Yu ZHAO

E-mail: yzhao334@berkeley.edu

Address: 530 Kinkead way, #202, Albany, CA 94706

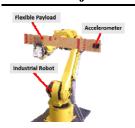
Homepage: https://yzhao334.github.io/



Education

Aug/2013-Present	University of California at Berkeley, M	Iechanical Engineering
	Ph.D candidate, estimated graduate by 2018, Advisor: Mas	ayoshi Tomizuka, GPA 3.95
Aug/2005-Jun/2013	Tsinghua University	
	B.S., M.S., Mechanical Engineering	
Skills & Expertise		
Skills	MATLAB/Simulink, CAD (Pro/ENGINEER, SolidWorks,	AutoCAD), ROS, Python,
	C/C++, robotics, deep learning, control, MCU, Ubuntu/Linux	
Expertise & interests	Dynamics, Control, Simulation, Robotics	
Working Experience		
Jun./2016-Aug./2016	Energid Technologies (Software, Cambridge, MA, U.S.)	Internship
	Online trajectory generation. Developing program to generate smooth trajectory with	
	bounded velocity, acceleration, and jerk on line.	
JunJul./2015 Sep./16	FANUC (Robotics company, Yamanashi, Japan)	Internship
		±
	Vibration suppression study for industrial robots.	Ĭ
Jul./2011-Aug./2011	· · · · · · · · · · · · · · · · · · ·	Internship

Selected Projects



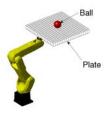
Intelligent motion control of robot manipulators

Modeling and analysis of robot dynamics with flexibility

Dynamics and control simulation & experiment

Nonlinear control & neural network based control

Vibration suppression with zero-time-delay input shaping



Optimal Manipulation of Ball-Plate System

Simulation of robotics kinematics and contact dynamics

Fast rendering in MATLAB

Optimal feedback control design



Spraying robot

Innovated machine design

Virtual prototype design using CAD & motion simulation (Pro/E)

Selected Publications

- [1] **Zhao, Yu,** Wenjie Chen, Te Tang, and Masayoshi Tomizuka. "Zero time delay input shaping for smooth settling of industrial robots." In *Automation Science and Engineering (CASE), 2016 IEEE International Conference on*, pp. 620-625. IEEE, 2016.
- [2] Zhao, Yu, Cong Wang, Xiaowen Yu, and Masayoshi Tomizuka. "Complete Dynamic Modelling of Flexible Joint Robots." In ASME 2015 Dynamic Systems and Control Conference, pp. V001T18A003-V001T18A003. American Society of Mechanical Engineers, 2015.
- [3] Yu, Xiaowen, Cong Wang, Yu Zhao, and Masayoshi Tomizuka. "Controller design and optimal tuning of a wafer handling robot." In *Automation Science and Engineering (CASE)*, 2015 IEEE International Conference on, pp. 640-646. IEEE, 2015.
- [4] Wang, Cong, Yu Zhao, Yubei Chen, and Masayoshi Tomizuka. "Nonparametric statistical learning control of robot manipulators for trajectory or contour tracking." *Robotics and Computer-Integrated Manufacturing* 35 (2015): 96-103.
- [5] Wang, Cong, Yu Zhao, Chung-Yen Lin, and Masayoshi Tomizuka. "Fast planning of well conditioned trajectories for model learning." In *Intelligent Robots and Systems (IROS 2014), 2014 IEEE/RSJ International Conference on*, pp. 1460-1465. IEEE, 2014.
- [6] Yu, Xiaowen, Cong Wang, Yu Zhao, and Masayoshi Tomizuka. "Dynamics modeling and identification of a dual-blade wafer handling robot." In ASME 2013 Dynamic Systems and Control Conference, pp. V003T39A004-V003T39A004. American Society of Mechanical Engineers, 2013.
- [7] Zhao, Yu, Tiemin Li, Xiaowen Yu, Xiaoqiang Tang, and Liping Wang. "Mobility analysis of a Sarrus Linkage-like 7-R single closed loop mechanism." In *Robotics and Automation (ICRA)*, 2013 IEEE International Conference on, pp. 4171-4176. IEEE, 2013.
- [8] **Yu, Zhao**, Li Tiemin, and Tang Xiaoqiang. "Geometric error modeling of machine tools based on screw theory." *Procedia Engineering* 24 (2011): 845-849.

Patents

Cable traction automobile coating conveyor, CN 102616668 A

Awards & Honors

2015 Student Travel Honorariums for ASME student member attending academic conferences
2015 Conference Travel Grants by Berkeley Graduate Division for attending academic conferences
2014 Nonresident Tuition Fellowship by Dept. ME, UC Berkeley
2008 Tsinghua University 12.9 Scholarship (For top 5% students in ME department)
2008 Beijing College Student Mechanical Design Competition, 2 Second Prizes (top 5%)
2005 Tsinghua University Freshman Mechanical Design Competition, Best Creativity Award
2005 Tsinghua University Freshman Mechanical Design Competition, Second Prize (top 3)