

1)

Consider the IVP

$$\left. \begin{aligned} \frac{du}{dt} &= \lambda u, \quad \lambda \in \mathbb{C}, \quad t > 0 \\ u(0) &= u_0 \end{aligned} \right\} \text{---} (*)$$

1. What is the solution $u(t)$?
2. For what values of λ is the solution
 - (i) Unstable
 - (ii) Stable
 - (iii) Asymptotically stable.

3. Let $\operatorname{Re}(\lambda) < 0$, and ^{Introduce a} ~~consider~~ uniform discretization of the time variable with a constant step-size $h > 0$
 $t_k = kh, \quad k = 0, 1, \dots$

Consider

$$(a) \quad \frac{u_{k+1} - u_k}{h} = \lambda u_k$$

$$(b) \quad \frac{u_{k+1} - u_k}{\Delta t} = \lambda u_{k+1}$$

$$(c) \quad \frac{u_{k+1} - u_{k-1}}{2h} = \lambda u_k$$

$$(d) \quad \frac{u_{k+1} - u_{k-1}}{2h} = \frac{\lambda}{2} (u_{k+1} + u_{k-1})$$

2)

For each of the following methods (a) – (d)

- (i) Show that the method is a consistent approximation of ~~the~~ the IVP ~~*~~
- (ii) What is the truncation error
- (iii) Derive the region of absolute stability.
- (iv) Is the method implicit or explicit
Give reasons!
- (v) Is the method one-step or multi-step
- (vi) What is the maximum allowable stable time-step.
- (vii) Is the method ~~cond~~ conditionally stable, unconditionally stable / unstable!

2) Consider the scheme approximating the IVP

$$U^* = U_k^* + \lambda h U_k$$

— (XX)

$$U_{k+1} = U_k + \frac{\lambda h}{2} (U_k + U^*)$$

- i) What is the order of accuracy.
- ii) Is this a one-step or two-step method
Why?

3)

- iii) Derive the growth factor and the region of absolute stability.
- iv) What is the maximum stable time-step.
- d) For the method $(**)$, if assume that you have computed the solution with the step size $h = 0.1$ and the error is $e = 0.1$. If you wanted to have 1% error, what is the ~~the~~ largest possible time-step required to achieve this.

Consider the IVP

$$\frac{du}{dt} = Au, \quad A \in \mathbb{R}^{n \times n}, \quad u \in \mathbb{R}^n \quad \text{--- } \textcircled{+}$$

$$u(0) = u_0$$

④ What is the solution $u(t)$

~~③ Consider the numerical method~~

- ⑤ Let λ_i denote the i -th eigenvalue of A . For what values of λ_i is $\textcircled{+}$
- (i) Unstable
 - (ii) Stable
 - (iii) Asymptotically stable

6) Consider the numerical method for (*)

~~$$U_{k+1} = U_k + h A U_k$$~~

$$U^* = U_k + h A U_k$$

$$U_{k+1} = U_k + \frac{h}{2} (A U_k + A U^*)$$

- (i) what is the order of accuracy of the approximation.
- (ii) Derive the growth factor
- (iii) what is the region of absolute stability.

7) Write down the RK4 approximation of (*) and (+), respectively.

8) Show that the numerical approximation (RK4) of (*) and (+) correspond to a truncated Taylor series expansion of the solution.

9) What is the truncation error

10)

5)
Consider the second order ODE

$$\left. \begin{aligned} \frac{d^2 u}{dt^2} + \beta \frac{du}{dt} + K^2 u &= 0, \\ u(0) &= f, \quad \frac{du}{dt}(0) = g, \end{aligned} \right\} \text{--- } \textcircled{++}$$

where β and K are real parameters.

10) Rewrite $\textcircled{++}$ as a first-order system

$$\frac{d\bar{u}}{dt} = A \bar{u} \text{ --- } \textcircled{+++}$$

11) Determine the matrix A and the initial condition $\bar{u} = 0$?

12) Determine the conditions on β for which $\textcircled{+++}$ is

- a) unstable
- b) stable
- c) asymptotically stable.

13) Let $\beta < 0$ and approximate $\textcircled{+++}$ with a one-step method

$$u_{k+1} - u_k - (t_{k+1} - t_k) \bar{\Phi}(t_k, u_k) = 0$$

i) $\bar{\Phi}(t_k, u_k) = A u_k$

ii) $\bar{\Phi}(t_k, u_k) = \frac{1}{2} (A u_k + A(u_k + A u_k))$

For (i) and (ii)

~~Determine~~

- Determine the truncation error
- What is the order of accuracy
- Determine the growth factor and the region of absolute stability.
- What is the maximum time-step required for stability.

(14) Consider the discretization of $(++)$

$$\frac{u_{k+1} - 2u_k + u_{k-1}}{h^2} + \beta \frac{u_{k+1} - u_{k-1}}{2h} + K^2 u_k = 0$$

- What is the truncation error and the order of accuracy.
- Is this a one-step or two-step method why?
- Is this method explicit or Implicit.
- In particular if $\beta = 0$? explicit or Implicit
- What is the maximum time-step required for stability.