

---

# HOMEWORK 1

---

A PREPRINT

**Dan Chang\***  
Department of Mechanical Engineering  
University of Wisconsin Madison

November 2, 2020

## 1 Problem A

$v$  belongs to the span of  $w_1, w_2, \dots, w_n$

$$v = \sum_{i=1}^n c_i w_i$$
$$\langle v, w_j \rangle = \sum_{i=1}^n c_i w_i \cdot w_j$$
$$= \sum_{i=1}^n c_i \|w_i\|^2$$

$\begin{cases} i \neq j, w_i \cdot w_j = 0 \\ i = j, w_i \cdot w_i = \|w_i\|^2 \end{cases}$

$$\text{So } \sum_{j=1}^n \frac{\langle v, w_j \rangle}{\|w_j\|^2} w_j = \sum_{j=1}^n c_j w_j = v$$

Figure 1: Problem A (a)

---

\*ychang253@wisc.edu

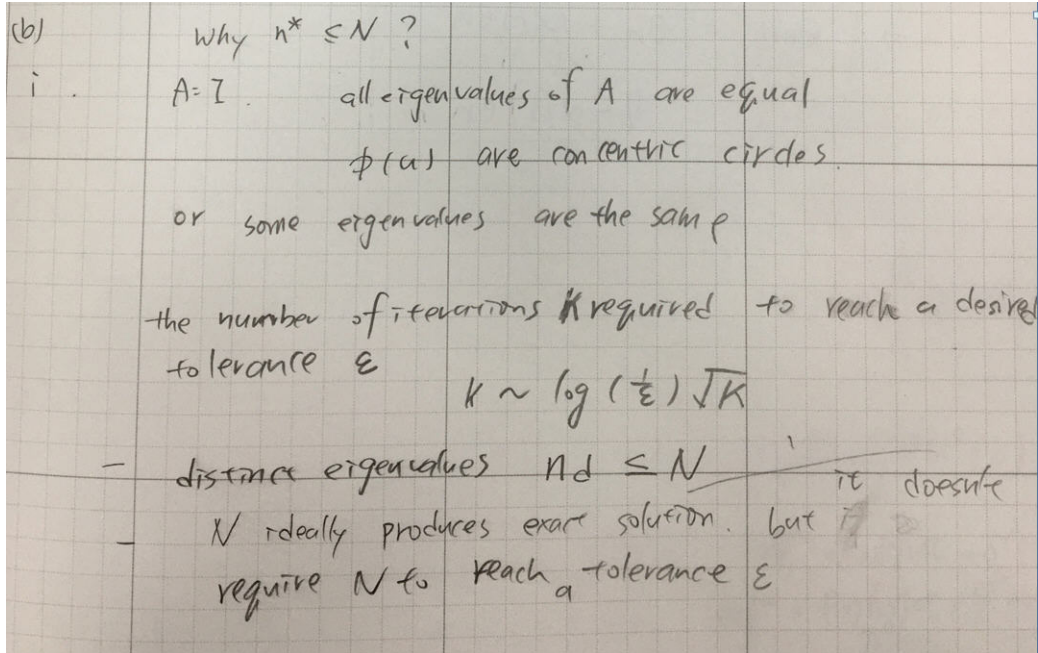


Figure 2: Problem A (b) i.

(b) ii

$$P_n = r_n - \sum_{j=0}^{n-1} \left( \frac{r_n^T A P_j}{P_j^T A P_j} \right) P_j$$

$n=1$   $P_1 = r_1 - \frac{r_1^T A P_0}{P_0^T A P_0} P_0$

$$P_1^T A P_0 = r_1^T A P_0 - \frac{r_1^T A P_0}{P_0^T A P_0} P_0^T A P_0 = 0$$

$n=2$   $P_2 = r_2 - \frac{r_2^T A P_0}{P_0^T A P_0} P_0 - \frac{r_2^T A P_1}{P_1^T A P_1} P_1$

$$P_2^T A P_1 = r_2^T A P_1 - \frac{r_2^T A P_0}{P_0^T A P_0} P_0^T A P_1 - \frac{r_2^T A P_1}{P_1^T A P_1} P_1^T A P_1 = 0$$

$$P_2^T A P_0 = r_2^T A P_0 - \frac{r_2^T A P_0}{P_0^T A P_0} P_0^T A P_0 - \frac{r_2^T A P_1}{P_1^T A P_1} P_1^T A P_0 = 0$$

Assume  $n=k$  holds  $\langle P_k, P_j \rangle_A = 0$  for  $0 \leq j < k$

$n=k+1$   $P_{k+1} = r_{k+1} - \frac{r_{k+1}^T A P_0}{P_0^T A P_0} P_0 - \frac{r_{k+1}^T A P_1}{P_1^T A P_1} P_1 - \dots - \frac{r_{k+1}^T A P_k}{P_k^T A P_k} P_k$

$$P_{k+1}^T A P_j \stackrel{?}{=} 0 \quad \text{for } j \neq k \text{ terms are zero}$$

$$P_{k+1}^T A P_k = r_{k+1}^T A P_k - \frac{r_{k+1}^T A P_k}{P_k^T A P_k} P_k^T A P_k = 0$$

Figure 3: Problem A (b) ii.

(c). i.  $A$  SPD

$$v = \sum_i v_i \phi_i$$

$$w = \sum_j w_j \phi_j$$

$$\langle Av, w \rangle = \left( \sum_i v_i \lambda_i \phi_i \right) \cdot \left( \sum_j w_j \phi_j \right) \quad \lambda = j$$

$$= \sum_n \lambda_n v_n \phi_n w_n \phi_n$$

$$= \sum_{n=1}^N \lambda_n \langle v, \phi_n \rangle \langle \phi_n, w \rangle$$

ii.  $\lambda \in \mathbb{C}$

$$Av = \lambda v$$

$$v^T A v = \lambda v^T v$$

$$v^T A^T v = \bar{\lambda} v^T v$$

$$\because A^T = A \Rightarrow \lambda = \bar{\lambda} \Rightarrow \lambda \in \mathbb{R}$$

$$\lambda = \frac{v^T A v}{v^T v} > 0$$

iii.  $\langle Av, v \rangle = \sum_{n=1}^N \lambda_n \langle v, \phi_n \rangle^2$

$$\Rightarrow \lambda_1 \|v\|^2 \leq \langle Av, v \rangle \leq \lambda_N \|v\|^2$$

$$\lambda_1 \left( \sum_{n=1}^N \langle v, \phi_n \rangle^2 \right) \leq \lambda_N \left( \sum_{n=1}^N \langle v, \phi_n \rangle^2 \right)$$

$$\therefore \lambda_N > \lambda_n > \lambda_1$$

iv.  $Av = \sum_n \lambda_n v_n \phi_n$

$$\|Av\| = \sum_n \lambda_n |v_n \phi_n| \leq \lambda_N \sum_n |v_n \phi_n| = \lambda_N \|v\|$$

Figure 4: Problem A (c)

A (d)

$$\begin{aligned}
 P_{n+1} &= Y_{n+1} + \beta_n P_n \\
 &= Y_n - \alpha_n A P_n + \beta_n P_n \\
 &= P_n - \beta_{n-1} P_{n-1} - \alpha_n A P_n + \beta_n P_n \\
 &= (1 + \beta_n) P_n - \alpha_n A P_n - \beta_{n-1} P_{n-1}
 \end{aligned}$$

Figure 5: Problem A (d)

(e) Cayley - Hamilton theorem

$$\begin{aligned}
 P(\lambda) &= \det(\lambda I_n - A) \\
 P(A) &= \underline{0} \text{ - zero matrix} \\
 \Rightarrow P(A) &= A^n + C_{n-1} A^{n-1} + \dots + C_1 A + (-1)^n \det(A) I_n = 0 \\
 A^n &\text{ could be a linear combination of } I_n, A, A^2, \dots, A^{n-1}
 \end{aligned}$$

Figure 6: Problem A (e)



(f) i. 
$$\begin{aligned} u_{n+1} &= u_n + \alpha (f - Au_n) \\ &= u_n + \alpha (Au - Au_n) \\ &= u_n + \alpha A(u - u_n) \end{aligned}$$

$$\Rightarrow e_{n+1} = u_{n+1} - u = u_n - u + \alpha A(u - u_n)$$

$$= e_n - \alpha A e_n$$

$$= (I - \alpha A) e_n$$

ii. 
$$\begin{aligned} \|e_{n+1}\| &\leq \rho \|e_n\| \\ &\leq \rho^2 \|e_{n-1}\| \\ &\leq \rho^n \|e_0\| \end{aligned}$$

if  $\rho < 1$ ,  $\|e_{n+1}\| \rightarrow 0$ .  $u_n$  converge to the solution  $u$ .

$B \doteq I - \alpha A \Rightarrow \|B e_n\| \leq \max(\lambda_B) \|e_n\| = \max(1 - \alpha \lambda_A)$

$A v = \lambda_A v$

$I v - \alpha A v = I v - \alpha \lambda_A v \Rightarrow \lambda_B = 1 - \alpha \lambda_A$

$(I - \alpha A) v = (1 - \alpha \lambda_A) v \Rightarrow \max(\lambda_B) = \max(1 - \alpha \lambda_A)$

Figure 7: Problem A (f) i. and ii.

iii.  $\rho = \max |1 - \alpha \lambda_j|$

must choose

$\rho(\lambda_1) = -\rho(\lambda_N)$

$1 - \alpha \lambda_1 = -(1 - \alpha \lambda_N)$

$\Rightarrow \alpha = \frac{2}{\lambda_N + \lambda_1}$

$\rho = \rho(\lambda_1) = 1 - \frac{2\lambda_1}{\lambda_N + \lambda_1} = 1 - \frac{2}{\frac{\lambda_N}{\lambda_1} + 1} = \frac{\frac{\lambda_N}{\lambda_1} - 1}{\frac{\lambda_N}{\lambda_1} + 1} = \frac{K-1}{K+1} < 1$

iv. Similar  $\tilde{\rho} = 1 - \alpha X$

$\rho < \tilde{\rho}(c) = -\tilde{\rho}(c)$

$\Rightarrow \alpha = \frac{2}{c + C}$

$\rho = \max |1 - \alpha \lambda_j| \leq \tilde{\rho}(c) = 1 - \frac{2c}{C+c} = \frac{\frac{C}{c} - 1}{\frac{C}{c} + 1} = \frac{K'-1}{K'+1} < 1$

Figure 8: Problem A (f) iii. and iv.

g) 
$$r_k = r_{k-1} - \alpha_{k-1} w_{k-1}$$
  

$$w_{k-1} = A p_{k-1}$$

i. 
$$r_1 = r_0 - \alpha_0 A p_0$$
  

$$= r_0 - \alpha_0 A r_0$$

Figure 9: Problem A (g) i.

ii 
$$r_{n+1} = r_n - \alpha_n w_n$$
  

$$= r_n - \alpha_n A p_n$$
  

$$= r_n - \alpha_n A (r_n + \beta_{n-1} p_{n-1})$$
  

$$= r_n - \alpha_n A r_n - \alpha_n \beta_{n-1} A p_{n-1}$$
  

$$= r_n - \alpha_n A r_n + \frac{\alpha_n \beta_{n-1}}{\alpha_{n-1}} (r_n - r_{n-1})$$

$A p_{n-1} = w_{n-1} =$

Figure 10: Problem A (g) ii.

(g) iii. From i:  $r_1 = r_0 - \alpha_0 A r_0$   
 $A r_0 = \frac{1}{\alpha_0} (r_0 - r_1)$   
 $\frac{A r_0}{\|r_0\|} = \frac{1}{\alpha_0} \frac{1}{\sqrt{r_0^T r_0}} (r_0 - r_1)$   
 $= r_0 \frac{r_0}{\|r_0\|} - \frac{1}{\alpha_0} \frac{1}{\sqrt{r_0^T r_0}} \frac{\sqrt{r_1^T r_1}}{1} \frac{r_1}{\sqrt{r_1^T r_1}}$   
 $= r_0 \frac{r_0}{\|r_0\|} - \frac{\beta_0}{\alpha_0} \frac{r_1}{\|r_1\|}$   
 So,  $A g_0 = r_0 g_0 - \beta_0 g_1$

From ii:  $r_{n+1} = r_n - \alpha_n A r_n + \frac{\alpha_n \beta_{n+1}}{\alpha_{n-1}} (r_n - r_{n-1})$   
 $A r_n = \frac{1}{\alpha_n} (r_n - r_{n+1}) + \frac{\beta_{n+1}}{\alpha_{n-1}} (r_n - r_{n-1})$   
 $= -\frac{\beta_{n+1}}{\alpha_{n-1}} r_{n-1} + \left( \frac{1}{\alpha_n} + \frac{\beta_{n+1}}{\alpha_{n-1}} \right) r_n - \frac{1}{\alpha_n} r_{n+1}$   
 $\frac{A r_n}{\|r_n\|} = \frac{-\frac{r_n^T r_n}{r_{n-1}^T r_{n-1}} \left( \frac{\sqrt{r_{n-1}^T r_{n-1}}}{\sqrt{r_n^T r_n}} \right) \frac{r_{n-1}}{\sqrt{r_{n-1}^T r_{n-1}}} + r_n \frac{r_n}{\|r_n\|} - \frac{1}{\alpha_n} \frac{\sqrt{r_{n+1}^T r_{n+1}}}{\sqrt{r_n^T r_n}} \frac{r_{n+1}}{\sqrt{r_{n+1}^T r_{n+1}}}}{\alpha_{n-1}}$   
 $= -\frac{\beta_{n+1}}{\alpha_{n-1}} \frac{r_{n-1}}{\|r_{n-1}\|} + r_n \frac{r_n}{\|r_n\|} - \frac{\beta_n}{\alpha_n} \frac{r_{n+1}}{\|r_{n+1}\|}$   
 So,  $A g_n = -\beta_{n+1} g_{n-1} + r_n g_n - \beta_n g_{n+1}$

Figure 11: Problem A (g) iii.

IV.  $AQ_n = \begin{bmatrix} q_{n-1} & q_n & \dots & q_n \end{bmatrix} \begin{bmatrix} r_0 - f_0 & & & \\ -f_0 & r_1 & & \\ & \vdots & \ddots & \\ & -f_{n-3} & r_{n-2} & -f_{n-2} \\ T_n & -f_{n-2} & r_{n-1} & \end{bmatrix} - f_n$

V.  $AQ_n = Q_n T_n - f_{n-1} q_n e_n^T$

$Q_n^T A Q_n = \underbrace{Q_n^T Q_n}_{I} T_n - f_{n-1} \underbrace{(Q_n^T q_n)}_{\substack{1 \\ 0}} e_n^T$

$q_n^T q_n = 1$   
 $q_i^T q_j = 0$

Figure 12: Problem A (g) iv. and v.



## 2 Problem B

The smallest value of  $N$  is 100 to make sure the uniform norm within  $10^{-2}$ .

Double click HW2.exe in the folder of HW2/x64/Release. Two function, ErrorOfLinearInterpolation and ErrorVsGridSpacing2DWave, will be executed. Then result will be displayed on screen, shown as Figure 13 . (Github repository is <https://github.com/ychang253/HW2.git>)

```
Problem B, N=100 , Error =0.00965511
Error beteen grid =511 and 1023 is 3.23242e-05
Error beteen grid =255 and 1023 is 0.000167077
Error beteen grid =127 and 1023 is 0.00074921
```

Figure 13: Screen output

## 3 Problem C

### 3.1 (a)

For  $n + 1 \geq 2$ .

$$U_{i,j}^{n+1} = 2U_{i,j}^n - U_{i,j}^{n-1} + \frac{\Delta t^2}{h^2} (U_{i-1,j}^n + U_{i+1,j}^n + U_{i,j-1}^n + U_{i,j+1}^n - 4U_{i,j}^n)$$

For  $n + 1 = 1$ . To know  $U_{i,j}^{-1}$  by the relation:  $\frac{U_{i,j}^1 - U_{i,j}^{-1}}{2\Delta t} = f(x)f(y)$ . Then the  $U_{i,j}^1$  can be determined.

$$U_{i,j}^1 = U_{i,j}^0 + f(x)f(y)\Delta t + \frac{\Delta t^2}{2h^2} (U_{i-1,j}^0 + U_{i+1,j}^0 + U_{i,j-1}^0 + U_{i,j+1}^0 - 4U_{i,j}^0)$$

Comparing to the result of reference grid 1023 X 1023 at time = 1 sec, the log-log plot of the error vs. grid spacing is shown as Figure 14 . The slope is close to 2 meaning current method is second-order accurate. Simulation result of time = 1 s is shown as Figure 15.

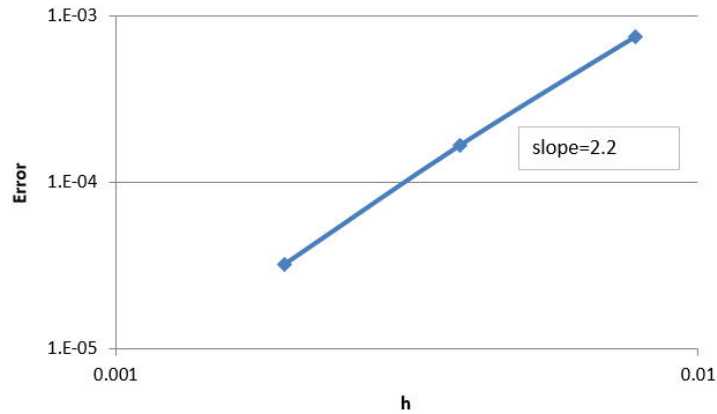


Figure 14: Error vs. Grid spacing

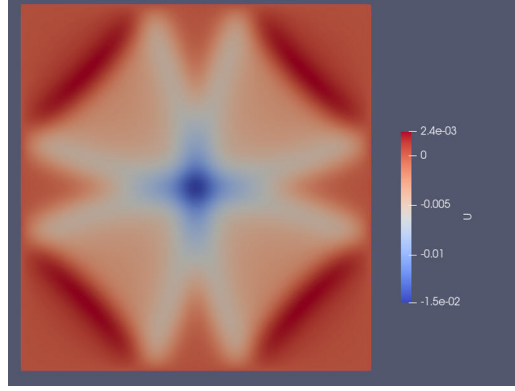


Figure 15: Simulation result at time=1s

### 3.2 (b)

$$y''(t) = \lambda y$$

$$y^{n+1} - (2 + \lambda \Delta t^2)y^n + y^{n-1} = 0$$

$$\rho^2 - (2 + \lambda \Delta t^2)\rho + 1 = 0$$

$$\rho = \left(1 + \frac{\lambda \Delta t^2}{2}\right) \pm \sqrt{\left(1 + \frac{\lambda \Delta t^2}{2}\right)^2 - 1}$$

If we want  $|\rho| \leq 1$ , then  $\text{Im}\left(1 + \frac{\lambda \Delta t^2}{2}\right) = 0$  and  $-1 \leq \text{Re}\left(1 + \frac{\lambda \Delta t^2}{2}\right) \leq 1$ , and finally we can get  $-4 \leq \lambda \Delta t^2 \leq 0$ . Plot in complex plane is shown as Figure 16.

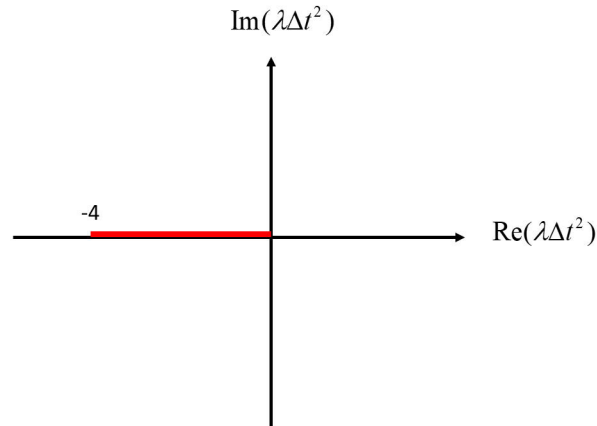


Figure 16: Stability region

**3.3 (c)**

Method of line

$$U'(t) = AU(t)$$

Since A is 2D Laplacian,  $\text{Max}(\lambda_A) = \frac{-8}{\Delta x^2}$ , combine with result from (a), then CFL condition  $\frac{\Delta t}{\Delta x} \leq \sqrt{\frac{1}{2}}$  is obtained.

**3.4 (d)**

$$U^n = e^{i(k_1 j_1 \Delta x + k_2 j_2 \Delta x - \omega n \Delta t)}$$

$$\frac{4}{\Delta t^2} \sin^2\left(\frac{\omega \Delta t}{2}\right) = \frac{4}{\Delta x^2} \left( \sin^2\left(\frac{k_1 \Delta x}{2}\right) + \sin^2\left(\frac{k_2 \Delta x}{2}\right) \right)$$

$$\sin^2\left(\frac{\omega \Delta t}{2}\right) = \frac{\Delta t^2}{\Delta x^2} \left( \sin^2\left(\frac{k_1 \Delta x}{2}\right) + \sin^2\left(\frac{k_2 \Delta x}{2}\right) \right)$$

For real  $\omega$ , right hand side must less than 1, so  $\frac{2\Delta t^2}{\Delta x^2} \leq 1$ . Finally, CFL condition  $\frac{\Delta t}{\Delta x} \leq \sqrt{\frac{1}{2}}$  is the same as result from (b).

**3.5 (e)**

$$u_{tt} + \frac{1}{12} \Delta t^2 u_{tttt} + O(\Delta t^4) = u_{xx} + \frac{1}{12} \Delta x^2 u_{xxxx} + u_{yy} + \frac{1}{12} \Delta x^2 u_{yyyy} + O(\Delta x^4)$$

$$u_{tttt} = u_{xxxx} + u_{yyyy} + 2u_{xxyy}$$

Modified equation will be :

$$u_{tt} = u_{xx} + u_{yy} + \frac{1}{12} (\Delta x^2 - \Delta t^2) (u_{xxxx} + u_{yyyy}) - \frac{1}{6} \Delta t^2 u_{xxyy}$$

Fourier series : If  $u_{tt} = u_{xx}$ , then  $\hat{u}_{tt}(\xi, t) = -\xi^2 \hat{u}(\xi, t)$  and  $\hat{u}(\xi, t) = e^{-i\xi^2 t} \hat{u}_0(\xi, t)$ .

If  $u_{tt} = u_{xxxx}$ , then  $\hat{u}_{tt}(\xi, t) = -\xi^4 \hat{u}(\xi, t)$  and  $\hat{u}(\xi, t) = e^{-i\xi^4 t} \hat{u}_0(\xi, t)$ .

Since modified equation  $u_{tt}$  is a combination of  $u_{xx}$  and  $u_{xxxx}$ , then the solution will be in this form

$$u(x, t) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} \hat{u}_0(\xi, t) e^{-i\xi(x - (a_1 + a_2 \xi)t)} d\xi$$

$\omega = (a_1 + a_2 \xi)$  is real, which mean the equation is dispersive.

**4 Problem D**

$$U_{i,j}^{n+1} = 2U_{i,j}^n - U_{i,j}^{n-1} + \Delta t^2 AU^n$$

$$U_{i,j}^{n+1} = (2I + \Delta t^2 A)U^n - U_{i,j}^{n-1} = B(\Delta t)U^n - U_{i,j}^{n-1}$$

Consider the LTE  $U_{i,j}^{n+1} = B(\Delta t)U^n - U_{i,j}^{n-1} + \Delta t^2 \tau^n$  and  $E^n = U^n - u^n$ , then  $E^n = B^n E^0 - \Delta t^2 \sum_{m=1}^N B^{n-m} \tau^{m-1}$ .

$$\|E\|^n \leq \|B\|^n \|E_0\| + \Delta t^2 \sum_{m=1}^N \|B\|^{n-m} \|\tau^{m-1}\|$$

Weak-stability

$$\|E\|^n \leq C_T \|E_0\| + \Delta t^2 N C_T \max \|\tau^{m-1}\|$$

$E_0 \rightarrow 0$  if initial condition is well handled, and  $\tau \rightarrow 0$  if  $\Delta t \rightarrow 0$