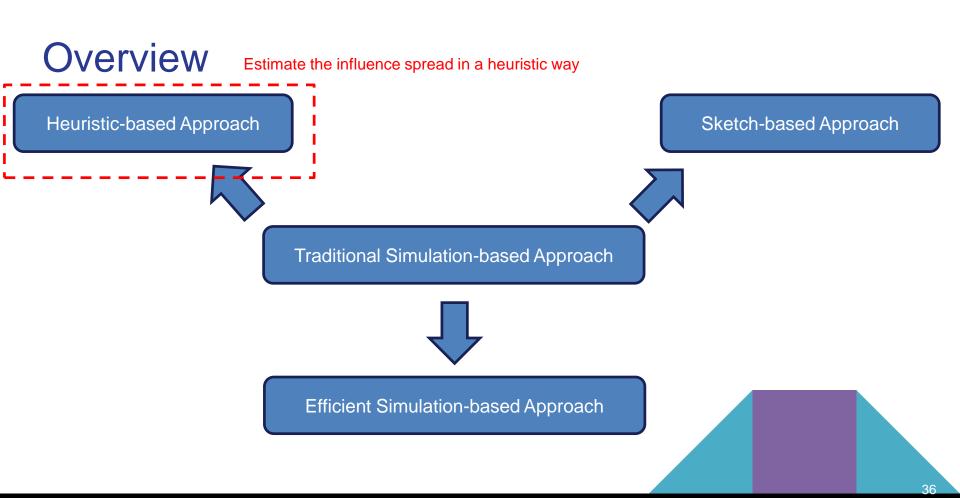
 CELF[3] estimates an upper bound of the marginal gain to avoid updating the marginal gain of all nodes

- Submodularity
 - $f(S_j \cup \{u\}) f(S_j) \le f(S_i \cup \{u\}) f(S_i)$ where $S_i \subseteq S_j$
 - $\Delta(u|S_i) = f(S_i \cup \{u\}) f(S_i)$ is an upper bound for any $\Delta(u|S_j)$ where $S_i \subseteq S_j$
- If the upper bound of node u is less than the updated marginal gain of node v,
 - the updated marginal gain of u is less than v's
 - no need to update the marginal gain of u

- Updates the marginal gain of nodes in descending order according to their upper bound
- Early terminates whenever the upper bound of a not updated node is less than the marginal gain of the updated node

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Enables an up to 700 times improvement compared with the traditional algorithm.



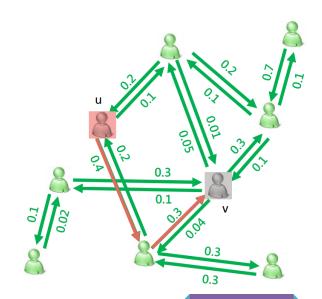
Heuristic approaches

- Exact influence computation is NP hard, for both IC and LT models -computation bottleneck [4][5]
- Design new heuristics
 - MIA for general IC model [4]
 - LDAG for LT model [5]
 - IRIE for IC model [6]

^[5] Chen, Wei, Yifei Yuan, and Li Zhang. Scalable influence maximization in social networks under the linear threshold model. ICDM 2010

Maximum Influence Arborescence (MIA)

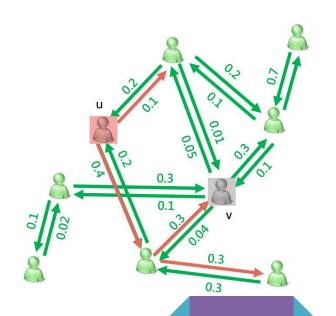
- For any pair of nodes u and v, find the maximum influence path (MIP) from u to v
- Ignore MIPs with too small probability (< parameter θ)



MIA (cont'd)

Local influence regions

- for every node v, all MIPs to v form its maximum influence in-arborescence (MIIA)
- for every node u, all MIPs from u form its maximum influence out-arborescence (MIOA)
- computing MIAs and the influence through MIAs is fast



MIA (cont'd)

 Recursive computation of activation probability ap(u) of a node u in its inarborescence, given a seed set S

```
Algorithm 2 ap(u, S, MIIA(v, \theta))

1: if u \in S then

2: ap(u) = 1

3: else if Ch(u) = \emptyset then

4: ap(u) = 0

5: else

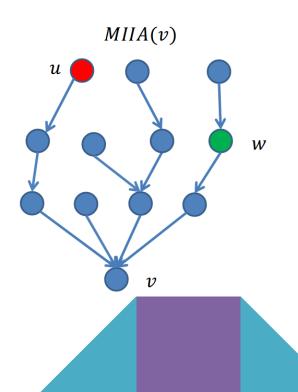
6: ap(u) = 1 - \prod_{w \in Ch(u)} (1 - ap(w) \cdot pp(w, u))
```

Can be us 7: end if enough

eds, but not efficient

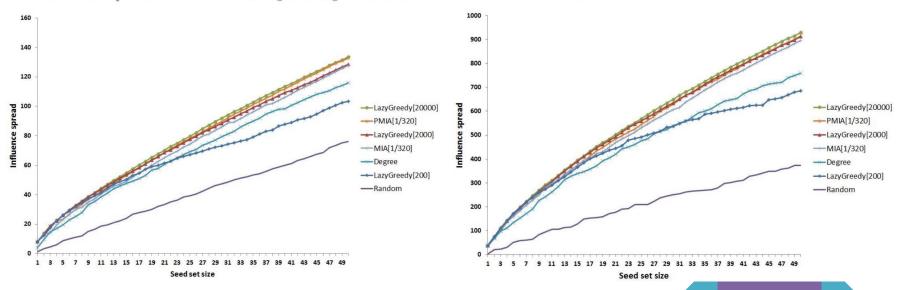
MIA (cont'd)

- u is the new seed in MIIA(v)
- Naive update: for each candidate W, redo
 the computation in the previous page to
 compute w's incremental influence to v
 O(|MIIA(v)|)
- Fast update: based on linear relationship of activation probabilities between any node w and root v, update incremental influence of all w's to v in two passes
 - O(|MIIA(v)|)

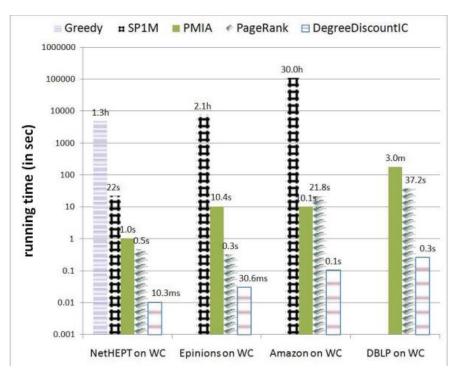


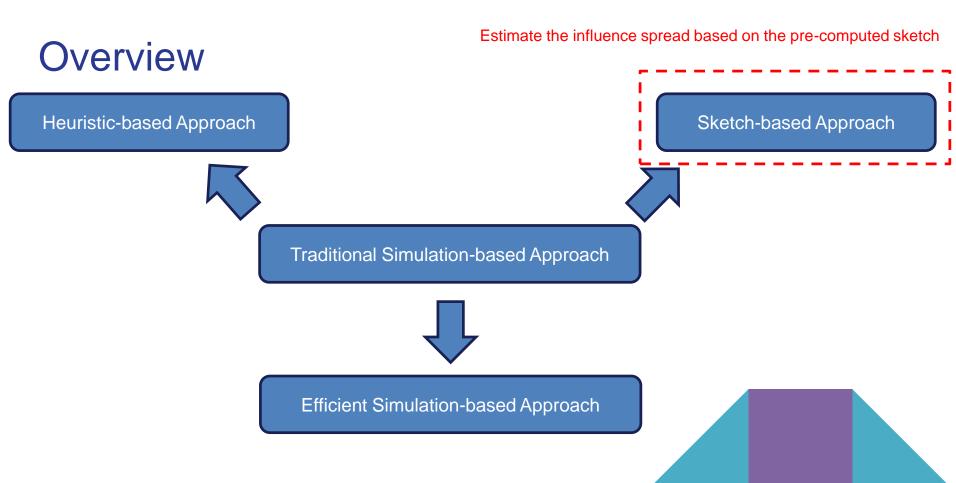
Experiment result

Influence spread in IC-UP[0.01] model Influence spread in IC-WC model



Experiment result





Sketch-based Approach

- Let $v \in V$ be a node in G, and g be a graph obtained by removing each edge e in G with 1 p(e) probability
 - The reverse reachable(RR) set
 - RR(v): contains all nodes in g that can reach v
 - The Radom RR set
 - For RR(v), v is randomly picked from V

Sketch-based Approach

• If a seed set S^* covers the maximal number of the RR set, S^* is likely to be the optimal seed set.

```
Algorithm 2: RR-SKETCH (G, k, \theta) [100]

Input : G = (V, E): A social graph k: A number; \theta: Number of RR Sets.

Output: S: Seed Set.

1 \mathcal{R} \leftarrow \emptyset, S \leftarrow \emptyset

2 Generate \theta random RR sets and insert them into \mathcal{R}

3 for i = 1, \dots, k do

4 | Pick node v_i that covers the most RR sets in \mathcal{R}

5 | Add v_i into S

6 | Remove from \mathcal{R} all RR sets that are covered by v_i

7 return S
```

Conclusion Pros: Efficient Cons: Without theoretical guarantees

Heuristic-based Approach

Pros:

- Efficient
- Theoretical guarantees

Cons: Not general

Sketch-based Approach

Traditional Simulation-based Approach



Efficient Simulation-based Approach

Pros:

- General
- Theoretical guarantees

Cons: Inefficient

Future directions(I)

- Context-aware influence maximization.
 - Topic-aware influence maximization[9]
 - Location-aware influence maximization[10][11]

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[11] X. Wang, Y. Zhang, W. Zhang, and X. Lin, "Distance-aware influence maximization in geo-social network," in ICDE, 2016

Future directions(II)

- Influence probability inference
 - o Influence probability between users is fundamental for influence spread estimation[12][13]

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Thanks!