



The Education University of Hong Kong

SENSESTORM TRAINING



Network Setup & Preparations

WiFi Connection:

SSID: IoT

PW: eduhk+IoT+2018

Preparations: shorturl.at/jmpzG

Rundown

1. Introduction of SenseStorm and the experimental platform
2. Facial recognition and gesture recognition with computer vision techniques
3. Object Classification with Supervised Learning
4. Implementation with Teachable Machine models
5. Summary and Q&A



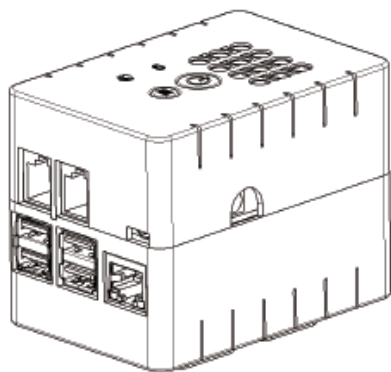
Section 1

Introduction of SenseStorm and experimental platform

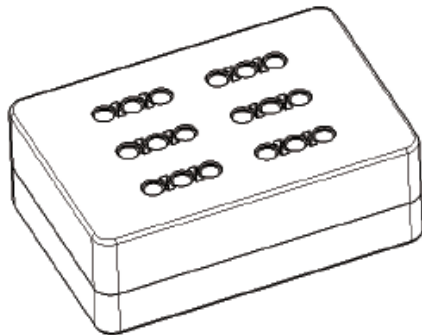


SenseStorm

SenseStorm主控



电池



Standalone
(VNC Viewer)

Learning Platform
(SenseStorm)

Components List

Main Control Board
(Raspberry Pi + SenseTime add-on board)

Camera

Color Sensor

Ultrasound Sensor

Battery

Charger

Speaker

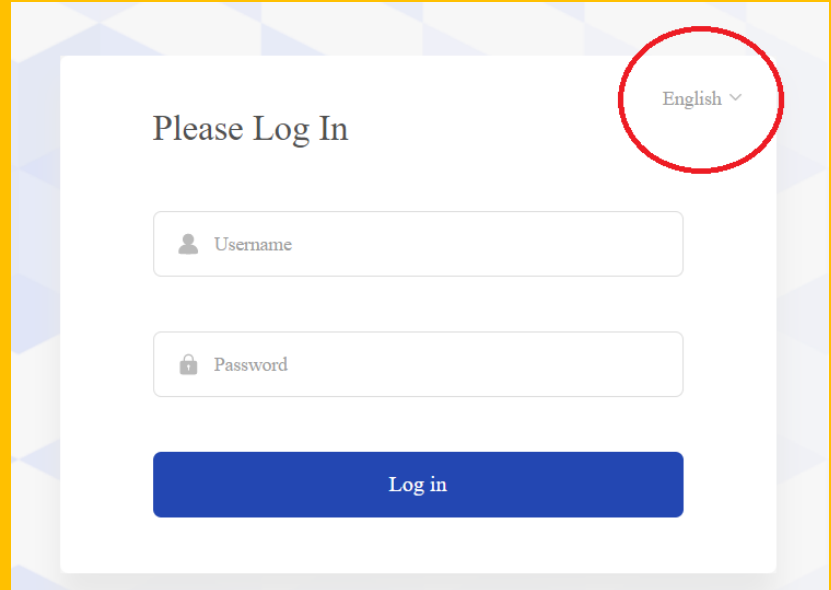
TF Card

SenseStudy Platform

Please login: hk.study.sensetime.com/course/login

Username:
eduhk01 ~ eduhk35

Password:
eduhk123



The screenshot shows the login interface of the SenseStudy Platform. It features a white login card on a light blue geometric background. At the top right of the card, there is a language selection dropdown menu labeled 'English' with a downward arrow, which is circled in red. The main heading of the card is 'Please Log In'. Below this, there are two input fields: the first is labeled 'Username' with a person icon, and the second is labeled 'Password' with a lock icon. At the bottom of the card is a prominent blue button labeled 'Log in'.

Logged

English ▾

STtrial01

Log Out

Please select the product you would like to use

v2.8

SenseStudy

v2.8

Download Center

Modify Password



Elementary AI, Volume I

4 Total Chapter(s) - 14 Total Lessons



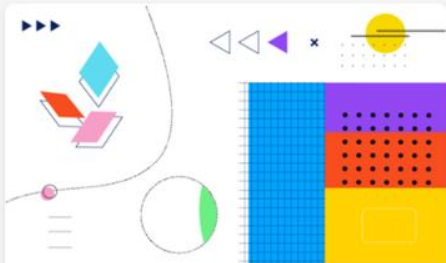
SenseStorm Workshop

2 Total Chapter(s) - 12 Total Lessons



Elementary AI, Volume II

4 Total Chapter(s) - 15 Total Lessons



gesture auto car

1 Total Chapter(s) - 1 Total Lessons

首頁 > SenseStorm Workshop



SenseStorm Workshop

共 2 章 12 節

全部

第 1 章

第 2 章



Introduction to SenseStorm: 智能小車的運動

未開始

第 1 章 第 1 節

開始挑戰



Introduction to SenseStorm: 使用揚聲器

未開始

第 1 章 第 2 節

開始挑戰



Introduction to SenseStorm: 使用顏色傳感器

未開始

第 1 章 第 3 節

開始挑戰



Introduction to SenseStorm: 使用超聲波傳感器

未開始

第 1 章 第 4 節

開始挑戰



Introduction to SenseStorm: 使用攝像

未開始



Introduction to SenseStorm: 智能巡

未開始

搜索你的硬件

SenseStorm - c12c0

SenseStorm - c171c3

首頁 > SenseStorm Workshop



SenseStorm Workshop

共 2 章 12 節

全部

第 1 章

第 2 章



Introduction to SenseStorm: 智能小車的運動

未開始

第 1 章 第 1 節

開始挑戰



Introduction to SenseStorm: 使用揚聲器

未開始

第 1 章 第 2 節

開始挑戰



Introduction to SenseStorm: 使用顏色傳感器

未開始

第 1 章 第 3 節

開始挑戰



Introduction to SenseStorm: 使用超聲波傳感器

未開始

第 1 章 第 4 節

開始挑戰



Introduction to SenseStorm: 使用攝像

未開始



Introduction to SenseStorm: 智能巡

未開始

搜索你的硬件

SenseStorm - cf12c0

SenseStorm - c171c3



Steps

1. Let's Build!

Please follow the construction manual (click [here](#) to download) to build the SenseStorm car and connect to SenseStorm.



2. run_time()

3. run()

4. Changing directions

5. Sleep()



Block



Python



Action



Detect



Output



Logic



Loops



Math



Text



Lists



Variables



Functions

Code

Run

Images

Terminal

Previous

1 / 5

Next

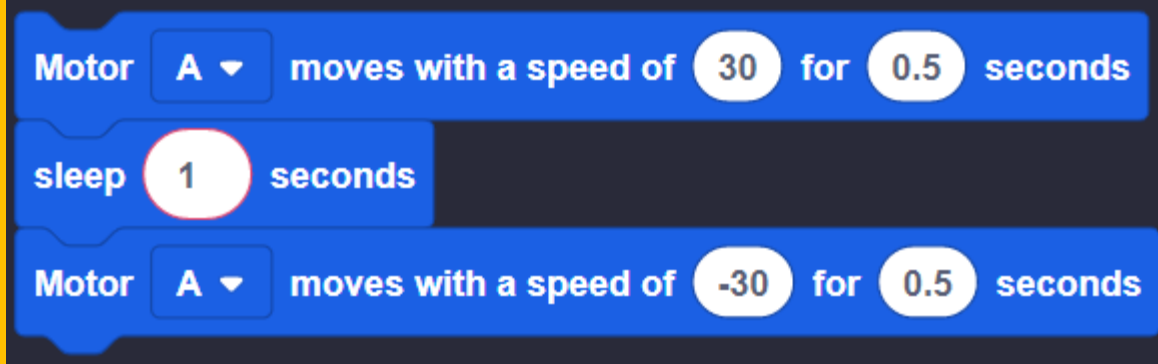
Explanation

Section 2

Facial recognition and gesture recognition with computer vision techniques

Basic operations

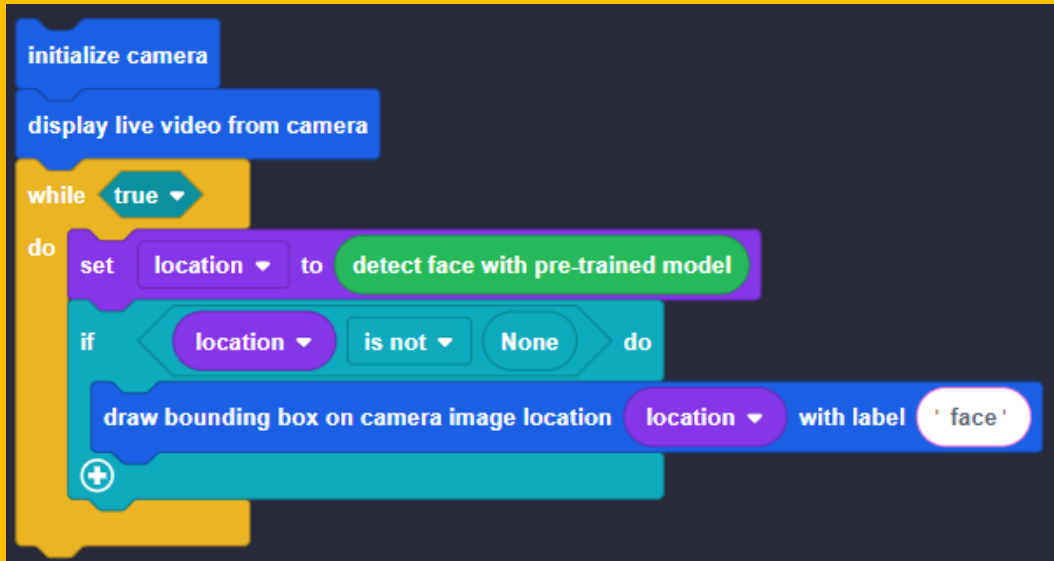
Basic operation of the motors



```
motor_a.run_time(30,0.5)  
sleep(1)  
motor_a.run_time(-30,0.5)
```

Basic operations

Face Detection



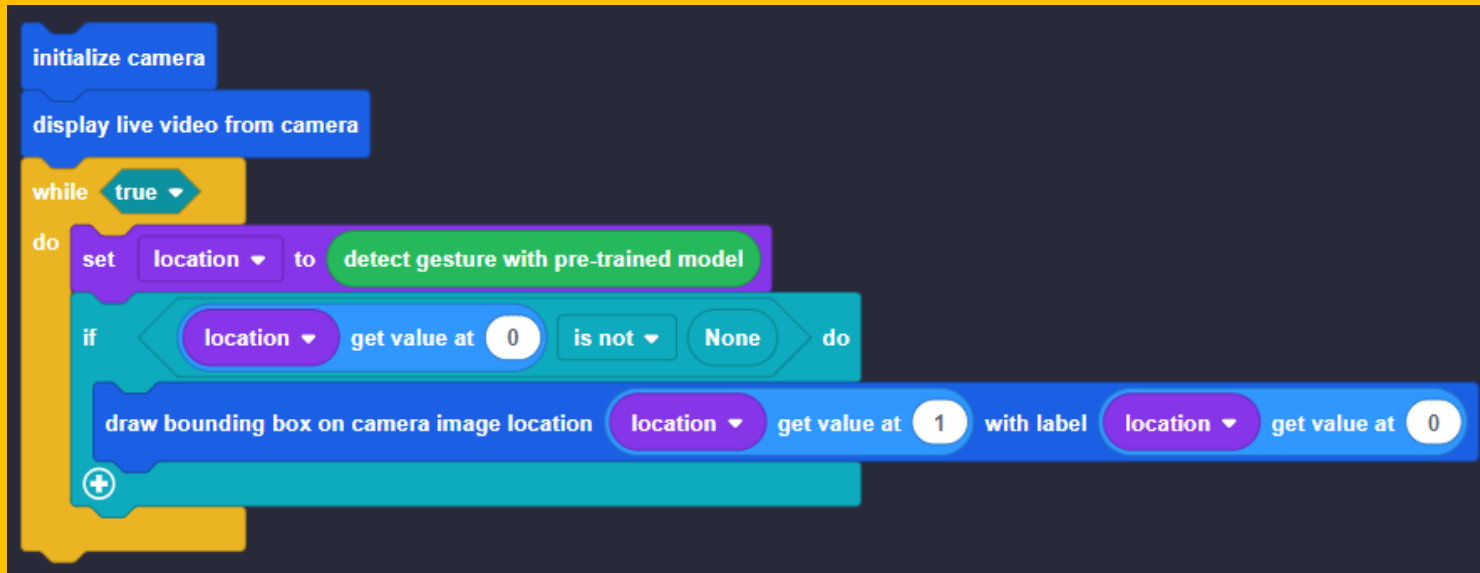
```
videostream=cv2.VideoCapture(0)  
display_video()
```

```
while True:  
    try:  
        location = detect_face(frame)  
        if location is not None:  
            draw_label_boundingbox(frame,  
location, 'face')  
    except:  
        break
```

```
clean_up()
```

Basic operations

Gesture Recognition



Basic operations

Gesture Recognition

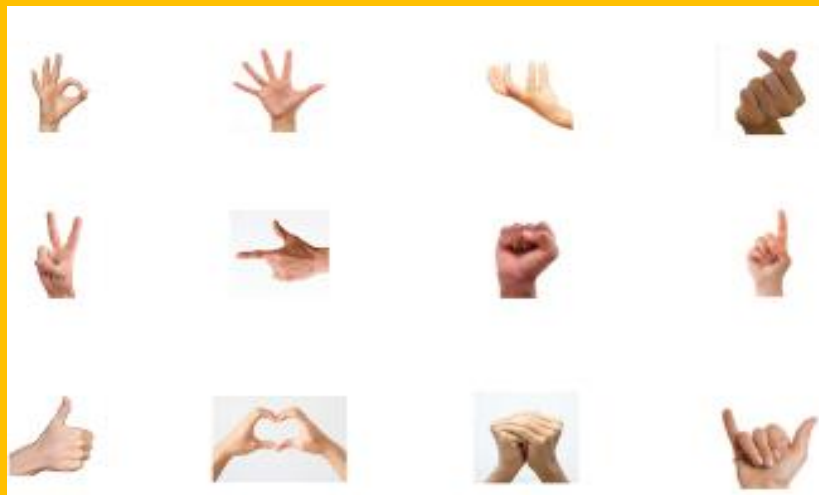
```
videostream=cv2.VideoCapture(0)  
display_video()
```

```
while True:  
    try:  
        location = extract_gesture(frame)  
        if location[0] is not None:  
            draw_label_boundingbox(frame, location[1], location[0])  
    except:  
        break
```

```
clean_up()
```


Basic operations

Gesture Recognition



手勢序號	手勢種類	手勢序號	手勢種類
0	"OK"	6	"GRAB"
1	"V"	7	"FIST"
2	"THUMB_UP"	8	"FIST_PALM_SALUTE"
3	"STOP"	9	"SINGLE_HAND_HEART"
4	"TICK"	10	"FOREFINGER_UP"
5	"HEART"	11	"SIX"

Section 3

Object Classification with Supervised Learning



Supervised Learning

Given a set of input/output pairs, learn to predict the output when given a new input.

= Learn by using model answers!

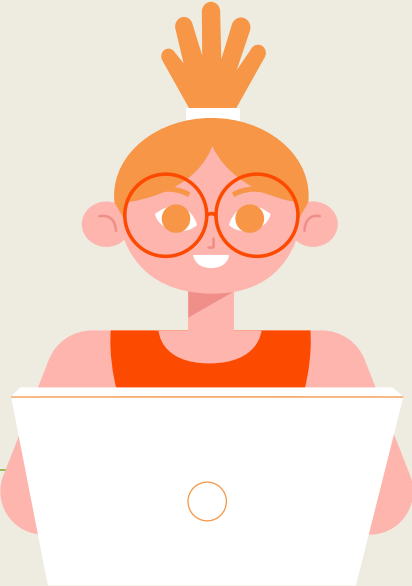




Unsupervised Learning

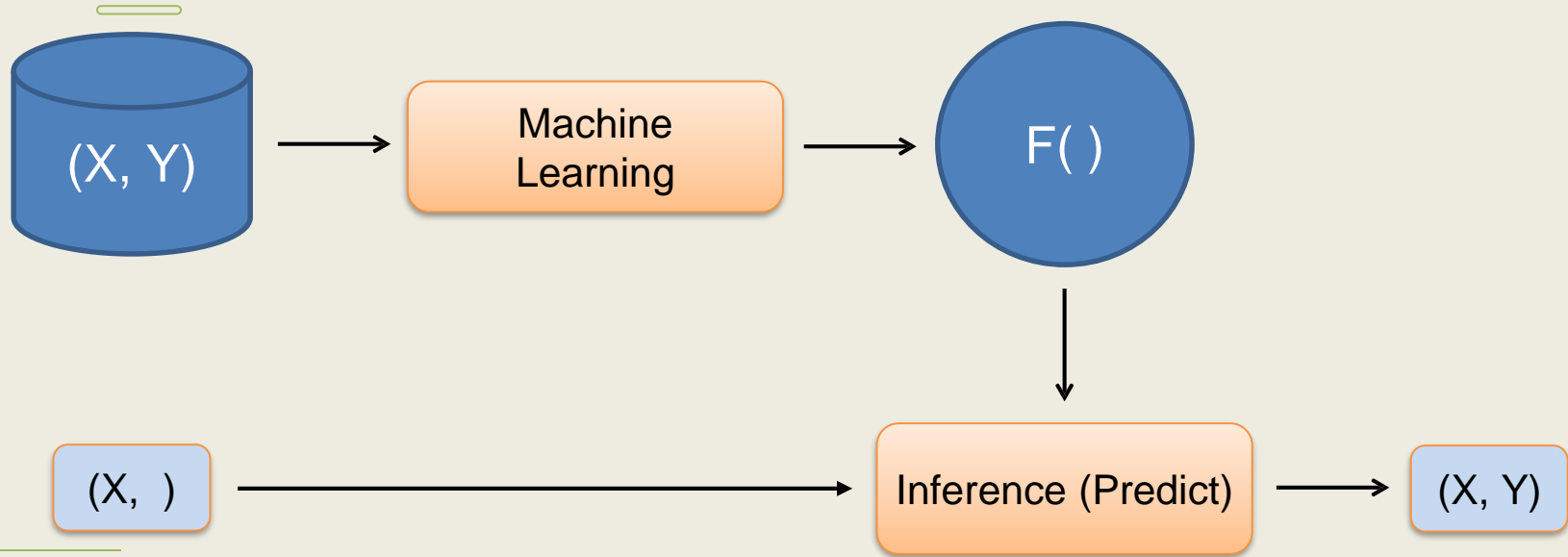
Given data without labels, model learns to group data with similar features together without knowing the true label of each group

= Learn by grouping similar things together!





Supervised Learning Procedure





Supervised Learning Procedure

Training Data Preparation: Images and labels



Data Pre-Processing: Features extraction



Model Training (to find $F(\cdot)$)



Testing Data Preparation: Images and labels



Model Testing ($Y = F(X)$)

SenseStudy Experiment



1

Practical implementation: Intelligent Classification Mini Car (SenseStorm Workshop 2.1)

2

3

4



SenseStorm Workshop

2 Total Chapter(s) - 12 Total Lessons



Lesson Grid:

Chapter	Lesson	Status	Action
Chapter 1	Introduction to SenseStorm: Controlling the Car's Movement	In Progress	Continue
	Introduction to SenseStorm: Using the Color Sensor	In Progress	Continue
	Introduction to SenseStorm: Using the Camera	In Progress	Continue
	SenseStorm Fun Projects: Intelligent Classification Mini Car	Completed	Restart
	SenseStorm Fun Projects: Smart Gate	In Progress	
Chapter 2	Introduction to SenseStorm: Using the Speaker	Not Started	Start
	Introduction to SenseStorm: Using the Ultrasonic Sensor	In Progress	Continue
	Introduction to SenseStorm: Integrated Exercise: Line Tracker	In Progress	Continue
	SenseStorm Fun Projects: Sorting Robot	Not Started	Start
	SenseStorm Fun Projects: Smart Fan	In Progress	



SenseStudy Experiment



1

Move USB image folder 'dog' into SenseStorm

Move USB image folder 'panda' into SenseStorm

Move USB image folder 'test' into SenseStorm

set label_dog to add labels 'dog' to all images in folder 'dog'

set label_panda to add labels 'panda' to all images in folder 'panda'

set labels to label_dog + label_panda

print labels

set img_dog to load images from folder 'dog'

set img_panda to load images from folder 'panda'

set imgs to img_dog + img_panda

show image imgs get value at 0

Training data preparation

set features to create an empty list

for each item item in list imgs

do set img_feature to extract image feature from item

append img_feature to list features

Data pre-processing

2

Model training

set handle to initialized classification model

use model handle, feature features, and label labels to train

3

set test_imgs to load images from folder 'test'

Use handle to classify objects in images list test_imgs

Use handle to classify objects in camera

Choose 1 from 2
Model testing

4



SenseStudy Experiment

Additional Task:

Real Face or Fake Face?

Ref video:

shorturl.at/lwS28

The script is organized into four numbered sections on the right side:

- 1. Setup:** Three blocks to move USB image folders into the SenseStorm environment: 'fake_face', 'real_face', and 'face_test'.
- 2. Data Loading:** A series of 'set' blocks. 'label_fake' is set to 'add labels' 'fake' to all images in folder 'fake_face'. 'label_real' is set to 'add labels' 'real' to all images in folder 'real_face'. 'labels' is set to a list containing 'label_fake' and 'label_real'. 'img_fake' is set to 'load images from folder' 'fake_face'. 'img_real' is set to 'load images from folder' 'real_face'. 'imgs' is set to a list containing 'img_fake' and 'img_real'. 'features' is set to 'create an empty list'.
- 3. Feature Extraction:** A 'for each item' loop over the 'imgs' list. Inside the loop, 'img_feature' is set to 'extract image feature from' the current 'item', and 'img_feature' is appended to the 'features' list.
- 4. Training and Testing:** 'handle' is set to 'initialized classification model'. A 'use model' block is used to train the model with 'handle', 'features', and 'labels'. 'test_imgs' is set to 'load images from folder' 'face_test'. Finally, 'Use' block is used to classify objects in the 'test_imgs' list using the 'handle' model.

Section 4

Implementation with Teachable Machine models



Teachable Machine Model Training

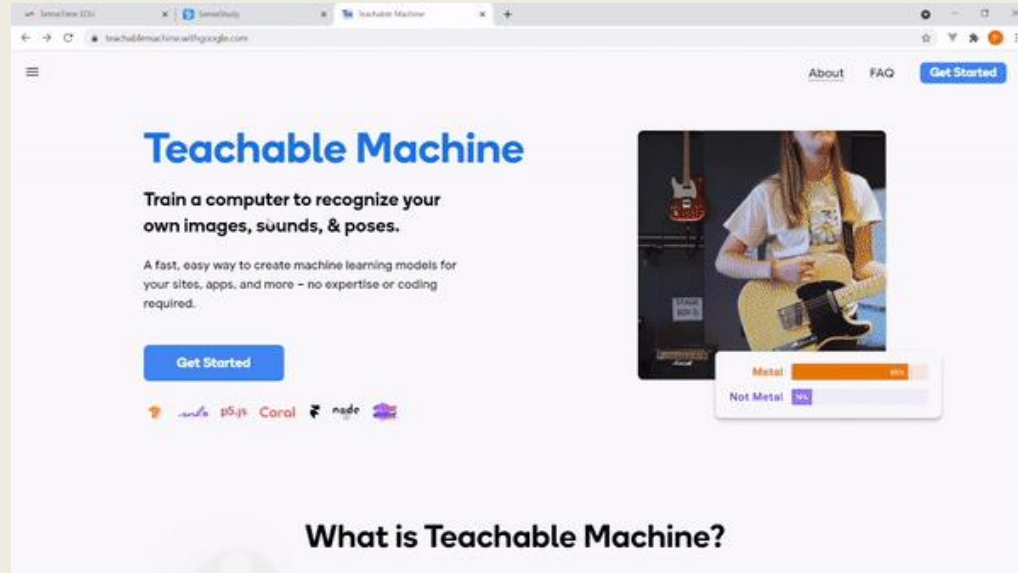


1

Training your own model: Step 1

Navigate to *Teachable Machine* and *Get Started*

2



3

4



Training your own model: Step 2

Choose *Image Project* and *Standard Image Model*

2

New Project

New Image Project

Standard image model

Best for most uses

224x224px color images

Export to TensorFlow, TFLite, and TF.js

Model size: around 5mb

Embedded image model

Best for microcontrollers

96x96px grayscale images

Export to TFLite for Microcontrollers, TFLite, and TF.js

Model size: around 500kb

[See what hardware supports these models.](#)

3

4



Teachable Machine Model Training

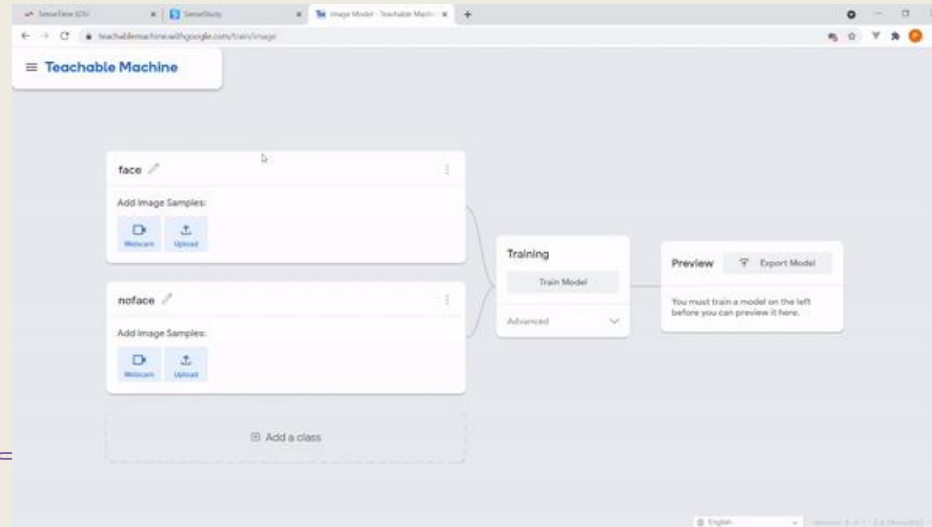


1

Training your own model: Step 3

1. Create and name a **Class**
2. Start **Collecting Data** (images of that class)

2



3

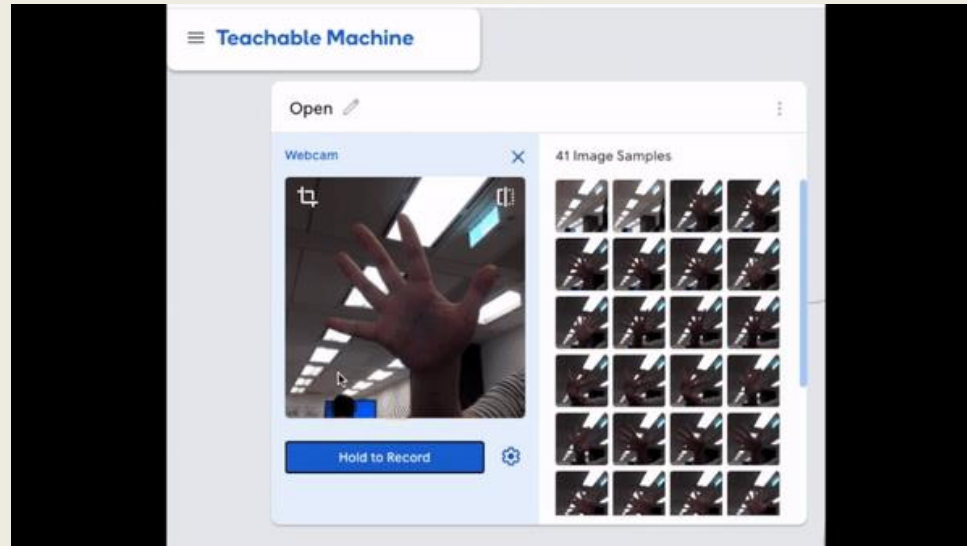
4



Training your own model: Step 3 (Cont'd)

3. Take/upload **multiple images**. Best if you use images of different angle, lighting, distance & background.

2



3

4



Teachable Machine Model Training

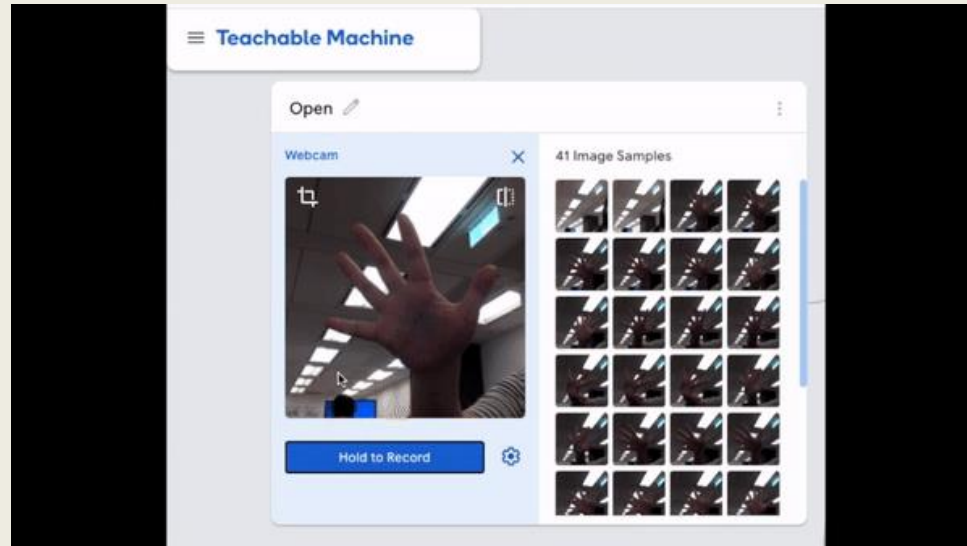


1

Training your own model: Step 4

Repeat step 3 for other classes as well (if any)

2



3

4



Teachable Machine Model Training



1

Training your own model: Step 5

Start *Training!*

Training

Training...

00:25 - 5 / 50

Advanced ^

Epochs: 50 ?

Batch Size: 16 ?

Learning Rate: 0.01 ?

Reset Defaults ⌚

Under the hood 📄

Teachable Machine

face

140 Image Samples

Webcam Upload

noface

Webcam

141 Image Samples

Hold to Record

Training

Train Model

Advanced

Preview

Export Model

You must train a model on the left before you can preview it here.

2

3

4



Teachable Machine Model Training

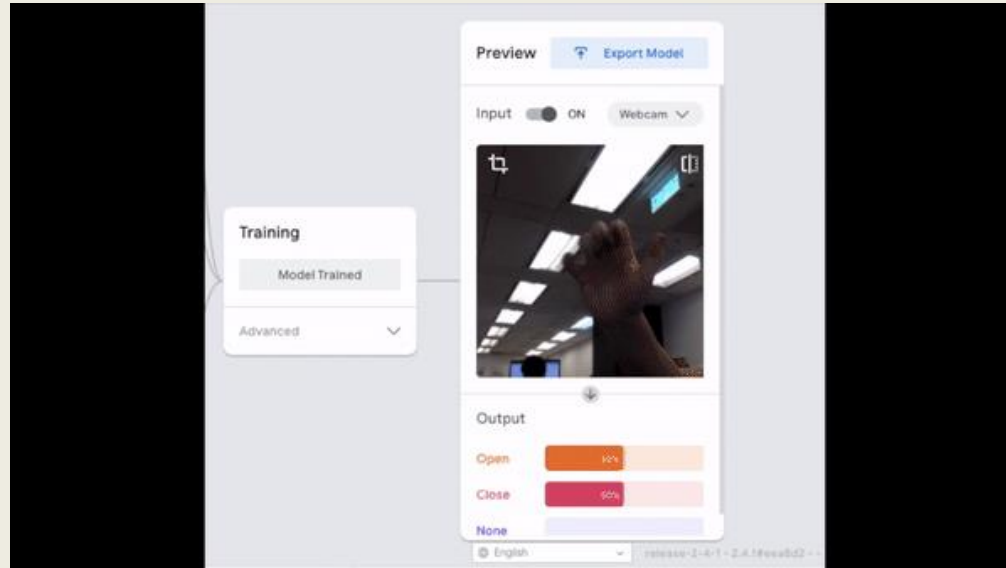


1

Training your own model: Step 6

Test out your model!

2



3

4



Training your own model: Step 7

If your model works well, ***export your model***.

Export your model to use it in projects.

Tensorflow.js ⓘ

Tensorflow ⓘ

Tensorflow Lite ⓘ

Model conversion type:



Floating point



Quantized



EdgeTPU



Download my model

Converts your model to a tflite quantized model. Note the conversion happens in the cloud, and in order to convert to quantized model a subset of the data is being uploaded, but not stored on the server.



Teachable Machine Model Training



1

2

3

4

The training procedure is completed!



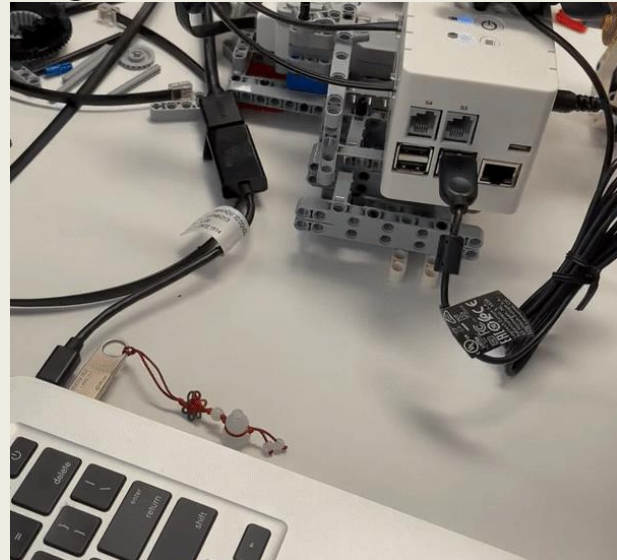
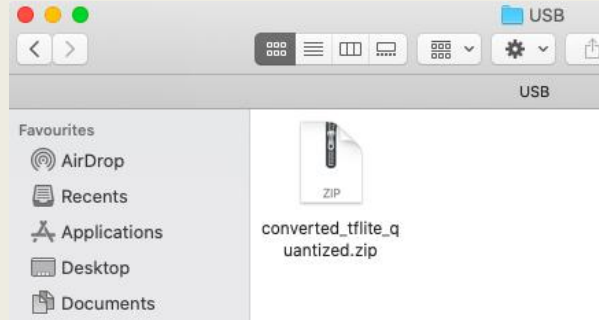
Training your own model: Step 8

If you want to use your model on SenseStorm,

2. Plug USB into SenseStorm

2

1. Move it into USB



3

4



Ref video:

<https://youtu.be/rxveUBwguMc>

Task:

After open the speaker, SenseStorm will speak out the name of the class you show to the camera.

How to do that?

Summary and Q&A



EduHK SenseStorm Q&A

WhatsApp 群组

