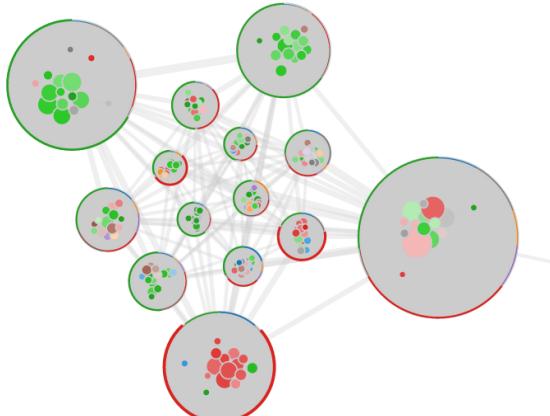


# Fast Eigen-Functions Tracking on Dynamic Graphs

Chen Chen and Hanghang Tong



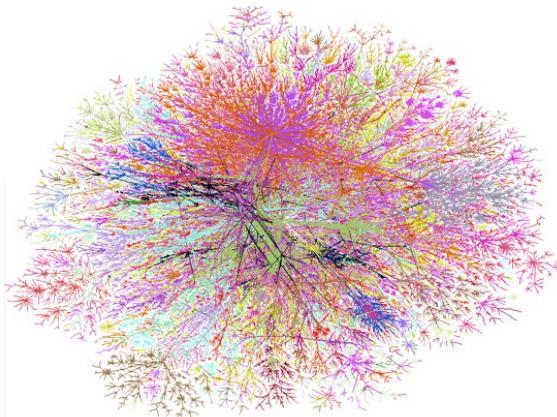
# Graphs are Ubiquitous!



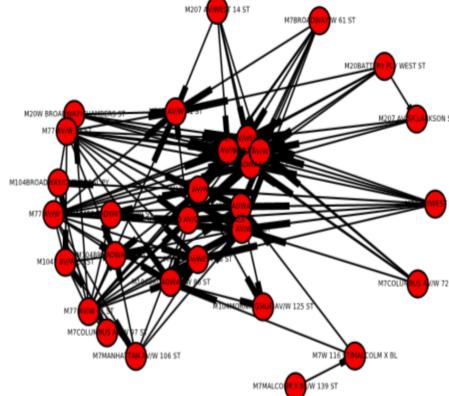
# Collaboration Network



# Hospital Network



# Autonomous Network



# Transportation Network

# Key Graph Parameters

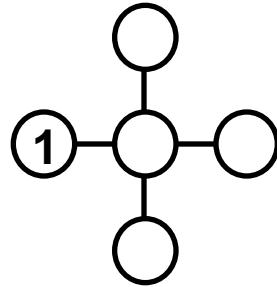
- P1: Epidemic Threshold (Propagation network)
- P2: Centrality of nodes (All networks)
- P3: Clustering Coefficient (Social network)
- P4: Graph Robustness (Router/Transportation)

# P1: Epidemic Threshold

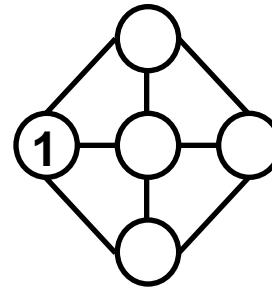
- **Questions:** How easy is it to spread disease?
- **Intuition**



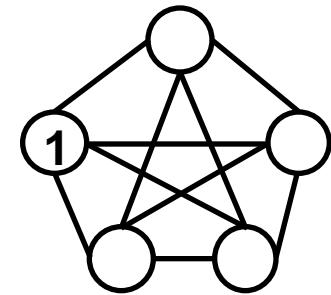
$$\lambda = 1.7$$



$$\lambda = 2.0$$



$$\lambda = 2.9$$



$$\lambda = 4.0$$

- **Solution:** Related to the leading eigenvalue ( $\lambda$ ) of the adjacency matrix for **ANY** cascade model [ICDM 2011]

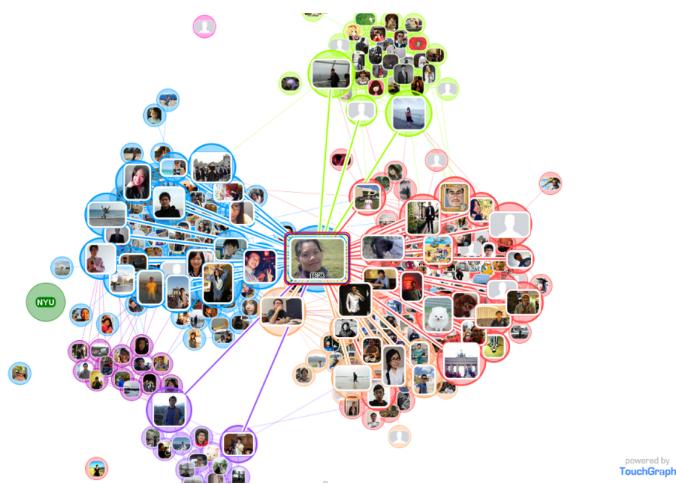
# P2: Node Centrality

- **Question:** How important is a node?
- **Intuition:** Having more important friends are considered influential
- **Commonly used:** Eigenvector Centrality

The eigenvector corresponding to the leading eigenvalue ( $Au = \lambda u$ )

# P3: Clustering Coefficient

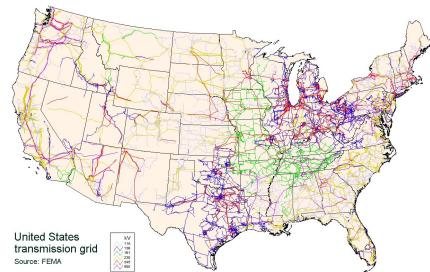
- **Question:** How the nodes in the graph cluster together?
- **Intuition:**



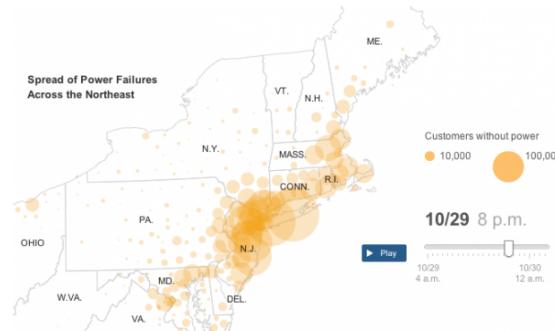
- **Solution:**  $C = \frac{3 \times \text{number of triangles}}{\text{number of connected triplets}}$

# P4: Graph Robustness

- **Question:** How robust is a graph under external attack?
- **Intuition:**



Power Grid  
[wikipedia.com]



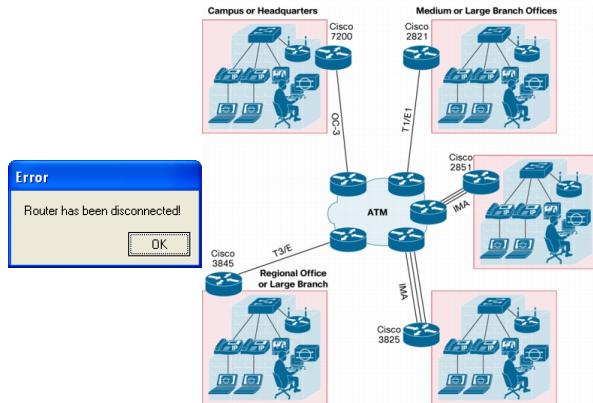
Sandy Aftermath  
[forbes.com]

- **Solution:**  $S(G) = \ln\left(\frac{1}{k} \sum_{i=1}^k e^{\lambda_i}\right)$  [SDM2014]

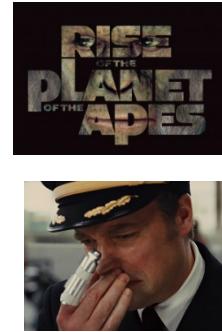
# Challenge: Graphs are Dynamic!



Social Networks



Router Networks  
[[www.cisco.com](http://www.cisco.com)]



Propagation Networks



Transportation Networks  
[[www.mapofworld.com](http://www.mapofworld.com)]

**How to track key graph parameters?**

# Eigen-Function Tracking

- Q1. Track key graph parameters
- Q2. Estimate the error of tracking algorithms
- Q3. Analyze attribution for drastic changes

# Roadmap

- ✓ ■ Motivations
- ➡ ■ Q1: Efficient tracking algorithms
- Q2: Error estimation methods
- Q3: Attribution analysis
- Conclusion

# Key Graph Parameters

- Observations: P1-P4 are all eigen-functions

$$f((\Lambda_k, U_k)) = \begin{cases} \lambda_1 & \text{P1. Epidemic Threshold} \\ u_1 & \text{P2. Eigenvector Centrality} \\ \Delta(G) = \frac{1}{6} \sum_{i=1}^k \lambda_i^3 & \text{P3. Clustering Coefficient} \\ S(G) = \ln\left(\frac{1}{k} \sum_{i=1}^k e^{\lambda_i}\right) & \text{(Triangles)} \text{ P4. Robustness Score} \end{cases}$$

# Goal: Tracking Top Eigen-Pairs

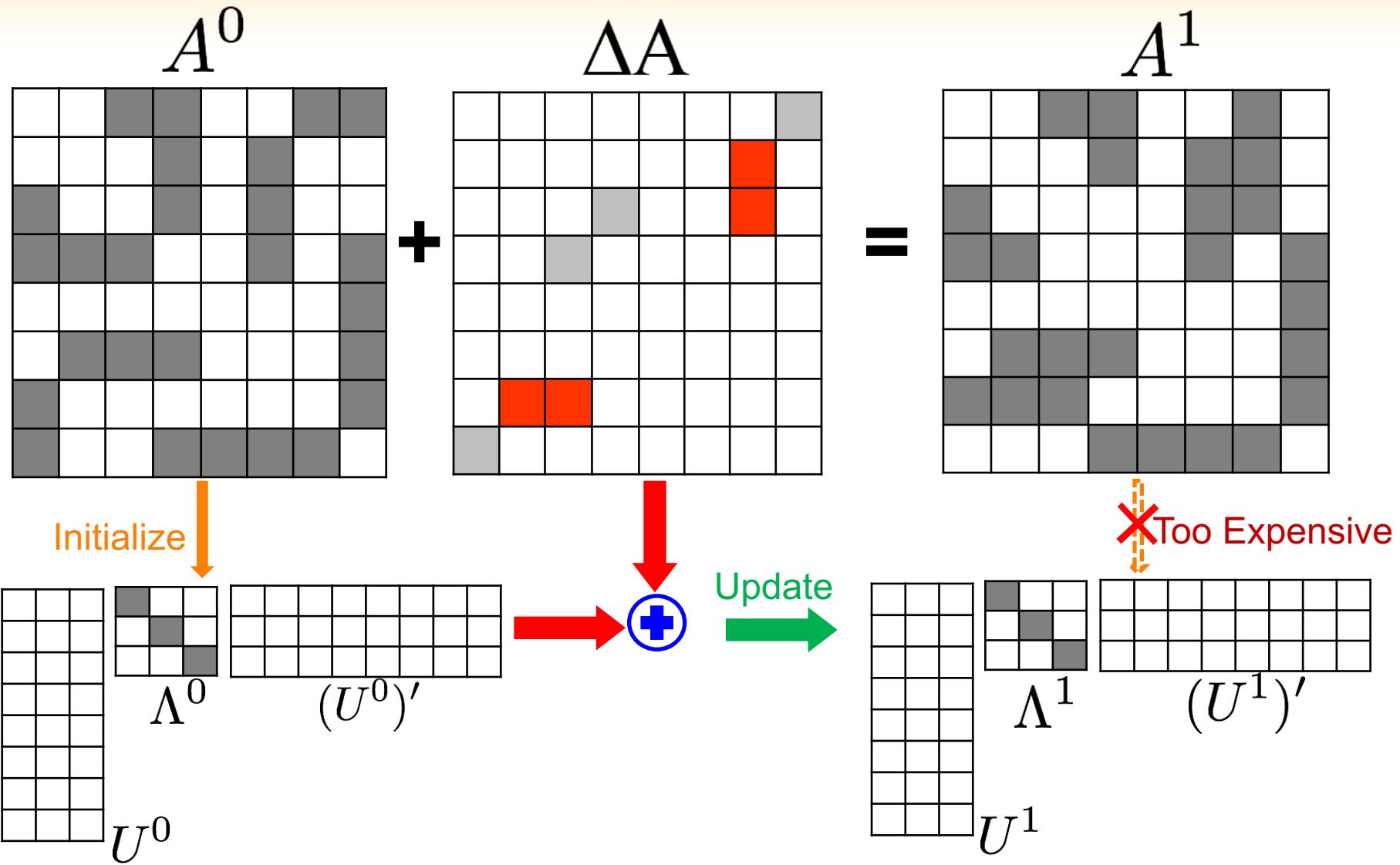
- Method 1.

- Calculate  $(\Lambda_k, U_k)$  **from scratch** whenever the structure changes
  - Lanczos algorithm  $O(T(mk + nk^2))$



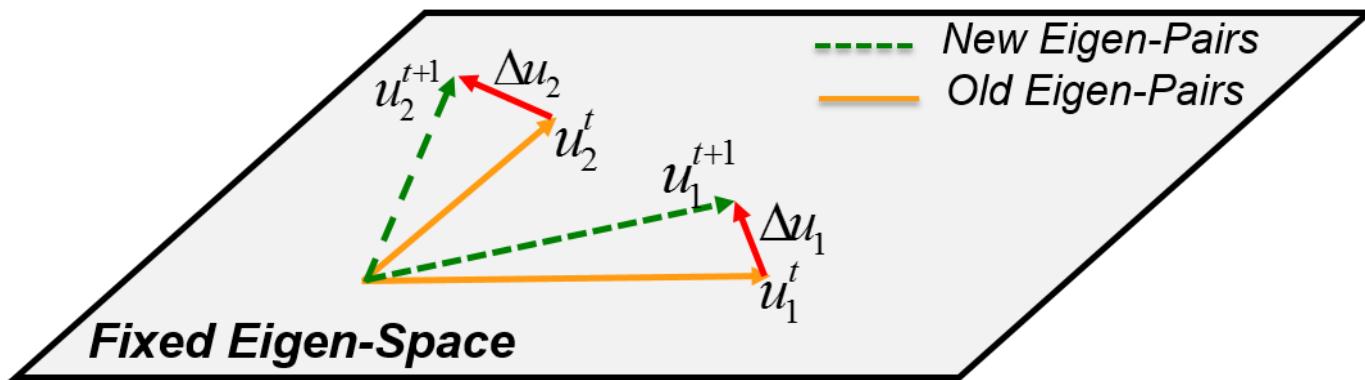
**Too costly for fast-changing large graphs!**

# Key Idea



# Key Idea: Incrementally Update

- Intuition:

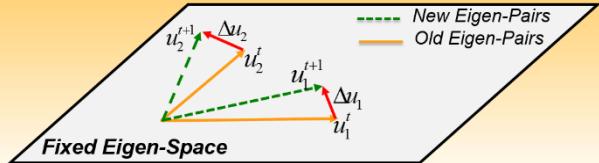


- Solution: Matrix Perturbation Theory

$$\begin{aligned} A^{t+1} u_1^{t+1} &= \lambda_1^{t+1} u_1^{t+1} \\ A^{t+1} u_2^{t+1} &= \lambda_2^{t+1} u_2^{t+1} \end{aligned} \quad \rightarrow \quad \begin{aligned} (A + \Delta A)(u_1 + \Delta u_1) &= (\lambda_1 + \Delta \lambda_1)(u_1 + \Delta u_1) \\ (A + \Delta A)(u_2 + \Delta u_2) &= (\lambda_2 + \Delta \lambda_2)(u_2 + \Delta u_2) \end{aligned}$$
$$\begin{aligned} A^{t+1} &= A^t + \Delta A \\ \lambda^{t+1} &= \lambda^t + \Delta \lambda \\ u^{t+1} &= u^t + \Delta u \end{aligned}$$

Time stamp omitted for brevity.

# Details: Step 1



$$(A + \Delta A)(u_1 + \Delta u_1) = (\lambda_1 + \Delta \lambda_1)(u_1 + \Delta u_1)$$

$$(A + \Delta A)(u_2 + \Delta u_2) = (\lambda_2 + \Delta \lambda_2)(u_2 + \Delta u_2)$$



$$Au_1 = \lambda_1 u_1 \quad Au_2 = \lambda_2 u_2$$

$$\underline{A\Delta u_1 + \Delta A u_1 + \Delta A \Delta u_1} = \underline{\lambda_1 \Delta u + \Delta \lambda_1 u_1 + \Delta \lambda_1 \Delta u_1}$$

$$\underline{A\Delta u_2 + \Delta A u_2 + \Delta A \Delta u_2} = \underline{\lambda_2 \Delta u + \Delta \lambda_2 u_2 + \Delta \lambda_2 \Delta u_2}$$

First order perturbation terms

High order perturbation terms

**Challenge:** two equation with four variables  $\Delta \lambda_1 \Delta \lambda_2 \Delta u_1 \Delta u_2$

**Solution:** Introduce additional constraints and assumptions

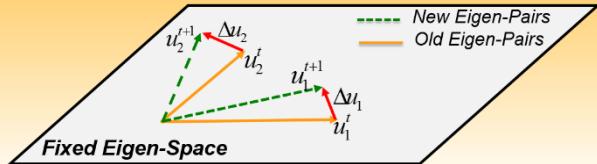
$$u_i^T u_i = 1 \quad u_i^T u_j = 0 \quad (i \neq j)$$

Constraints

$$\begin{aligned} \Delta u_1 &= \alpha_{11} u_1 + \alpha_{12} u_2 & \Delta \lambda_i \ll \lambda_i \\ \Delta u_2 &= \alpha_{21} u_1 + \alpha_{22} u_2 & \Delta u_i \ll u_i \end{aligned}$$

Assumptions

# Details: Estimate $\Delta\lambda_i$



- Discard high order term

$$A\Delta u_i + \Delta A u_i + \Delta A \Delta u_i = \lambda_i \Delta u_i + \Delta \lambda_i u_i + \Delta \lambda_i \Delta u_i$$

1

$$\Delta \lambda_i \ll \lambda_i, \Delta u_i \ll u_i$$

$$A\Delta u_i + \Delta A u_i = \lambda_i \Delta u_i + \Delta \lambda_i u_i$$

2

Multiply  $u_i'$  on both side

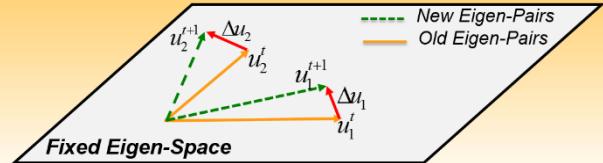
$$u_i' A \Delta u_i + u_i' \Delta A u_i = u_i' \lambda_i \Delta u_i + u_i' \Delta \lambda_i u_i$$

3

$$A u_i = \lambda_i u_i, u_i' u_i = 1$$

$$\Delta \lambda_i = u_i' \Delta A u_i$$

# Estimate $\Delta u_i$ (Option 1)



$$A\Delta u_i + \Delta A u_i = \lambda_i \Delta u_i + \Delta \lambda_i u_i \quad (\text{Discard high order})$$

↓

Multiply  $u_j'$  on both side

1

$$u_j' A \Delta u_i + u_j' \Delta A u_i = u_j' \lambda_i \Delta u_i + u_j' \Delta \lambda_i u_i$$
2

$$\downarrow$$

$Au_j = \lambda_j u_j, u_j' u_i = 0$

3

$$u_j' \Delta A u_i = (\lambda_i - \lambda_j) u_j' \Delta u_i$$
3

$$\downarrow$$

$\Delta u_i = \sum_{p=1}^k \alpha_{ip} u_p$

4

**(Trip-Basic)**

$$\alpha_{ij} = \frac{u_j' \Delta A u_i}{\lambda_i - \lambda_j}$$

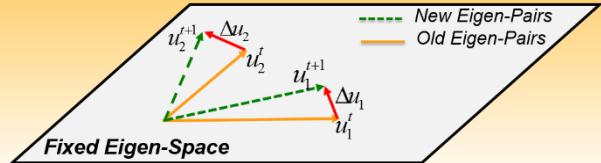
4
 $u_j' \Delta A u_i = (\lambda_i - \lambda_j) \left( \sum_{p=1, p \neq j}^k \alpha_{ip} u_j' u_p + \alpha_{ij} u_j' u_j \right)$

$u_i' u_j = 0, u_i' u_i = 1$

**Time Complexity:**  $O(Tk^2(s + n))$  ( $s = |\Delta A|$ )

Lanczos:  $O(T(mk + nk^2))$

# Estimate $\Delta u_i$ (Option 2)



- Keep high order perturbation terms

$$A\Delta u_i + \Delta A u_i + \underline{\Delta A \Delta u_i} = \lambda_i \Delta u + \Delta \lambda_i u_i + \underline{\Delta \lambda_i \Delta u_i}$$



$$\Delta \lambda_i = u_i' \Delta A u_i, \Delta u_i = \sum_{j=1}^k \alpha_{ij} u_j$$

**(Trip)**

$$\alpha_i = (D - X)^{-1} X(:, i) \quad (\alpha_i = [\alpha_{i1}, \alpha_{i2}, \dots, \alpha_{ik}])$$

where  $X = U_k' \Delta A U_k$ ,  $D = \text{diag}(\lambda_i + \Delta \lambda_i - \lambda_j)$  ( $j = 1, \dots, k$ )

**(Trip-Basic)**  $\alpha_{ij} = \frac{u_j' \Delta A u_i}{\lambda_i - \lambda_j} \leftrightarrow \alpha_i = D^{-1} X(:, i)$

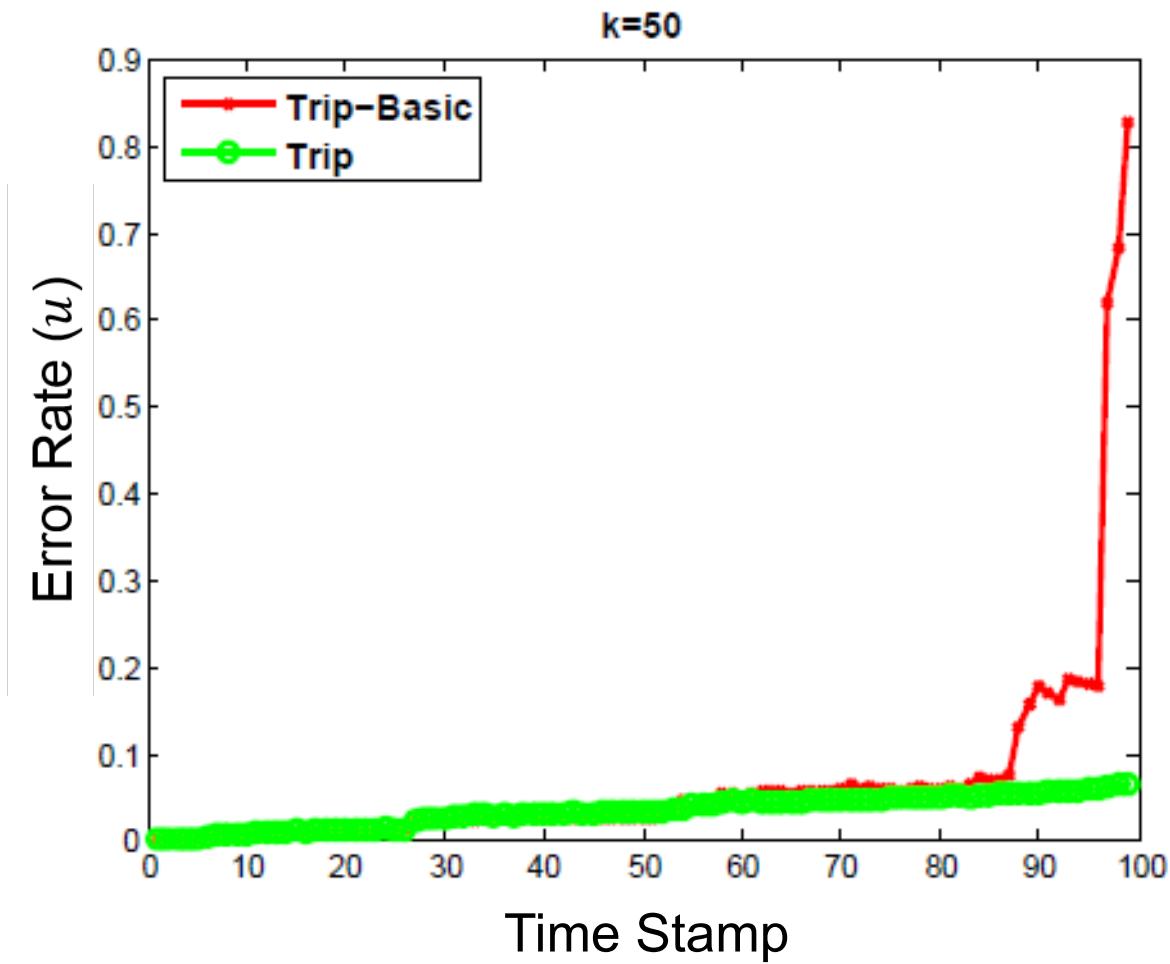
where  $X = U_k' \Delta A U_k$ ,  $D = \text{diag}(\lambda_i - \lambda_j)$  ( $j = 1, \dots, k$ )

**Time Complexity:**  $O(T(k^4 + k^2(n+s)))$  ( $s = |\Delta A|$ )

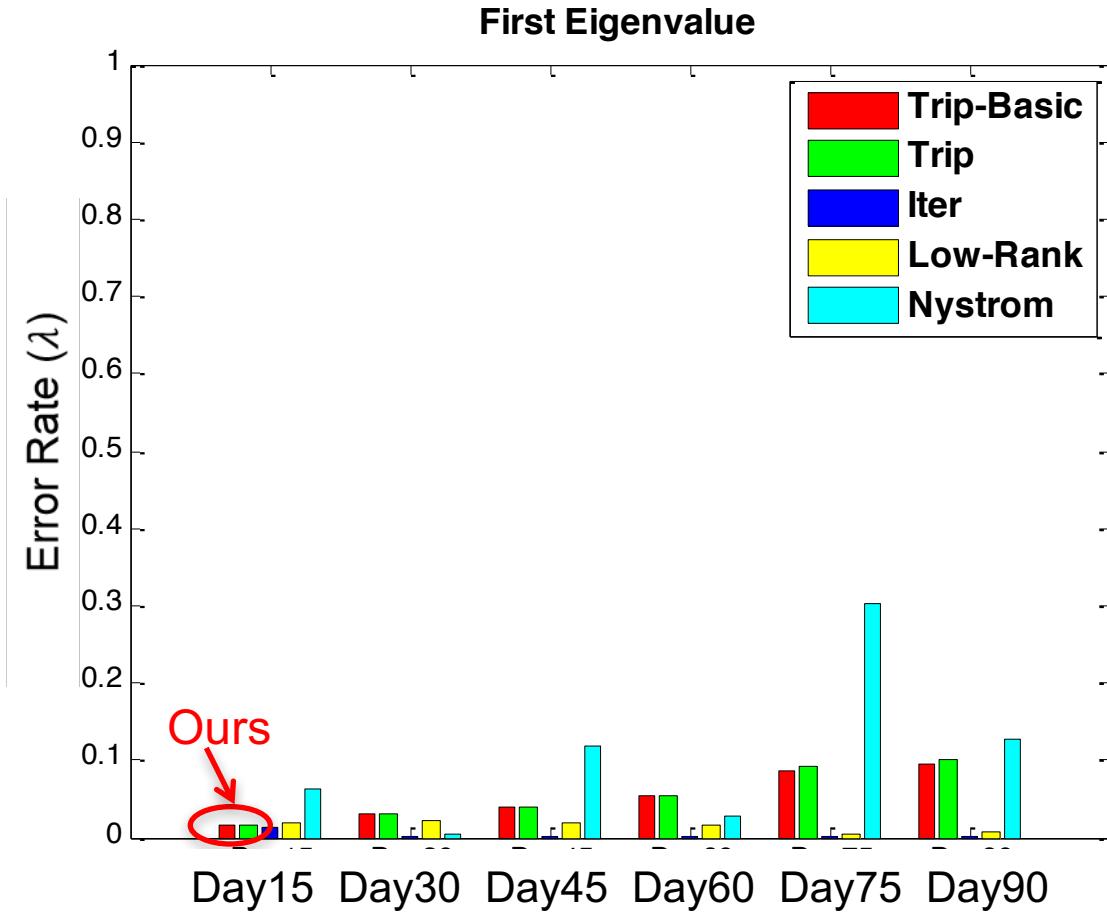
# Evaluation

- Data set:
  - Autonomous systems AS-733  
(<https://snap.stanford.edu/data/as.html>)
  - 100 days time spans
    - (11/08/1997-02/16/1998)
    - (03/15/1998-06/26/1998)
  - Maximum #nodes = 4,013
  - Maximum #edges = 14,399

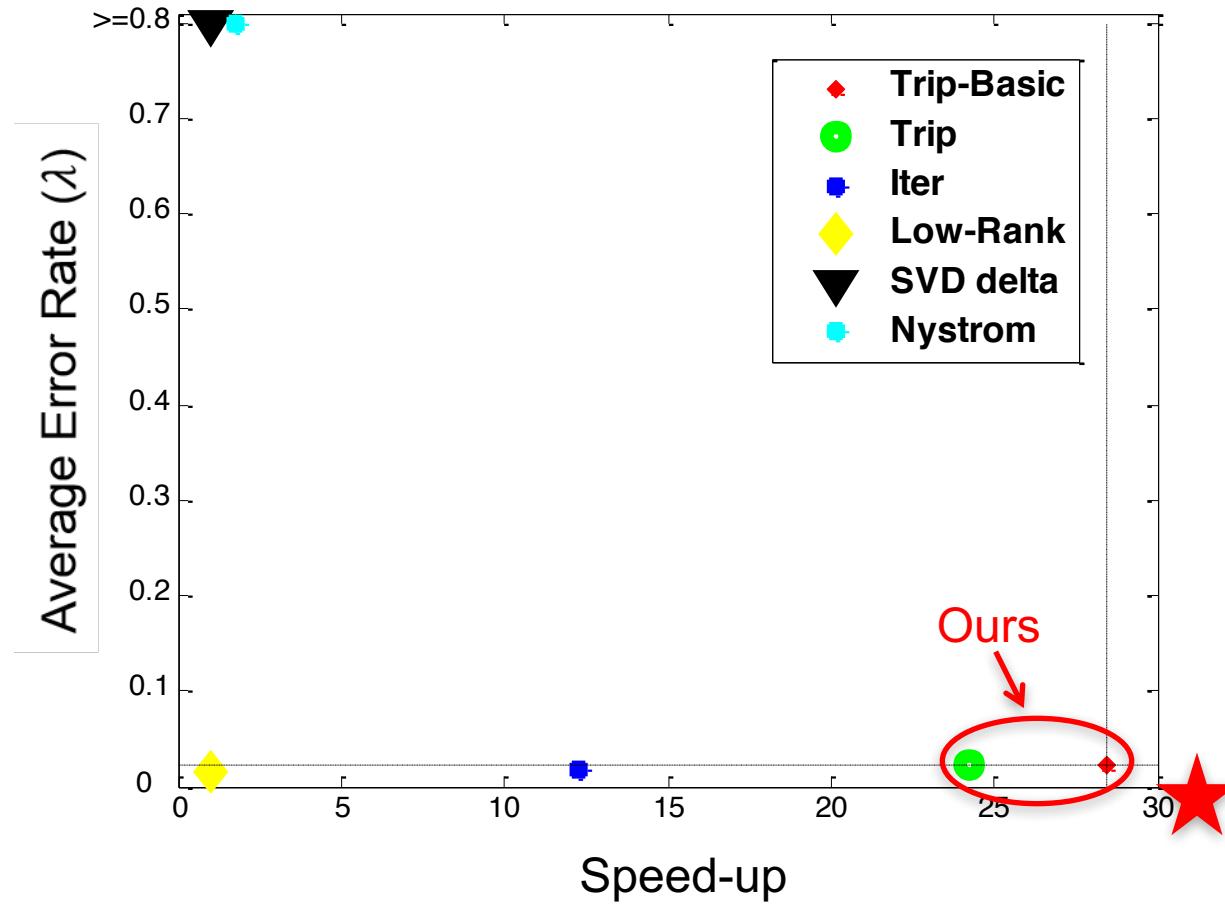
# Trip-Basic vs. Trip: Effectiveness



# Effectiveness Comparison



# Effectiveness vs. Efficiency

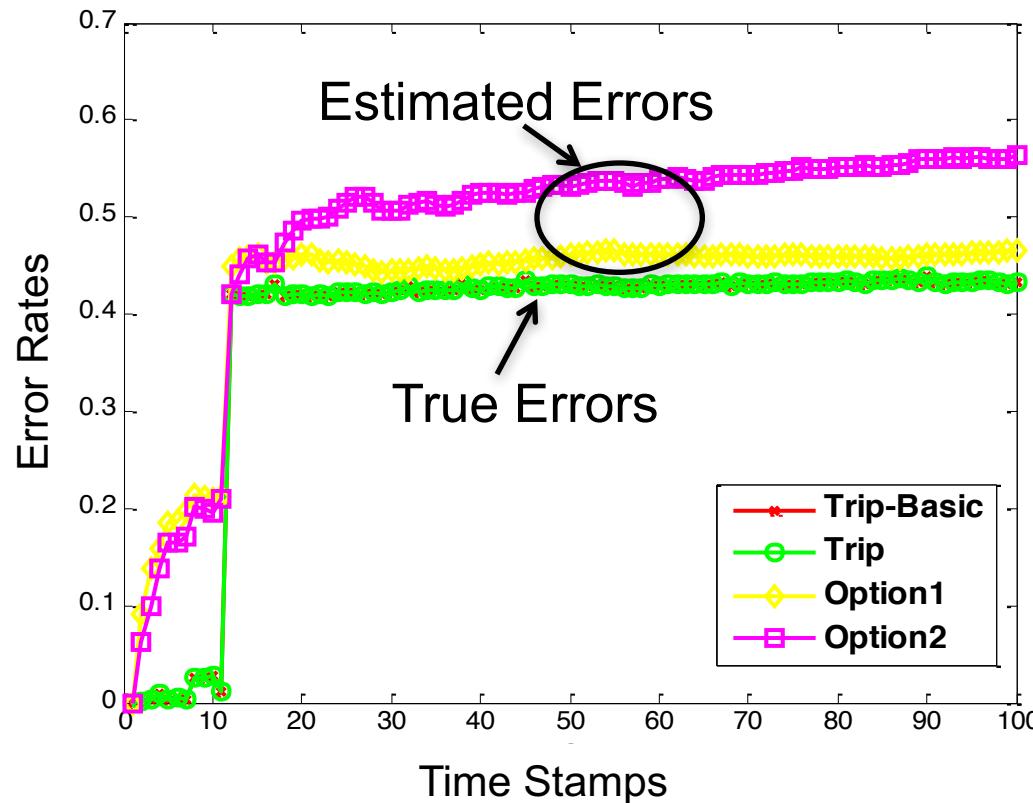


# Roadmap

- ✓ ■ Motivations
- ✓ ■ Q1: Efficient tracking algorithms
- ➡ ■ Q2: Error estimation methods
- Q3: Attribution analysis
- Conclusion

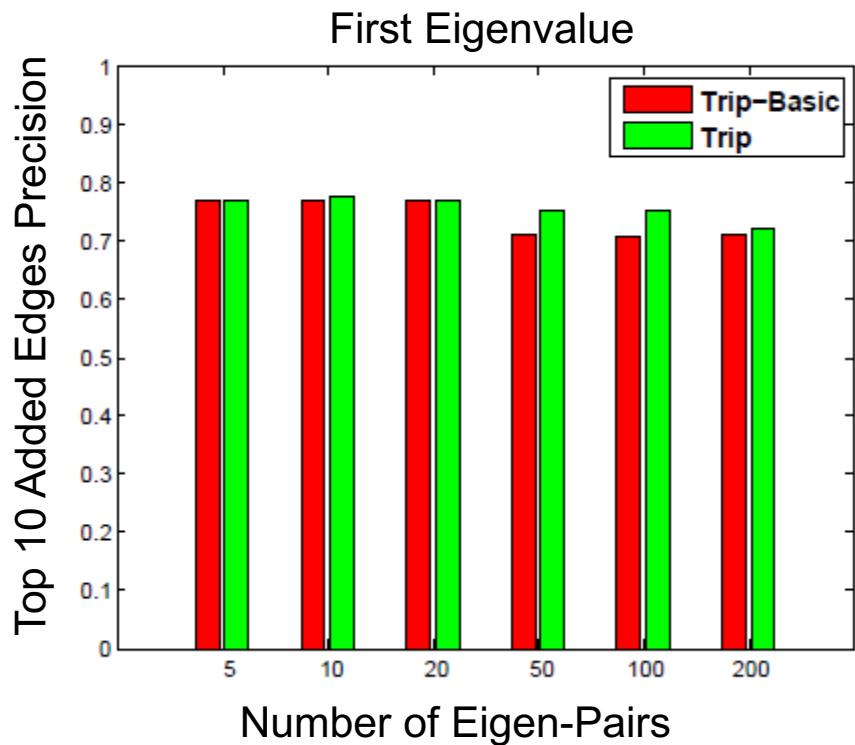
# Q2.Error Estimation

- Setting:  $c_1 = 0.005, c_2 = 0.025$

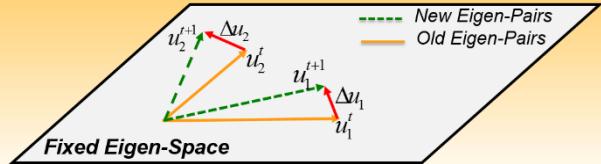


# Q3. Attribution Analysis

## ■ Precision (Edge Addition)



# Conclusion



- Goal: Tracking key graph parameters
- Solutions:
  - Key idea:
    - Fixed eigen-space, Matrix perturbation theory
  - Algorithms: Trip-Basic, Trip
- More Details:
  - Error Estimation
  - Attribution Analysis