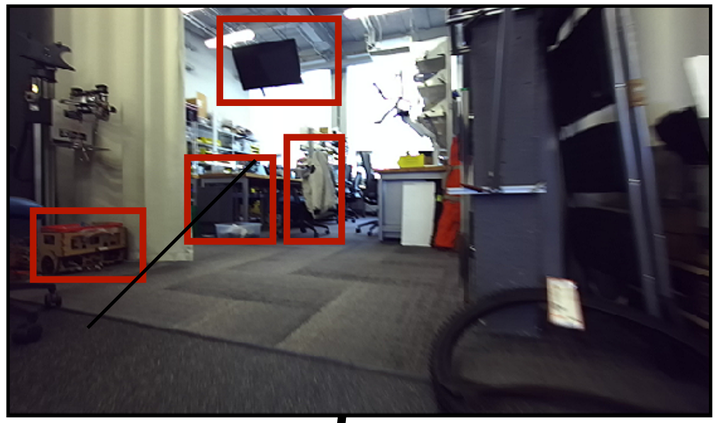
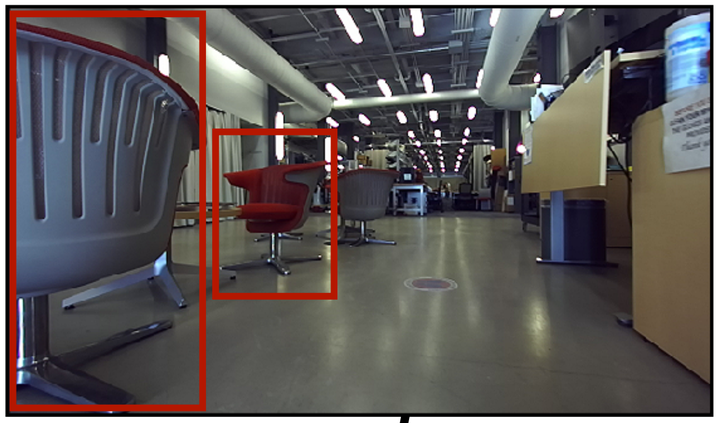
Robot trajectory

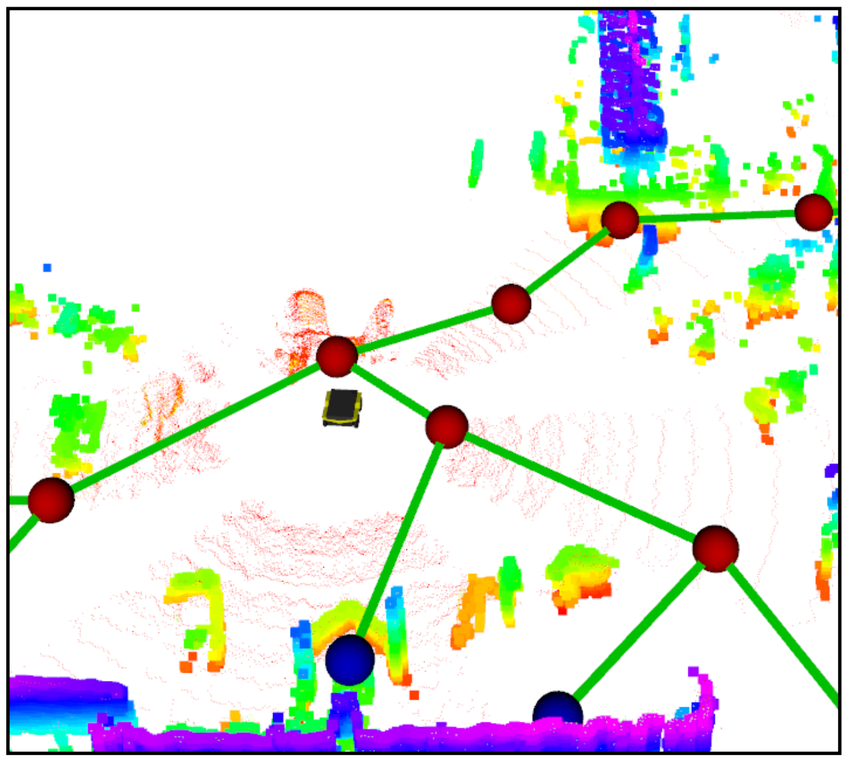
Object node

Region node

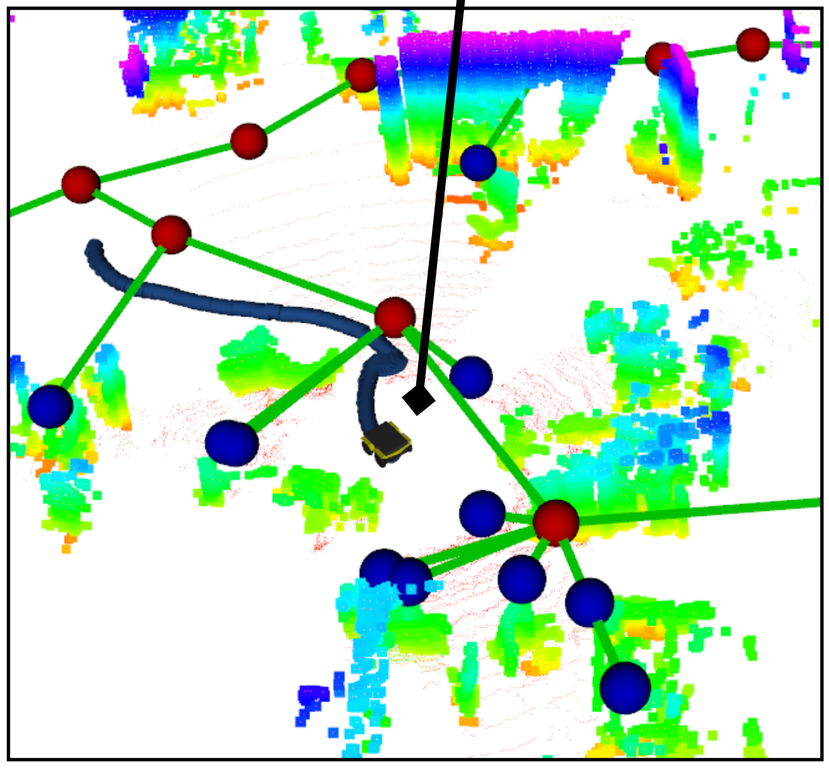
Find me a place to sit



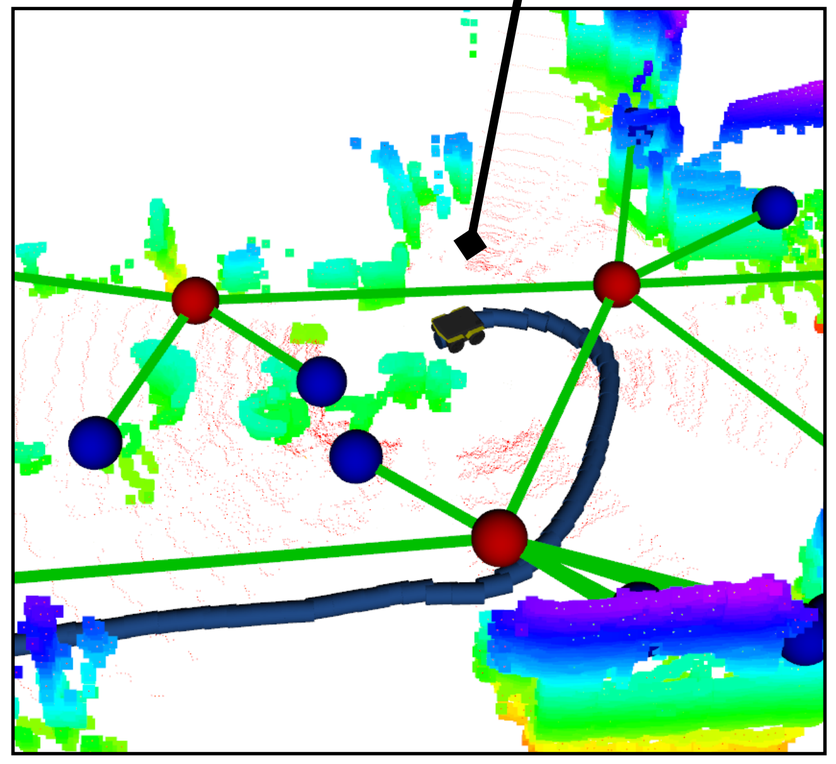




Initial world model



Intermediate world model



Final world model