



矩阵求导

$$\frac{\partial f(\mathbf{x})}{\partial \mathbf{x}}$$

矩阵求导公式的数学推导（矩阵求导——基础篇）



lterator

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0. 前言

1、看本文之前**请务必**先看这篇文章：

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矩阵求导
 $\frac{\partial f(\mathbf{x})}{\partial \mathbf{x}}$

下文以“本质篇”指代上面这篇文章。

2、本文介绍**向量变元的实值标量函数**、**矩阵变元的实值标量函数**中最基础的矩阵求导公式的**数学推导**。掌握了这些**最基础**的推导，才能理解之后的那些千变万化的**技巧**。

3、进阶的技巧（**矩阵的迹** $\text{tr}(\mathbf{A})$ 与**一阶实矩阵微分** $d\mathbf{X}$ ）会在**下一篇**讲，本篇不涉及。

4、本文使用的符号与**本质篇**相同。

5、看懂本文需要了解**本质篇**所提及的知识，以及了解本科阶段线性代数中**矩阵乘法**、**向量内积**的知识，**无需任何其他知识**。

6、有一个矩阵求导的网站，大家可以验证自己算的结果是否正确。

Matrix Calculus
www.matrixcalculus.org/

一. 向量变元的实值标量函数

$$f(\mathbf{x}), \mathbf{x} = [x_1, x_2, \dots, x_n]^T$$

我们使用**梯度向量**形式，即（本质篇_6）式



$$\nabla_{\mathbf{x}} f(\mathbf{x}) = \frac{\partial f(\mathbf{x})}{\partial \mathbf{x}} = \left[\frac{\partial f}{\partial x_1}, \frac{\partial f}{\partial x_2}, \dots, \frac{\partial f}{\partial x_n} \right]^T \quad (\text{本质篇}_6)$$

1、四个法则

1.1 常数求导^[1]:

与一元函数常数求导相同：结果为零向量

$$\frac{\partial c}{\partial \mathbf{x}} = \mathbf{0}_{n \times 1} \quad (1)$$

其中， c 为常数。

证明：

$$\begin{aligned} \frac{\partial c}{\partial \mathbf{x}} &= \begin{bmatrix} \frac{\partial c}{\partial x_1} \\ \frac{\partial c}{\partial x_2} \\ \vdots \\ \frac{\partial c}{\partial x_n} \end{bmatrix} \\ &= \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \end{bmatrix} \\ &= \mathbf{0}_{n \times 1} \end{aligned} \quad (2)$$

证毕。

1.2 线性法则^[1]

与一元函数求导线性法则相同：相加再求导等于求导再相加，常数提外面

$$\frac{\partial [c_1 f(\mathbf{x}) + c_2 g(\mathbf{x})]}{\partial \mathbf{x}} = c_1 \frac{\partial f(\mathbf{x})}{\partial \mathbf{x}} + c_2 \frac{\partial g(\mathbf{x})}{\partial \mathbf{x}} \quad (3)$$

其中， c_1, c_2 为常数。

证明：



$$\begin{aligned} \frac{\partial [c_1 f(\boldsymbol{x}) + c_2 g(\boldsymbol{x})]}{\partial \boldsymbol{x}} &= \begin{bmatrix} \frac{\partial (c_1 f + c_2 g)}{\partial x_1} \\ \frac{\partial (c_1 f + c_2 g)}{\partial x_2} \\ \vdots \\ \frac{\partial (c_1 f + c_2 g)}{\partial x_n} \end{bmatrix} \\ &= \begin{bmatrix} c_1 \frac{\partial f}{\partial x_1} + c_2 \frac{\partial g}{\partial x_1} \\ c_1 \frac{\partial f}{\partial x_2} + c_2 \frac{\partial g}{\partial x_2} \\ \vdots \\ c_1 \frac{\partial f}{\partial x_n} + c_2 \frac{\partial g}{\partial x_n} \end{bmatrix} \tag{4} \\ &= c_1 \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \\ \vdots \\ \frac{\partial f}{\partial x_n} \end{bmatrix} + c_2 \begin{bmatrix} \frac{\partial g}{\partial x_1} \\ \frac{\partial g}{\partial x_2} \\ \vdots \\ \frac{\partial g}{\partial x_n} \end{bmatrix} \\ &= c_1 \frac{\partial f(\boldsymbol{x})}{\partial \boldsymbol{x}} + c_2 \frac{\partial g(\boldsymbol{x})}{\partial \boldsymbol{x}} \end{aligned}$$

证毕。

1.3 乘积法则^[1]

与一元函数求导乘积法则相同：前导后不导 加 前不导后导

$$\frac{\partial [f(\boldsymbol{x})g(\boldsymbol{x})]}{\partial \boldsymbol{x}} = \frac{\partial f(\boldsymbol{x})}{\partial \boldsymbol{x}} g(\boldsymbol{x}) + f(\boldsymbol{x}) \frac{\partial g(\boldsymbol{x})}{\partial \boldsymbol{x}} \tag{5}$$

证明：



$$\begin{aligned}
 \frac{\partial[f(\mathbf{x})g(\mathbf{x})]}{\partial \mathbf{x}} &= \begin{bmatrix} \frac{\partial(fg)}{\partial x_1} \\ \frac{\partial(fg)}{\partial x_2} \\ \vdots \\ \frac{\partial(fg)}{\partial x_n} \end{bmatrix} \\
 &= \begin{bmatrix} \frac{\partial f}{\partial x_1}g + f\frac{\partial g}{\partial x_1} \\ \frac{\partial f}{\partial x_2}g + f\frac{\partial g}{\partial x_2} \\ \vdots \\ \frac{\partial f}{\partial x_n}g + f\frac{\partial g}{\partial x_n} \end{bmatrix} \\
 &= \begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \\ \vdots \\ \frac{\partial f}{\partial x_n} \end{bmatrix} g + f \begin{bmatrix} \frac{\partial g}{\partial x_1} \\ \frac{\partial g}{\partial x_2} \\ \vdots \\ \frac{\partial g}{\partial x_n} \end{bmatrix} \\
 &= \frac{\partial f(\mathbf{x})}{\partial \mathbf{x}} g(\mathbf{x}) + f(\mathbf{x}) \frac{\partial g(\mathbf{x})}{\partial \mathbf{x}}
 \end{aligned} \tag{6}$$

证毕。

1.4 商法则^[1]

与一元函数求导商法则相同：（上导下不导 减 上不导下导）除以（下的平方）：

$$\frac{\partial \left[\frac{f(\mathbf{x})}{g(\mathbf{x})} \right]}{\partial \mathbf{x}} = \frac{1}{g^2(\mathbf{x})} \left[\frac{\partial f(\mathbf{x})}{\partial \mathbf{x}} g(\mathbf{x}) - f(\mathbf{x}) \frac{\partial g(\mathbf{x})}{\partial \mathbf{x}} \right] \tag{7}$$

其中， $g(\mathbf{x}) \neq 0$ 。

证明：



$$\begin{aligned} \frac{\partial \left[\frac{f(\boldsymbol{x})}{g(\boldsymbol{x})} \right]}{\partial \boldsymbol{x}} &= \begin{bmatrix} \frac{\partial(\frac{f}{g})}{\partial x_1} \\ \frac{\partial(\frac{f}{g})}{\partial x_2} \\ \vdots \\ \frac{\partial(\frac{f}{g})}{\partial x_n} \end{bmatrix} \\ &= \begin{bmatrix} \frac{1}{g^2} \left(\frac{\partial f}{\partial x_1} g - f \frac{\partial g}{\partial x_1} \right) \\ \frac{1}{g^2} \left(\frac{\partial f}{\partial x_2} g - f \frac{\partial g}{\partial x_2} \right) \\ \vdots \\ \frac{1}{g^2} \left(\frac{\partial f}{\partial x_n} g - f \frac{\partial g}{\partial x_n} \right) \end{bmatrix} \\ &= \frac{1}{g^2} \left(\begin{bmatrix} \frac{\partial f}{\partial x_1} \\ \frac{\partial f}{\partial x_2} \\ \vdots \\ \frac{\partial f}{\partial x_n} \end{bmatrix} g - f \begin{bmatrix} \frac{\partial g}{\partial x_1} \\ \frac{\partial g}{\partial x_2} \\ \vdots \\ \frac{\partial g}{\partial x_n} \end{bmatrix} \right) \\ &= \frac{1}{g^2(\boldsymbol{x})} \left[\frac{\partial f(\boldsymbol{x})}{\partial \boldsymbol{x}} g(\boldsymbol{x}) - f(\boldsymbol{x}) \frac{\partial g(\boldsymbol{x})}{\partial \boldsymbol{x}} \right] \end{aligned} \tag{8}$$

证毕。

2、几个公式

2.1

$$\frac{\partial(\boldsymbol{x}^T \boldsymbol{a})}{\partial \boldsymbol{x}} = \frac{\partial(\boldsymbol{a}^T \boldsymbol{x})}{\partial \boldsymbol{x}} = \boldsymbol{a} \tag{9}$$

其中， \boldsymbol{a} 为常数向量， $\boldsymbol{a} = (a_1, a_2, \cdots, a_n)^T$ 。

证明：



$$\begin{aligned}
 \frac{\partial(\mathbf{x}^T \mathbf{a})}{\partial \mathbf{x}} &= \frac{\partial(\mathbf{a}^T \mathbf{x})}{\partial \mathbf{x}} \\
 &= \frac{\partial(a_1 x_1 + a_2 x_2 + \cdots + a_n x_n)}{\partial \mathbf{x}} \\
 &= \begin{bmatrix} \frac{\partial(a_1 x_1 + a_2 x_2 + \cdots + a_n x_n)}{\partial x_1} \\ \frac{\partial(a_1 x_1 + a_2 x_2 + \cdots + a_n x_n)}{\partial x_2} \\ \vdots \\ \frac{\partial(a_1 x_1 + a_2 x_2 + \cdots + a_n x_n)}{\partial x_n} \end{bmatrix} \\
 &= \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_n \end{bmatrix} \\
 &= \mathbf{a}
 \end{aligned} \tag{10}$$

证毕。

2.2

$$\frac{\partial(\mathbf{x}^T \mathbf{x})}{\partial \mathbf{x}} = 2\mathbf{x} \tag{11}$$

证明：

$$\begin{aligned}
 \frac{\partial(\mathbf{x}^T \mathbf{x})}{\partial \mathbf{x}} &= \frac{\partial(x_1^2 + x_2^2 + \cdots + x_n^2)}{\partial \mathbf{x}} \\
 &= \begin{bmatrix} \frac{\partial(x_1^2 + x_2^2 + \cdots + x_n^2)}{\partial x_1} \\ \frac{\partial(x_1^2 + x_2^2 + \cdots + x_n^2)}{\partial x_2} \\ \vdots \\ \frac{\partial(x_1^2 + x_2^2 + \cdots + x_n^2)}{\partial x_n} \end{bmatrix} \\
 &= \begin{bmatrix} 2x_1 \\ 2x_2 \\ \vdots \\ 2x_n \end{bmatrix} \\
 &= 2 \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \\
 &= 2\mathbf{x}
 \end{aligned} \tag{12}$$

证毕。



$$\frac{\partial(\mathbf{x}^T \mathbf{A} \mathbf{x})}{\partial \mathbf{x}} = \mathbf{A} \mathbf{x} + \mathbf{A}^T \mathbf{x} \quad (13)$$

其中, $\mathbf{A}_{n \times n}$ 是常数矩阵, $\mathbf{A}_{n \times n} = (a_{ij})_{i=1, j=1}^{n, n}$ 。

证明:

$$\begin{aligned} & \frac{\partial(\mathbf{x}^T \mathbf{A} \mathbf{x})}{\partial \mathbf{x}} = \frac{\partial(a_{11}x_1x_1 + a_{12}x_1x_2 + \cdots + a_{1n}x_1x_n + a_{21}x_2x_1 + a_{22}x_2x_2 + \cdots + a_{2n}x_2x_n + \cdots + a_{n1}x_nx_1 + a_{n2}x_nx_2 + \cdots + a_{nn}x_nx_n)}{\partial \mathbf{x}} \\ &= \begin{bmatrix} \frac{\partial(a_{11}x_1x_1 + a_{12}x_1x_2 + \cdots + a_{1n}x_1x_n + a_{21}x_2x_1 + a_{22}x_2x_2 + \cdots + a_{2n}x_2x_n + \cdots + a_{n1}x_nx_1 + a_{n2}x_nx_2 + \cdots + a_{nn}x_nx_n)}{\partial x_1} \\ \frac{\partial(a_{11}x_1x_1 + a_{12}x_1x_2 + \cdots + a_{1n}x_1x_n + a_{21}x_2x_1 + a_{22}x_2x_2 + \cdots + a_{2n}x_2x_n + \cdots + a_{n1}x_nx_1 + a_{n2}x_nx_2 + \cdots + a_{nn}x_nx_n)}{\partial x_2} \\ \vdots \\ \frac{\partial(a_{11}x_1x_1 + a_{12}x_1x_2 + \cdots + a_{1n}x_1x_n + a_{21}x_2x_1 + a_{22}x_2x_2 + \cdots + a_{2n}x_2x_n + \cdots + a_{n1}x_nx_1 + a_{n2}x_nx_2 + \cdots + a_{nn}x_nx_n)}{\partial x_n} \end{bmatrix} \\ &= \begin{bmatrix} (a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n) + (a_{11}x_1 + a_{21}x_2 + \cdots + a_{n1}x_n) \\ (a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n) + (a_{12}x_1 + a_{22}x_2 + \cdots + a_{n2}x_n) \\ \vdots \\ (a_{n1}x_1 + a_{n2}x_2 + \cdots + a_{nn}x_n) + (a_{1n}x_1 + a_{2n}x_2 + \cdots + a_{nn}x_n) \end{bmatrix} \\ &= \begin{bmatrix} a_{11}x_1 + a_{12}x_2 + \cdots + a_{1n}x_n \\ a_{21}x_1 + a_{22}x_2 + \cdots + a_{2n}x_n \\ \vdots \\ a_{n1}x_1 + a_{n2}x_2 + \cdots + a_{nn}x_n \end{bmatrix} + \begin{bmatrix} a_{11}x_1 + a_{21}x_2 + \cdots + a_{n1}x_n \\ a_{12}x_1 + a_{22}x_2 + \cdots + a_{n2}x_n \\ \vdots \\ a_{1n}x_1 + a_{2n}x_2 + \cdots + a_{nn}x_n \end{bmatrix} \\ &= \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{n1} & a_{n2} & \cdots & a_{nn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} + \begin{bmatrix} a_{11} & a_{21} & \cdots & a_{n1} \\ a_{12} & a_{22} & \cdots & a_{n2} \\ \vdots & \vdots & \ddots & \vdots \\ a_{1n} & a_{2n} & \cdots & a_{nn} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} \\ &= \mathbf{A} \mathbf{x} + \mathbf{A}^T \mathbf{x} \end{aligned} \quad (14)$$

证毕。

2.4

$$\frac{\partial(\mathbf{a}^T \mathbf{x} \mathbf{x}^T \mathbf{b})}{\partial \mathbf{x}} = \mathbf{a} \mathbf{b}^T \mathbf{x} + \mathbf{b} \mathbf{a}^T \mathbf{x} \quad (15)$$

其中, \mathbf{a}, \mathbf{b} 为常数向量, $\mathbf{a} = (a_1, a_2, \cdots, a_n)^T, \mathbf{b} = (b_1, b_2, \cdots, b_n)^T$ 。

证明:

因为 $\mathbf{a}^T \mathbf{x} = \mathbf{x}^T \mathbf{a}, \mathbf{x}^T \mathbf{b} = \mathbf{b}^T \mathbf{x}$, 所以有

$$\frac{\partial(\mathbf{a}^T \mathbf{x} \mathbf{x}^T \mathbf{b})}{\partial \mathbf{x}} = \frac{\partial(\mathbf{x}^T \mathbf{a} \mathbf{b}^T \mathbf{x})}{\partial \mathbf{x}} \quad (16)$$



$$\frac{\partial(\mathbf{a}^T \mathbf{x} \mathbf{x}^T \mathbf{b})}{\partial \mathbf{x}} = \frac{\partial(\mathbf{x}^T \mathbf{a} \mathbf{b}^T \mathbf{x})}{\partial \mathbf{x}} = \mathbf{a} \mathbf{b}^T \mathbf{x} + \mathbf{b} \mathbf{a}^T \mathbf{x} \quad (17)$$

证毕。

二. 矩阵变元的实值标量函数

$$f(\mathbf{X}), \mathbf{X}_{m \times n} = (x_{ij})_{i=1, j=1}^{m, n}$$

我们使用梯度矩阵形式，即（本质篇_11）式

$$\begin{aligned} \nabla_{\mathbf{X}} f(\mathbf{X}) &= \frac{\partial f(\mathbf{X})}{\partial \mathbf{X}_{m \times n}} \\ &= \begin{bmatrix} \frac{\partial f}{\partial x_{11}} & \frac{\partial f}{\partial x_{12}} & \cdots & \frac{\partial f}{\partial x_{1n}} \\ \frac{\partial f}{\partial x_{21}} & \frac{\partial f}{\partial x_{22}} & \cdots & \frac{\partial f}{\partial x_{2n}} \\ \vdots & \vdots & \vdots & \vdots \\ \frac{\partial f}{\partial x_{m1}} & \frac{\partial f}{\partial x_{m2}} & \cdots & \frac{\partial f}{\partial x_{mn}} \end{bmatrix}_{m \times n} \end{aligned} \quad (\text{本质篇}_{11})$$

1、四个法则

1.1 常数求导^[1]:

与一元函数常数求导相同：结果为零矩阵

$$\frac{\partial c}{\partial \mathbf{X}} = \mathbf{0}_{m \times n} \quad (18)$$

其中， c 为常数。

证明：

$$\begin{aligned} \frac{\partial c}{\partial \mathbf{X}} &= \begin{bmatrix} \frac{\partial c}{\partial x_{11}} & \frac{\partial c}{\partial x_{12}} & \cdots & \frac{\partial c}{\partial x_{1n}} \\ \frac{\partial c}{\partial x_{21}} & \frac{\partial c}{\partial x_{22}} & \cdots & \frac{\partial c}{\partial x_{2n}} \\ \vdots & \vdots & \vdots & \vdots \\ \frac{\partial c}{\partial x_{m1}} & \frac{\partial c}{\partial x_{m2}} & \cdots & \frac{\partial c}{\partial x_{mn}} \end{bmatrix}_{m \times n} \\ &= \begin{bmatrix} 0 & 0 & \cdots & 0 \\ 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \vdots & \vdots \\ 0 & 0 & \cdots & 0 \end{bmatrix}_{m \times n} \\ &= \mathbf{0}_{m \times n} \end{aligned} \quad (19)$$

证毕。

1.2 线性法则^[1]

与一元函数求导线性法则相同：相加再求导等于求导再相加，常数提外面

$$\frac{\partial[c_1 f(\mathbf{X}) + c_2 g(\mathbf{X})]}{\partial \mathbf{X}} = c_1 \frac{\partial f(\mathbf{X})}{\partial \mathbf{X}} + c_2 \frac{\partial g(\mathbf{X})}{\partial \mathbf{X}} \quad (20)$$



其中, c_1, c_2 为常数。

证明:

$$\begin{aligned}
 \frac{\partial [c_1 f(\mathbf{X}) + c_2 g(\mathbf{X})]}{\partial \mathbf{X}} &= \begin{bmatrix} \frac{\partial (c_1 f + c_2 g)}{\partial x_{11}} & \frac{\partial (c_1 f + c_2 g)}{\partial x_{12}} & \cdots & \frac{\partial (c_1 f + c_2 g)}{\partial x_{1n}} \\ \frac{\partial (c_1 f + c_2 g)}{\partial x_{21}} & \frac{\partial (c_1 f + c_2 g)}{\partial x_{22}} & \cdots & \frac{\partial (c_1 f + c_2 g)}{\partial x_{2n}} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial (c_1 f + c_2 g)}{\partial x_{m1}} & \frac{\partial (c_1 f + c_2 g)}{\partial x_{m2}} & \cdots & \frac{\partial (c_1 f + c_2 g)}{\partial x_{mn}} \end{bmatrix} \\
 &= \begin{bmatrix} c_1 \frac{\partial f}{\partial x_{11}} + c_2 \frac{\partial g}{\partial x_{11}} & c_1 \frac{\partial f}{\partial x_{12}} + c_2 \frac{\partial g}{\partial x_{12}} & \cdots & c_1 \frac{\partial f}{\partial x_{1n}} + c_2 \frac{\partial g}{\partial x_{1n}} \\ c_1 \frac{\partial f}{\partial x_{21}} + c_2 \frac{\partial g}{\partial x_{21}} & c_1 \frac{\partial f}{\partial x_{22}} + c_2 \frac{\partial g}{\partial x_{22}} & \cdots & c_1 \frac{\partial f}{\partial x_{2n}} + c_2 \frac{\partial g}{\partial x_{2n}} \\ \vdots & \vdots & \ddots & \vdots \\ c_1 \frac{\partial f}{\partial x_{m1}} + c_2 \frac{\partial g}{\partial x_{m1}} & c_1 \frac{\partial f}{\partial x_{m2}} + c_2 \frac{\partial g}{\partial x_{m2}} & \cdots & c_1 \frac{\partial f}{\partial x_{mn}} + c_2 \frac{\partial g}{\partial x_{mn}} \end{bmatrix} \quad (21) \\
 &= c_1 \begin{bmatrix} \frac{\partial f}{\partial x_{11}} & \frac{\partial f}{\partial x_{12}} & \cdots & \frac{\partial f}{\partial x_{1n}} \\ \frac{\partial f}{\partial x_{21}} & \frac{\partial f}{\partial x_{22}} & \cdots & \frac{\partial f}{\partial x_{2n}} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial f}{\partial x_{m1}} & \frac{\partial f}{\partial x_{m2}} & \cdots & \frac{\partial f}{\partial x_{mn}} \end{bmatrix} + c_2 \begin{bmatrix} \frac{\partial g}{\partial x_{11}} & \frac{\partial g}{\partial x_{12}} & \cdots & \frac{\partial g}{\partial x_{1n}} \\ \frac{\partial g}{\partial x_{21}} & \frac{\partial g}{\partial x_{22}} & \cdots & \frac{\partial g}{\partial x_{2n}} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial g}{\partial x_{m1}} & \frac{\partial g}{\partial x_{m2}} & \cdots & \frac{\partial g}{\partial x_{mn}} \end{bmatrix} \\
 &= c_1 \frac{\partial f(\mathbf{X})}{\partial \mathbf{X}} + c_2 \frac{\partial g(\mathbf{X})}{\partial \mathbf{X}}
 \end{aligned}$$

证毕。

1.3 乘积法则^[1]

与一元函数求导乘积法则相同：前导后不导 加 前不导后导

$$\frac{\partial [f(\mathbf{X})g(\mathbf{X})]}{\partial \mathbf{X}} = \frac{\partial f(\mathbf{X})}{\partial \mathbf{X}} g(\mathbf{X}) + f(\mathbf{X}) \frac{\partial g(\mathbf{X})}{\partial \mathbf{X}} \quad (22)$$

证明:

$$\begin{aligned}
 \frac{\partial [f(\mathbf{X})g(\mathbf{X})]}{\partial \mathbf{X}} &= \begin{bmatrix} \frac{\partial (fg)}{\partial x_{11}} & \frac{\partial (fg)}{\partial x_{12}} & \cdots & \frac{\partial (fg)}{\partial x_{1n}} \\ \frac{\partial (fg)}{\partial x_{21}} & \frac{\partial (fg)}{\partial x_{22}} & \cdots & \frac{\partial (fg)}{\partial x_{2n}} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial (fg)}{\partial x_{m1}} & \frac{\partial (fg)}{\partial x_{m2}} & \cdots & \frac{\partial (fg)}{\partial x_{mn}} \end{bmatrix} \\
 &= \begin{bmatrix} \frac{\partial f}{\partial x_{11}} g + f \frac{\partial g}{\partial x_{11}} & \frac{\partial f}{\partial x_{12}} g + f \frac{\partial g}{\partial x_{12}} & \cdots & \frac{\partial f}{\partial x_{1n}} g + f \frac{\partial g}{\partial x_{1n}} \\ \frac{\partial f}{\partial x_{21}} g + f \frac{\partial g}{\partial x_{21}} & \frac{\partial f}{\partial x_{22}} g + f \frac{\partial g}{\partial x_{22}} & \cdots & \frac{\partial f}{\partial x_{2n}} g + f \frac{\partial g}{\partial x_{2n}} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial f}{\partial x_{m1}} g + f \frac{\partial g}{\partial x_{m1}} & \frac{\partial f}{\partial x_{m2}} g + f \frac{\partial g}{\partial x_{m2}} & \cdots & \frac{\partial f}{\partial x_{mn}} g + f \frac{\partial g}{\partial x_{mn}} \end{bmatrix} \quad (23) \\
 &= \begin{bmatrix} \frac{\partial f}{\partial x_{11}} & \frac{\partial f}{\partial x_{12}} & \cdots & \frac{\partial f}{\partial x_{1n}} \\ \frac{\partial f}{\partial x_{21}} & \frac{\partial f}{\partial x_{22}} & \cdots & \frac{\partial f}{\partial x_{2n}} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial f}{\partial x_{m1}} & \frac{\partial f}{\partial x_{m2}} & \cdots & \frac{\partial f}{\partial x_{mn}} \end{bmatrix} g + f \begin{bmatrix} \frac{\partial g}{\partial x_{11}} & \frac{\partial g}{\partial x_{12}} & \cdots & \frac{\partial g}{\partial x_{1n}} \\ \frac{\partial g}{\partial x_{21}} & \frac{\partial g}{\partial x_{22}} & \cdots & \frac{\partial g}{\partial x_{2n}} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial g}{\partial x_{m1}} & \frac{\partial g}{\partial x_{m2}} & \cdots & \frac{\partial g}{\partial x_{mn}} \end{bmatrix} \\
 &= \frac{\partial f(\mathbf{X})}{\partial \mathbf{X}} g(\mathbf{X}) + f(\mathbf{X}) \frac{\partial g(\mathbf{X})}{\partial \mathbf{X}}
 \end{aligned}$$

1.4 商法则^[1]

与一元函数求导商法则相同：（上导下不导 减 上不导下导）除以（下的平方）：

$$\frac{\partial \left[\frac{f(\boldsymbol{X})}{g(\boldsymbol{X})} \right]}{\partial \boldsymbol{X}} = \frac{1}{g^2(\boldsymbol{X})} \left[\frac{\partial f(\boldsymbol{X})}{\partial \boldsymbol{X}} g(\boldsymbol{X}) - f(\boldsymbol{X}) \frac{\partial g(\boldsymbol{X})}{\partial \boldsymbol{X}} \right]$$

(24)

其中， $g(\boldsymbol{X}) \neq 0$ 。

证明：



证毕。

2、几个公式

2.1

$$\frac{\partial (\boldsymbol{a}^T \boldsymbol{X} \boldsymbol{b})}{\partial \boldsymbol{X}} = \boldsymbol{a} \boldsymbol{b}^T$$

(26)

其中， $\boldsymbol{a}_{m \times 1}, \boldsymbol{b}_{n \times 1}$ 为常数向量， $\boldsymbol{a} = (a_1, a_2, \dots, a_m)^T, \boldsymbol{b} = (b_1, b_2, \dots, b_n)^T$ 。

证明（右击公式，选择在新标签页中打开图片，公式就可以放大了~）：

$$\begin{aligned} & \frac{\partial (\boldsymbol{a}^T \boldsymbol{X} \boldsymbol{b})}{\partial \boldsymbol{X}} = \frac{\begin{matrix} \partial(a_1 b_1 x_{11} + a_1 b_2 x_{12} + \dots + a_1 b_n x_{1n} \\ + a_2 b_1 x_{21} + a_2 b_2 x_{22} + \dots + a_2 b_n x_{2n} \\ + \dots \\ + a_m b_1 x_{m1} + a_m b_2 x_{m2} + \dots + a_m b_n x_{mn}) \end{matrix}}{\partial \boldsymbol{X}} \\ &= \begin{bmatrix} \frac{\partial(a_1 b_1 x_{11} + a_1 b_2 x_{12} + \dots + a_1 b_n x_{1n} + a_2 b_1 x_{21} + a_2 b_2 x_{22} + \dots + a_2 b_n x_{2n} + \dots + a_m b_1 x_{m1} + a_m b_2 x_{m2} + \dots + a_m b_n x_{mn})}{\partial x_{11}} & \frac{\partial(a_1 b_1 x_{11} + a_1 b_2 x_{12} + \dots + a_1 b_n x_{1n} + a_2 b_1 x_{21} + a_2 b_2 x_{22} + \dots + a_2 b_n x_{2n} + \dots + a_m b_1 x_{m1} + a_m b_2 x_{m2} + \dots + a_m b_n x_{mn})}{\partial x_{12}} & \dots & \frac{\partial(a_1 b_1 x_{11} + a_1 b_2 x_{12} + \dots + a_1 b_n x_{1n} + a_2 b_1 x_{21} + a_2 b_2 x_{22} + \dots + a_2 b_n x_{2n} + \dots + a_m b_1 x_{m1} + a_m b_2 x_{m2} + \dots + a_m b_n x_{mn})}{\partial x_{1n}} \\ \frac{\partial(a_1 b_1 x_{11} + a_1 b_2 x_{12} + \dots + a_1 b_n x_{1n} + a_2 b_1 x_{21} + a_2 b_2 x_{22} + \dots + a_2 b_n x_{2n} + \dots + a_m b_1 x_{m1} + a_m b_2 x_{m2} + \dots + a_m b_n x_{mn})}{\partial x_{21}} & \frac{\partial(a_1 b_1 x_{11} + a_1 b_2 x_{12} + \dots + a_1 b_n x_{1n} + a_2 b_1 x_{21} + a_2 b_2 x_{22} + \dots + a_2 b_n x_{2n} + \dots + a_m b_1 x_{m1} + a_m b_2 x_{m2} + \dots + a_m b_n x_{mn})}{\partial x_{22}} & \dots & \frac{\partial(a_1 b_1 x_{11} + a_1 b_2 x_{12} + \dots + a_1 b_n x_{1n} + a_2 b_1 x_{21} + a_2 b_2 x_{22} + \dots + a_2 b_n x_{2n} + \dots + a_m b_1 x_{m1} + a_m b_2 x_{m2} + \dots + a_m b_n x_{mn})}{\partial x_{2n}} \\ \vdots & \vdots & \ddots & \vdots \\ \frac{\partial(a_1 b_1 x_{11} + a_1 b_2 x_{12} + \dots + a_1 b_n x_{1n} + a_2 b_1 x_{21} + a_2 b_2 x_{22} + \dots + a_2 b_n x_{2n} + \dots + a_m b_1 x_{m1} + a_m b_2 x_{m2} + \dots + a_m b_n x_{mn})}{\partial x_{m1}} & \frac{\partial(a_1 b_1 x_{11} + a_1 b_2 x_{12} + \dots + a_1 b_n x_{1n} + a_2 b_1 x_{21} + a_2 b_2 x_{22} + \dots + a_2 b_n x_{2n} + \dots + a_m b_1 x_{m1} + a_m b_2 x_{m2} + \dots + a_m b_n x_{mn})}{\partial x_{m2}} & \dots & \frac{\partial(a_1 b_1 x_{11} + a_1 b_2 x_{12} + \dots + a_1 b_n x_{1n} + a_2 b_1 x_{21} + a_2 b_2 x_{22} + \dots + a_2 b_n x_{2n} + \dots + a_m b_1 x_{m1} + a_m b_2 x_{m2} + \dots + a_m b_n x_{mn})}{\partial x_{mn}} \end{bmatrix}_{m \times n} \\ &= \begin{bmatrix} a_1 b_1 & a_1 b_2 & \dots & a_1 b_n \\ a_2 b_1 & a_2 b_2 & \dots & a_2 b_n \\ \vdots & \vdots & \ddots & \vdots \\ a_m b_1 & a_m b_2 & \dots & a_m b_n \end{bmatrix}_{m \times n} \\ &= \begin{bmatrix} a_1 \\ a_2 \\ \vdots \\ a_m \end{bmatrix} [b_1, b_2, \dots, b_n] \\ &= \boldsymbol{a} \boldsymbol{b}^T \end{aligned}$$

(27)

证毕。

2.2

$$\frac{\partial (\boldsymbol{a}^T \boldsymbol{X}^T \boldsymbol{b})}{\partial \boldsymbol{X}} = \boldsymbol{b} \boldsymbol{a}^T$$

(28)

其中， $\boldsymbol{a}_{n \times 1}, \boldsymbol{b}_{m \times 1}$ 为常数向量， $\boldsymbol{a} = (a_1, a_2, \dots, a_n)^T, \boldsymbol{b} = (b_1, b_2, \dots, b_m)^T$ 。

证明：



$$\frac{\partial(\mathbf{a}^T \mathbf{X}^T \mathbf{b})}{\partial \mathbf{X}} = \frac{\partial(\mathbf{a}^T \mathbf{X}^T \mathbf{b})^T}{\partial \mathbf{X}} = \frac{\partial(\mathbf{b}^T \mathbf{X} \mathbf{a})}{\partial \mathbf{X}} \quad (29)$$

由 (26) 式得:

$$\frac{\partial(\mathbf{a}^T \mathbf{X}^T \mathbf{b})}{\partial \mathbf{X}} = \frac{\partial(\mathbf{b}^T \mathbf{X} \mathbf{a})}{\partial \mathbf{X}} = \mathbf{b} \mathbf{a}^T \quad (30)$$

证毕。

2.3

$$\frac{\partial(\mathbf{a}^T \mathbf{X} \mathbf{X}^T \mathbf{b})}{\partial \mathbf{X}} = \mathbf{a} \mathbf{b}^T \mathbf{X} + \mathbf{b} \mathbf{a}^T \mathbf{X} \quad (31)$$

其中, $\mathbf{a}_{m \times 1}, \mathbf{b}_{m \times 1}$ 为常数向量, $\mathbf{a} = (a_1, a_2, \dots, a_m)^T, \mathbf{b} = (b_1, b_2, \dots, b_m)^T$ 。

证明 (右击公式, 选择在新标签页中打开图片, 公式就可以放大了~):



证毕。

2.4

$$\frac{\partial(\mathbf{a}^T \mathbf{X}^T \mathbf{X} \mathbf{b})}{\partial \mathbf{X}} = \mathbf{X} \mathbf{b} \mathbf{a}^T + \mathbf{X} \mathbf{a} \mathbf{b}^T \quad (33)$$

其中, $\mathbf{a}_{n \times 1}, \mathbf{b}_{n \times 1}$ 为常数向量, $\mathbf{a} = (a_1, a_2, \dots, a_n)^T, \mathbf{b} = (b_1, b_2, \dots, b_n)^T$ 。

证明:

我们来看一下 (本质篇_9) 式:

$$\begin{aligned} \mathbf{D}_{\mathbf{X}} f(\mathbf{X}) &= \frac{\partial f(\mathbf{X})}{\partial \mathbf{X}_{m \times n}^T} \\ &= \begin{bmatrix} \frac{\partial f}{\partial x_{11}} & \frac{\partial f}{\partial x_{21}} & \dots & \frac{\partial f}{\partial x_{m1}} \\ \frac{\partial f}{\partial x_{12}} & \frac{\partial f}{\partial x_{22}} & \dots & \frac{\partial f}{\partial x_{m2}} \\ \vdots & \vdots & \vdots & \vdots \\ \frac{\partial f}{\partial x_{1n}} & \frac{\partial f}{\partial x_{2n}} & \dots & \frac{\partial f}{\partial x_{mn}} \end{bmatrix}_{n \times m} \end{aligned} \quad (\text{本质篇}_9)$$

再来看一下 (本质篇_11) 式:

$$\begin{aligned} \nabla_{\mathbf{X}} f(\mathbf{X}) &= \frac{\partial f(\mathbf{X})}{\partial \mathbf{X}_{m \times n}} \\ &= \begin{bmatrix} \frac{\partial f}{\partial x_{11}} & \frac{\partial f}{\partial x_{12}} & \dots & \frac{\partial f}{\partial x_{1n}} \\ \frac{\partial f}{\partial x_{21}} & \frac{\partial f}{\partial x_{22}} & \dots & \frac{\partial f}{\partial x_{2n}} \\ \vdots & \vdots & \vdots & \vdots \\ \frac{\partial f}{\partial x_{m1}} & \frac{\partial f}{\partial x_{m2}} & \dots & \frac{\partial f}{\partial x_{mn}} \end{bmatrix}_{m \times n} \end{aligned} \quad (\text{本质篇}_{11})$$



$$\frac{\partial f(\mathbf{X})}{\partial \mathbf{X}_{m \times n}^T} = \left(\frac{\partial f(\mathbf{X})}{\partial \mathbf{X}_{m \times n}} \right)^T \quad (34)$$

所以，我们把 (31) 式中的分母的**矩阵变元**写为**转置**，就有：

$$\begin{aligned} \frac{\partial (\mathbf{a}^T \mathbf{X} \mathbf{X}^T \mathbf{b})}{\partial \mathbf{X}^T} &= \left(\frac{\partial (\mathbf{a}^T \mathbf{X} \mathbf{X}^T \mathbf{b})}{\partial \mathbf{X}} \right)^T \\ &= (\mathbf{a} \mathbf{b}^T \mathbf{X} + \mathbf{b} \mathbf{a}^T \mathbf{X})^T \\ &= \mathbf{X}^T \mathbf{b} \mathbf{a}^T + \mathbf{X}^T \mathbf{a} \mathbf{b}^T \end{aligned} \quad (35)$$

对于 (33) 式，我们将其写为如下形式：

$$\frac{\partial (\mathbf{a}^T \mathbf{X}^T \mathbf{X} \mathbf{b})}{\partial \mathbf{X}} = \frac{\partial (\mathbf{a}^T (\mathbf{X}^T) (\mathbf{X}^T)^T \mathbf{b})}{\partial (\mathbf{X}^T)^T} \quad (36)$$

然后对 (36) 式使用 (35) 式，得：

$$\begin{aligned} \frac{\partial (\mathbf{a}^T \mathbf{X}^T \mathbf{X} \mathbf{b})}{\partial \mathbf{X}} &= \frac{\partial (\mathbf{a}^T (\mathbf{X}^T) (\mathbf{X}^T)^T \mathbf{b})}{\partial (\mathbf{X}^T)^T} \\ &= (\mathbf{X}^T)^T \mathbf{b} \mathbf{a}^T + (\mathbf{X}^T)^T \mathbf{a} \mathbf{b}^T \\ &= \mathbf{X} \mathbf{b} \mathbf{a}^T + \mathbf{X} \mathbf{a} \mathbf{b}^T \end{aligned} \quad (37)$$

证毕。

三. 完

本文到这里就结束了，相信大家也和我一样，会觉的后面那几个求导公式，如果**按照定义**去推导的话，**十分的麻烦，而且容易出错**。

所以，在下一篇文章中，我们将介绍**向量变元的实值标量函数**、**矩阵变元的实值标量函数**进阶的矩阵求导的技巧：**矩阵的迹 $\text{tr}(\mathbf{A})$** 与**一阶实矩阵微分 $d\mathbf{X}$** ，它们可以极大地化简我们的推导过程。

欢迎大家点赞、关注、收藏、转发噢~

矩阵求导系列其他文章：

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[矩阵求导的本质与分子布局、分母布局的本质（矩阵求导——本质篇） - Iterator的文章 - 知乎](#)

参考

编辑于 2020-12-10 15:06



「真诚赞赏，手留余香」

赞赏

4 人已赞赏




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$$\frac{\partial f(\boldsymbol{x})}{\partial \boldsymbol{x}}$$

对称矩阵的求导，以多元布斯的极大似然估计为例

Iterator




42 条评论

切换为时间排序

写下你的评论...



精选评论 (3)

-  **Iterator (作者)** 回复 吃酸奶只舔盖
z3.ax1x.com/2021/10/27/...
2021-10-27
4 查看回复
-  **Iterator (作者)**
2021-09-30
知乎的公式渲染好像经常崩溃，有一些比较长的公式会显示不出来，大家可以按照评论区置顶的方法，拿到latex代码后，用typora或者其他支持mathjax的markdown编辑器查看。
赞
-  **Iterator (作者)**
2021-01-12



右击公式，选择在新标签页中打开，然后复制url中的/equation?tex= 后面一堆的代码，然后去 [UrlEncode编码/UrlDecode解码 - 站长工具](#) 这个地方选择UrlDecode，就可以看到latex代码了。（如果代码比较长可以按住shift + end可以直接拖到末尾）例如 [zhihu.com/equation?...](#)

复制的内容为： f%28x%29%3Dx%2B2+%5C%5C%5C%5C+%5Ctag%7Be.g.1%7D



👍 3

评论 (42)


 钢铁直男

2021-02-25

感谢感谢，我的机器学习有救了


 

👍 4


 anonymous

03-20

矩阵求导典型的在数学课被直接忽略的内容。国内除了数学系的，其他很多都没管这方面内容



👍 2

 吃酸奶只舔盖

2021-09-15

答主，有部分图片挂了，能更新一下么。谢谢

👍 2

 Iterator (作者) 回复 吃酸奶只舔盖

2021-10-27

[z3.ax1x.com/2021/10/27/...](#)

👍 4  查看回复

 ainiweibai 回复 Iterator (作者)

06-09

感谢答主！！


👍 赞

 何其速也

2020-11-11

建议你去看下贾松圭的矩阵不等式

👍 2


 Iterator (作者) 回复 何其速也

2020-11-11

啊？为什么？



👍 赞

 何其速也 回复 Iterator (作者)

2020-11-11

有个转换公式之类的，可以方便解决你文章里的计算

👍 1

[查看全部 6 条回复](#)

 幼安

2021-11-05

感谢作者救命🙏

👍 赞

 III

2021-10-21



- Iterator (作者) 回复 III

2021-10-21
- 应该就挂了几个，我现在都不敢动它 = = 不过你看置顶评论，能有办法看挂的公式
- 赞

晨风

2021-10-12

大佬再接再厉！

赞

枝江hku

2021-09-26

瑞思拜

赞

海峰

2021-09-24

作者了不起

赞

呈寻糯米叉烧包

2021-09-19

我大受震撼

赞

Eric

2021-09-12

作者分子、分母布局的定义搞不清楚，很多和教材反了

赞

Iterator (作者) 回复 Eric

2021-09-12

这两个名词“分子布局、分母布局”在一些经典的矩阵分析书籍（张贤达、史荣昌）中压根就没有提过，不过是网上流传的很多讲义上为了方便直观理解而给出的，然后后来的人也不考虑严谨性就直接给沿用了。不知道你说的教材是指专门的机器学习教材还是矩阵分析教材？可以给出书籍名称和页码，我校正一下。

5

雁过无声

2021-08-25

公式2.3的图显示不出来，网页版和APP都看不见。不过还是谢谢答主了🙏

赞

雁过无声

2021-08-24

感谢作者

赞

Perry Yang

2021-05-12

建议亲可以把最后一行放到开头

赞

zerolord

2021-03-25

太贴心了，作者棒棒！👍

赞

酱二狗

2021-03-17

哈哈我最近也在看张贤达老师的书，答主码字总结辛苦了！！！个人习惯求行向量偏导，感觉答主的例题是不是求的梯度嘞，总和你差个转置~不得不说迹那块的技巧太丰富了，我这几天已经傻了

赞

A导

2021-02-24

答主数学公式用什么软件生成的

赞

Iterator (作者) 回复 A导

2021-02-24



A导 回复 Iterator (作者)

2021-02-26

好的，我用的AXMath，感觉并不是很方便

👍 赞

1 2 下一页