

UNIVERSITY OF CALIFORNIA
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**A MOTION PLANNING PROBLEM FOR HYBRID SYSTEMS
WITH APPLICATIONS**

A thesis submitted in partial satisfaction of the
requirements for the degree of

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in

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by

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Abstract

A Motion Planning Problem for Hybrid Systems with Applications

by

Author1 Name

A clear, concise abstract explaining the why, what, and how of your work.

A loving dedication.

Chapter 1

Introduction

Chapter 2

Results

Chapter 3

Conclusion

Bibliography