```
Recall: 1.4 ways to multiply matrices
          O. dot product
           O column
           3. row
         · D columns multiply rows
         2. Block multiplication is allowed when block shapes
          match correctly
§ 2.5 Inverse Matrites
  Let A be a square Matrix
Def A is invertible if there exists A such that
                 ATA = I and AAT = I.
  Not all matrices have inverses. Ex. cyclic difference matrix
   Note 1: A is invertible if and only of it has a privots
            ( I will show you later)
   Note 2: A is unique
     Assume BA = I and AC=I. Then B=C
         Pf: B(AC) = (BA)C & BI=IC & B=C
   Note 3. If A is invertible, then Ax=b \Rightarrow x=A^{-1}b
   (A^{-1}A) x = A^{-1}(A \times) = A^{-1}b
           EX = A + b
   Note 4: If A is reinvertible, then Ax=0 \Rightarrow x=0
  ATTE Ex 1: A = \begin{bmatrix} 1 & 2 \\ 1 & 3 \end{bmatrix} A \times = 0 has solution x = (2, 1).
                A is not invertible
```

To Note 6

If
$$A = \begin{bmatrix} d_i & 0 \\ 0 & d_n \end{bmatrix}$$
 with $d_i \neq 0$, $i = 1, \dots, n$.

Then
$$A^{+} = \begin{bmatrix} d_1^{-1} & 0 \\ 0 & d_n^{-1} \end{bmatrix}$$

The inverse of AB

If A and B are invertible, so is AB

Note: Inverse come in reverse order.

Ex 2. (Inverse of Elimination matrix)

$$E = \begin{bmatrix} 1 & 0 & 0 \\ -5 & 0 & 0 \end{bmatrix}, E = \begin{bmatrix} 1 & 0 & 0 \\ 5 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

Ex 3.

$$F = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & -4 & 1 \end{bmatrix}, F^{\dagger} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 4 & 1 \end{bmatrix}$$

Computing
$$A^{-1}$$
 by Gauss-Jordan Elimination.

Let A be a square matrix. Assume $A^{-1} = \mathbb{L} \times_1 \times_2 \times_3 \mathbb{I}$

Then $A \cdot A^{-1} = A \mathbb{L} \times_1 \times_2 \times_3 \mathbb{I} = \mathbb{I} = \mathbb{L} e_1 e_2 e_3 \mathbb{I}$
 $A \times_1 = e_1 = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$
 $A \times_2 = e_2 = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$

$$A \times_3 = e_3 = \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$

I dea: the Gauss-Jordan method computes At by solving the above

Let
$$= \begin{bmatrix} 2 & -1 & 0 \\ -1 & 2 & -1 \\ 0 & -1 & 2 \end{bmatrix}$$

$$[A I] = [A e_i e_2 e_3] = \begin{bmatrix} 2 & -1 & 0 & 1 & 0 & 0 \\ -1 & 2 & -1 & 0 & 1 & 0 \\ 0 & -1 & 2 & 0 & 0 & 1 \end{bmatrix}$$

$$\frac{x_3 + \frac{2}{3}x_2}{000}$$
 $\frac{2}{3} + \frac{1}{2} = \frac{2}{3} = \frac{2}{3}$
 $\frac{2}{3} = \frac{2}{3} = \frac{2}{3}$
 $\frac{2}{3} = \frac{2}{3} = \frac{2}{3}$

@ Tordon: reduce AU to I by elimination.

Gauss-Jordan. ATEA I] = [I AT]

Singular versus Invertible Assume A 2's Privot test: A-1 exists exactly when A has a full set of n

With in privots, Axi=er has a solution, i=1: Set $A^{-1} = [x_1, \dots, x_n]$

Ex 6. Let L be a trangular matrix.

Then L is invertible (=) no diagonal entries are zero

 $[LI7] = \begin{bmatrix} 1 & 0 & 0 & 1 & 0 & 0 \\ 3 & 1 & 0 & 0 & 1 & 0 \\ 4 & 5 & 1 & 0 & 0 & 1 \end{bmatrix}$ ivot test)

73-572 [1 0 0 1 1 0 0] 0 1 0 | -3 1 0] Recognizing on Invertible Matrix Theorem, Dragonally dominant matrices are invertible Let A be a segume matrix with each asit on the On exeach row, $|a_{ii}| > \sum_{j \neq i} |a_{ij}|$ $A = \begin{bmatrix} 3 & 1 & 1 \\ 1 & 3 & 1 \\ 1 & 1 & 3 \end{bmatrix}$ Pf: Fact: A is invertible (Ax=0 has only zero vector solution. Assure x 25 a non7 ero solution of Ax =0 Let 1xil be the largest component of X. Then $a_{i1} \times_i + \cdots + a_{in} \times_i + \cdots + a_{in} \times_n = 0$ (asixi = - Z asyxy $\Rightarrow |a_{ir} \times i| = |\sum_{j \neq i} a_{ij} \times y| \leq \sum_{j \neq i} |a_{ij}| |x_{j}| < \frac{1}{|a_{ii}|} |x_{j}|$ < 23 larg 11xs/

< 1907/1Xi/, a contradiction.