

CONTENT



組員介紹



王予欣 資料處理 視覺化



王昱 組長 系統管理



王嘉宏 系統管理 資料管理及處理



曾昱璇 網路爬蟲 視覺化



顧芠菱 資料處理 機器學習



楊雅婷 前端架構建置管理 視覺化

專利分析

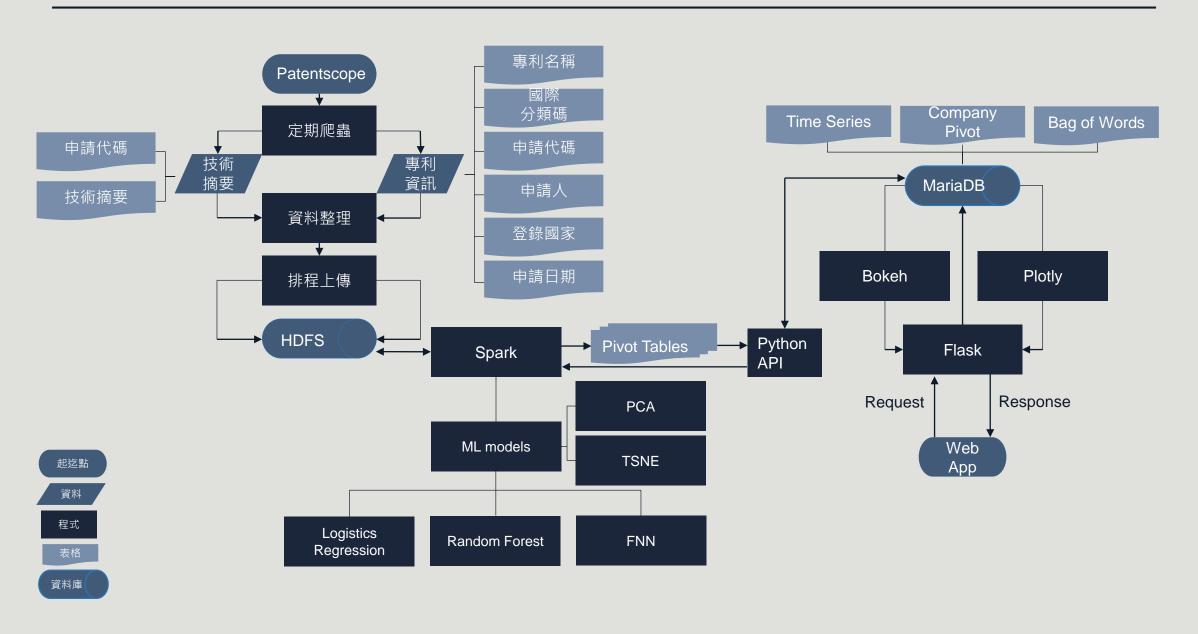
- 專利文件具有商業價值及戰略意義
- WIPO收錄超過9000萬筆專利文件,需要巨量資料技術進行分析
- 專利分類由專利官審批,長期為人詬病

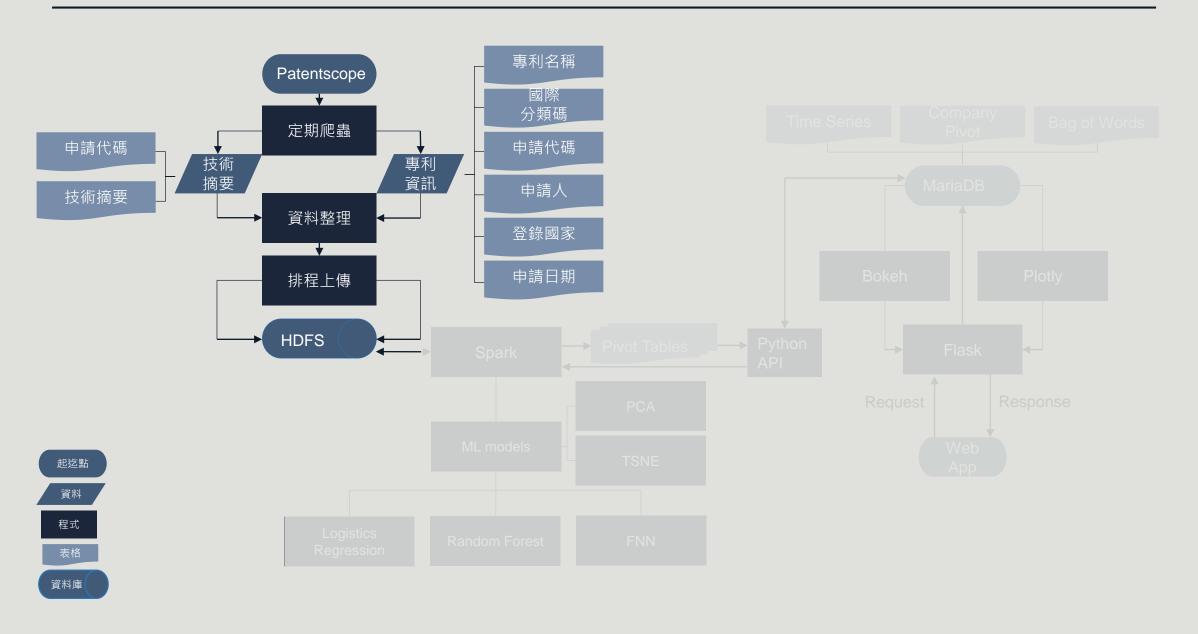


專案目標

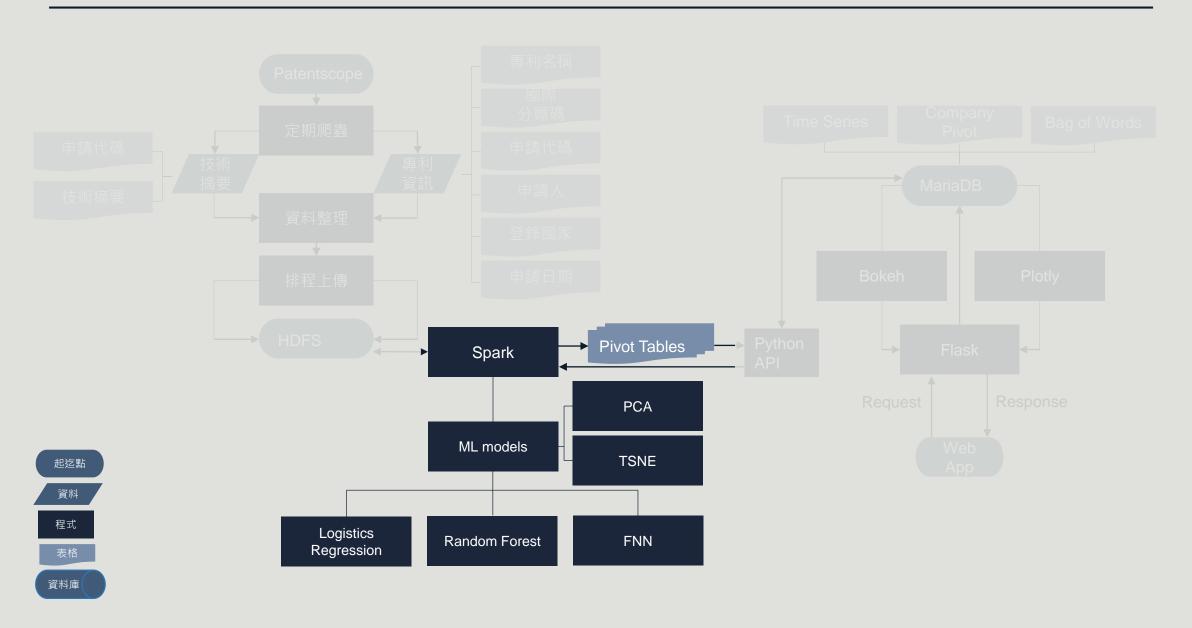
- 建立專利資料庫
- 繪製圖形互動式專利地圖
 - 尋找專利技術破口
 - 協助企業研發策略布局
- 以AI文字探勘技術分類IPC
- 建立易於操作及可視化之儀表板
 - 可了解產業趨勢
 - 分析公司競合關係
- 建立智慧專利分類落點分析



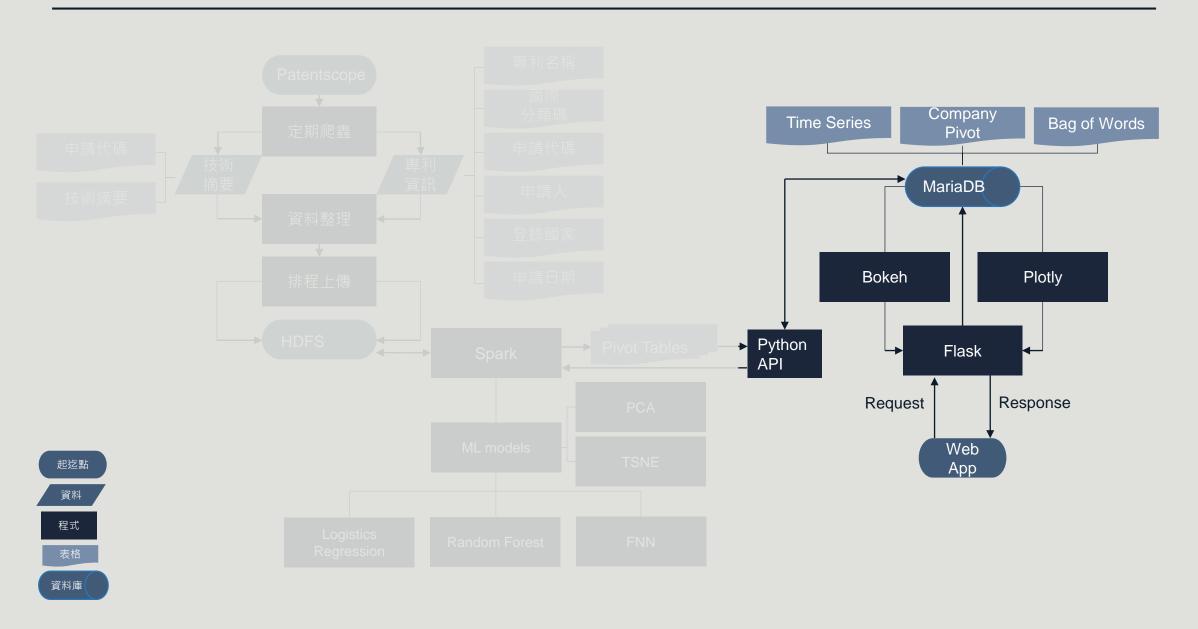




組員介紹主題介紹主義統架構工工工資料處理工工機器學習工工工資料視覺化



祖員介紹主主題介紹主義統架構工工工資料處理工工機器學習工工工資料視覺化工工



組員介紹主題介紹主義統架構工工資料處理工工機器學習工工資料視覺化

Hadoop叢集

資料爬蟲 python

- Selenium爬取 資料
- Bash排程定期 下載更新資料

資料前處理 python/bash

- 將資料轉為 Json及csv結構
- Bash排程處理 及監控

自動上傳 bash

- 叢集效能管理
- 自動排程上傳

Spark

資料預處理 PySpark • 使用Docker測 試程式

• 隨機森林

• 邏輯回歸

• GBT

• FNN

機器學習

PySpark

- 視覺化 Plotly/Bokeh
- 產生Web app 圖形模板
- Pivot表建立

Web APP

資料庫 MySQL

- Pivot表資料庫
- 快速回應前端 請求

前端架構 flask

- Flask製作 server
- 串聯前後端

Web APP HTML

- Dashboard
- 專利類別預測機

組員介紹

主題介紹

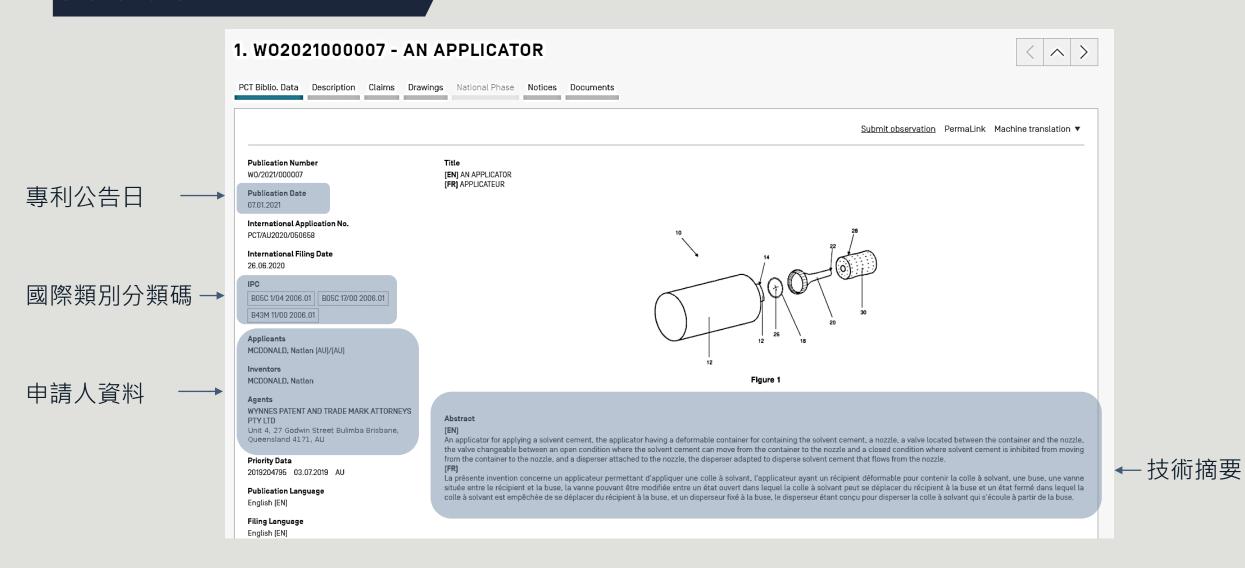
系統架構

資料處理

機器學習

資料視覺化

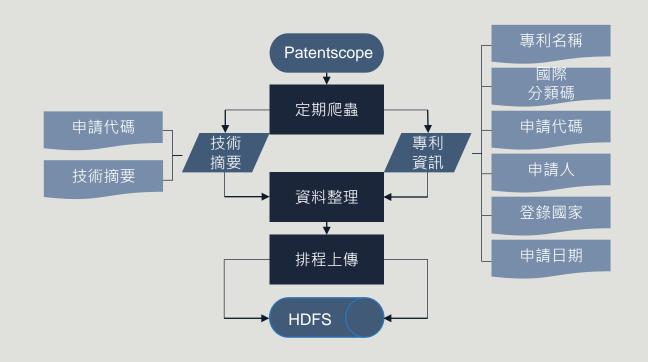
資料簡介



組員介紹 主題介紹 系統架構 資料處理 機器學習 資料視覺化

資料前處理

- 資料抓取後按內容與需求 將資料分為兩批並進行前處理
- 將處理完的檔案上傳至叢集



組員介紹 主題介紹 系統架構 資料處理 機器學習 資料視覺化 其他討論

資料前處理

• Python+Bash+Crontab,爬蟲、資料前處理、上傳及監控,**全自動化完成**

```
# m h dom mon dow command

#專利號碼爬蟲
0 0 * * 1 P_number.py

#專利爬蟲
0 12 * * 1 P_scraper.PY

#資料前處理
0 12 * * 2 Make_JSON.py
0 0 * * 3 abs.py

#資料上傳
0 6 * * 3 bash Update_ABS.sh
0 12 * * 4 bash Update_JSO.sh
```

專利資料庫 |

- 專利摘要資料表
 - 紀錄所有專利之技術簡介
 - 自然語言
 - 包含大量專業詞彙、化學式等
 - 資料庫蒐集超過400,000筆
 - 用於訓練智慧專利預測模型

root

|-- Application_Number : string (nullable = true)

|-- Abstract: string (nullable = true)

```
_c0
PCT/EP2001/009832|Liquid crystal mi...|
PCT/KR2000/000814|The present inven...|
PCT/IL2000/000667|The present inven...|
PCT/DK2001/000750|The invention rel...|
PCT/EP2001/012972 The invention rel...
PCT/GB1992/000681 Compounds having ...
PCT/EP2007/000257 | The invention rel...
PCT/GB1992/001189 | Compounds of gene...
PCT/RU2001/000190 | The inventive met... |
PCT/EP2004/007957 | The invention rel...
PCT/IL2000/000459|The present inven...|
PCT/KR2006/002440 A diagnostic kit ...
PCT/KR2001/001941|The present inven...|
PCT/SE2002/000250|To facilitate eg ...|
|PCT/GR1993/000005|A technique for t...|
PCT/DE2001/001579 | The invention rel...
PCT/IL2001/000088 A method and circ...
PCT/KR2001/000965 A preferable embo...
PCT/GB2001/002487 | New spisulosine d...
|PCT/HU2001/000068|A system of appar...|
only showing top 20 rows
```

專利資料庫Ⅱ

- 專利元資料表
 - 紀錄該專利之所有元資料,包含申請人、申請年分、行業別等資訊
 - 資料庫蒐集超過400,000筆
 - 用以實作統計描述,可萃取出具戰略價值之資訊
 - 統計描述結果可以儀表板方式呈現

```
root
-- Agents: string (nullable = true)
 -- Applicants: array (nullable = true)
    -- element: string (containsNull = true)
 -- Application_Number: string (nullable = true)
  Designated States: struct (nullable = true)
    |-- African Intellectual Property Organization : array (nullable = true)
       |-- element: string (containsNull = true)
    |-- African Regional Intellectual Property Organization: array (nullable = true)
       |-- element: string (containsNull = true)
    -- Eurasian Patent Organization : array (nullable = true)
       |-- element: string (containsNull = true)
     -- European Patent Office : array (nullable = true)
       |-- element: string (containsNull = true)
    |-- Global: array (nullable = true)
       |-- element: string (containsNull = true)
 -- IPC: array (nullable = true)
    |-- element: string (containsNull = true)
 -- Inventors: string (nullable = true)
 -- PublicationNo_Name: string (nullable = true)
 -- Publication Date: string (nullable = true)
 -- Publication_Number: string (nullable = true)
|-- Title: array (nullable = true)
   |-- element: string (containsNull = true)
 -- mono_ipc: string (nullable = true)
 -- qua_ipc: string (nullable = true)
|-- tri_ipc: string (nullable = true)
```

專利資料庫Ⅱ

- 專利元資料表
 - 紀錄該專利之所有元資料,包含申請人、申請年分、行業別等資訊
 - 資料庫蒐集超過400,000筆
 - 用以實作統計描述,可萃取出具戰略價值之資訊
 - 統計描述結果可以儀表板方式呈現

```
|-- Applicants: array (nullable = true)
| |-- element: string (containsNull = true)
```

```
|-- Designated_States: struct (nullable = true)
```

```
|-- IPC: array (nullable = true)
| |-- element: string (containsNull = true)
```

|-- Publication_Date: string (nullable = true)

組員介紹 主題介紹 系統架構 資料處理 機器學習 資料視覺化 其他討論

專利資料庫Ⅱ

• 專利元資料表

44		4			++		4				
Agents		Application_Number				PublicationNo_Name				ipc_simplified	
++-		++			+		+		+		++
'ОСИПОВА, Наталья	[' [CY]/[CY] (All	PCT/IB2011/002779	[[BF, BJ,	CF,	'ЯСНЕЦОВ, Владими	1. W02012028965	08-03-2012	WO/2012/028965	[EN), COMBINATION	[A]	A
nan	[' [BY]/[BY] (AM,	PCT/BY2015/000005	[[BF, BJ,	CF,	'ЖАВНЕРКО, Геннад :	1. W02017070769	04-05-2017	WO/2017/070769	$ [{\sf EN})$, COMPOSITE O $ $	[C, G]	c
nan	[' [BY]/[BY] (AM,	PCT/BY2015/000005	[[BF, BJ,	CF,	'ЖАВНЕРКО, Геннад :	1. W02017070769	04-05-2017	WO/2017/070769	[EN), COMPOSITE O	[C, G]	G
"000 'МЕЖДУНАРОДН [[' [RU]/[RU] (All	PCT/EA2007/000006	[[BF, BJ,	CF,	'ТАХАУТДИНОВ Шафа	1. W02008046426	24-04-2008	WO/2008/046426	[EN), METHOD FOR	[B]	B
nan	[' [AZ]/[AZ]': 'Б	PCT/AZ2017/000007	[[BF, BJ,	CF,	'АЛЫЕВ, Абульфат :	1. W02019056075	28-03-2019	WO/2019/056075	[EN], METHOD FOR	[C, G]	C
nan	[' [AZ]/[AZ]': 'Б	PCT/AZ2017/000007	[[BF, BJ,	CF,	'АЛЫЕВ, Абульфат :	1. W02019056075	28-03-2019	WO/2019/056075	[EN), METHOD FOR	[C, G]	G
'BENEDETTO, Marco	[' [IT]/[IT]': 'C	PCT/IB2015/056276	[[BF, BJ,	CF,	'MOGNA, Giovanni' :	1. W02016027231	25-02-2016	WO/2016/027231	[EN], METHOD FOR	[A]	A
nan	[' [BY]/[BY] (AL,	PCT/BY2014/000007	[[BF, BJ,	CF,	'ШИРИПОВ, Владими :	1. W02016033674	10-03-2016	WO/2016/033674	[EN), DEVICE FOR	[B]	B
nan	[' [US]/[US] (All	PCT/IB2009/050270	[[BF, BJ,	CF,	'ИВАЩЕНКО Андрей :	1. W02009093206	30-07-2009	WO/2009/093206	[EN), 3-SULFONYL	[C, A]	C
nan	[' [US]/[US] (All	PCT/IB2009/050270	[[BF, BJ,	CF,	'ИВАЩЕНКО Андрей :	1. W02009093206	30-07-2009	WO/2009/093206	[EN), 3-SULFONYL	[C, A]	A
nan	[' [DE]/[DE] (All	PCT/EP2011/062178	[[BF, BJ,	CF,	'FISCHER, Rüdiger :	1. W02012010525	26-01-2012	WO/2012/010525	[DE), VERWENDUNG	[A]	A
nan	[' [AZ]/[AZ] (All	PCT/AZ2008/000002	[[BF, BJ,	CF,	'ГАШИМОВ, Ариф Ма :	1. W02009105840	03-09-2009	WO/2009/105840	[EN], METHOD FOR	[H]	H
HOFFMANN EITLE S	[' [IT]/[IT]': 'A	PCT/IB2018/058051	[[BF, BJ,	CF,	'FERRARI, Alessio' :	1. W02019077521	25-04-2019	WO/2019/077521	[EN), LIQUID COMP	[A]	A
'БАЗАНОВ, Юрий Бо	[' [RU]/[RU]': 'O	PCT/IB2015/050897	[[BF, BJ,	CF,	'ЕРИМБЕТОВ, Кенес :	1. W02015118488	13-08-2015	WO/2015/118488	[EN), AGENT FOR T	[A]	A
'DR. LASSE WEINMA	[' [DE]/[DE]': 'J	PCT/EP2016/072524	[[BF, BJ,	CF,	HUDECEK, Michael	1. W02017050884	30-03-2017	WO/2017/050884	[EN), A METHOD FO	[C, A]	C
'DR. LASSE WEINMA	[' [DE]/[DE]': 'J	PCT/EP2016/072524	[[BF, BJ,	CF,	HUDECEK, Michael	1. W02017050884	30-03-2017	WO/2017/050884	[EN), A METHOD FO	[C, A]	A
'ФЕДОРОВ, Дмитрий	[' [RU]/[RU] (All	PCT/IB2012/052483	[[BF, BJ,	CF,	'ШУРИГИН, Михаил :	1. W02012156938	22-11-2012	WO/2012/156938	[EN), COMPOUNDS P	[C, A]	C
'ФЕДОРОВ, Дмитрий	[' [RU]/[RU] (All	PCT/IB2012/052483	[[BF, BJ,	CF,	'ШУРИГИН, Михаил :	1. W02012156938	22-11-2012	WO/2012/156938	[EN), COMPOUNDS P	[C, A]	A
					BENNETT, Nichola			WO/2010/133882	[EN), DISACCHARIN	[C, A]	c
					'BENNETT, Nichola			WO/2010/133882	[EN), DISACCHARIN	[C, A]	A
+		++			++		+		+		++

組員介紹 主題介紹 系統架構 資料處理 機器學習 資料視覺化 其他討論

資料處理

講者:王嘉宏

資料預處理

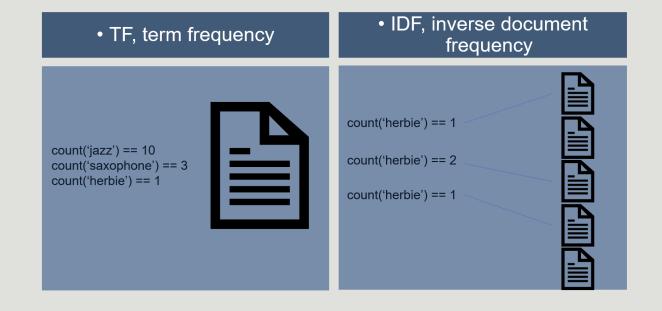
- 將專利摘要,轉換整**文件集**為機器學習模型 可處理的**向量型態**。
- 使用TF-IDF技術
 - TF: 詞頻, 該單字在文本內出現次數。
 - **IDF**:逆向文件頻率,該單字在整份文件集的稀 有程度。

範例:

- 1. 'Python python Spark Spark' -> (5,[0,4],[2.0,2.0]), (5,[0,4],[0.8109302162163288,0.0])
- 2. 'Python SQL' -> (5,[1,4], [1.0,1.0]), (5,[1,4],[0.4054651081081644,0.0])



資料預處理



資料預處理

- 專利摘要為技術之敘述,屬自然語言。
- 去除標段落及標點符號

The invention relates to a method for positioning an operating apparatus (28) in respect of a bending machine (3) of a production line (1) for bending sheet metal. A work surface (39) having specified boundaries is defined for the operating apparatus (28), within which work surface the operating apparatus (28) can be relocated. A target position is transmitted to an operating-control unit (35) via a first communication interface (33) and a current actual position of the operating apparatus (28) is determined. In addition, a target travel path (40) between the positions is determined and a generated travel command is transmitted to a travel drive (36). The operating apparatus (28) is automatically and autonomously relocated along the target travel path (40) and parked positioned at the target position.



The invention relates to a method for positioning an operating apparatus in respect of a bending machine of a production line for bending sheet metal. A work surface having specified boundaries is defined for the operating apparatus within which work surface the operating apparatus can be relocated. A target position is transmitted to an operating-control unit via a first communication interface and a current actual position of the operating apparatus is determined. In addition, a target travel path between the positions is determined and a generated travel command is transmitted to a travel drive The operating apparatus is automatically and autonomously relocated along the target travel path and parked positioned at the target position

專利摘要

建立詞袋

文字向量化

組員介紹 主題介紹 系統架構 資料處理 機器學習 資料視覺化 其他討論

資料預處理

- 去除常見、無代表性之單字
- 計算詞頻(Term Frequency)
- 建立詞袋
- 計算逆向文件頻率(Inverse Document Frequency)

```
vocabList counts
 invention 115492.0
       one 102200.0
     least | 79562.0
      said 75129.0
    method
            66887.0
     first | 65188.0
    device
            60588.0
comprising
            60137.0
   relates 54586.0
    second 52090.0
            51299.0
     means
    system | 48751.0
  provided
            47785.0
            45356.0
 comprises
  material 44986.0
   surface| 44534.0
   present | 43967.0
      also 41774.0
   wherein 39181.0
       may 37113.0
only showing top 20 rows
```

專利摘要

建立詞袋

文字向量化

組員介紹 主題介紹 系統架構 資料處理 機器學習 資料視覺化 其他討論

資料預處理

- 計算逆向文件頻率(Inverse Document Frequency)
- 資料集欄位數量:197097欄
- 文件完全轉為向量,可進行後續 NLP模型訓用

The invention relates to a method for positioning an operating apparatus in respect of a bending machine of a production line for bending sheet metal. A work surface having specified boundaries is defined for the operating apparatus within which work surface the operating apparatus can be relocated. A target position is transmitted to an operating-control unit via a first communication interface and a current actual position of the operating apparatus is determined. In addition, a target travel path between the positions is determined and a generated travel command is transmitted to a travel drive The operating apparatus is automatically and autonomously relocated along the target travel path and parked positioned at the target position



 $(197091,[1,2,10,12,32,34,42,56,65,79,107,176,274,327,409,457,1454,1506,1978,5511,9097,20862,111267],[1.461182438344008,1.737658437916606,2.2927314\\140520427,1.9731288448602595,3.0686465493899537,2.95946759801359,3.19\\97371715396246,3.397178705855117,10.001082332066941,3.96404803120971\\66,3.693323452225631,3.4594725571388643,3.8269897521016234,8.61911244\\8393286,4.592682480112563,9.439976943617742,5.405258149925722,5.24750\\2070531855,5.614978680907791,7.166959538317104,7.984255148400509,9.40\\564082933167,0.0])$

專利摘要

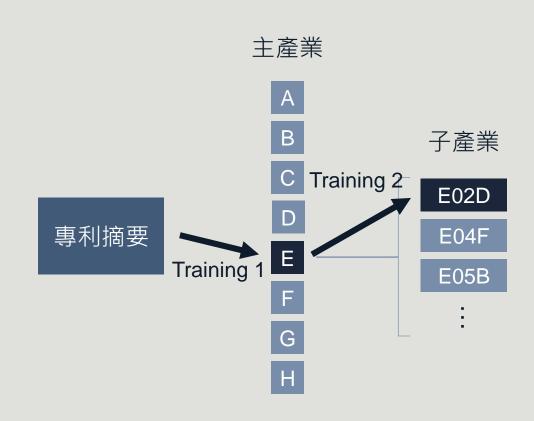
建立詞袋

文字向量化

組員介紹 主題介紹 系統架構 資料處理 機器學習 資料視覺化 其他討論

智慧分類模型建立

- 將向量化之**專利摘要**與之**國際分類代碼(IPC)** 放入模型中訓練,並篩選表現最佳者
- 訓練目標類別
 - 大分類:8大類別
 - 子分類:654 子類別
- 使用以下三種演算法做訓練:
 - 羅吉斯回歸
 - 隨機森林
 - 前饋神經網絡FNN
- 困難:
 - 樣本具超高維度
 - 類別標籤數量龐大



且員介紹 主題介紹 系統架構 資料處理 機器學習 資料視覺化 其他討論

模型訓練結果

模型精準度	羅吉斯回歸	隨機森林	前饋神經網絡
8大分類	0.435	0.275	0.392
654子分類	0.448	0.298	0.573

大分類

mono_ipc	rawFeatures	features	indexedLabel	rawPrediction	probability p	rediction
A ((18778,[0,2,3,4,6 (1877	8,[0,2,3,4,6	0.0	[-104.76359778962	[0.0,1.0,0.0,0.0,	1.0
A ((18778,[6,30,104, (1877	8,[6,30,104,	0.0	[-30.771753986580	9.68753173195840	4.6
B ((18778,[0,3,4,6,7 (1877	8,[0,3,4,6,7	2.0	[-44.143478410535	[8.36028938053069	6.
G ((18778,[0,4,5,13, (1877	8,[0,4,5,13,	3.0	[-591.92806829425	[0.0,1.0,0.0,1.41	1.
H ((18778,[0,2,3,4,5 (1877	8,[0,2,3,4,5	4.0	[-128.38596039992	[0.0,1.0,6.126823	1.
A ((18778,[0,2,10,12 (1877	8,[0,2,10,12	0.0	[123.477958694314	[1.0,1.3851310503	0.
A ((18778,[0,4,10,22 (1877	8,[0,4,10,22	0.0	[-64.171678946210	[1.04878786001143	2.
A ((18778,[0,4,13,18 (1877	8,[0,4,13,18	0.0	[-103.12443197521	9.19483065458986	1
A ((18778,[0,29,35,3 (1877	8,[0,29,35,3	0.0	[-64.812648897485	[5.62490008980729	1.
B ((18778,[0,1,2,4,1 (1877	8,[0,1,2,4,1	2.0	[362.210024830556	[0.50166976777357	0
C ((18778,[0,1,4,19, (1877	8,[0,1,4,19,	1.0	[260.589861064609	[1.36651082401933	1.
C ((18778,[1,5,6,10, (1877	8,[1,5,6,10,	1.0	[-237.93966907686	[0.0,1.0,0.0,0.0,	1.
C ((18778,[1,21,27,4 (1877	8,[1,21,27,4	1.0	[442.683092368988	[1.0,1.5864390454	0.
H ((18778,[2,5,11,13 (1877	8,[2,5,11,13	4.0	[-287.82276444534	[0.0,0.0,0.0,0.0,	4.
A ((18778,[0,4,6,7,8 (1877	8,[0,4,6,7,8	0.0	[617.470316544188	[1.0,0.0,4.026423	0.
A ((18778,[6,14,25,2 (1877	8,[6,14,25,2	0.0	[527.002157581215	[1.0,0.0,5.405655	0.
A ((18778,[12,13,17, (1877	8,[12,13,17,		[446.542771845157		0.
B ((18778,[0,1,4,5,1 (1877	8,[0,1,4,5,1		[-75.970922642582		1.
B ((18778,[1,2,8,24, (1877	8,[1,2,8,24,		[-437.05160358736		2.
B ((18778,[33,67,74, (1877	8,[33,67,74,	2.0	[-122.15498839713	[1.57253193804042	1.

only showing top 20 rows

子分類

qua_ipc	rawFeatures	features	indexedLabel	rawPrediction	probability	prediction
G06F (763	9,[0,2,4,5,10 (7639	,[0,2,4,5,10	42.0	[15.6640025456533	[7.46096478311355	10.0
E02D (7639	9,[0,1,2,3,8, (7639	,[0,1,2,3,8,	4.0	[1.77767684816139]	[0.00230542461085]	10.0
E21B (7639	9,[1,7,8,10,1 (7639	,[1,7,8,10,1	0.0	[52.0229897849143	[1.0,2.6766560717	0.0
E21B (7639	9,[3,7,12,15, (7639	,[3,7,12,15,	0.0	[39.7653993751308	[0.999999999395	0.0
E21B (7639	9,[6,9,10,11, (7639	,[6,9,10,11,	0.0	[52.0800113979501]	[0.9999999999999]	0.0
E05B (7639	9,[6,13,14,32 (7639	,[6,13,14,32	3.0	[-14.759699366231	[4.91360304031870	3.0
E21B (7639	9,[0,4,10,11, (7639	,[0,4,10,11,	0.0	[32.7894998876437]	[0.99999999008463]	0.6
E01F (7639	9,[0,1,2,4,5, (7639	,[0,1,2,4,5,	17.0	[15.5314053225411]	[0.75042430289094	0.6
E04G (7639	9,[2,4,7,9,10 (7639	,[2,4,7,9,10	11.0	[12.4515389380917]	[0.00452199175885	6.6
E06B (7639	9,[0,1,4,9,10 (7639	,[0,1,4,9,10	2.0	[-3.3033431012007	[1.35350069937513	2.6
E04F (7639	9,[0,1,3,4,5, (7639	,[0,1,3,4,5,	5.0	[0.80486068135602	[7.52630682918305	5.6
E02D (7639	9,[0,1,2,3,4, (7639	,[0,1,2,3,4,	4.0	[0.25900809221544	[1.60346273539367	12.0
E04F (7639	9,[4,5,6,8,9, (7639	,[4,5,6,8,9,	5.0	[-2.6942295703053	[3.80655763141517	1.6
E05B (7639	9,[5,8,11,14, (7639	,[5,8,11,14,	3.0	[11.9750531760996	[1.34162422812507	3.6
E05B (7639	9,[0,6,14,30, (7639	,[0,6,14,30,	3.0	[-2.6728806228139	[5.85350730477927	3.6
E21B (7639	9,[1,2,9,10,2 (7639	,[1,2,9,10,2	0.0	[42.9613195052480	[0.9999999999999	0.6
E21B (763	9,[26,31,32,3 (7639	,[26,31,32,3	0.0	[10.2162036509116	[0.80265519253776	0.6
E04B (7639	9,[2,5,6,10,1 (7639	,[2,5,6,10,1	1.0	[3.60328195088580	[2.09515775121467	1.6
E21B (7639	9,[1,2,4,15,1 (7639	,[1,2,4,15,1	0.0	[21.8988986377348	[0.99999884488019	0.6
E21B (7639	9,[7,21,26,35 (7639	,[7,21,26,35	0.0	[25.2543261396910	[0.99978150042154	0.6

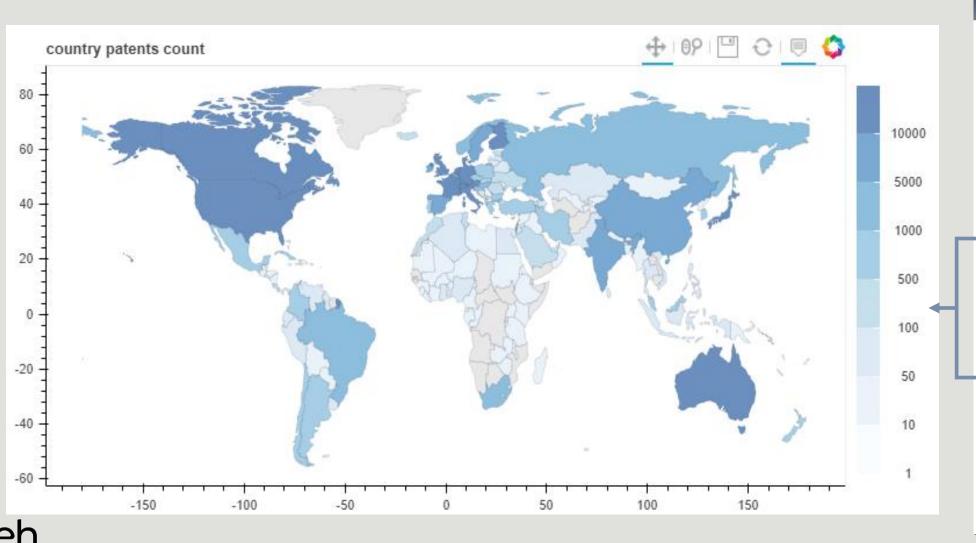
組員介紹 主題介紹 系統架構 資料處理 機器學習 資料視覺化 其他討論

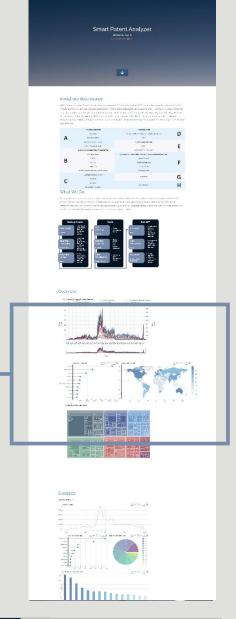
資料解讀

- 化繁為簡
- 觀眾導向
- 可讀性
- 表明觀點
- 資料重複性
- 由果推因,回溯推理

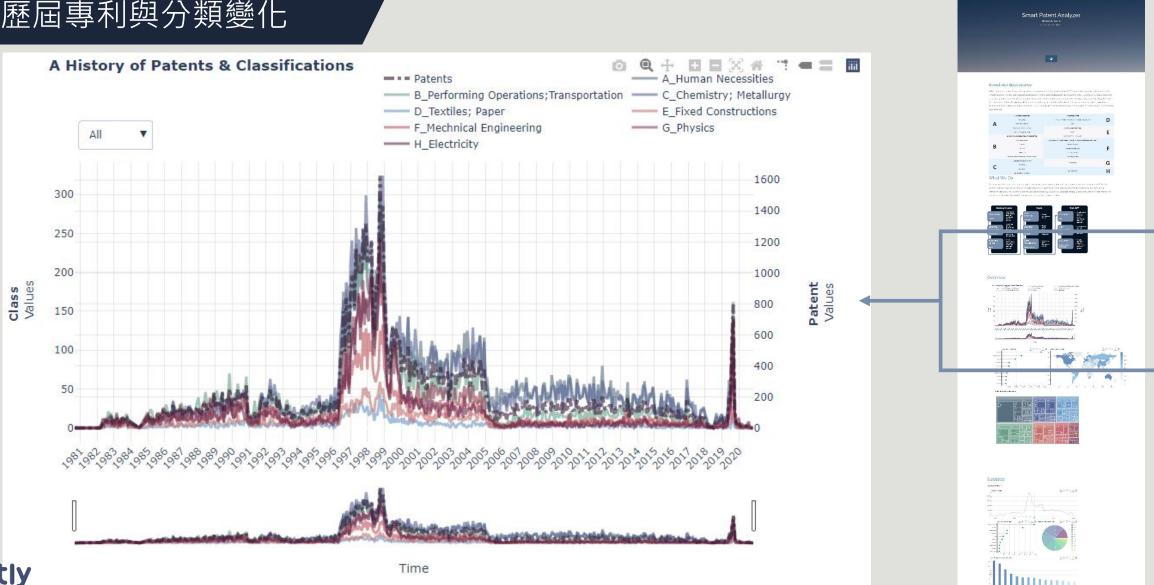
```
{ □
  "PublicationNo_Name": 1. W01982002074 - DEVICE FOR PRESSING GEOPHYSICAL DEVICES AGAINST THE WALL OF A BORE HOLE".
  "Title": ☐
     "EN), DEVICE FOR PRESSING GEOPHYSICAL DEVICES AGAINST THE WALL OF A BORE HOLE), ",
     "FR), \"DISPOSITIF DE COMPRESSION DAPPAREILS GEOPHYSIQUES SUR LA PAROI DUN TROU DE FORAGE\"),"
  "Publication_Number": "W0/1982/002074",
                                                          申請日期
   "Publication_Date": "24-06-1982",
  "Application_Number": "PCT/SU1980/000201".
   IPC":[ 🖃
    "'E21B 23/01', '2006.01'",
    "'E21B 47/00', '2012.01'",
                                                       國際類別分類碼
    "'E21B 49/10', '2006.01'",
    "'G01V 1/147', '2006.01'",
     "'G01V 11/00', '2006.01'",
    "'G01V 3/18', '2006.01'"
   Applicants": 🖃
    "' [SU]/[SU] (AllexceptUS)': 'VSESOYUZNY NAUCHNO-ISSLEDOVATELSKY INSTITUT RAZVED",
                                                                                申請人資料/國家
    "' [SU]/[SU] (UsOnly)': 'KUTUKOV, Viktor, Pavlovich''
  "Inventors": "'PEVZNER, Aleksandr, Abramovich', 'PEVZNER, Lev, Abramovich', 'PRITSKER, Leonid, Semenovich', 'BUTUZOV, Yury, Alekseevich
  "Agents": "'THE USSR CHAMBER OF COMMERCE AND INDUSTRY'",
   "Designated_States":{ 🖃
    "Global":[
       "AU",
                                    申請國家
       " DE",
       " GB".
                                              bokeh iiii plotly
```

國家的專利申請數





歷屆專利與分類變化

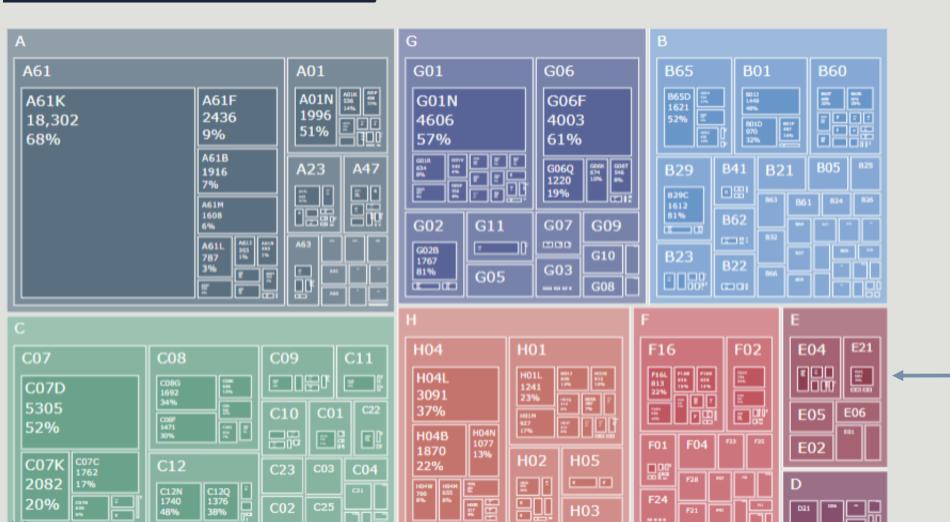


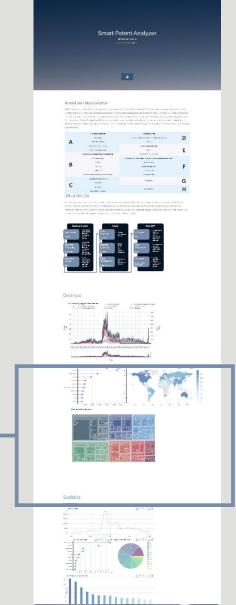
iii plotly

資料處理

資料視覺化

專利與分類的階層關聯



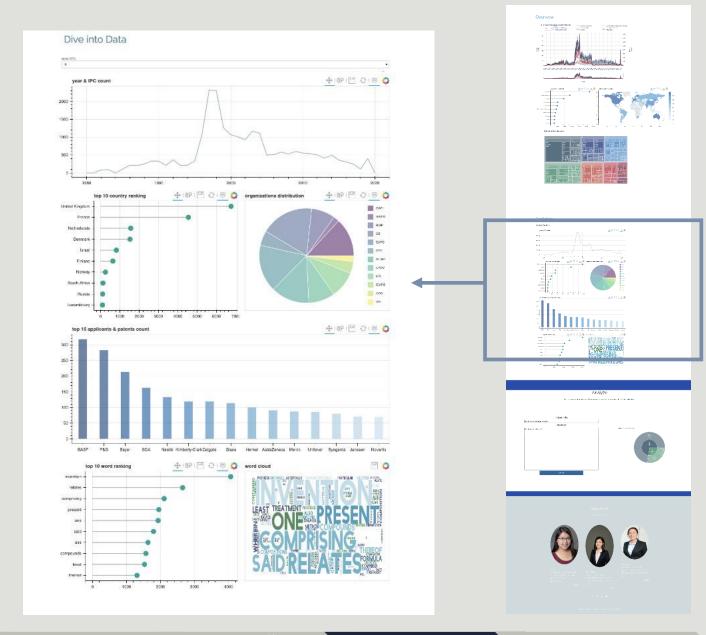


H₀3

互動式圖表呈現

- 主要目的:
 - 協助企業研發策略布局

- 可篩選特定專利類別查看:
 - 年份專利數量增長趨勢
 - 國家/組織專利數量分佈
 - 各類別公司專利數量排名
 - 文字雲,可與專利分類落點分析對應





專利智慧分類落點分析

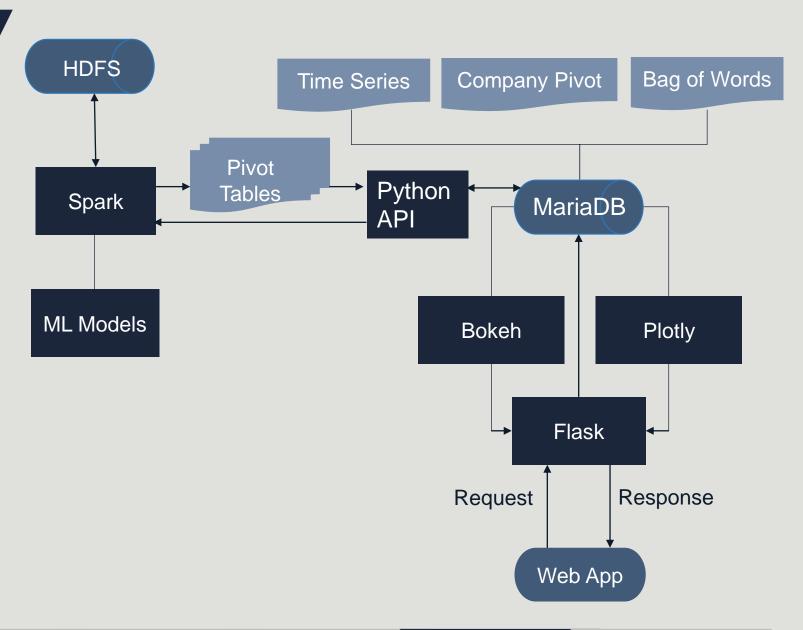
Analyze Fill in your abstract below. Then we will provide a prediction of IPC classification. Patent Title Input your company name Abstract Patent Classifications Input your abstract





Web開發

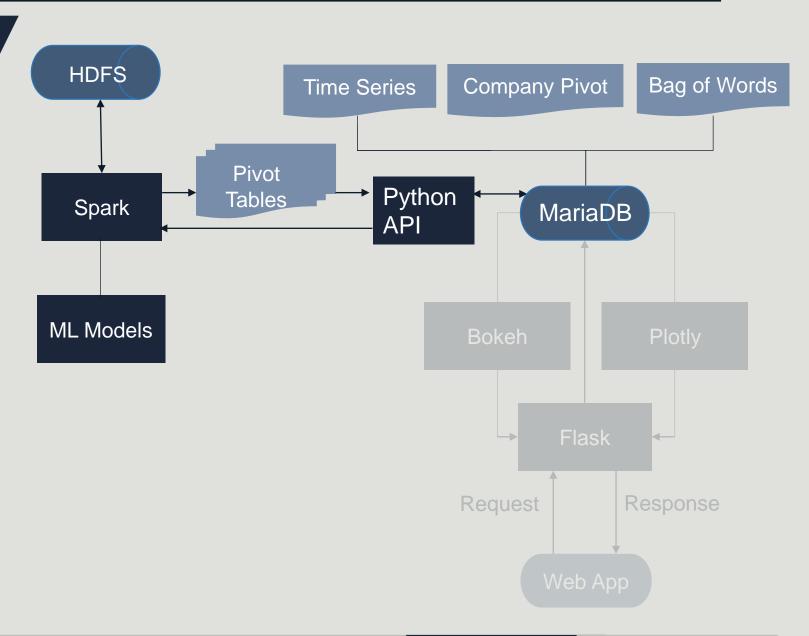
- 目的:動態網頁、自動化更新
 - 串聯前端架構與後端資料庫



組員介紹 主題介紹 系統架構 資料處理 機器學習 資料視覺化 其他討論

Web開發

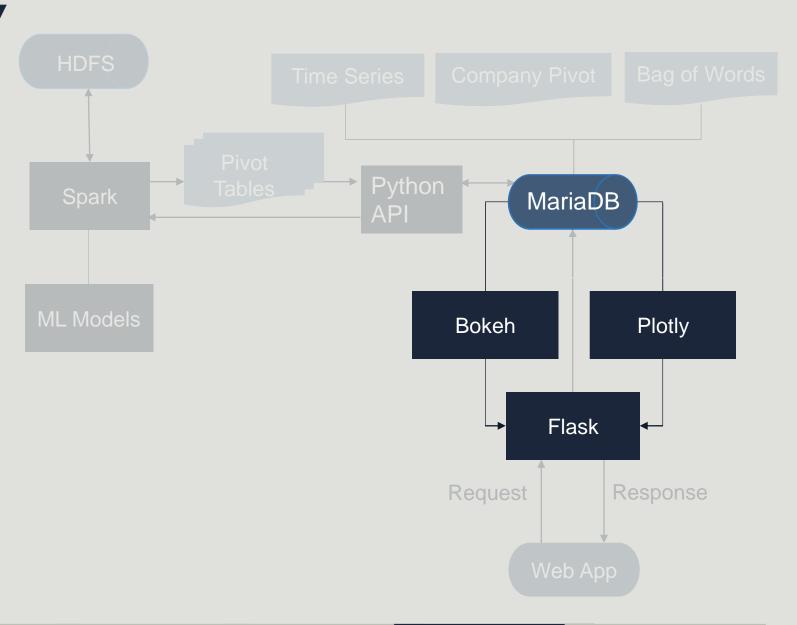
- 目的:動態網頁、自動化更新
 - 串聯前端架構與後端資料庫
- 後端資料庫
 - Spark · MySQL



組員介紹 主題介紹 系統架構 資料處理 機器學習 資料視覺化 其他討論

Web開發

- 目的:動態網頁、自動化更新
 - 串聯前端架構與後端資料庫
- 資料準備
 - Spark · MySQL
- 網頁後端
 - Bokeh · Plotly · Flask



組員介紹

E題介紹

系統架構

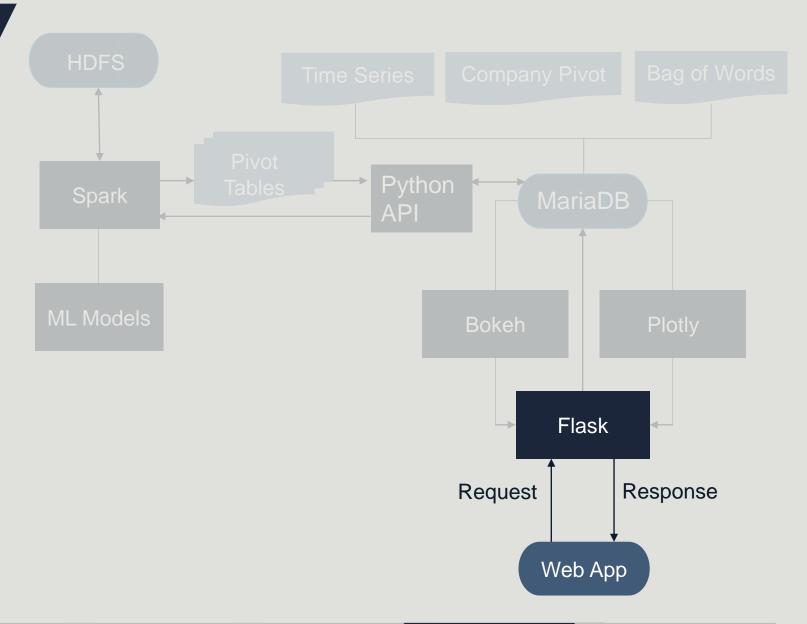
資料處理

肾學器

資料視覺化

Web開發

- 目的:動態網頁、自動化更新
 - 串聯前端架構與後端資料庫
- 資料準備
 - Spark \ MySQL
- 網頁後端
 - Bokeh \ Plotly \ Flask
- 網頁前端
 - HTML \ CSS \ BootStrap \ JavaScript



狙員介紹

主題介紹

系統架構

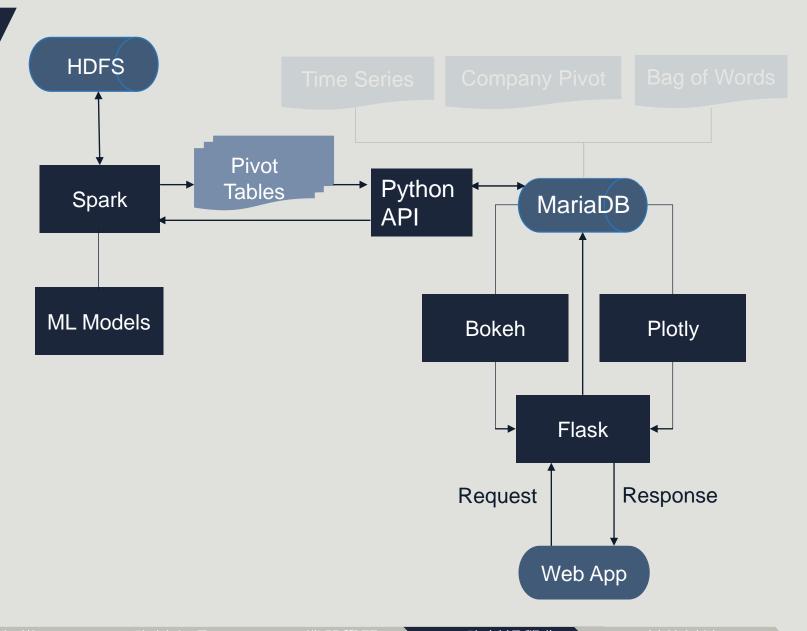
資料處理

肾學器

資料視覺化

Web開發

- 目的:動態網頁、自動化更新
 - 串聯前端架構與後端資料庫
- 資料準備
 - Spark \ MySQL
- 網頁後端
 - Bokeh \ Plotly \ Flask
- 網頁前端
 - HTML \ CSS \ BootStrap \ JavaScript



組員介紹

E題介紹

系統架構

資料處理

と器學習

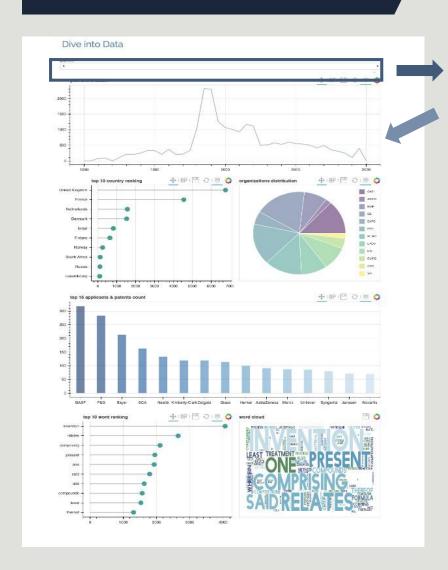
資料視覺化

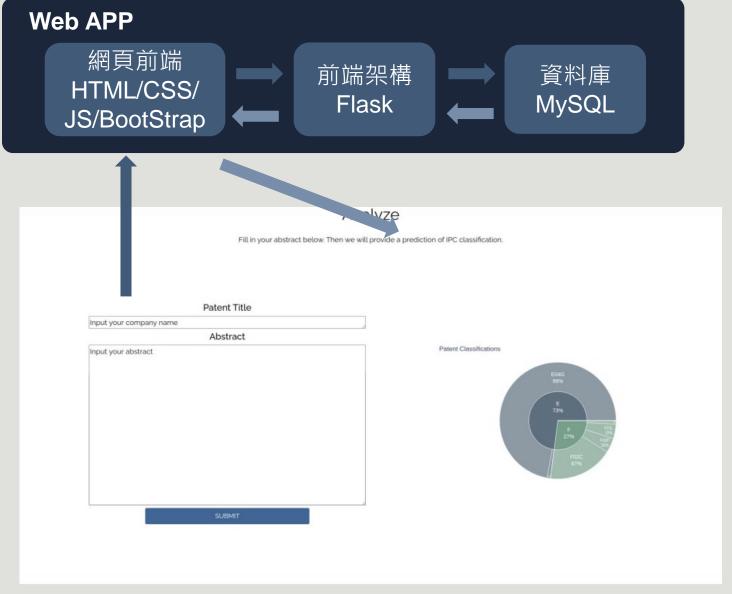
Flask

Flask SQLAIchemy Jinja2 WTForms, **FlaskForm** 網 資 頁前 • 連接資料庫 • Python表單 • Python模 料 驗證 板語言 庫 • 可將變數 • 避免CSRF 端 導入HTML 攻擊

組員介紹 主題介紹 系統架構 資料處理 機器學習 資料視覺化 其他討論

儀表板結果呈現



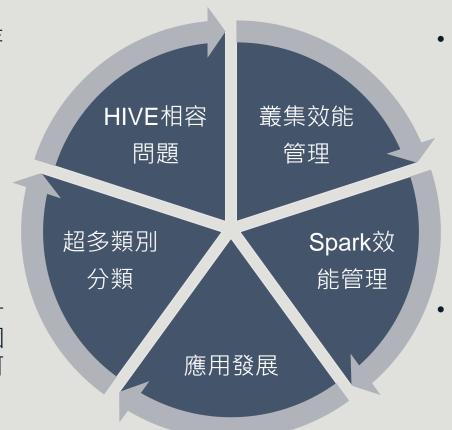


員介紹 主題介紹 系統架構 資料處理 機器學習 資料視覺化 其他討論

未來展望

將資料輸出為樞紐分析表,並存 入MySQL資料庫中作中轉站

• 改用許多二元分類模型組合為一套訓練模型集合,分別訓練各個不同之類別。結果亦表明此法可提升準確率



• 批次處理上傳資料,並建立監控機制

定期壓縮資料成parquet及bzip2檔, 並調校spark session

- 改善前端網頁應用功能
- 優化機器學習之模型表現
- 連結更多與產業、財經方面之分析,完善並最 大化專利分析所帶來之效用

16th 第二組

智慧戰略

Thank You

王予欣 / 王昱 / 王嘉宏 / 曾昱璇 / 顧芠菱 / 楊雅婷