

Network-Node Stochastic Programming

Python Modeling Code for (c) and (d)

```
import itertools
from pyomo.environ import *
from pyomo.core import *
from pyomo.pysp.annotations import
(PySP_ConstraintStageAnnotation,
StochasticConstraintBoundsAnnotation,
StochasticConstraintBodyAnnotation)

theta1_table = [1,1,1,1,1,1,0,0,0]
theta2_table = [1,1,1,1,1,1,0,0,0]
d1_rhs_table = [0,1,2,3,5]
d2_rhs_table = [0,1,2,3,5]
d3_rhs_table = [0,1,2,3]

model = ConcreteModel()

#-----C-----
# model.constraint_stage =
PySP_ConstraintStageAnnotation()
# model.stoch_matrix =
StochasticConstraintBodyAnnotation()
# num_scenarios = len(theta1_table)*len(theta2_table)
# scenario_data = dict(('Scenario'+str(i),
(theta1val, theta2val))
#                       for i, (theta1val, theta2val)
in
#                       enumerate
(itertools.product(theta1_table, theta2_table),1))
#-----D-----
model.constraint_stage =
PySP_ConstraintStageAnnotation()
model.stoch_rhs =
StochasticConstraintBoundsAnnotation()
model.stoch_matrix =
StochasticConstraintBodyAnnotation()

num_scenarios =
len(theta1_table)*len(theta2_table)*len(d1_rhs_table)
* len(d2_rhs_table) * len(d3_rhs_table)

scenario_data = dict(('Scenario'+str(i), (theta1val,
theta2val, d1_rhs_val, d2_rhs_val, d3_rhs_val))
                    for i, (theta1val, theta2val,
d1_rhs_val, d2_rhs_val, d3_rhs_val) in
                    enumerate
(itertools.product(theta1_table, theta2_table,
d1_rhs_table, d2_rhs_table, d3_rhs_table),1))
#-----
model.d1_rhs = Param(mutable=True, initialize=0.0)
model.d2_rhs = Param(mutable=True, initialize=0.0)
model.d3_rhs = Param(mutable=True, initialize=0.0)

model.x1 = Var(within=NonNegativeReals)
model.x2 = Var(within=NonNegativeReals)
model.x3 = Var(within=NonNegativeReals)
model.f11 = Var(within=NonNegativeReals)
model.f12 = Var(within=NonNegativeReals)
model.f21 = Var(within=NonNegativeReals)
model.f22 = Var(within=NonNegativeReals)
model.f31 = Var(within=NonNegativeReals)
model.f32 = Var(within=NonNegativeReals)
model.s1 = Var(within=NonNegativeReals)
model.s2 = Var(within=NonNegativeReals)
```

```
model.s3 = Var(within=NonNegativeReals)
model.theta1 = Param(mutable=True, initialize=0)
model.theta2 = Param(mutable=True, initialize=0)

model.FirstStageCost = Expression(initialize=0)
model.SecondStageCost =
Expression(initialize=model.s1+model.s2+model.s3)

model.budget =
Constraint(expr=model.x1+model.x2+4*model.x3 <= 10)
model.constraint_stage.declare(model.budget,1)

#-----C-----
# model.d1 =
Constraint(expr=model.f11+model.f12+model.s1 == 2.05)
# model.constraint_stage.declare(model.d1,2)

# model.d2 =
Constraint(expr=model.f21+model.f22+model.s2 == 2.05)
# model.constraint_stage.declare(model.d2,2)

# model.d3 =
Constraint(expr=model.f31+model.f32+model.s3 == 1.5)
# model.constraint_stage.declare(model.d3,2)
#-----D-----
model.d1 =
Constraint(expr=model.f11+model.f12+model.s1 ==
model.d1_rhs)
model.constraint_stage.declare(model.d1,2)
model.stoch_rhs.declare(model.d1)

model.d2 =
Constraint(expr=model.f21+model.f22+model.s2 ==
model.d2_rhs)
model.constraint_stage.declare(model.d2,2)
model.stoch_rhs.declare(model.d2)

model.d3 =
Constraint(expr=model.f31+model.f32+model.s3 ==
model.d3_rhs)
model.constraint_stage.declare(model.d3,2)
model.stoch_rhs.declare(model.d3)
#-----
model.c1 =
Constraint(expr=model.f11+model.f22+model.f32-model.t
heta1*model.x1 <= 0)
model.constraint_stage.declare(model.c1,2)
model.stoch_matrix.declare(model.c1,
variables=[model.x1])

model.c2 =
Constraint(expr=model.f12+model.f21+model.f32-model.t
heta2*model.x2 <= 0)
model.constraint_stage.declare(model.c2,2)
model.stoch_matrix.declare(model.c2,
variables=[model.x2])

model.c3 =
Constraint(expr=model.f12+model.f22+model.f31-model.x
3 <= 0)
model.constraint_stage.declare(model.c3,2)

model.obj =
Objective(expr=model.FirstStageCost+model.SecondStage
Cost)
```

```

def pypsp_scenario_tree_model_callback():
    from pyomo.pysp.scenariotree.tree_structure_model
    import \
        CreateConcreteTwoStageScenarioTreeModel

    st_model =
    CreateConcreteTwoStageScenarioTreeModel(num_scenarios
    )

    first_stage = st_model.Stages.first()
    second_stage = st_model.Stages.last()

    # First Stage
    st_model.StageCost[first_stage] =
    'FirstStageCost'
    st_model.StageVariables[first_stage].add('x1')
    st_model.StageVariables[first_stage].add('x2')
    st_model.StageVariables[first_stage].add('x3')

    # Second Stage
    st_model.StageCost[second_stage] =
    'SecondStageCost'
    st_model.StageVariables[second_stage].add('f11')
    st_model.StageVariables[second_stage].add('f12')
    st_model.StageVariables[second_stage].add('f21')
    st_model.StageVariables[second_stage].add('f22')
    st_model.StageVariables[second_stage].add('f31')
    st_model.StageVariables[second_stage].add('f32')
    st_model.StageVariables[second_stage].add('s1')
    st_model.StageVariables[second_stage].add('s2')
    st_model.StageVariables[second_stage].add('s3')
    return st_model

def pypsp_instance_creation_callback(scenario_name,
node_names):
    #
    # Clone a new instance and update the stochastic
    # parameters from the sampled scenario
    #
    instance = model.clone()
    theta1_val, theta2_val, d1_rhs_val, d2_rhs_val,
d3_rhs_val = scenario_data[scenario_name]
    instance.theta1.value = theta1_val
    instance.theta2.value = theta2_val
    #-----D-----
    instance.d1_rhs.value = d1_rhs_val
    instance.d2_rhs.value = d2_rhs_val
    instance.d3_rhs.value = d3_rhs_val
    #-----
    return instance

```

(c) Total execution time=3.67 seconds

(d) Total execution time=370.37 seconds

(C-1)SD input smps files

network_c.cor

```

* Source: Pyomo MPS Writer
* Format: Free MPS
*

```

```

NAME Scenario1
OBJSENSE
MIN
ROWS
N obj
L c_u_budget_

```

```

E c_e_d1_
E c_e_d2_
E c_e_d3_
L c_u_c1_
L c_u_c2_
L c_u_c3_
E c_e_ONE_VAR_CONSTANT
COLUMNS
    x1 c_u_budget_ 1
    x1 c_u_c1_ -1
    x2 c_u_budget_ 1
    x2 c_u_c2_ -1
    x3 c_u_budget_ 4
    x3 c_u_c3_ -1
    f11 c_e_d1_ 1
    f11 c_u_c1_ 1
    f12 c_e_d1_ 1
    f12 c_u_c2_ 1
    f12 c_u_c3_ 1
    f21 c_e_d2_ 1
    f21 c_u_c2_ 1
    f22 c_e_d2_ 1
    f22 c_u_c1_ 1
    f22 c_u_c3_ 1
    f31 c_e_d3_ 1
    f31 c_u_c3_ 1
    f32 c_e_d3_ 1
    f32 c_u_c1_ 1
    f32 c_u_c2_ 1
    s1 obj 1
    s1 c_e_d1_ 1
    s2 obj 1
    s2 c_e_d2_ 1
    s3 obj 1
    s3 c_e_d3_ 1
    ONE_VAR_CONSTANT obj 0
    ONE_VAR_CONSTANT c_e_ONE_VAR_CONSTANT 1
RHS
    RHS c_u_budget_ 10
    RHS c_e_d1_ 2.0499999999999998
    RHS c_e_d2_ 2.0499999999999998
    RHS c_e_d3_ 1.5
    RHS c_u_c1_ 0
    RHS c_u_c2_ 0
    RHS c_u_c3_ 0
    RHS c_e_ONE_VAR_CONSTANT 1
BOUNDS
    LO BOUND x1 0
    LO BOUND x2 0
    LO BOUND x3 0
    LO BOUND f11 0
    LO BOUND f12 0
    LO BOUND f21 0
    LO BOUND f22 0
    LO BOUND f31 0
    LO BOUND f32 0
    LO BOUND s1 0
    LO BOUND s2 0
    LO BOUND s3 0
ENDATA

```

network_c.tim

```

TIME network
PERIODS IMPLICIT
x1 obj TIME1

```

```
f11 c_e_d1_ TIME2
ENDATA
```

network_c_revised.sto

```
STOCH retail
INDEP DISCRETE
x1 c_u_c1_-1 0.7
x2 c_u_c2_0 0.3
x1 c_u_c1_0 0.3
x2 c_u_c2_-1 0.7
ENDATA
```

(C-2) Output Console

```
Yului-MacBook:Debug yul$ ./sd

Beginning SD...

Please enter the name of the problem files (eg. `exags1p`):
network_c
mkdir: ./sdoutput: File exists
mkdir: ./sdoutput/network_c: File exists
Reading problems from ./sdinput/network_c/network_c.cor
the filename is : ./sdinput/network_c/network_c.cor
Specified objective sense: MINIMIZE
Selected objective name: obj
Selected RHS name: RHS
Selected bound name: BOUND
finished loading core file via external Solver.
-0.700000
-0.700000
Vector x_k from the mean problem ::
16.59999999913667068085 4.99999999949012696732
4.99999999935742867052 0.00000000028811110114
2.04999999981604874577 0.0000000003835065432
2.04999999981604652532 0.0000000003835065432
0.00000000021140979251 1.44999999969580239956
0.00000000014588982868 0.00000000014588982868
0.05000000009321703409 1.00000000000000000000
Objective from the mean problem : 0.050000

num_rv = 2;
num_cipher = 1;

----- Replication No.0 -----
+++++++>*****Max_pi*****:
6.000000

----- Replication No.1 -----
++++++Warning: Output names have been modified to
conform to LP format.
Warning: Output names have been modified to conform to LP
format.
+++Warning: Output names have been modified to conform
to LP format.
+Warning: Output names have been modified to conform to
LP format.
+++++++>*****Max_pi*****: 6.000000

----- Replication No.2 -----
+++++++>
```

Begin evaluation of average solution

```
.....
obs:10000 mean:1.250491 error: 0.041535
0.95 CI: [1.224521 , 1.276461]
.....
```

(ETC...)

Final Estimate

```
obs:172378 mean:1.253933
0.95 C.I.: [1.247663 , 1.260203]
```

```
*****Max_pi*****: 6.000000
```

Ending SD...

Total running time: 7512.242000 ms

(C-3) Output Result

Problem:		network_c				
First Stage Rows:		2				
First Stage Columns:		3				
First Stage Non-zeros:		3				
Mean solution is recommended for this instance.						
Number of replications:		3				
Status:		MEAN SOLUTION				
Total Objective Function Upper Bound:		1.254, [1.247663, 1.260203], half-width: 0.006, stdev: 0.003				
Total Objective Function Lower Bound:		1.324, [1.116794, 1.530871], half-width: 0.207, stdev: 0.048				
First Stage Solutions:						
No.	Row name	Activity	Lower bound	Upper bound	Dual	Dual STDEV
0	obj	1.253933e+00				
1	c_u_budget_	1.000000e+01		1.000000e+01	-2.463713e-01	4.998181e-03
No.	Column name	Activity	Lower bound	Upper bound	Reduced Cost	RC STDEV
1	x1	2.050111e+00	0.000000e+00		0.000000e+00	0.000000e+00
2	x2	2.050111e+00	0.000000e+00		0.000000e+00	0.000000e+00
3	x3	1.474945e+00	0.000000e+00		0.000000e+00	0.000000e+00

Hence, we get the optimal value of

$$\mathbf{x1 = 2.0501, x2 = 2.0501, x3 = 1.4750}$$

(D-1) smps files

network_d.cor

```
* Source:   Pyomo MPS Writer
* Format:   Free MPS
*
NAME Scenario1
OBJSENSE
MIN
ROWS
N obj
L c_u_budget_
E c_e_d1_
E c_e_d2_
E c_e_d3_
L c_u_c1_
L c_u_c2_
L c_u_c3_
E c_e_ONE_VAR_CONSTANT
COLUMNS
  x1 c_u_budget_ 1
  x1 c_u_c1_ -1
  x2 c_u_budget_ 1
  x2 c_u_c2_ -1
  x3 c_u_budget_ 4
  x3 c_u_c3_ -1
  f11 c_e_d1_ 1
  f11 c_u_c1_ 1
  f12 c_e_d1_ 1
  f12 c_u_c2_ 1
  f12 c_u_c3_ 1
  f21 c_e_d2_ 1
  f21 c_u_c2_ 1
  f22 c_e_d2_ 1
  f22 c_u_c1_ 1
  f22 c_u_c3_ 1
  f31 c_e_d3_ 1
  f31 c_u_c3_ 1
  f32 c_e_d3_ 1
  f32 c_u_c1_ 1
  f32 c_u_c2_ 1
  s1 obj 1
  s1 c_e_d1_ 1
  s2 obj 1
  s2 c_e_d2_ 1
  s3 obj 1
  s3 c_e_d3_ 1
  ONE_VAR_CONSTANT obj 0
  ONE_VAR_CONSTANT c_e_ONE_VAR_CONSTANT 1
RHS
  RHS c_u_budget_ 10
  RHS c_e_d1_ 0
  RHS c_e_d2_ 0
  RHS c_e_d3_ 0
  RHS c_u_c1_ 0
  RHS c_u_c2_ 0
  RHS c_u_c3_ 0
  RHS c_e_ONE_VAR_CONSTANT 1
BOUNDS
LO BOUND x1 0
LO BOUND x2 0
LO BOUND x3 0
LO BOUND f11 0
LO BOUND f12 0
LO BOUND f21 0
LO BOUND f22 0
LO BOUND f31 0
```

```
LO BOUND f32 0
LO BOUND s1 0
LO BOUND s2 0
LO BOUND s3 0
ENDATA
```

network_d.tim

```
TIME network
PERIODS IMPLICIT
  x1 obj TIME1
  f11 c_e_d1_ TIME2
ENDATA
```

network_d.sto

```
STOCH retail
INDEP      DISCRETE
RHS        c_e_d1_ 0      0.05
RHS        c_e_d1_ 1      0.2
RHS        c_e_d1_ 2      0.5
RHS        c_e_d1_ 3      0.2
RHS        c_e_d1_ 5      0.05
RHS        c_e_d2_ 0      0.05
RHS        c_e_d2_ 1      0.2
RHS        c_e_d2_ 2      0.5
RHS        c_e_d2_ 3      0.2
RHS        c_e_d2_ 5      0.05
RHS        c_e_d3_ 0      0.1
RHS        c_e_d3_ 1      0.4
RHS        c_e_d3_ 2      0.4
RHS        c_e_d3_ 3      0.1
x1          c_u_c1_ -1     0.7
x1          c_u_c1_ 0      0.3
x2          c_u_c2_ -1     0.7
x2          c_u_c2_ 0      0.3
ENDATA
```

(E-1) Output Console

Yului-MacBook:Debug yul\$./sd

Beginning SD...

Please enter the name of the problem files (eg. `exags1p'):
network_d
mkdir: ./sdoutput: File exists
Reading problems from ./sdinput/network_d/network_d.cor
the filename is : ./sdinput/network_d/network_d.cor
Specified objective sense: MINIMIZE
Selected objective name: obj
Selected RHS name: RHS
Selected bound name: BOUND
finished loading core file via external Solver.
2.050000
2.050000
1.500000
-0.700000
-0.700000
Vector x_k from the mean problem ::
16.59999999913668489171 4.99999999949014206635
4.99999999935741357149 0.00000000028811109845

```

2.04999999981605007804 0.00000000003835065390
2.04999999981605185440 0.00000000003835065390
0.00000000021140979064 1.44999999969578707848
0.00000000014588982748 0.00000000014588982748
0.05000000009324059858 1.00000000000000000000
Objective from the mean problem : 0.050000

num_rv = 5;
num_cipher = 1;

----- Replication No.0 -----
+++++++Warning: Output names have been
modified to conform to LP format.
Warning: Output names have been modified to conform to LP
format.
+>*****Max_pi*****: 6.000000

----- Replication No.1 -----
+++++++Warning: Output names have been modified
to conform to LP format.
Warning: Output names have been modified to conform to LP
format.
+Warning: Output names have been modified to conform to
LP format.
>*****Max_pi*****: 6.000000

----- Replication No.2 -----
+++++++Warning: Output names have been
modified to conform to LP format.
>

Begin evaluation of average solution
.....

obs:10000 mean:1.810400 error: 0.039467
0.95 CI: [1.774675 , 1.846125]
.....

obs:20000 mean:1.801300 error: 0.027890
0.95 CI: [1.776181 , 1.826419]
.....

obs:30000 mean:1.803500 error: 0.022772
0.95 CI: [1.782965 , 1.824035]
.....

obs:40000 mean:1.800275 error: 0.019738
0.95 CI: [1.782508 , 1.818042]
.....

obs:50000 mean:1.796300 error: 0.017678
0.95 CI: [1.780422 , 1.812178]
.....

obs:60000 mean:1.792733 error: 0.016168
0.95 CI: [1.778241 , 1.807226]
.....

obs:70000 mean:1.794871 error: 0.014958
0.95 CI: [1.781448 , 1.808295]
.....

obs:80000 mean:1.793413 error: 0.014011
0.95 CI: [1.780849 , 1.805976]

```

```

.....

obs:90000 mean:1.795678 error: 0.013189
0.95 CI: [1.783836 , 1.807519]
.....

obs:100000 mean:1.797750 error: 0.012518
0.95 CI: [1.786498 , 1.809002]
.....

obs:110000 mean:1.794745 error: 0.011945
0.95 CI: [1.784026 , 1.805465]
.....

obs:120000 mean:1.794275 error: 0.011441
0.95 CI: [1.784010 , 1.804540]
.....

obs:130000 mean:1.792977 error: 0.011004
0.95 CI: [1.783112 , 1.802842]
.....

obs:140000 mean:1.791564 error: 0.010600
0.95 CI: [1.782069 , 1.801060]
.....

obs:150000 mean:1.793207 error: 0.010239
0.95 CI: [1.784026 , 1.802387]
.....

Final Estimate
obs:157253 mean:1.792901
0.95 C.I.: [1.783936 , 1.801865]

*****Max_pi*****: 6.000000

Ending SD...

Total running time: 6902.213000 ms

```

(E-2) Output Result

Problem:		network_d				
First Stage Rows:		2				
First Stage Columns:		3				
First Stage Non-zeros:		3				
Mean solution is recommended for this instance.						
Number of replications:		3				
Status:		MEAN SOLUTION				
Total Objective Function Upper Bound:		1.793, [1.783936, 1.801865], half-width: 0.009, stdev: 0.005				
Total Objective Function Lower Bound:		1.803, [1.451430, 2.154955], half-width: 0.352, stdev: 0.082				
First Stage Solutions:						
No.	Row name	Activity	Lower bound	Upper bound	Dual	Dual STDEV
0	obj	1.792901e+00				
1	c_u_budget_	1.000000e+01		1.000000e+01	-1.778810e-01	3.177198e-03
No.	Column name	Activity	Lower bound	Upper bound	Reduced Cost	RC STDEV
1	x1	3.000000e+00	0.000000e+00		0.000000e+00	0.000000e+00
2	x2	3.000000e+00	0.000000e+00		0.000000e+00	0.000000e+00
3	x3	1.000000e+00	0.000000e+00		0.000000e+00	0.000000e+00

Hence, we get the optimal value of
 $x_1 = 3.00$, $x_2 = 3.00$, $x_3 = 1.00$