

Itô integral (some extensions)

$$\int_0^t X dY \quad Y = B$$

$$\underbrace{\int_0^t B_1^{(s)} dB_2^{(s)}}_{\text{}} \quad \int_0^t \underbrace{f_s}_{\text{}} d\underbrace{B_s}_{\text{}} \quad \underbrace{\mathcal{F}_t}_{\text{}}$$

- more general assumption on measurability condition

Assume: there is a filtration $\{\mathcal{H}_t\}$ s.t.

- B_t is martingale with respect to \mathcal{H}
- and f is \mathcal{H} adapted.

(Note: $\mathcal{F}_t \subset \mathcal{H}_t$)

$$(B_1, B_2, \dots, B_n)$$

$$\mathcal{F}_t^{(n)} = \sigma \left\{ \underbrace{B_1(s_1), \dots, B_n(s_n)}_{\text{}} : \substack{s_k \leq t \\ 1 \leq k \leq n} \right\}$$

each B_k is mart. with respect to $\mathcal{F}_t^{(n)}$

$$\left(\substack{s < t \\ B_k(t) - B_k(s) \text{ indep of } \mathcal{F}_s^{(n)}} \right)$$

We can define $\int_0^t f(s) dB_k$

$$\left(\text{e.g. } \int B_2 dB_1, \int \sin(B_1^2 + B_2^2) dB_2 \dots \right)$$

Can also define

$$\int_0^t \underset{\substack{\uparrow \\ (v_{11} \dots v_{1n} \\ \vdots \\ v_{m1} \dots v_{mn})}}{v} \underset{\substack{\uparrow \\ (dB_1 \dots dB_n)}}{dB} = \int_0^t \begin{pmatrix} v_{11} & \dots & v_{1n} \\ \vdots & & \vdots \\ v_{m1} & \dots & v_{mn} \end{pmatrix} \begin{pmatrix} dB_1 \\ \vdots \\ dB_n \end{pmatrix}$$

$$\int_0^t f dB \quad f \in \mathcal{H}^2. \quad \underline{\underline{\mathbb{E} \int_0^T f^2 ds < \infty.}}$$

$$f(B) = e^{B^4} \quad \int_0^T f(B_s) dB_s = \int_0^T \underbrace{e^{B_s^4}}_{\text{not adapted}} dB_s$$

$$\mathbb{E} \int_0^T e^{2B_s^4} ds \not\approx \infty$$

$$\left(\int_{-\infty}^{+\infty} e^{-x^2} e^{x^4} dx = \infty \right)$$

$$\mathcal{H}_{[0,T]}^2 \xrightarrow{\quad} L_{loc}^2[0,T]$$

|| def

all adapted measurable functions f

$$\text{s.t.} \quad \mathbb{P} \left(\int_0^T f^2 dt < \infty \right) = 1$$

$$\left(\text{In fact } \forall \text{ continuous } g: \mathbb{R} \rightarrow \mathbb{R}. \right. \\ \left. f_t \stackrel{\text{def}}{=} \underline{g(B_t)} \in L_{loc}^2 \right)$$

Def. (localizing sequence for \mathcal{H}^2 .)

An increasing seq of stopping times $\{\nu_n\}$
is called an \mathcal{H}^2 localizing seq for f
if $f_n(\omega, t) \stackrel{\text{def}}{=} f(\omega, t) \mathbb{1}_{t \leq \nu_n} \in \mathcal{H}^2, \forall n$.

and
$$P \left(\bigcup_{n=1}^{\infty} \{ \omega : \nu_n = T \} \right) = 1$$

prop. $\forall f \in L^2_{loc} [0, T]$,

$$\tau_n = \inf \left\{ s : \int_0^s f^2 dt \geq n \text{ or } s \geq T \right\}$$

is a localizing seq.

Pf. $f_n^{(t)} = f^{(t)} \mathbb{1}_{t \leq \tau_n}$

$$\int_0^T f_n^2 ds = \int_0^{\tau_n} f_{(s)}^2 ds \leq n < \infty$$

$$\Rightarrow f_n \in \mathcal{H}^2 \quad \forall n \quad \checkmark$$

In general,
$$\bigcup_{n=1}^{\infty} \{ \omega : \tau_n = T \}$$

$$= \left\{ \omega : \int_0^T f^2 ds < \infty \right\}$$

$$\left\{ \omega : \int_0^T f(\omega, t) dt < \infty \right\}$$

$$P(\dots) = 1 \quad \checkmark$$

Define $\int_0^T f dB$ for $f \in L^2_{loc}$.

1). Let $\{\nu_n\}$ be a localizing seq for f .

$$2) \quad \underline{X_t^{(n)}} = \int_0^t \underbrace{f(\omega, s) \mathbb{1}_{s \leq \nu_n(\omega)}}_{\pi \mathcal{H}^2} dB_s$$

$$3) \quad \underline{\int_0^T f dB_s} \stackrel{\text{def}}{=} \lim_{n \rightarrow \infty} X_t^{(n)}$$

Key Lemma: \exists a continuous X

$$P(X_t = \lim_{n \rightarrow \infty} X_t^{(n)}) = 1$$

$$\forall t \in [0, T]$$