UNIVERSITY OF CALIFORNIA SANTA CRUZ

A MOTION PLANNING PROBLEM FOR HYBRID SYSTEMS WITH APPLICATIONS

A thesis submitted in partial satisfaction of the requirements for the degree of

MASTER OF SCIENCE

in

ELECTRICAL AND COMPUTER ENGINEERING

by

Author1 Name

December 2018

oroved:	
Ricardo C	G. Sanfelice, Chair
Reader 1	
Reader 2	

Dean Name

Vice Provost and Dean of Graduate Studies

Copyright © by Author1 Name 2018

Table of Contents

List of Figures	iv
List of Tables	\mathbf{v}
Abstract	vi
Dedication	vii
1 Introduction	1
2 Results	2
3 Conclusion	3
Bibliography	4

List of Figures

List of Tables

Abstract

A Motion Planning Problem for Hybrid Systems with Applications

by

Author1 Name

A clear, concise abstract explaining the why, what, and how of your work.

A loving dedication.

Chapter 1

Introduction

Chapter 2

Results

Chapter 3

Conclusion

Bibliography