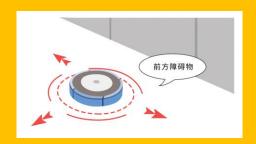


#### Lecture 1

# Operation of an Al Smart Car – Movements, Sensors, Face Detection and Gesture Recognition

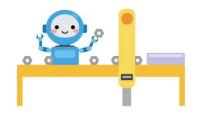
# WHAT IS A ROBOT?

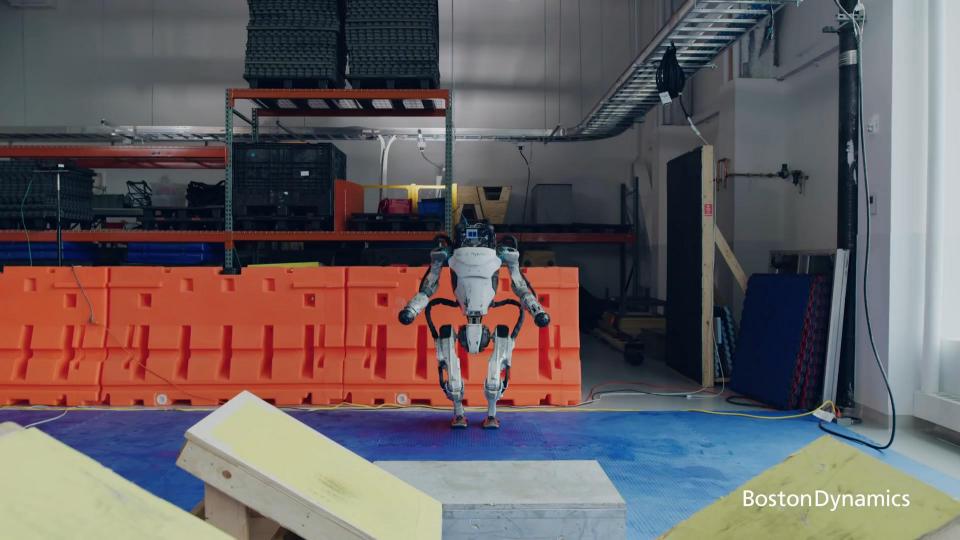
A robot is a machine that can perform various functions through its own power and control.







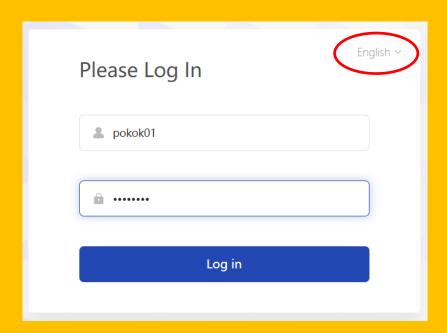




Please login: hk.study.sensetime.com/course/login

Username: pokok01 ~ pokok30

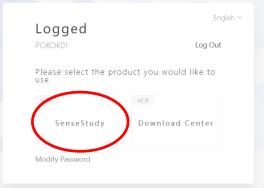
Password: pokok123

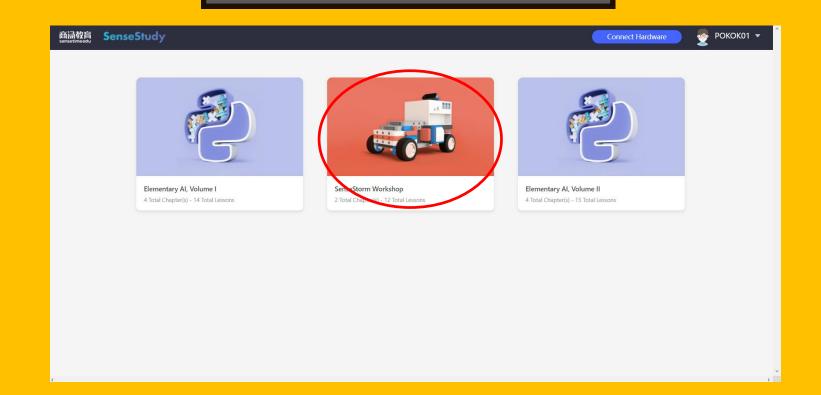


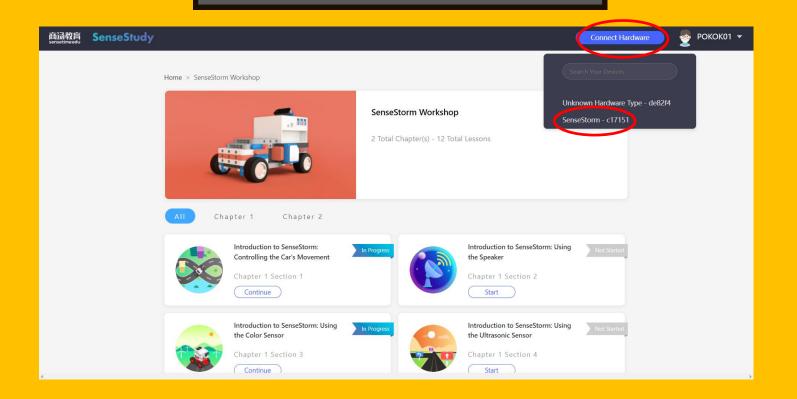
#### **Preparation – Connect SenseStorm with the Platform**

- 1. Make sure your laptop use the same "pkss\_607" WIFI network as SenseStorm.
- 2. Log into SenseStudy platform, and use the "SenseStorm Workshop" course package.
- 3. On the right upper corner of the interface, click the "Connect to hardware" and find the <u>series no.</u> of your SenseStorm. Click "Connect".





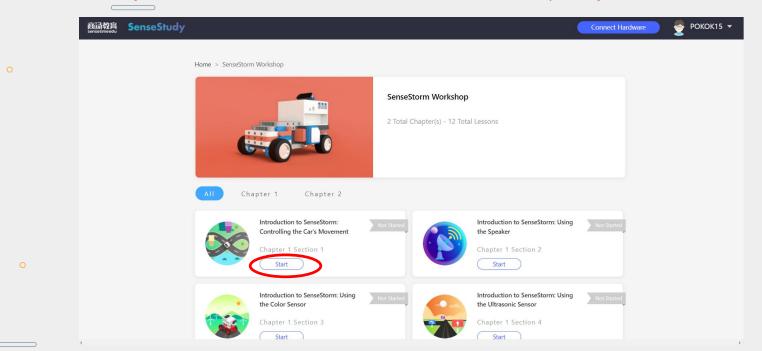




# **Q** SenseStudy Experiment



Choose Experiment: Introduction to SenseStorm (Chapter 1 Section 1)



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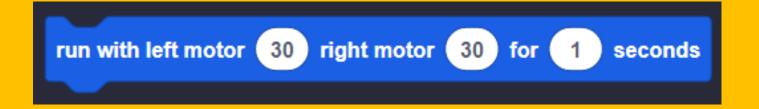
#### **Build a Smart Car**



**Building Manual Download:** 

shorturl.at/deBRW

Move Forward, Backward, Left-turn, Right-turn and U-turn



#### **Use the Ultrasonic Sensor**

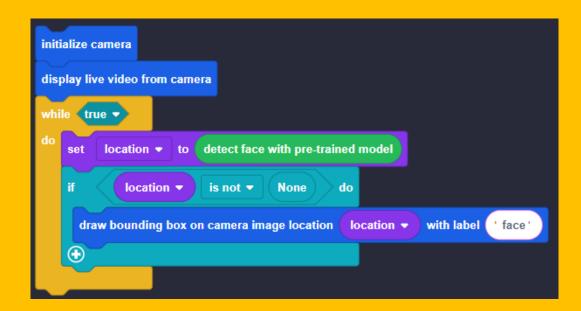
```
while true ▼

do print use ultrasonic sensor $2 ▼ to get distance
```

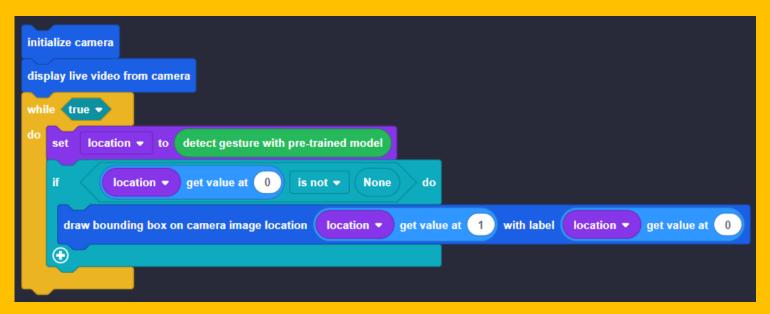
#### **Use the Color Sensor**



#### **Face Detection**



#### **Gesture Recognition**



# Gesture Recognition



手勢序	級 手勢種類	手勢序號	等 手勢種類
0	"OK"	6	"GRAB"
1	"V"	7	"FIST"
2	"THUMB_UP"	8	"FIST_PALM_SALUTE"
3	"STOP"	9	"SINGLE_HAND_HEART"
4	"TICK"	10	"FOREFINGER_UP"
5	"HEART"	11	"SIX"