

# One-Step Methods

# General one-step methods

- ▶ initial value problem (IVP)

$$\begin{cases} \frac{du}{dt} = f(t, u) \\ u(0) = u_0 \end{cases}$$

$$u(t) = ? \\ t \in [0, T]$$

- ▶ equivalent integral equation

$$u(t) = u(0) + \int_0^t f(s, u(s)) ds, \quad t \in [0, T]$$

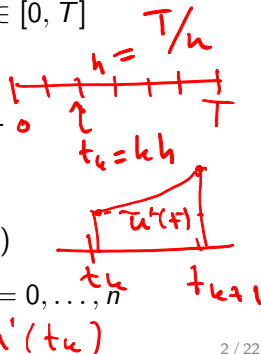
- ▶ numerical grid for  $t$ :

$$0 = t_0 < t_1 < t_2 < \dots < t_n = T$$

- ▶ uniform grid:  $t_k = kh$ ,  $k = 0, \dots, n$

- ▶ one-step method for approximation  $u_k \approx u(t_k)$

$$u_{k+1} = u_k + (t_{k+1} - t_k) \phi(t_k, u_k), \quad k = 0, \dots, n$$



# Euler's method

- ▶ basic idea: approximate integral in

$$u(t_{k+1}) = u(t_k) + \int_{t_k}^{t_{k+1}} \frac{du}{dt}(s) f(s, u(s)) ds$$

- ▶ rectangle rule

$$\int_{t_k}^{t_{k+1}} f(u(s), s) ds \approx (t_{k+1} - t_k) f(t_k, u(t_k))$$

- ▶ Euler's method

$$u_{k+1} = u_k + (t_{k+1} - t_k) f(t_k, u_k)$$

or for equidistant grid

$$u_{k+1} = u_k + hf(t_k, u_k)$$

- ▶ Euler's method is the simplest one-step method with

$$\phi(t, u) = f(t, u)$$



## example

► IVP

$$\frac{du}{dt} = -4t(1+t^2)u^2, \quad u(0) = 1$$

► exact solution (by separation of variables, see ODE course)

$$u(t) = \frac{1}{(t^2 + 1)^2}$$

$$\left\{ \begin{array}{l} \frac{du}{dt} = -4tu^2 \\ u(0) = 1 \end{array} \right.$$

```
f = lambda t, u : -4*t*(1+t**2)*u**2
```

```
phi = f; n = 8; h = 1.0/n
```

```
th = np.linspace(0,1,n+1)
```

```
uh = np.zeros(n+1) # Euler
```

```
uh[0] = 1.0
```

```
for k,tk in enumerate(th[:-1]):
```

```
    uh[k+1] = uh[k] + h*phi(tk,uh[k])
```

```
tex = np.linspace(0,1,129)
```

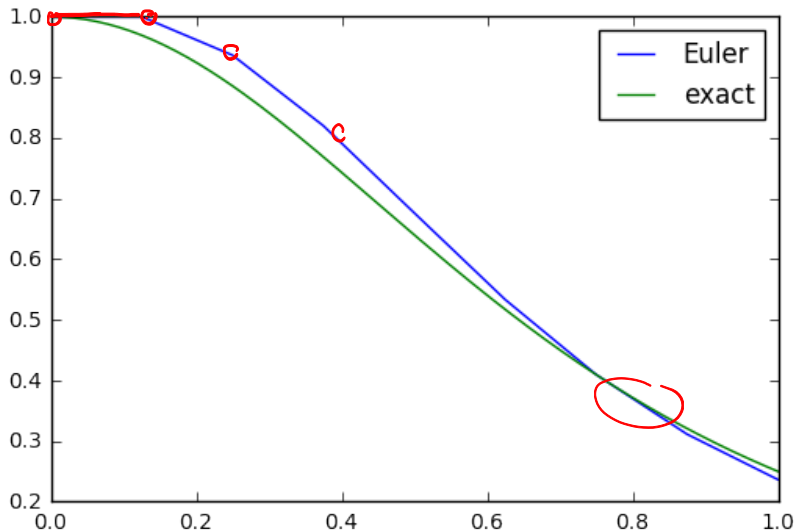
```
uex = np.zeros(129) # exact
```

```
for k,tk in enumerate(tex):
```

```
    uex[k] = 1.0/(tk**2+1)**2 ✓
```

|| Euler

```
plt.plot(th,u_h,label='Euler');plt.plot(tex,u_ex,label='exact')
```



## recursion for error

- ▶ error at time  $t_k$  – definition

$$e_k = \underline{u_k} - \underline{u(t_k)}$$

- ▶ recursion: change in error = change in approximation minus change in exact value

$$e_{k+1} = e_k + (\underline{u_{k+1}} - \underline{u_k}) - (\underline{u(t_{k+1})} - \underline{u(t_k)})$$

- ▶ Euler's method for approximation

$$\underline{u_{k+1} - u_k} = \underline{hf(t_k, u_k)}$$

- ▶ exact solution *almost* satisfies Euler's method

$$u(t_{k+1}) \neq u(t_k) + hf(t_k, u(t_k)) + hL(t_k, h)$$

where

$$L(t, h) = \frac{u(t+h) - u(t)}{h} - f(t, u(t))$$

is called the local discretisation error or truncation error

- ▶ substituting this into the formula for  $e_{k+1}$  gives

$$e_{k+1} = e_k + h(f(t_k, \underline{u_k}) - f(t_k, \underline{u(t_k)})) - hL(t_k, h)$$

## interpretation and bound on error growth

$$\begin{aligned} x &\leq Mx \\ \hline x &\leq x \Rightarrow x \leq 2x \end{aligned}$$

- ▶ formula from last slide

$$e_{k+1} = e_k + h(f(t_k, u_k) - f(t_k, u(t_k))) - hL(t_k, h)$$

- ▶ the error  $e_{k+1}$  consists of three parts:
  - ▶ the previous error  $e_k$  at  $t_k$
  - ▶ the effect of  $e_k$  on the Euler method:  $h(f(t_k, u_k) - f(t_k, u(t_k)))$
  - ▶ the error generated by the rectangle rule approximation:  
 $-hL(t_k, h)$
- ▶ assumption:  $f(u, t)$  Lipschitz-continuous in  $u$ , i.e.



$$\|f(u, t) - f(v, t)\| \leq M\|u - v\|$$

$$f(t, u)$$

- ▶ triangle inequality for error

$$\|e_{k+1}\| \leq (1 + hM)\|e_k\| + hL_k$$

$$\text{where } L_k = \|L(t_k, h)\|$$

$$|u$$

$$\begin{aligned} &\Rightarrow u: \\ &|-u+v| \\ &\leq M \cdot |u-v| \end{aligned}$$



## a lemma

### Lemma

If the  $d_k > 0$  satisfy, for some  $C > 1$  and  $D > 0$

$$d_{k+1} \leq Cd_k + D, \quad k = 0, 1, 2, \dots$$

then

$$d_k \leq C^k d_0 + D \frac{C^k - 1}{C - 1}, \quad k = 0, 1, 2, \dots$$

### Proof

- ▶ by recursion
- ▶ similar to geometric series

## error bound for Euler's method

### Proposition

Let  $T = nh$ ,  $M$  Lipschitz constant for  $f(\cdot, t)$ ,  $L = \max_{k=0, \dots, n} L_k$  and  $e_k$  be the error of Euler's method for  $du/dt = f(u, t)$ . Then

$$|e_n| \leq \exp(TM) |e_0| + hL \frac{\exp(TM) - 1}{M}$$

- remark: often,  $e_0 = 0$

### Proof:

- apply bound for  $|e_{k+1}|$
- use lemma with  $C = 1 + hM$ ,  $D = hL$  and  $d_k = |e_k|$

example  $f(t, u) = -u$

$$\dot{u} = -u \quad u = e^{-t} u_0$$

- ▶  $T = 1$ ,  $M = 1$  and

$$\begin{aligned} L(t, h) &= \frac{\exp(-(t+h)) - \exp(-t)}{h} + \exp(-t) \\ &= \exp(-\tau) - \exp(-t), \quad \tau \in [t, t+h] \end{aligned}$$

and by mean value theorem  $L = h/2$  thus

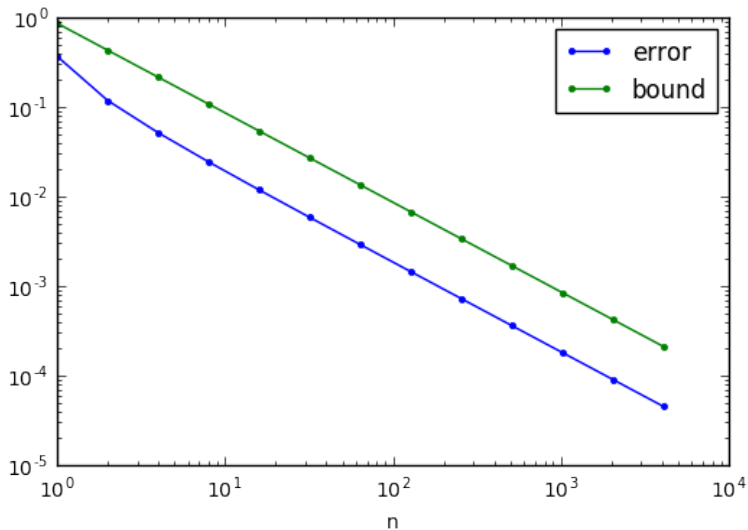
- ▶ (notice the usage of letter  $e$  in  $e = 2.71\dots$  and the error  $e_n$ )
- ▶ error bound

$$\underline{|e_n| \leq h(e-1)/2}$$

- ▶ remark: the error bound is a bit pessimistic but we will see how to get a better bound later

```
f = lambda u,t : -u
phi = f;
nvec = (1,2,4,8,16,32,64,128,256,512,1024,2048,4096)
error = np.zeros(len(nvec)); bound = np.zeros(len(nvec))
for i,n in enumerate(nvec):
    h = 1.0/n
    th = np.linspace(0,1,n+1)
    uh = np.zeros(n+1) # Euler
    uh[0] = 1.0
    for k,tk in enumerate(th[:-1]):
        uh[k+1] = uh[k] + h*phi(uh[k],tk)
    uex = np.exp(-th)
    eh = uh - uex
    error[i] = abs(eh).max()
    bound[i] = (np.e-1)*h/2
```

```
plt.loglog(nvec,error,'.-',label='error')  
plt.loglog(nvec,bound,'.-',label='bound')  
plt.xlabel('n')  
plt.legend();
```



# one-step methods

$$u_n \approx u(t_n)$$

- methods of the form

$$u_{k+1} = u_k + h \phi(t_k, u_k)$$



- *Euler's method*:

$$\phi(t, u) = f(t, u)$$

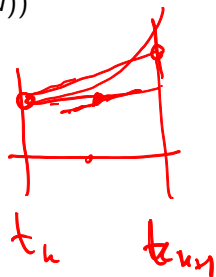
- *Heun's method*:

$$\phi(t, u) = \frac{1}{2}(f(t, u) + f(t + h, u + hf(t, u)))$$

- *midpoint method*:

$$\phi(t, u) = f(t + h/2, u + hf(t, u)/2)$$

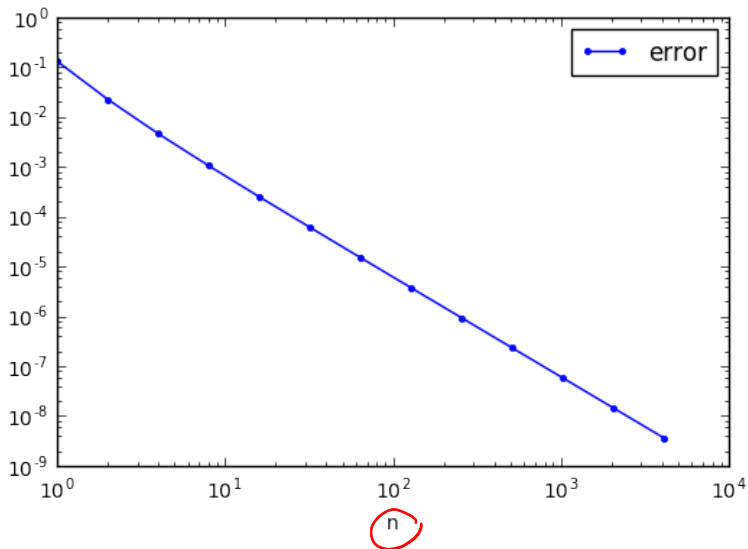
- these methods are referred to as *explicit methods*



## example for Heun's method

```
f = lambda t, u : -u
phi = lambda t, u, h, f=f : 0.5*(f(t,u) \
                                + f(t+h,u+h*f(t,u)))
nvec = (1,2,4,8,16,32,64,128,256,512,1024,2048,4096)
error = np.zeros(len(nvec))
for i,n in enumerate(nvec):
    h = 1.0/n
    th = np.linspace(0,1,n+1)
    uh = np.zeros(n+1) # Heun
    uh[0] = 1.0
    for k,tk in enumerate(th[:-1]):
        uh[k+1] = uh[k] + h*phi(tk, uh[k],h)
    uex = np.exp(-th)
    eh = uh - uex
    error[i] = abs(eh).max()
```

```
plt.loglog(nvec,error,'.-',label='error')  
plt.xlabel('n')  
plt.legend();
```





## fourth order Runge-Kutta method

- ▶ a classical method still some times used today
- ▶ four auxiliary functions

$$k_1 = f(t, u)$$

$$k_2 = f(t + h/2, u + hk_1/2)$$

$$k_3 = f(t + h/2, u + hk_2/2)$$

$$k_4 = f(t + h, u + hk_3)$$

- ▶ the function  $\phi(t, u)$

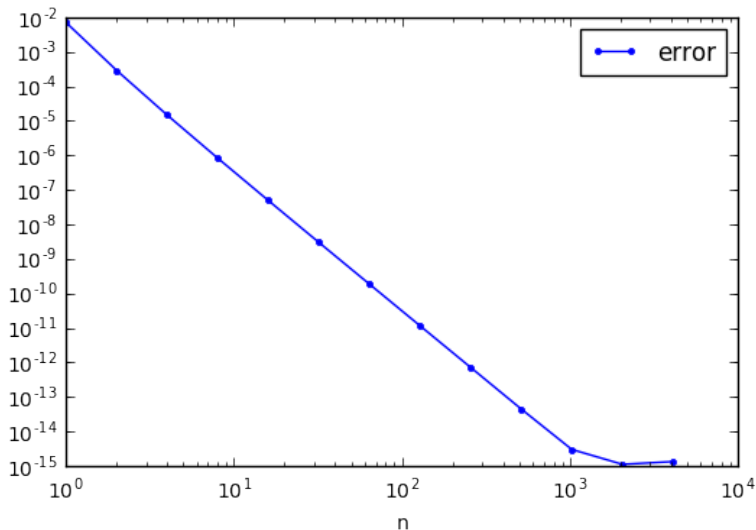
$$\phi(t, u) = \frac{1}{6}(k_1 + 2k_2 + 2k_3 + k_4)$$

- ▶ connection with Simpson's quadrature method

```
def phi(t,u,h,f=f):  
    k1 = f(t,u)  
    k2 = f(t+h/2,u+h*k1/2)  
    k3 = f(t+h/2,u+h*k2/2)  
    k4 = f(t+h,u+h*k3)  
    return (k1+2*k2+2*k3+k4)/6.0  
  
nvec = (1,2,4,8,16,32,64,128,256,512,1024,2048,4096)  
error = np.zeros(len(nvec))  
for i,n in enumerate(nvec):  
    h = 1.0/n  
    th = np.linspace(0,1,n+1)  
    uh = np.zeros(n+1) # RK4  
    uh[0] = 1.0  
    for k,tk in enumerate(th[:-1]):  
        uh[k+1] = uh[k] + h*phi(tk, uh[k],h)  
    uex = np.exp(-th)  
    eh = uh - uex  
    error[i] = abs(eh).max()
```

```
plt.loglog(nvec,error,'.-',label='error')  
plt.xlabel('n')  
plt.legend();
```

$nh = T$



# local discretisation error of one-step method



- ▶ recall general formula for one-step method

$$u_{k+1} = u_k + h\phi(t_k, u_k)$$

- ▶ how well the exact solution satisfies the one-step method

$$L(t, h) = \frac{u(t+h) - u(t)}{h} - \phi(t, u(t))$$

## Definition (consistency):

- ▶ The one-step method is consistent if

$$\lim_{h \rightarrow 0+} \sup_t L(t, h) = 0$$

- ▶ The one-step method is consistent of order p if

$$L(t, h) = O(h^p)$$

$$\leftarrow \rightarrow |L(t, h)| \leq C h^p$$

as  $h \rightarrow 0$  uniformly in  $t$

- ▶  $L(t, h)$  is  $O(h^p)$  means here that there exists a  $C > 0$  such that

$$|L(t, h)| \leq C h^p$$

## stability of one-step method

### **Definition (stability):**

*The one-step method defined by  $\phi(t, u)$  is stable if  $\phi(t, \cdot)$  is Lipschitz continuous, i.e.,*

$$\|\phi(t, u) - \phi(t, v)\| \leq M \|u - v\|$$

for all  $t \in [0, T]$

$$\left( \|f(t, u) - f(t, v)\| \leq L \|u - v\| \right)$$

# convergence theorem for one-step methods

## Theorem

A one-step method which is stable and consistent is convergent.

- ▶ remark: converse holds as well (Lax equivalence theorem)

## Proof

- ▶ Same as for Euler's method
- ▶ here we have

$$u_{k+1} - u_k = h\varphi(t_k, u_k)$$

$$u(t_{k+1}) - u(t_k) = h\phi(t_k, u(t_k)) + hL(t_k, h)$$

and

$$e_{k+1} - e_k = h(\varphi(t_k, u_k) - \varphi(t_k, u(t_k))) - hL(t_k, h)$$

$$\|\phi(t, u) - \phi(t, v)\| \leq M\|u - v\|$$

- ▶ as for Euler we get then

$$\|e_{k+1}\| \leq (1 + hM)\|e_k\| + hL_k$$

and thus

$$\|e_n\| \leq \exp(TM)\|e_0\| + L \frac{\exp(TM) - 1}{M}$$