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# X-ray Imaging

BME/EECS 516

X-ray Lecture #2



# Announcements

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- HW #5 due today
- MRI Project due Tuesday 11/21
- Tuesday, 11/14 – guest lectures from local medical imaging industry
  - David Sarment from Xoran Technologies
  - John Seamans (UM) formerly with Delphinus Medical and GE Healthcare
- US and MRI Demos – 11/21 during class time. More info to come...

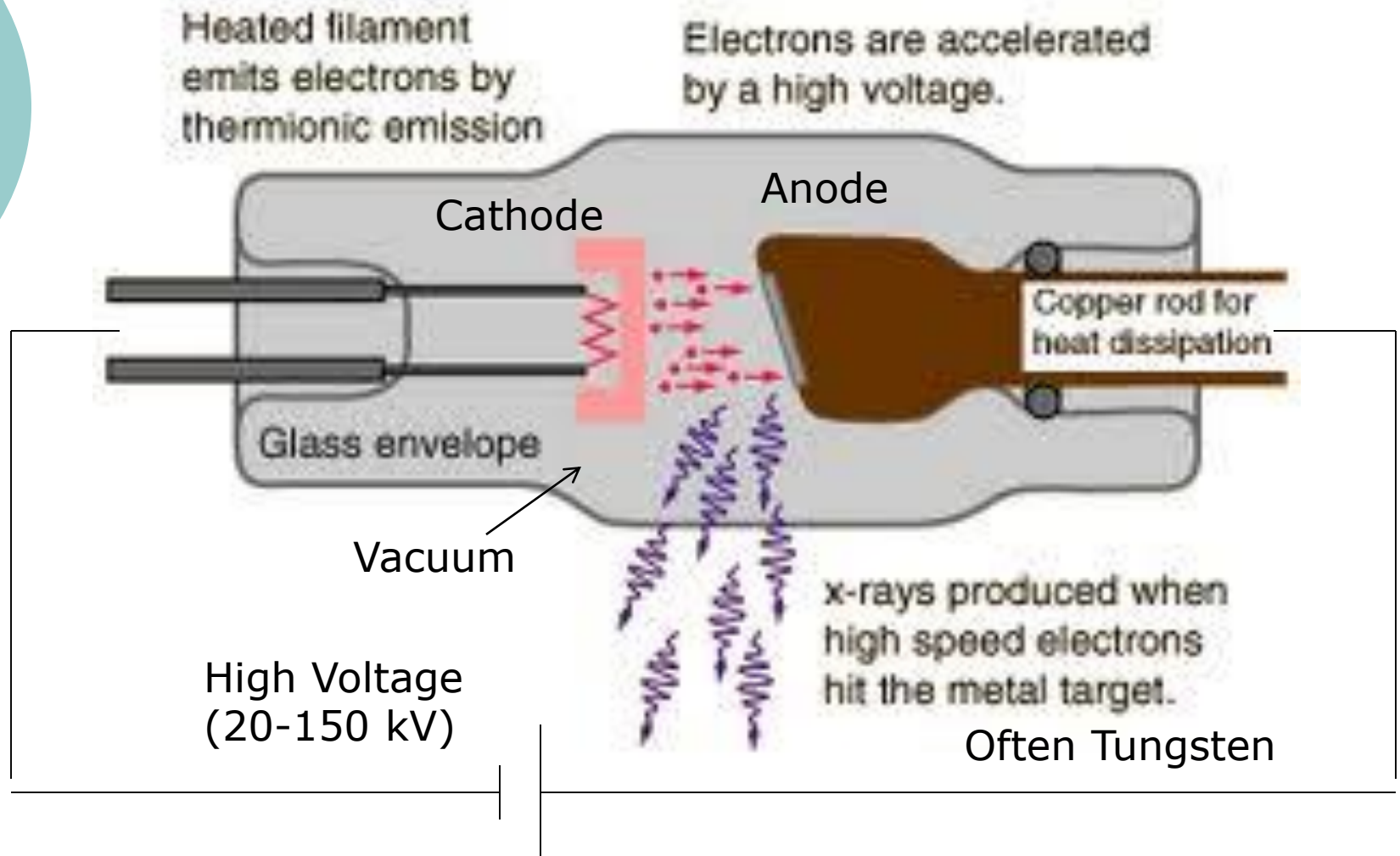
# Physics - Radiation

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- a process in which energetic streams of particles or photons travel through a medium or space
- X-ray photon - appropriate amount of interaction for imaging
- Behavior of Radiation Along a Line:

$$N(x) = N(0) \exp\left[-\int_0^x \mu(x') dx'\right]$$

# X-ray Tube





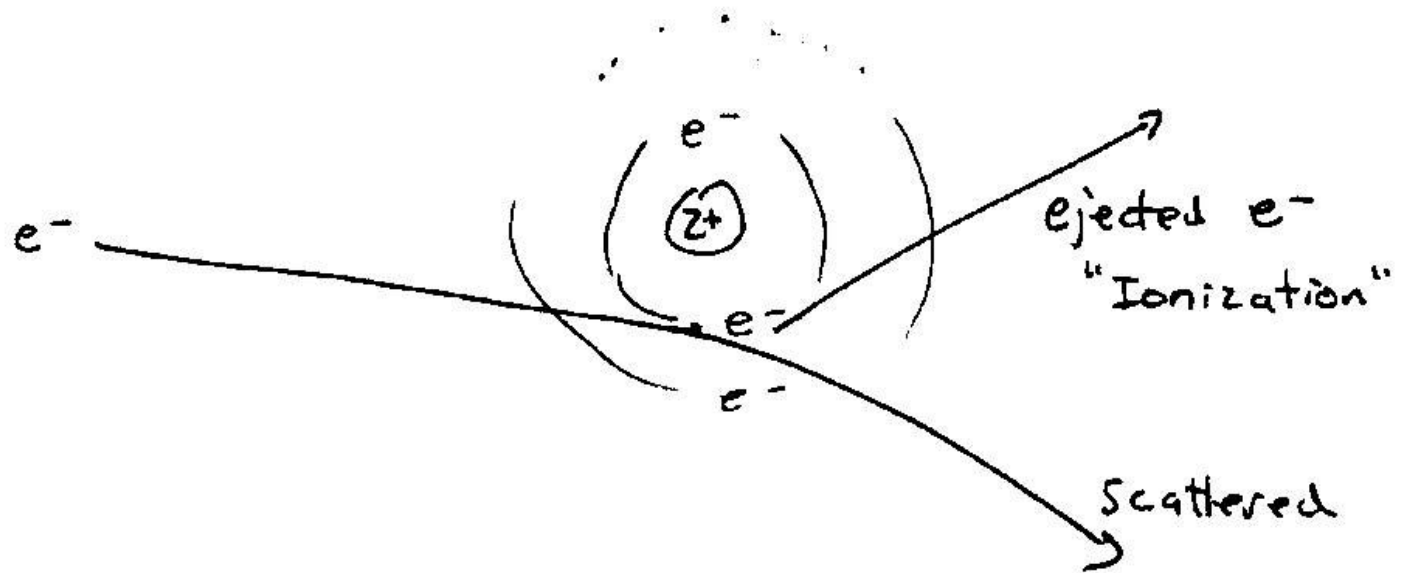
# Generation of x-rays: electron interactions

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1. Inelastic (energy absorbing) scattering with atomic electrons
  - An electron with enough energy can eject an orbital electron out of the inner shell of a metal atom.
  - Electrons from higher energy level fill up the vacancy
  - X-ray photon are emitted from **spontaneous energy state transitions.**

# Generation of x-rays: electron interactions

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# Generation of x-rays: electron interactions

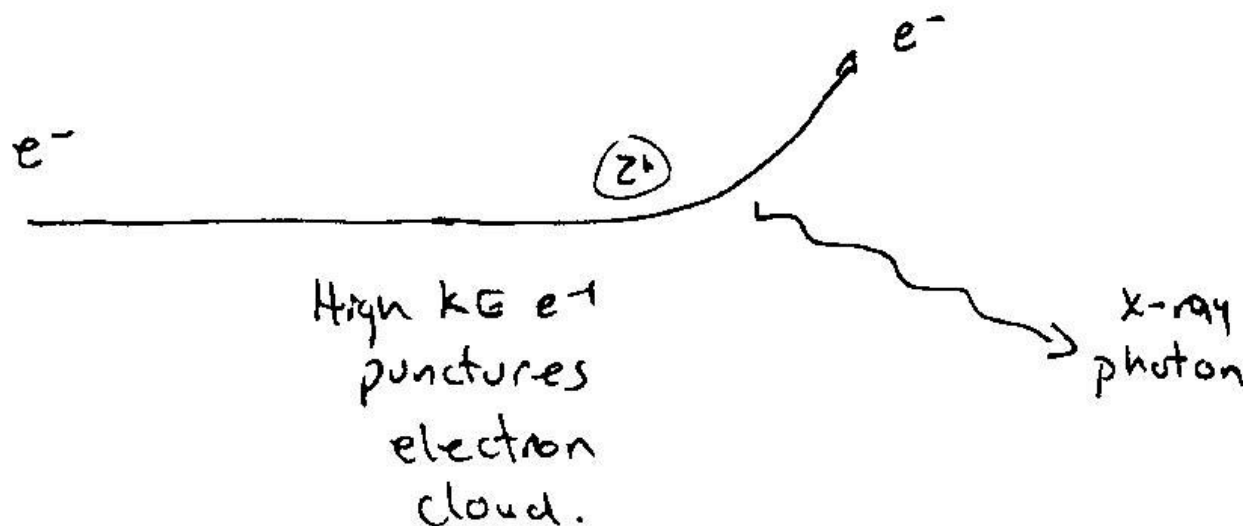
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- The process produce discrete emission spectrum –spectral lines.  
“Characteristic” x-ray energies for W
  - 58.5 keV
  - Any combination of shell transition energies (e.g. 3.2 and 61.7 keV).
- Bohr model accounts for absorption/generation of discrete valued energies.

# Generation of x-rays: electron interactions

## 2. Bremsstrahlung "Braking"

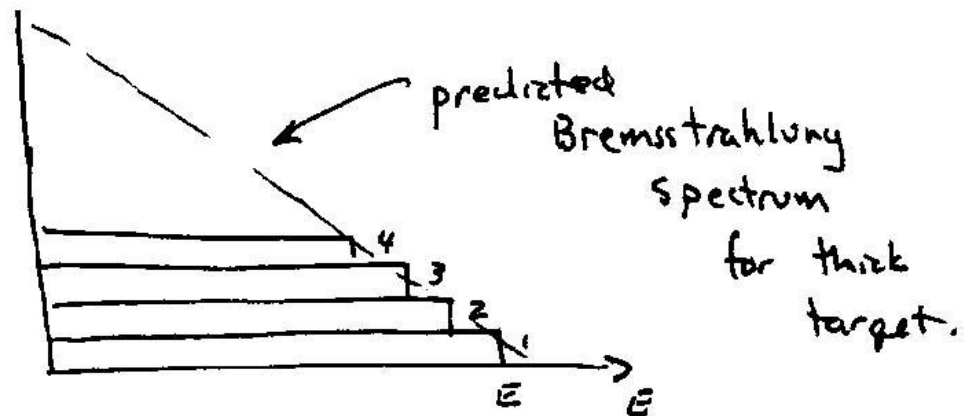
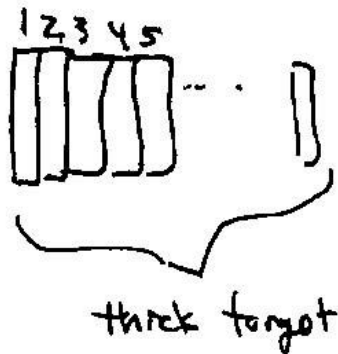
Radiation – accelerated electrons scattered by a strong electric field near the high-Z nuclei. X-rays have continuous spectrum





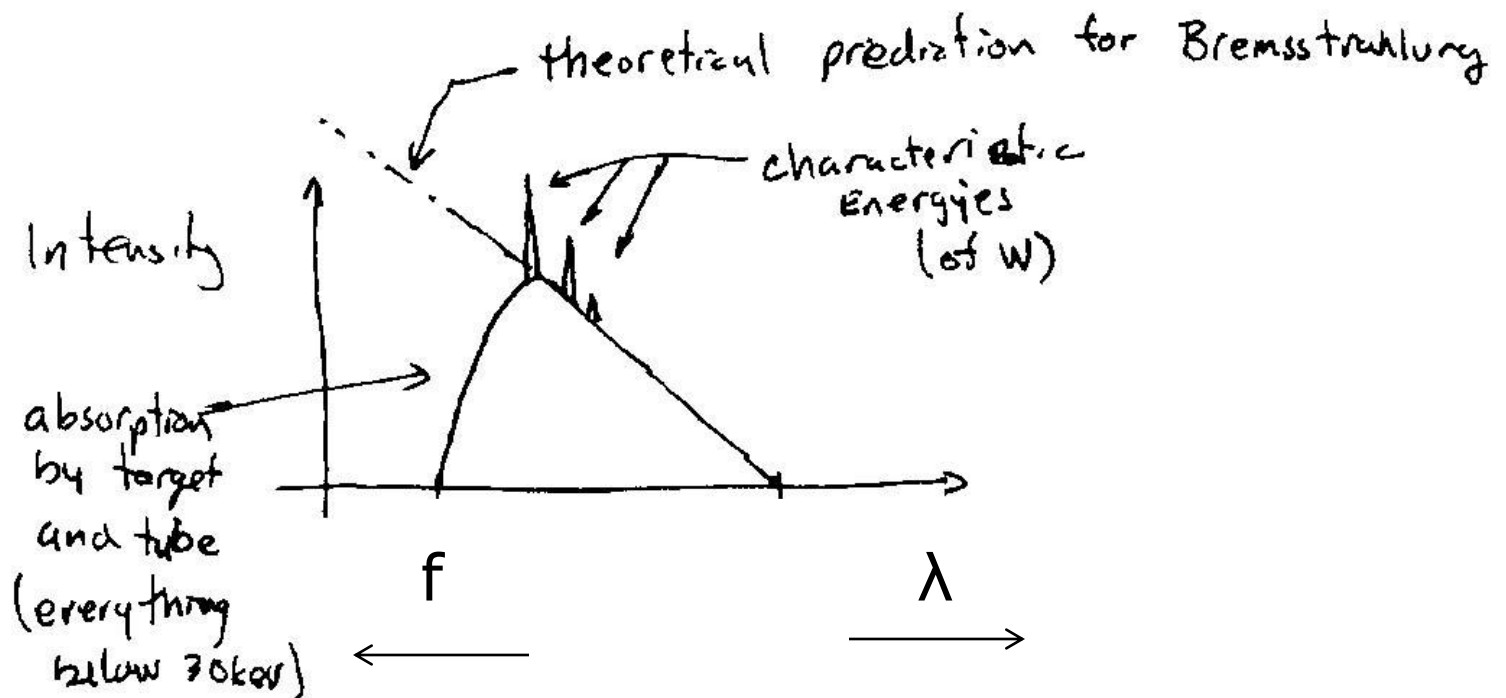
# Generation of x-rays: electron interactions

- Thick target (anode)
  - Modeled as a series of thin targets.
  - Each thin target produces a new uniform spectrum, but with a lower peak energy.
  - Resultant spectrum is approximately linear from a peak at 0 keV to 0 at  $E$ .



# The x-ray Spectrum

- Spectrum will have a combination of Bohr (discrete) energies and Bremsstrahlung



# The x-ray Spectrum

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- The x-ray spectrum is function of photon energy:  $I_o = I_o(E)$
- $I$  represents energy/unit time/unit area or power/unit area.

# Attenuation Coefficient

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- The x-ray spectrum is a function of photon energy  $E$ :  $I_0 = I_0(E)$
- The attenuation function is also a function of  $E$ :  $\mu = \mu(x, y, z, E)$ .

- The intensity at the output to form image:

$$I_d(x, y) = \int_E I_0(E) \exp\left(-\int \mu(x, y, z, E) dz\right) dE$$

$I_d$  tells us nothing about  $z$  or  $E$  – it only gives us  $x, y$  information.

# Attenuation Coefficient

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- Two important material properties affecting  $\mu$ : tissue density  $\rho$  and the atomic number  $Z$ 
  - Because most x-ray photon/tissue interactions are photon/electron interactions.
- Attenuation is caused by x-ray photon interaction with the matter

# X-ray Photon Interactions

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- **Rayleigh-Thompson Scattering** – spontaneous, very low energy phenomenon
- **Photoelectric Absorption** – low energy phenomenon
- **Compton Scattering** – mid energy phenomenon
- **Pair Production** – high energy phenomenon
- In general, attenuation coefficient constituents:

$$\mu(E) = \mu_{rt}(E) + \mu_{pe}(E) + \mu_{cs}(E) + \mu_{pp}(E)$$



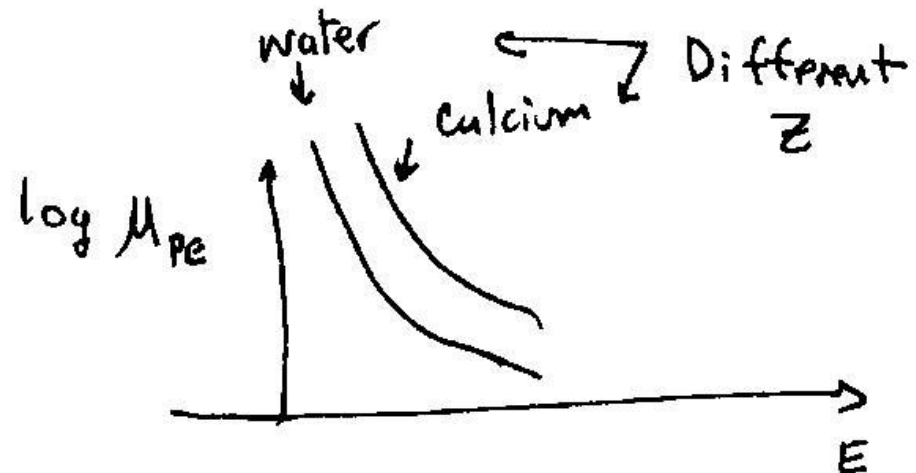
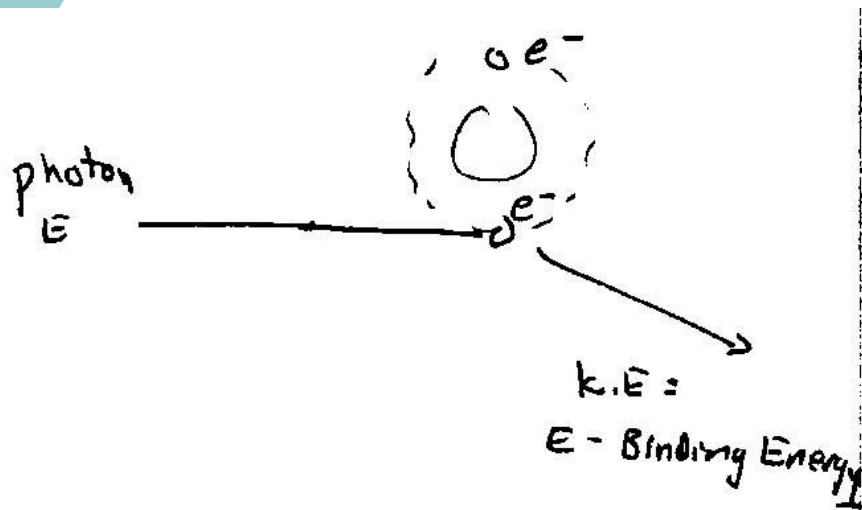
# Photoelectric Absorption

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- Absorption of photon by interacting with a tightly bound electron
- Leads to ejection of an electron – vacancy filled by an electron falling into it from the next shell
- If the ejected electron kinetic energy (= Absorbed photon energy) is less than binding energy of the electron, the electron is unable to escape the material.

# Photoelectric Absorption

- photoelectric effect increases rapidly with atomic number,  $Z$  and with decreasing photon energy .



- Dominates  $\mu$  in the lower energy part of the diagnostic spectrum ( $< 50$  keV)



# Compton Scattering

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- Scattering of photons by an elastic collision with a free electron in the outer shell.
- Part of the x-ray energy is transferred to the electron; the rest taken by the scattered “degraded” photon.
- Elastic collisions preserve  $E$  and momentum ( $p$ ).

# Compton Scattering

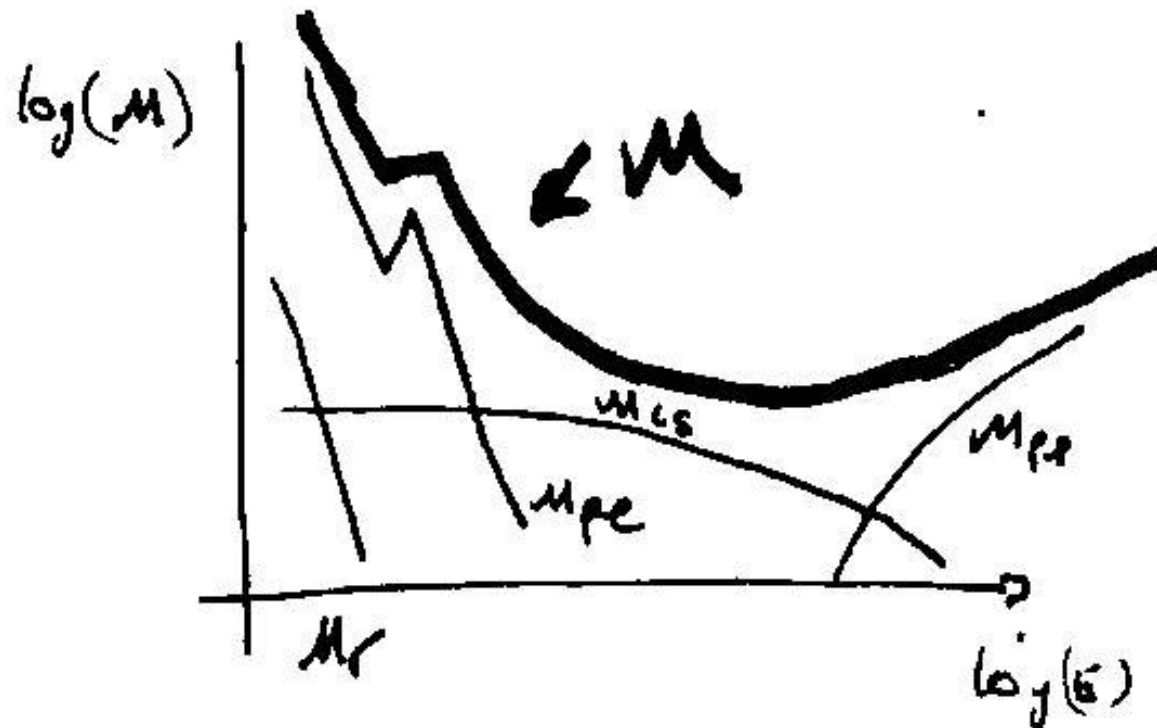
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- $\mu_{cs}$  is nearly constant across diagnostic spectrum
- Compton scatter comes mostly from atomic electrons ( $\mu_{cs}$  is proportional to  $\rho$ )
- At higher  $E$ , Compton scatter dominates over the PE effect.

# Total Linear Attenuation Coefficient for Photons

- The combined coefficient

$$\mu(E) = \mu_{rt}(E) + \mu_{pe}(E) + \mu_{cs}(E) + \mu_{pp}(E)$$



## X-ray Attenuation Coefficients for muscle, fat, bone

Note - mass attenuation coefficient:  $\mu/\rho$

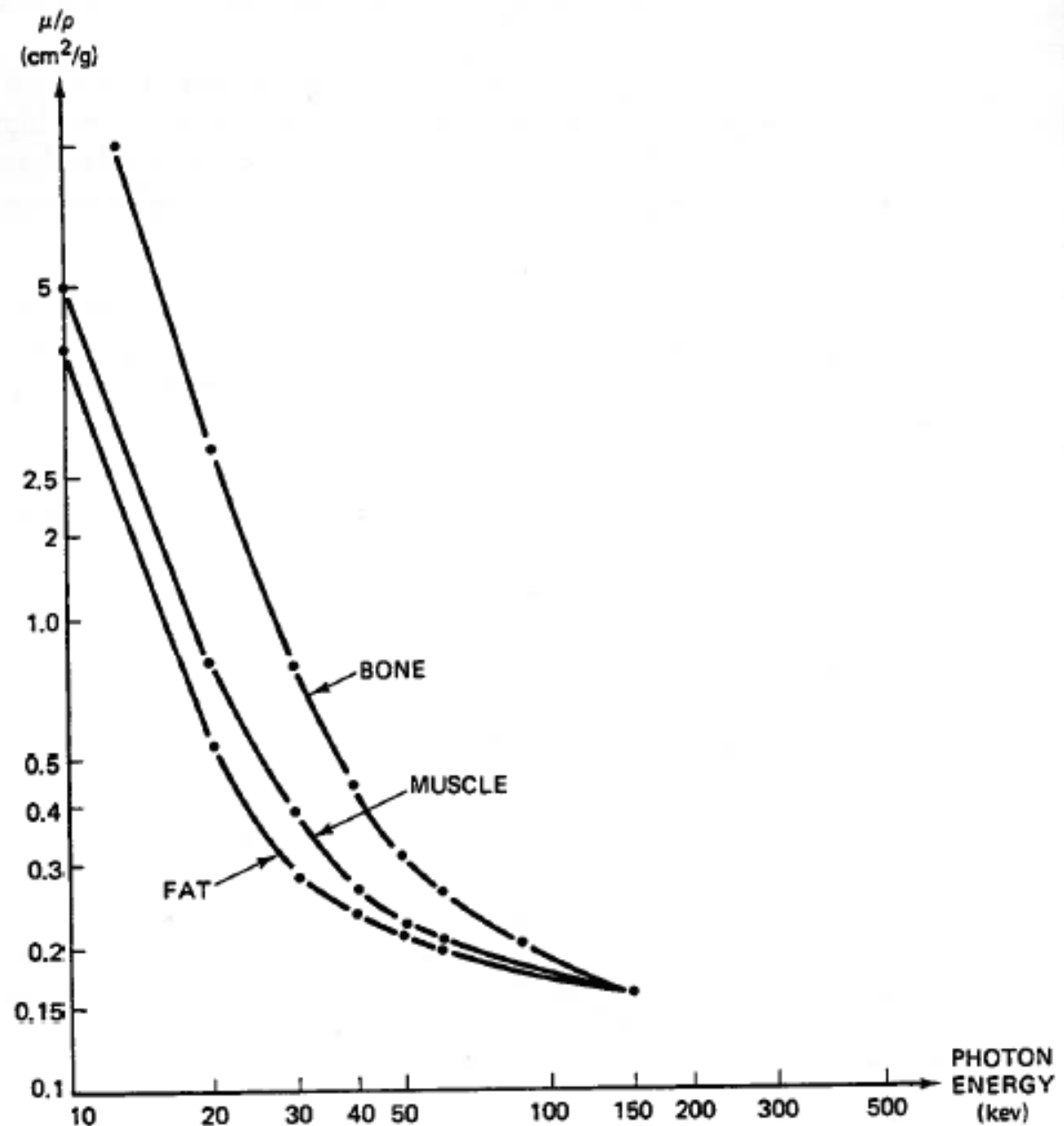


FIG. 3.7 X-ray attenuation coefficients for muscle, fat, and bone, as a function of photon energy.



# Topics for Today

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- Source geometry and magnification
- Finite source sizes



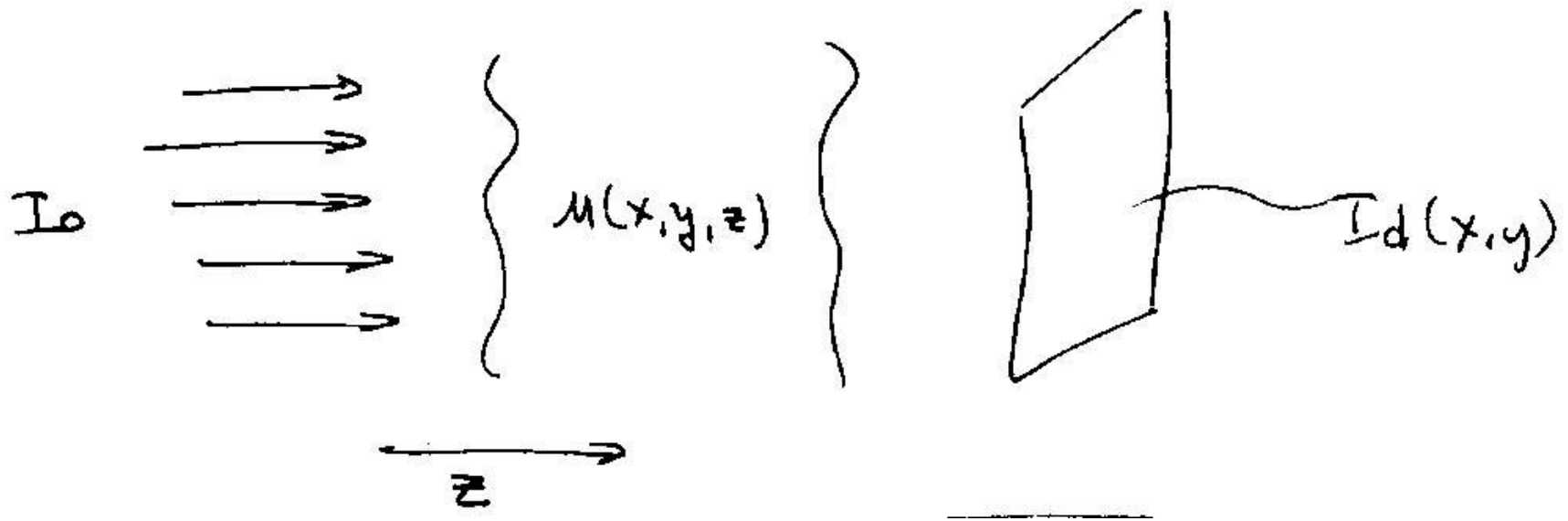
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# Source Issues

Parallel X-ray Imaging  
System

Practical X-ray Sources

# Parallel X-ray Imaging System

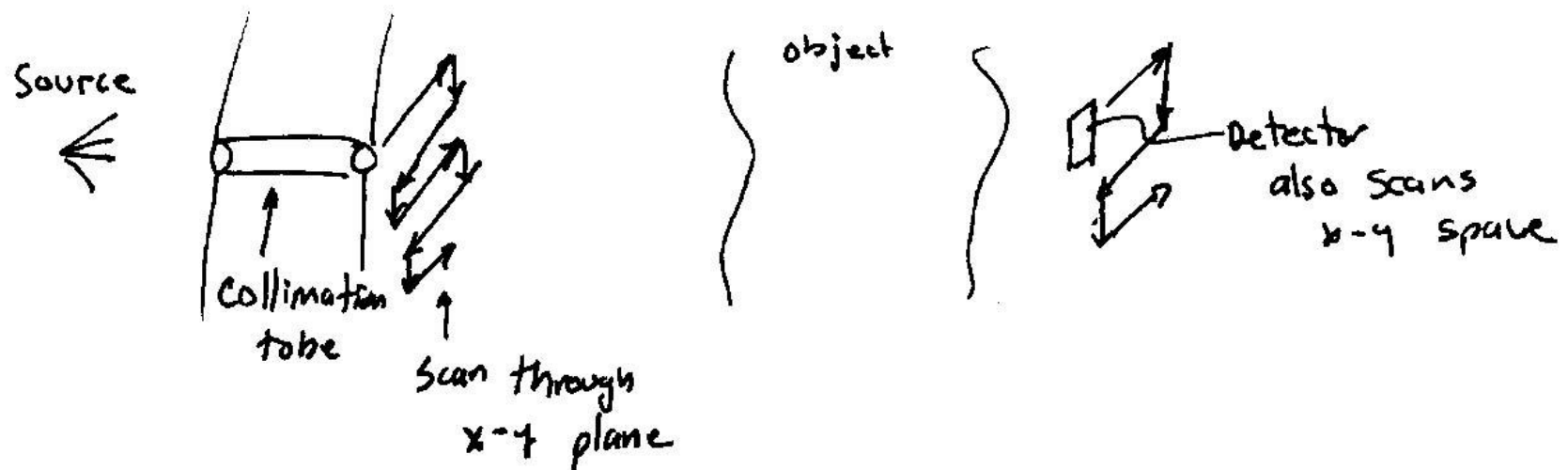


$$I_d(x, y) = I_0 \exp\left(-\int \mu(x, y, z) dz\right)$$

However, there are essentially no practical medical projection x-ray systems where the source has parallel rays.

# Parallel X-ray Imaging System

- Some scanning systems may achieve parallel rays - appropriate for industrial inspection operations, but too slow for medical applications.

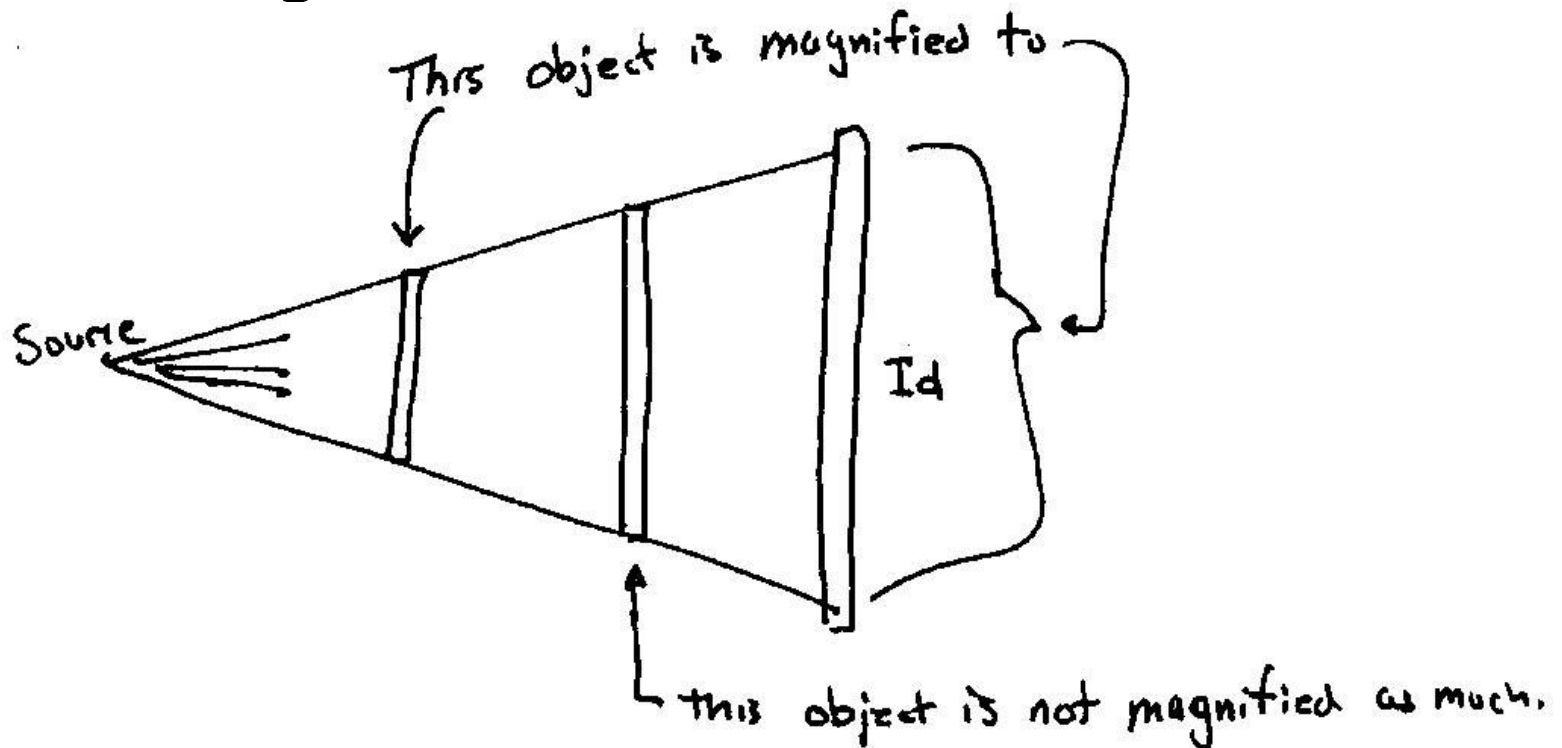




# Practical X-ray Sources – two main issues

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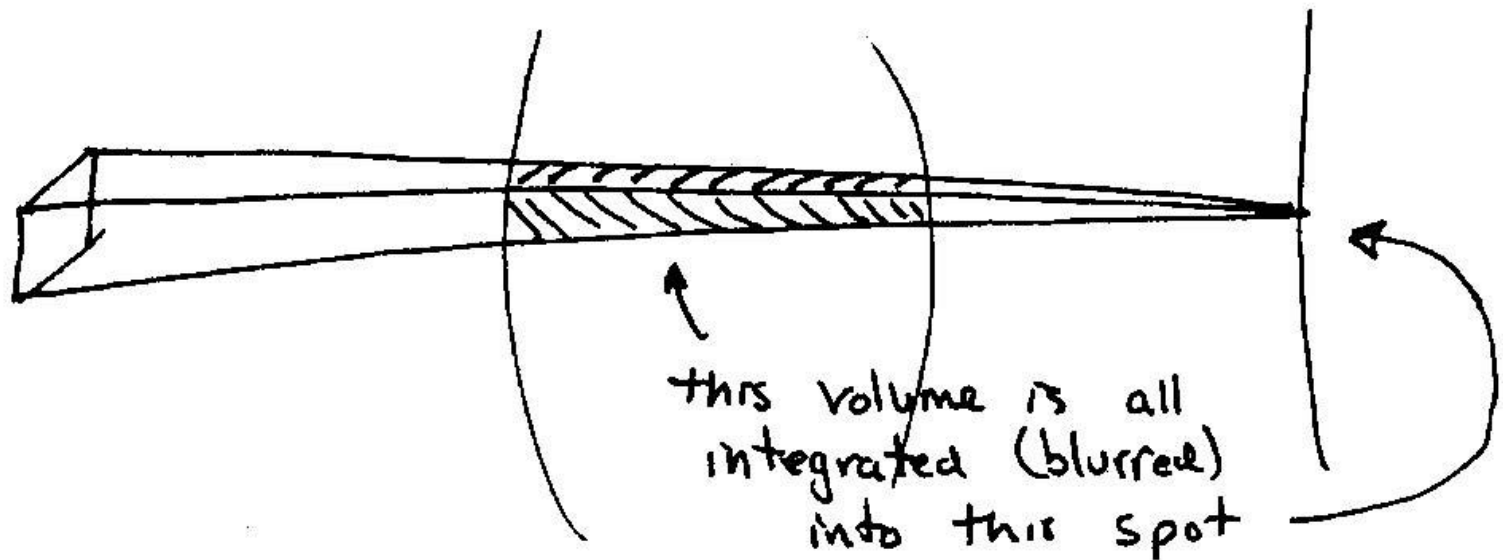
1. Geometric distortions due to point geometry – “depth dependent magnification.”



# Practical X-ray Sources – two main issues

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2. Resolution loss (blurring) due to finite (large) source sizes



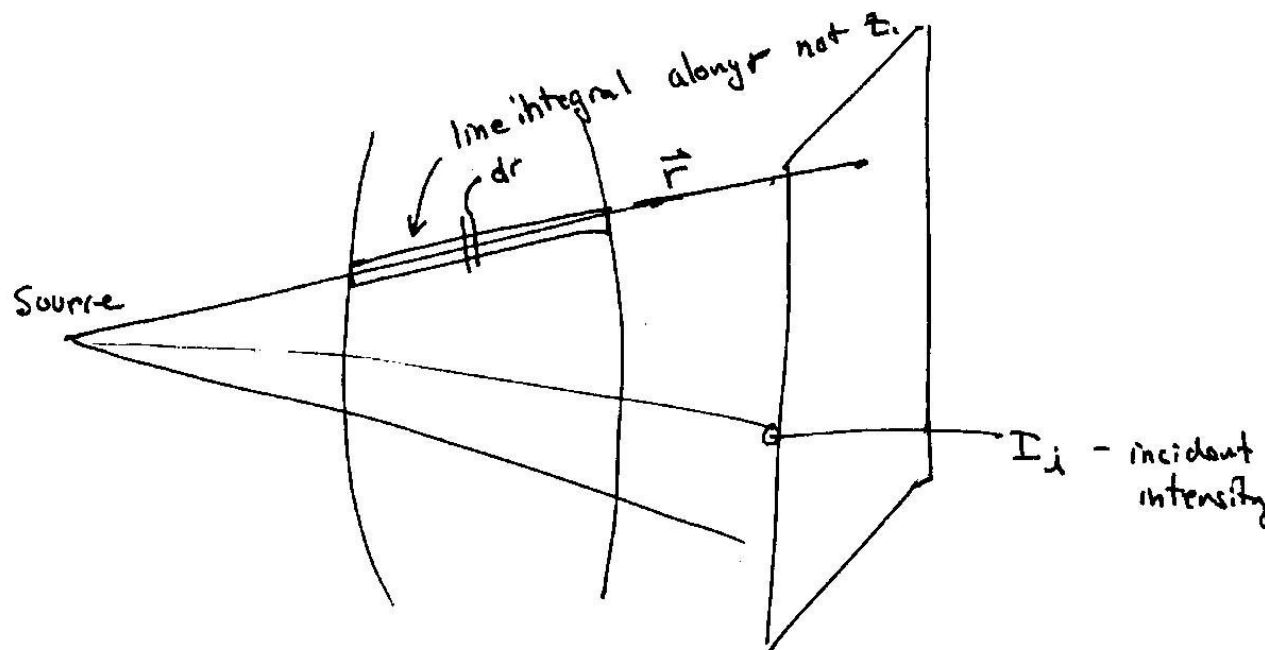


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# **Point Source Geometry Intensity Variations**

# Point Source Geometry

- Find expressions for the image intensity,  $I_d(x_d, y_d)$ , for a point source geometry



$$I_d(x_d, y_d) = I_i(x_d, y_d) \exp\left(-\int \mu(x, y, z) dr\right)$$

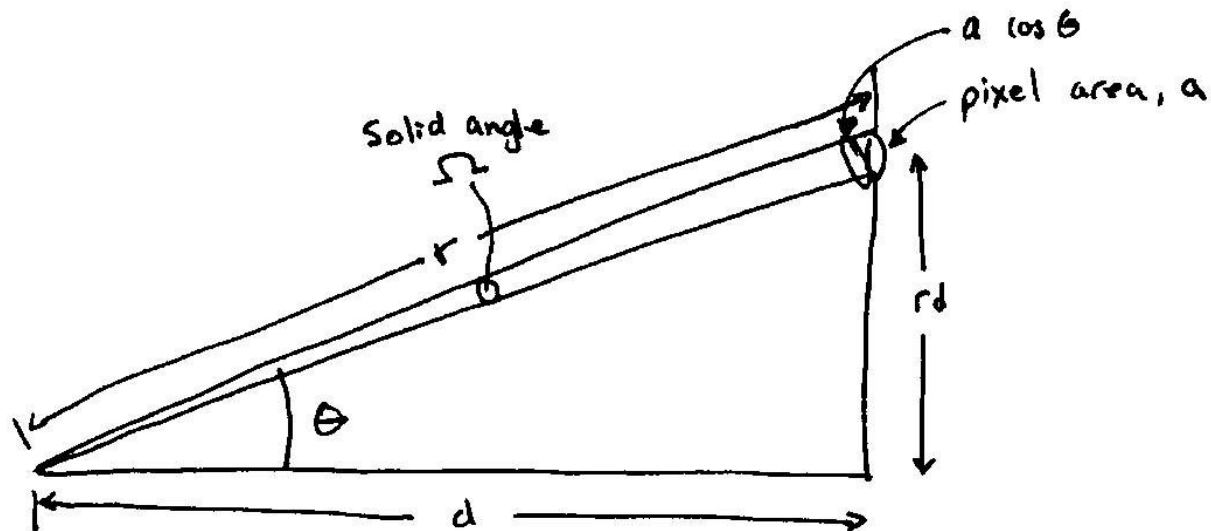
# Point Source Geometry

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- $(x_d, y_d)$  - coordinate system in the output detector plane.
- $(x, y, z)$  - coordinate system of the object.
- $I_i(x_d, y_d)$  - spatially variant incident intensity replaces  $I_o$ .
- The integration is along some path  $r$  with variable of integration  $dr$ .
- $I_d(x_d, y_d)$  – image intensity

# Intensity Variations

- Incident intensity - maximal at the center and falls off towards the edges.
  - Increases in distance from the source
  - Rays obliquely striking the detector.



# Intensity Variations

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- Intensity - power/unit area - expression for the intensity  $I_i$ :

$$I_i = \frac{(\text{photons})(\text{mean photon } E)}{(\text{unit area})(\text{exposure time})} = \frac{kN}{a} \frac{\Omega}{4\pi}$$

- $k$  - scaling coefficient
- $N$  - number of photon emitted during the observation time
- $\Omega/4\pi$  - fraction of the surface of a sphere that is subtended by pixel area  $a$ .

# Intensity Variations

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- $\Omega$  – solid angle
- For a pixel of area  $a$  at some position angle  $\theta$  away from the origin, the part of a sphere covered will be  $a \cos \theta$ . Thus:

$$\frac{\Omega}{4\pi} = \frac{a \cos \theta}{4\pi r^2} \quad \text{or} \quad \Omega = \frac{a \cos \theta}{r^2}$$



# Intensity Variations

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- Intensity at the origin of the detector -  $I_0 = I_i(0,0)$  .
  - At the origin,  $\theta = 0$
  - Distance from the source to the detector -  $r = d$
$$\Omega = a/d^2 \text{ and } I_0 = I_i(0,0) = \frac{kN}{4\pi d^2}$$
- Intensity,  $I_0$ , falls off with  $1/d^2$  as the detector moves away from the source.

# Intensity Variations

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$$I_0 = \frac{kN}{4\pi d^2} \Rightarrow k = I_0 \frac{4\pi d^2}{N}$$

$$I_i = \frac{kN}{a} \frac{\Omega}{4\pi} = I_0 d^2 \frac{\cos \theta}{r^2} \quad \cos \theta = \frac{d}{r}$$

$$I_i = I_0 \cos^3 \theta = I_0 \left( \frac{d}{r} \right)^3$$

- $\cos^3 \theta$  (or its representation) - *incident intensity obliquity term* - has two components
  - $\cos^2 \theta$  term - increase in distance from the source to the detector
  - $\cos \theta$  term - rays obliquely striking the detector

# Intensity Variations

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- Put this expression in the coordinate system of the detector using and

$$r_d^2 = x_d^2 + y_d^2 \qquad r^2 = d^2 + r_d^2$$

$$I_i(x_d, y_d) = I_0 \left( \frac{d}{\sqrt{d^2 + r_d^2}} \right)^3 = I_0 \frac{1}{\left( 1 + \left( \frac{r_d}{d} \right)^2 \right)^{3/2}}$$

# Question

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- A chest x-ray system has a detector plane of 40x40 cm. The distance between the x-ray tube and the detector plane is 20 cm. At the edge of the detector plane, the x-ray intensity is \_\_\_\_ of the intensity at the center.
  - A)  $\sqrt{1/2}$
  - B)  $\sqrt{1/8}$
  - C)  $\sqrt{1/27}$
  - D)  $\sqrt{1/125}$

# Question

---

- A chest x-ray system has a detector plane of 40x40 cm. The distance between the x-ray tube and the detector plane is 20 cm. At the edge of the detector plane, the x-ray intensity is \_\_\_\_ of the intensity at the center.
  - A)  $\sqrt{1/2}$
  - B)  $\sqrt{1/8}$
  - C)  $\sqrt{1/27}$
  - D)  $\sqrt{1/125}$
- Answer B) -  $\cos^3 \frac{\pi}{4} = 0.35$



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Questions?

**Point Source Geometry  
Intensity Variations**



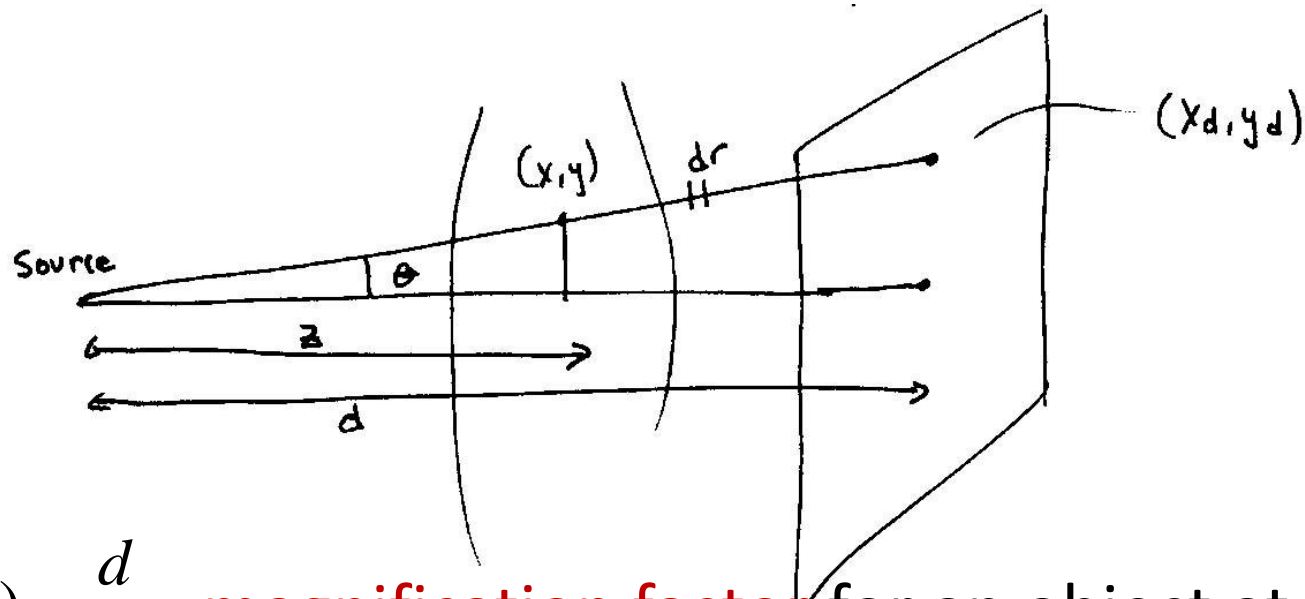
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# **Point Geometry Magnification**

Practical X-ray Sources

# Point Source

- A point in the object  $(x, y)$  at depth  $z$  - it will strike the detector at a position  $(x_d, y_d) = \left( x \frac{d}{z}, y \frac{d}{z} \right)$



$M(z) = \frac{d}{z}$  - **magnification factor** for an object at depth  $z$ .



# Point Source Magnification

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- Attenuation coefficient at location  $(x_d, y_d)$  in output coordinates

$$I_d(x_d, y_d) = I_i(x_d, y_d) \exp\left(-\int \mu(x, y, z) dr\right)$$

$$\mu(x, y, z) = \mu\left(\frac{x_d}{M(z)}, \frac{y_d}{M(z)}, z\right)$$

$$I_i(x_d, y_d) = I_0 \frac{1}{\left(1 + \left(\frac{r_d}{d}\right)^2\right)^{3/2}}$$

# Point Source Magnification

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- Attenuation coefficient at location  $(x_d, y_d)$  in output coordinates

$$I_d(x_d, y_d) = \frac{I_0}{\left(1 + \left(\frac{r_d}{d}\right)^2\right)^{3/2}} e^{-\int \mu\left(\frac{x_d}{M(z)}, \frac{y_d}{M(z)}, z\right) dr}$$



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# Finite (Large) Sources

Not a point source anymore

# Finite (Large) Sources

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- First consider a “thin” object. Let the attenuation coefficient be:

$$\mu(x, y, z) = \tau(x, y)\delta(z - z_0)$$

$$\begin{aligned} I_d(x_d, y_d) &= I_0 \exp\left(-\int \tau\left(\frac{x_d}{M(z)}, \frac{y_d}{M(z)}\right)\delta(z - z_0)dz\right) \\ &= I_0 \exp\left(-\tau\left(\frac{x_d}{M(z_0)}, \frac{y_d}{M(z_0)}\right)\right) \end{aligned}$$

# Finite (Large) Sources

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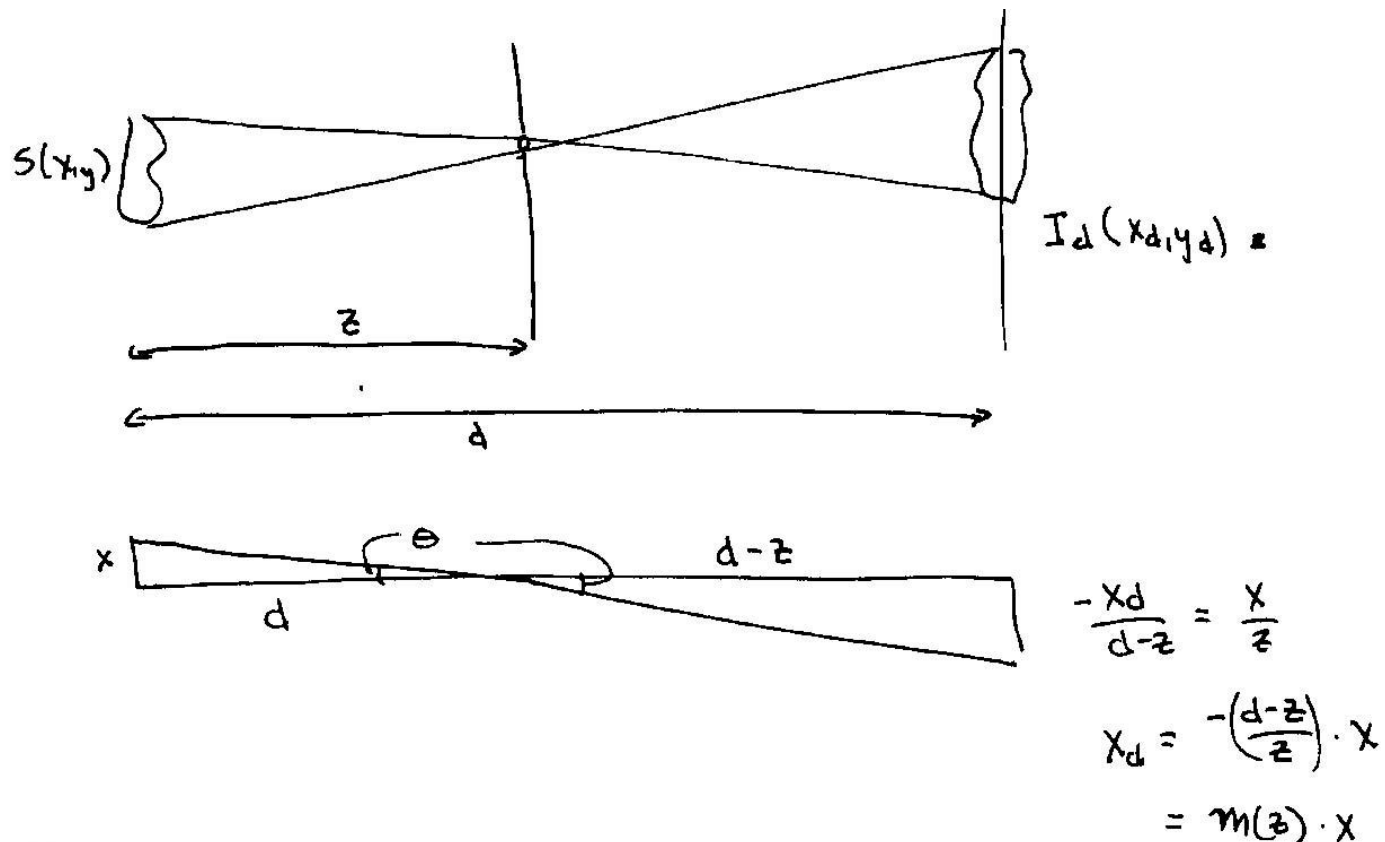
- $M = M(z_0) = d / z_0$  - is the *object magnification factor*
- Including the  $I_i$  term:

$$I_d(x_d, y_d) = I_i \exp\left(-\tau\left(\frac{x_d}{M}, \frac{y_d}{M}\right)\right) = I_i t\left(\frac{x_d}{M}, \frac{y_d}{M}\right)$$

where  $t = \exp(-\tau)$  is the *transmission function*

# Finite (Large) Sources

- Consider a finite source function  $s(x,y)$  and a very small pinhole transmission function:



# Finite (Large) Sources

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Now the image is an image of the source with the *source magnification factor*,

$$I_d(x_d, y_d) = ks \left( \frac{x_d}{m}, \frac{y_d}{m} \right) \quad m = m(z) = -\frac{d-z}{z}$$

- $k$  - scaling factor that is proportional to the area of the pinhole
- If  $I_d$  is to represent the impulse response of the system

# Finite (Large) Sources

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- The area of the pinhole:  $\iint \delta(x, y) dx dy = 1$

- Capture efficiency of the pinhole

$$\eta = \frac{\text{pinhole area}}{4\pi z^2} = \frac{1}{4\pi z^2}$$

- Total number of photon emitted

$$N = \iint s(x, y) dx dy$$



# Finite (Large) Sources

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- Total number of photons to get through the pinhole  $N\eta = \frac{N}{4\pi z^2}$

- The same number at the detector

$$\iint k_s\left(\frac{x_d}{m}, \frac{y_d}{m}\right) dx_d dy_d = kNm^2 = \frac{N}{4\pi z^2}$$

- Hence, the scaling coefficient is

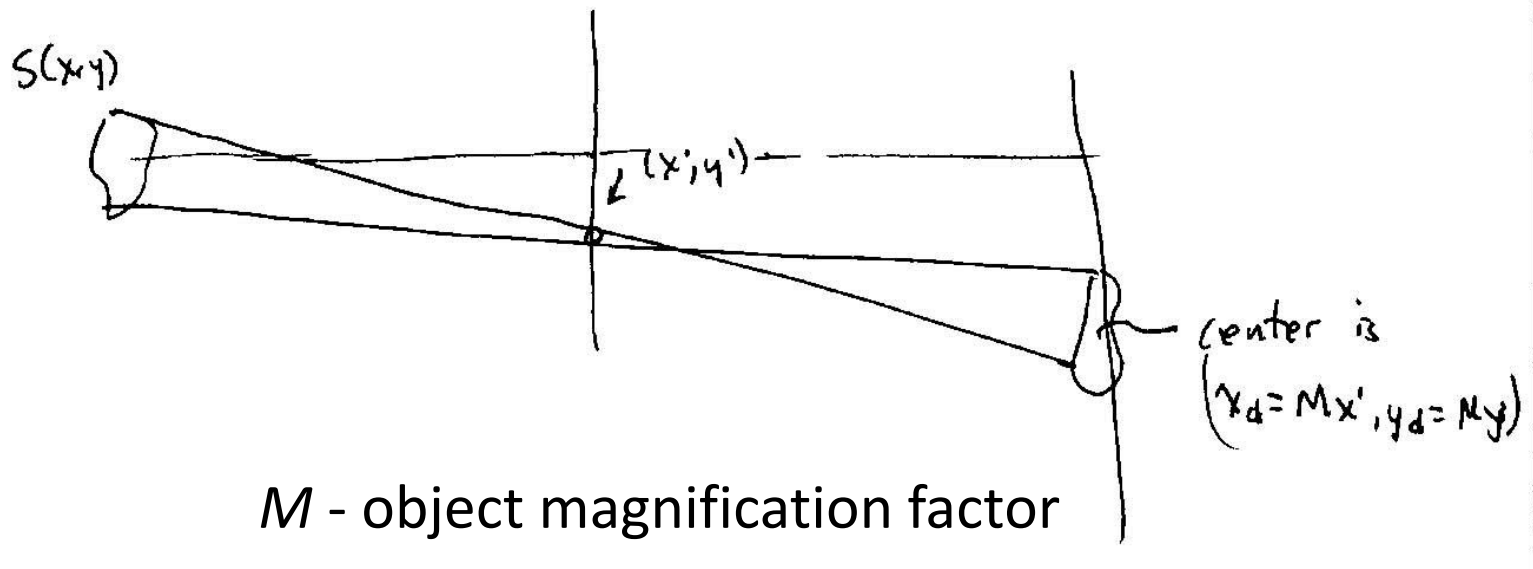
$$k = \frac{1}{4\pi z^2 m^2}$$

# Finite (Large) Sources

$$I_d(x_d, y_d) = \frac{1}{4\pi z^2 m^2} s\left(\frac{x_d}{m}, \frac{y_d}{m}\right)$$

- let the pinhole be at position  $(x', y')$

$$t(x, y) = \delta(x - x', y - y')$$



# Finite (Large) Sources

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- The image of the source is now located at  $(x_d = Mx', y_d = My')$
- The impulse response function is:

$$h(x_d, y_d; x', y') = I_d(x_d, y_d) = \frac{1}{4\pi z^2 m^2} s\left(\frac{x_d - Mx'}{m}, \frac{y_d - My'}{m}\right)$$

- Now we can calculate the image for an arbitrary transmission function using the superposition integral – recall linear system in FT lectures.

# Finite (Large) Sources

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$$I_d(x_d, y_d) = \iint t(x' y') h(x_d, y_d; x', y') dx' dy'$$

$$= \frac{1}{4\pi\zeta^2 m^2} \iint t(x' y') s\left(\frac{x_d - Mx'}{m}, \frac{y_d - My'}{m}\right) dx' dy' \text{ and sub } Mx' = x$$

$$= \frac{1}{4\pi\zeta^2 m^2 M^2} \iint t\left(\frac{x}{M}, \frac{y}{M}\right) s\left(\frac{x_d - x}{m}, \frac{y_d - y}{m}\right) dx dy$$

$$= \frac{1}{4\pi d^2 m^2} s\left(\frac{x_d}{m}, \frac{y_d}{m}\right) ** t\left(\frac{x_d}{M}, \frac{y_d}{M}\right)$$

# Finite (Large) Sources

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- The final image is equal to the convolution of the magnified source and the magnified object.
  - **The object is blurred by the source function.**

- The frequency domain equivalent:

$$F_{2D} \{I_d(x_d, y_d)\} = \frac{1}{4\pi z^2} S(mu, mv) T(Mu, Mv)$$

# Finite (Large) Sources

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- The object is magnified by  $M(z_0)$  and blurred by  $m(z_0)$ 
  - $m(z_0) = -(d-z_0)/z_0 = 1-d/z_0$
  - $M(z_0) = d/z_0$
- If  $z_0 = \frac{1}{3} d$ , object is magnified by ? and blurred by ?

# Finite (Large) Sources

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- If  $z_0 = 1/3 d$ , object is magnified by 3 times and blurred by -2 magnified source

# Finite (Large) Sources

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- The object is **magnified by  $M(z_0)$**  and **blurred by  $m(z_0)$** 
  - $m(z_0) = -(d-z_0)/z_0 = 1-d/z_0$
  - $M(z_0) = d/z_0$
- If  $z_0 = 1/3 d$ , object is magnified by ? and blurred by ?
- If  $z_0 = 2/3 d$ , object is magnified by ? and blurred by ?



# Finite (Large) Sources

---

- The object is magnified by  $M(z_0)$  and blurred by  $m(z_0)$ 
  - $m(z_0) = -(d-z_0)/z_0 = 1-d/z_0$
  - $M(z_0) = d/z_0$
- If  $z_0 = 1/3 d$ , object is magnified by 3 times and blurred by -2 magnified source
- If  $z_0 = 2/3 d$ , object is magnified by 1.5 times and blurred by -0.5 magnified source

# Finite (Large) Sources

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- To minimize source blurring, we should
  - A) position the subject as close to the source as possible
  - B) position the subject right in the middle between the source and the detector
  - C) position the subject immediately next to or on top of the detector

# Finite (Large) Sources

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- To minimize the blurring, we should
  - A) position the subject as close to the source as possible
  - B) position the subject right in the middle between the source and the detector
  - C) position the subject immediately next to or on top of the detector
- Answer: C)

# Finite (Large) Sources

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- To minimize the magnification of the object on the image, we should
  - A) position the subject as close to the source as possible
  - B) position the subject right in the middle between the source and the detector
  - C) position the subject immediately next to or on top of the detector

# Finite (Large) Sources

---

- To minimize the magnification of the object on the image, we should
  - A) position the subject as close to the source as possible
  - B) position the subject right in the middle between the source and the detector
  - C) position the subject immediately next to or on top of the detector
- Answer: C)

# Finite (Large) Sources

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- When  $|m|$  is made small, i.e., the depth plane as far from the source as possible:  $z_0 \rightarrow d$ 
  - *The least blurring*
  - Reduces geometric distortions
  - Common practice for x-ray imaging is to position the subject immediately next to or on top of the detector

# Finite (Large) Sources

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- If the thickness of the body is not a limiting factor, then let  $d, z \rightarrow \infty$ .
  - Make the system close to a parallel ray geometry with  $|m| \rightarrow 0$  and  $M \rightarrow 1$ .
  - Main problem:  $I_0 \propto 1/d^2 \rightarrow 0$  and  $\text{SNR} \propto \sqrt{I_0} \rightarrow 0$ .
- Make  $s(x,y)$  as small as possible to reduce blurring, but might reduce the number of photons created and thus reduce SNR.

# Finite (Large) Sources

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- For a complex object, make

$$\mu(x, y, z) = \sum \tau_i(x, y) \delta(z - z_i)$$

and each plane will have its own magnification factors.

- gives you some idea of how blurring and magnification might affect different parts of a real object differently.





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# Questions?

Finite (Large) Sources



# Overall System Response

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Object Blurring

# Overall System Response

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- The detector response –  $h(r_d)$
- Add the detector response to the other system elements. The overall system response is:

$$I_d(x_d, y_d) = \frac{1}{4\pi d^2 m^2} s\left(\frac{x_d}{m}, \frac{y_d}{m}\right) **_t \left(\frac{x_d}{M}, \frac{y_d}{M}\right) ** h(r_d)$$

# Overall System Response

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- The impulse response function

$$h(x_d, y_d) = \frac{1}{4\pi d^2 m^2} s\left(\frac{x_d}{m}, \frac{y_d}{m}\right) ** h(r_d)$$

- For a circularly symmetric source function:

$$h(x_d, y_d) = \frac{1}{4\pi d^2 m^2} s\left(\frac{r_d}{m}\right) ** h(r_d)$$



# True or False

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- The detector blurs the magnified object, not the source
- The magnified source also blurs the magnified object
- Source and object have the same magnification factors



# True or False

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- The detector blurs the magnified object, not the source **True**
- The magnified source also blurs the magnified object **True**
- Source and object have the same magnification factors **False**

# Object Blurring

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- Examine the response in the coordinate system of the object  $(x, y)$  rather than the detector  $(x_d, y_d)$ :

$$I(x, y) = ks \left( \frac{Mx}{m}, \frac{My}{m} \right) ** t(x, y) ** h(Mr_d)$$

- Effective magnification of source:  $\left| \frac{m}{M} \right| = \frac{d - z}{d}$
- Effective magnification of the detector response  $\frac{1}{M} = \frac{z}{d}$

# Object Blurring

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- The two magnified blurring effects are in competition:
  - To make the source blurring  $(d-z)/d$  small, make  $z \rightarrow d$
  - To make the detector blurring  $z/d$  small, make  $z \rightarrow 0$



# Object Blurring

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- Comments:

- For most x-ray systems, the detector response is very small and the source is almost always bigger. Therefore, we would like to make  $z \rightarrow d$ .
- For other kinds of systems, e.g. digital fluoroscopy systems, the detector resolution is a bit larger and for these systems an intermediate  $z$  may be appropriate.



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# Questions?

Over all System Response  
Object Blurring



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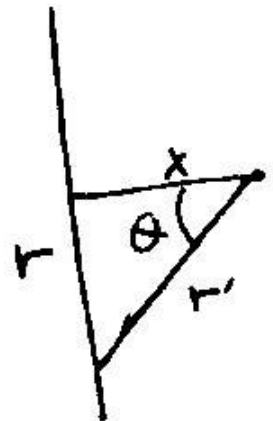
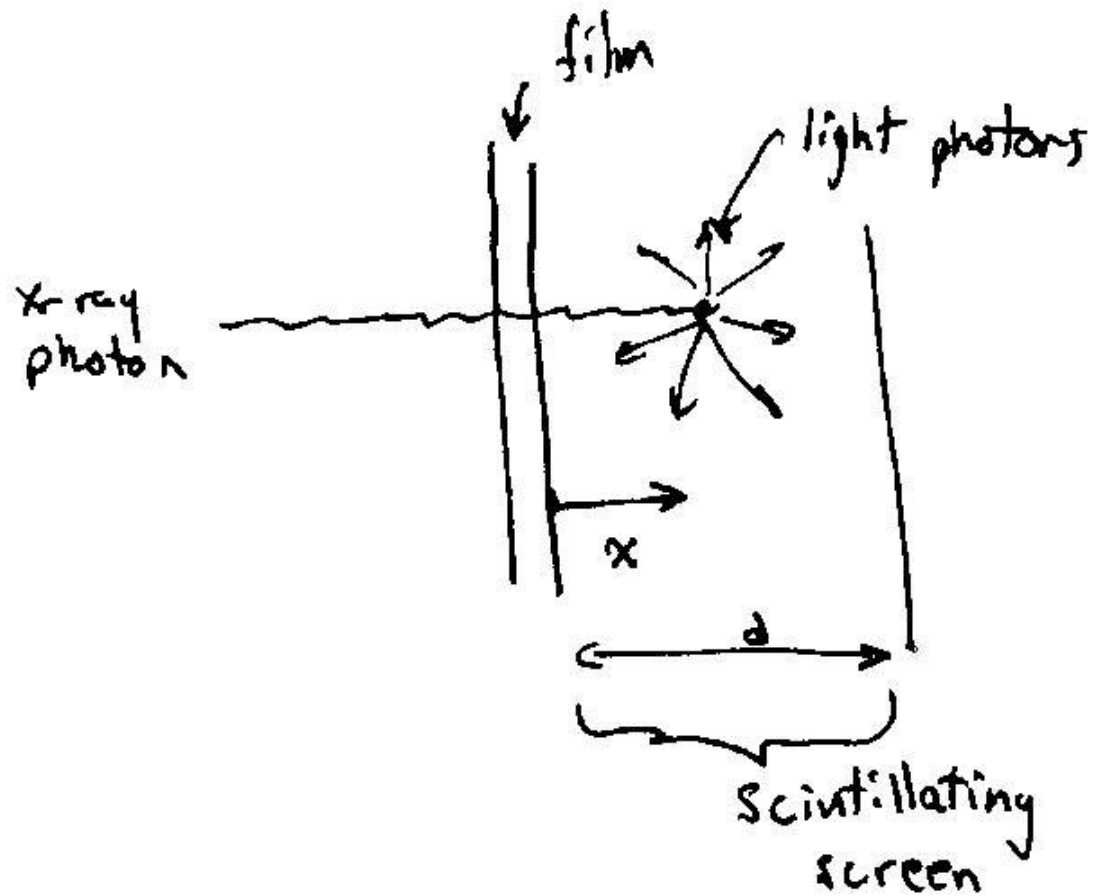
# **X-ray Detection**

# X-ray Detection – Photographic Film

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- Traditional x-ray detector – film based
  - Not used anymore
- Films are generally not very sensitive to x-rays, so x-rays must first be converted to visible light by a scintillator
- Materials such as sodium iodide (NaI) can "convert" an X-ray photon to a visible photon

# X-ray Detection – Photographic Film



# X-ray Detection – Image Plate

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- Photo-stimulable phosphors (PSPs) are sensitive to X-rays (often called image plates)
  - Can store weak radioactive signal in a phosphor plate
  - Can be stimulated with visible light and produce a luminescent signal (image readout with a laser)
  - require higher X-ray exposure – needs intensifying screens.
  - Film X-ray equipment requires no modification to use them.

# Flat Panel Detector

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- Scintillator layer of gadolinium oxysulfide or cesium iodide converts x-rays to light.
- A silicon-on glass detector array (mix between LCD and digital camera sensor chip) is behind the scintillator layer.
- Each pixel on the glass detector contains a photodiode – generates electronic signal for producing a digital image.
- Typical pitch: 100  $\mu\text{m}$ , 2-4k pixels/side



# Flat Panel Detector

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## ○ Advantages

- Electronic storage
- More sensitive - allows a lower dose of radiation
- Faster and cheaper than film.
- Lighter, more durable, smaller in volume, more accurate, and have much less image distortion than image plates.
- Can be produced in larger sizes



# Flat Panel Detectors

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# Philips C-arm

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# Detector Issues

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- In selecting detector characteristics, we will have a resolution/SNR trade-off
  - The thicker detectors have better SNR, but a larger impulse response (i.e. worse resolution)



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# Questions?

X-ray Detection



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# **SNR and Noise in X-ray system**

# Noise in X-ray system

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- X-ray images are created from intensity values that are related to the number of photons( $N$ ) that strike a detector element in a finite period of time (from intensity  $I$ )

- In X-ray,  $SNR = \frac{\bar{S}}{\sigma_s} = \frac{N}{\sqrt{N}} = \sqrt{N}$



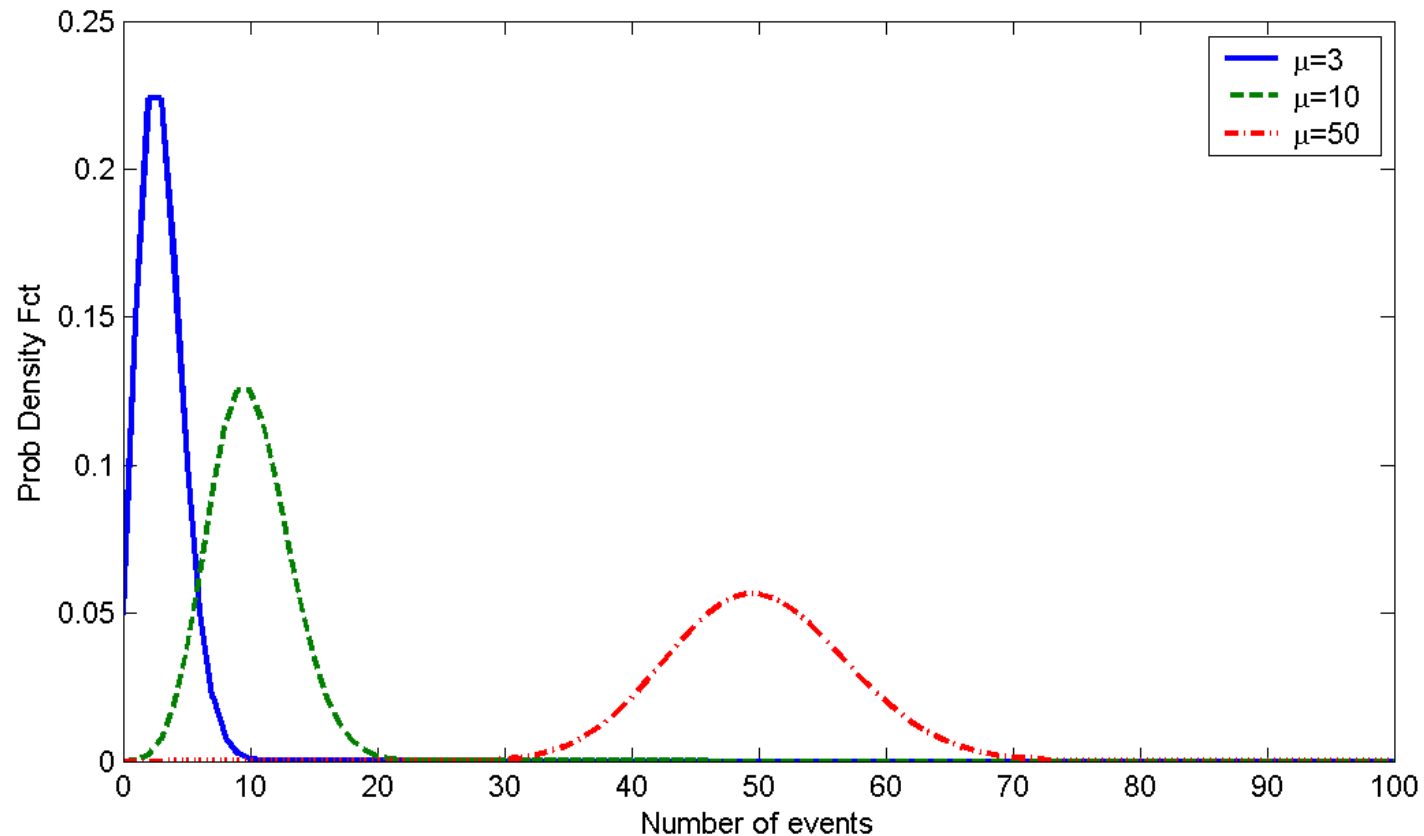
# SNR of a Poisson Measurement

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- SNR increases as the square root of the number of photons.
  - *SNR increases as the square root of the dose to the patient.*
- By averaging together two neighboring pixels, roughly double the photon counts and improve the SNR by  $\sqrt{2}$ .

# SNR of a Poisson Measurement

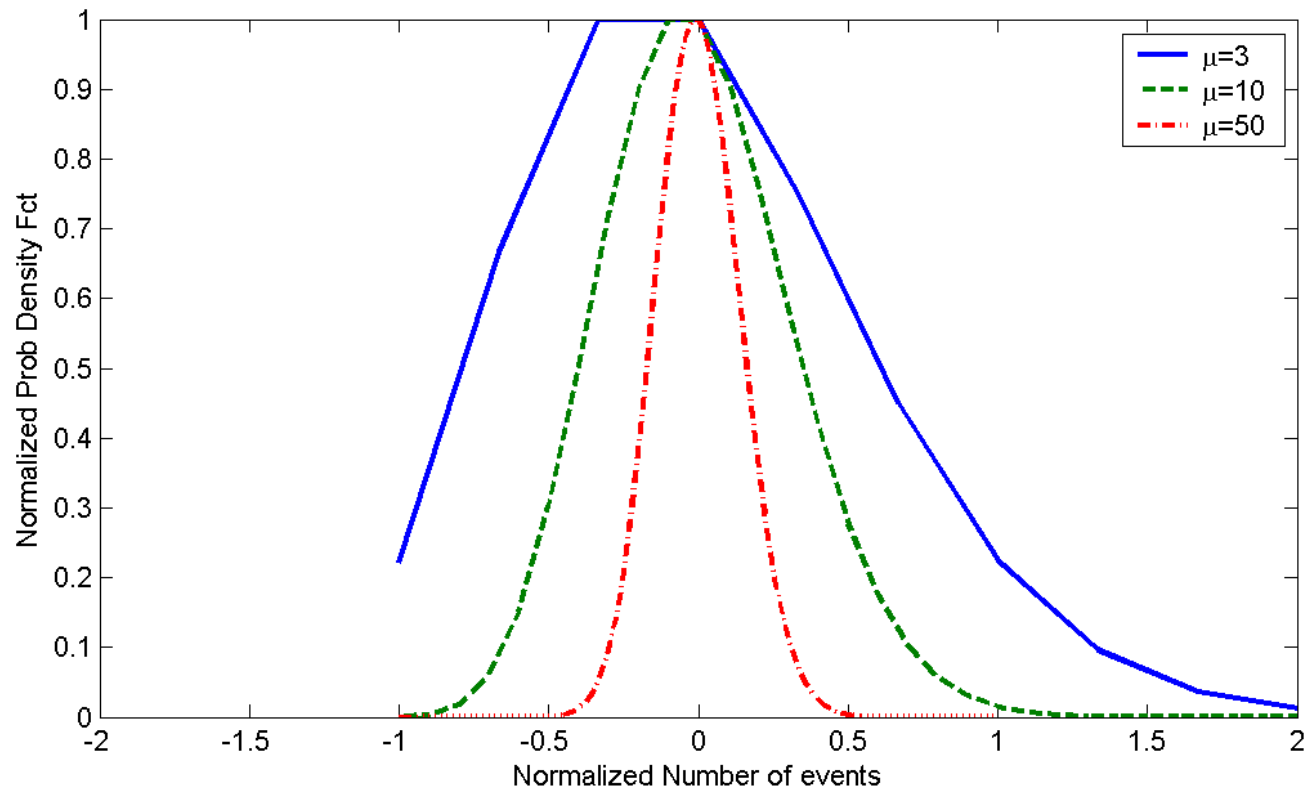
Poisson distributions as the mean increases from 3 to 50





# SNR of a Poisson Measurement

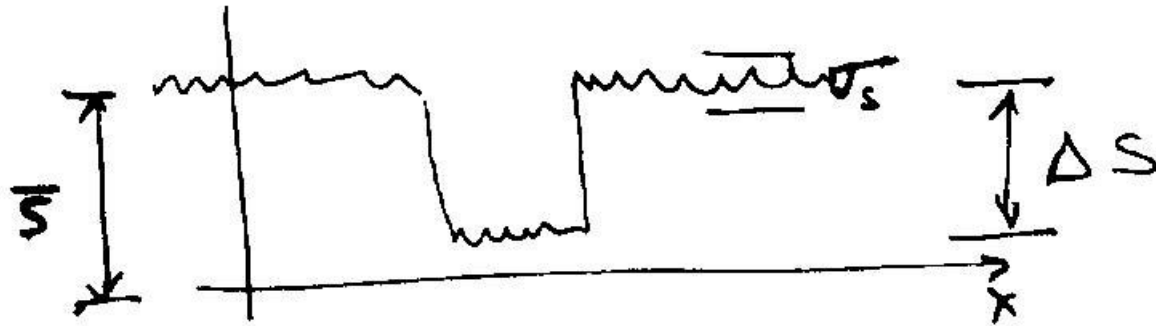
Poisson distributions (subtract the mean and divide the x-axis by the mean)



# Noise in Detectors

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- Consider an output to an x-ray



- We define a number of quantities

# Noise in Detectors

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We define a number of quantities

- Contrast:  $C = \Delta S / \bar{S}$
- Signal to Noise Ratio:  $SNR = \bar{S} / \sigma_s$
- Contrast to Noise Ratio:

$$CNR = \Delta S / \sigma_s = C \cdot SNR$$

# Noise in Detectors

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- Suppose the incident x-ray photons arriving at the detector are Poisson( $N$ ) and that the detector has efficiency  $\eta$

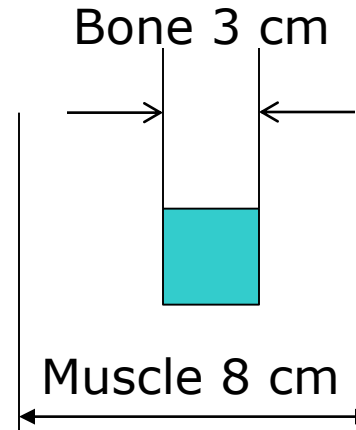
$$SNR_{\text{det}} = \frac{\eta N}{\sqrt{\eta N}} = \sqrt{\eta N}$$

# Example - Contrast

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Photon energy = 90 keV

- Bone -  $\mu_b = 0.4 \text{ cm}^{-1}$
- Muscle -  $\mu_m = 0.2 \text{ cm}^{-1}$



- Calculate contrast  $C = \frac{\Delta S}{\bar{S}}$ . To simplify, use parallel x-ray beams.

# Example : Contrast

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- Muscle only:

$$I_m = I_0 e^{-m_m \times 8} = I_0 e^{-0.2 \times 8} = 0.202 I_0$$

- Muscle + bone:

$$I_{m+b} = I_0 e^{-m_m \times (8-3) - m_b \times 3} = I_0 e^{-0.2 \times 5 - 0.4 \times 3} = 0.111 I_0$$

- Calculate contrast:

$$C = \frac{DS}{S} = \frac{I_m - I_{m+b}}{I_m} = \frac{0.202 I_0 - 0.111 I_0}{0.202 I_0} = 0.45$$



# Questions

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SNR and noise