Multi-GPU Graph Analytics

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Introduction - about Gunrock

Gunrock is a multi-GPU graph processing library, which targets at:

- High performance analytics of large graphs
- Low programming complexity in implementing parallel graph algorithms on GPUs

Homepage: http://gunrock.github.io

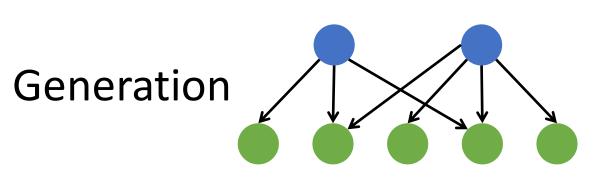
The copyright of Gunrock is owned by The Regents of the University of California, 2015. All source code are released under Apache 2.0.

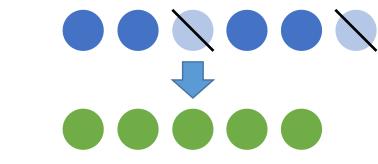


Programming Model

Graph algorithm as a data-centric process

Frontier: compact queue of nodes or edges



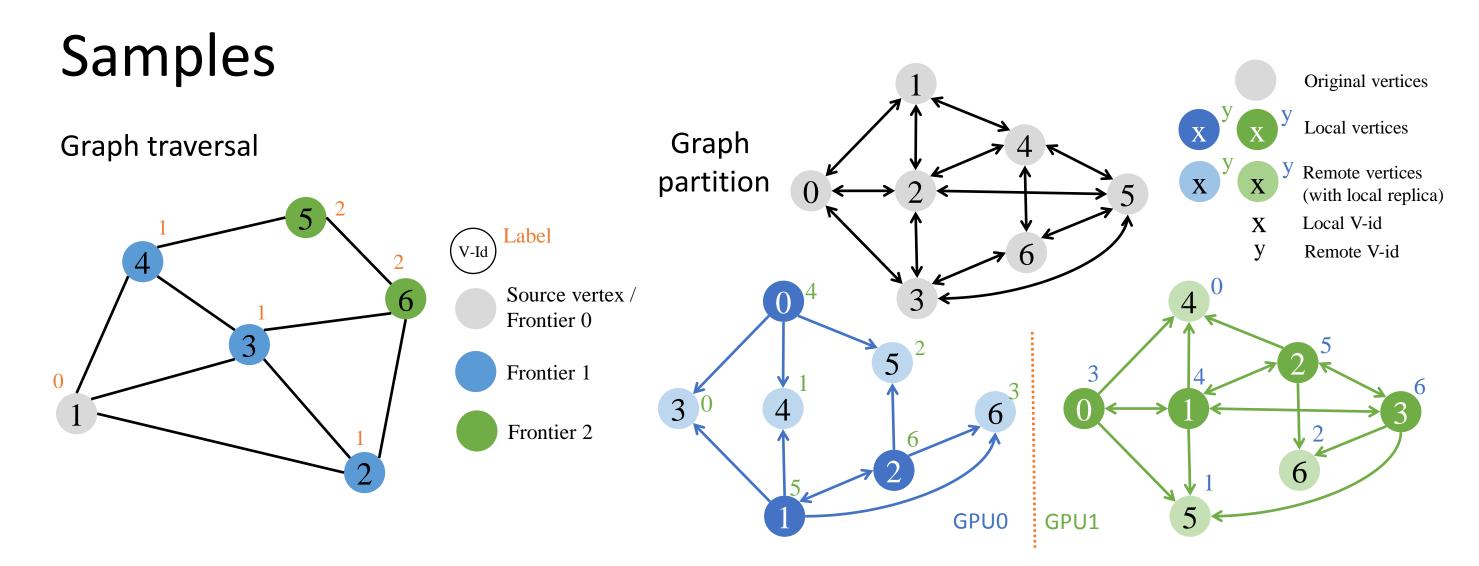


Advance: visit neighbor lists Filter: select and reorganize

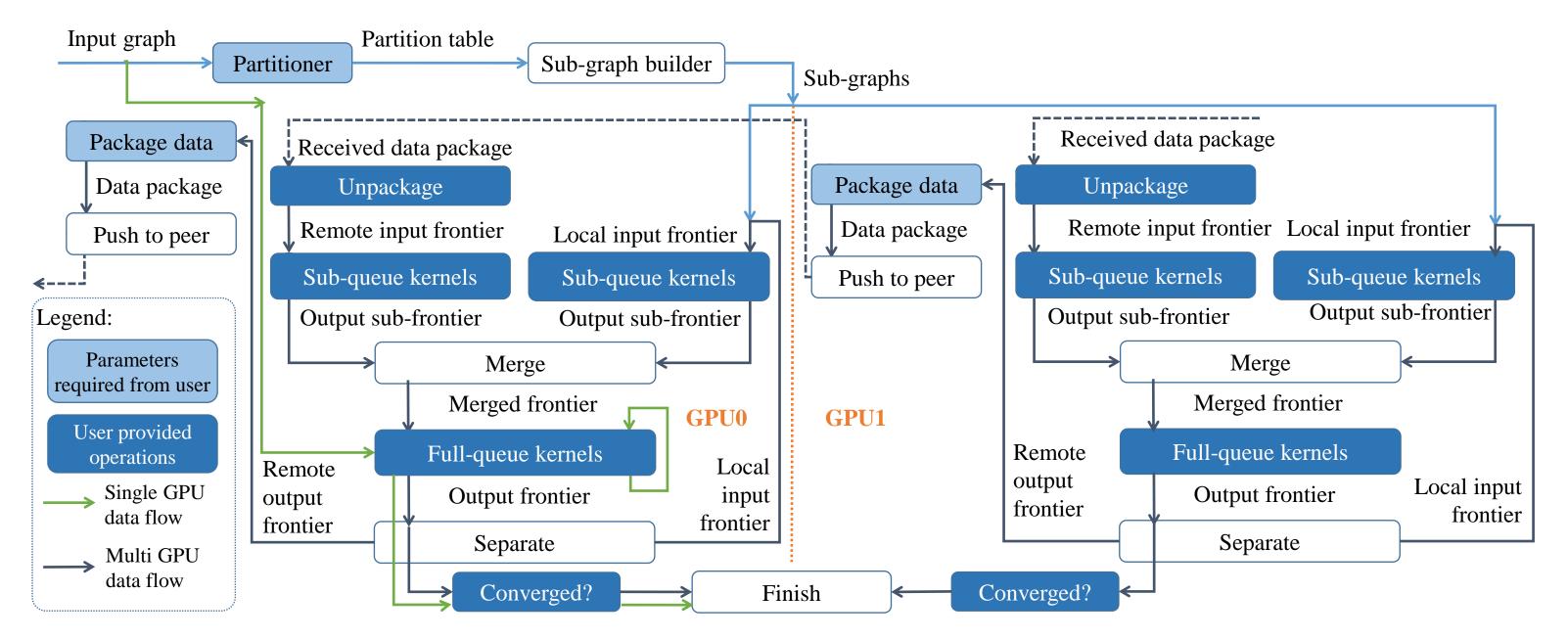
Operation



Compute: per-element computation kernels in parallel can be combined with advance or filter



Multi-GPU Framework



Gunrock's multi-GPU framework aims at:

- Programmability: easy to develop graph primitives to support multiple GPUs

 hides most implementation details in the framework, and only requires
 little inputs (what data to exchange, how to combine data, when to stop)
- Algorithm generality: support a wide range of graph algorithms
 -> isolates from the actual algorithm implementations
- Hardware compatibility: usable on most single node GPU systems
 -> works on any number of GPUs, with or w/o peer GPU memory access
- Performance: low runtime, and leverages the underlying hardware well
 -> uses multiple CPU control threads and GPU streams to overlap computations on different portions of frontier, as well as communication
- Scalability: scalable in terms of both performance and memory usage
 -> Performs just enough GPU memory (re)allocation to keep usage small

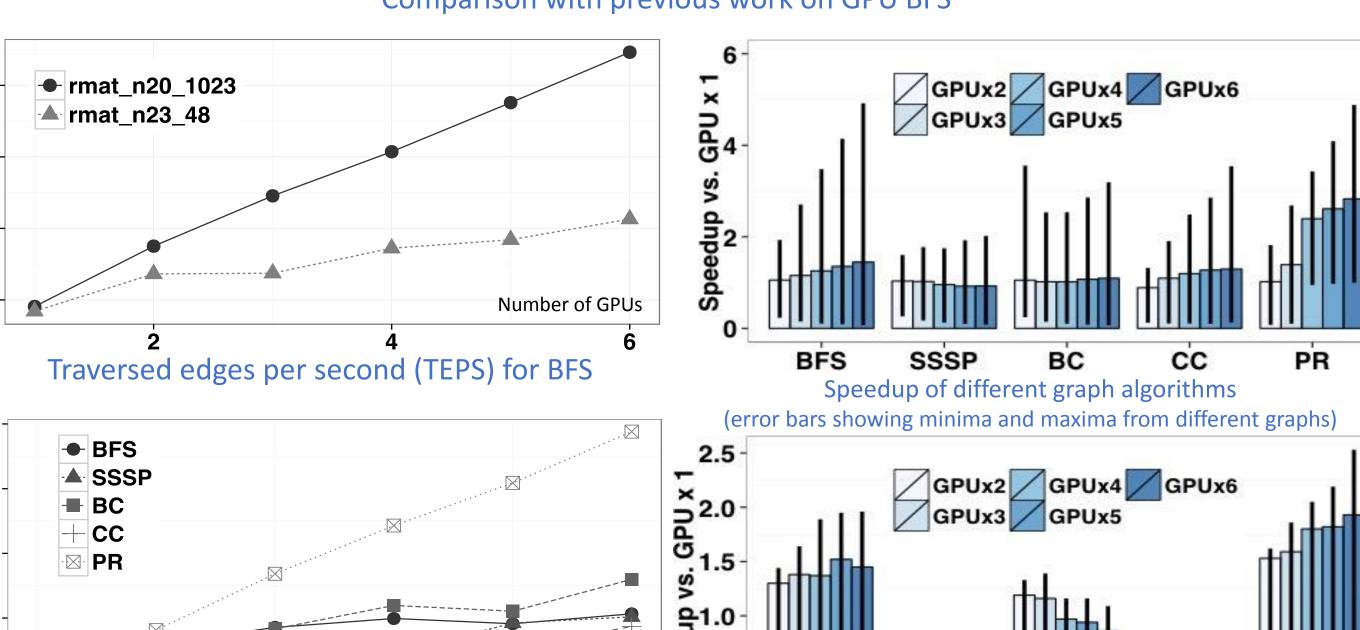
Future Work

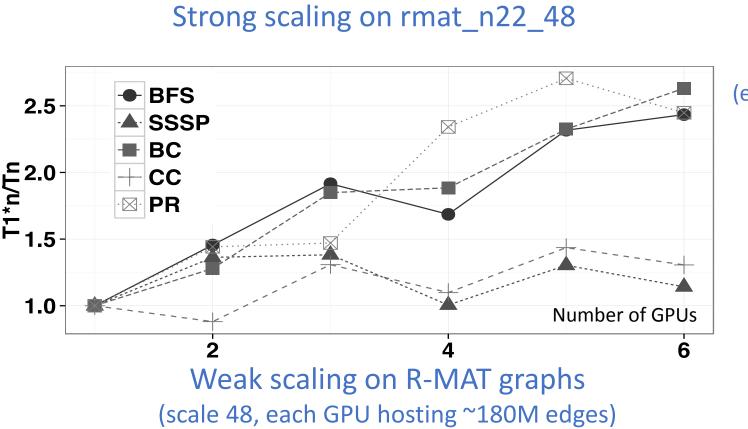
- performance analysis and optimization
- extending Gunrock onto multiple nodes
- asynchronized graph algorithms
- 2D partitioning
- Fixed partitioning
- more algorithms

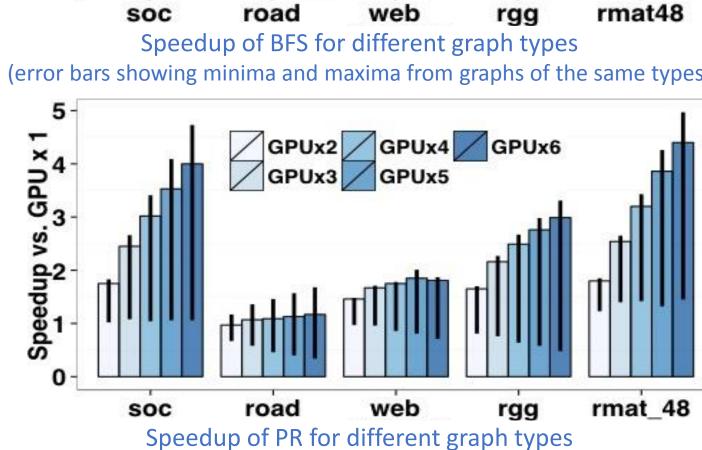
Results

	ref.	ref. hardware	ref. performance	our hardware	our performance
rmat_n20_128	Merrill et al. [3]	4x Tesla C2050	8.3 GTEPS	4x Tesla K40	11.2 GTEPS
rmat_n20_16	Zhong et al. [4]	4x Tesla C2050	15.4 ms	4x Tesla K40	9.29 ms
peak GTEPS	Fu et al. [5]	16x Tesla K20	15 GTEPS	6x Tesla K40	22.3 GTEPS
peak GTEPS	Fu et al. [5]	64x Tesla K20	29.1 GTEPS	6x Tesla K40	22.3 GTEPS

Comparison with previous work on GPU BFS







(error bars showing minima and maxima from graphs of the same types)

Acknowledgement

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References

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