Kaiyuan Xu



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Education

Junior, *Tsinghua University*, Beijing. Department of Automation Engineering GPA: 85/100 Ranking:65/140

Sept.2012-Present

Experience

Autonomous Soccer Robot Control System Based on ROS

Lead Developer.

Sept.2013-July.2014

- Building a new ROS-based autonomous robot software system consisting of Vision, Behavior, Motion Control and Simulation which was used in RoboCup2014, Brazil;
- Member of Tsinghua Hephaestus, the Robocup Soccer Team of China in AdultSize, Humanoid League;
- Lead developer of the Motion part;

Programming Platform Based on C++ and Unity3D

Team Leader.

Sept.2013-May.2014

- Building a new programming platform which consists of Logic, UI and network for the programming contest for freshmen in Department of Automation Engineering, Tsinghua University;
- Leader of a 10-people team and technical leader of the Logic part.

Two-Wheel Self-Balanced Vehicle Based on Myrio

Team Leader.

Nov.2014-Jan.2015

- Building a self-balanced vehicle control system based on myrio which has the function of self-balancing, moving forward and backward and turning.
- Leader of a 3-people team and responsible for control algorithm and filtering of the gyro.

Cross-platform P2P Instant Messenger

Team Leader.

Dec.2014-Jan.2015

- Course project, building a cross-platform P2P instant messenger on both PC and Android, with functions like chatting, file transmission and voice chat, etc.
- Leader of a 3-people team and responsible for android developing and voice that

AI for Game 2048 based on Machine Learning

Leader Developer.

Dec.2014

- o Course project, developing an AI to play 2048 game using machine learning.
- Developing an AI which has a 84.4% winning percentage and has a possibility of 46.8% to achieve 4096.
- Cooperating with a classmate and responsible for the realization of TDL algorithm and UI.

Languages

English: *CET-4: 640/710 CET-6: 565/710*

Computer skills

Computer Language: C, C++, C#, JAVA(Android)

Other Language: Verilog, LATEX

Professional Softwares: Visual Studio, Qt Creator, Ecilipse, Unity3D, Matlab, LabVIEW, Multisim, QuartusII, Modelsim, Altium Designer

Awards and Fellowships

Awards:.

- 3rd Place in RoboCup2014 Soccer Robot Humanoid league AdultSize Competition(*Team member*)
- 3rd Place in RoboCup2014 Soccer Robot Humanoid league AdultSize Technical Challenge(Team member)

Fellowships:.

Tsinghua Fellowship for Technology Innovation

Social Activities

Minister. Sept.2013–Jul.2014

Network Ministry of Student Technology Association of Automation

Teach Assistant. Sept.2014–Jul.2015

Undergraduate Curriculum: Interdisciplinary Research Training of Prof. Mingguo Zhao

徐凯源



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教育背景

本科,清华大学,北京.

自动化系

学分绩: 85/100 排名: 65/140

2012.9 至今

项目经历

基于 ROS 平台的足球机器人自动控制系统

主要成员.

2013.9 - 2014.7

- o 建立基于 ROS 平台的足球机器人软件系统,包括视觉、步态、决策、仿真四部分。该系统用于 2014 年在巴西举办的 RoboCup 中。
- 。 清华火神队成员,参加 RoboCup 机器人足球人型组成人组别比赛。
- 步态组核心成员。

清华大学自动化系新生 C 语言大赛比赛平台

平台组组长.

2013.9 - 2014.7

- 。 搭建 C 语言大赛比赛平台,主要包括逻辑、渲染、网络三部分。该平台用于 2014 年清华大学自动化系新生 C 语言比赛中。
- 领导 10 人团队完成基于 C++ 的逻辑底层、基于 Unity 3D 的前端渲染和基于 Qt 及 MySQL 的网络通信。
- 平台组组长,逻辑组负责人。

基于 NI Myrio 平台的自平衡车

项目组组长.

2014.11 - 2015.1

- o 设计开发基于 Myrio 的自平衡车控制系统,实现自平衡、前进后退、转向等功能。
- 三人项目组组长,负责控制算法和陀螺仪滤波。

跨平台 P2P 即时通信软件

项目组组长.

2014.12 - 2015.1

- 。 课程项目,设计开发跨平台 P2P 聊天工具,可在个人电脑和安卓端运行。
- 。 具备聊天、文件传输和语音聊天功能。
- 三人项目组组长,负责安卓端开发和语音聊天。

基于机器学习的 2048 游戏 AI 设计

主要成员.

2014.12

- · 课程项目,利用机器学习,设计开发 2048 游戏自动算法。
- 设计的 AI 最终胜率达 84.4%, 达到 4096 的概率达 46.8%。
- o 两人合作完成,负责 TDL 算法的实现和界面的编写。

语言技能

英语: 四级: *640/710* 六级: *565/710*

计算机技能

编程语言: C, C++, C#, JAVA(Android)

其他语言: Verilog, LATEX

专业工具: Visual Studio, Qt Creator, Ecilipse, Unity3D, Matlab, Lab-

VIEW, Multisim, QuartusII, Modelsim, Altium Designer

获奖情况

竞赛获奖.

。 2014 年 RoboCup 机器人足球人型组成人组别第三名 (队员)

o 2014 年 RoboCup 机器人足球人型组成人组别技巧挑战赛第三名 (队员) 奖学金.

。 2013-2014 清华大学科技创新优秀奖(校设奖学金)

社会活动

部长. 2013.9-2014.7

清华大学自动化系科协网络部

助教. 2014.9 至今

本科生课程: 交叉训练项目, 开课教师: 赵明国副教授