ECE 551 Digital Design And Synthesis

Fall '16

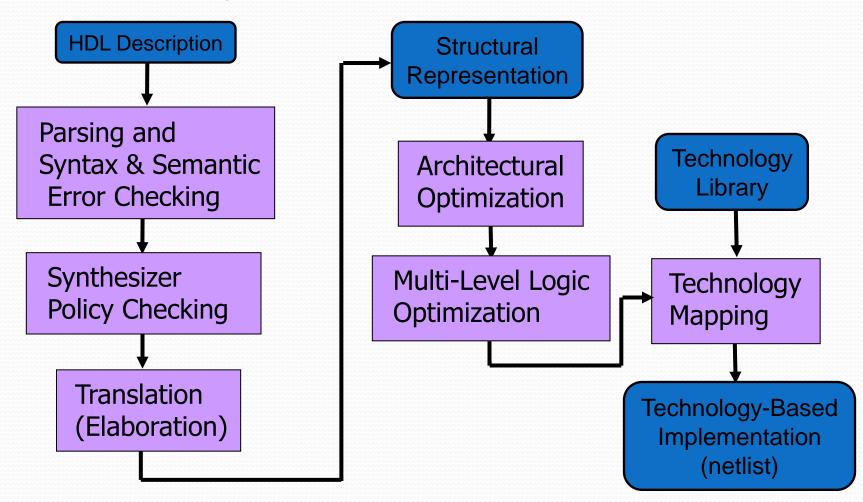
Synthesis Flow Synthesis Optimizations

Administrative Matters

HW4 Due Fri Nov 11th

• Project spec out soon. Make sure teams are formed. Stay after class today if not yet part of a team of 3-4 students.

Internal Synthesizer Flow



nitial Steps (Analyze Verilog File)

- Parsing for Syntax and Semantics Checking
 - Gives error messages and warnings to user
 - User may modify the HDL description in response
- Synthesizer Policy Checking
 - Check for adherence to allowable language constructs
 - Check for usage recommendations
- This is where you find out you can't use certain Verilog constructs
- This is synthesizer-dependent
 - Example: Design Vision allows indexed part-select (guess[i*2:2]), but the Xilinx tool does not
 - Certain things common to MOST synthesizers

Translation (Elaboration)

- Unrolls loops, substitutes macros & parameters, computes constant functions, evaluates generate conditionals
- Builds a structural representation of the design
- Like a netlist, but includes larger components
 - Not just gate-level, may include adders, etc.
- Gives additional errors or warnings to the user
 - Issues in initial transformation to hardware.
- Affects quality achieved by optimization steps
 - Structural representation depends on HDL quality
 - Poor HDL can prevent optimization

Importance of Translation

- It is important for the tool to recognize the sort of logic structures you are trying to describe.
- If it sees a 32-bit full adder, the tool has built-in solutions for optimizing adders
 - Ripple-carry, carry-save, carry look-ahead, etc.
- If it just sees a Boolean function with 65 inputs, it has to work a lot harder to achieve the same results
 - Do you think it can invent a CLA on the fly?

Optimization in Synthesis

- None of these are guaranteed!
 - Most synthesizers will make at least some attempt
- Detect and eliminate redundant logic
- Detect combinational feedback loops
- Exploit don't-care conditions
- Try to detect unused states (logic states you can't get to)
- Synthesize optimal, multilevel realizations subject to:
 - constraints on area and/or speed
 - available technology (library)

Optimization Process

- Optimization modifies the initial netlist resulting from elaboration.
 - Architecture choices made first (CLA,RCA,...)
 - Boolean logic level optimization next
 - Maps to cells from the technology library
 - Attempts to meet all specified constraints
- The process is divided into major phases
 - All or some selection of the major phases may be performed during optimization
 - Phase selection can be controlled by the user

Optimization Phases

- Architectural optimization
 - High-level optimizations that occur before the design is mapped to the logic-level
 - Based on constraints and high-level coding style
 - Level of parallelism?
 - Building block choices like adder architecture (DW components)
 - After optimization circuit function is represented by a generic, technology-independent netlist (GTECH)

Architectural Optimization

- In Synopsys, types include:
 - Sharing common mathematical subexpressions
 - Sharing resources
 - Selecting DesignWare implementations
 - Reordering operators
 - Identifying arithmetic expressions for datapath synthesis

Architectural Optimization

- Examples:
 - Replace an adder used as a counter with incrementor
 - Replace adder and separate subtractor with adder/subtractor if not used simultaneously

```
if (\simsub) z = a + b; else z = a - b;
```

- Performs selection of pre-designed components (Synopsys DesignWare)
 - adders, multipliers, shifters, comparators, muxes, etc.
- Need good code for synthesizer to do this
- Designer still knows more about the project

Logic/Gate-Level Optimization

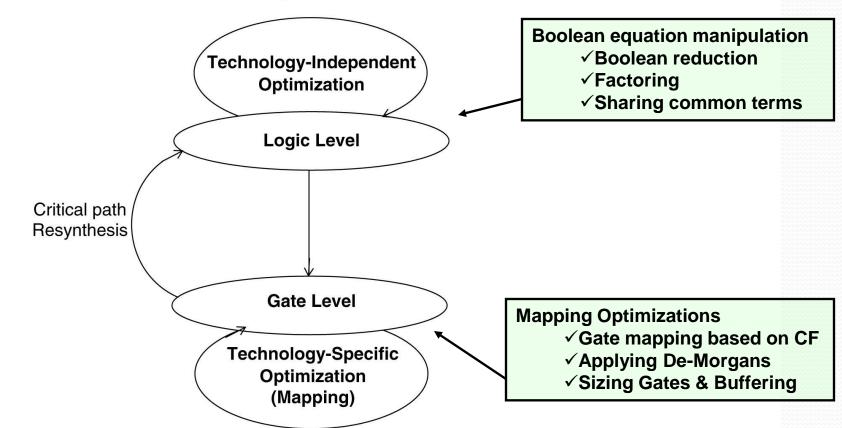
- Works on the generic netlist created by logic synthesis
- Produces a technology-specific netlist.
- In Synopsys, it consists of four stages:
 - Mapping
 - Delay optimization
 - Design rule fixing
 - Area optimization
- This phase often runs in multiple iterations if constraints are not met on the first try

Logic/Gate-Level Optimization

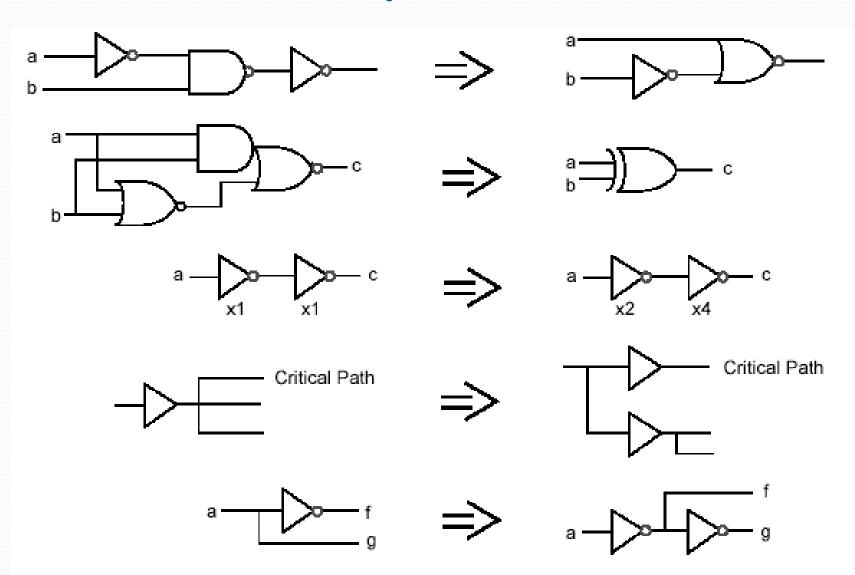
- Mapping
 - Generates a gate level implementation
 - Tries to meet timing and area goals
- Delay optimization
 - Tries to fix delay violations from mapping phase.
 - Does not fix design rule violations or meet area constraints.
- Design rule fixing
 - Tries to correct design rule violations
 - Inserting buffers or resizing existing cells
 - If necessary, violates optimization constraints
- Area optimization
 - Tries to meet area constraints, which have lowest priority

Combinational Optimization

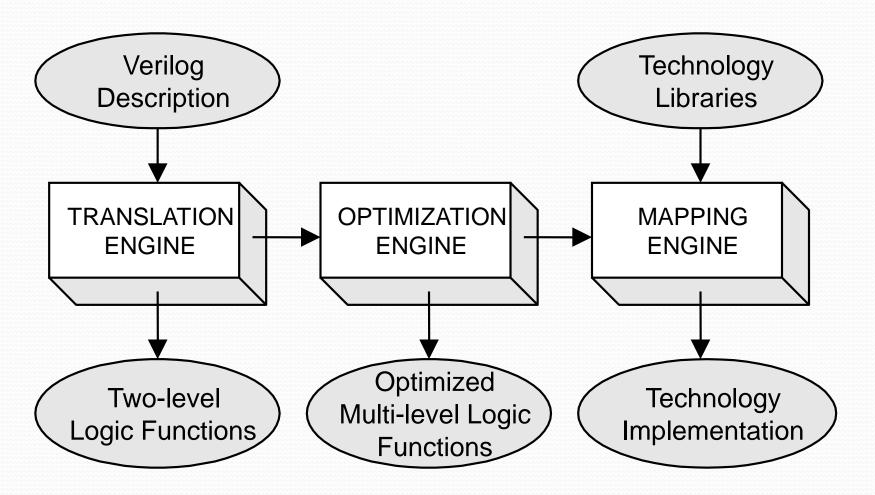
Figure 1-3 Combinational Optimization Phases



Gate-Level Optimization



Logic-Level Optimizations



Logic Optimizations

- Area
 - Number of gates fewer == smaller
 - Fan in of gates (# inputs) fewer == smaller
 - Drive Strength (transistor width) narrower == smaller
- Delay
 - Number of logic levels fewer == faster (usually)
 - Fan in of gates (# inputs) fewer == faster
- Gate Effort → Summation of Fan in of gates needed to implement function

 $GateEffort = \sum fanin(gates)$

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 Note that examples that follow ignore NOT gates for gate count / levels of circuits

Logic Optimizations

- Decomposition
- Extraction
- Factoring
- Substitution
- Elimination
- You don't have to remember the names of these
- But understand the concept and the motivation

Decomposition

- Find common expressions
- Reduce redundancy
 - Reduce area (number/size of gates)
- May increase delay
 - More levels of logic

Decomposition Example

• F = abc + abd + a'c'd' + b'c'd'

~7 gates, ~3 levels

- F = ab(c + d) + c'd'(a' + b')
- F = ab(c + d) + (c + d)'(ab)'
- X = ab
- \bullet Y = c + d
- F = XY + X'Y'

- 1 gate, 1 level
- 1 gate, 1 level
- 3 gates, 3 levels (or what?)
- Gate Effort = 4*(3-input AND) + 4-input OR = 16 effort
- Gate Effort = 2-input AND + 2-input OR + 2*(2-input AND)
 + 2-input OR = 10 effort

Extraction

- Find common sub-expressions in functions
- Like decomposition, but across more than one function
- Reduce redundancy
 - Reduce area (number/size of gates)
- May increase delay if more logic levels introduced

Extraction Example

- F = (a + b)cd + e
- G = (a + b) e'
- H = cde
- Define common terms: X = a + b, Y = cd
- F = XY + e
- G = Xe'
- H = Ye

- 3 gates, 3 levels
- 2 gates, 2 levels
- 1 gate, 1 level
- 1 gate, 1 level (each)
- 3 gates, 3 levels
- 2 gate, 2 levels
- 2 gate, 2 levels

- Before:
 - (3) 2-input ORs, (2) 3-input ANDs, (1) 2-input AND
 - Gate Effort = 6 + 6 + 2 = 14
- After
 - (2) 2-input ORs, (4) 2-input ANDs
 - Gate Effort = 4 + 8 = 12

Factoring

- Traditional two-level logic is sum-of-products
- Sometimes better expressed by product-of-sums
 - Fewer literals => less area
- May increase delay if logic equation not completely factored (becomes multi-level)

Factoring Example

- Definitely good:
 - F = ac + ad + bc + bd
 - F = (a + b)(c + d)
- Maybe good:
 - F = ac + ad + e
 - F = a(c + d) + e

- Gate Effort = 8 + 4
- Gate Effort = 4 + 2
- Gate Effort = 7
- Gate Effort = 6
- Factoring may improve area...
- But will likely increase delay (tradeoff)

Substitution

- Similar to Extraction (in fact a sub-case of extraction)
- When one function is subfunction of another
- Reduce area
 - Fewer gates
- Can increase delay if more logic levels

Substitution Example

- G = a + b
- F = a + b + c
- F = G + c

- 1 gate, 1 level 1 gate, 1 level
- 2 gate, 2 levels

- Before:
 - (1) 2-input OR, (1) 3-input OR => Gate Effort = 5
- After
 - (2) 2-input ORs (but increased levels) => Gate Effort = 4

Elimination (Flattening)

- Opposite of previous optimizations
- Goal is to reduce delay
 - Make signals travel though as few logic levels as possible
- But will likely increase area
 - Gate replication / redundant logic

Elimination Example

•
$$G = c + d$$

•
$$G = c + d$$

•
$$F = ac + ad + bc'd'$$

1 gate, 1 level

3 gates, 3 levels

1 gate, 1 level

4 gates, 2 levels

• Before:

- (2) 2-input ORs, (2) 2-input ANDs
- After:
 - (1) 2-input OR, (1) 3-input OR, (2) 2-input ANDs,
 - (1) 3-input AND (but fewer levels)

compile_ultra Optimizations

- High effort, maximum optimization
- Automatic hierarchical ungrouping
 - Ungroups small modules before mapping
 - Ungroups critical path based on delay
- Automatic datapath extraction
 - E.g. carry-save adders
- Boundary optimization
 - Propagates logic across hierarchical boundaries (constants, NC inputs/outputs, NOT)
- Sequential inversion
 - Sequential elements can have their outputs inverted

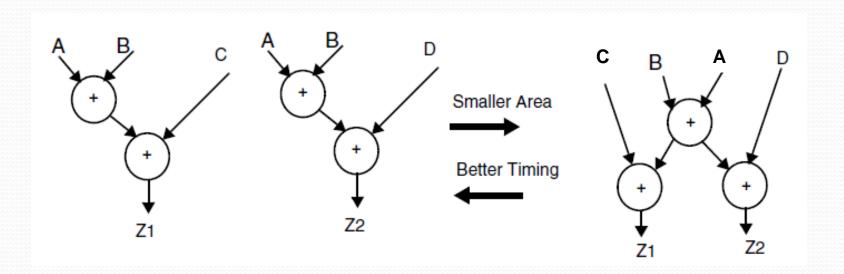
How to Ensure a Job Offer Once You Have the on-site Interview





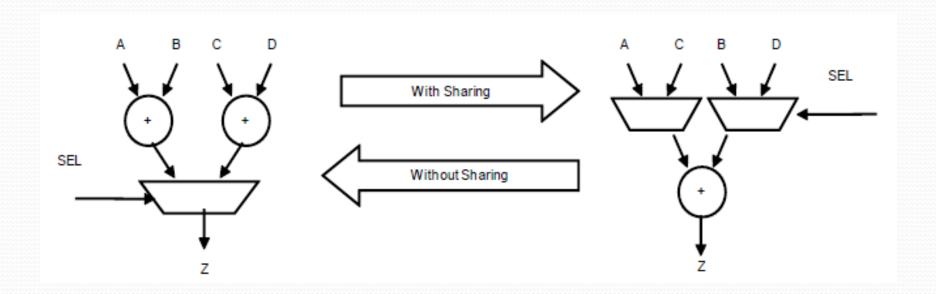
Sharing and Unsharing

- Expression sharing may be overridden later due to timing
 - $Z_1 \le A + B + C$
 - $Z_2 \le A + B + D$
 - Arrival time is A < B < D < C



Sharing and Unsharing

- Mutually exclusive operations can share resources
 - if(SEL) Z = A + B
 - else Z = C + D



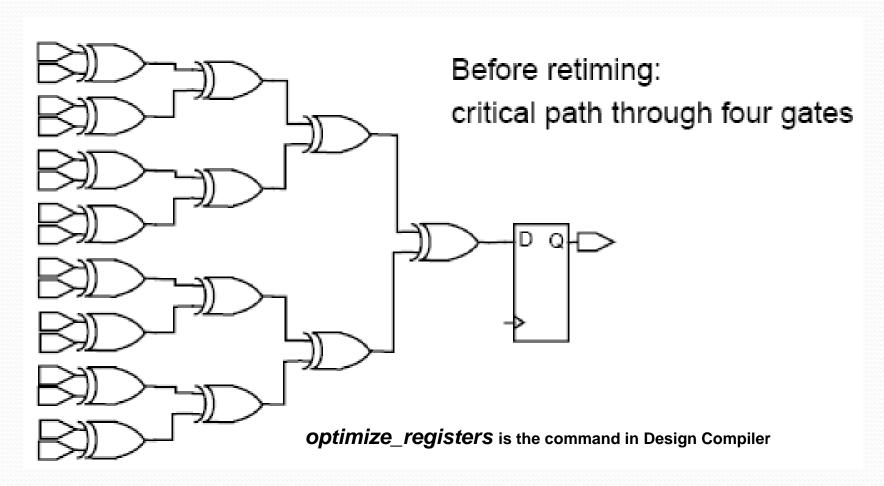
Sequential Inversion

- set compile_seqmap_enable_output_inversion true
- Allows the mapping of sequential elements in the design to library cells whose outputs are inverted.
- This can reduce area and or speed
- Not applicable for compile_ultra, because compile_ultra already does this.

Register Retiming

- At the HDL level, determining the optimal placement of registers is difficult and tedious at best, or just plain impossible at worst
- The register retiming tool moves registers through the synthesized combinational logic network to improve timing and/or area
 - Equalize delay (i.e. reduce critical path delay by increasing delay in other paths)
 - Reduce the number of flip-flops if timing criteria are met
 - Usually propagate registers forward
- Can also automatically pipeline combinational logic modules

Register Retiming Example [1]



Register Retiming Example [2]

