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```
% BME/EECS516
% MRI Project Template
clc
clear all
% Other m-files required: ift2, ift, ft2, ft, blochsim_516
% Subfunctions: none
% MAT-files required: object18.mat

%Programme: YUZHOU CHEN
%DATA:November 23, 2023
%Oct 2022;
%Last revision: Oct-30-2022
```

Select whether to load complex 2D object or create simple point object

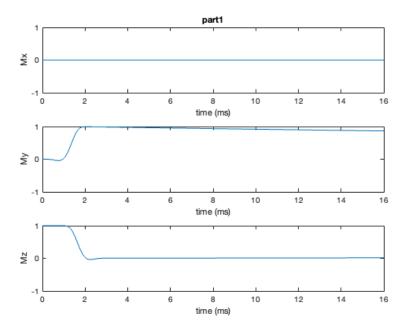
```
complexobj = 0;
if complexobj
  % 2D Object for reconstruction
  load object23;
else
  % Single point object at (x,y,z) = (2,2,0) cm;
 % Point object has T1 of 1000 ms, T2 of 100 ms
 obj_x = 4;
 obj_y = 4;
 obj_z = 0;
 obj_T1 = 1000;
 obj_T2 = 100;
FOVx = 16;
FOVy = 12;
Nx = 80;
Ny = 60;
T read = 8;
T_y = 2;
obj_n = length(obj_x); % Determine number of objects
```

Define simulation constants

Physical constants

```
\mbox{\ensuremath{\$}} Initialize B vectors, the effective (\mbox{\ensuremath{x}},\mbox{\ensuremath{y}},\mbox{\ensuremath{z}}) applied magnetic field
% Vectors define applied magnetic field at time tp n for object obj n
bx = zeros([totalTimepoints obj_n]);
by = zeros([totalTimepoints obj_n]);
bz = zeros([totalTimepoints obj_n]);
% Define a 90 RF pulse
rf90pw = 3;
                               % Pulse width in ms
sincper = rf90pw/4;
                               % in ms (this is the sinc stretch parameter)
                               % e.g. sinc(time/sincper) as shown below
rf_timepoints = rf90pw/dt;
                               % Number of simulation steps for RF
rf_time = [-(rf_timepoints-1) / 2 : (rf_timepoints-1) / 2]'.*dt; % Time vector for creating sinc, centered at 0
rf_shape = hanning(rf_timepoints) .* sinc(rf_time./sincper); % Sinc waveform shape with hanning window, with amplitude 1
rf_amplitude90 = (pi / 2)/(gam * dt * sum(rf_shape));
                                                                  % REPLACE 0 with amplitude of the RF pulse here, in T
% Scale rf shape by a rf90 (amplitude), then fill the remainder of the time with zeros
b1_90 = rf_amplitude90.*[rf_shape; zeros([totalTimepoints-rf_timepoints 1])];
m0 = [0; 0; 1];
gz = 0;
omega_shift = gam * gz * 0;
```

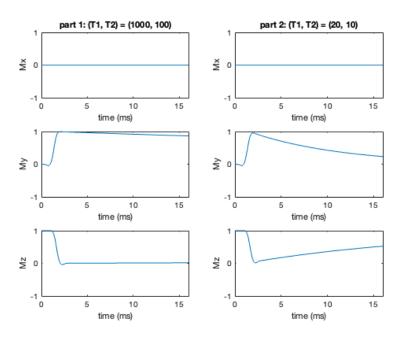
```
bx = b1_90;
[mx,my,mz] = blochsim_516(m0,bx,by,bz,obj_T1,obj_T2,dt);
figure (1)
subplot(3,1,1)
plot(time,mx);xlabel('time (ms)');ylabel('Mx');axis([0 endtime -1 1]);title('part1');
subplot(3,1,2)
plot(time,my);xlabel('time (ms)');ylabel('My');axis([0 endtime -1 1]);
subplot(3,1,3)
plot(time,mz);xlabel('time (ms)');ylabel('Mz');axis([0 endtime -1 1]);
```



```
obj_T1_1 = 20;
obj_T2_2 = 10;
[mx_2,my_2,mz_2] = blochsim_516(m0,bx,by,bz,obj_T1_1,obj_T2_2,dt);

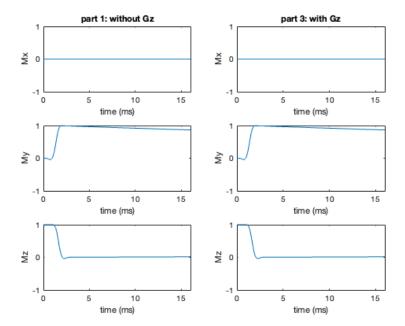
figure (2)
subplot(3,2,1)
plot(time,mx);xlabel('time (ms)');ylabel('Mx');axis([0 endtime -1 1]);title('part 1: (T1, T2) = (1000, 100)');
subplot(3,2,3)
plot(time,my);xlabel('time (ms)');ylabel('My');axis([0 endtime -1 1]);
subplot(3,2,5)
plot(time,mz);xlabel('time (ms)');ylabel('Mz');axis([0 endtime -1 1]);
```

```
subplot(3,2,2)
plot(time,mx_2);xlabel('time (ms)');ylabel('Mx');axis([0 endtime -1 1]);title('part 2: (T1, T2) = (20, 10)');
subplot(3,2,4)
plot(time,my_2);xlabel('time (ms)');ylabel('My');axis([0 endtime -1 1]);
subplot(3,2,6)
plot(time,mz_2);xlabel('time (ms)');ylabel('Mz');axis([0 endtime -1 1]);
```

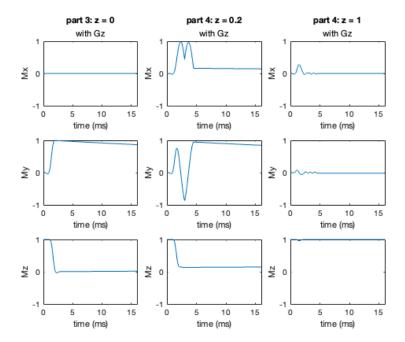


Create gradients Create gz

```
rf90bw = 1 / sincper;
                        %bandwith of RF
slThick = 1;
                        % Slick thickness in cm
gz1_a = 2*pi*rf90bw/gam/slThick;
                                             % REPLACE 0 with amplitude of gzl in T/cm
gz1_pw = rf90pw;
                          \mbox{\ensuremath{\$}} Match the width of gzl to the RF pulse
gz2_a = -gz1_a;
                          % REPLACE 0 with amplitude of gz2 in T/cm
gz2_pw = rf90pw/2;
% gz step size is dt, with amplitude values in T/cm
gz = (time < gz1_pw) \cdot * gz1_a \cdot ...
      + (time >= gz1_pw).*(time < (gz1_pw+gz2_pw)) .* gz2_a;
bz_3 = gz * obj_z;
[mx_3,my_3,mz_3] = blochsim_516(m0,bx,by,bz_3,obj_T1,obj_T2,dt);
figure (3)
subplot(3,2,1)
plot(time,mx);xlabel('time (ms)');ylabel('Mx');axis([0 endtime -1 1]);title('part 1: without Gz');
subplot(3,2,3)
plot(time,my);xlabel('time (ms)');ylabel('My');axis([0 endtime -1 1]);
subplot(3,2,5)
plot(time,mz);xlabel('time (ms)');ylabel('Mz');axis([0 endtime -1 1]);
subplot(3,2,2)
plot(time,mx_3);xlabel('time (ms)');ylabel('Mx');axis([0 endtime -1 1]);title('part 3: with Gz');
subplot(3,2,4)
plot(time,my_3);xlabel('time (ms)');ylabel('My');axis([0 endtime -1 1]);
subplot(3,2,6)
plot(time,mz_3);xlabel('time (ms)');ylabel('Mz');axis([0 endtime -1 1]);
```

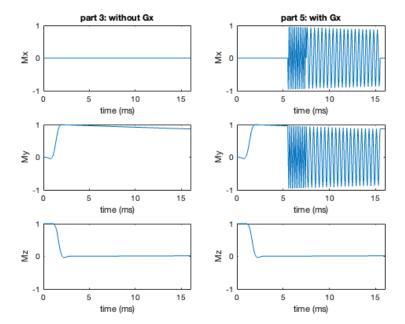


```
obj_z_41 = 0.2;
obj_z_42 = 1;
bz_41 = gz * obj_z_41;
bz_42 = gz * obj_z_42;
[mx_41,my_41,mz_41] = blochsim_516(m0,bx,by,bz_41,obj_T1,obj_T2,dt);
[mx 42,my 42,mz 42] = blochsim 516(m0,bx,by,bz 42,obj T1,obj T2,dt);
figure (4)
subplot(3,3,1)
plot(time, mx_3); xlabel('time (ms)'); ylabel('Mx'); axis([0 endtime -1 1]); title('part 3: z = 0'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 3: z = 0'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 3: z = 0'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 3: z = 0'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 3: z = 0'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 3: z = 0'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 3: z = 0'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 3: z = 0'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 3: z = 0'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 3: z = 0'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 3: z = 0'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 3: z = 0'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 3: z = 0'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 3: z = 0'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 3: z = 0'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 3: z = 0'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 3: z = 0'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 3: z = 0'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 3: z = 0'); subtitle('with Gz'); axis([0 endtime -1 1]); title('with Gz'); axis([0 endtime -1 1]); ax
subplot(3,3,4)
plot(time,my 3);xlabel('time (ms)');ylabel('My');axis([0 endtime -1 1]);
subplot(3,3,7)
plot(time,mz_3);xlabel('time (ms)');ylabel('Mz');axis([0 endtime -1 1]);
subplot(3,3,2)
plot(time, mx\_41); xlabel('time (ms)'); ylabel('Mx'); axis([0 endtime -1 1]); title('part 4: z = 0.2'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 4: z = 0.2'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 4: z = 0.2'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 4: z = 0.2'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 4: z = 0.2'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 4: z = 0.2'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 4: z = 0.2'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 4: z = 0.2'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 4: z = 0.2'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 4: z = 0.2'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 4: z = 0.2'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 4: z = 0.2'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 4: z = 0.2'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 4: z = 0.2'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 4: z = 0.2'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 4: z = 0.2'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 4: z = 0.2'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 4: z = 0.2'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 4: z = 0.2'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 4: z = 0.2'); subtitle('with Gz'); axis([0 endtime -1 1]); title('part 4: z = 0.2'); subtitle('with Gz'); axis([0 endtime -1 1]); title('with Gz'); axis([0 endtime -1 1]); axis([0 endti
subplot(3,3,5)
plot(time,my_41);xlabel('time (ms)');ylabel('My');axis([0 endtime -1 1]);
subplot(3,3,8)
plot(time,mz_41);xlabel('time (ms)');ylabel('Mz');axis([0 endtime -1 1]);
subplot(3,3,3)
plot(time,mx_42);xlabel('time (ms)');ylabel('Mx');axis([0 endtime -1 1]);title('part 4: z = 1');subtitle('with Gz');
subplot(3,3,6)
plot(time,my_42);xlabel('time (ms)');ylabel('My');axis([0 endtime -1 1]);
subplot(3,3,9)
plot(time,mz 42);xlabel('time (ms)');ylabel('Mz');axis([0 endtime -1 1]);
```

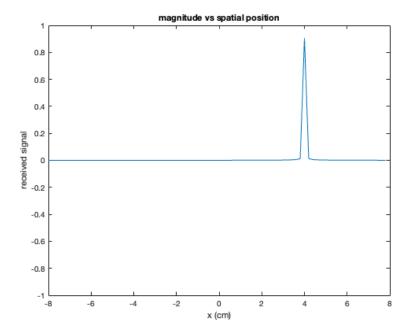


Create gx

```
k_x = 1/Fovx;
gx_5b = Nx* k_x / T_read / gambar;
gx_5a = -2 * gx_5b;
t_gx_1 = 5.5;
t_gx_2 = 7.5;
t gx 3 = 15.5;
gx_5 = (time >= t_gx_1).*(time < t_gx_2).* gx_5a...
      + (time >= t_gx_2).*(time < t_gx_3) .* gx_5b;
bx_5 = b1_90;
by_5 = zeros([totalTimepoints obj_n]);
bz 5 = gx 5 * obj x;
[mx_5,my_5,mz_5] = blochsim_516(m0,bx_5,by_5,bz_5,obj_T1,obj_T2,dt);
figure (5)
subplot(3,2,1)
plot(time,mx_3);xlabel('time (ms)');ylabel('Mx');axis([0 endtime -1 1]);title('part 3: without Gx');
subplot(3,2,3)
plot(time,my_3);xlabel('time (ms)');ylabel('My');axis([0 endtime -1 1]);
subplot(3,2,5)
plot(time,mz_3);xlabel('time (ms)');ylabel('Mz');axis([0 endtime -1 1]);
subplot(3,2,2)
subplot(3,2,4)
plot(time,my_5);xlabel('time (ms)');ylabel('My');axis([0 endtime -1 1]);
subplot(3,2,6)
plot(time,mz_5);xlabel('time (ms)');ylabel('Mz');axis([0 endtime -1 1]);
```

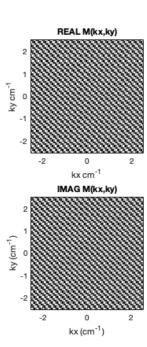


```
nread = 80;
npe = 60;
by_6 = zeros([totalTimepoints obj_n]);
sig_6 = zeros([nread 1]);
gy 6 = zeros([totalTimepoints 1]);
bz_6 = gx_5 * obj_x;
[mx_6, my_6, mz_6] = blochsim_516(m0, bx_5, by_6, bz_6, obj_T1, obj_T2, dt);
M_6 = mx_6 + 1i * my_6;
index_1 = 1;
for index = 1 : totalTimepoints
    if (index >= 151 && index <= 310) && mod(index,2) == 1</pre>
    sig_6(index_1,1) = M_6(index,1);
    index_1 = index_1 + 1;
    end
end
xpos = [-nread/2:nread/2-1]/nread.*FOVx;
ypos = [-npe/2:npe/2-1]/npe*FOVy;
figure(6)
plot(xpos,abs(ift(sig_6)));xlabel('x (cm)');ylabel('received signal');axis([-8 8 -1 1]);title('magnitude vs spatial position');
```

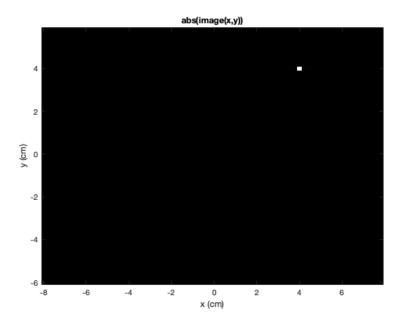


Create gy

```
k_y = 1/FOVy;
gy_max = Ny * k_y / gambar / T_y / 2;
delta_gy = 2 * pi / (gam * 2 *FOVy);
by_7 = zeros([totalTimepoints obj_n]);
sig_7 = zeros([nread npe]);
M_7 = zeros([totalTimepoints npe]);
for pe = 1:npe
    gy_7 = (time >= t_gx_1).*(time < t_gx_2).*(delta_gy * (pe - 1) - gy_max);
    bz_7 = gx_5 * obj_x + gy_7 * obj_y + gz * obj_z;
    [mx_7, my_7, mz_7] = blochsim_516(m0, bx_5, by_7, bz_7, obj_T1, obj_T2, dt);
    M_7(:,pe) = mx_7 + 1i * my_7;
    index_1 = 1;
    for index = 1 : totalTimepoints
        if (index >= 151 && index <= 310) && mod(index,2) == 1</pre>
        sig_7(index_1,pe) = M_7(index,pe);
        index_1 = index_1 + 1;
        end
    end
% show images for parts 7-10
W_kx = k_x * Nx;
W_ky = k_y * Ny;
kxpos = linspace(-W_kx/2, W_kx/2, Nx); % vector of kx locations
kypos = linspace(-W_ky/2, W_ky/2, Ny); % vector of ky locations
figure(7)
subplot(2,1,1)
imagesc(kxpos,kypos,real(sig_7)'); colormap gray; axis('image'); axis('xy')
xlabel('kx cm^{-1})';
ylabel('ky cm^{-1}');
title('REAL M(kx,ky)')
% disp 'Press any key to continue...'; pause
subplot(2,1,2)
imagesc(kxpos,kypos,imag(sig_7)'); colormap gray; axis('image'); axis('xy')
xlabel('kx (cm^{-1})');
ylabel('ky (cm^{-1})');
title('IMAG M(kx,ky)')
%disp 'Press any key to continue...'; pause
```

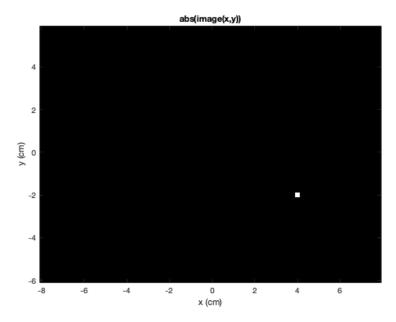


```
figure(8)
imagesc(xpos,ypos,abs(ift2(sig_7))'); colormap gray; axis('image'); axis('xy')
xlabel('x (cm)');
ylabel('y (cm)');
title('abs(image(x,y))')
%disp 'Press any key to continue...'; pause
```



```
by_9 = zeros([totalTimepoints obj_n]);
sig_9 = zeros([nread npe]);
index_1 = 1;
M_9 = zeros([totalTimepoints npe]);
for pe = 1:npe
    gy_9 = (time >= t_gx_1).*(time < t_gx_2) .* (delta_gy * (pe - 1) - gy_max);
    bz_9 = gx_5 * obj_x + gy_9 * 10 + gz * obj_z;</pre>
```

```
[mx_9, my_9, mz_9] = blochsim_516 (m0, bx_5, by_7, bz_9, obj_T1, obj_T2, dt);
    M_9(:,pe) = mx_9 + 1i * my_9;
    index_1 = 1;
    for index = 1 : totalTimepoints
        if (index >= 151 \&\& index <= 310) \&\& mod(index,2) == 1
        sig_9(index_1,pe) = M_9(index,pe);
        index_1 = index_1 + 1;
        end
    end
end
figure(9)
imagesc(xpos,ypos,abs(ift2(sig_9))'); colormap gray; axis('image'); axis('xy')
xlabel('x (cm)');
ylabel('y (cm)');
title('abs(image(x,y))')
%disp 'Press any key to continue...'; pause
```



part 10 11

```
load object23.mat
b1_90_x = zeros([totalTimepoints 1]);
b1_90_y = zeros([totalTimepoints 1]);
obj_n = 2850;
m0_10 = [zeros([2 obj_n]);
        ones([1 obj_n])];
M_10 = zeros([totalTimepoints npe]);
sig_10 = zeros([nread npe]);
for slice = 1:2 % slice loop
    if slice == 1
        z_slice = 0;
    else
        z_slice = 1;
   end
    omega_shift = gam * gz1_a * z_slice;
    for tt = 1 : totalTimepoints
        b1_90_x(tt,:) = b1_90(tt,:) * cos(omega_shift * tt * dt);
        b1_90_y(tt,:) = b1_90(tt,:) * sin(omega_shift * tt * dt);
        bx_10 = b1_90_x * ones([1 obj_n]);
        by_10 = b1_90_y * ones([1 obj_n]);
        gx_10 = gx_5;
        gz_10 = gz;
        %figure (10)
    for pe = 1:npe
```

```
gy_10 = (time \ge t_gx_1).*(time < t_gx_2).*(delta_gy * (pe - 1) - gy_max);
        bz_10 = gx_10 * obj_x + gy_10 * obj_y + gz * obj_z;
        [mx_10,my_10,mz_10] = blochsim_516(m0_10,bx_10,by_10,bz_10,obj_T1,obj_T2,dt);
         subplot(3,1,1)
8
          plot(time,sum(mx_10,2)/obj_n);xlabel('time (ms)');ylabel('Mx');axis([0 endtime -1 1]);title('part 10');
9
         subplot(3,1,2)
8
          plot(time,sum(my_10,2)/obj_n);xlabel('time (ms)');ylabel('My');axis([0 endtime -1 1]);
9
         subplot(3,1,3)
જ
         plot(time,sum(mz 10,2)/obj n);xlabel('time (ms)');ylabel('Mz');axis([0 endtime -1 1]);
કૃ
         pause(0.01);
        M_10(:,pe) = sum(mx_10,2) + 1i.*sum(my_10,2);
        index_1 = 1;
        for index = 1 : totalTimepoints
            if (index >= 151 && index <= 310) && mod(index,2) == 1</pre>
                sig_10(index_1,pe) = M_10(index,pe);
                index_1 = index_1 + 1;
            end
        end
    end
    %close(figure(10))
    if slice == 1
        figure(11)
    else
        figure(12)
    end
    subplot(2,2,1)
    imagesc(kxpos,kypos,real(sig_10)'); colormap gray; axis('image'); axis('xy')
    xlabel('kx (cm^{-1})');
   ylabel('ky (cm^{-1})');
    title('real(M(kx,ky))')
    subplot(2,2,2)
    imagesc(kxpos,kypos,imag(sig_10)'); colormap gray; axis('image'); axis('xy')
    xlabel('kx (cm^{-1})');
    ylabel('ky (cm^{-1})');
    title('imag(M(kx,ky))')
        subplot(2,2,3)
    imagesc(kxpos,kypos,abs(sig_10)'); colormap gray; axis('image'); axis('xy')
    xlabel('kx (cm^{-1})');
    ylabel('ky (cm^{-1})');
    title('abs(M(kx,ky))')
    subplot(2,2,4)
    imagesc(xpos,ypos,abs(ift2(sig 10))'); colormap gray; axis('image'); axis('xy')
    xlabel('x (cm)');
   ylabel('y (cm)');
    title('abs(image(x,y))')
end
```

