

CS 615 – Deep Learning

Artificial Neurons

Slides adapted from material created by E. Alpaydin Prof. Mordohai, Prof. Greenstadt, Pattern Classification (2nd Ed.), Pattern Recognition and Machine Learning



Objectives

- Artificial Neurons
- Evaluating a classifier
- Logistic activation function
- Log likelihood objective function
- Softmax activation function with cross entropy objective function



Artificial Neurons

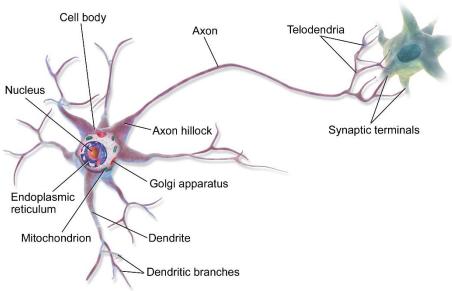
- In the previous material (on **linear regression**) we discussed the idea of estimating an output value as $\hat{y} = g(x) = x\theta$ where θ is a vector of parameters.
- And to learn the values of these parameters, we can start with an initial guess, and iteratively update them based on the gradient of the least squared error.
- But what if the output was a binary value?
 - Or a probability?
- Then we could use it for binary classification!



Artificial Neurons

• A simple "network" that takes the weighed sum of the inputs, $x\theta$ and applies some function to it is called an *artificial* neuron

• These are the building blocks of artificial and deep networks.





Artificial Neurons

- Technically a linear regression module is an artificial neuron.
- The function that processes $x\theta$ is referred to as the activation function
- For linear regression this was the linear activation function:

$$g(x) = x\theta$$

- At this time we're also going to move to the notation $g(x|\theta)$ for reasons seen later.
- A non-linear activation function is the threshold/step function:

$$g(x) = x\theta > t$$

An artificial neuron that uses this is referred to as a perceptron.



Artificial Neurons for Classification

- Now we want to use artificial neurons for classification.
- In doing so we'll have several decisions:
 - 1. What is our activation function?
 - 2. What is our objective function?
- Both of these give rise to a particular gradient rule used to learn the model's parameters.
- Let's look at a few common combinations....



Finding the Weights

- Let's start with the squared error objective function.
- Recall that given some function $g(x|\theta)$, for a single observation, (x,y), we can generalize the squared error as:

$$J = (y - \hat{y})^2 = (y - g(x|\theta))^2$$

• The gradient of this, with respect to a single parameter θ_i , is then:

$$\frac{\partial J}{\partial \theta_i} = -2 \left(\frac{\partial}{\partial \theta_i} g(x|\theta) \right) \left(y - g(x|\theta) \right)$$



Gradient of SE

$$\frac{\partial J}{\partial \theta_i} = -2\left(\frac{\partial}{\partial \theta_i}g(x|\theta)\right)\left(y - g(x|\theta)\right)$$

- So we obviously need to find the partial derivative of g with respect to θ_i
 - Note: With linear regression, $g(x|\theta) = x\theta$ and therefore $\frac{\partial}{\partial \theta_i} g(x|\theta) = x_i$
 - Which results in a gradient of $\frac{\partial J}{\partial \theta_i} = -2x_i(y x\theta)$
- So what is $\frac{\partial}{\partial \theta_i} g(x|\theta)$ when $g(x|\theta) = x\theta > 0$?



Update Rule

$$\frac{\partial J}{\partial \theta_i} = -2 \left(\frac{\partial}{\partial \theta_i} g(x|\theta) \right) \left(y - g(x|\theta) \right)$$

- So what is $\frac{\partial}{\partial \theta_i} g(x|\theta)$ when $g(x|\theta) = x\theta > 0$?
- There's basically two cases:
 - Case 1: When $x\theta > 0$

•
$$\frac{\partial}{\partial \theta_i} g(x|\theta) = x_i$$

- Case 2: When $x\theta \leq 0$
 - $\frac{\partial}{\partial \theta_i} g(x|\theta) = 0$
- Therefore:

$$\frac{\partial}{\partial \theta_i}(x\theta > 0) = \begin{cases} x_i & if \ x\theta > 0 \\ 0 & otherwise \end{cases}$$



Update Rule

$$\frac{\partial}{\partial \theta_i}(x\theta > 0) = \begin{cases} x_i & \text{if } x\theta > 0\\ 0 & \text{otherwise} \end{cases}$$

• Plugging this back into $\frac{\partial J}{\partial \theta_i} = -2\left(\frac{\partial}{\partial \theta_i}g(x|\theta)\right)\left(y - g(x|\theta)\right)$ we get our gradient update rule for SE with perceptrons as:

$$\frac{\partial J}{\partial \theta_i} = \begin{cases} -2x_i(y-1) & if \ x\theta > 0 \\ -2x_iy & otherwise \end{cases}$$

Which we can also write as:

$$\frac{\partial J}{\partial \theta_i} = \begin{cases} 2x_i(1-y) & if \ x\theta > 0 \\ -2x_iy & otherwise \end{cases}$$

• We can vectorize the parameters:

$$\frac{\partial J}{\partial \theta} = \begin{cases} 2x^{T}(1-y) & \text{if } x\theta > 0 \\ -2x^{T}y & \text{otherwise} \end{cases}$$



Logistic Activation Function

- Let's take a look at another activation function.
- An activation function this is non-linear, but differentiable, is the logistic function (sometimes known as the sigmoid or logit function):

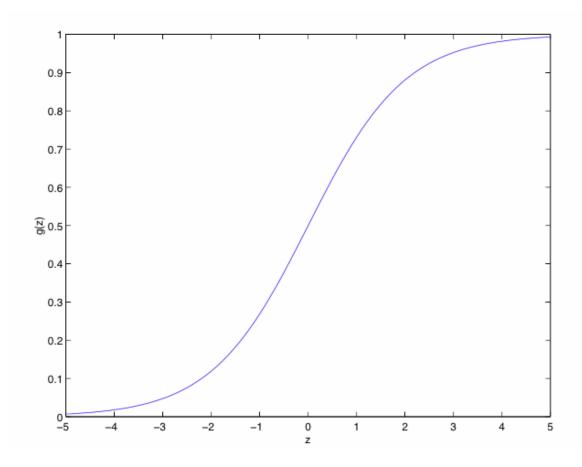
$$g(x|\theta) = \frac{1}{1 + e^{-x\theta}}$$



Logistic Function

- The logistic function, defined as $g(z) = \frac{1}{1+e^{-z}}$ tends towards 0 as z decreases and tends towards 1 as z increases
- For our purposes $z = x\theta$ and therefore our activation function is:

$$g(x|\theta) = \frac{1}{1 + e^{-x\theta}}$$





Logistic Function

- Let's see how we can use the logistic function, with the least squared error objective function, to define our gradient rule!
- Recall for the LSE:

$$J = (y - \hat{y})^2 = (y - g(x|\theta))^2$$

And the gradient of this is:

$$\frac{\partial J}{\partial \theta_i} = -2\left(\frac{\partial}{\partial \theta_i}g(x|\theta)\right)\left(y - g(x|\theta)\right)$$

• What is $\frac{\partial}{\partial \theta_i} g(x|\theta)$ for the logistic activation function?



Derivative of Logistic Function

•
$$\frac{\partial}{\partial \theta_i} g(x|\theta) = \frac{\partial}{\partial \theta_i} \left(\frac{1}{1 + e^{-x\theta}} \right) = \frac{\partial}{\partial \theta_i} \left(1 + e^{-x\theta} \right)^{-1}$$

• =
$$-1(0 - x_i e^{-x\theta})(1 + e^{-x\theta})^{-2} = \frac{x_i e^{-x\theta}}{(1 + e^{-x\theta})^2}$$

$$\bullet = x_i \frac{1}{1 + e^{-x\theta}} \frac{e^{-x\theta}}{1 + e^{-x\theta}}$$

• =
$$x_i g(x|\theta) (1 - g(x|\theta))$$



Gradient Rule w/ Logistic Function

• So when
$$g(x|\theta)$$
 is the logistic function, its partial derivative is:
$$\frac{\partial}{\partial \theta_i} g(x|\theta) = x_i g(x|\theta) \big(1 - g(x|\theta)\big)$$

• Plugging this back into $\frac{\partial J}{\partial \theta_i} = -2\left(\frac{\partial}{\partial \theta_i}g(x|\theta)\right)\left(y - g(x|\theta)\right)$ we get our gradient update rule for the SE of a perceptrons with a logistic activation function to be:

$$\frac{\partial J}{\partial \theta_i} = -2\left(x_i g(x|\theta) \left(1 - g(x|\theta)\right)\right) \left(y - g(x|\theta)\right)$$
$$= -2x_i \hat{y} (1 - \hat{y})(y - \hat{y})$$



Gradient Rule w/ Logistic Function

$$\frac{\partial J}{\partial \theta_i} = -2x_i \hat{y} (1 - \hat{y})(y - \hat{y})$$

- Now let's try to vectorize!
- Vectorizing over all parameters is now:

$$\frac{\partial J}{\partial \theta} = -2x^T \hat{y} (1 - \hat{y})(y - \hat{y})$$

And our batch gradient update is:

$$\frac{\partial J}{\partial \theta} = -\frac{2}{N} X^T \hat{Y} (1 - \hat{Y})^T (Y - \hat{Y})$$



Gradient Rule w/ Logistic Function

$$\frac{\partial J}{\partial \theta} = -\frac{2}{N} X^T \hat{Y} (1 - \hat{Y})^T (Y - \hat{Y})$$

- Ok, at least this isn't piecewise/conditional!
- But it's not too pretty.
- There are other objective functions that are (often) better suited for classification.
- One such function is called the log likelihood



Log Likelihood

• Given a observation (x, y), we can compute the **likelihood** that we are correct as

$$\ell = (\hat{y})^y (1 - \hat{y})^{(1-y)} = (g(x|\theta))^y (1 - g(x|\theta))^{(1-y)}$$

- Our technique will of course be to find the gradient of this with respect to one of the parameters.
- However, this can be made easier if we first take the log of this.
- Recall
 - The log of a product is the sum of its logs: ln(mn) = ln(m) + ln(n)
 - The log of an exponent is the exponent times the log of its base: $ln(a^x) = xln(a)$

• Therefore our log likelihood objective function is:
$$J = \ln(\ell) = y \ln(g(x|\theta)) + (1-y) \ln(1-g(x|\theta))$$



To Maximum Likelihood

$$J = y \ln(g(x|\theta)) + (1-y) \ln(1-g(x|\theta))$$

• First off, a reminder...

$$\frac{\partial}{\partial x}(\ln x) = \frac{1}{x} \cdot \frac{\partial}{\partial x}(x)$$

Therefore

$$\frac{\partial J}{\partial \theta_i} = \left(\frac{\partial}{\partial \theta_i} g(x|\theta)\right) \frac{y}{g(x|\theta)} + \left(\frac{\partial}{\partial \theta_i} \left(1 - g(x|\theta)\right)\right) \frac{(1 - y)}{1 - g(x|\theta)}$$

• And of course $\frac{\partial}{\partial \theta_i} g(x|\theta)$ depends on what our activation function $g(x|\theta)$ is.



To Maximum Likelihood

$$\frac{\partial J}{\partial \theta_i} = \left(\frac{\partial}{\partial \theta_i} g(x|\theta)\right) \frac{y}{g(x|\theta)} + \left(\frac{\partial}{\partial \theta_i} \left(1 - g(x|\theta)\right)\right) \frac{(1-y)}{1 - g(x|\theta)}$$

 If we choose the logistic function to be our activation function, its partial derivative is:

$$\frac{\partial}{\partial \theta_i} g(x|\theta) = x_i g(x|\theta) (1 - g(x|\theta))$$

And therefore our gradient is just:

$$\frac{\partial J}{\partial \theta_i} = x_i (y - g(x|\theta)) = x_i (y - \hat{y})$$



To Maximum Likelihood

$$\frac{\partial J}{\partial \theta_i} = x_i (y - \hat{y})$$

Vectorizing this for all parameters we have

$$\frac{\partial J}{\partial \theta} = x^T (y - \hat{y})$$

And our batch gradient is just:

$$\frac{\partial J}{\partial \theta} = \frac{1}{N} X^T (Y - \hat{Y})$$

- What we just derived (maximizing the log likelihood based on the output of a logistic function) is called logistic regression
 - Which is confusing since it's actually used for classification, not regression.
 - Nevertheless...



Gradient Ascent Rule

- One last thing!
- Since we want to *maximize* the log likelihood, we want to *add* some amount of the gradient to the parameters.

$$\theta \coloneqq \theta + \eta \frac{\partial J}{\partial \theta}$$



Evaluation

- How do we evaluate when we're doing classification?
- I suppose we could use the RMSE, but that may make less sense.
- We could just count how often we predict the correct class
 - We call this accuracy.
 - Let Y_i be the true class, and \widehat{Y}_i be the predicted class for observation i.

$$accuracy = \frac{1}{N} \sum_{i=1}^{N} (Y_i == \widehat{Y}_i)$$



Class Priors

- It's also important to have some sort of baseline accuracy.
- The class prior is the likelihood (probability) of a class.
- So for our baseline, we can just use the highest of the class priors.
 - Since naively assigning all test samples that class, would result in that accuracy.



Binary Classification Error Types

- If we're doing binary classification (just two classes), then there's some additional evaluations we can do.
- In binary classification, often we're focused on attempting to "find" one particular class.
 - We refer to this as the positive class.
 - The other data is called the negative class.
- From this we can describe four different possibilities:
 - True positive = Hit
 - True negative = Correct rejection
 - False positive = False Alarm (Type 1 error)
 - False negative = Miss (Type 2 error)

	Predicted positive	Predicted negative	
Positive	True positives	False negatives	
examples			
Negative	False positives	True negatives	
examples			



Evaluating your Classifier

- From the four error types, we can establish some binary-classificationspecific measurements:
- Precision percentage of things that were classified as positive and actually were positive
 - $Precision = \frac{TP}{TP+FP}$
- Recall the percentage of true positives (sensitivity) correctly identified

•
$$Recall = \frac{TP}{TP+FN}$$

• f-measure – The weighted harmonic mean of precision and recall

•
$$F_1 = \frac{2*precision*recall}{precision+recall}$$



Evaluating your Classifier

- Related to this, we sometimes will look at the true positive rate vs the false positive rate
 - The true positive rate is

$$TPR = Recall = \frac{TP}{TP + FN}$$

The false positive rate is

$$FPR = \frac{FP}{FP + TN}$$



Logistic Regression Example

• Let's classifying whether a person will buy a product or not

	Y	X-Variables							
							(Omit-	Prev	Prev
Obs.			Is	Is	Has	Is Pro-	ted Vari-	Child	Parent
No.	Buy	Income	Female	Married	College	fessional	ables)	Mag	Mag
1	0	24000	1	0	1	1		0	0
2	1	75000	1	1	1	1		1	0
3	0	46000	1	1	0	0		0	0
4	1	70000	0	1	0	1		1	0
5	0	43000	1	0	0	0		0	1
6	0	24000	1	1	0	0		0	0
7	0	26000	1	1	1	0		0	0
8	0	38000	1	1	0	0		0	0
9	0	39000	1	0	1	1		0	0
10	0	49000	0	1	0	0		0	0
-	-		-	-	-	-			-
-	-		-			-		-	
:					:				:
654	0	10000	1	0	0	0		0	0
655	1	75000	0	1	0	1		0	0
656	0	72000	0	0	1	0		0	0
657	0	33000	0	0	0	0		0	0
658	0	58000	0	1	1	1		0	0
659	1	49000	1	1	0	0		0	0
660	0	27000	1	1	0	0		0	0
661	0	4000	1	0	0	0		0	0
662	0	40000	1	0	1	1		0	0
663	0	75000	1	1	1	0		0	0
664	0	27000	1	0	0	0		0	0
665	0	22000	0	0	0	1		0	0
666	0	8000	1	1	0	0		0	0
667	1	75000	1	1	1	0		0	0
668	0	21000	0	1	0	0		0	0
669	0	27000	1	0	0	0		0	0
670	0	3000	1	0	0	0		0	0
671	1	75000	1	1	0	1		0	0
672	1	51000	1	1	0	1		0	0
673	0	11000	0	1	0	0		0	0

KidCreative.csv



Logistic Regression Example

- Make some design decisions:
 - Randomize data
 - Use 2/3 training, 1/3 testing
 - Standardize features
 - Add bias feature
 - Initialize parameters to random values in the range [-1, 1]
 - Since our equation is based on log likelihood, let's terminate when change in sum of log likelihoods doesn't change more than eps
 - Recall the log likelihood of an example being correct is

$$y \ln\left(\frac{1}{1 + e^{-x\theta}}\right) + (1 - y) \ln\left(1 - \frac{1}{1 + e^{-x\theta}}\right)$$

- But be careful... log(0) = -Inf. So you might need to deal with this somehow
- Let's dynamically allow the learning parameter η to adapt!
- Let's do batch regression



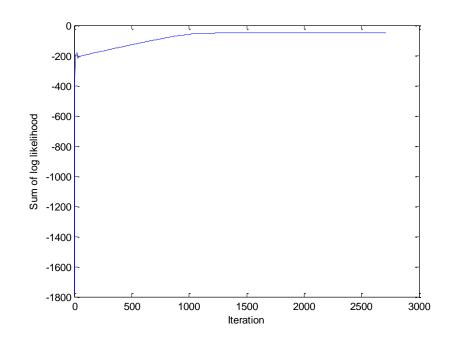
Example

 θ = -12.7663 5.1987 0.9057 0.6136 0.0880 -0.3606 -0.4920 -29.3976 0.2140 -0.0329 0.7355 0.3957 0.0054 0.9061 1.1647 0.1887 0.1881

Choosing Class 1 if $g_{\theta}(x) \ge 0.5$ we get:

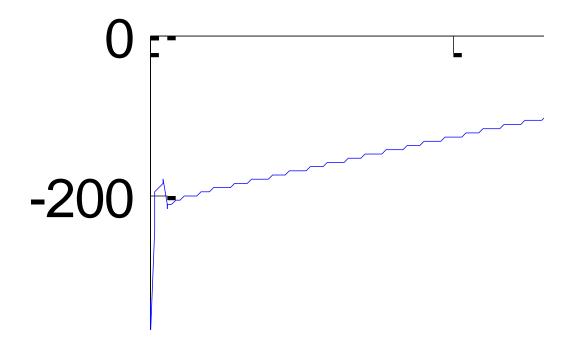
Precision: 0.7708 Recall: 0.7551

F-Measure: 0.7629





Example





Multiple Classes

- What if we had multiple classes to decide among?
- There are ways that we can make this decision using a bunch of binary classifiers, but let's look at how we can do this directly.



Multi-Class MLE + Logistic Activation

- In order to do multi-class classification, there will be three main changes:
 - 1. Our target for each observation will now be a binary vector. Therefore $Y \in \mathcal{R}^{N \times K}$
 - 2. Likewise, our estimations will be a vector: $\hat{y} \in \mathcal{R}^{1 \times K}$
 - 3. And finally, our parameters will now be a $D \times K$ matrix
- Given all of this, lets adapt our maximum likelihood with logistic activation equations and gradient rules for multi-class classification:

$$\ell_{\theta}(x,y) = \prod_{k=1}^{K} g(x|\theta_{:,k})^{y_k} \left(1 - g(x|\theta_{:,k})\right)^{(1-y_k)}$$

Taking the log of this we get our objective function:

$$J = \sum_{k=1}^{K} y_k \ln(g(x|\theta_{:,k})) + (1 - y_k) \ln(1 - g(x|\theta_{:,k}))$$



Multi-Class MLE + Logistic Activation

$$J = \sum_{k=1}^{K} y_k \ln (g(x|\theta_{:,k})) + (1 - y_k) \ln (1 - g(x|\theta_{:,k}))$$

- Now we need to find the gradient with respect to each $\theta_{i,k}$, i.e $\frac{\partial J}{\partial \theta_{i,k}}$
- Fortunately, the only term of the summation that will contribute is when k=k.
- Therefore we have:

$$\frac{\partial J}{\partial \theta_{i,k}} = x_i \left(y_k - g(x|\theta_{:,k}) \right) = x_i (y_k - \hat{y}_k)$$



Multi-Class MLE + Logistic Activation

$$J = \sum_{k=1}^{K} y_k \ln (g(x|\theta_{:,k})) + (1 - y_k) \ln (1 - g(x|\theta_{:,k}))$$

$$\frac{\partial J}{\partial \theta_{i,k}} = x_i (y_k - \hat{y}_k)$$

• Vectorizing this for all i, k we get the matrix:

$$\frac{\partial J}{\partial \theta} = x^T (y - \hat{y})$$

And the batch version would be

$$\frac{\partial J}{\partial \theta} = \frac{1}{N} X^T (Y - \hat{Y})$$



Multi-Class Evaluation

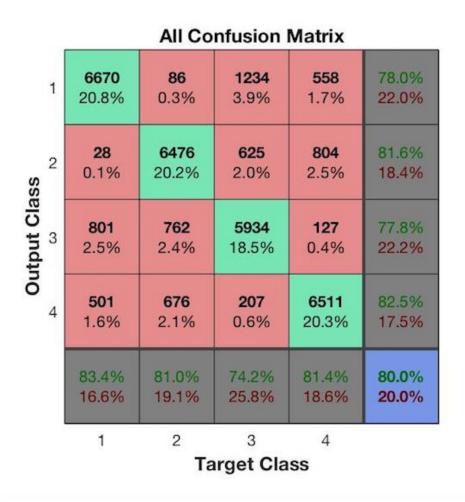
• Just like binary classification, we can evaluate the accuracy of a multiclass classifier:

$$accuracy = \frac{1}{N} \sum_{i=1}^{N} (Y_i == \widehat{Y}_i)$$

- In addition, particular to multi-class classification, we may be interested in investigating which classes get confused with which other classes
- To observe this, we can look at a confusion matrix

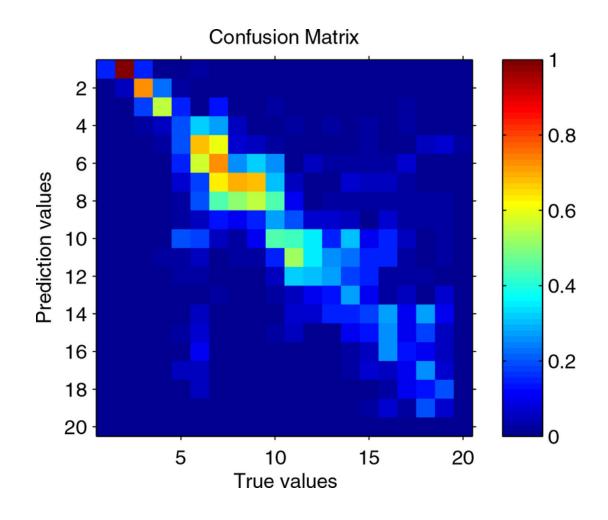


Confusion Matrix





Confusion Matrix





Additional Objective Functions

- Another common objective function for multi-class classification is cross entropy
- So let's take a look at that.
- But to do this, we must first learn about the *softmax* activation function.



Softmax

- It is sometimes advantageous to be able to think of the output values as class probabilities.
- To be a valid distribution, we want these outputs to sum to one.
- The softmax function does this!
- The softmax function gives us back the probability of an observation belonging to class j, which we'll indicate as \hat{y}_i .
- This is computed as:

$$P(y = j) = \hat{y}_j = \frac{e^{x\theta_{:,j}}}{\sum_{k=1}^{K} e^{x\theta_{:,k}}}$$



Entropy

- Entropy measure the randomness in a system.
- Given a probability distribution $p=(p_1,p_2,...p_K)$ such that $\sum_{k=1}^K p_k=1$, the entropy is computed as:

$$H = \sum_{k=1}^{K} -p_k \ln p_k$$



Cross Entropy Loss

• If we have two distributions, a, b and want to compare them, we can use *cross* entropy:

$$H = \sum_{k=1}^{K} -a_k \ln b_k$$

• If we consider our target outputs to be and our output is from the softmax activation function (or really any activation function the provides a valid output probability), then we can compute the *cross-entropy loss objective function*:

$$J = -\sum_{k=1}^{K} y_k \ln(\hat{y}_k)$$



Cross Entropy Loss

$$J = -\sum_{k=1}^{K} y_k \ln(\hat{y}_k)$$

• Since typically our y distribution will be all zeros, with just one location having a probability of one (say $y_a=1$) then this simplifies to:

$$J = -\ln(\hat{y}_a)$$



Gradient of Softmax with Cross Entropy

- Now we need to find the update rule for all the parameters $\theta_{i,j}$, i.e $\frac{\partial f}{\partial \theta_{i,j}}$, when we have a softmax function and cross entropy objective function.
- In order to do this, we need to write our cross-entropy objective function in terms of θ

$$J = -\ln(\hat{y}_a)$$

$$J = -\ln\left(\frac{e^{x\theta_{:,a}}}{\sum_{k=1}^{K} e^{x\theta_{:,k}}}\right)$$



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Gradient of Cross Entropy

$$J = -\ln\left(\frac{e^{x\theta_{:,a}}}{\sum_{k=1}^{K} e^{x\theta_{:,k}}}\right)$$

• Now we can take the partial gradient of this with respect to a parameters $\theta_{i.i}$:

$$\frac{\partial J}{\partial \theta_{i,j}} = -\frac{\sum_{k=1}^{K} e^{x\theta_{:,k}}}{e^{x\theta_{:,a}}} \left(\frac{\partial}{\partial \theta_{i,j}} \left(\frac{e^{x\theta_{:,a}}}{\sum_{k=1}^{K} e^{x\theta_{:,k}}} \right) \right)$$

Now again there will be two cases



Gradient of Cross Entropy

$$\frac{\partial J}{\partial \theta_{i,j}} = -\frac{\sum_{k=1}^{K} e^{x\theta_{:,k}}}{e^{x\theta_{:,a}}} \left(\frac{\partial}{\partial \theta_{i,j}} \left(\frac{e^{x\theta_{:,a}}}{\sum_{k=1}^{K} e^{x\theta_{:,k}}} \right) \right)$$

• Case 1: $j \neq a$

$$\frac{\partial J}{\partial \theta_{i,j}} = -\frac{\sum_{k=1}^{K} e^{x\theta_{:,k}}}{e^{x\theta_{:,a}}} \left(\frac{\left(0 \sum_{k=1}^{K} e^{x\theta_{:,k}}\right) - \left(e^{x\theta_{:,a}} x_{i} e^{x\theta_{:,j}}\right)}{\left(\sum_{k=1}^{K} e^{x\theta_{:,k}}\right)^{2}} \right)$$

$$= \frac{\sum_{k=1}^{K} e^{x\theta_{:,k}}}{e^{x\theta_{:,a}}} \left(\frac{e^{x\theta_{:,a}} x_i e^{x\theta_{:,j}}}{\left(\sum_{k=1}^{K} e^{x\theta_{:,k}}\right)^2} \right) = \frac{x_i e^{x\theta_{:,j}}}{\sum_{k=1}^{K} e^{x\theta_{:,k}}} = x_i \hat{y}_j$$



Gradient of Cross Entropy

$$\frac{\partial J}{\partial \theta_{i,j}} = -\frac{\sum_{k=1}^{K} e^{x\theta_{:,k}}}{e^{x\theta_{:,a}}} \left(\frac{\partial}{\partial \theta_{i,j}} \left(\frac{e^{x\theta_{:,a}}}{\sum_{k=1}^{K} e^{x\theta_{:,k}}} \right) \right)$$

• Case 2: j = a

$$\frac{\partial J}{\partial \theta_{i,j}} = -\frac{\sum_{k=1}^{K} e^{x\theta_{:,k}}}{e^{x\theta_{:,a}}} \left(\frac{(x_i e^{x\theta_{:,j}} \sum_{k=1}^{K} e^{x\theta_{:,k}}) - (e^{x\theta_{:,j}} x_i e^{x\theta_{:,j}})}{(\sum_{k=1}^{K} e^{x\theta_{:,k}})^2} \right)$$

$$= \frac{x_i(e^{x\theta_{:,j}} - \sum_{k=1}^K e^{x\theta_{:,k}})}{\sum_{k=1}^K e^{x\theta_{:,k}}} = x_i(\hat{y}_j - 1)$$

• Thus:

$$\frac{\partial J}{\partial \theta_{i,j}} = \begin{cases} x_i \hat{y}_j & \text{if } j \neq a \\ x_i (\hat{y}_j - 1) & \text{Otherwise} \end{cases}$$
Matt Burlick, Drexel University

A: The night class.



Gradient of Cross Entropy

$$\frac{\partial J}{\partial \theta_{i,j}} = \begin{cases} x_i \hat{y}_j & \text{if } j \neq a \\ x_i (\hat{y}_j - 1) & \text{Otherwise} \end{cases}$$

Since our target y is a binary vector, then we can write this as:

$$\frac{\partial J}{\partial \theta_{i,j}} = x_i (\hat{y}_j - y_j)$$

• If \hat{y} is the vector of predicted class probabilities, then we can vectorize this to update all the parameters at once as:

$$\frac{\partial J}{\partial \theta} = x^T (\hat{y} - y)$$

And to do batch updates:

$$\frac{\partial J}{\partial \theta} = X^T (\hat{Y} - Y)$$

Cost_function





Multi_class with binary classifer

 Given all of this, lets adapt our maximum likelihood with logistic activation equations and gradient rules for multi-class classification:

$$\ell_{\theta}(x,y) = \prod_{k=1}^{K} g(x|\theta_{:,k})^{y_k} \left(1 - g(x|\theta_{:,k})\right) \xrightarrow{(1-y_k)} \frac{\partial J}{\partial \theta} = \frac{1}{N} X^T (Y - \widehat{Y})$$

Softmax with Cross Entropy

$$H = \sum_{k=1}^{K} -a_k \ln b_k$$

$$J = -\sum_{k=1}^{K} y_k \ln(\hat{y}_k)$$

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• Since typically our y distribution will be all zeros, with just one location having a probability of one (say $y_a = 1$) then this simplifies to:

$$J = -\ln(\hat{y}_a)$$

$$\frac{\partial J}{\partial \theta_{i,j}} = \begin{cases} x_i \hat{y}_j & \text{if } j \neq a \\ x_i (\hat{y}_j - 1) & \text{Otherwise} \end{cases}$$

a: The right class.